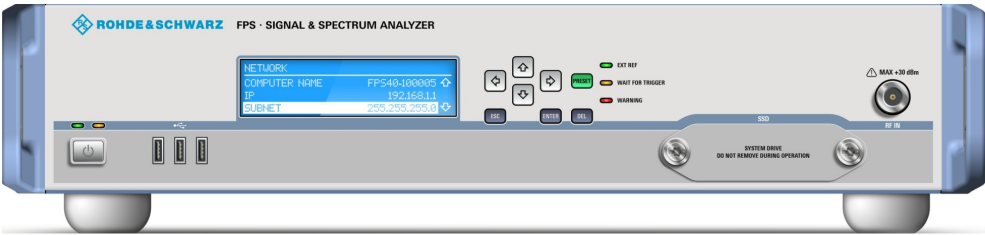


R&S®FPS

Signal and Spectrum Analyzer

User Manual



1176.8445.02 – 07

This manual applies to the following R&S®FPS models with firmware version 1.30 and higher:

- R&S®FPS4 (1319.2008K04)
- R&S®FPS7 (1319.2008K07)
- R&S®FPS13 (1319.2008K13)
- R&S®FPS30 (1319.2008K30)
- R&S®FPS40 (1319.2008K40)

In addition to the base unit, the following options are described:

- R&S FPS-B4, OCXO (1321.4291.02)
- R&S FPS-B10, external generator control (1321.4256.02)
- R&S FPS-B22, preamplifier (1321.4027.02)
- R&S FPS-B24, preamplifier (1321.4279.xx)
- R&S FPS-B25, electronic attenuator (1321.4033.02)
- R&S FPS-B40 bandwidth extension (1321.4040.02)
- R&S FPS-B160 bandwidth extension (1321.4285.xx)

The firmware of the instrument makes use of several valuable open source software packages. For information, see the "Open Source Acknowledgement" on the user documentation CD-ROM (included in delivery).

Rohde & Schwarz would like to thank the open source community for their valuable contribution to embedded computing.

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Subject to change – Data without tolerance limits is not binding.

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Trade names are trademarks of the owners.

The following abbreviations are used throughout this manual: R&S®FPS is abbreviated as R&S FPS. R&S MultiView is abbreviated as MultiView.

Basic Safety Instructions

Always read through and comply with the following safety instructions!

All plants and locations of the Rohde & Schwarz group of companies make every effort to keep the safety standards of our products up to date and to offer our customers the highest possible degree of safety. Our products and the auxiliary equipment they require are designed, built and tested in accordance with the safety standards that apply in each case. Compliance with these standards is continuously monitored by our quality assurance system. The product described here has been designed, built and tested in accordance with the EC Certificate of Conformity and has left the manufacturer's plant in a condition fully complying with safety standards. To maintain this condition and to ensure safe operation, you must observe all instructions and warnings provided in this manual. If you have any questions regarding these safety instructions, the Rohde & Schwarz group of companies will be happy to answer them.

Furthermore, it is your responsibility to use the product in an appropriate manner. This product is designed for use solely in industrial and laboratory environments or, if expressly permitted, also in the field and must not be used in any way that may cause personal injury or property damage. You are responsible if the product is used for any purpose other than its designated purpose or in disregard of the manufacturer's instructions. The manufacturer shall assume no responsibility for such use of the product.

The product is used for its designated purpose if it is used in accordance with its product documentation and within its performance limits (see data sheet, documentation, the following safety instructions). Using the product requires technical skills and, in some cases, a basic knowledge of English. It is therefore essential that only skilled and specialized staff or thoroughly trained personnel with the required skills be allowed to use the product. If personal safety gear is required for using Rohde & Schwarz products, this will be indicated at the appropriate place in the product documentation. Keep the basic safety instructions and the product documentation in a safe place and pass them on to the subsequent users.








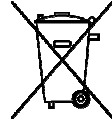

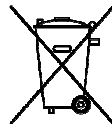


Observing the safety instructions will help prevent personal injury or damage of any kind caused by dangerous situations. Therefore, carefully read through and adhere to the following safety instructions before and when using the product. It is also absolutely essential to observe the additional safety instructions on personal safety, for example, that appear in relevant parts of the product documentation. In these safety instructions, the word "product" refers to all merchandise sold and distributed by the Rohde & Schwarz group of companies, including instruments,

Basic Safety Instructions

systems and all accessories. For product-specific information, see the data sheet and the product documentation.

Safety labels on products

The following safety labels are used on products to warn against risks and dangers.

Symbol	Meaning	Symbol	Meaning
	Notice, general danger location Observe product documentation	○	ON/OFF supply voltage
	Caution when handling heavy equipment	⏻	Standby indication
	Danger of electric shock	≡	Direct current (DC)
	Warning! Hot surface	~	Alternating current (AC)
	Protective conductor terminal	⎓	Direct/alternating current (DC/AC)
	Ground	□	Device fully protected by double (reinforced) insulation
	Ground terminal		EU labeling for batteries and accumulators For additional information, see section "Waste disposal/Environmental protection", item 1.
	Be careful when handling electrostatic sensitive devices	 	EU labeling for separate collection of electrical and electronic devices For additional information, see section "Waste disposal/Environmental protection", item 2.
	Warning! Laser radiation For additional information, see section "Operation", item 7.		

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Signal words and their meaning

The following signal words are used in the product documentation in order to warn the reader about risks and dangers.



Indicates a hazardous situation which, if not avoided, will result in death or serious injury.



Indicates a hazardous situation which, if not avoided, could result in death or serious injury.



Indicates a hazardous situation which, if not avoided, could result in minor or moderate injury.



Indicates information considered important, but not hazard-related, e.g. messages relating to property damage. In the product documentation, the word ATTENTION is used synonymously.

These signal words are in accordance with the standard definition for civil applications in the European Economic Area. Definitions that deviate from the standard definition may also exist in other economic areas or military applications. It is therefore essential to make sure that the signal words described here are always used only in connection with the related product documentation and the related product. The use of signal words in connection with unrelated products or documentation can result in misinterpretation and in personal injury or material damage.

Operating states and operating positions

The product may be operated only under the operating conditions and in the positions specified by the manufacturer, without the product's ventilation being obstructed. If the manufacturer's specifications are not observed, this can result in electric shock, fire and/or serious personal injury or death. Applicable local or national safety regulations and rules for the prevention of accidents must be observed in all work performed.

1. Unless otherwise specified, the following requirements apply to Rohde & Schwarz products:
predefined operating position is always with the housing floor facing down, IP protection 2X, use only indoors, max. operating altitude 2000 m above sea level, max. transport altitude 4500 m above sea level. A tolerance of $\pm 10\%$ shall apply to the nominal voltage and $\pm 5\%$ to the nominal frequency, overvoltage category 2, pollution severity 2.

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2. Do not place the product on surfaces, vehicles, cabinets or tables that for reasons of weight or stability are unsuitable for this purpose. Always follow the manufacturer's installation instructions when installing the product and fastening it to objects or structures (e.g. walls and shelves). An installation that is not carried out as described in the product documentation could result in personal injury or even death.
3. Do not place the product on heat-generating devices such as radiators or fan heaters. The ambient temperature must not exceed the maximum temperature specified in the product documentation or in the data sheet. Product overheating can cause electric shock, fire and/or serious personal injury or even death.

Electrical safety

If the information on electrical safety is not observed either at all or to the extent necessary, electric shock, fire and/or serious personal injury or death may occur.

1. Prior to switching on the product, always ensure that the nominal voltage setting on the product matches the nominal voltage of the AC supply network. If a different voltage is to be set, the power fuse of the product may have to be changed accordingly.
2. In the case of products of safety class I with movable power cord and connector, operation is permitted only on sockets with a protective conductor contact and protective conductor.
3. Intentionally breaking the protective conductor either in the feed line or in the product itself is not permitted. Doing so can result in the danger of an electric shock from the product. If extension cords or connector strips are implemented, they must be checked on a regular basis to ensure that they are safe to use.
4. If there is no power switch for disconnecting the product from the AC supply network, or if the power switch is not suitable for this purpose, use the plug of the connecting cable to disconnect the product from the AC supply network. In such cases, always ensure that the power plug is easily reachable and accessible at all times. For example, if the power plug is the disconnecting device, the length of the connecting cable must not exceed 3 m. Functional or electronic switches are not suitable for providing disconnection from the AC supply network. If products without power switches are integrated into racks or systems, the disconnecting device must be provided at the system level.

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5. Never use the product if the power cable is damaged. Check the power cables on a regular basis to ensure that they are in proper operating condition. By taking appropriate safety measures and carefully laying the power cable, ensure that the cable cannot be damaged and that no one can be hurt by, for example, tripping over the cable or suffering an electric shock.
6. The product may be operated only from TN/TT supply networks fuse-protected with max. 16 A (higher fuse only after consulting with the Rohde & Schwarz group of companies).
7. Do not insert the plug into sockets that are dusty or dirty. Insert the plug firmly and all the way into the socket provided for this purpose. Otherwise, sparks that result in fire and/or injuries may occur.
8. Do not overload any sockets, extension cords or connector strips; doing so can cause fire or electric shocks.
9. For measurements in circuits with voltages $V_{\text{rms}} > 30 \text{ V}$, suitable measures (e.g. appropriate measuring equipment, fuse protection, current limiting, electrical separation, insulation) should be taken to avoid any hazards.
10. Ensure that the connections with information technology equipment, e.g. PCs or other industrial computers, comply with the IEC60950-1/EN60950-1 or IEC61010-1/EN 61010-1 standards that apply in each case.
11. Unless expressly permitted, never remove the cover or any part of the housing while the product is in operation. Doing so will expose circuits and components and can lead to injuries, fire or damage to the product.
12. If a product is to be permanently installed, the connection between the protective conductor terminal on site and the product's protective conductor must be made first before any other connection is made. The product may be installed and connected only by a licensed electrician.
13. For permanently installed equipment without built-in fuses, circuit breakers or similar protective devices, the supply circuit must be fuse-protected in such a way that anyone who has access to the product, as well as the product itself, is adequately protected from injury or damage.
14. Use suitable overvoltage protection to ensure that no overvoltage (such as that caused by a bolt of lightning) can reach the product. Otherwise, the person operating the product will be exposed to the danger of an electric shock.
15. Any object that is not designed to be placed in the openings of the housing must not be used for this purpose. Doing so can cause short circuits inside the product and/or electric shocks, fire or injuries.

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16. Unless specified otherwise, products are not liquid-proof (see also section "Operating states and operating positions", item 1). Therefore, the equipment must be protected against penetration by liquids. If the necessary precautions are not taken, the user may suffer electric shock or the product itself may be damaged, which can also lead to personal injury.
17. Never use the product under conditions in which condensation has formed or can form in or on the product, e.g. if the product has been moved from a cold to a warm environment. Penetration by water increases the risk of electric shock.
18. Prior to cleaning the product, disconnect it completely from the power supply (e.g. AC supply network or battery). Use a soft, non-linting cloth to clean the product. Never use chemical cleaning agents such as alcohol, acetone or diluents for cellulose lacquers.

Operation

1. Operating the products requires special training and intense concentration. Make sure that persons who use the products are physically, mentally and emotionally fit enough to do so; otherwise, injuries or material damage may occur. It is the responsibility of the employer/operator to select suitable personnel for operating the products.
2. Before you move or transport the product, read and observe the section titled "Transport".
3. As with all industrially manufactured goods, the use of substances that induce an allergic reaction (allergens) such as nickel cannot be generally excluded. If you develop an allergic reaction (such as a skin rash, frequent sneezing, red eyes or respiratory difficulties) when using a Rohde & Schwarz product, consult a physician immediately to determine the cause and to prevent health problems or stress.
4. Before you start processing the product mechanically and/or thermally, or before you take it apart, be sure to read and pay special attention to the section titled "Waste disposal/Environmental protection", item 1.
5. Depending on the function, certain products such as RF radio equipment can produce an elevated level of electromagnetic radiation. Considering that unborn babies require increased protection, pregnant women must be protected by appropriate measures. Persons with pacemakers may also be exposed to risks from electromagnetic radiation. The employer/operator must evaluate workplaces where there is a special risk of exposure to radiation and, if necessary, take measures to avert the potential danger.

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6. Should a fire occur, the product may release hazardous substances (gases, fluids, etc.) that can cause health problems. Therefore, suitable measures must be taken, e.g. protective masks and protective clothing must be worn.
7. Laser products are given warning labels that are standardized according to their laser class. Lasers can cause biological harm due to the properties of their radiation and due to their extremely concentrated electromagnetic power. If a laser product (e.g. a CD/DVD drive) is integrated into a Rohde & Schwarz product, absolutely no other settings or functions may be used as described in the product documentation. The objective is to prevent personal injury (e.g. due to laser beams).
8. EMC classes (in line with EN 55011/CISPR 11, and analogously with EN 55022/CISPR 22, EN 55032/CISPR 32)
 - Class A equipment:
Equipment suitable for use in all environments except residential environments and environments that are directly connected to a low-voltage supply network that supplies residential buildings
Note: Class A equipment is intended for use in an industrial environment. This equipment may cause radio disturbances in residential environments, due to possible conducted as well as radiated disturbances. In this case, the operator may be required to take appropriate measures to eliminate these disturbances.
 - Class B equipment:
Equipment suitable for use in residential environments and environments that are directly connected to a low-voltage supply network that supplies residential buildings

Repair and service

1. The product may be opened only by authorized, specially trained personnel. Before any work is performed on the product or before the product is opened, it must be disconnected from the AC supply network. Otherwise, personnel will be exposed to the risk of an electric shock.
2. Adjustments, replacement of parts, maintenance and repair may be performed only by electrical experts authorized by Rohde & Schwarz. Only original parts may be used for replacing parts relevant to safety (e.g. power switches, power transformers, fuses). A safety test must always be performed after parts relevant to safety have been replaced (visual inspection, protective conductor test, insulation resistance measurement, leakage current measurement, functional test). This helps ensure the continued safety of the product.

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Batteries and rechargeable batteries/cells

If the information regarding batteries and rechargeable batteries/cells is not observed either at all or to the extent necessary, product users may be exposed to the risk of explosions, fire and/or serious personal injury, and, in some cases, death. Batteries and rechargeable batteries with alkaline electrolytes (e.g. lithium cells) must be handled in accordance with the EN 62133 standard.

1. Cells must not be taken apart or crushed.
2. Cells or batteries must not be exposed to heat or fire. Storage in direct sunlight must be avoided. Keep cells and batteries clean and dry. Clean soiled connectors using a dry, clean cloth.
3. Cells or batteries must not be short-circuited. Cells or batteries must not be stored in a box or in a drawer where they can short-circuit each other, or where they can be short-circuited by other conductive materials. Cells and batteries must not be removed from their original packaging until they are ready to be used.
4. Cells and batteries must not be exposed to any mechanical shocks that are stronger than permitted.
5. If a cell develops a leak, the fluid must not be allowed to come into contact with the skin or eyes. If contact occurs, wash the affected area with plenty of water and seek medical aid.
6. Improperly replacing or charging cells or batteries that contain alkaline electrolytes (e.g. lithium cells) can cause explosions. Replace cells or batteries only with the matching Rohde & Schwarz type (see parts list) in order to ensure the safety of the product.
7. Cells and batteries must be recycled and kept separate from residual waste. Rechargeable batteries and normal batteries that contain lead, mercury or cadmium are hazardous waste. Observe the national regulations regarding waste disposal and recycling.

Transport

1. The product may be very heavy. Therefore, the product must be handled with care. In some cases, the user may require a suitable means of lifting or moving the product (e.g. with a lift-truck) to avoid back or other physical injuries.
2. Handles on the products are designed exclusively to enable personnel to transport the product. It is therefore not permissible to use handles to fasten the product to or on transport equipment such as cranes, fork lifts, wagons,

Basic Safety Instructions

etc. The user is responsible for securely fastening the products to or on the means of transport or lifting. Observe the safety regulations of the manufacturer of the means of transport or lifting. Noncompliance can result in personal injury or material damage.

3. If you use the product in a vehicle, it is the sole responsibility of the driver to drive the vehicle safely and properly. The manufacturer assumes no responsibility for accidents or collisions. Never use the product in a moving vehicle if doing so could distract the driver of the vehicle. Adequately secure the product in the vehicle to prevent injuries or other damage in the event of an accident.

Waste disposal/Environmental protection

1. Specially marked equipment has a battery or accumulator that must not be disposed of with unsorted municipal waste, but must be collected separately. It may only be disposed of at a suitable collection point or via a Rohde & Schwarz customer service center.
2. Waste electrical and electronic equipment must not be disposed of with unsorted municipal waste, but must be collected separately. Rohde & Schwarz GmbH & Co. KG has developed a disposal concept and takes full responsibility for take-back obligations and disposal obligations for manufacturers within the EU. Contact your Rohde & Schwarz customer service center for environmentally responsible disposal of the product.
3. If products or their components are mechanically and/or thermally processed in a manner that goes beyond their intended use, hazardous substances (heavy-metal dust such as lead, beryllium, nickel) may be released. For this reason, the product may only be disassembled by specially trained personnel. Improper disassembly may be hazardous to your health. National waste disposal regulations must be observed.
4. If handling the product releases hazardous substances or fuels that must be disposed of in a special way, e.g. coolants or engine oils that must be replenished regularly, the safety instructions of the manufacturer of the hazardous substances or fuels and the applicable regional waste disposal regulations must be observed. Also observe the relevant safety instructions in the product documentation. The improper disposal of hazardous substances or fuels can cause health problems and lead to environmental damage.

For additional information about environmental protection, visit the Rohde & Schwarz website.

Instrucciones de seguridad elementales

¡Es imprescindible leer y cumplir las siguientes instrucciones e informaciones de seguridad!

El principio del grupo de empresas Rohde & Schwarz consiste en tener nuestros productos siempre al día con los estándares de seguridad y de ofrecer a nuestros clientes el máximo grado de seguridad. Nuestros productos y todos los equipos adicionales son siempre fabricados y examinados según las normas de seguridad vigentes. Nuestro sistema de garantía de calidad controla constantemente que sean cumplidas estas normas. El presente producto ha sido fabricado y examinado según el certificado de conformidad de la UE y ha salido de nuestra planta en estado impecable según los estándares técnicos de seguridad. Para poder preservar este estado y garantizar un funcionamiento libre de peligros, el usuario deberá atenerse a todas las indicaciones, informaciones de seguridad y notas de alerta. El grupo de empresas Rohde & Schwarz está siempre a su disposición en caso de que tengan preguntas referentes a estas informaciones de seguridad.

Además queda en la responsabilidad del usuario utilizar el producto en la forma debida. Este producto está destinado exclusivamente al uso en la industria y el laboratorio o, si ha sido expresamente autorizado, para aplicaciones de campo y de ninguna manera deberá ser utilizado de modo que alguna persona/cosa pueda sufrir daño. El uso del producto fuera de sus fines definidos o sin tener en cuenta las instrucciones del fabricante queda en la responsabilidad del usuario. El fabricante no se hace en ninguna forma responsable de consecuencias a causa del mal uso del producto.









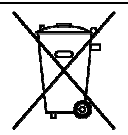
Se parte del uso correcto del producto para los fines definidos si el producto es utilizado conforme a las indicaciones de la correspondiente documentación del producto y dentro del margen de rendimiento definido (ver hoja de datos, documentación, informaciones de seguridad que siguen). El uso del producto hace necesarios conocimientos técnicos y ciertos conocimientos del idioma inglés. Por eso se debe tener en cuenta que el producto solo pueda ser operado por personal especializado o personas instruidas en profundidad con las capacidades correspondientes. Si fuera necesaria indumentaria de seguridad para el uso de productos de Rohde & Schwarz, encontraría la información debida en la documentación del producto en el capítulo correspondiente. Guarde bien las informaciones de seguridad elementales, así como la documentación del producto, y entréguelas a usuarios posteriores.

Instrucciones de seguridad elementales


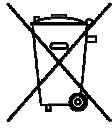


Tener en cuenta las informaciones de seguridad sirve para evitar en lo posible lesiones o daños por peligros de toda clase. Por eso es imprescindible leer detalladamente y comprender por completo las siguientes informaciones de seguridad antes de usar el producto, y respetarlas durante el uso del producto. Deberán tenerse en cuenta todas las demás informaciones de seguridad, como p. ej. las referentes a la protección de personas, que encontrarán en el capítulo correspondiente de la documentación del producto y que también son de obligado cumplimiento. En las presentes informaciones de seguridad se recogen todos los objetos que distribuye el grupo de empresas Rohde & Schwarz bajo la denominación de "producto", entre ellos también aparatos, instalaciones así como toda clase de accesorios. Los datos específicos del producto figuran en la hoja de datos y en la documentación del producto.

Señalización de seguridad de los productos

Las siguientes señales de seguridad se utilizan en los productos para advertir sobre riesgos y peligros.

Símbolo	Significado	Símbolo	Significado
	Aviso: punto de peligro general Observar la documentación del producto	○	Tensión de alimentación de PUESTA EN MARCHA / PARADA
	Atención en el manejo de dispositivos de peso elevado	⏻	Indicación de estado de espera (standby)
	Peligro de choque eléctrico	— — —	Corriente continua (DC)
	Advertencia: superficie caliente	~	Corriente alterna (AC)
	Conexión a conductor de protección	⎓	Corriente continua / Corriente alterna (DC/AC)
	Conexión a tierra		El aparato está protegido en su totalidad por un aislamiento doble (reforzado)
	Conexión a masa		Distintivo de la UE para baterías y acumuladores Más información en la sección "Eliminación/protección del medio ambiente", punto 1.

Instrucciones de seguridad elementales

Símbolo	Significado	Símbolo	Significado
	Aviso: Cuidado en el manejo de dispositivos sensibles a la electrostática (ESD)	 	Distintivo de la UE para la eliminación por separado de dispositivos eléctricos y electrónicos Más información en la sección "Eliminación/protección del medio ambiente", punto 2.
	Advertencia: rayo láser Más información en la sección "Funcionamiento", punto 7.		

Palabras de señal y su significado

En la documentación del producto se utilizan las siguientes palabras de señal con el fin de advertir contra riesgos y peligros.



Indica una situación de peligro que, si no se evita, causa lesiones graves o incluso la muerte.



Indica una situación de peligro que, si no se evita, puede causar lesiones graves o incluso la muerte.



Indica una situación de peligro que, si no se evita, puede causar lesiones leves o moderadas.



Indica información que se considera importante, pero no en relación con situaciones de peligro; p. ej., avisos sobre posibles daños materiales.

En la documentación del producto se emplea de forma sinónima el término CUIDADO.

Las palabras de señal corresponden a la definición habitual para aplicaciones civiles en el área económica europea. Pueden existir definiciones diferentes a esta definición en otras áreas económicas o en aplicaciones militares. Por eso se deberá tener en cuenta que las palabras de señal aquí descritas sean utilizadas siempre solamente en combinación con la correspondiente documentación del producto y solamente en combinación con el producto correspondiente. La utilización de las palabras de señal en combinación con productos o documentaciones que no les correspondan puede llevar a interpretaciones equivocadas y tener por consecuencia daños en personas u objetos.

Instrucciones de seguridad elementales

Estados operativos y posiciones de funcionamiento

El producto solamente debe ser utilizado según lo indicado por el fabricante respecto a los estados operativos y posiciones de funcionamiento sin que se obstruya la ventilación. Si no se siguen las indicaciones del fabricante, pueden producirse choques eléctricos, incendios y/o lesiones graves con posible consecuencia de muerte. En todos los trabajos deberán ser tenidas en cuenta las normas nacionales y locales de seguridad del trabajo y de prevención de accidentes.

1. Si no se convino de otra manera, es para los productos Rohde & Schwarz válido lo que sigue:
como posición de funcionamiento se define por principio la posición con el suelo de la caja para abajo, modo de protección IP 2X, uso solamente en estancias interiores, utilización hasta 2000 m sobre el nivel del mar, transporte hasta 4500 m sobre el nivel del mar. Se aplicará una tolerancia de $\pm 10\%$ sobre el voltaje nominal y de $\pm 5\%$ sobre la frecuencia nominal. Categoría de sobrecarga eléctrica 2, índice de suciedad 2.
2. No sitúe el producto encima de superficies, vehículos, estantes o mesas, que por sus características de peso o de estabilidad no sean aptos para él. Siga siempre las instrucciones de instalación del fabricante cuando instale y asegure el producto en objetos o estructuras (p. ej. paredes y estantes). Si se realiza la instalación de modo distinto al indicado en la documentación del producto, se pueden causar lesiones o, en determinadas circunstancias, incluso la muerte.
3. No ponga el producto sobre aparatos que generen calor (p. ej. radiadores o calefactores). La temperatura ambiente no debe superar la temperatura máxima especificada en la documentación del producto o en la hoja de datos. En caso de sobrecalentamiento del producto, pueden producirse choques eléctricos, incendios y/o lesiones graves con posible consecuencia de muerte.

Seguridad eléctrica

Si no se siguen (o se siguen de modo insuficiente) las indicaciones del fabricante en cuanto a seguridad eléctrica, pueden producirse choques eléctricos, incendios y/o lesiones graves con posible consecuencia de muerte.

1. Antes de la puesta en marcha del producto se deberá comprobar siempre que la tensión preseleccionada en el producto coincida con la de la red de alimentación eléctrica. Si es necesario modificar el ajuste de tensión, también se deberán cambiar en caso dado los fusibles correspondientes del producto.

Instrucciones de seguridad elementales

2. Los productos de la clase de protección I con alimentación móvil y enchufe individual solamente podrán enchufarse a tomas de corriente con contacto de seguridad y con conductor de protección conectado.
3. Queda prohibida la interrupción intencionada del conductor de protección, tanto en la toma de corriente como en el mismo producto. La interrupción puede tener como consecuencia el riesgo de que el producto sea fuente de choques eléctricos. Si se utilizan cables alargadores o regletas de enchufe, deberá garantizarse la realización de un examen regular de los mismos en cuanto a su estado técnico de seguridad.
4. Si el producto no está equipado con un interruptor para desconectarlo de la red, o bien si el interruptor existente no resulta apropiado para la desconexión de la red, el enchufe del cable de conexión se deberá considerar como un dispositivo de desconexión.
El dispositivo de desconexión se debe poder alcanzar fácilmente y debe estar siempre bien accesible. Si, p. ej., el enchufe de conexión a la red es el dispositivo de desconexión, la longitud del cable de conexión no debe superar 3 m).
Los interruptores selectores o electrónicos no son aptos para el corte de la red eléctrica. Si se integran productos sin interruptor en bastidores o instalaciones, se deberá colocar el interruptor en el nivel de la instalación.
5. No utilice nunca el producto si está dañado el cable de conexión a red.
Compruebe regularmente el correcto estado de los cables de conexión a red. Asegúrese, mediante las medidas de protección y de instalación adecuadas, de que el cable de conexión a red no pueda ser dañado o de que nadie pueda ser dañado por él, p. ej. al tropezar o por un choque eléctrico.
6. Solamente está permitido el funcionamiento en redes de alimentación TN/TT aseguradas con fusibles de 16 A como máximo (utilización de fusibles de mayor amperaje solo previa consulta con el grupo de empresas Rohde & Schwarz).
7. Nunca conecte el enchufe en tomas de corriente sucias o llenas de polvo. Introduzca el enchufe por completo y fuertemente en la toma de corriente. La no observación de estas medidas puede provocar chispas, fuego y/o lesiones.
8. No sobrecargue las tomas de corriente, los cables alargadores o las regletas de enchufe ya que esto podría causar fuego o choques eléctricos.
9. En las mediciones en circuitos de corriente con una tensión $U_{\text{eff}} > 30 \text{ V}$ se deberán tomar las medidas apropiadas para impedir cualquier peligro (p. ej. medios de medición adecuados, seguros, limitación de tensión, corte protector, aislamiento etc.).

Instrucciones de seguridad elementales

10. Para la conexión con dispositivos informáticos como un PC o un ordenador industrial, debe comprobarse que éstos cumplan los estándares IEC60950-1/EN60950-1 o IEC61010-1/EN 61010-1 válidos en cada caso.
11. A menos que esté permitido expresamente, no retire nunca la tapa ni componentes de la carcasa mientras el producto esté en servicio. Esto pone a descubierto los cables y componentes eléctricos y puede causar lesiones, fuego o daños en el producto.
12. Si un producto se instala en un lugar fijo, se deberá primero conectar el conductor de protección fijo con el conductor de protección del producto antes de hacer cualquier otra conexión. La instalación y la conexión deberán ser efectuadas por un electricista especializado.
13. En el caso de dispositivos fijos que no estén provistos de fusibles, interruptor automático ni otros mecanismos de seguridad similares, el circuito de alimentación debe estar protegido de modo que todas las personas que puedan acceder al producto, así como el producto mismo, estén a salvo de posibles daños.
14. Todo producto debe estar protegido contra sobretensión (debida p. ej. a una caída del rayo) mediante los correspondientes sistemas de protección. Si no, el personal que lo utilice quedará expuesto al peligro de choque eléctrico.
15. No debe introducirse en los orificios de la caja del aparato ningún objeto que no esté destinado a ello. Esto puede producir cortocircuitos en el producto y/o puede causar choques eléctricos, fuego o lesiones.
16. Salvo indicación contraria, los productos no están impermeabilizados (ver también el capítulo "Estados operativos y posiciones de funcionamiento", punto 1). Por eso es necesario tomar las medidas necesarias para evitar la entrada de líquidos. En caso contrario, existe peligro de choque eléctrico para el usuario o de daños en el producto, que también pueden redundar en peligro para las personas.
17. No utilice el producto en condiciones en las que pueda producirse o ya se hayan producido condensaciones sobre el producto o en el interior de éste, como p. ej. al desplazarlo de un lugar frío a otro caliente. La entrada de agua aumenta el riesgo de choque eléctrico.
18. Antes de la limpieza, desconecte por completo el producto de la alimentación de tensión (p. ej. red de alimentación o batería). Realice la limpieza de los aparatos con un paño suave, que no se deshilache. No utilice bajo ningún concepto productos de limpieza químicos como alcohol, acetona o diluyentes para lacas nitrocelulósicas.

Instrucciones de seguridad elementales

Funcionamiento

1. El uso del producto requiere instrucciones especiales y una alta concentración durante el manejo. Debe asegurarse que las personas que manejen el producto estén a la altura de los requerimientos necesarios en cuanto a aptitudes físicas, psíquicas y emocionales, ya que de otra manera no se pueden excluir lesiones o daños de objetos. El empresario u operador es responsable de seleccionar el personal usuario apto para el manejo del producto.
2. Antes de desplazar o transportar el producto, lea y tenga en cuenta el capítulo "Transporte".
3. Como con todo producto de fabricación industrial no puede quedar excluida en general la posibilidad de que se produzcan alergias provocadas por algunos materiales empleados —los llamados alérgenos (p. ej. el níquel)—. Si durante el manejo de productos Rohde & Schwarz se producen reacciones alérgicas, como p. ej. irritaciones cutáneas, estornudos continuos, enrojecimiento de la conjuntiva o dificultades respiratorias, debe avisarse inmediatamente a un médico para investigar las causas y evitar cualquier molestia o daño a la salud.
4. Antes de la manipulación mecánica y/o térmica o el desmontaje del producto, debe tenerse en cuenta imprescindiblemente el capítulo "Eliminación/protección del medio ambiente", punto 1.
5. Ciertos productos, como p. ej. las instalaciones de radiocomunicación RF, pueden a causa de su función natural, emitir una radiación electromagnética aumentada. Deben tomarse todas las medidas necesarias para la protección de las mujeres embarazadas. También las personas con marcapasos pueden correr peligro a causa de la radiación electromagnética. El empresario/operador tiene la obligación de evaluar y señalar las áreas de trabajo en las que exista un riesgo elevado de exposición a radiaciones.
6. Tenga en cuenta que en caso de incendio pueden desprenderse del producto sustancias tóxicas (gases, líquidos etc.) que pueden generar daños a la salud. Por eso, en caso de incendio deben usarse medidas adecuadas, como p. ej. máscaras antigás e indumentaria de protección.

Instrucciones de seguridad elementales

7. Los productos con láser están provistos de indicaciones de advertencia normalizadas en función de la clase de láser del que se trate. Los rayos láser pueden provocar daños de tipo biológico a causa de las propiedades de su radiación y debido a su concentración extrema de potencia electromagnética. En caso de que un producto Rohde & Schwarz contenga un producto láser (p. ej. un lector de CD/DVD), no debe usarse ninguna otra configuración o función aparte de las descritas en la documentación del producto, a fin de evitar lesiones (p. ej. debidas a irradiación láser).
8. Clases de compatibilidad electromagnética (conforme a EN 55011 / CISPR 11; y en analogía con EN 55022 / CISPR 22, EN 55032 / CISPR 32)
 - Aparato de clase A:
Aparato adecuado para su uso en todos los entornos excepto en los residenciales y en aquellos conectados directamente a una red de distribución de baja tensión que suministra corriente a edificios residenciales.
Nota: Los aparatos de clase A están destinados al uso en entornos industriales. Estos aparatos pueden causar perturbaciones radioeléctricas en entornos residenciales debido a posibles perturbaciones guiadas o radiadas. En este caso, se le podrá solicitar al operador que tome las medidas adecuadas para eliminar estas perturbaciones.
 - Aparato de clase B:
Aparato adecuado para su uso en entornos residenciales, así como en aquellos conectados directamente a una red de distribución de baja tensión que suministra corriente a edificios residenciales.

Reparación y mantenimiento

1. El producto solamente debe ser abierto por personal especializado con autorización para ello. Antes de manipular el producto o abrirlo, es obligatorio desconectarlo de la tensión de alimentación, para evitar toda posibilidad de choque eléctrico.
2. El ajuste, el cambio de partes, el mantenimiento y la reparación deberán ser efectuadas solamente por electricistas autorizados por Rohde & Schwarz. Si se reponen partes con importancia para los aspectos de seguridad (p. ej. el enchufe, los transformadores o los fusibles), solamente podrán ser sustituidos por partes originales. Después de cada cambio de partes relevantes para la seguridad deberá realizarse un control de seguridad (control a primera vista, control del conductor de protección, medición de resistencia de aislamiento, medición de la corriente de fuga, control de funcionamiento). Con esto queda garantizada la seguridad del producto.

Instrucciones de seguridad elementales

Baterías y acumuladores o celdas

Si no se siguen (o se siguen de modo insuficiente) las indicaciones en cuanto a las baterías y acumuladores o celdas, pueden producirse explosiones, incendios y/o lesiones graves con posible consecuencia de muerte. El manejo de baterías y acumuladores con electrolitos alcalinos (p. ej. celdas de litio) debe seguir el estándar EN 62133.

1. No deben desmontarse, abrirse ni triturarse las celdas.
2. Las celdas o baterías no deben someterse a calor ni fuego. Debe evitarse el almacenamiento a la luz directa del sol. Las celdas y baterías deben mantenerse limpias y secas. Limpiar las conexiones sucias con un paño seco y limpio.
3. Las celdas o baterías no deben cortocircuitarse. Es peligroso almacenar las celdas o baterías en estuches o cajones en cuyo interior puedan cortocircuitarse por contacto recíproco o por contacto con otros materiales conductores. No deben extraerse las celdas o baterías de sus embalajes originales hasta el momento en que vayan a utilizarse.
4. Las celdas o baterías no deben someterse a impactos mecánicos fuertes indebidos.
5. En caso de falta de estanqueidad de una celda, el líquido vertido no debe entrar en contacto con la piel ni los ojos. Si se produce contacto, lavar con agua abundante la zona afectada y avisar a un médico.
6. En caso de cambio o recarga inadecuados, las celdas o baterías que contienen electrolitos alcalinos (p. ej. las celdas de litio) pueden explotar. Para garantizar la seguridad del producto, las celdas o baterías solo deben ser sustituidas por el tipo Rohde & Schwarz correspondiente (ver lista de recambios).
7. Las baterías y celdas deben reciclarse y no deben tirarse a la basura doméstica. Las baterías o acumuladores que contienen plomo, mercurio o cadmio deben tratarse como residuos especiales. Respete en esta relación las normas nacionales de eliminación y reciclaje.

Transporte

1. El producto puede tener un peso elevado. Por eso es necesario desplazarlo o transportarlo con precaución y, si es necesario, usando un sistema de elevación adecuado (p. ej. una carretilla elevadora), a fin de evitar lesiones en la espalda u otros daños personales.

Instrucciones de seguridad elementales

2. Las asas instaladas en los productos sirven solamente de ayuda para el transporte del producto por personas. Por eso no está permitido utilizar las asas para la sujeción en o sobre medios de transporte como p. ej. grúas, carretillas elevadoras de horquilla, carros etc. Es responsabilidad suya fijar los productos de manera segura a los medios de transporte o elevación. Para evitar daños personales o daños en el producto, siga las instrucciones de seguridad del fabricante del medio de transporte o elevación utilizado.
3. Si se utiliza el producto dentro de un vehículo, recae de manera exclusiva en el conductor la responsabilidad de conducir el vehículo de manera segura y adecuada. El fabricante no asumirá ninguna responsabilidad por accidentes o colisiones. No utilice nunca el producto dentro de un vehículo en movimiento si esto pudiera distraer al conductor. Asegure el producto dentro del vehículo debidamente para evitar, en caso de un accidente, lesiones u otra clase de daños.

Eliminación/protección del medio ambiente

1. Los dispositivos marcados contienen una batería o un acumulador que no se debe desechar con los residuos domésticos sin clasificar, sino que debe ser recogido por separado. La eliminación se debe efectuar exclusivamente a través de un punto de recogida apropiado o del servicio de atención al cliente de Rohde & Schwarz.
2. Los dispositivos eléctricos usados no se deben desechar con los residuos domésticos sin clasificar, sino que deben ser recogidos por separado. Rohde & Schwarz GmbH & Co.KG ha elaborado un concepto de eliminación de residuos y asume plenamente los deberes de recogida y eliminación para los fabricantes dentro de la UE. Para desechar el producto de manera respetuosa con el medio ambiente, diríjase a su servicio de atención al cliente de Rohde & Schwarz.
3. Si se trabaja de manera mecánica y/o térmica cualquier producto o componente más allá del funcionamiento previsto, pueden liberarse sustancias peligrosas (polvos con contenido de metales pesados como p. ej. plomo, berilio o níquel). Por eso el producto solo debe ser desmontado por personal especializado con formación adecuada. Un desmontaje inadecuado puede ocasionar daños para la salud. Se deben tener en cuenta las directivas nacionales referentes a la eliminación de residuos.

Instrucciones de seguridad elementales

4. En caso de que durante el trato del producto se formen sustancias peligrosas o combustibles que deban tratarse como residuos especiales (p. ej. refrigerantes o aceites de motor con intervalos de cambio definidos), deben tenerse en cuenta las indicaciones de seguridad del fabricante de dichas sustancias y las normas regionales de eliminación de residuos. Tenga en cuenta también en caso necesario las indicaciones de seguridad especiales contenidas en la documentación del producto. La eliminación incorrecta de sustancias peligrosas o combustibles puede causar daños a la salud o daños al medio ambiente.

Se puede encontrar más información sobre la protección del medio ambiente en la página web de Rohde & Schwarz.

Quality management and environmental management

Certified Quality System
ISO 9001

Certified Environmental System
ISO 14001

Sehr geehrter Kunde,

Sie haben sich für den Kauf eines Rohde&Schwarz-Produktes entschieden. Sie erhalten damit ein nach modernsten Fertigungsmethoden hergestelltes Produkt. Es wurde nach den Regeln unserer Qualitäts- und Umweltmanagementsysteme entwickelt, gefertigt und geprüft. Rohde&Schwarz ist unter anderem nach den Managementsystemen ISO 9001 und ISO 14001 zertifiziert.

Der Umwelt verpflichtet

- ▮ Energie-effiziente, RoHS-konforme Produkte
- ▮ Kontinuierliche Weiterentwicklung nachhaltiger Umweltkonzepte
- ▮ ISO 14001-zertifiziertes Umweltmanagementsystem

Dear customer,

You have decided to buy a Rohde&Schwarz product. This product has been manufactured using the most advanced methods. It was developed, manufactured and tested in compliance with our quality management and environmental management systems. Rohde&Schwarz has been certified, for example, according to the ISO 9001 and ISO 14001 management systems.

Environmental commitment

- ▮ Energy-efficient products
- ▮ Continuous improvement in environmental sustainability
- ▮ ISO 14001-certified environmental management system

Cher client,

Vous avez choisi d'acheter un produit Rohde&Schwarz. Vous disposez donc d'un produit fabriqué d'après les méthodes les plus avancées. Le développement, la fabrication et les tests de ce produit ont été effectués selon nos systèmes de management de qualité et de management environnemental. La société Rohde&Schwarz a été homologuée, entre autres, conformément aux systèmes de management ISO 9001 et ISO 14001.

Engagement écologique

- ▮ Produits à efficience énergétique
- ▮ Amélioration continue de la durabilité environnementale
- ▮ Système de management environnemental certifié selon ISO 14001





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Customer Support

Technical support – where and when you need it

For quick, expert help with any Rohde & Schwarz equipment, contact one of our Customer Support Centers. A team of highly qualified engineers provides telephone support and will work with you to find a solution to your query on any aspect of the operation, programming or applications of Rohde & Schwarz equipment.

Up-to-date information and upgrades

To keep your instrument up-to-date and to be informed about new application notes related to your instrument, please send an e-mail to the Customer Support Center stating your instrument and your wish.

We will take care that you will get the right information.

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1 Preface

1.1 About this Manual

This User Manual describes general instrument functions and settings common to all applications and operating modes in the R&S FPS. Furthermore, it provides all the information specific to **RF measurements in the Spectrum application**. All other operating modes and applications are described in the specific application manuals.

The main focus in this manual is on the measurement results and the tasks required to obtain them.



Manual operation

Although the R&S FPS does not have a built-in display, it is recommended that you connect an external monitor to the instrument initially to get familiar with the instrument and its manual operation before using it in pure remote mode. Thus, this manual starts with a detailed description on how to operate the instrument manually using an external monitor and mouse. The commands required for remote operation are provided as a reference at the end of this document.

The following topics are included:

- **Welcome to the R&S FPS**
Introduction to and getting familiar with the instrument
- **Operating Modes and Applications**
The concept of using multiple operating modes
- **Measurements**
Descriptions of the individual measurements in the Spectrum application, including result types and configuration settings.
- **Common Measurement Settings**
Description of the measurement settings common to all measurement types with their corresponding remote control commands
- **Common Measurement Analysis and Display Functions**
Description of the settings and functions provided to analyze results independently of the measurement type with their corresponding remote control commands
- **Data Management**
Description of general functions to handle data files (configuration and result data, not I/Q data)
- **General Instrument Setup**
Description of general instrument settings and functions that are independent of the current operating mode
- **Network and Remote Operation**
Detailed information on setting up the instrument in a network and operating it remotely.
- **Remote Commands**

Remote commands required to configure and perform measurements in a remote environment, sorted by tasks

Remote commands required to set up the environment and to perform common tasks on the instrument, sorted by tasks

Programming examples demonstrate the use of many commands and can usually be executed directly for test purposes


- **Maintenance**
Information on tasks required to maintain operability of the instrument
- **Troubleshooting**
Hints and tips on how to handle errors
- **List of Commands**
Alphabetical list of all remote commands described in the manual
- **Index**

1.2 Documentation Overview

The user documentation for the R&S FPS consists of the following parts:

- Printed Getting Started manual
- Online Help system on the instrument
- Documentation CD-ROM with:
 - Getting Started
 - User Manuals for base unit and firmware applications
 - Service Manual
 - Release Notes
 - Data sheet and product brochures

Online Help

The Online Help is embedded in the instrument's firmware. It offers quick, context-sensitive access to the complete information needed for operation and programming. Online help is available using the  icon on the toolbar of the R&S FPS.

Getting Started

This manual is delivered with the instrument in printed form and in PDF format on the CD-ROM. It provides the information needed to set up and start working with the instrument. Basic operations and handling are described. Safety information is also included.

The Getting Started manual in various languages is also available for download from the Rohde & Schwarz website, on the R&S FPS product page at <http://www.rohde-schwarz.com/product/FPS.html>.

User Manuals

User manuals are provided for the base unit and each additional (firmware) application.

The user manuals are available in PDF format - in printable form - on the Documentation CD-ROM delivered with the instrument. In the user manuals, all instrument functions are described in detail. Furthermore, they provide a complete description of the remote control commands with programming examples.

The user manual for the base unit provides basic information on operating the R&S FPS in general, and the Spectrum application in particular. Furthermore, the software functions that enhance the basic functionality for various applications are described here. An introduction to remote control is provided, as well as information on maintenance, instrument interfaces and troubleshooting.

In the individual application manuals, the specific instrument functions of the application are described in detail. For additional information on default settings and parameters, refer to the data sheets. Basic information on operating the R&S FPS is not included in the application manuals.

All user manuals are also available for download from the Rohde & Schwarz website, on the R&S FPS product page at <http://www2.rohde-schwarz.com/product/FPS.html>.

Service Manual

This manual is available in PDF format on the Documentation CD-ROM delivered with the instrument. It describes how to check compliance with rated specifications, instrument function, repair, troubleshooting and fault elimination. It contains all information required for repairing the R&S FPS by replacing modules.

Release Notes

The release notes describe the installation of the firmware, new and modified functions, eliminated problems, and last minute changes to the documentation. The corresponding firmware version is indicated on the title page of the release notes.

The most recent release notes are also available for download from the Rohde & Schwarz website, on the R&S FPS product page at <http://www2.rohde-schwarz.com/product/FPS.html> > Downloads > Firmware.

1.3 Typographical Conventions

The following text markers are used throughout this documentation:

Convention	Description
"Graphical user interface elements"	All names of graphical user interface elements on the screen, such as dialog boxes, menus, options, buttons, and softkeys are enclosed by quotation marks.
KEYS	Key names are written in capital letters.
File names, commands, program code	File names, commands, coding samples and screen output are distinguished by their font.
<i>Input</i>	Input to be entered by the user is displayed in italics.

Convention	Description
Links	Links that you can click are displayed in blue font.
"References"	References to other parts of the documentation are enclosed by quotation marks.

2 Welcome to the R&S FPS

The R&S FPS is a new high-performance Rohde & Schwarz signal and spectrum analyzer developed to meet demanding customer requirements. Offering low phase noise, wide analysis bandwidth and straightforward and intuitive operation, the analyzer makes measurements fast and easy.

This user manual contains a description of the functionality that the instrument provides, including remote control operation. The latest version is available for download at the product homepage (<http://www2.rohde-schwarz.com/product/FPS.html>).

3 Getting Started

Note: the following chapters are identical to those in the printed R&S FPS Getting Started manual.

- [Preparing for Use](#)..... 18
- [Instrument Tour](#).....33
- [Miniature Display](#).....39
- [Controlling the R&S FPS Remotely](#)..... 47
- [Operating the Instrument in Manual Mode](#).....70

3.1 Preparing for Use

- [Putting into Operation](#)..... 18
- [Windows Operating System](#).....23
- [Connecting USB Devices](#).....27
- [Performing a Self Alignment and a Self Test](#)..... 29
- [Checking the Supplied Options](#).....30
- [Protecting Data Using the Secure User Mode](#)..... 30

3.1.1 Putting into Operation

This section describes the basic steps to be taken when setting up the R&S FPS for the first time.

⚠ WARNING

Risk of injury and instrument damage

The instrument must be used in an appropriate manner to prevent electric shock, fire, personal injury, or damage.

- Do not open the instrument casing.
- Read and observe the "Basic Safety Instructions" at the beginning of this manual or on the documentation CD-ROM, in addition to the safety instructions in the following sections. Notice that the data sheet may specify additional operating conditions.

NOTICE

Risk of instrument damage

Note that the general safety instructions also contain information on operating conditions that will prevent damage to the instrument. The instrument's data sheet may contain additional operating conditions.

NOTICE**Risk of electrostatic discharge (ESD)**

Electrostatic discharge (ESD) can cause damage to the electronic components of the instrument and the device under test (DUT). ESD is most likely to occur when you connect or disconnect a DUT or test fixture to the instrument's test ports. To prevent ESD, use a wrist strap and cord and connect yourself to the ground, or use a conductive floor mat and heel strap combination.

For details, refer to the safety instructions delivered in electronic format on the documentation CD-ROM.

NOTICE**Risk of instrument damage during operation**

An unsuitable operating site or test setup can cause damage to the instrument and to connected devices. Ensure the following operating conditions before you switch on the instrument:

- All fan openings are unobstructed and the airflow perforations are unimpeded. The minimum distance from the wall is 10 cm.
- The instrument is dry and shows no sign of condensation.
- The instrument is positioned as described in the following sections.
- The ambient temperature does not exceed the range specified in the data sheet.
- Signal levels at the input connectors are all within the specified ranges.
- Signal outputs are correctly connected and are not overloaded.

**EMI impact on measurement results**

Electromagnetic interference (EMI) may affect the measurement results.

To suppress generated electromagnetic interference (EMI):

- Use suitable shielded cables of high quality. For example, use double-shielded RF and LAN cables.
- Always terminate open cable ends.
- Note the EMC classification in the data sheet.

• Unpacking and Checking the Instrument	19
• Accessory List	20
• Placing or Mounting the Instrument	20
• Connecting the AC Power	22
• Switching the Instrument On and Off	22

3.1.1.1 Unpacking and Checking the Instrument

Check the equipment for completeness using the delivery note and the accessory lists for the various items. Check the instrument for any damage. If there is damage, imme-

diately contact the carrier who delivered the instrument. Make sure not to discard the box and packing material.



Packing material

Retain the original packing material. If the instrument needs to be transported or shipped at a later date, you can use the material to protect the control elements and connectors.

NOTICE

Risk of damage during transportation and shipment

Insufficient protection against mechanical and electrostatic effects during transportation and shipment can damage the instrument.

- Always make sure that sufficient mechanical and electrostatic protection is provided.
- When shipping an instrument, the original packaging should be used. If you do not have the original packaging, use sufficient padding to prevent the instrument from moving around inside the box. Pack the instrument in antistatic wrap to protect it from electrostatic charging.
- Secure the instrument to prevent any movement and other mechanical effects during transportation.

The **carrying handles** at the front and side of the casing are designed to lift or carry the instrument. Do not apply an excessive external force to the handles.

Observe the information on transporting heavy instruments in the basic safety instructions included at the front of the printed manual and on the supplied CD ROM.

3.1.1.2 Accessory List

The instrument comes with the following accessories:

- Power cable
- "Getting Started" printed manual
- "R&S FPS User Documentation" CD-Rom

3.1.1.3 Placing or Mounting the Instrument

The R&S FPS is designed for use under laboratory conditions, either on a bench top or in a rack.

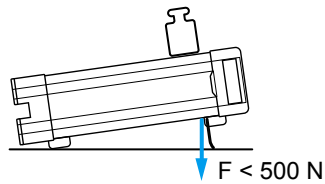
Bench Top Operation

If the R&S FPS is operated on a bench top, the surface should be flat. The instrument can be used in horizontal position, standing on its feet, or with the support feet on the bottom extended.

⚠ CAUTION**Risk of injury if feet are folded out**

The feet may fold in if they are not folded out completely or if the instrument is shifted. This may cause damage or injury.

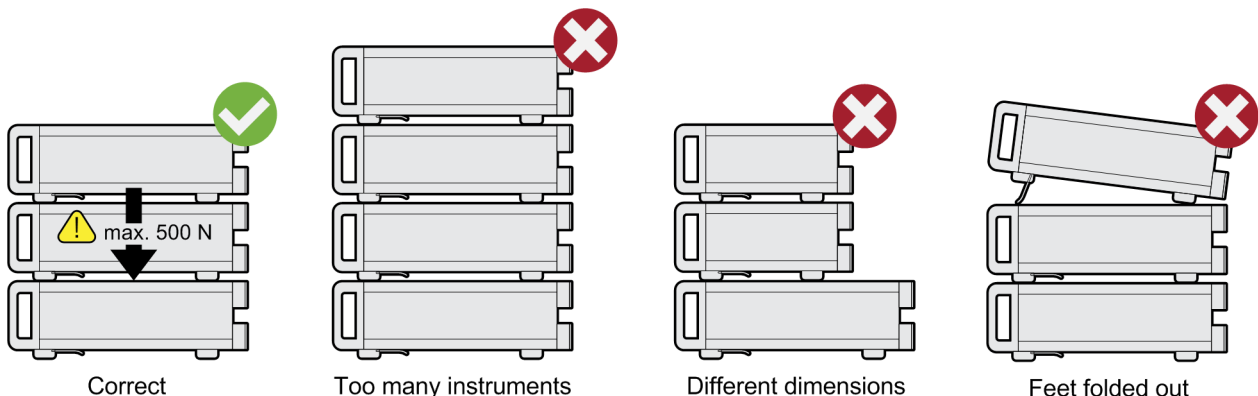
- Fold the feet completely in or completely out to ensure stability of the instrument. Never shift the instrument when the feet are folded out.
- When the feet are folded out, do not work under the instrument or place anything underneath.
- The feet can break if they are overloaded. The overall load on the folded-out feet must not exceed 500 N.

**⚠ CAUTION****Risk of injury and instrument damage if stacking instruments**

A stack of instruments may tilt over and cause injury. Furthermore, the instruments at the bottom of the stack may be damaged due to the load imposed by the instruments on top.

Observe the following instructions when stacking instruments:

- Never stack more than three instruments. If you need to stack more than three instruments, install them in a rack.
- The overall load imposed on the lowest instrument must not exceed 500 N.
- All instruments must have the same dimensions (width and length).
- If the instruments have foldable feet, fold them in completely.



Rackmounting

The R&S FPS can be installed in a rack using a rack adapter kit (Order No. see data sheet). The installation instructions are part of the adapter kit.

NOTICE

Risk of instrument damage in a rack

An insufficient airflow can cause the instrument to overheat, which may disturb the operation and even cause damage.

Make sure that all fan openings are unobstructed, that the airflow perforations are unimpeded, and that the minimum distance from the wall is 10 cm.

3.1.1.4 Connecting the AC Power

In the standard version, the R&S FPS is equipped with an AC power supply connector. The R&S FPS can be used with different AC power voltages and adapts itself automatically to it. Refer to the datasheet for the requirements of voltage and frequency. The AC power connector is located on the rear panel of the instrument.

For details on the connector refer to [chapter 3.2.2.11, "AC Power Supply Connection and Main Power Switch"](#), on page 38.



- ▶ Connect the R&S FPS to the AC power supply using the supplied power cable. Since the instrument is assembled in line with the specifications for safety class EN61010, it may only be connected to an outlet that has a ground contact.

3.1.1.5 Switching the Instrument On and Off

Switching the instrument on

- ▶ Press the AC power switch on the rear panel to position "I".
The instrument is supplied with AC power. After booting, the instrument is ready for operation. A green LED above the POWER key indicates this.



Warm-up time for OCXO

When the instrument is switched on, the OCXO requires an extended warm-up time (see data sheet). No warm-up time is required when starting from standby mode.

Switching the instrument off

1. Press the POWER key on the front panel of the R&S FPS.
2. Change the AC power switch on the rear panel to position "O", or disconnect the instrument from the AC power supply.

The R&S FPS changes into off mode.

NOTICE**Risk of losing data**

If you switch off the running instrument using the rear panel switch or by disconnecting the power cord, the instrument loses its current settings. Furthermore, program data may be lost.

Press the Power key first to shut down the application properly.

3.1.2 Windows Operating System

The instrument contains the Windows 7 operating system which has been configured according to the instrument's features and needs. Changes in the system setup are only required when peripherals like keyboard or a printer are installed or if the network configuration does not comply with the default settings. After the R&S FPS is started, the operating system boots and the instrument firmware is started automatically.

To ensure that the instrument software functions properly, certain rules must be adhered to concerning the operating system.

NOTICE**Risk of causing instrument unusability**

The instrument is equipped with the Windows 7 operating system. Additional software can therefore be installed on the instrument. The use and installation of additional software may impair instrument function. Thus, run only programs that Rohde & Schwarz has tested for compatibility with the instrument software.

The drivers and programs used on the instrument under Windows 7 have been adapted to the instrument. Existing instrument software must always be modified using only update software released by Rohde & Schwarz.

The following program packages have been tested:

- Symantec Endpoint Security – Virus-protection software
- FileShredder - for reliable deletion of files on the hard disk

**Error message display**

Note that any error messages caused by the Windows 7 operating system are only visible on an external monitor or via RemoteDesktop from a controller PC. Thus, if operation of the R&S FPS seems to fail for no obvious reason, try connecting a monitor or a controller PC to check for any messages awaiting confirmation or action.

(See [chapter 3.1.3, "Connecting USB Devices"](#), on page 27 or [chapter 3.4.6, "How to Set Up Remote Desktop"](#), on page 62)

3.1.2.1 Virus Protection

Users must take appropriate steps to protect their instruments from infection. Beside the use of strong firewall settings and regularly scanning any removable storage device used with a Rohde & Schwarz instrument, it is also recommended that anti-virus software be installed on the instrument. While Rohde & Schwarz does NOT recommend running anti-virus software in the background ("on-access" mode) on Windows-based instruments, due to potentially degrading instrument performance, it does recommend running it during non-critical hours.

For details and recommendations, see the Rohde & Schwarz White Paper "Malware Protection" available at <http://www.rohde-schwarz.com/appnote/1EF73>.

3.1.2.2 Service Packs and Updates

Microsoft regularly creates security updates and other patches to protect Windows-based operating systems. These are released through the Microsoft Update website and associated update server. Instruments using Windows, especially those that connect to a network, should be updated regularly.

For more details and information on configuring automatic updates see the R&S White Paper "Malware Protection" (available at <http://www.rohde-schwarz.com/appnote/1EF73>).

3.1.2.3 Login

Windows 7 requires that users identify themselves by entering a user name and password in a login window. By default, the R&S FPS provides two user accounts:

- **"Instrument"**: an administrator account with unrestricted access to the computer/domain
- **"NormalUser"**: a standard user account with limited access

Some administrative tasks require administrator rights (e.g. the configuration of a LAN network). Refer to the description of the basic instrument setup (SETUP menu) to find out which functions are affected.



Secure User Mode

If the secure user mode option (R&S FPS-K33) is installed, an additional account is provided: the **"SecureUser"**.

The "SecureUser" is a standard user account with limited functionality. In particular, administrative tasks such as LAN configuration or general instrument settings are not available. Furthermore, for a "SecureUser", data that the R&S FPS normally stores on the solid-state drive is redirected to volatile memory instead. Data that is stored in volatile memory can be accessed by the user during the current instrument session; however, when the instrument's power is removed, all data in volatile memory is erased.

For details see [chapter 3.1.6, "Protecting Data Using the Secure User Mode"](#), on page 30.

Automatic login

For the administrator account, an automatic login function is active by default. If activated, login is carried out automatically for the administrator (with full access) in the background when the R&S FPS is started, without having to enter a password. This function is active until you explicitly deactivate it or change the password.

For information on how to deactivate or re-activate the automatic login, refer to "[The Automatic Login Function](#)" on page 25.

Passwords

For all default user accounts, the initial password is 894129. Note that this password is very weak, and it is recommended that you change the password for both users after initial login. You can change the password in Windows 7 for any user at any time via "Start > Control Panel > User Accounts".

NOTICE

Changing the password and use of auto-login function

Note that when you change the default passwords, the default auto-login function no longer works! You must reactivate it manually as described in "[Reactivating the automatic login function](#)" on page 26.

Beware that since the R&S FPS has no real display, if the auto-login function is deactivated and the R&S FPS is rebooted, you require an external monitor and keyboard or a RemoteDesktop access to the R&S FPS to enter the password. Otherwise, the Windows operating system will not complete login and the R&S FPS remains inoperable.

The Automatic Login Function

When shipped, the instrument is already configured to automatically log on under Windows 7 using the default administrator account ("Instrument") and password.



In order to change the settings for the automatic login function for the R&S FPS, a controller PC or an external monitor and keyboard must be connected to the R&S FPS. See [chapter 3.4.6, "How to Set Up Remote Desktop"](#), on page 62.

If the auto-login function is deactivated and the R&S FPS is rebooted, you require an external monitor and keyboard or a RemoteDesktop access on the R&S FPS to enter the password. Otherwise, the Windows operating system will not complete login and the R&S FPS remains inoperable.

Deactivating the automatic login function

To deactivate the automatic login function, perform the following steps:

1. 

Select the "Windows" icon in the toolbar to access the operating system of the R&S FPS (see also [chapter 3.1.2.4, "Accessing the Start Menu"](#), on page 27).

2. In the "Start" menu, select "Run".
The "Run" dialog box is displayed.
3. Enter the command `C:\R_S\INSTR\USER\NO_AUTOLOGIN.REG`.
4. Press the ENTER key to confirm.
The automatic login function is deactivated. The next time you switch on the instrument, you are prompted to enter your user name and password (using an external monitor and keyboard or RemoteDesktop from a controller PC, not via the R&S FPS miniature display!) before the firmware is started.


Adapting the automatic login function to a new password

If you change the "Instrument" user's (administrator's) password, which is used during automatic login, this function no longer works. You must then adapt the settings for the command that activates the auto login function first.

If the SecureUser or the NormalUser are enabled, those passwords are used for auto-login. In that case, if you change any of the passwords, the autologin function must be adapted each time you change the user account.

1. Open the `C:\R_S\INSTR\USER\NO_AUTOLOGIN.REG` file in any text editor (e.g. Notepad).
2. In the line `"DefaultPassword"="894129"`, replace the default password (894129) by the new password which is to be used for automatic login.
3. Save the changes to the file.

Reactivating the automatic login function

1. 
Select the "Windows" icon in the toolbar to access the operating system of the R&S FPS.
2. In the "Start" menu, select "Run".
The "Run" dialog box is displayed.
3. Enter the command `C:\R_S\INSTR\USER\AUTOLOGIN.REG`.
4. Press the ENTER key to confirm.
The automatic login function is reactivated. It will be applied the next time the instrument is rebooted.

Switching users when using the automatic login function

Which user account is used is defined during login. However, you can also switch the user account to be used when the automatic login function is active.

1. 

Select the "Windows" icon in the toolbar to access the operating system of the R&S FPS.

2. In the "Start" menu, select the arrow next to the "Shut down" button and then "Log off".

The "Login" dialog box is displayed, in which you can enter the different user account name and password.

3.1.2.4 Accessing the Start Menu



The Windows "Start" menu provides access to the Windows 7 functionality and installed programs. To open the "Start" menu, select the "Windows" icon on the R&S FPS toolbar, or press the "Windows" key or the CTRL + ESC key combination on the (external) keyboard.

All necessary system settings can be defined in the "Start > Control Panel" menu (for required settings refer to the Windows 7 documentation and to the hardware description).

3.1.2.5 Accessing the Windows Task Bar

The Windows task bar also provides quick access to commonly used programs, for example Paint or Wordpad, but also IECWIN, the auxiliary remote control tool provided free of charge and installed by Rohde & Schwarz.



For details on the IECWIN tool, see the "Network and Remote Control" chapter of the R&S FPS User Manual.



To open the task bar, select the "Windows" icon on the R&S FPS toolbar, or press the "Windows" key or the CTRL + ESC key combination on your (external) keyboard.

3.1.3 Connecting USB Devices

The USB interfaces on the front and (optionally) rear panels of the R&S FPS allow you to connect USB devices directly to the instrument. This number can be increased as necessary by using USB hubs. Due to the large number of available USB devices, there is almost no limit to the expansions that are possible with the R&S FPS.

The following list shows various USB devices that can be useful:

- Memory stick for easy transfer of data to/from a computer (e.g. firmware updates)
- CD-ROM drives for easy installation of firmware applications
- Keyboard or mouse to simplify the entry of data, comments, file names, etc.
- Printer for printing out measurement results

Installing USB devices is easy under Windows, because all USB devices are plug&play. After a device is connected to the USB interface, automatically searches for a suitable device driver.

If Windows does not find a suitable driver, it will prompt you to specify a directory that contains the driver software. If the driver software is on a CD, connect a USB CD-ROM drive to the instrument before proceeding.

When a USB device is subsequently disconnected from the R&S FPS, Windows immediately detects the change in hardware configuration and deactivates the corresponding driver.

All USB devices can be connected to or disconnected from the instrument during operation.

Connecting a memory stick or CD-ROM drive

If installation of a memory stick or CD-ROM drive is successful, Windows informs you that the device is ready to use. The device is made available as a new drive and is displayed in Windows Explorer. The name of the drive depends on the manufacturer.

Connecting a keyboard

The keyboard is detected automatically when it is connected. The default input language is English – US.

Select "Start > Control Panel > Clock, Language, and Region > Change keyboards or other input methods" to configure the keyboard properties. To access the Windows operating system, press the Windows key on the external keyboard.

Connecting a mouse

The mouse is detected automatically when it is connected.

Select "Start > Control Panel > Devices and Printers > Mouse" to configure the mouse properties. To access the Windows operating system, press the Windows key on the external keyboard.

Connecting a printer

When printing a file, the instrument checks whether a printer is connected and turned on and whether the appropriate printer driver is installed. If required, printer driver installation is initiated. A printer driver needs to be installed only once.

To install a printer, select "Start > Control Panel > Devices and Printers > Add a printer". To access the Windows operating system, press the Windows key on the external keyboard.

You can load updated and improved driver versions or new drivers from an installation disk, USB memory stick or another external storage medium. If the instrument is integrated in a network, you can also install driver data stored in a network directory.

Select "Start > Control Panel > Devices and Printers > Device Manager > Update Device drivers" to install the driver.

3.1.4 Performing a Self Alignment and a Self Test



During instrument start, the installed hardware is checked against the current firmware version to ensure the hardware is supported. If not, an error message is displayed ("WRONG_FW") and you are asked to update the firmware. Until the firmware version is updated, self-alignment fails.

(For details refer to the R&S FPS User Manual).

Furthermore, it may be necessary to align the data to a reference source by performing a self alignment when strong temperature changes occur.



Operating temperature

Before performing this functional test, make sure that the instrument has reached its operating temperature (for details, refer to the data sheet).

To perform a self alignment directly on the R&S FPS

- ▶ In the R&S FPS's mini display, navigate to "System commands" > "Self align". For details on working with the mini display, see [chapter 3.3, "Miniature Display"](#), on page 39.

To perform a self alignment via Remote Desktop

Performing a self alignment via Remote Desktop requires a controller PC to be connected, see [chapter 3.4.6, "How to Set Up Remote Desktop"](#), on page 62.

1. Select the SETUP key in the soft front panel on the Remote Desktop.
2. Select the "Alignment" softkey.
3. Select the "Start Self Alignment" button in the "Alignment" dialog box.

Once the system correction values have been calculated successfully, a message is displayed.



To display the alignment results again later

- Select the SETUP key in the soft front panel on the Remote Desktop.
- Select the "Alignment" softkey.

Self tests

The self test does not need to be repeated every time the instrument is switched on. It is only necessary when instrument malfunction is suspected.

To perform a self test directly on the R&S FPS

- ▶ In the R&S FPS's mini display, navigate to "System commands" > "Selftest".

For details on working with the mini display, see [chapter 3.3, "Miniature Display"](#), on page 39.

To perform a self test via Remote Desktop

Performing a self alignment via Remote Desktop requires a controller PC to be connected, see [chapter 3.4.6, "How to Set Up Remote Desktop"](#), on page 62.

1. Select the SETUP key in the soft front panel on the Remote Desktop.
2. Select the "Service" softkey.
3. Switch to the "Selftest" tab in the "Service" dialog box.
4. Select the "Start Selftest" button.

Once the instrument modules have been checked successfully, a message is displayed.

3.1.5 Checking the Supplied Options

The instrument may be equipped with both hardware and firmware options. In order to check whether the installed options correspond to the options indicated on the delivery note, proceed as follows.

Checking the supplied options via Remote Desktop requires a controller pc or an external monitor, mouse and keyboard to be connected, see [chapter 3.4.6, "How to Set Up Remote Desktop"](#), on page 62.

1. Select the SETUP key in the soft front panel on the Remote Desktop.
2. Select the "System Config" softkey.
3. Switch to the "Versions + Options" tab in the "System Configuration" dialog box.
A list with hardware and firmware information is displayed.
4. Check the availability of the hardware options as indicated in the delivery note.

3.1.6 Protecting Data Using the Secure User Mode

During normal operation, the R&S FPS uses a solid-state drive to store its operating system, instrument firmware, instrument self-alignment data, and any user data created during operation. If necessary, the solid-state drive can be removed from the R&S FPS and locked in a secure place to protect any classified data it may contain.

Redirecting storage to volatile memory

Alternatively, to avoid storing any sensitive data on the R&S FPS permanently, the *secure user mode* was introduced (option R&S FPS-K33). In secure user mode the instrument's solid-state drive is write-protected so that no information can be written to memory permanently. Data that the R&S FPS normally stores on the solid-state drive

is redirected to volatile memory instead, which remains available only until the instrument is switched off. This data includes:

- Windows 7 operating system files
- Firmware shutdown files containing information on last instrument state
- Self-alignment data
- General instrument settings such as the IP address
- Measurement settings
- User data created during operation (see also [table 8-2](#))
- Any data created by other applications installed on the R&S FPS, for example text editors (Notepad), the Clipboard, drawing tools etc.

Data that is stored in volatile memory can be accessed by the user just as in normal operation; however, when the instrument's power is switched off, all data in this memory is cleared. Thus, in secure user mode, the instrument always starts in a defined, fixed state when switched on.

In order to store data such as measurement results permanently, it must be stored to an external storage device, such as a memory stick.



Limited storage space

The volatile memory used to store data in secure user mode is restricted to 256 MB. Thus, a "Memory full" error may occur although the hard disk indicates that storage space is still available.

Storing required data permanently

Any data that is to be available for subsequent sessions with the R&S FPS, such as predefined instrument settings, transducer factors or self-alignment data, must be stored on the instrument permanently, *prior to activating the secure user mode*.



Self-alignment data

Note that self-alignment data becomes invalid with time and due to temperature changes. Therefore, to achieve optimal accuracy, it may be preferable to perform a new self-alignment at the start of each new session on the R&S FPS.

Restricted operation

Due to the fact that permanent storage is not possible, the following functions are not available in secure user mode:

- Firmware update
- Activating a new option key

Furthermore, since the "SecureUser" used in secure user mode does not have administrator rights, **administrative tasks** such as LAN configuration and some general instrument settings are not available. Refer to the description of the basic instrument setup (SETUP menu) to find out which functions are affected.



RemoteDesktop restricted for "SecureUser" by default

For security reasons, the "SecureUser" is not allowed Remote Desktop access to the R&S FPS by default. You must explicitly add the "SecureUser" to the Remote Desktop group (see [chapter 3.4.6.5, "How to Add or Remove Users to the Remote Desktop Users Group"](#), on page 67). If you do not allow this user RemoteDesktop access, the "SecureUser" will only be able to operate the R&S FPS using remote commands or via the miniature display.

Activating and deactivating secure user mode

Only a user with administrator rights can activate (and deactivate) the secure user mode. Once activated, a restart is required. The special user "SecureUser" is then logged on to the R&S FPS automatically (using the automatic login function, see ["The Automatic Login Function"](#) on page 25). While the secure user mode is active, a message is displayed in the status bar at the bottom of the screen, and in the miniature display "SecUsr" is displayed.

In order to deactivate the secure user mode, the "SecureUser" must log off and the "Instrument" user (administrator) must log on.



Switching users when using the automatic login function

In the "Start" menu, select the arrow next to the "Shut down" button and then "Log off". The "Login" dialog box is displayed, in which you can enter the different user account name and password.

The secure user mode setting and automatic login is automatically deactivated when the "Instrument" user logs on. The "SecureUser" is no longer available.

For administrators ("Instrument" user), the secure user mode setting is available in the general system configuration settings (see [chapter 9.3.4.5, "General Configuration Settings"](#), on page 520).

Alternatively, you can activate or deactivate the secure user function via the miniature display (see ["Enable SecureUser / Disable SecureUser"](#) on page 43. In this case, you must enter the administrator ("Instrument" user) password.

Remote control

Initially after installation of the R&S FPS-K33 option, secure user mode must be enabled manually once before remote control is possible.

(See `SYSTEM:SECurity[:STATe].`)

3.2 Instrument Tour

3.2.1 Front Panel View

This chapter describes the front panel, including all function keys and connectors.

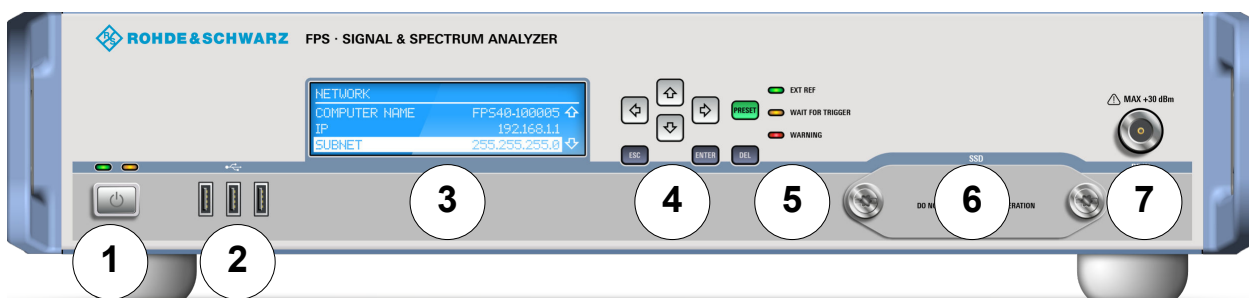


Fig. 3-1: Front panel view

- 1 = On/Off button
- 2 = USB connectors
- 3 = Mini display
- 4 = Navigation and data input controls
- 5 = Status LEDs
- 6 = Solid State Disk (SSD) containing instrument firmware
- 7 = RF Input 50 Ω connector (optionally front or rear panel)

NOTICE

Instrument damage caused by cleaning agents

Cleaning agents contain substances that may damage the instrument. For example, cleaning agents that contain a solvent may damage the front panel labeling, plastic parts, or the display.

Never use cleaning agents such as solvents (thinners, acetone, etc), acids, bases, or other substances.

The outside of the instrument can be cleaned sufficiently using a soft, lint-free dust cloth.

On / off button

The POWER key is located on the lower left corner of the front panel. It starts up and shuts down the instrument.

See also [chapter 3.1.1.5, "Switching the Instrument On and Off"](#), on page 22.

Mini display



The R&S FPS is equipped with a miniature display on the front panel that provides basic information and allows for very basic instrument configuration (such as changing the IP address). For details see [chapter 3.3, "Miniature Display"](#), on page 39.

USB

The front panel provides three female USB connectors (USB-A) to connect devices like an external monitor, a mouse (recommended: R&S PSL-Z10, order number 1157.7060.03) or a keyboard (recommended: R&S PSL-Z2, order number 1157.6870.03). In addition, a memory stick can be connected to store and reload instrument settings and measurement data.



The rear panel provides further USB connectors, including a male (USB-B) connector. See [chapter 3.2.2.10, "USB"](#), on page 38.

Navigation Keys

The navigation keys can be used to navigate through menus or entries in the display.

Data Input Controls

Type of key	Description
ESC key	Exits the current function without storing changes
ENTER key	Stores the current entry and closes the edit mode
DEL key	Deletes the character to the left of the cursor

Status LEDs

Indicate the instrument's operating status:

Table 3-1: Status LEDs

Label	Description
EXT REF	External reference connected and active
WAIT FOR TRIGGER	Measurement waiting for trigger
WARNING	Warning or system error

Removable Solid State Disk (SSD)

The removable solid state disk contains the instrument firmware and all measurement data from the R&S FPS, allowing you to store the data securely in an external location.

RF INPUT 50Ω

A device under test (DUT) can be connected to the R&S FPS to provide RF input which is then analyzed. The DUT is connected to the instrument's RF INPUT via a cable equipped with an appropriate connector.

The RF Input connector may be provided on the front or rear panel, as requested by the customer.

NOTICE

Risk of instrument damage

Do not overload the input. For maximum allowed values, see the data sheet. For AC-coupling, a DC input voltage of 50 V must never be exceeded. For DC-coupling, DC voltage must not be applied at the input. In both cases, noncompliance will destroy the input mixers.

3.2.2 Rear Panel View

This figure shows the rear panel view of the R&S FPS. The individual elements are described in more detail in the subsequent sections.

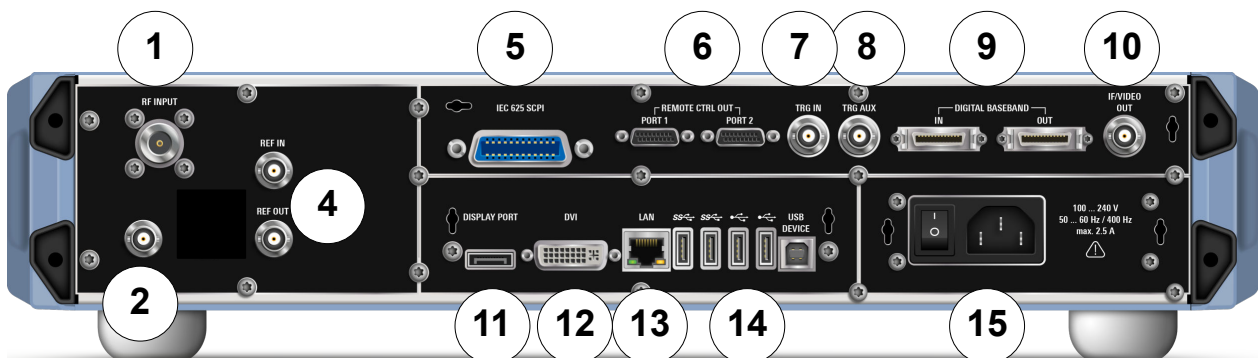


Fig. 3-2: Rear panel view

- 1 = RF Input 50 Ω connector (optionally front or rear panel)
- 2 = NOISE SOURCE CONTROL
- 4 = REF INPUT/OUTPUT connectors
- 5 = IEC 625 (GPIB) SCPI interface
- 6 = PCIe Remote Control Out Ports 1/2
- 7 = TRG IN connector
- 8 = TRG AUX connector
- 9 = DIGITAL BASEBAND INPUT/OUTPUT connectors (option B17, currently not available)
- 10 = IF/VIDEO out connector
- 11 = DISPLAY PORT for external display

- 12 = DVI connector for external display
- 13 = LAN connector
- 14 = USB (DEVICE) connectors
- 15 = AC Power Supply Connection and Main Power Switch

3.2.2.1 RF INPUT 50Ω

A device under test (DUT) can be connected to the R&S FPS to provide RF input which is then analyzed. The DUT is connected to the instrument's RF INPUT via a cable equipped with an appropriate connector.

The RF Input connector may be provided on the front or rear panel, as requested by the customer.

NOTICE

Risk of instrument damage

Do not overload the input. For maximum allowed values, see the data sheet. For AC-coupling, a DC input voltage of 50 V must never be exceeded. For DC-coupling, DC voltage must not be applied at the input. In both cases, noncompliance will destroy the input mixers.

3.2.2.2 NOISE SOURCE CONTROL

The noise source control female connector is used to provide the supply voltage for an external noise source, e.g., to measure the noise figure and gain of amplifiers and frequency converting devices.

Conventional noise sources require a voltage of +28 V in order to be switched on and 0 V to be switched off. The output supports a maximum load of 100 mA.

3.2.2.3 REF INPUT / REF OUTPUT

The REF INPUT connectors are used to provide an external reference signal to the R&S FPS.

The REF OUTPUT connectors can be used to provide an external reference signal (or the OCXO reference signal) from the R&S FPS to other devices that are connected to this instrument.

Connector	Reference signal	Usage
REF INPUT	1...20 MHz 0...10 dBm	To provide an external reference signal on the R&S FPS.
REF OUTPUT	10 MHz 10 dBm	To provide the internal reference signal from the R&S FPS to another device continuously. Also used to provide OCXO reference signal to another device.

3.2.2.4 GPIB (SCPI) Remote Control Connector

The IEC 625 GPIB interface is in compliance with IEEE488 and SCPI. A computer for remote control of the R&S FPS can be connected via this interface. For more details refer to [chapter 3.4, "Controlling the R&S FPS Remotely"](#), on page 47.

3.2.2.5 Remote Control Output (PCIe) Connectors

Two PCIe output connectors are provided to control connected devices remotely from the R&S FPS, for example as external tracking generators. Note that these connectors **cannot be used for input** to control the R&S FPS remotely from a PC, for example.

For details on controlling an external generator via the PCIe connectors see [chapter 6.2.4, "Optional External Generator Control"](#), on page 305.

3.2.2.6 TRIGGER INPUT / OUTPUT

The female TRG IN connector for external trigger or gate input is used to control the measurement by means of an external signal. The voltage levels can range from 0.5 to 3.5 V. The default value is 1.4 V. The typical input impedance is 10 kΩ.

The female BNC TRG AUX connector can be used to receive a second external signal or to provide a signal to another device. The signal is TTL compatible (0 V / 5 V). You can control the connector usage in the "Trigger" settings (TRIG key).

3.2.2.7 IF/VIDEO OUTPUT

The female BNC connector can be used for various outputs:

- Intermediate frequency (IF) output of approximately 20 MHz
- Video output (1V)

Which output is provided is defined in the software (INPUT/OUTPUT key). For details see the User Manual.

3.2.2.8 DISPLAY PORT and DVI

You can connect an external monitor or other display device to the R&S FPS to operate the instrument from a remote PC (see also [chapter 3.4.6, "How to Set Up Remote Desktop"](#), on page 62).

Two different types of connectors are provided for this purpose:

- DISPLAY PORT
- DVI (Digital visual interface)

3.2.2.9 LAN

The LAN interface can be used to connect the R&S FPS to a local network for remote control, printouts and data transfer. The assignment of the RJ-45 connector supports

twisted-pair category 5 UTP/STP cables in a star configuration (UTP stands for *unshielded twisted pair*, and STP for *shielded twisted pair*).

For details see [chapter 10, "Network and Remote Operation"](#), on page 543.

3.2.2.10 USB

The rear panel provides four additional female USB (USB-A) connectors to connect devices like a keyboard, a mouse or a memory stick (see also "USB" on page 34). The two left-most connectors provide USB 3.0 interfaces.

Furthermore, a male USB DEVICE connector (USB-B) is provided, for example to connect a printer.

3.2.2.11 AC Power Supply Connection and Main Power Switch

An AC power supply connector and main power switch are located in a unit on the rear panel of the instrument.

Main power switch function:

Position 1: The instrument is in operation.

Position O: The entire instrument is disconnected from the AC power supply.

For details refer to [chapter 3.1.1.4, "Connecting the AC Power"](#), on page 22.

3.2.3 Additional Hardware Options Without External Connectors

Some additional hardware options are available which have no external connectors and are not visible on the outside of the R&S FPS.

- [OCXO Option \(R&S FPS-B4\)](#).....38
- [Bandwidth Extension 160 MHz \(R&S FPS-B160\)](#).....38

3.2.3.1 OCXO Option (R&S FPS-B4)

This option generates a 10 MHz reference signal with a very precise frequency. If installed, and if no external signal is used, this signal is used as an internal reference.



Warm-up time for OCXO

When the instrument is switched on, the OCXO requires an extended warm-up time (see data sheet). No warm-up time is required when starting from standby mode.

3.2.3.2 Bandwidth Extension 160 MHz (R&S FPS-B160)

The signal analysis bandwidth of the R&S FPS can be extended by a hardware option (R&S FPS-B160). The bandwidth extension allows for a linear bandwidth up to a maximum of 160 MHz with an output sample rate of up to 10 GHz. While the extension can

be activated or deactivated manually in the R&S FPS base unit (I/Q Analyzer application), it is activated automatically in some applications that also support I/Q data analysis. See the application-specific documentation for details.

3.3 Miniature Display

The R&S FPS is equipped with a miniature display on the front panel (see also "[Mini display](#)" on page 34).

The display provides the following information:

- The serial number, firmware version and model of the instrument
- The IP address of the instrument
- The GPIB address of the instrument
- System messages, for example when errors occur

Furthermore, it provides the following functions directly on the instrument:

- Configuring network settings, including LXI and GPIB parameters
- Performing selftests, self alignment
- Resetting the instrument to a predefined state
- Changing display settings



The miniature front panel display is meant as a service interface, not for measurement display. If the display fails for any reason, switch the instrument off and back on again to restore the display.

Note that any error messages *caused by the Windows 7 operating system* are not displayed on the miniature front panel display. They are only visible on an external monitor or via RemoteDesktop from a controller PC. Thus, if operation of the R&S FPS seems to fail for no obvious reason, try connecting a monitor or a controller PC to check for any messages awaiting confirmation or action.

(See [chapter 3.1.3, "Connecting USB Devices"](#), on page 27 or [chapter 3.4.6, "How to Set Up Remote Desktop"](#), on page 62)

3.3.1 Functions and Settings in the Mini Display Menu

The following functions and settings are available via the menu in the R&S FPS's mini display.



Some of the following functions are also available in manual mode via the soft front panel, see [chapter 10, "Network and Remote Operation"](#), on page 543 and [chapter 9, "General Instrument Setup"](#), on page 505.

Network.....	40
L Computer Name.....	40
L DHCP.....	41

L IP Address.....	41
L Subnet Mask.....	41
System commands.....	41
L Preset.....	41
L Self align.....	41
L Selftest.....	41
L LAN Reset.....	42
L Reboot.....	42
L Enable NormalUser / Disable NormalUser.....	42
L Enable SecureUser / Disable SecureUser.....	43
GPIB.....	43
L GPIB Address.....	43
LXI parameters.....	44
L Version.....	44
L Features.....	44
L Computer Name.....	44
L MAC.....	44
L IP.....	44
L ICMP/VXI-11 Discovery.....	44
System messages.....	44
Display.....	45
L Backlight saving.....	45
L Normal/inverse color.....	45
Info.....	45
L Serial.....	45
L FW version.....	45
L Model.....	45
L uC version.....	45

Network

Configures the settings for operation in a local area network (LAN), for example to control the instrument from a remote PC or use a network printer.

NOTICE! Risk of network problems. All network parameters can be edited by the administrator ("Instrument" user) only. Beware that changing the computer name has major effects in a network.

For details, see [chapter 3.4, "Controlling the R&S FPS Remotely"](#), on page 47.

Computer Name ← Network

Each instrument is delivered with an assigned computer name, but this name can be changed. The naming conventions of Windows apply. If too many characters and/or numbers are entered, an error message is displayed in the status line.

The default instrument name is a non-case-sensitive string with the following syntax:

<Type><variant>-<serial_number>

For example FPS13-123456

The serial number can be found on the rear panel of the instrument. It is the third part of the device ID printed on the bar code sticker:

**DHCP ← Network**

Switches between DHCP server available (On) or not available (Off). If a DHCP server is available in the network, the IP address and subnet mask of the instrument are obtained automatically from the DHCP server.

IP Address ← Network

Defines the IP address. The TCP/IP protocol is preinstalled with the IP address 10.0.0.10. If the DHCP server is available ("DHCP On"), the setting is read-only.

The IP address consists of four number blocks separated by dots. Each block contains 3 numbers in maximum (e.g. 100.100.100.100), but also one or two numbers are allowed in a block (as an example see the preinstalled address).

Subnet Mask ← Network

Defines the subnet mask. The TCP/IP protocol is preinstalled with the subnet mask 255.255.255.0. If the DHCP server is available ("DHCP On"), this setting is read-only.

The subnet mask consists of four number blocks separated by dots. Each block contains 3 numbers in maximum (e.g. 100.100.100.100), but also one or two numbers are allowed in a block (as an example see the preinstalled address).

System commands

Provides basic system functions.

Preset ← System commands

When delivered, the R&S FPS has a default configuration. You can restore this defined initial state at any time as a known starting point for measurements. This is often recommendable as a first step in troubleshooting when unusual measurement results arise.

Remote command:

*RST or SYSTem:PRESet

Self align ← System commands

Starts recording correction data for the instrument. If the correction data acquisition fails or if the correction values are deactivated, a corresponding message is displayed in the status field.

For details see [chapter 9.1, "Basics on Alignment"](#), on page 505.

Remote command:

*CAL? on page 589, see also CALibration[:ALL]? on page 911

Selftest ← System commands

If the R&S FPS fails you can perform a self test of the instrument to identify any defective modules.

Once the self test is started, all modules are checked consecutively and the test result is displayed.

Remote command:

[*TST?](#) on page 592

[DIAGnostic:SERVice:STEST:RESult?](#) on page 913

LAN Reset ← System commands

Resets the LAN configuration to its default settings (LCI function).

According to the LXI standard, an LCI must set the following parameters to a default state.

Parameter	Value
TCP/IP Mode	DHCP + Auto IP Address
Dynamic DNS	Enabled
ICMP Ping	Enabled
Password for LAN configuration	LxiWebIfc

The LAN configuration can be reset to its default settings directly on the instrument via the R&S FPS's mini display ("System commands" > "LAN reset"), or in the "Network" tab of the "Network + Remote" dialog box or using the instrument's LXI Browser interface.

Remote command:

[SYSTem:LXI:LANReset](#) on page 925

Reboot ← System commands

Reboots the instrument, including the operating system.

Remote command:

[SYSTem:REBoot](#) on page 938

Enable NormalUser / Disable NormalUser ← System commands

Activates or deactivates the "NormalUser" account.

The NormalUser can only be activated by a user with administrator rights.

If enabled, the R&S FPS requires a reboot and then automatically logs in using the "NormalUser" account (indicated by "NormUsr" in the miniature display.).

The "NormalUser" is a standard user account with limited functionality. In particular, administrative tasks such as LAN configuration or general instrument settings are not available. Refer to the description of the basic instrument setup (SETUP menu) to find out which functions are affected.

If disabled, the R&S FPS requires a reboot. The R&S FPS attempts to login using the "Instrument" (administrator) account. You must enter the administrator ("Instrument" user) password on the R&S FPS (default: "894129"). For details see ["To enter a password"](#) on page 46.

Note: Deactivated auto-login function. If the auto-login function is deactivated and the R&S FPS is rebooted, you require an external monitor and keyboard and a Remote-

Desktop access on the R&S FPS to enter the password. Otherwise, the Windows operating system will not complete login and the R&S FPS remains inoperable. For details see ["The Automatic Login Function"](#) on page 25

Enable SecureUser / Disable SecureUser ← System commands

Activates or deactivates the secure user mode.

The secure user mode can only be activated or deactivated by a user with administrator rights. You must enter the administrator ("Instrument" user) password on the R&S FPS (default: "894129"). For details see ["To enter a password"](#) on page 46.

If enabled, the R&S FPS requires a reboot and then automatically logs in using the "SecureUser" account (indicated by "SecUsr" in the miniature display.)

For a "SecureUser", data that the R&S FPS normally stores on the solid-state drive is redirected to volatile memory instead. Data that is stored in volatile memory can be accessed by the user during the current instrument session; however, when the instrument's power is removed, all data in volatile memory is erased. Administrative tasks are not allowed by the "SecureUser".

Before you activate secure user mode, store any instrument settings that are required beyond the current session, such as predefined instrument settings, transducer files, or self-alignment data.

If disabled, the R&S FPS requires a reboot and then automatically logs in using the "Instrument" (administrator) account.

Note: Deactivated auto-login function. If the auto-login function is deactivated and the R&S FPS is rebooted, you require an external monitor and keyboard and a Remote-Desktop access on the R&S FPS to enter the password. Otherwise, the Windows operating system will not complete login and the R&S FPS remains inoperable. For details see ["The Automatic Login Function"](#) on page 25

For details on the secure user mode see [chapter 3.1.6, "Protecting Data Using the Secure User Mode"](#), on page 30.

Remote command:

`SYSTEM:SECURITY[:STATE]` on page 931

Note: Initially after installation of the R&S FPS-K33 option, secure user mode must be enabled manually once before remote control is possible.

GPIB

Alternatively to connecting the R&S FPS to a LAN, the GPIB interface can be used to connect a remote PC.

For details see [chapter 3.4.1.2, "GPIB Interface \(IEC 625/IEEE 418 Bus Interface\)"](#), on page 51).

GPIB Address ← GPIB

Defines the GPIB address. Values from 0 to 30 are allowed. The default address is 20.

Remote command:

`SYSTEM:COMMUNICATE:GPIB[:SELF]:ADDRESS` on page 924

LXI parameters

On the R&S FPS the LXI Class C functionality is already installed and enabled; thus, the instrument can be accessed via any web browser (e.g. the Microsoft Internet Explorer), for example to change the LAN settings using the LXI Web browser interface.

Note that LXI parameters are not available for the "SecureUser" or "NormalUser" accounts (see ["Enable NormalUser / Disable NormalUser"](#) on page 42 and ["Enable SecureUser / Disable SecureUser"](#) on page 43).

Version ← LXI parameters

Displays the current LXI version on the R&S FPS (read-only).

Features ← LXI parameters

Displays the extended LXI features installed on the R&S FPS (read-only).

Computer Name ← LXI parameters

Each instrument is delivered with an assigned computer name, but this name can be changed. The naming conventions of Windows apply. If too many characters and/or numbers are entered, an error message is displayed in the status line.

The default instrument name is a non-case-sensitive string with the following syntax:

<Type><variant>-<serial_number>

For example FPS13-123456

The serial number can be found on the rear panel of the instrument. It is the third part of the device ID printed on the bar code sticker:

**MAC ← LXI parameters**

Media Access Control address (MAC address), a unique identifier for the network card in the R&S FPS

IP ← LXI parameters

IP address of the R&S FPS as defined in the operating system (see also ["IP Address"](#) on page 41).

ICMP/VXI-11 Discovery ← LXI parameters

"ICMP" indicates whether the ping responder is active or not.

If "VXI-11 Discovery" is enabled, connected devices are detected automatically using the VXI-11 protocol.

(See ["VXI-11 Protocol"](#) on page 50).

System messages

Displays the system messages generated by the R&S FPS.

The messages are displayed in the order of their occurrence; the most recent messages are placed at the top of the list.

Display

Provides functions for the display itself.

Backlight saving ← Display

If enabled, the backlight of the display is turned off to save energy.

Normal/inverse color ← Display

Switches between a display with light characters on a dark background (normal) or dark characters on a light background (inverted).

Info

Provides information on the R&S FPS installation.

This information can be useful when problems occur with the instrument and you require support from Rohde & Schwarz.

Serial ← Info

Serial number of the R&S FPS

FW version ← Info

Currently installed firmware version

Model ← Info

Instrument model

uC version ← Info

Microcontroller version

3.3.2 Working with the Miniature Instrument Display

Using the miniature display on the front panel of the R&S FPS you can change basic instrument settings and perform hardware functions directly on the instrument, without additional devices such as a controller PC or external monitor.

To display a particular setting in the menu

The information and configuration settings are displayed in a hierarchical menu structure.

- ▶ To navigate within the menu structure, do one of the following:
 - Press the <Up Arrow> and <Down Arrow> keys to scroll through the menus.
 - Press the ENTER key to select a particular menu item (either to edit a setting or to select the submenu).
 - Press the ESC key to move back up in the menu structure.

To edit a configuration value

1. Navigate to the required menu item as described in ["To display a particular setting in the menu"](#) on page 45.
2. Press the ENTER key to select the displayed configuration setting and switch to edit mode.
3. To change the value, do one of the following:
 - Press the <Up Arrow> and <Down Arrow> keys to scroll through the available entry values (e.g. digits in an IP address).
 - Press the <Left Arrow> and <Right Arrow> keys to scroll within the entry (e.g. to the second or third part of the IP address).
 - Press the DEL key to delete the character to the left of the cursor.
4. Press the ENTER key again to store the entry and exit the edit mode.

To enter a password

For some functions you must enter the administrator ("Instrument" user) password on the R&S FPS (default: "894129").

1. Navigate to the required menu item as described in ["To display a particular setting in the menu"](#) on page 45.
2. Press the ENTER key to select the function.
3. For each character in the password:
 - a) Press the <Up Arrow> and <Down Arrow> keys to scroll through the available characters.
 - b) When the required character appears, press the <Right Arrow> key to move to the next character.
The currently selected character is displayed normally, all others are hidden by asterisks (*) for discretion.
4. When the password is complete, press the ENTER key again to store the entry and exit the edit mode.

3.3.3 Configuring the Display Settings

This section describes how to configure basic display settings on the R&S FPS. For further basic instrument settings see the R&S FPS User Manual.

To change the display colors

You can switch between a display with light characters on a dark background (normal) or dark characters on a light background (inverted).

1. In the R&S FPS's mini display menu, navigate to "Display" > "Normal/inverse colors" and press the ENTER key.
2. Use the <Left Arrow> and <Right Arrow> keys to toggle the setting.

3. Press the ENTER key again to store the entry and exit the edit mode.

To turn off the display backlight

You can turn off the backlight of the display to save energy.

1. In the R&S FPS's mini display menu, navigate to "Display" > "Backlight saving" and press the ENTER key.
2. Use the <Left Arrow> and <Right Arrow> keys to toggle the setting.
3. Press the ENTER key again to store the entry and exit the edit mode.

3.4 Controlling the R&S FPS Remotely

Since the R&S FPS was designed without a screen (except for the mini display for basic information and settings), it will typically be used to perform measurements under remote control. However, the developers of such programs will find it convenient to get familiar with the instrument and its functions using manual operation initially, and then design the programs accordingly. Once developed and tested, the programs can be executed from a remote PC, with no manual interaction required. The computer that is used for remote control is called "controller" here.



All instrument functions and settings, as well as any background information, are described for manual operation, assuming an external keyboard, mouse and monitor are connected, or a controller PC with Remote Desktop is being used.

Various methods for remote control are supported:

- Connecting the instrument to a (LAN) network (see [chapter 3.4.2, "How to Configure a Network"](#), on page 53)
- Using the LXI browser interface in a LAN network (see [chapter 3.4.2.3, "How to Configure the LAN Using the LXI Browser Interface"](#), on page 55)
- Using the Windows Remote Desktop application in a LAN network (see [chapter 3.4.6, "How to Set Up Remote Desktop"](#), on page 62)

For details on remote control interfaces see [chapter 3.4.1, "Remote Control Interfaces and Protocols"](#), on page 48



PCIe connectors

Note that the PCIe *output* connectors are provided to control connected devices remotely from the R&S FPS, for example as external tracking generators. They **cannot be used for input** to control the R&S FPS remotely from a PC, for example.

Remote operation

Remote operation of the instrument from a connected computer is possible using SCPI commands. Sending remote commands requires the instrument to be configured in a LAN network or connected to a PC via the GPIB interface as described in [chap-](#)

ter 3.4.2, "How to Configure a Network", on page 53 and chapter 3.4.5, "How to Start a Remote Control Session from a PC", on page 62.

Manual operation via Remote Desktop

Remote Desktop is a Windows application which can be used to access and control the instrument from a remote computer through a LAN connection. While the R&S FPS is in operation, the instrument's graphical results and control elements are displayed on the remote computer, and Remote Desktop provides access to all of the applications, files, and network resources of the instrument. Thus, remote (manual) operation of the instrument is possible. The following tasks can be performed using Remote Desktop:

- Access to the control functions via a virtual front panel
- Printout of measurement results directly from the controller
- Storage of measured data on the controller's hard disk

This documentation provides basic instructions on setting up the Remote Desktop for the R&S FPS. For details refer to the Windows 7 operating system documentation.

3.4.1 Remote Control Interfaces and Protocols

The instrument supports different interfaces and protocols for remote control. The following table gives an overview.

Table 3-2: Remote control interfaces and protocols

Interface	Protocols, VISA [®] address string	Remarks
Local Area Network (LAN)	<ul style="list-style-type: none"> • HiSLIP High-Speed LAN Instrument Protocol (IVI-6.1) TCPIP::host address::hislip0[::INSTR] • VXI-11 TCPIP::host address::inst0[::INSTR] Library: VISA • socket communication (Raw Ethernet, simple Telnet) TCPIP::host address[::LAN device name]::<port>:: SOCKET Library: VISA or socketcontroller 	<p>A LAN connector is located on the rear panel of the instrument.</p> <p>The interface is based on TCP/IP and supports various protocols.</p> <p>For a description of the protocols refer to:</p> <p>VXI-11 Protocol</p> <p>HiSLIP Protocol</p> <p>Socket Communication</p>
GPIB (IEC/IEEE Bus Interface)	<p>VISA[®] address string:</p> <p>GPIB::primary address[::INSTR]</p> <p>(no secondary address)</p>	<p>A GPIB bus interface according to the IEC 625.1/IEEE 488.1 standard is located on the rear panel of the instrument.</p> <p>For a description of the interface refer to 3.4.1.2 GPIB Interface (IEC 625/IEEE 418 Bus Interface).</p>
USB	<p>VISA[®] address string:</p> <p>USB::<vendor ID>::<product_ID>::<serial_number>[::INSTR]</p>	<p>USB connectors are located on the front and rear panel of the instrument.</p> <p>For a description of the interface refer to 3.4.1.3 USB Interface.</p>

Interface	Protocols, VISA ^{*)} address string	Remarks
PCIe		Two PCIe connectors are located on the rear panel of the instrument. Currently this interface is only available to control an external generator, which requires option R&S FPS-B10 (See chapter 6.2.4, "Optional External Generator Control" , on page 305).
<p>^{*)} VISA is a standardized software interface library providing input and output functions to communicate with instruments. A VISA installation on the controller is a prerequisite for remote control using the indicated interfaces. (See also chapter 3.4.1.4, "VISA Libraries", on page 53).</p>		



Within this interface description, the term GPIB is used as a synonym for the IEC/IEEE bus interface.

3.4.1.1 LAN Interface

To be integrated in a LAN, the instrument is equipped with a LAN interface, consisting of a connector, a network interface card and protocols. The network card can be operated with the following interfaces:

- 10 Mbit/s Ethernet IEEE 802.3
- 100 Mbit/s Ethernet IEEE 802.3u
- 1Gbit/s Ethernet IEEE 802.3ab

For remote control via a network, the PC and the instrument must be connected via the LAN interface to a common network with TCP/IP network protocol. They are connected using a commercial RJ45 cable (shielded or unshielded twisted pair category 5). The TCP/IP network protocol and the associated network services are preconfigured on the instrument. Software for instrument control and the VISA program library must be installed on the controller.

VISA library

Instrument access is usually achieved from high level programming platforms using VISA as an intermediate abstraction layer. VISA encapsulates the low level VXI, GPIB, LAN or USB function calls and thus makes the transport interface transparent for the user. See [chapter 3.4.1.4, "VISA Libraries"](#), on page 53 for details.

The R&S FPS supports various LAN protocols such as LXI, RSIB, raw socket or the newer HiSLIP protocol.

IP address

Only the IP address or a valid DNS host name is required to set up the connection. The host address is part of the "VISA resource string" used by the programs to identify and control the instrument.

The VISA resource string has the form:

```
TCPIP::host address[::LAN device name][::INSTR]
```

or

```
TCPIP::host address::port::SOCKET
```

where:

- **TCPIP** designates the network protocol used
- **host address** is the IP address or host name of the device
- **LAN device name** defines the protocol and the instance number of a sub-instrument;
 - `inst0` selects the VXI-11 protocol (default)
 - `hislip0` selects the newer HiSLIP protocol
- **INSTR** indicates the instrument resource class (optional)
- **port** determines the used port number
- **SOCKET** indicates the raw network socket resource class

Example:

- Instrument has the IP address `192.1.2.3`; the valid resource string using VXI-11 protocol is:

```
TCPIP::192.1.2.3::INSTR
```
- A raw socket connection can be established using:

```
TCPIP::192.1.2.3::5025::SOCKET
```



Identifying instruments in a network

If several instruments are connected to the network, each instrument has its own IP address and associated resource string. The controller identifies these instruments by means of the resource string.

For details on configuring the LAN connection, see [chapter 3.4.2, "How to Configure a Network"](#), on page 53.

- [VXI-11 Protocol](#)..... 50
- [HiSLIP Protocol](#)..... 50
- [Socket Communication](#)..... 51

VXI-11 Protocol

The VXI-11 standard is based on the ONC RPC (Open Network Computing Remote Procedure Call) protocol which in turn relies on TCP/IP as the network/transport layer. The TCP/IP network protocol and the associated network services are preconfigured. TCP/IP ensures connection-oriented communication, where the order of the exchanged messages is adhered to and interrupted links are identified. With this protocol, messages cannot be lost.

HiSLIP Protocol

The HiSLIP (**H**igh **S**peed **L**AN **I**nstrument **P**rotocol) is the successor protocol for VXI-11 for TCP-based instruments specified by the IVI foundation. The protocol uses

two TCP sockets for a single connection - one for fast data transfer, the other for non-sequential control commands (e.g. `Device Clear` or `SRQ`).

HiSLIP has the following characteristics:

- High performance as with raw socket network connections
- Compatible IEEE 488.2 support for Message Exchange Protocol, Device Clear, Serial Poll, Remote/Local, Trigger, and Service Request
- Uses a single IANA registered port (4880), which simplifies the configuration of firewalls
- Supports simultaneous access of multiple users by providing versatile locking mechanisms
- Usable for IPv6 or IPv4 networks



Note that HiSLIP data is sent to the device using the "fire and forget" method with immediate return, as opposed to VXI-11, where each operation is blocked until a VXI-11 device handshake returns. Thus, a successful return of a VISA operation such as `viWrite()` does not guarantee that the instrument has finished or started the requested command, but is delivered to the TCP/IP buffers.

For more information see also the application note at: <http://www.rohde-schwarz.com/appnote/1MA208>.

Socket Communication

An alternative way for remote control of the software is to establish a simple network communication using sockets. The socket communication, also referred to as "Raw Ethernet communication", does not necessarily require a VISA installation on the remote controller side. It is available by default on all operating systems.

The simplest way to establish socket communication is to use the built-in telnet program. The telnet program is part of every operating system and supports a communication with the software on a command-by-command basis. For more convenience and to enable automation by means of programs, user-defined sockets can be programmed.

Socket connections are established on a specially defined port. The socket address is a combination of the IP address or the host name of the instrument and the number of the port configured for remote-control. All R&S FPS use port number 5025 for this purpose. The port is configured for communication on a command-to-command basis and for remote control from a program.

3.4.1.2 GPIB Interface (IEC 625/IEEE 418 Bus Interface)

A GPIB interface is integrated on the rear panel of the instrument.

By connecting a PC to the R&S FPS via the GPIB connection you can send remote commands to control and operate the instrument.

To be able to control the instrument via the GPIB bus, the instrument and the controller must be linked by a GPIB bus cable. A GPIB bus card, the card drivers and the pro-

gram libraries for the programming language used must be provided in the controller. The controller must address the instrument with the GPIB bus address (see [chapter 3.4.2.4, "How to Change the GPIB Instrument Address"](#), on page 58). You can set the GPIB address and the ID response string. The GPIB language is set as SCPI by default and cannot be changed for the R&S FPS.

Notes and Conditions

In connection with the GPIB interface, note the following:

- Up to 15 instruments can be connected
- The total cable length is restricted to a maximum of 15 m or 2 m times the number of devices, whichever is less; the cable length between two instruments should not exceed 2 m.
- A wired "OR"-connection is used if several instruments are connected in parallel.
- Any connected IEC-bus cables should be terminated by an instrument or controller.

3.4.1.3 USB Interface

For remote control via the USB connection, the PC and the instrument must be connected via the USB type B interface. A USB connection requires the VISA library to be installed. VISA detects and configures the R&S instrument automatically when the USB connection is established. You do not have to enter an address string or install a separate driver.

USB address

The used USB address string is:

```
USB::::<product ID>::[::INSTR]
```

where:

- <vendor ID> is the vendor ID for Rohde & Schwarz (0x0AAD)
- <product ID> is the product ID for the Rohde & Schwarz instrument
- <serial number> is the individual serial number on the rear of the instrument

Table 3-3: Product IDs for R&S FPS

Instrument model	Product ID
FPS4	F9
FPS7	FA
FPS13	FB
FPS30	FC
FPS40	FD

Example:

```
USB::0x0AAD::0x00FB::100001::INSTR
```

0x0AAD is the vendor ID for Rohde&Schwarz

0x00FB is the product ID for the R&S FPS13

100001 is the serial number of the particular instrument

3.4.1.4 VISA Libraries

VISA is a standardized software interface library providing input and output functions to communicate with instruments. The I/O channel (LAN or TCP/IP, USB, ...) is selected at initialization time by means of the channel-specific address string ("VISA resource string") indicated in [table 3-2](#), or by an appropriately defined VISA alias (short name).

A VISA installation is a prerequisite for remote control using the following interfaces:

- [chapter 3.4.1.1, "LAN Interface"](#), on page 49
- [chapter 3.4.1.2, "GPIB Interface \(IEC 625/IEEE 418 Bus Interface\)"](#), on page 51
- [chapter 3.4.1.3, "USB Interface"](#), on page 52

For more information about VISA refer to the user documentation.

3.4.2 How to Configure a Network

NOTICE**Risk of network failure**

Before connecting the instrument to the network or configuring the network, consult your network administrator. Errors may affect the entire network.

The R&S FPS is equipped with a network interface and can be connected to an Ethernet LAN (local area network). Provided the appropriate rights have been assigned by the network administrator and the Windows 7 firewall configuration is adapted accordingly, the interface can be used, for example:

- To transfer data between a controller and the tester, e.g. in order to run a remote control program; see the "Remote Control" chapter in the R&S FPS User Manual
- To access or control the measurement from a remote computer using the "Remote Desktop" application (or a similar tool); see [chapter 3.4.6, "How to Set Up Remote Desktop"](#), on page 62
- To connect external network devices (e.g. printers)
- To transfer data from a remote computer and back, e.g. using network folders

A precondition for operating or monitoring the R&S FPS remotely is that it is connected to a LAN network or a PC connected to the GPIB interface. This is described here.



Windows Firewall Settings

A firewall protects an instrument by preventing unauthorized users from gaining access to it through a network. Rohde & Schwarz highly recommends the use of the firewall on your instrument. R&S instruments are shipped with the Windows firewall enabled and preconfigured in such a way that all ports and connections for remote control are enabled. For more details on firewall configuration see the R&S White Paper "Malware Protection" (available at <http://www.rohde-schwarz.com/appnote/1EF73>) and the Windows 7 help system.

3.4.2.1 How to Connect the Instrument to the Network

There are two methods to establish a LAN connection to the instrument:

- A non-dedicated network (Ethernet) connection from the instrument to an existing network made with an ordinary RJ-45 network cable. The instrument is assigned an IP address and can coexist with a computer and with other hosts on the same network.
- A dedicated network connection (Point-to-point connection) between the instrument and a single computer made with a (crossover) RJ-45 network cable. The computer must be equipped with a network adapter and is directly connected to the instrument. The use of hubs, switches, or gateways is not required, however, data transfer is still performed using the TCP/IP protocol. An IP address has to be assigned to the instrument and the computer, see [chapter 3.4.2.2, "How to Assign the IP Address"](#), on page 54.

Note: As the R&S FPS uses a 1 GBit LAN, a crossover cable is not necessary (due to Auto-MDI(X) functionality).

- ▶ To establish a non-dedicated network connection, connect a commercial RJ-45 cable to one of the LAN ports.
To establish a dedicated connection, connect a (crossover) RJ-45 cable between the instrument and a single PC.

If the instrument is connected to the LAN, Windows 7 automatically detects the network connection and activates the required drivers.

The network card can be operated with a 1 GBit Ethernet IEEE 802.3u interface.

3.4.2.2 How to Assign the IP Address

Depending on the network capacities, the TCP/IP address information for the instrument can be obtained in different ways.

- If the network supports dynamic TCP/IP configuration using the Dynamic Host Configuration Protocol (DHCP), all address information can be assigned automatically.
- If the network does not support DHCP, or if the instrument is set to use alternate TCP/IP configuration, the addresses must be set manually.

By default, the instrument is configured to use dynamic TCP/IP configuration and obtain all address information automatically. This means that it is safe to establish a physical connection to the LAN without any previous instrument configuration.

NOTICE

Risk of network errors

Connection errors can affect the entire network. If your network does not support DHCP, or if you choose to disable dynamic TCP/IP configuration, you must assign valid address information before connecting the instrument to the LAN. Contact your network administrator to obtain a valid IP address.

Assigning the IP address directly on the R&S FPS

1. In the R&S FPS's mini display, navigate to "Network" > "DHCP".
2. If DHCP is "Off", you must enter the IP address manually, as described in the following steps.
Note: When DHCP is changed from "On" to "Off", the previously set IP address and subnet mask are retrieved.
If DHCP is "On", the IP address of the DHCP server is obtained automatically. The configuration is saved, and you are prompted to restart the instrument. You can skip the remaining steps.
Note: When a DHCP server is used, a new IP address may be assigned each time the instrument is restarted. This address must first be determined on the instrument itself. Thus, when using a DHCP server, it is recommended that you use the permanent computer name, which determines the address via the DNS server.
3. In the R&S FPS's mini display, navigate to "Network" > "IP".
4. Enter the "IP Address", for example *10.0.0.10*. The IP address consists of four number blocks separated by dots. Every block contains 3 numbers in maximum. Enter the required address: Use the <Up Arrow> and <Down Arrow> keys to scroll through the digits 1-10 and the <Left Arrow> and <Right Arrow> keys to move between the individual numbers and blocks.
5. Enter the "Subnet Mask", for example *255.255.255.0*. The subnet mask consists of four number blocks separated by dots. Every block contains 3 numbers in maximum.
6. Press the ENTER key to store the entry and exit the edit mode.
7. In the R&S FPS's mini display, navigate to "System commands" > "Reboot system" to restart the system.

3.4.2.3 How to Configure the LAN Using the LXI Browser Interface

LAN eXtensions for Instrumentation (LXI) is an instrumentation platform for measuring instruments and test systems that is based on standard Ethernet technology. LXI is intended to be the LAN-based successor to GPIB, combining the advantages of Ether-

net with the simplicity and familiarity of GPIB. The LXI browser interface allows for easy configuration of the LAN.

The instrument's LXI browser interface works correctly with all W3C compliant browsers.

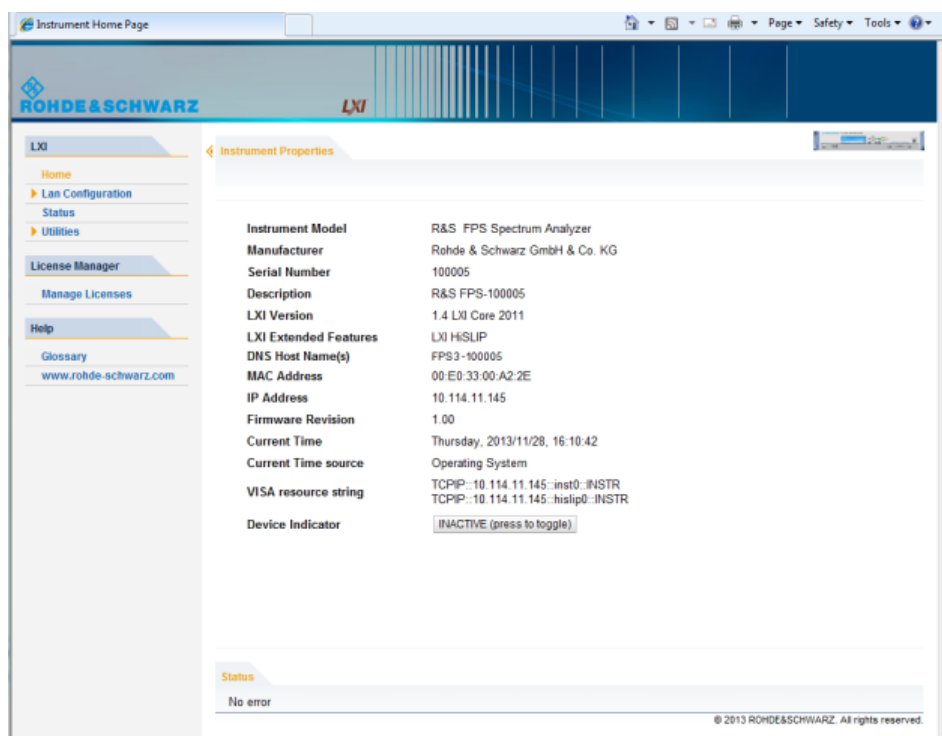


Restrictions

Only user accounts with administrator rights can make use of the LXI functionality. For details see [chapter 3.1.2.3, "Login"](#), on page 24.

In order to configure the LAN interface using the LXI Browser Interface, a controller PC or an external monitor, mouse and keyboard must be connected to the R&S FPS. The settings required to set up this function are available directly on the R&S FPS, via the mini display.

- ▶ In the web browser on the Remote Desktop, open the `http://<instrument-hostname>` or `http://<instrument-ip-address>` page, e.g. `http://10.113.10.203`.
The default password to change LAN configurations is *LxiWebIfc*.
The "Instrument Home Page" (welcome page) opens.



The instrument home page displays the device information required by the LXI standard including the VISA resource string in read-only format.

The most important control elements in the navigation pane of the browser interface are the following

- "LAN Configuration" opens the menu with configuration pages.

- "Status" displays information about the LXI status of the instrument.
- "Help > Glossary" opens a document with a glossary of terms related to the LXI standard.

LAN Configuration

The LAN configuration consists of three parts:

- "IP configuration" provides all mandatory LAN parameters.
- "Advanced LAN Configuration" provides LAN settings that are not declared mandatory by the LXI standard.
- "Ping Client" provides the ping utility to verify the connection between the instrument and other devices.

IP Configuration

The "LAN Configuration > IP configuration" web page displays all mandatory LAN parameters and allows their modification.

The "TCP/IP Mode" configuration field controls how the IP address for the instrument gets assigned (see also [chapter 3.4.2.2, "How to Assign the IP Address"](#), on page 54). For the manual configuration mode, the static IP address, subnet mask, and default gateway are used to configure the LAN. The automatic configuration mode uses DHCP server or Dynamic Link Local Addressing (Automatic IP) to obtain the instrument IP address.



Changing the LXI password

Changing the LAN configuration is password-protected. The default password is *Lxi-WebIfc* (notice upper and lower case characters).

To check or change the LXI password using the R&S FPS's mini display, navigate to "LXI parameters" > "Password".

You can also change the LXI password in the "Network + Remote" dialog box, see [chapter 10.3.4, "LXI Settings"](#), on page 582.

Advanced LAN Configuration

The "LAN Configuration > Advanced LAN Configuration" parameters in the LXI web configuration are used as follows:

- The "Negotiation" configuration field provides different Ethernet speed and duplex mode settings. In general, the "Auto Detect" mode is sufficient.
- "ICMP Ping" must be enabled to use the ping utility.
- "VXI-11" is the protocol that is used to detect the instrument in the LAN. According to the standard, LXI devices must use VXI-11 to provide a detection mechanism; other additional detection mechanisms are permitted.
- mDNS and DNS-SD are two additional protocols: Multicast DNS and DNS Service Discovery. They are used for device communication in zero configuration networks working without DNS and DHCP

Ping Client

Ping is a utility that verifies the connection between the LXI-compliant instrument and another device. The ping command uses the ICMP echo request and echo reply packets to determine whether the LAN connection is functional. Ping is useful for diagnosing IP network or router failures. The ping utility is not password-protected.

To initiate a ping between the LXI-compliant instrument and a second connected device:

1. Enable "ICMP Ping" on the "Advanced LAN Configuration" web page (enabled after an LCI).
2. Enter the IP address of the second device **without the ping command and without any further parameters** into the "Destination Address" field (e.g. *10.113.10.203*).
3. Select "Submit".

3.4.2.4 How to Change the GPIB Instrument Address

In order to operate the instrument via remote control, it must be addressed using the GPIB address. The remote control address is factory-set to 20, but it can be changed if it does not fit in the network environment. For remote control, addresses 0 through 30 are allowed. The GPIB address is maintained after a reset of the instrument settings.

To change the GPIB address

1. In the R&S FPS's mini display menu, navigate to "GPIB" > "GPIB address" and press the ENTER key.
2. Enter the required address: Use the <Up Arrow> and <Down Arrow> keys to scroll through the digits 1-10 and the <Left Arrow> and <Right Arrow> keys to move between the first and second digits.
3. Press the ENTER key again to store the entry and exit the edit mode.

Remote command:

```
SYST:COMM:GPIB:ADDR 18
```

3.4.3 How to Log on to the Network

Windows 7 requires that users identify themselves by entering a user name and password in a login window. You can set up two types of user accounts, either an administrator account with unrestricted access to the computer/domain or a standard user account with limited access. The instrument provides an auto-login function for the administrator account, i.e. login with unrestricted access is carried out automatically in the background. By default, the user name for the administrator account is "Instrument", and the user name for the standard user account is "NormalUser". In both cases the initial password is "894129". You can change the password in Windows 7 for

any user at any time. Some administrative tasks require administrator rights (e.g. firmware updates or the configuration of a LAN network).

Refer to [chapter 9, "General Instrument Setup"](#), on page 505 to find out which functions are affected.

At the same time you log on to the operating system, you are automatically logged on to the network. As a prerequisite, the user name and the password must be identical on the instrument and on the network.


3.4.3.1 How to Create Users

After the software for the network has been installed, the instrument issues an error message the next time it is switched on because there is no user named "instrument" (= default user ID for Windows 7 automatic login) in the network. Thus, a matching user must be created in the R&S FPS and in the network, the password must be adapted to the network password, and the automatic login mechanism must then be deactivated.



In order to configure users for the R&S FPS, a controller pc or an external monitor, mouse and keyboard must be connected to the R&S FPS. See [chapter 3.4.6, "How to Set Up Remote Desktop"](#), on page 62.

The network administrator is responsible for creating new users in the network. A new user can be created on the instrument using the "User Account" dialog box:

- 
Select the "Windows" icon in the toolbar to access the operating system of the R&S FPS.
- In the "Start" menu, select "Control Panel" and then select "User Accounts."
- Select "Give other users access to this computer" and then "Add".
The "Add New User" dialog box is displayed.
- Enter the name of the new user in the text field and select "Next".
- Define the level of access you want to allow the new user:
 - Select "Standard" to create an account with limited rights.
 - Select "Administrator" to create an account with administrator rights.**Note:** Full firmware functionality requires administrator rights.
- Select the "Finish" button.
The new user is created.

3.4.3.2 How to Change the User Password



In order to change the user passwords for the R&S FPS, a controller pc or an external monitor, mouse and keyboard must be connected to the R&S FPS. See [chapter 3.4.6, "How to Set Up Remote Desktop"](#), on page 62.

After the new user has been created on the instrument, the password must be adapted to the network password. This is also done using the "User Accounts" dialog box.

1. Select the "Windows" icon in the toolbar to access the operating system of the R&S FPS.
2. Select CTRL + ALT + DELETE, then select "Change a password".
3. Enter the user account name.
4. Enter the old password.
5. Enter the new password in the upper text line and repeat it in the following line.
6. Select ENTER.
The new password is now active.

3.4.3.3 How to Activate or Deactivate the Automatic Login Mechanism



In order to activate or deactivate the automatic login mechanism on the R&S FPS, a controller pc or an external monitor, mouse and keyboard must be connected to the R&S FPS. See [chapter 3.4.6, "How to Set Up Remote Desktop"](#), on page 62.


Deactivating the automatic login mechanism

When shipped, the instrument is already configured to automatically log on under Windows 7. To deactivate the automatic login mechanism, perform the following steps:

1. Select the "Windows" icon in the toolbar to access the operating system of the R&S FPS.
2. In the "Start" menu, select "Run".
The "Run" dialog box is displayed.
3. Enter the command `C:\R_S\INSTR\USER\NO_AUTOLOGIN.REG`.
4. Select the ENTER key to confirm.

The automatic login mechanism is deactivated. The next time you switch on the instrument, you are prompted to enter your user name and password before the firmware is started.

Reactivating the automatic login mechanism


1. 
Select the "Windows" icon in the toolbar to access the operating system of the R&S FPS.
2. In the "Start" menu, select "Run".
The "Run" dialog box is displayed.
3. Enter the command `C:\R_S\INSTR\USER\AUTOLOGIN.REG`.
4. Select the ENTER key to confirm.
The automatic login mechanism is reactivated. It will be applied the next time the instrument is switched on.

3.4.4 How to Share Directories (only with Microsoft Networks)

Sharing directories makes data available for other users. This is only possible in Microsoft networks. Sharing is a property of a file or directory.



In order to configure shared directories on the R&S FPS, a controller pc or an external monitor, mouse and keyboard must be connected to the R&S FPS. See [chapter 3.4.6, "How to Set Up Remote Desktop"](#), on page 62.

1. 
Select the "Windows" icon in the toolbar to access the operating system of the R&S FPS.
2. In the "Start" menu, select "Programs", "Accessories" and then select "Windows Explorer".
3. Select the desired folder with the right mouse button.
4. In the context menu, select "Sharing with > Specific people".
The dialog box for sharing a directory is displayed.
5. Select a user from the list or add a new name and select the "Add" button.
6. Select the "Share" button.
7. Select "Done" to close the dialog box.
The drive is shared and can be accessed by the selected users.

3.4.5 How to Start a Remote Control Session from a PC

When you switch on the instrument, it is always in manual operation state ("local" state) and can be operated via Remote Desktop from an external PC.

1. Send an addressed command (`GTR` - Go to Remote) from a controller to the instrument.

The instrument is switched to remote control ("remote" state). Operation via the soft front panel (on the Remote Desktop) is disabled. (The keys on the R&S FPS remain enabled.) The instrument remains in the remote state until it is reset to the manual state via the remote control interface.

Switching from manual operation to remote control and vice versa does not affect the other instrument settings.

2. To obtain optimum performance during remote control, send the `SYSTEM:DISPlay:UPDate OFF` command to hide the display of results and diagrams on the controller PC or external monitor (default setting in remote control).
3. To enable manual operation via the soft front panel on the Remote Desktop again, switch the instrument to local mode using the remote command `GTL` (Go to Local), that is, deactivate the `REN` line of the remote control interface.

3.4.6 How to Set Up Remote Desktop

Remote Desktop is a Windows application which can be used to access and control the instrument from a remote computer through a LAN connection. While the instrument is in operation, the instrument uses the display on the remote computer, and Remote Desktop provides access to all of the applications, files, and network resources of the instrument. Thus, remote operation of the R&S FPS is possible.

With Windows 7, Remote Desktop Client is part of the operating system. For other versions of Windows, Microsoft offers the Remote Desktop Client as an add-on.

This section provides basic instructions on setting up the Remote Desktop for the R&S FPS. For details refer to the Windows 7 operating system documentation.

3.4.6.1 How to Configure the R&S FPS for Remote Operation via Remote Desktop



By default, the R&S FPS is configured to allow Remote Desktop access by any user (except for the "SecureUser", see [chapter 3.4.6.5, "How to Add or Remove Users to the Remote Desktop Users Group"](#), on page 67), and to use a fixed IP address.

To change the settings for remote operation, you must connect an external monitor, mouse and keyboard, or connect a controller PC and set up a Remote Desktop connection with the default settings as described in [chapter 3.4.6.3, "How to Start and Close the Remote Desktop"](#), on page 65.

To change the settings for Remote Desktop access



To avoid problems, use a fixed IP address (see [chapter 3.4.2.2, "How to Assign the IP Address"](#), on page 54).

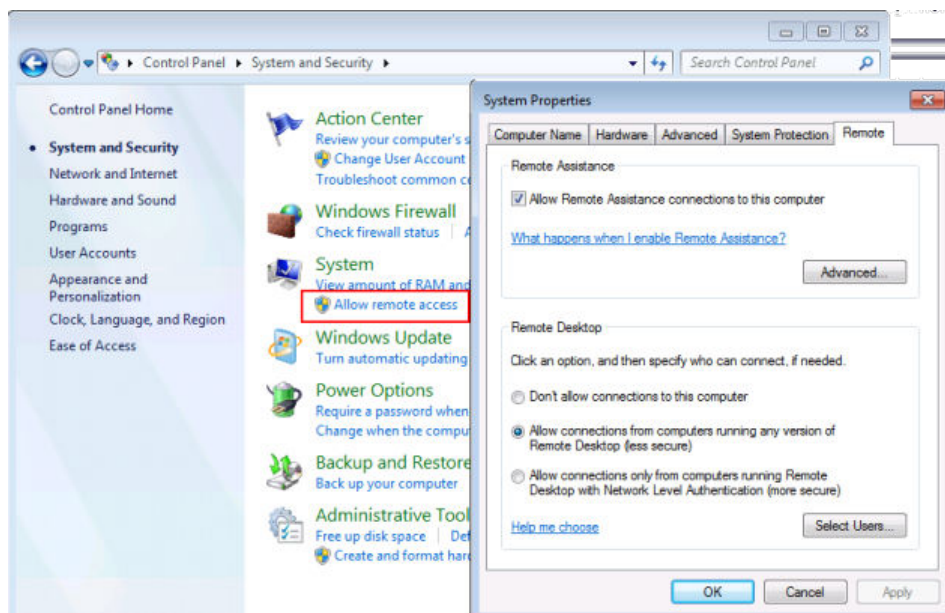
When a DHCP server is used, a new IP address is assigned each time the instrument is restarted. This address must first be determined on the instrument itself. Thus, using a DHCP server is not suitable for remote operation of the R&S FPS via Remote Desktop.

1.



Select the "Windows" icon in the toolbar to access the operating system of the R&S FPS.

2. In the "Start" menu, select the "Control Panel" and then "System and Security".
3. In the "System" area, select "Allow remote access".



4. In the "Remote" tab, in the "Remote Desktop" area, activate the "Allow connections from computers running Remote Desktop" option.
5. Define which users are to be given access to the R&S FPS via Remote Desktop. If the secure user mode is deactivated, the "SecureUser" account is also deactivated. Thus, the procedure described here will not work for the "SecureUser". Instead, see [chapter 3.4.6.5, "How to Add or Remove Users to the Remote Desktop Users Group"](#), on page 67.

Note: Administrator user accounts (e.g. "Instrument") are automatically enabled for Remote Desktop.

- a) Select the "Select Users" button.

- b) Select the users or create new user accounts as described in [chapter 3.4.3.1, "How to Create Users"](#), on page 59.
 - c) Select "OK" to confirm the settings.
6. The R&S FPS is now ready for connection setup with the Remote Desktop program of the controller.

3.4.6.2 How to Configure the Controller

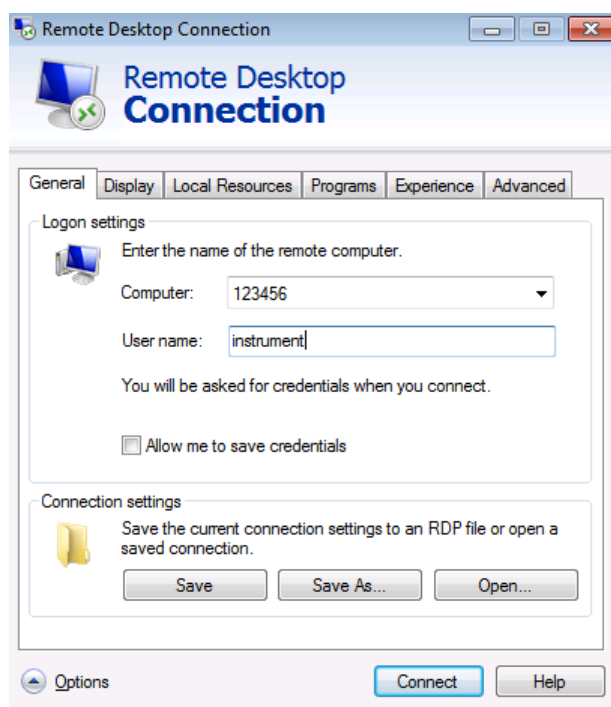


Remote Desktop Client

With Windows 7, Remote Desktop Client is part of the operating system and can be accessed via "Start > Programs > Accessories > Remote Desktop Connection".

For other versions of Windows, Microsoft offers the Remote Desktop Client as an add-on.

1. In the "Start" menu of the controller, select "All Programs > Accessories > Remote Desktop Connection".
The "Remote Desktop Connection" dialog box is displayed.
2. Select the "Options >>" button.
The dialog box is expanded to display the configuration data.



3. Open the "Experience" tab.
The settings on this tab are used to select and optimize the connection speed.
4. In the list, select the appropriate connection (for example: LAN (10 Mbps or higher)).

Depending on your selection (and how powerful the connection is), the options are activated or deactivated.

5. To improve the performance, you can deactivate the "Desktop background", "Show window contents while dragging" and "Menu and window animation" options.
6. Open the "Local Resources" tab to enable printers, local drives and serial interfaces.
7. If you will need to access drives of the controller from the R&S FPS (e.g. in order to store settings or to copy files from the controller to the R&S FPS), activate the "Disk drives" option.
Windows will then map drives of the controller to the corresponding network drives.
8. To use printers connected to the controller while accessing them from the R&S FPS, activate the "Printers" options. Do not change the remaining settings.
9. Open the "Display" tab.
The options to configure the R&S FPS screen display are displayed.
10. Under "Remote desktop size", you can set the size of the R&S FPS window on the desktop of the controller.
11. Under "Colors", do not change the settings.
12. Set the "Display the connection bar when I use the full screen" option:
If activated, a bar showing the network address of the R&S FPS will appear at the top edge of the screen. You can use this bar to reduce, minimize or close the window.
If deactivated, the only way you can return to the controller desktop from the R&S FPS screen in full screen mode is to select "Disconnect" from the "Start" menu.

3.4.6.3 How to Start and Close the Remote Desktop

To set up a connection from the controller to the R&S FPS

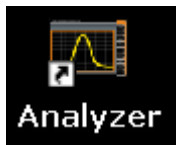
1. On the controller, in the "Remote Desktop Connection" dialog box (see [chapter 3.4.6.2, "How to Configure the Controller"](#), on page 64), open the "General" tab.
2. In the "Computer" field, enter the IP address of the R&S FPS (see [chapter 3.4.2.2, "How to Assign the IP Address"](#), on page 54 to determine the IP address).
In the "User name" field, enter *instrument* to log in as an administrator, or *Normal User* to log in as a standard user.
In the "Password" field, enter *894129*.
3. To save the connection configuration for later use:
 - a) Select the "Save As" button.
The "Save As" dialog box is displayed.
 - b) Enter the name for the connection information (* .RDP).

4. To load an existing connection configuration:
 - a) Select the "Open" button.
The "Open" dialog box is displayed.
 - b) Select the * .RDP file.
5. Select the "Connect" button.
The connection is set up.
6. If the "Disk drives" option is activated on the "Local Resources" tab, a warning is displayed indicating that the drives are enabled for access from the R&S FPS.
Select "OK" to confirm the warning.

7. After a few moments, the R&S FPS screen is displayed and manual operation is possible.

For details on manual operation see [chapter 3.5, "Operating the Instrument in Manual Mode"](#), on page 70.

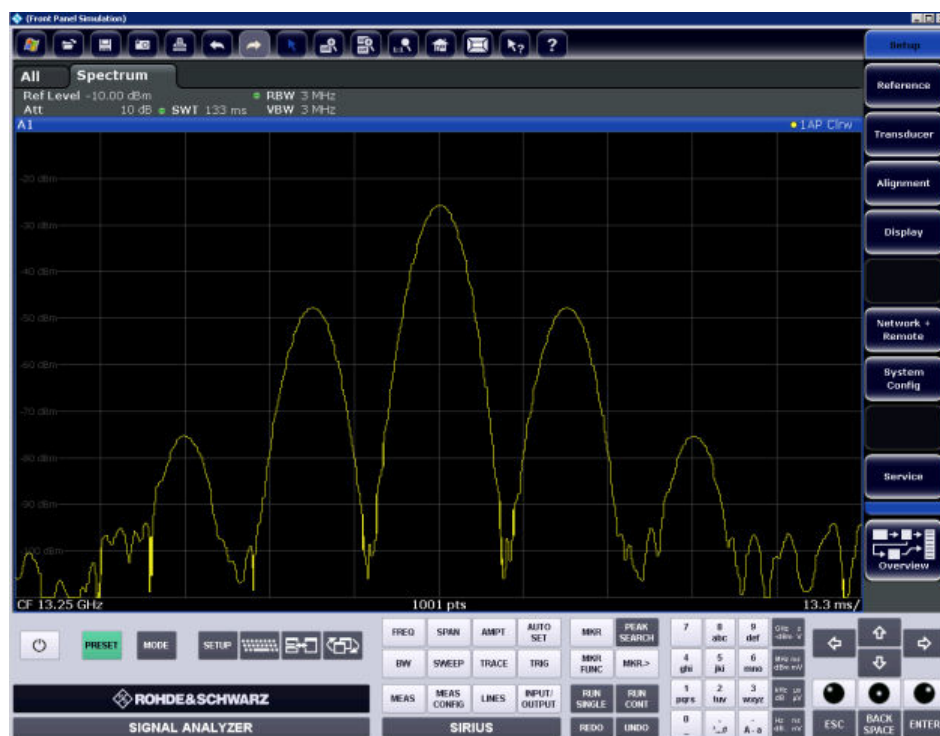
8. If a dark screen appears or a dark square appears in the upper left-hand corner of the screen, you must restart the R&S FPS in order to see the modified screen resolution.

	<ul style="list-style-type: none">• Select the key combination ALT + F4.• The R&S FPS firmware is shut down, which may take a few seconds.• On the desktop, double-click the "Analyzer" icon.
--	---

The firmware restarts and then automatically opens the graphical user interface from which you can access all instrument functions and settings.

For more information see [chapter 3.5.1.3, "Front Panels"](#), on page 73.

9. After the connection is established, the R&S FPS screen is displayed in the "Remote Desktop" application window.



To terminate Remote Desktop control

- ▶ On the controller, close the "Remote Desktop" window at any time. The connection to the R&S FPS is terminated.

Restoring the connection to the R&S FPS

Follow the instructions above for setting up a connection to the R&S FPS. If the connection is terminated and then restored, the R&S FPS remains in the same state.

3.4.6.4 How to Shut Down the R&S FPS via Remote Desktop

1. Select the R&S FPS's soft front panel on the Remote Desktop and close the application with the key combination ALT + F4.
A safety query is displayed to warn you that the instrument cannot be reactivated via remote operation and asks you whether you want to continue the shutdown process.
2. Confirm the safety query with "Yes".
The connection with the controller is terminated and the R&S FPS is shut down.

3.4.6.5 How to Add or Remove Users to the Remote Desktop Users Group

Only users in the Remote Desktop Users Group are allowed to connect to the R&S FPS via Remote Desktop. You can add the users to this group directly when you

allow remote access on the R&S FPS, as described in [chapter 3.4.6, "How to Set Up Remote Desktop"](#), on page 62. Furthermore, you can add or remove users to this group at any time.



In order to add or remove users to the Remote Desktop users group for the R&S FPS, a controller pc or an external monitor, mouse and keyboard must be connected to the R&S FPS. See [chapter 3.4.6, "How to Set Up Remote Desktop"](#), on page 62.



Secure User Mode

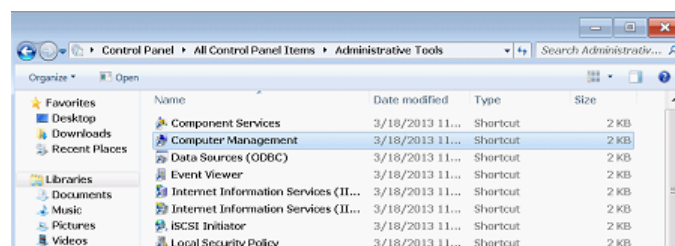
For security reasons, the "SecureUser" used in secure user mode is not allowed Remote Desktop access to the R&S FPS by default (see [chapter 3.1.6, "Protecting Data Using the Secure User Mode"](#), on page 30). You must explicitly add the "SecureUser" to the Remote Desktop group. If you do not allow this user RemoteDesktop access, the "SecureUser" will only be able to operate the R&S FPS using remote commands or via the miniature display.

1. If necessary, disable the "SecureUser" on the R&S FPS (miniature display: "System commands > Disable SecureUser").
2. Login using the administrator ("Instrument" user) account.
3. Start a RemoteDesktop connection to the R&S FPS as described in ["To set up a connection from the controller to the R&S FPS"](#) on page 65.

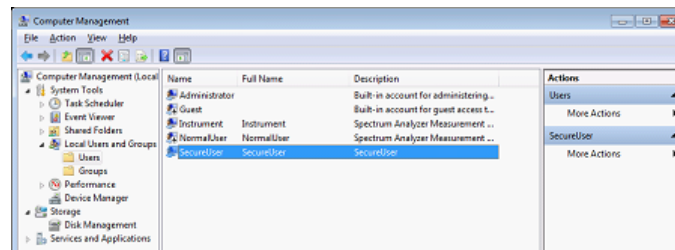


Select the "Windows" icon in the toolbar to access the operating system of the R&S FPS.

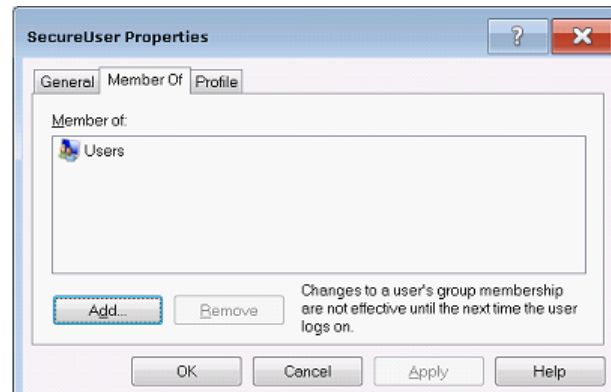
5. Open the Windows Explorer.
6. Select the directory:
Control Panel\All Control Panel Items\Administrative Tools.
7. Double-click "Computer Management".



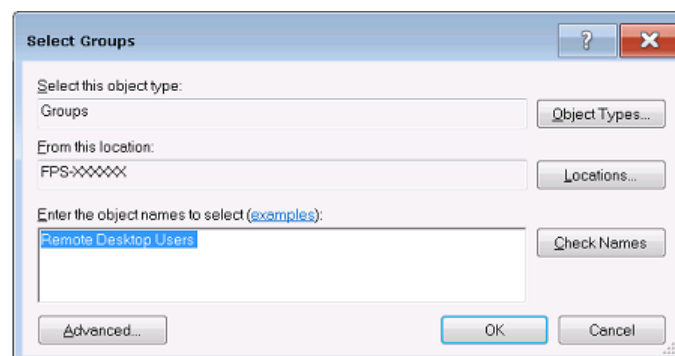
8. In the "Computer Management" dialog box, select "Local Users and Groups\Users" on the left side.



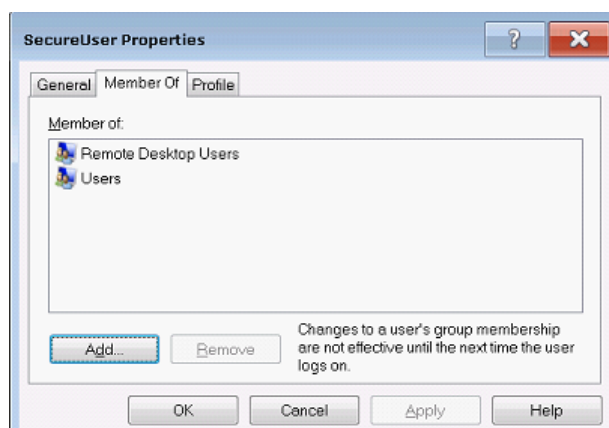
9. Double-click the user to be added, for example: "SecureUser".



10. In the "SecureUser Properties" dialog box, switch to the "Member of" tab and click "Add".



11. In the "Select Groups" dialog box, enter the "Remote Desktop Users" group and select "OK".



12. Select "Apply".
13. Select "OK" and close all dialog boxes.
14. Reboot the R&S FPS firmware so the changes become effective.

The new user (e.g. "SecureUser") should now be able to access the R&S FPS via RemoteDesktop.

3.5 Operating the Instrument in Manual Mode

The R&S FPS is completely remote-controlled; it does not provide a display for manual measurement control. The miniature display on the front panel of the R&S FPS allows only for very basic instrument configuration (see [chapter 3.3, "Miniature Display"](#), on page 39).

However, although the R&S FPS does not have a built-in display for manual measurement control, it is possible to operate it interactively in manual mode using a graphical user interface on an external monitor or a controller PC.

It is recommended that you use the manual mode initially to get familiar with the instrument and its functions before using it in pure remote mode. Thus, this section describes in detail how to operate the instrument manually using a controller PC and mouse, or an external monitor, mouse and keyboard. It describes what kind of information is displayed in the diagram area, how to use the soft front panel keys and other interface elements, and how to use the Online Help.

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3.5.1 Graphical User Interface Elements (Soft Front Panel)

All tasks necessary to operate the instrument can be performed using the graphical user interface provided by the soft front panel, a virtual front panel displayed on the external monitor or the Remote Desktop.

All measurement results are displayed. Additionally, the display provides status and setting information, allows you to switch between various measurement tasks, and provides access to all measurement functions.



Fig. 3-3: Graphical user interface elements in the R&S FPS's soft front panel

- 1 = Toolbar with standard application functions, e.g. print, save/open file etc.
- 2 = Tabs for individual measurement channels
- 3 = Channel bar for firmware and measurement settings
- 4 = Input field for measurement setting
- 5 = Softkeys for function access
- 6 = Window title bar with diagram-specific (trace) information
- 7 = Measurement results area
- 8 = Diagram footer with diagram-specific information, depending on application
- 9 = Instrument status bar with error messages, progress bar and date/time display
- 10 = Front panel with keys, keypad, navigation elements

3.5.1.1 Toolbar

Standard functions can be performed via the icons in the toolbar at the top of the screen.



















You can hide the toolbar display in order to enlarge the display area for the measurement results ("Setup > Display > Displayed Items"). See the R&S FPS User Manual for details.



The following functions are available:

Table 3-4: Standard Application Functions in the Toolbar

Icon	Description
	Windows: displays the Windows "Start" menu and task bar
	Open: opens a file from the instrument ("Save/Recall" menu)
	Store: stores data on the instrument ("Save/Recall" menu)
	Print: defines print settings ("Print" menu)
	Undo: reverts last operation
	Redo: repeats previously reverted operation
	Selection mode: the cursor can be used to select (and move) markers in a zoomed display
	Zoom mode: displays a dotted rectangle in the diagram that can be expanded to define the zoom area
	Multiple zoom mode: multiple zoom areas can be defined for the same diagram
	Zoom off: displays the diagram in its original size
	SmartGrid: activates "SmartGrid" mode to configure the screen layout
	Sequencer: opens the "Sequencer" menu to perform consecutive measurements
	Help (+ Select): allows you to select an object for which context-specific help is displayed
AL	Analysis line (MSRA mode only): opens a dialog box to display and position an analysis line in MSRA measurements (see R&S FPS MSRA User Manual)
	Help: displays context-sensitive help topic for currently selected element

Icon	Description
	Print immediately: prints the current display (screenshot) as configured
In "SmartGrid" mode only:	
	Exit "SmartGrid" mode

3.5.1.2 Softkeys

Softkeys are virtual keys provided by the software. Softkeys are dynamic, i.e. depending on the selected function key, a different list of softkeys is displayed on the right side of the screen.

A list of softkeys for a certain function key is also called a menu. Softkeys can either perform a specific function or open a dialog box.

The "More" softkey indicates that the menu contains more softkeys than can be displayed at once on the screen. When selected, it displays the next set of softkeys.

Recognizing the softkey status by color

A softkey is highlighted orange when its associated dialog box is open. If it is a toggle softkey, the current state is highlighted blue. If an instrument function is not available temporarily due to a specific setting, the associated softkey is deactivated and its text is colored gray.

Some softkeys belong to a certain (firmware) option. If this option is not installed in your instrument, the associated softkeys are not displayed.



You can hide the softkey display in order to enlarge the display area for the measurement results ("Setup > Display > Displayed Items"). See the User Manual for details.

3.5.1.3 Front Panels

The virtual "Front Panel" provides (static) function keys to access basic instrument functions and softkey menus, as well as a keypad and navigation keys.



Fig. 3-4: Front panel elements

- 1 = System keys
- 2 = Function keys
- 3 = Keypad
- 4 = Navigation keys

The measurement and instrument functions and settings can be accessed by selecting the corresponding keys in the front panel. To activate a key, select the key in the display using the mouse pointer.

The virtual front panel is displayed by default when you connect an external monitor or use Remote Desktop with the R&S FPS.

To toggle the front panel display, press the F6 key on the controller PC or an external keyboard.

Mini Front Panel

The Mini Front Panel displays only the basic system and function keys in a detached dialog box that can be moved around the screen.

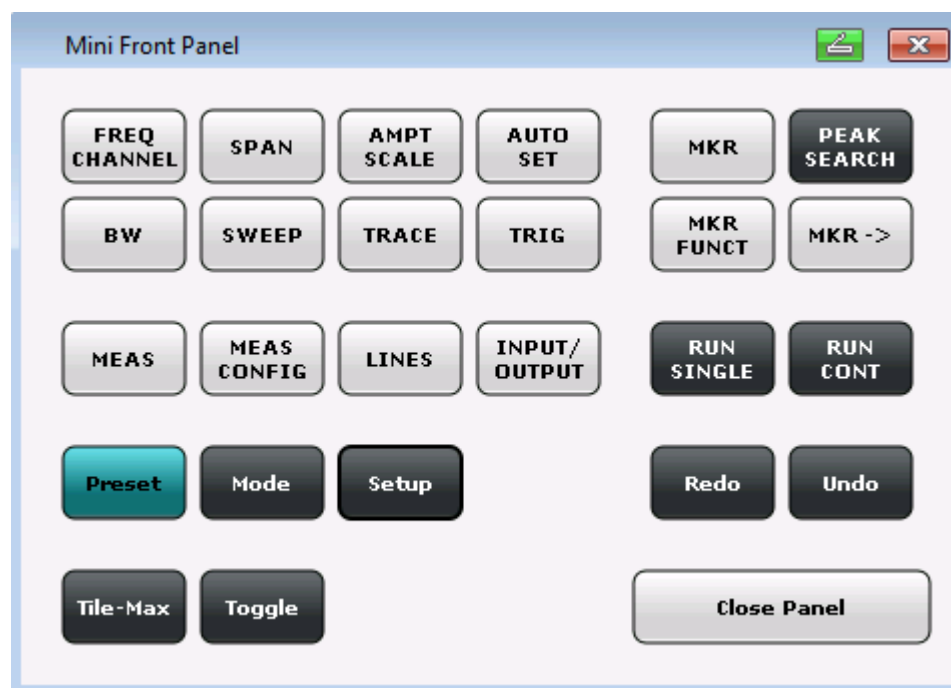


Fig. 3-5: Mini Front Panel

You can close the window by selecting "Close Panel" or the key combination ALT + M (be aware of the keyboard language defined in the operating system!).

To display the front panel or mini front panel

1. If neither the default front panel nor the mini front panel are displayed, press the F6 key on the controller pc or external keyboard to access the virtual system keys.
2. Select the SETUP key and then the "Display" softkey.
3. Select the "Displayed Items" tab.
4. Select "Front Panel: On" or "Mini Front Panel: On".




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SYSTEM Keys

The virtual SYSTEM keys set the instrument to a defined state, change basic settings, and provide print and display functions.

A detailed description of the corresponding functions is provided in the R&S FPS User Manual.

Table 3-5: SYSTEM keys

SYSTEM key	Assigned functions
PRESET	Resets the instrument to the default state.
MODE	Provides the selection between applications
SETUP	Provides basic instrument configuration functions, e.g.: <ul style="list-style-type: none"> • Reference frequency (external/internal) • Date, time, display configuration • Firmware update and enabling of options • Information about instrument configuration incl. firmware version and system error messages • Service support functions
	Switches between the on-screen keyboard display: at the top of the screen at the bottom of the screen off
 (Tile-Max)	Switches between maximized and split (tiled) display of the focused area
 (Toggle)	Toggles the focus area between windows.

Function Keys

The virtual function keys provide access to the most common measurement settings and functions.

A detailed description of the corresponding functions is provided in the R&S FPS User Manual.

Table 3-6: Function keys

Function key	Assigned functions
Basic measurement settings	
FREQ	Sets the center frequency as well as the start and stop frequencies for the frequency range under consideration. This key is also used to set the frequency offset and the signal track function.

Function key	Assigned functions
SPAN	Sets the frequency span to be analyzed.
AMPT	Sets the reference level, the displayed dynamic range, the RF attenuation and the unit for the level display. Sets the level offset and the input impedance. Activates the preamplifier (option RF Preamplifier, R&S FPS-B22).
AUTO SET	Enables automatic settings for level, frequency or sweep type mode.
BW	Sets the resolution bandwidth and the video bandwidth.
SWEEP	Sets the sweep time and the number of measurement points. Selects continuous measurement or single measurement.
TRACE	Configures the measured data acquisition and the analysis of the measurement data.
TRIG	Sets the trigger mode, the trigger threshold, the trigger delay, and the gate configuration in the case of gated sweep.
Marker functions	
MKR	Sets and positions the absolute and relative measurement markers (markers and delta markers).
PEAK SEARCH	Performs a peak search for active marker. If no marker is active, normal marker 1 is activated and the peak search is performed for it.
MKR FUNC	Provides additional analysis functions of the measurement markers: Frequency counter (Sig Count) Fixed reference point for relative measurement markers (Ref Fixed) Noise marker (Noise Meas) Phase noise (Phase Noise) n dB down function Peak list
MKR->	Used for search functions of the measurement markers (maximum/minimum of the trace). Assigns the marker frequency to the center frequency, and the marker level to the reference level. Restricts the search area (Search Limits) and characterizes the maximum points and minimum points (Peak Excursion).
Measurement and evaluation functions	

Function key	Assigned functions
MEAS	Provides the measurement functions. Measurement of multicarrier adjacent channel power (Ch Power ACLR) Carrier to noise spacing (C/N C/No) Occupied bandwidth (OBW) Spectrum emission mask measurement (Spectrum Emission Mask) Spurious emissions (Spurious Emissions) Measurement of time domain power (Time Domain Power) Signal statistics: amplitude probability distribution (APD) and cumulative complementary distribution function (CCDF) Third-order intercept point (TOI) AM modulation depth (AM Mod Depth)
MEAS CONFIG	Provides access to measurement configuration.
LINES	Configures display lines and limit lines.
INPUT/OUTPUT	Displays softkeys for input/output functions.
Measurement start functions	
RUN SINGLE	Starts a single new measurement (Single Sweep Mode).
RUN CONT	Starts a continuous measurement (Continuous Sweep Mode).
Function execution	
UNDO	Reverts last operation
REDO	Repeats previously reverted operation.

UNDO/REDO keys

- The virtual UNDO key reverts the previously performed action, i.e. the status before the previous action is retrieved.
The undo function is useful, for example, if you are performing a zero span measurement with several markers and a limit line defined and accidentally click the "ACP" softkey. In this case, very many settings would be lost. However, if you select UNDO immediately afterwards, the previous status is retrieved, i.e. the zero span measurement and all settings.
- The virtual REDO key repeats the previously reverted action, i.e. the most recently performed action is repeated.



The UNDO function is not available after a PRESET or "RECALL" operation. When these functions are used, the history of previous actions is deleted.

The UNDO/REDO functions are not available for some applications; see Release Notes for details.

Keypad

The virtual keypad is used to enter alphanumeric parameters, including the corresponding units (see also [chapter 3.5.4, "Entering Data"](#), on page 87). It contains the following keys:

Table 3-7: Keys on the keypad

Type of key	Description
Alphanumeric keys	Enter numbers and (special) characters in edit dialog boxes.
Decimal point	Inserts a decimal point "." at the cursor position.
Sign key	Changes the sign of a numeric parameter. In the case of an alphanumeric parameter, inserts a "-" at the cursor position.
Unit keys (GHz/-dBm MHz/dBm, kHz/dB and Hz/dB)	These keys add the selected unit to the entered numeric value and complete the entry. In the case of level entries (e.g. in dB) or dimensionless values, all units have the value "1" as multiplying factor. Thus, they have the same function as an ENTER key.

Navigation Controls

The navigation controls include a virtual rotary knob, navigation keys, and data input function keys. They allow you to navigate within the display or within dialog boxes.

Rotary knob simulation

The virtual rotary knob has several functions:

- Increments (clockwise direction) or decrements (counter-clockwise direction) the instrument parameter at a defined step width in the case of a numeric entry.
- Shifts the selection bar within focussed areas (e.g. lists).
- Shifts markers, limit lines, etc on the screen.
- Moves the scroll bar vertically, if the scroll bar is focussed.
- Acts like the ENTER key, when it is selected.

To simulate the use of a rotary knob, use the keys displayed beneath the arrow keys:

Table 3-8: Rotary knob simulation keys

Icon	Function
	Turn left
	Enter
	Turn right

Navigation keys

The virtual navigation keys can be used alternatively to the rotary knob to navigate through dialog boxes, diagrams or tables.

Arrow Up/Arrow Down Keys

The <arrow up> or <arrow down> keys do the following:

- In a numeric edit dialog box, increase or decrease the instrument parameter.
- In a list, scroll forward and backward through the list entries.
- In a table, move the selection bar vertically.

- In windows or dialog boxes with vertical scroll bar, move the scroll bar.

Arrow Left/Arrow Right Keys

The <arrow left> or <arrow right> keys do the following:

- In an alphanumeric edit dialog box, move the cursor.
- In a list, scroll forward and backward through the list entries.
- In a table, move the selection bar horizontally.
- In windows or dialog boxes with horizontal scroll bar, move the scroll bar.

Data input keys

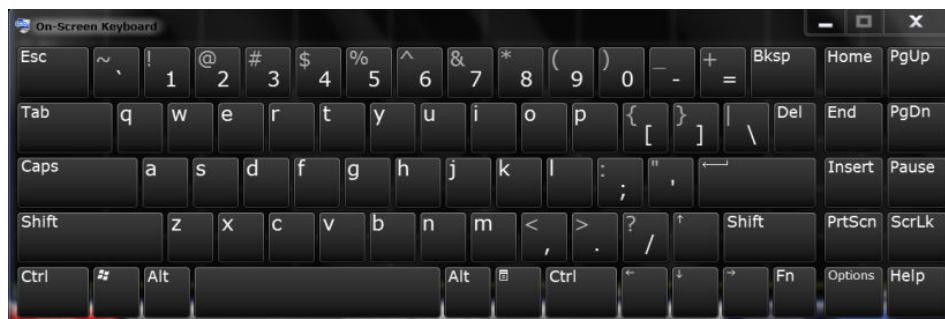
Some additional virtual keys are provided for data input in dialog boxes and input fields.

Table 3-9: Data input keys

Type of key	Description
ESC key	<p>Closes all kinds of dialog boxes, if the edit mode is not active. Quits the edit mode, if the edit mode is active. In dialog boxes that contain a "Cancel" button it activates that button.</p> <p>For "Edit" dialog boxes the following mechanism is used:</p> <ul style="list-style-type: none"> • If data entry has been started, it retains the original value and closes the dialog box. • If data entry has not been started or has been completed, it closes the dialog box.
BACKSPACE key	<p>If an alphanumeric entry has already been started, this key deletes the character to the left of the cursor.</p>
ENTER key	<ul style="list-style-type: none"> • Concludes the entry of dimensionless entries. The new value is accepted. • With other entries, this key can be used instead of the "Hz/dB" unit key. • In a dialog box, selects the default or focussed element.

3.5.1.4 On-screen Keyboard

The on-screen keyboard is an additional means of interacting with the instrument without having to connect an external keyboard.



The on-screen keyboard display can be switched on and off as desired using the "On-Screen Keyboard" function key beneath the screen.



When you press this key, the display switches between the following options:

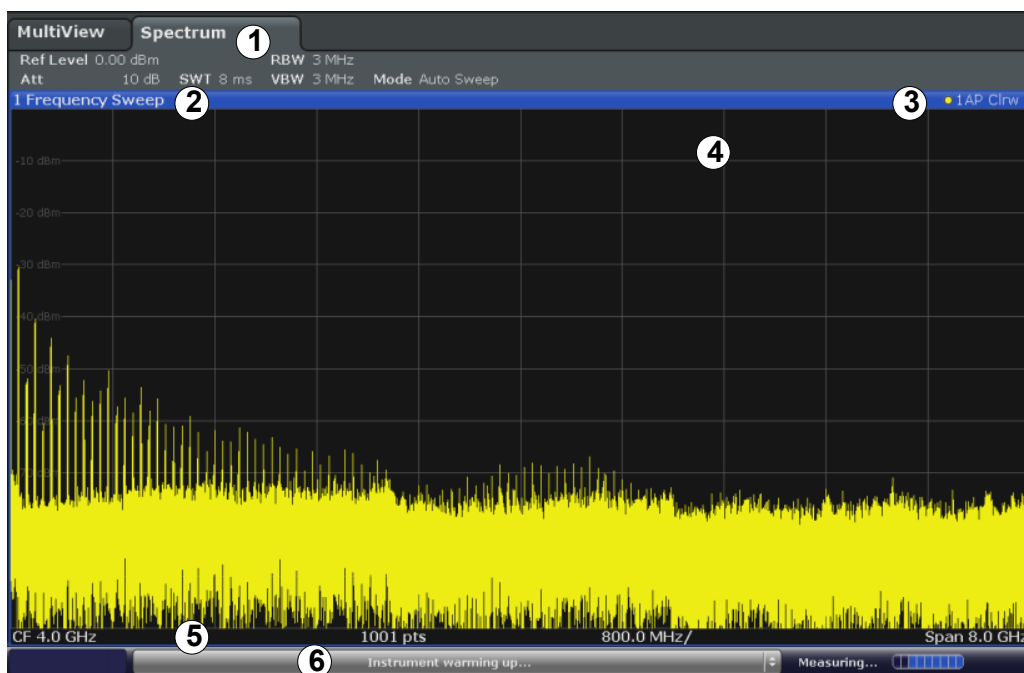
- Keyboard displayed at the top of the screen
- Keyboard displayed at the bottom of the screen
- No keyboard displayed



You can use the TAB key on the on-screen keyboard to move the focus from one field to another in dialog boxes.

3.5.2 Understanding the Display Information

The following figure shows a measurement diagram during manual analyzer operation. All different information areas are labeled. They are explained in more detail in the following sections.



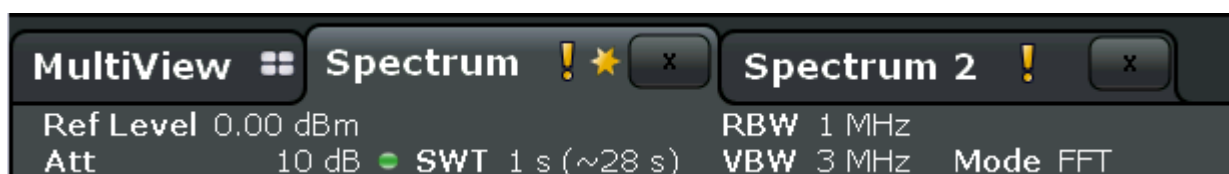
- 1 = Channel bar for firmware and measurement settings
- 2+3 = Window title bar with diagram-specific (trace) information
- 4 = Diagram area with marker information
- 5 = Diagram footer with diagram-specific information, depending on measurement application
- 6 = Instrument status bar with error messages, progress bar and date/time display


- [Channel Bar](#)..... 81
- [Window Title Bar](#)..... 83
- [Trace Information in Window Title Bar](#)..... 83
- [Marker Information](#)..... 84

- [Frequency and Span Information in Diagram Footer](#)..... 85
- [Instrument and Status Information](#)..... 85
- [Error Information](#)..... 86

3.5.2.1 Channel Bar

Using the R&S FPS you can handle several different measurement tasks (channels) at the same time (although they can only be performed asynchronously). For each channel, a separate tab is displayed on the screen. In order to switch from one channel display to another, simply select the corresponding tab.



The  icon on the tab label indicates that the displayed trace no longer matches the current instrument settings. This may be the case, for example, if a trace is frozen and the instrument settings are changed. As soon as a new measurement is performed, the icon disappears.

An orange "IQ" (in MSRA mode only) indicates that the results displayed in the MSRA application(s) no longer match the data captured by the MSRA Master. The "IQ" disappears after the results in the application(s) are refreshed.

Alternatively, if many tabs are displayed, select the tab selection list icon at the right end of the channel bar and select the channel you want to switch to from the list.

Channel-specific settings

Beneath the channel name, information on channel-specific settings for the measurement are displayed in the **channel bar**. A bullet next to the setting indicates that user-defined settings are used, not automatic settings. A green bullet indicates this setting is valid and the measurement is correct. A red bullet indicates an invalid setting that does not provide useful results. Channel information varies depending on the active application.

In the Spectrum application, the R&S FPS shows the following settings:

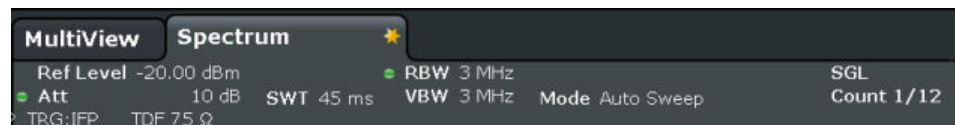
Table 3-10: Channel settings displayed in the channel bar in the Spectrum application

Ref Level	Reference level
m.+el.Att	Mechanical and electronic RF attenuation that has been set.
Ref Offset	Reference level offset
SWT	Sweep time that has been set. If the sweep time does not correspond to the value for automatic coupling, a bullet is displayed in front of the field. The color of the bullet turns red if the sweep time is set below the value for automatic coupling. In addition, the UNCAL flag is shown. In this case, the sweep time must be increased.

Meas Time	Measurement time, calculated from analysis bandwidth and number of samples (for statistics measurements)
RBW	Resolution bandwidth that has been set. If the bandwidth does not correspond to the value for automatic coupling, a green bullet appears in front of the field.
VBW	Video bandwidth that has been set. If the bandwidth does not correspond to the value for automatic coupling, a green bullet is displayed in front of the field.
AnBW	Analysis bandwidth (for statistics measurements)
Compatible	Compatible device mode (FSP, FSU, default; default not displayed)
Mode	Indicates which sweep mode type is selected: <ul style="list-style-type: none"> • "Auto FFT": automatically selected FFT sweep mode • "Auto sweep": automatically selected swept sweep mode • "FFT": manually selected FFT sweep mode

Common settings

In addition to the channel-specific settings, the channel bar above the diagram also displays information on instrument settings that affect the measurement results even though this is not immediately apparent from the display of the measured values. This information is displayed in gray font and only when applicable for the current measurement, as opposed to the channel-specific settings that are always displayed.



The following types of information may be displayed, if applicable.

Table 3-11: Common settings displayed in the channel bar

SGL	The sweep is set to single sweep mode.
Sweep Count	The current signal count for measurement tasks that involve a specific number of subsequent sweeps see "Sweep / Average Count" on page 361
TRG	Trigger source see "Trigger Source" on page 374 <ul style="list-style-type: none"> • EXT: External • IFP: IF power (+trigger bandwidth) • RFP: RF power • VID: Video
6dB/RRC/CHN	Filter type for sweep bandwidth see "Filter Type" on page 361
YIG Bypass	The YIG filter is deactivated.
PA	The preamplifier is activated.
GAT	The frequency sweep is controlled via the TRIGGER INPUT connector.
TDF	A transducer factor is activated.

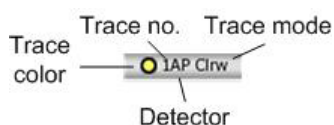
75 Ω	The input impedance of the instrument is set to 75 Ω.
FRQ	A frequency offset ≠ 0 Hz is set.
DC/AC	An external DC or AC calibration signal is in use.
<NOR APR> Ext. Gen	<p>An external generator is being controlled by the R&S FPS (requires option R&S FPS-B10).</p> <p>NOR: the measurements are normalized with the results of the external generator calibration</p> <p>APR (approximation): the measurements are normalized with the results of the external generator calibration; however, the measurement settings have been changed since calibration</p> <p>If neither label is displayed, no calibration has been performed yet or normalization is not active.</p> <p>For details see chapter 6.2.4, "Optional External Generator Control", on page 305.</p>
LVL	A level offset is applied to the external generator signal (only if external generator control is active).

3.5.2.2 Window Title Bar

Each channel in the R&S FPS display may contain several windows. Each window can display either a graph or a table as a result of the channel measurement. Which type of result evaluation is displayed in which window is defined in the display configuration (see [chapter 3.5.5, "Displaying Results"](#), on page 89). The window's title bar indicates which type of evaluation is displayed.

3.5.2.3 Trace Information in Window Title Bar

Information on the displayed traces is indicated in the window title bar.



Trace color		Color of trace display in diagram
Trace no.		Trace number (1 to 6)
Detector		Selected detector:
	AP	AUTOPEAK detector
	Pk	MAX PEAK detector
	Mi	MIN PEAK detector
	Sa	SAMPLE detector
	Av	AVERAGE detector
	Rm	RMS detector

Trace Mode		Sweep mode:
	Clr	CLEAR/WRITE
	Max	MAX HOLD
	Min	MIN HOLD
	Avg	AVERAGE (Lin/Log/Pwr)
	View	VIEW
Norm/NCor		Correction data is not used.

3.5.2.4 Marker Information

Marker information is provided either in the diagram grid or in a separate marker table, depending on the configuration.

Marker information in diagram grid

Within the diagram grid, the x and y-axis positions of the last 2 markers or delta markers that were set, if available, as well as their index are displayed. The value in the square brackets after the index indicates the trace to which the marker is assigned. (Example: M2[1] defines marker 2 on trace 1.) For more than 2 markers, a separate marker table is displayed beneath the diagram by default.

Marker information in marker table

In addition to the marker information displayed within the diagram grid, a separate marker table may be displayed beneath the diagram. This table provides the following information for all active markers:

Type	Marker type: N (normal), D (delta), T (temporary, internal)
Ref	Reference (for delta markers)
Trc	Trace to which the marker is assigned
X-value	x-value of the marker
Y-value	y-value of the marker
Func	Activated marker or measurement function
Func. Result	Result of the active marker or measurement function

The functions are indicated with the following abbreviations:

FXD	Fixed reference marker
PHNoise	Phase noise measurement
CNT	Signal count
TRK	Signal tracking
NOise	Noise measurement

MDepth	AM modulation depth
TOI	Third order intercept measurement

3.5.2.5 Frequency and Span Information in Diagram Footer

The diagram footer (beneath the diagram) contains the following information, depending on the current application:

Label	Information
CF	Center frequency
Span	Frequency span (frequency domain display)
ms/	Time per division (time domain display)
Pts	Number of sweep points or (rounded) number of currently displayed points in zoom mode

3.5.2.6 Instrument and Status Information

Global instrument settings, the instrument status and any irregularities are indicated in the status bar beneath the diagram.




Hiding the status bar

You can hide the status bar display, e.g. in order to enlarge the display area for the measurement results ("Setup > Display > Displayed Items").

See [chapter 9.4.2, "Displayed Items"](#), on page 529.

The following information is displayed:

Instrument status

	The instrument is configured for operation with an external reference.
---	--

Progress

The progress of the current operation is displayed in the status bar.



Date and time

The date and time settings of the instrument are displayed in the status bar.





You can hide the date and time display in the status bar, or the entire status bar ("Setup > Display > Displayed Items").

For details see the R&S FPS User Manual.

Error messages

If errors or irregularities are detected, a keyword and an error message, if available, are displayed in the status bar.

3.5.2.7 Error Information

If errors or irregularities are detected, a keyword and an error message, if available, are displayed in the status bar.




Note that the status bar is only visible on an external monitor or via RemoteDesktop from a controller PC (see [chapter 3.1.3, "Connecting USB Devices"](#), on page 27 or [chapter 3.4.6, "How to Set Up Remote Desktop"](#), on page 62).

Depending on the type of message, the status message is indicated in varying colors.

Table 3-12: Status bar information - color coding

Color	Type	Description
red	Fatal	A serious error occurred in the application; regular operation is no longer possible.
red	Error	An error occurred during a measurement, e.g. due to missing data or wrong settings, so that the measurement cannot be completed correctly.
orange	Warning	An irregular situation occurred during measurement, e.g. the settings no longer match the displayed results, or the connection to an external device was interrupted temporarily.
gray	Information	Information on the status of individual processing steps.
gray	Message	An event or state has occurred that may lead to an error during further operation.
green	No errors	No messages displayed.



If any error information is available for a measurement channel, the  icon is displayed next to the channel name.

This is particularly useful when the MultiView tab is displayed, as the status bar in the MultiView tab always displays the information for the currently selected measurement only.

Furthermore, a status bit is set in the `STATUS:QUESTIONABLE:EXTENDED:INFO` register for the application concerned (see "[STATUS:QUESTIONABLE:EXTENDED:INFO Register](#)" on page 565). Messages of a specific type can be queried using the `SYST:ERR:EXT?` command, see [SYSTem:ERRor:EXTended?](#) on page 929.

The following keywords are used:

IF OVLD	Overload of the IF signal path after the input mixer. <ul style="list-style-type: none"> • Increase the reference level.
INPUT OVLD	The signal level at the RF input connector exceeds the maximum. The RF input is disconnected from the input mixer to protect the device. In order to re-enable measurement, decrease the level at the RF input connector and reconnect the RF input to the mixer input.
LOUNL	Error in the instrument's frequency processing hardware was detected.
NO REF	Instrument was set to an external reference but no signal was detected on the reference input.
OVEN	OCXO reference frequency (option R&S FPS-B4) has not yet reached its operating temperature. The message usually disappears a few minutes after power has been switched on.
RF OVLD	Overload of the input mixer. <ul style="list-style-type: none"> • Increase the RF attenuation (for RF input). • Reduce the input level (for digital input)
UNCAL	One of the following conditions applies: <ul style="list-style-type: none"> • Correction data has been switched off. • No correction values are available, for example after a firmware update. • Record the correction data by performing a self alignment (For details refer to chapter 3.1.4, "Performing a Self Alignment and a Self Test", on page 29).
WRONG_FW	The firmware version is out-of-date and does not support the currently installed hardware. Until the firmware version is updated, this error message is displayed and self-alignment fails. (For details refer to chapter 9.3.4.4, "Firmware Updates" , on page 519).

3.5.3 Changing the Focus

Any selected function is always performed on the currently focused element in the display, e.g. a dialog field, diagram, or table row. Which element is focused is indicated by a blue frame (diagram, window, table) or is otherwise highlighted (softkey, marker etc.). Moving the focus is most easily done by selecting the element in the display using the mouse pointer. Alternatively, use the "Tab" key on the on-screen keyboard to move the focus from one element to the next on the display.



To move the focus between any displayed diagrams or tables in a window, select the "Change focus" key. The focus moves from the diagram to the first table to the next table etc. and then back to the diagram, within the same window.

3.5.4 Entering Data

Data can be entered in dialog boxes using an external keyboard or the keyboard of the controller PC.

3.5.4.1 Entering Numeric Parameters

If a field requires numeric input, the keypad provides only numbers.

1. Enter the parameter value using the keypad, or change the currently used parameter value by using the rotary knob (small steps) or the UP or DOWN keys (large steps) in the soft front panel.
2. After entering the numeric value via keypad, select the corresponding unit key. The unit is added to the entry.
3. If the parameter does not require a unit, confirm the entered value by selecting the ENTER key or any of the unit keys. The editing line is highlighted in order to confirm the entry.

3.5.4.2 Entering Alphanumeric Parameters

If a field requires alphanumeric input, you can use the on-screen keyboard to enter numbers and (special) characters (see [chapter 3.5.1.4, "On-screen Keyboard"](#), on page 79).

Alternatively, you can use the virtual keypad. Every alphanumeric key represents several characters and one number. The decimal point key (.) represents special characters, and the sign key (-) toggles between capital and small letters. For the assignment refer to [table 3-13](#). In principle, the input of alphanumeric parameters works like writing an SMS on your cell phone.

To enter numbers and (special) characters via the virtual keypad

1. Select the key once to enter the first possible value.
All characters available via this key are displayed in a popup.
2. To choose a different value provided by this key, select the key again, until your desired value is displayed.
With each key stroke the next possible value of this key is displayed. If all possible values have been displayed, the series starts with the first value again. For information on the series refer to [table 3-13](#).
3. To change from capital to small letters and vice versa, select the sign key (-).
4. After entering a value, wait for 2 seconds (to use the same key again), or start the next entry by selecting another key.

To enter a blank

- ▶ Select the "Space" bar, or select the "0" key and wait 2 seconds.

To correct an entry

1. Using the arrow keys, move the cursor to the right of the entry you want to delete.
2. Select the BACKSPACE key.

The entry to the left of the cursor is deleted.

3. Enter your correction.

To complete the entry

- ▶ Select the ENTER key or the rotary knob.

To cancel the entry

- ▶ Select the ESC key.
The dialog box is closed without changing the settings.

Table 3-13: Keys for alphanumeric parameters

Key name (upper inscription)	Series of (special) characters and number provided
7	7 μ Ω ° € ¥ \$ ¢
8	A B C 8 Ä Æ Å Ç
9	D E F 9 É
4	G H I 4
5	J K L 5
6	M N O 6 Ñ Ö
1	P Q R S 1
2	T U V 2 Ü
3	W X Y Z 3
0	<blank> 0 – @ + / \ < > = % &
.	. * : _ , ; " ' ? () #
–	<toggles between capital and small letters>

3.5.5 Displaying Results

The R&S FPS provides several instrument applications for different analysis tasks and different types of signals, e.g. 3G FDD, I/Q analysis or basic spectrum analysis. For each application, a new measurement channel is created and displayed in a separate tab on the screen.

The results of a measurement channel can be evaluated in many different ways, both graphically and numerically. For each evaluation method the results are displayed in a separate window in the tab.

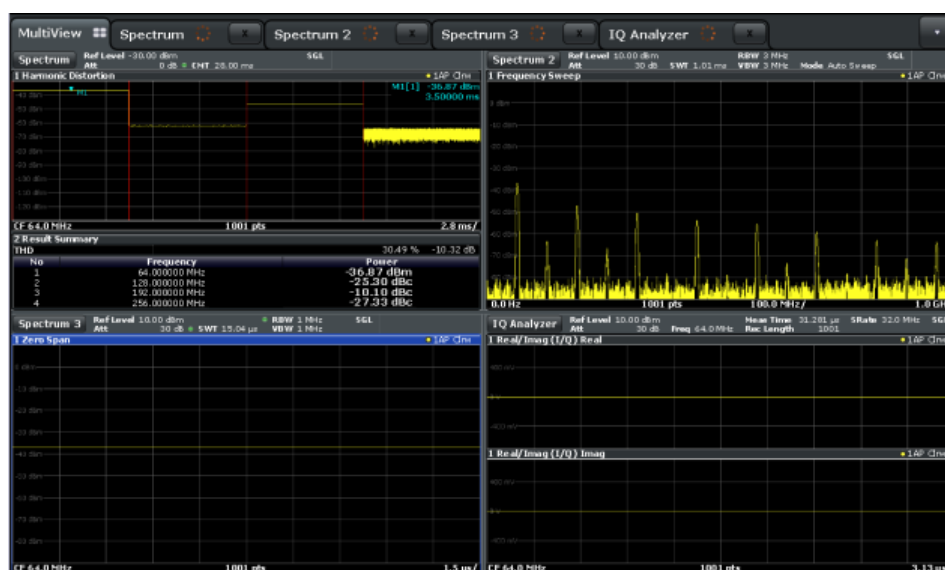
The R&S FPS allows you to configure the display to suit your specific requirements and optimize analysis.

3.5.5.1 Activating channels

When you activate an application, a new measurement channel is created which determines the measurement settings for that application. The same application can be activated with different measurement settings by creating several channels for the same application. Whenever you switch channels, the corresponding measurement settings are restored. Each channel is displayed in a separate tab on the screen.

An additional tab ("MultiView") provides an overview of all currently active channels at once.

Only one measurement can be performed at any time, namely the one in the currently active channel. However, in order to perform the configured measurements consecutively, a Sequencer function is provided.



To start a new channel

1. Select the MODE key in the soft front panel.
2. In the "Mode" dialog box, select the required application on the "New Channel" tab. A new tab is displayed for the new channel.

To change the application in an active channel

1. Select the tab of the channel you want to change.
2. Select the MODE key.
3. In the "Mode" dialog box, select the new application to be displayed on the "Replace Current Channel" tab.

The selected application is displayed in the current channel.

3.5.5.2 Laying out the Result Display with the SmartGrid

Measurement results can be evaluated in many different ways, for example graphically, as summary tables, statistical evaluations etc. Each type of evaluation is displayed in a separate window in the channel tab. Up to 16 individual windows can be displayed per measurement channel (i.e. per tab). To arrange the diagrams and tables on the screen, the Rohde & Schwarz SmartGrid function helps you find the target position simply and quickly.

Principally, the layout of the windows on the screen is based on an underlying grid, the SmartGrid. However, the SmartGrid is dynamic and flexible, allowing for many different layout possibilities. The SmartGrid functionality provides the following basic features:

- Windows can be arranged in columns or in rows, or in a combination of both.
 - Windows can be arranged in up to four rows and four columns.
 - Windows are moved simply by dragging them to a new position on the screen, possibly changing the layout of the other windows, as well.
 - All evaluation methods available for the currently selected measurement are displayed as icons in the evaluation bar. If the evaluation bar contains more icons than can be displayed at once on the screen, it can be scrolled vertically. The same evaluation method can be displayed in multiple windows simultaneously.
 - New windows are added by dragging an evaluation icon from the evaluation bar to the screen. The position of each new window depends on where you drop the evaluation icon in relation to the existing windows.
 - All display configuration actions are only possible in SmartGrid mode. When SmartGrid mode is activated, the evaluation bar replaces the current softkey menu display. When the SmartGrid mode is deactivated again, the previous softkey menu display is restored.
- | | |
|---|----|
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| • How to Activate SmartGrid Mode | 93 |
| • How to Add a New Result Window | 93 |
| • How to Close a Result Window | 94 |
| • How to Arrange the Result Windows | 94 |

Background Information: The SmartGrid Principle

SmartGrid display

During any positioning action, the underlying SmartGrid is displayed. Different colors and frames indicate the possible new positions. The position in the SmartGrid where you drop the window determines its position on the screen.

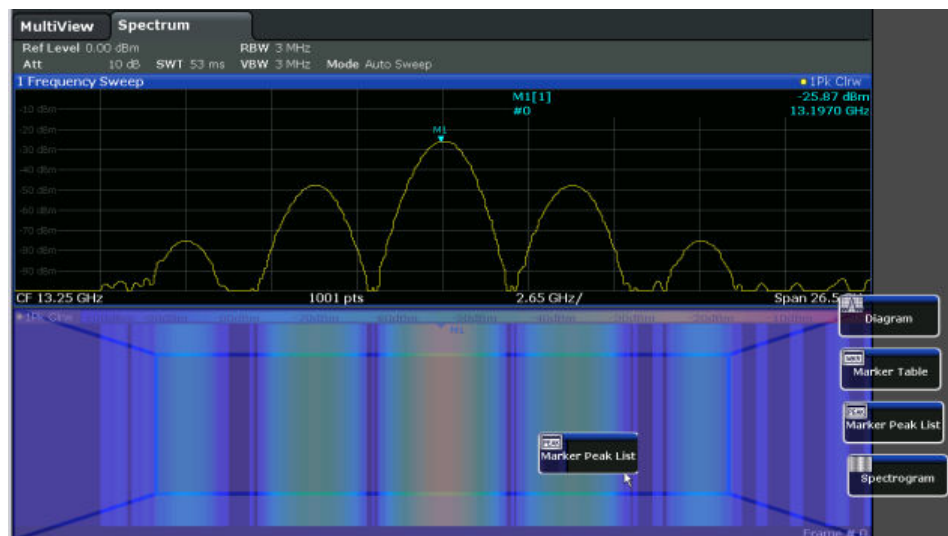


Fig. 3-6: Moving a window in SmartGrid mode

The brown area indicates the possible "drop area" for the window, i.e. the area in which the window can be placed. A blue area indicates the (approximate) layout of the window as it would be if the icon were dropped at the current position. The frames indicate the possible destinations of the new window with respect to the existing windows: above/below, right/left or replacement (as illustrated in figure 3-7). If an existing window would be replaced, the drop area is highlighted in a darker color shade.

Positioning the window

The screen can be divided into up to four rows. Each row can be split into up to four columns, where each row can have a different number of columns. However, rows always span the entire width of the screen and may not be interrupted by a column. A single row is available as the drop area for the window in the SmartGrid. The row can be split into columns, or a new row can be inserted above or below the existing row (if the maximum of 4 has not yet been reached).

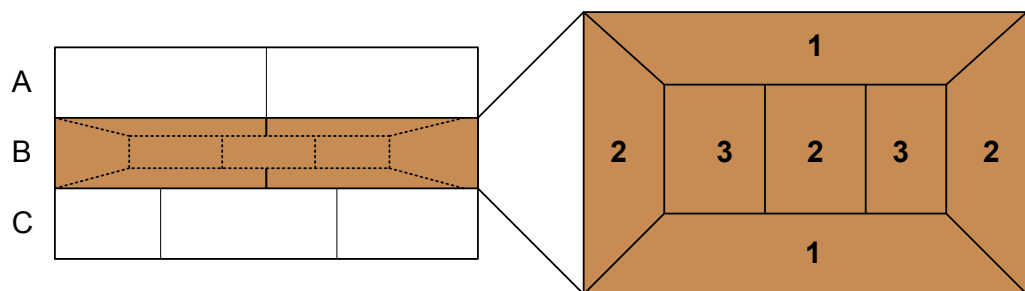


Fig. 3-7: SmartGrid window positions

- 1 = Insert row above or below the existing row
- 2 = Create a new column in the existing row
- 3 = Replace a window in the existing row

SmartGrid functions

Once the evaluation icon has been dropped, icons in each window provide delete and move functions.



The "Move" icon allows you to move the position of the window, possibly changing the size and position of the other displayed windows.



The "Delete" icon allows you to close the window, enlarging the display of the remaining windows.

How to Activate SmartGrid Mode

All display configuration actions are only possible in SmartGrid mode. In SmartGrid mode the evaluation bar replaces the current softkey menu display. When the SmartGrid mode is deactivated again, the previous softkey menu display is restored.

► To activate SmartGrid mode, do one of the following:



Select the "SmartGrid" icon from the toolbar.

- Select the "Display Config" button in the configuration "Overview".
- Select the "Display Config" softkey from the MEAS CONFIG menu.

The SmartGrid functions and the evaluation bar are displayed.



To close the SmartGrid mode and restore the previous softkey menu select the "Close" icon in the right-hand corner of the toolbar, or press any key.

How to Add a New Result Window

Each type of evaluation is displayed in a separate window. Up to 16 individual windows can be displayed per measurement channel (i.e. per tab).

1. Activate SmartGrid mode.

All evaluation methods available for the currently selected measurement are displayed as icons in the evaluation bar.

2. Select the icon for the required evaluation method from the evaluation bar. If the evaluation bar contains more icons than can be displayed at once on the screen, it can be scrolled vertically. Set the mouse pointer in the evaluation bar between the icons and move it up or down until the required icon appears.
3. Drag the required icon from the evaluation bar to the SmartGrid, which is displayed in the diagram area, and drop it at the required position. (See ["How to Arrange the Result Windows"](#) on page 94 for more information on positioning the window).

Remote command:

[LAYout:ADD\[:WINDow\]?](#) on page 733 / [LAYout:WINDow<n>:ADD?](#) on page 737

How to Close a Result Window

- ▶ To close a window, activate SmartGrid mode and select the "Delete" icon for the window.

**Remote command:**

[LAYout:REMove\[:WINDow\]](#) on page 735 / [LAYout:WINDow<n>:REMove](#) on page 738

How to Arrange the Result Windows

1. Select an icon from the evaluation bar or the "Move" icon for an existing evaluation window.



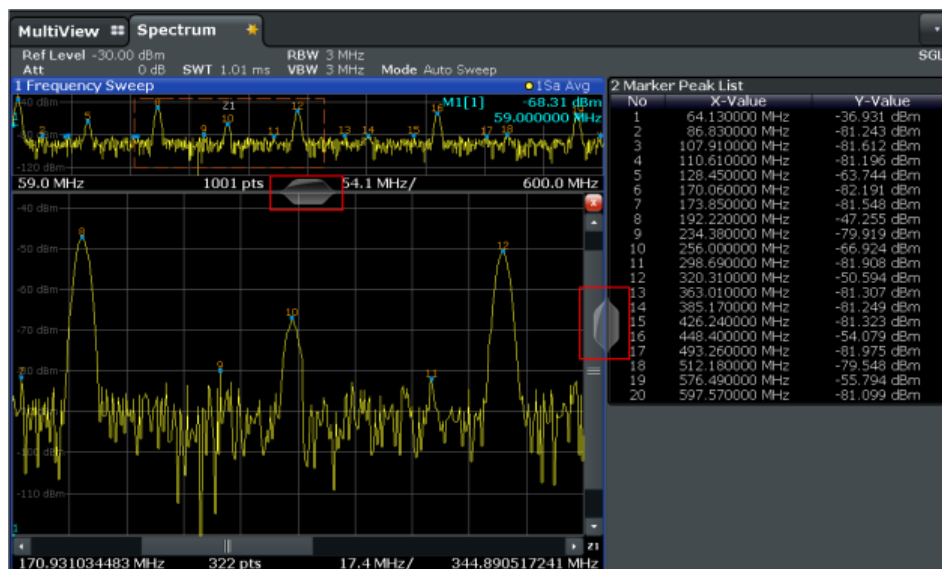
2. Drag the evaluation over the SmartGrid.
A blue area shows where the window will be placed.
3. Move the window until a suitable area is indicated in blue.
4. Drop the window in the target area.
The windows are rearranged to the selected layout, and "Delete" and "Move" icons are displayed in each window.
5. To close a window, select the corresponding "Delete" icon.

**Remote command:**

[LAYout:REPLace\[:WINDow\]](#) on page 735 / [LAYout:WINDow<n>:REPLace](#) on page 738

3.5.5.3 Changing the Size of Windows

Each channel tab may contain several windows to evaluate the measurement results using different methods. A "splitter" allows you to change the size of neighboring windows.



The splitters are not available in SmartGrid mode.

- ▶ To change the size of two neighboring windows, drag the splitter between the windows in either direction.

3.5.5.4 Switching Between a Split and Maximized Window Display

To get an overview of the results, displaying several windows at the same time may be helpful. However, the individual windows may become rather small. In this case it is useful to maximize an individual window to the entire screen temporarily in order to analyze the results in more detail.



To switch between a split and a maximized display without having to close and re-open windows, select the SPLIT/MAXIMIZE key. In maximized display, the currently focused window is maximized. In split display, all active windows are displayed.

3.5.5.5 Changing the Display

The display can be optimized for your individual needs. The following display functions are available and are described in detail in [chapter 9.4, "Display Settings"](#), on page 528 and [chapter 7, "Common Analysis and Display Functions"](#), on page 385.

- Displaying or hiding a simulation of the entire front panel of the instrument on the screen ("Soft Front Panel")
- Displaying the main function hardkeys in a separate window on the screen ("Mini Front Panel")
- Hiding or showing various screen elements
- Selecting a display theme and colors
- Changing the display update rate
- Zooming into the diagram

3.5.6 Getting Help

If any questions or problems concerning the R&S FPS arise, an extensive online help system is provided on the instrument and can be consulted at any time. The help system is context-sensitive and provides information specifically for the current operation or setting to be performed. In addition, general topics provide an overview on complete tasks or function groups as well as background information.

3.5.6.1 Calling Up Help

The online help can be opened at any time by selecting one of the "Help" icons on the toolbar or by selecting the F1 key on an external or the online keyboard.

Calling context-sensitive help

- ▶ To display the "Help" dialog box for the currently focused screen element, e.g. a softkey or a setting in an opened dialog box, select the "Help" icon on the toolbar.



The "Help" dialog box "View" tab is displayed. A topic containing information about the focused screen element is displayed.

If no context-specific help topic is available, a more general topic or the "Contents" tab is displayed.



For standard Windows dialog boxes (e.g. File Properties, Print dialog etc.), no context-sensitive help is available.

- ▶ To display a help topic for a screen element not currently focused:
 - a) Select the "Help pointer" icon on the toolbar.



The pointer changes its shape to a "?" and an arrow.

- b) Select the screen element to change the focus.

A topic containing information about the selected (now focused) screen element is displayed.

3.5.6.2 Using the Help Window

The Help window contains several tabs:

- "View" - shows the selected help topic
- "Contents" - contains a table of help contents
- "Index" - contains index entries to search for help topics
- "Search" - provides text search



The Help toolbar provides some buttons:

- To browse the topics in the order of the table of contents: Up arrow = previous topic, Down arrow = next topic
- To browse the topics visited before: Left arrow = back, Right arrow = forward
- To increase or decrease the font



To search for a topic in the index

The index is sorted alphabetically. You can browse the list, or search for entries in the list.

1. Switch to the "Index" tab.
2. Select the "Keyboard" icon besides the entry field.
3. Enter the first characters of the keyword you are interested in.
The entries containing these characters are displayed.
4. Double-click the suitable index entry.
The "View" tab with the corresponding help topic is displayed.

To search topics for a text string

1. Switch to the "Search" tab.
2. Select the "Keyboard" icon besides the entry field.
3. Enter the string you want to find.
If you enter several strings with blanks between, topics containing all words are found (same as AND operator).

For advanced search, consider the following:

- To find a defined string of several words, enclose it in quotation marks. For example, a search for *"trigger qualification"* finds all topics with exactly *"trigger*

qualification". A search for *trigger qualification* finds all topics that contain the words *trigger* and *qualification*.

- Use "Match whole word" and "Match case" to refine the search.
- Use operators AND, OR, and NOT.

To close the Help window

- ▶ Select the "Close" icon in the upper right corner of the help window.
Or:
Press the ESC key on the front panel.

4 Applications and Operating Modes

The R&S FPS provides several applications for different analysis tasks and different types of signals, e.g. W-CDMA, I/Q analysis or basic spectrum analysis. When you activate an application, a new measurement channel is created which determines the measurement settings for that application. The same application can be activated with different measurement settings by creating several channels for the same application. Each channel is displayed in a separate tab on the screen.



The maximum number of measurement channels may be limited by the available memory on the instrument.

Independent vs correlating measurements

With the **conventional R&S FPS Signal and Spectrum Analyzer** you can perform several different measurements almost simultaneously. However, the individual measurements are independent of each other - **each application captures and evaluates its own set of data**, regardless of what the other applications do.

In some cases it may be useful to **analyze the exact same input data using different applications**. For example, imagine capturing data from a base station and analyzing the RF spectrum in the Analog Demodulation application. If a spur or an unexpected peak occurs, you may want to analyze the same data in the I/Q Analyzer to see the real and imaginary components of the signal and thus detect the reason for the irregular signal. Normally when you switch to a different application, evaluation is performed on the data that was captured by that application, and not the previous one. In our example that would mean the irregular signal would be lost. Therefore, a second operating mode is available in the R&S FPS: Multi-Standard Radio Analyzer (MSRA) mode.

Multi-Standard Radio Analyzer mode

In **Multi-Standard Radio Analyzer (MSRA) mode**, data acquisition is performed once as an I/Q measurement, and the captured data is then evaluated by any number of applications for different radio standards. Data acquisition and global configuration settings are controlled globally, while the evaluation and display settings can be configured individually for each application. Using the Multi-Standard Radio Analyzer, unwanted correlations between different signal components using different transmission standards can be detected. Thus, for example, an irregularity in a GSM burst can be examined closer in the R&S FPS 3G FDD BTS (W-CDMA) application to reveal dependencies like a change in the EVM value.

Distinct operating modes

Although the applications themselves are identical in all operating modes, the handling of the data between applications is not. Thus, the operating mode determines which applications are available and active. Whenever you change the operating mode, the currently active measurement channels are closed. The default operating mode is Signal and Spectrum Analyzer mode; however, the presetting can be changed.

Remote command:

INST:MODE SAN, see [INSTrument:MODE](#) on page 596

Switching between applications

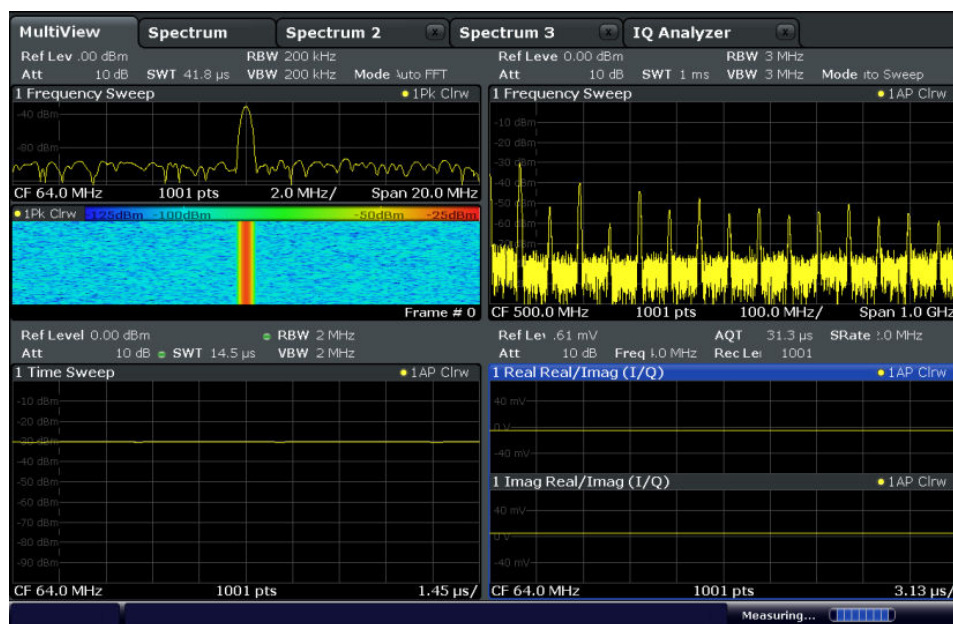
When you switch to a new application, a set of parameters is passed on from the current application to the new one:

- center frequency and frequency offset
- reference level and reference level offset
- attenuation

After initial setup, the parameters for the measurement channel are stored upon exiting and restored upon re-entering the channel. Thus, you can switch between applications quickly and easily.

4.1 R&S MultiView

Each application is displayed in a separate tab. An additional tab ("MultiView") provides an overview of all currently active channels at a glance. In the "MultiView" tab, each individual window contains its own channel bar with an additional button. Select this button to switch to the corresponding channel display quickly.

**Remote command:**

DISPlay:FORMat on page 732

4.2 Available Applications

The R&S FPS provides some applications in the base unit while others are available only if the corresponding firmware options are installed. Not all R&S FPS applications are supported in MSRA mode. For an overview of supported MSRA applications see the R&S FPS MSRA User Manual.



Spectrogram application

Spectrogram measurements are not a separate application, but rather a trace evaluation method, thus they are available as an evaluation method for the Display Configuration, not by creating a new channel. Spectrograms are configured and activated in the "Trace" settings. See [chapter 7.3.1.7, "Working with Spectrograms"](#), on page 403 for details.

Spectrum.....	101
1xEV-DO BTS.....	101
1xEV-DO MS.....	102
3G FDD BTS.....	102
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Analog Demodulation.....	102
cdma2000 BTS.....	102
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Noise Figure.....	103
Phase Noise.....	103
TD-SCDMA BTS.....	104
TD-SCDMA UE.....	104
Vector Signal Analysis (VSA).....	104
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Spectrum

In the Spectrum application the provided functions correspond to those of a conventional spectrum analyzer. The analyzer measures the frequency spectrum of the RF input signal over the selected frequency range with the selected resolution and sweep time, or, for a fixed frequency, displays the waveform of the video signal. This application is used in the initial configuration.

For details see [chapter 5, "Measurements"](#), on page 111.

Remote command:

INST:SEL SAN, see [INSTrument\[:SElect\]](#) on page 597

1xEV-DO BTS

The 1xEV-DO BTS application requires an instrument equipped with the 1xEV-DO BTS Measurements option, R&S FPS-K84. This application provides test measurements for 1xEV-DO BTS downlink signals (base station signals) according to the test specification.

For details see the R&S FPS-K84/-K85 User Manual.

Remote command:

INST:SEL BDO, see [INSTrument\[:SElect\]](#) on page 597

1xEV-DO MS

The 1xEV-DO MS application requires an instrument equipped with the 1xEV-DO MS Measurements option, R&S FPS-K85. This application provides test measurements for 1xEV-DO MS uplink signals (mobile signals) according to the test specification.

For details see the R&S FPS-K84/-K85 User Manual.

Remote command:

INST:SEL MDO, see [INSTrument\[:SElect\]](#) on page 597

3G FDD BTS

The 3G FDD BTS application requires an instrument equipped with the 3GPP Base Station Measurements option, R&S FPS-K72. This application provides test measurements for W-CDMA downlink signals (base station signals) according to the test specification.

For details see the R&S FPS-K72/-K73 User Manual.

Remote command:

INST:SEL BWCD, see [INSTrument\[:SElect\]](#) on page 597

3G FDD UE

The 3G FDD UE application requires an instrument equipped with the 3GPP User Equipment Measurements option, R&S FPS-K73. This application provides test measurements for W-CDMA uplink signals (mobile signals) according to the test specification.

For details see the R&S FPS-K72/-K73 User Manual.

Remote command:

INST:SEL MWCD, see [INSTrument\[:SElect\]](#) on page 597

Analog Demodulation

The Analog Demodulation application requires an instrument equipped with the corresponding optional software. This application provides measurement functions for demodulating AM, FM, or PM signals.

For details see the R&S FPS-K7 User Manual.

Remote command:

INST:SEL ADEM, see [INSTrument\[:SElect\]](#) on page 597

cdma2000 BTS

The cdma2000 BTS application requires an instrument equipped with the cdma2000 BTS Measurements option, R&S FPS-K82. This application provides test measurements for cdma2000 BTS downlink signals (base station signals) according to the test specification.

For details see the R&S FPS-K82/-K83 User Manual.

Remote command:

INST:SEL BC2K, see [INSTrument\[:SElect\]](#) on page 597

cdma2000 MS

The cdma2000 MS application requires an instrument equipped with the cdma2000 MS Measurements option, R&S FPS-K83. This application provides test measurements for cdma2000 MS uplink signals (mobile signals) according to the test specification.

For details see the R&S FPS-K82/-K83 User Manual.

Remote command:

INST:SEL MC2K, see [INSTrument\[:SElect\]](#) on page 597

GSM

The GSM application requires an instrument equipped with the GSM Measurements option R&S FPS-K10. This application provides GSM measurements.

For details see the R&S FPS-K10 User Manual.

Remote command:

INST:SEL GSM, see [INSTrument\[:SElect\]](#) on page 597

I/Q Analyzer

The I/Q Analyzer application provides measurement and display functions for I/Q data.

For details see the R&S FPS I/Q Analyzer User Manual.

Remote command:

INST:SEL IQ, see [INSTrument\[:SElect\]](#) on page 597

LTE

The LTE application requires an instrument equipped with the LTE Measurements option R&S FPS-K10. This application provides LTE measurements.

For details see the R&S FPS-K10x (LTE Downlink) User Manual.

Remote command:

INST:SEL LTE, see [INSTrument\[:SElect\]](#) on page 597

Noise Figure

The Noise Figure application requires an instrument equipped with the Noise Figure Measurements option R&S FPS-K30. This application provides noise figure measurements.

For details see the R&S FPS-K30 User Manual.

Remote command:

INST:SEL NOISE, see [INSTrument\[:SElect\]](#) on page 597

Phase Noise

The Phase Noise application requires an instrument equipped with the Phase Noise Measurements option, R&S FPS-K40. This application provides measurements for phase noise tests.

For details see the R&S FPS-K40 User Manual.

Remote command:

INST:SEL PNOISE, see [INSTrument\[:SElect\]](#) on page 597

TD-SCDMA BTS

The TD-SCDMA BTS application requires an instrument equipped with the TD-SCDMA Base Station Measurements option, R&S FPS-K76. This application provides test measurements for TD-SCDMA downlink signals (base station signals) according to the test specification.

For details see the R&S FPS-K76/-K77 User Manual.

Remote command:

INST:SEL BTDS, see [INSTrument\[:SElect\]](#) on page 597

TD-SCDMA UE

The TD-SCDMA UE application requires an instrument equipped with the TD-SCDMA User Equipment Measurements option, R&S FPS-K77. This application provides test measurements for TD-SCDMA uplink signals (mobile signals) according to the test specification.

For details see the R&S FPS-K76/-K77 User Manual.

Remote command:

INST:SEL MTDS, see [INSTrument\[:SElect\]](#) on page 597

Vector Signal Analysis (VSA)

The VSA application requires an instrument equipped with the Vector Signal Analysis option, R&S FPS-K70. This application provides measurements and evaluations for Vector Signal Analysis.

For details see the R&S FPS-K70 User Manual.

Remote command:

INST:SEL DDEM, see [INSTrument\[:SElect\]](#) on page 597

WLAN

The WLAN application requires an instrument equipped with the WLAN option, R&S FPS-K91/91n. This application provides measurements and evaluations according to the WLAN IEEE 802.11 standards.

For details see the R&S FPS-K91 User Manual.

Remote command:

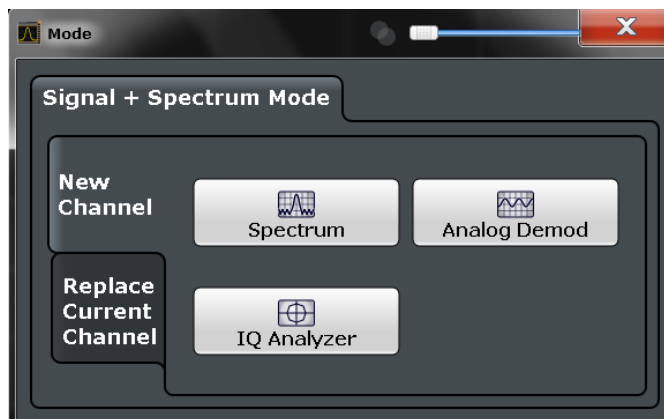
INST:SEL WLAN, see [INSTrument\[:SElect\]](#) on page 597

4.3 Selecting the Operating Mode

The default operating mode is Signal and Spectrum Analyzer mode, however, the pre-setting can be changed.

(See [chapter 9.3.4.5, "General Configuration Settings"](#), on page 520).

Both the operating mode and the application can be selected in the "Mode" dialog box which is displayed when you press the MODE key.



To switch the operating mode, select the corresponding tab.

The remote commands required to perform these tasks are described in [chapter 11.4, "Selecting the Operating Mode and Application"](#), on page 593.

To activate the Signal and Spectrum Analyzer operating mode

1. Select the MODE key.

A dialog box opens that contains all operating modes and applications currently available on your R&S FPS.

2. Select the "Signal and Spectrum Analyzer" tab.

3. Confirm the message informing you that you are changing operating modes.

The R&S FPS stores and closes all active measurement channels in the current operating mode, then opens a new measurement channel for the Signal and Spectrum Analyzer operating mode.

Note: when you return to the previous operating mode, the stored configuration of all measurement channels is restored.

The default Spectrum measurement channel is displayed and the Sequencer is automatically activated in continuous mode (see [chapter 4.5, "Running a Sequence of Measurements"](#), on page 107).

4.4 Starting an Application

The default application in Signal and Spectrum Analyzer mode is a Spectrum measurement.

The application can be selected in the "Mode" dialog box which is displayed when you press the MODE key.

To select an application, select the corresponding button.



The measurement channels are labeled with their default name. If that name already exists, a sequential number is added. In remote control, the name of the measurement channel can be changed. For details and an overview of default names see [table 11-1](#).

Switching between applications

When you switch to a new application, a set of parameters is passed on from the current application to the new one:

- center frequency and frequency offset
- reference level and reference level offset
- attenuation

After initial setup, the parameters for the measurement channel are stored upon exiting and restored upon re-entering the channel. Thus, you can switch between applications quickly and easily.



To deactivate a channel, simply close the corresponding tab.

The remote commands required to perform these tasks are described in [chapter 11.4, "Selecting the Operating Mode and Application"](#), on page 593.

New Channel	106
Replace Current Channel	106
Duplicate Current Channel	106

New Channel

The applications selected on this tab are started in a new channel, i.e. a new tab in the display.

Remote command:

[INSTrument:CREate\[:NEW\]](#) on page 594

[INSTrument\[:SElect\]](#) on page 597

Replace Current Channel

The applications selected on this tab are started in the currently displayed channel, replacing the current application.

Remote command:

[INSTrument:CREate:REPLace](#) on page 594

Duplicate Current Channel

The currently active channel can be duplicated, i.e. a new measurement channel of the same type and with the identical measurement settings is started. The name of the new channel is the same as the copied channel, extended by a consecutive number (e.g. "Spectrum" -> "Spectrum 2").

This command is not available if the MSRA Master channel is selected.

Remote command:


[INSTrument:CREate:DUPLicate](#) on page 593

4.5 Running a Sequence of Measurements

Only one measurement can be performed at any time, namely the one in the currently active channel. However, in order to perform the configured measurements consecutively, a Sequencer function is provided.

- [The Sequencer Concept](#)..... 107
- [Sequencer Settings](#)..... 109
- [How to Set Up the Sequencer](#)..... 109

4.5.1 The Sequencer Concept

The instrument can only be in one specific channel at any time. Thus, only one measurement can be performed at any time, namely the one in the currently active channel. However, in order to perform the configured measurements consecutively, a Sequencer function is provided, which changes the application of the instrument as required. If activated, the measurements configured in the currently active channels are performed one after the other in the order of the tabs. For each individual measurement, the sweep count is considered. Thus, each measurement may consist of several sweeps. The currently active measurement is indicated by a  symbol in the tab label. The result displays of the individual channels are updated in the tabs as the measurements are performed. Sequential operation itself is independent of the currently *displayed* tab.

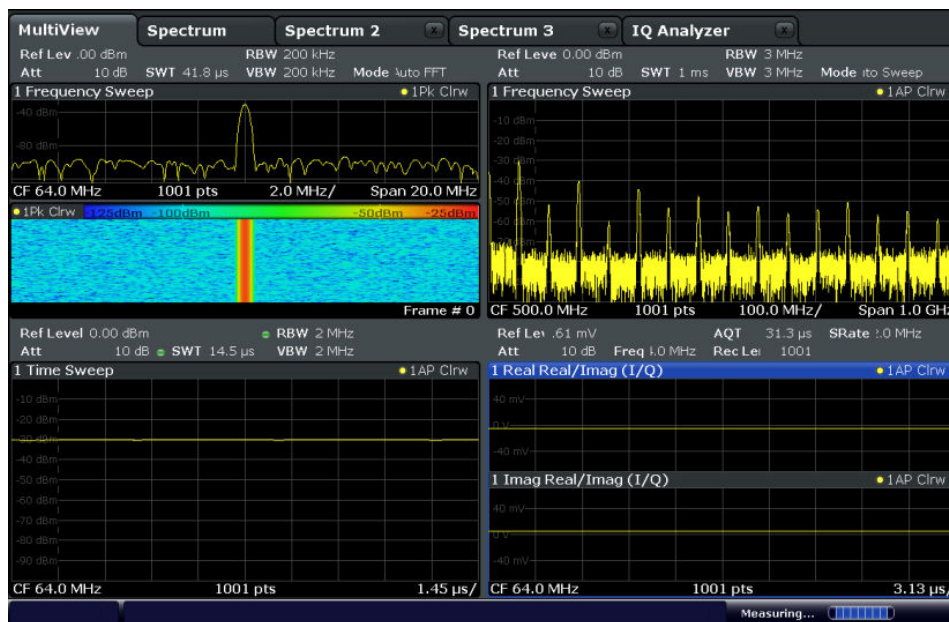
Sequencer modes

Three different Sequencer modes are available:

- **Single Sequence**
Similar to single sweep mode; each measurement is performed once, until all measurements in all active channels have been performed.
- **Continuous Sequence**
Similar to continuous sweep mode; the measurements in each active channel are performed one after the other, repeatedly, in the same order, until sequential operation is stopped. This is the default Sequencer mode.
- **Channel-defined Sequence**
First, a single sequence is performed. Then, only channels in continuous sweep mode are repeated continuously.

Example: Sequencer procedure

Assume the following active channel definition:



Tab name	application	Sweep mode	Sweep count
Spectrum	Spectrum	Cont. Sweep	5
Spectrum 2	Spectrum	Single Sweep	6
Spectrum 3	Spectrum	Cont. Sweep	2
IQ Analyzer	IQ Analyzer	Single Sweep	7

For **single Sequence**, the following sweeps will be performed:

5x Spectrum, 6x Spectrum 2, 2 x Spectrum 3, 7x IQ Analyzer

For **continuous Sequence**, the following sweeps will be performed:

5x Spectrum, 6x Spectrum 2, 2 x Spectrum 3, 7x IQ Analyzer,

5x Spectrum, 6x Spectrum 2, 2 x Spectrum 3, 7x IQ Analyzer,

...

For **channel-defined Sequence**, the following sweeps will be performed:

5x Spectrum, 6x Spectrum 2, 2 x Spectrum 3, 7x IQ Analyzer,

5x Spectrum, 2 x Spectrum 3,

5x Spectrum, 2 x Spectrum 3,

...

RUN SINGLE/RUN CONT and Single Sweep/Sweep Continuous keys

While the Sequencer is active, the RUN SINGLE and RUN CONT keys control the Sequencer, not individual sweeps. RUN SINGLE starts the Sequencer in single mode, while RUN CONT starts the Sequencer in continuous mode.

The "Single Sweep" and "Continuous Sweep" *softkeys* control the sweep mode for the currently selected channel only; the sweep mode only has an effect the next time the Sequencer activates that channel, and only for a channel-defined sequence. In this case, a channel in single sweep mode is swept only once by the Sequencer. A channel in continuous sweep mode is swept repeatedly.

4.5.2 Sequencer Settings



The "Sequencer" menu is available from the toolbar.

Sequencer State.....	109
Sequencer Mode.....	109

Sequencer State

Activates or deactivates the Sequencer. If activated, sequential operation according to the selected Sequencer mode is started immediately.

Remote command:

`SYSTem:SEQuencer` on page 600

`INITiate<n>:SEQuencer:IMMediate` on page 598

`INITiate<n>:SEQuencer:ABORt` on page 598

Sequencer Mode

Defines how often which measurements are performed. The currently selected mode softkey is highlighted blue. During an active Sequencer process, the selected mode softkey is highlighted orange.

"Single Sequence"

Each measurement is performed once, until all measurements in all active channels have been performed.

"Continuous Sequence"

The measurements in each active channel are performed one after the other, repeatedly, in the same order, until sequential operation is stopped.

This is the default Sequencer mode.

"Channel-defined Sequence"

First, a single sequence is performed. Then, only channels in continuous sweep mode are repeated.

Remote command:

`INITiate<n>:SEQuencer:MODE` on page 599

4.5.3 How to Set Up the Sequencer

In order to perform the configured measurements consecutively, a Sequencer function is provided.

1. Configure a channel for each measurement configuration as required, including the sweep mode.

2. In the toolbar, select the "Sequencer" icon.



The "Sequencer" menu is displayed.

3. Toggle the "Sequencer" softkey to "On".

A continuous sequence is started immediately.

4. To change the Sequencer mode and start a new sequence immediately, select the corresponding mode softkey, or press the RUN SINGLE or RUN CONT key.

The measurements configured in the currently active channels are performed one after the other in the order of the tabs until the Sequencer is stopped.

The result displays in the individual channels are updated as the measurements are performed.

To stop the Sequencer

- ▶ To stop the Sequencer temporarily, press the highlighted RUN SINGLE or RUN CONT key (not for a channel-defined sequence). To continue the Sequencer, press the key again.

To stop the Sequencer permanently, select the "Sequencer" icon in the toolbar and toggle the "Sequencer" softkey to "Off".

5 Measurements

In the Spectrum application, the R&S FPS provides a variety of different measurement functions.

- **Basic measurements** - measure the spectrum of your signal or watch your signal in time domain
- **Power measurements** - calculate the powers involved in modulated carrier signals
- **Emission measurements** - detect unwanted signal emission
- **Statistic measurements** - evaluate the spectral distribution of the signal
- **Special measurements** - provide characteristic values of the signal

The individual functions are described in detail in the following chapters.



Measurements on I/Q-based data

The I/Q Analyzer application (*not Master*) in **MSRA mode** can also perform measurements on the captured I/Q data in the time and frequency domain.

The measurements are configured using the same settings as described here for the Spectrum application.

The results, however, may differ slightly as hardware settings are not adapted automatically as for the Spectrum application. Additionally, the analysis interval used for the measurement is indicated as in all MSRA applications.

For more information see the R&S FPS MSRA User Manual.

• Available Measurement Functions.....	111
• Basic Measurements.....	116
• Channel Power and Adjacent-Channel Power (ACLR) Measurement.....	136
• Carrier-to-Noise Measurements.....	187
• Occupied Bandwidth Measurement (OBW).....	190
• Spectrum Emission Mask (SEM) Measurement.....	196
• Spurious Emissions Measurement.....	239
• Statistical Measurements (APD, CCDF).....	252
• Time Domain Power Measurement.....	267
• Harmonic Distortion Measurement.....	271
• Third Order Intercept (TOI) Measurement.....	277
• AM Modulation Depth Measurement.....	287

5.1 Available Measurement Functions

The measurement function determines which settings, functions and evaluation methods are available in the R&S FPS. The various measurement functions are described in detail here. They are selected in the "Select Measurement" dialog box that is displayed when you press the MEAS key or select "Select Measurement" in the configuration "Overview".

When you select a measurement function, the measurement is started with its default settings immediately and the corresponding measurement configuration menu is displayed. The measurement configuration menu can be displayed at any time by pressing the MEAS CONFIG key.

The easiest way to configure measurements is using the configuration "Overview", see [chapter 6.1, "Configuration Overview"](#), on page 291.

In addition to the measurement-specific parameters, the general parameters can be configured as usual, see [chapter 6, "Common Measurement Settings"](#), on page 291. Many measurement functions provide special result displays or evaluation methods; however, in most cases the general evaluation methods are also available, see [chapter 7, "Common Analysis and Display Functions"](#), on page 385.

After a preset, the R&S FPS performs a basic frequency sweep.

Frequency Sweep.....	112
Zero Span.....	112
Ch Power ACLR.....	113
C/N, C/No.....	113
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Spectrum Emission Mask.....	114
Spurious Emissions.....	114
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CCDF.....	114
Time Domain Power.....	115
TOI.....	115
AM Mod Depth.....	115
Harmonic Distortion.....	115
Marker Functions.....	116
All Functions Off.....	116

Frequency Sweep

A common frequency sweep of the input signal over a specified span. Can be used for general purposes to obtain basic measurement results such as peak levels and spectrum traces. The "Frequency" menu is displayed. This is the default measurement if no other function is selected.

Use the general measurement settings to configure the measurement, e.g. via the "Overview" (see [chapter 6, "Common Measurement Settings"](#), on page 291).

Remote command:

[SENSe:]FREQuency:START on page 745, [SENSe:]FREQuency:STOP on page 745

INITiate<n>[:IMMediate] on page 606

INITiate<n>:CONTInuous on page 605

Zero Span

A sweep in the time domain at the specified (center) frequency, i.e. the frequency span is set to zero. The display shows the time on the x-axis and the signal level on the y-axis, as on an oscilloscope. On the time axis, the grid lines correspond to 1/10 of the current sweep time.

Use the general measurement settings to configure the measurement, e.g. via the "Overview" (see [chapter 6, "Common Measurement Settings"](#), on page 291).

Most result evaluations can also be used for zero span measurements, although some functions (e.g. markers) may work slightly differently and some may not be available. If so, this will be indicated in the function descriptions (see [chapter 7, "Common Analysis and Display Functions"](#), on page 385).

Remote command:

[SENSE:] FREQuency: SPAN on page 744
 INITiate<n>[:IMMediate] on page 606
 INITiate<n>:CONTInuous on page 605

Ch Power ACLR

Measures the active channel or adjacent-channel power for one or more carrier signals, depending on the current measurement configuration, and opens a submenu to configure the channel power measurement.

For details see [chapter 5.3, "Channel Power and Adjacent-Channel Power \(ACLR\) Measurement"](#), on page 136.

Remote command:

CALC:MARK:FUNC:POW:SEL ACP, see [CALCulate<n>:MARKer<m>:FUNCTION:POWer:SElect](#) on page 609

Results:

CALC:MARK:FUNC:POW:RES? ACP, see [CALCulate<n>:MARKer<m>:FUNCTION:POWer<sb>:RESult?](#) on page 607
[chapter 11.5.3, "Measuring the Channel Power and ACLR"](#), on page 611

C/N, C/No

Measures the carrier/noise ratio and opens a submenu to configure the measurement. Measurements without (C/N) and measurements with reference to the bandwidth (C/No) are possible.

Carrier/noise measurement is only possible in the frequency domain (span > 0).

For details see [chapter 5.4, "Carrier-to-Noise Measurements"](#), on page 187.

Remote command:

CALC:MARK:FUNC:POW:SEL CN | CN0 [CALCulate<n>:MARKer<m>:FUNCTION:POWer:SElect](#) on page 609

Results:

CALC:MARK:FUNC:POW:RES? CN | CN0, see [CALCulate<n>:MARKer<m>:FUNCTION:POWer<sb>:RESult?](#) on page 607
[chapter 11.5.4, "Measuring the Carrier-to-Noise Ratio"](#), on page 647

OBW

Measures the occupied bandwidth, i.e. the bandwidth which must contain a defined percentage of the power, and opens a submenu to configure the measurement. For details see [chapter 5.5, "Occupied Bandwidth Measurement \(OBW\)"](#), on page 190.

OBW measurement is only possible in the frequency domain (span > 0).

Remote command:

CALC:MARK:FUNC:POW:SEL OBWCALCulate<n>:MARKer<m>:FUNCTION:POWer:
SElect on page 609

Results:

CALC:MARK:FUNC:POW:RES? OBW, see CALCulate<n>:MARKer<m>:FUNCTION:
POWer<sb>:RESult? on page 607
chapter 11.5.5, "Measuring the Occupied Bandwidth", on page 647

Spectrum Emission Mask

Activates a Spectrum Emission Mask (SEM) measurement, which monitors compliance with a spectral mask, and opens a submenu to configure the measurement.

For details see chapter 5.6, "Spectrum Emission Mask (SEM) Measurement", on page 196.

Remote command:

SENS:SWE:MODE ESP, see [SENSe:]SWEep:MODE on page 651

Results:

CALC:MARK:FUNC:POW:RES? CPOW | PPOW, see CALCulate<n>:MARKer<m>:
FUNCTION:POWer<sb>:RESult? on page 607
CALC:LIM:FAIL?, see CALCulate<n>:LIMit<k>:FAIL? on page 877
TRACe<n>[:DATA] on page 813
TRACe<n>[:DATA]:X? on page 815
chapter 11.5.6, "Measuring the Spectrum Emission Mask", on page 649

Spurious Emissions

Activates the Spurious Emissions measurement, which monitors unwanted RF products outside the assigned frequency band generated by an amplifier. A submenu to configure the measurement is opened.

For details see chapter 5.7, "Spurious Emissions Measurement", on page 239.

Remote command:

SENS:SWE:MODE LIST, see [SENSe:]SWEep:MODE on page 651

Results:

TRAC:DATA? SPUR, see TRACe<n>[:DATA] on page 813
chapter 11.5.7, "Measuring Spurious Emissions", on page 684

APD

Measures the amplitude probability density (APD) and opens a submenu to configure the measurement.

For details see chapter 5.8, "Statistical Measurements (APD, CCDF)", on page 252.

Remote command:

CALCulate<n>:STATistics:APD[:STATe] on page 697

Results:

CALCulate<n>:STATistics:RESult<t>? on page 704

CCDF

Measures the complementary cumulative distribution function (CCDF) and opens a submenu to configure the measurement.

For details see [chapter 5.8, "Statistical Measurements \(APD, CCDF\)"](#), on page 252.

Remote command:

[CALCulate<n>:STATistics:CCDF\[:STATe\]](#) on page 697

Results:

[CALCulate<n>:STATistics:CCDF:X<t>?](#) on page 704

[CALCulate<n>:STATistics:RESult<t>?](#) on page 704

Time Domain Power

Measures the power in zero span and opens a submenu to configure the measurement. For details see [chapter 5.2, "Basic Measurements"](#), on page 116.

A time domain power measurement is only possible for zero span.

Remote command:

[CALCulate<n>:MARKer<m>:FUNCTION:SUMMary\[:STATe\]](#) on page 708
[chapter 11.5.9, "Measuring the Time Domain Power"](#), on page 706

TOI

Measures the third order intercept point and opens a submenu to configure the measurement.

For details see [chapter 5.11, "Third Order Intercept \(TOI\) Measurement"](#), on page 277.

Remote command:

[CALCulate<n>:MARKer<m>:FUNCTION:TOI\[:STATe\]](#) on page 719

[CALCulate<n>:MARKer<m>:FUNCTION:TOI:RESult?](#) on page 719

[chapter 11.5.11, "Measuring the Third Order Intercept Point"](#), on page 718

AM Mod Depth

Measures the AM modulation depth and opens a submenu to configure the measurement. An AM-modulated carrier is required in the window to ensure correct operation.

For details see [chapter 5.12, "AM Modulation Depth Measurement"](#), on page 287.

Remote command:

[CALCulate<n>:MARKer<m>:FUNCTION:MDEPth\[:STATe\]](#) on page 721

[CALCulate<n>:MARKer<m>:FUNCTION:MDEPth:RESult?](#) on page 721

[chapter 11.5.12, "Measuring the AM Modulation Depth"](#), on page 720

Harmonic Distortion

Measures the harmonic distortion, including the total harmonic distortion, and opens a submenu to configure the measurement.

For details see [chapter 5.10, "Harmonic Distortion Measurement"](#), on page 271.

Remote command:

[CALCulate<n>:MARKer<m>:FUNCTION:HARMonics\[:STATe\]](#) on page 715

First harmonic: [CALCulate<n>:MARKer<m>:FUNCTION:CENTer](#) on page 741.

THD: [CALCulate<n>:MARKer<m>:FUNCTION:HARMonics:DISToRtion?](#)
on page 717

List of harmonics: [CALCulate<n>:MARKer<m>:FUNCTION:HARMonics:LIST?](#)
on page 717

[chapter 11.5.10, "Measuring the Harmonic Distortion"](#), on page 715

Marker Functions

In addition to the measurement functions, some special marker functions are available. See [chapter 7.4.3, "Marker Function Configuration"](#), on page 450.

All Functions Off

Switches off all measurement functions and returns to a basic frequency sweep.

5.2 Basic Measurements

Basic measurements are common sweeps in the time or frequency domain which provide an overview of the basic input signal characteristics.

If no other measurement function is selected, or if all measurement functions are switched off, the R&S FPS performs a basic frequency or time sweep. After a preset, a frequency sweep is performed.

Use the general measurement settings to configure the measurement, e.g. via the "Overview" (see [chapter 6, "Common Measurement Settings"](#), on page 291).

5.2.1 How to Perform a Basic Sweep Measurement

To perform one or more single sweeps

1. Configure the frequency and span to be measured ("Frequency" dialog box, see [chapter 6.3, "Frequency and Span Configuration"](#), on page 333).
2. Configure the number of sweeps to be performed in a single measurement ("Sweep Config" dialog box, see ["Sweep / Average Count"](#) on page 361).
3. If necessary, configure how the signal is processed internally ("Bandwidth" dialog box, see ["Sweep Type"](#) on page 362).
4. If necessary, configure a trigger for the measurement ("Trigger/Gate Settings" dialog box, see [chapter 6.6, "Trigger and Gate Configuration"](#), on page 366).
5. Define how the results are evaluated for display ("Trace" dialog box, see [chapter 7.3.2.1, "Trace Settings"](#), on page 409).
6. If necessary, configure the vertical axis of the display ("Amplitude" dialog box, see [chapter 6.4, "Amplitude and Vertical Axis Configuration"](#), on page 342).
7. To start the measurement, select one of the following:
 - RUN SINGLE key
 - "Single Sweep" softkey in the "Sweep" menu

The defined number of sweeps are performed, then the measurement is stopped. While the measurement is running, the RUN SINGLE key is highlighted. To abort the measurement, press the RUN SINGLE key again. The key is no longer highlighted. The results are not deleted until a new measurement is started.

8. To repeat the same number of sweeps without deleting the last trace, select the "Continue Single Sweep" softkey in the "Sweep" menu.

To start continuous sweeping

1. If you want to average the trace or search for a maximum over more (or less) than 10 sweeps, configure the "Average/Sweep Count" ("Sweep Config" dialog box, see ["Sweep / Average Count"](#) on page 361).
2. To start the measurement, select one of the following:
 - RUN CONT key
 - "Continuous Sweep" softkey in the "Sweep" menu

After each sweep is completed, a new one is started automatically. While the measurement is running, the RUN CONT key is highlighted. To stop the measurement, press the RUN CONT key again. The key is no longer highlighted. The results are not deleted until a new measurement is started.

5.2.2 Measurement Examples - Measuring a Sinusoidal Signal

One of the most common measurement tasks that can be handled using a signal analyzer is determining the level and frequency of a signal. When measuring an unknown signal, you can usually start with the presets.

NOTICE

High input values

If levels higher than +30 dBm (=1 W) are expected or are possible, a power attenuator must be inserted before the RF input of the analyzer. Otherwise, signal levels exceeding 30 dBm can damage the RF attenuator or the input mixer. The total power of all occurring signals must be taken into account.

Test setup

- Connect the RF output of the signal generator to the RF input of the R&S FPS.

Table 5-1: Signal generator settings (e.g. R&S SMW)

Frequency	128 MHz
Level	-30 dBm

- [Measuring the Level and Frequency Using Markers](#).....117
- [Measuring the Signal Frequency Using the Signal Counter](#)..... 119

5.2.2.1 Measuring the Level and Frequency Using Markers

The level and frequency of a sinusoidal signal can be measured easily using the marker function. The R&S FPS always displays its amplitude and frequency at the marker position. The frequency measurement uncertainty is determined by the refer-

ence frequency of the R&S FPS, the resolution of the marker frequency display and the number of sweep points.

1. Select PRESET to reset the instrument.
2. Connect the signal to be measured to the RF INPUT connector on the R&S FPS.
3. Set the center frequency to *128 MHz*.
4. Reduce the frequency span to *1 MHz*.

Note: Coupled settings. When the frequency span is defined, the resolution bandwidth, the video bandwidth and the sweep time are automatically adjusted, because these functions are defined as coupled functions in the presets.

5. Select MKR to activate marker 1 and automatically set it to the maximum of the trace.

The level and frequency values measured by the marker are displayed in the marker information at the top of the display.

Note: Performing a peak search. When a marker is initially activated, it automatically performs the peak search function (as shown in the example).

If a marker was already active, select the PEAK SEARCH key or the "Peak" soft-key in the MKR > menu in order to set the currently active marker to the maximum of the displayed signal.

Increasing the Frequency Resolution

The frequency resolution of the marker is determined by the resolution of the trace. A trace consists of 1001 trace points, i.e. if the frequency span is 1 MHz, each trace point represents a span of approximately 1 kHz. This corresponds to a maximum uncertainty of +/- 0.5 kHz.

You can increase the resolution of the trace by reducing the frequency span.

Reducing the frequency span to 10 kHz

- ▶ Reduce the frequency span to *1 MHz*.

The resolution of the trace is now approximately 10 Hz (10 kHz span / 1001 trace points), thus, the precision of the marker frequency display increases to approximately ±5 Hz.

Setting the Reference Level

The reference level is the level at the upper limit of the diagram. To achieve the widest dynamic range possible for a spectrum measurement, use the entire level span of the R&S FPS. In other words, the highest level that occurs in the signal should be located at the top edge of the diagram (= reference level) or immediately below it.



Low Reference Levels

If the selected reference level is lower than the highest signal that occurs in the spectrum, the signal path in the R&S FPS is overloaded.

In this case, the message "IFOVL" is displayed in the error message field.

In the presets, the value of the reference level is 0 dBm. If the input signal is -30 dBm, the reference level can be reduced by 30 dB without causing the signal path to be overloaded.

Reducing the reference level by 30 dB

- ▶ Set the reference level to *-30 dBm*.

The maximum of the trace is near the maximum of the measurement diagram. The increase in the displayed noise is not substantial. Thus, the distance between the signal maximum and the noise display (=dynamic range) has increased.

Setting the reference level with the help of a marker

You can also use a marker to shift the maximum value of the trace directly to the top edge of the diagram. If the marker is located at the maximum level of the trace (as in this example), the reference level can be moved to the marker level as follows:

1. Press the MKR -> key.
2. Select "Ref Lvl = Mkr Lvl".

The reference level is set to the current marker level.

5.2.2.2 Measuring the Signal Frequency Using the Signal Counter

The built-in signal counter allows you to measure the frequency more accurately than measuring it with the marker. The frequency sweep is stopped at the marker, and the R&S FPS measures the frequency of the signal at the marker position (see also [chapter 7.4.1.5, "Performing a Highly Accurate Frequency Measurement \(Signal Count\)"](#), on page 432).

In the following example, the frequency of the generator at 128 MHz is shown using the marker.

Prerequisite

Precise frequency measurements require a precise reference frequency. Therefore, an external reference frequency from the signal generator is used. Connect the signal generator's "Ref OUT" connector to the analyzer's "Ref IN" connector.

1. Select PRESET to reset the instrument.
2. Set the center frequency to *128 MHz*.
3. Set the frequency span to *1 MHz*.

4. Select "Setup" > "Reference" > "External Reference 10 MHz" to activate the external reference frequency.
5. Select MKR to activate marker 1 and automatically set it to the maximum of the trace.
The level and the frequency of the marker are displayed in the marker results in the diagram or the marker table.
6. Select MKR FUNC > "Signal Count" to activate the signal counter.
The result of the signal counter is displayed in the marker results.
7. If necessary, increase the resolution of the signal counter by selecting "Signal Count Resolution" (in the "Signal Count" menu).



Prerequisites for using the internal signal counter

In order to obtain a correct result when measuring the frequency with the internal signal counter, an RF sinusoidal signal or a spectral line must be available. The marker must be located more than 25 dB above the noise level to ensure that the specified measurement accuracy is adhered to.

5.2.3 Measurement Example – Measuring Levels at Low S/N Ratios

The minimum signal level a signal analyzer can measure is limited by its intrinsic noise. Small signals can be swamped by noise and therefore cannot be measured. For signals that are just above the intrinsic noise, the accuracy of the level measurement is influenced by the intrinsic noise of the R&S FPS.

The displayed noise level of a signal analyzer depends on its noise figure, the selected RF attenuation, the selected reference level, the selected resolution and video bandwidth and the detector.

For details see:

- [chapter 6.4.1.2, "RF Attenuation"](#), on page 344
- [chapter 6.4.1.1, "Reference Level"](#), on page 342
- [chapter 6.5.1.1, "Separating Signals by Selecting an Appropriate Resolution Bandwidth"](#), on page 352
- [chapter 6.5.1.2, "Smoothing the Trace Using the Video Bandwidth"](#), on page 353
- [chapter 7.3.1.1, "Mapping Samples to sweep Points with the Trace Detector"](#), on page 397

This measurement example shows the different factors influencing the S/N ratio.

Table 5-2: Signal generator settings (e.g. R&S SMW)

Frequency	128 MHz
Level	-95 dBm

1. Preset the R&S FPS.

2. Set the center frequency to *128 MHz*.
3. Set the span to *100 MHz*.
4. Set the reference level to *-30 dBm*.

The signal is measured with the auto peak detector and is completely hidden in the intrinsic noise of the R&S FPS.

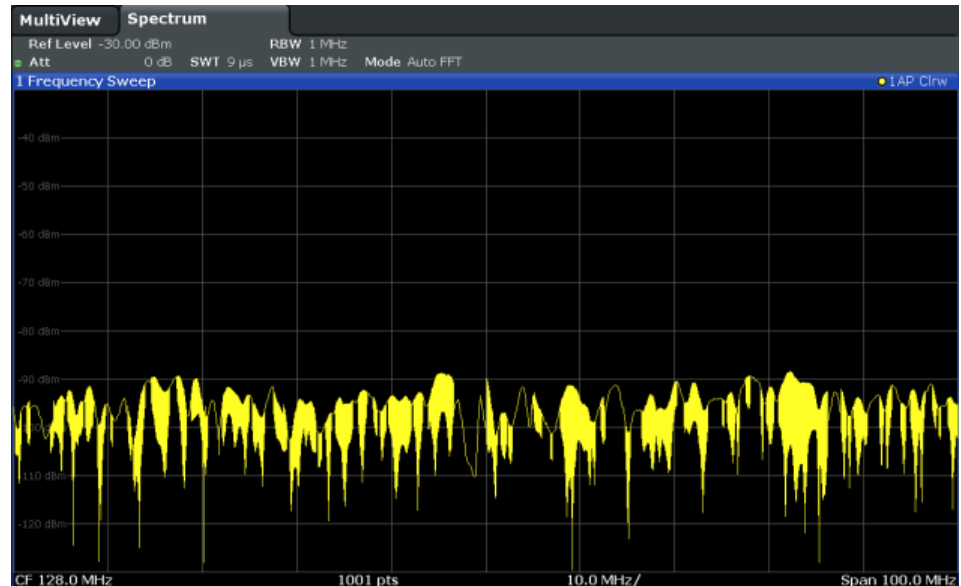


Fig. 5-1: Sine wave signal with low S/N ratio

5. To suppress noise spikes, average the trace. In the "Traces" configuration dialog, set the "Trace mode" to "Average" (see ["Trace Mode"](#) on page 410).

The traces of consecutive sweeps are averaged. To perform averaging, the R&S FPS automatically switches on the sample detector. The RF signal, therefore, can be more clearly distinguished from noise.

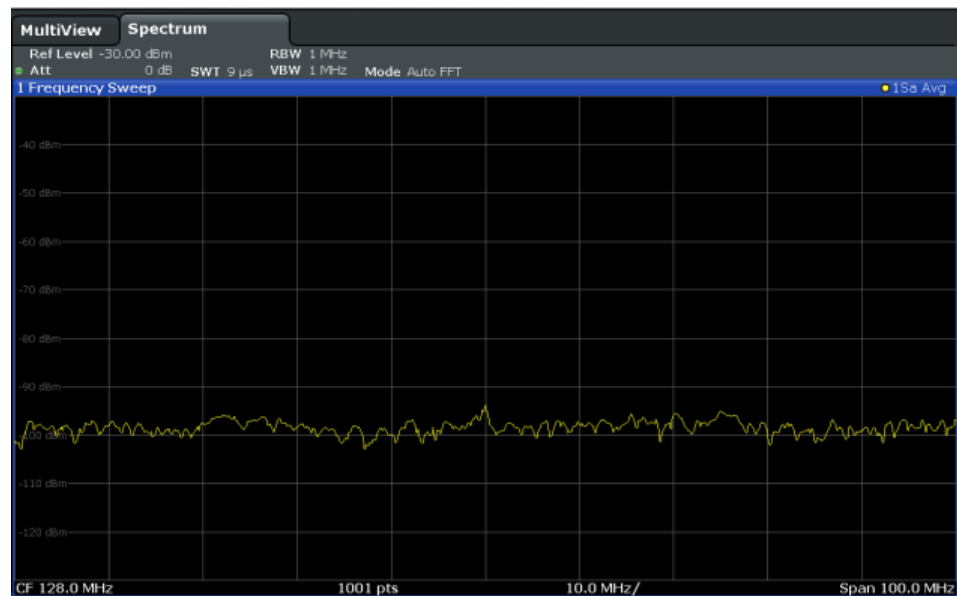


Fig. 5-2: RF sine wave signal with low S/N ratio with an averaged trace

6. Instead of trace averaging, you can select a video filter that is narrower than the resolution bandwidth. Set the trace mode back to "Clear Write", then set the VBW to 10 kHz manually in the "Bandwidth" configuration dialog.

The RF signal can be distinguished from noise more clearly.

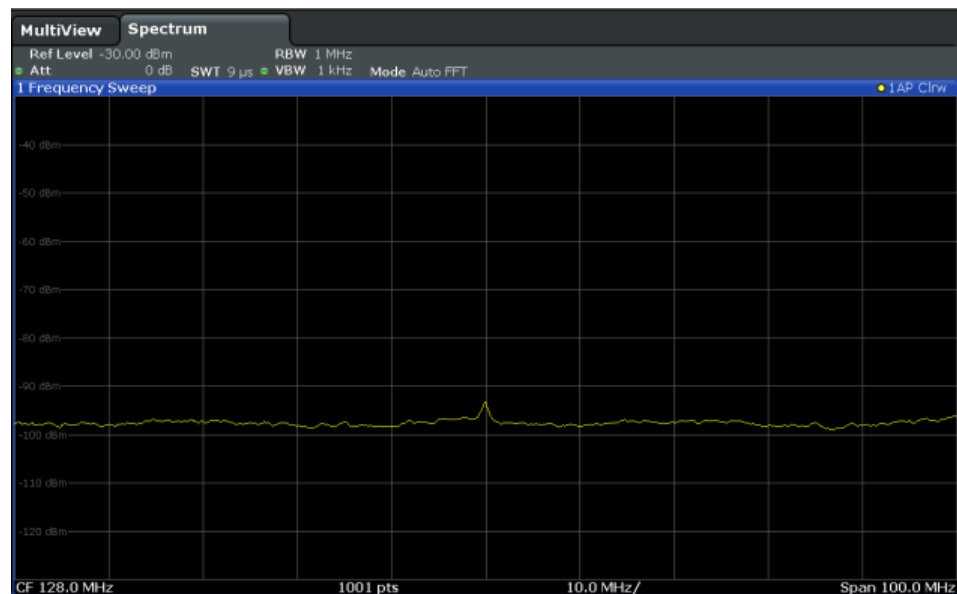


Fig. 5-3: RF sine wave signal with low S/N ratio with a smaller video bandwidth

7. By reducing the resolution bandwidth by a factor of 10, the noise is reduced by 10 dB. Set the RBW to 100 kHz.

The displayed noise is reduced by approximately 10 dB. The signal, therefore, emerges from noise by about 10 dB. Compared to the previous setting, the video bandwidth has remained the same, i.e. it has increased relative to the smaller resolution bandwidth. The averaging effect of the video bandwidth is therefore reduced. The trace will be noisier.

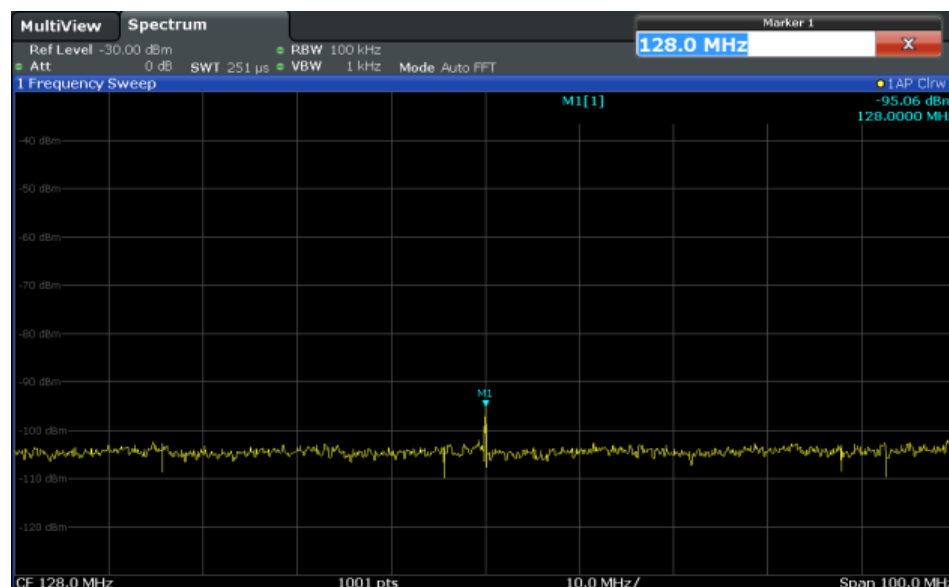


Fig. 5-4: Reference signal at a smaller resolution bandwidth

5.2.4 Measurement Examples - Measuring Signal Spectra with Multiple Signals

- [Separating Signals by Selecting the Resolution Bandwidth](#)..... 123
- [Measuring the Modulation Depth of an AM-Modulated Carrier in the Frequency Domain](#).....127
- [Measuring AM-Modulated Signals](#)..... 128

5.2.4.1 Separating Signals by Selecting the Resolution Bandwidth

A basic feature of a Signal and Spectrum Analyzer is the ability to separate the spectral components of a mixture of signals. The resolution at which the individual components can be separated is determined by the resolution bandwidth. Selecting a resolution bandwidth that is too large may make it impossible to distinguish between spectral components, i.e. they are displayed as a single component (see also [chapter 6.5.1.1, "Separating Signals by Selecting an Appropriate Resolution Bandwidth"](#), on page 352).

Two signals with the same amplitude can be resolved if the resolution bandwidth is smaller than or equal to the frequency spacing of the signal. If the resolution bandwidth is equal to the frequency spacing, the spectrum display shows a level drop of 3 dB precisely in the center of the two signals. Decreasing the resolution bandwidth makes the level drop larger, which thus makes the individual signals clearer.

In this measurement example we will analyze two signals with a level of -30 dBm each and a frequency spacing of 30 kHz.

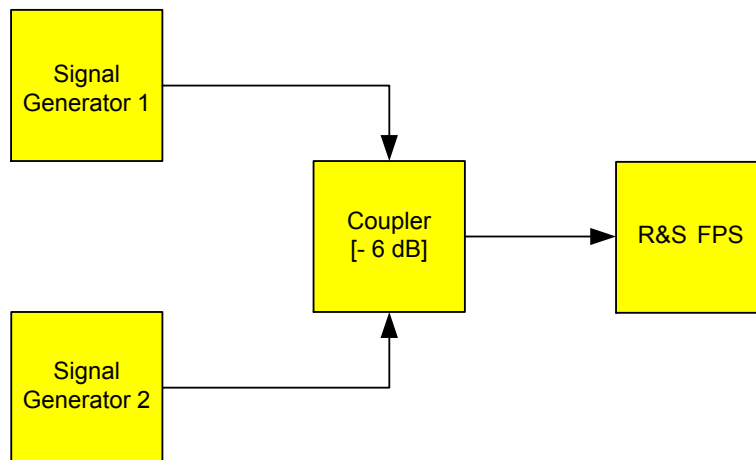


Fig. 5-5: Test setup

Table 5-3: Signal generator settings (e.g. R&S SMW)

	Level	Frequency
Signal generator 1	-30 dBm	128,00 MHz
Signal generator 2	-30 dBm	128,03 MHz

1. Select PRESET to reset the instrument.
2. Set the center frequency to *128.015 MHz*.
3. Set the frequency span to *300 kHz*.
4. Set the resolution bandwidth to *30 kHz* and the video bandwidth to *1 kHz*.

Note: Larger video bandwidths. The video bandwidth is set to 1 kHz in order to make the level drop in the center of the two signals clearly visible. At larger video bandwidths, the video voltage that results from envelope detection is not sufficiently suppressed. This produces additional voltages, which are visible in the trace, in the transition area between the two signals.

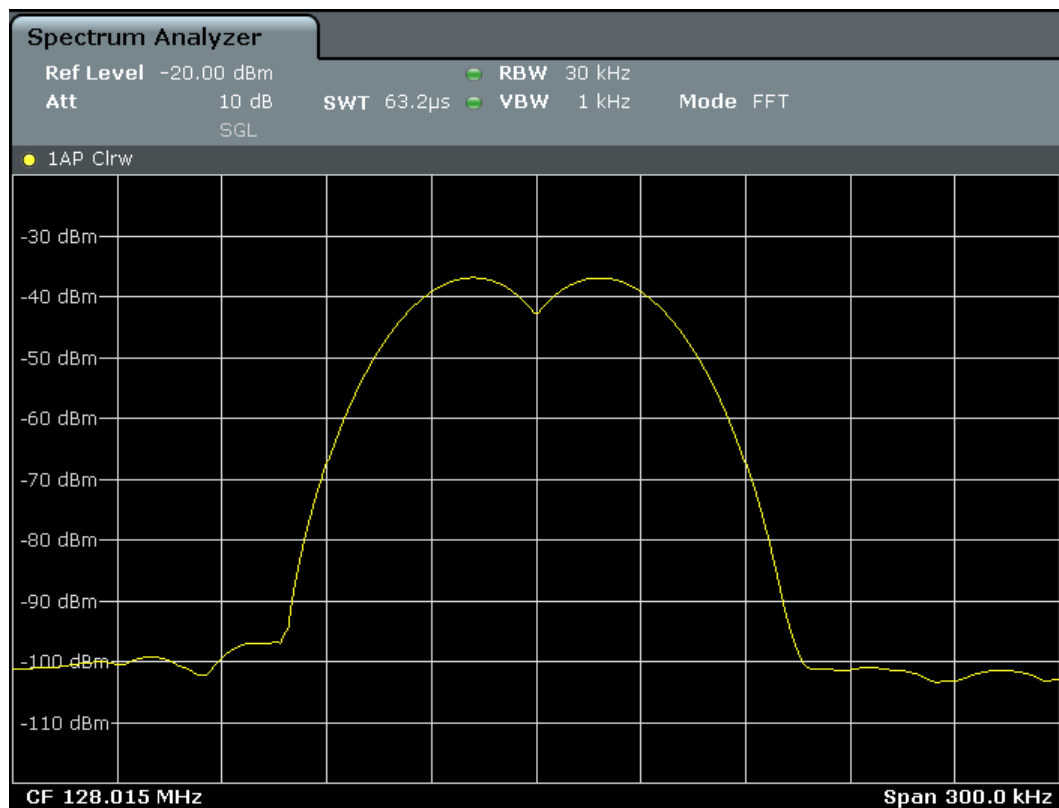


Fig. 5-6: Measurement of two equally-leveled RF sinusoidal signals with the resolution bandwidth which corresponds to the frequency spacing of the signals

Matching generator and R&S FPS frequencies

The level drop is located exactly in the center of the display only if the generator frequencies match the frequency display of the R&S FPS exactly. To achieve exact matching, the frequencies of the generators and the R&S FPS must be synchronized.

- Set the resolution bandwidth to 100 kHz.

It is no longer possible to clearly distinguish the two generator signals.

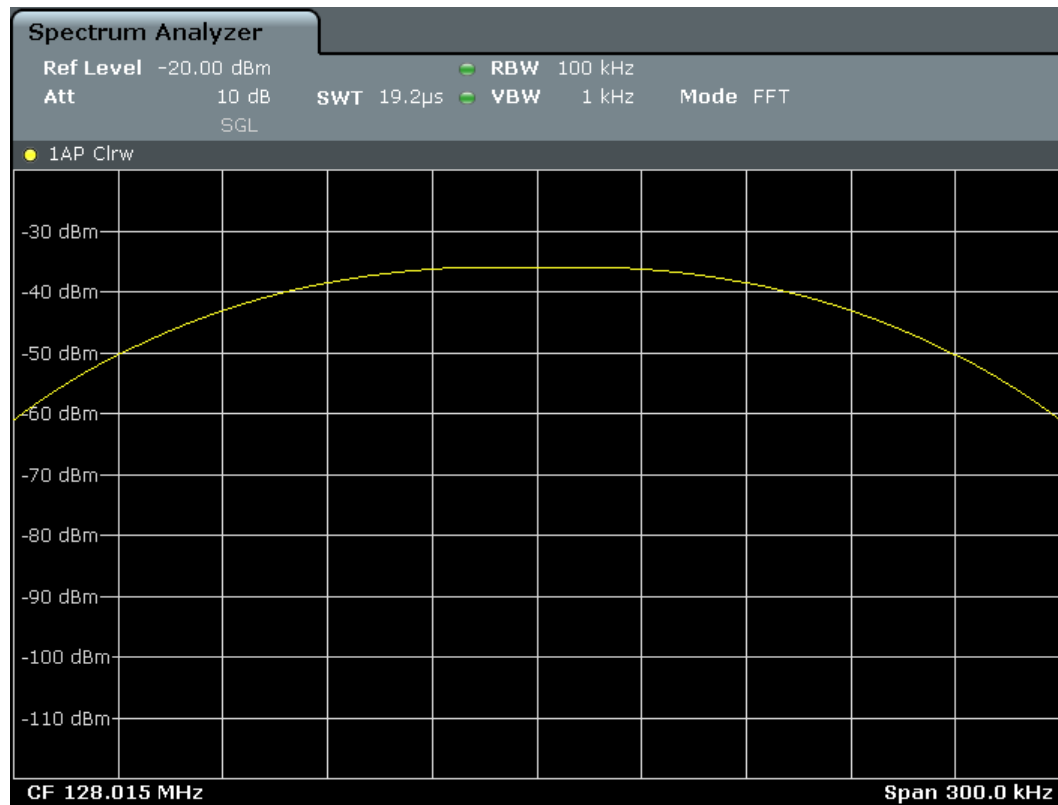


Fig. 5-7: Measurement of two equally-leveled RF sinusoidal signals with a resolution bandwidth which is larger than their frequency spacing

6. Set the resolution bandwidth to 1 kHz.

The two generator signals are shown with high resolution. However, the sweep time becomes longer. At smaller bandwidths, the noise display decreases simultaneously (10 dB decrease in noise floor for a decrease in bandwidth by a factor of 10).

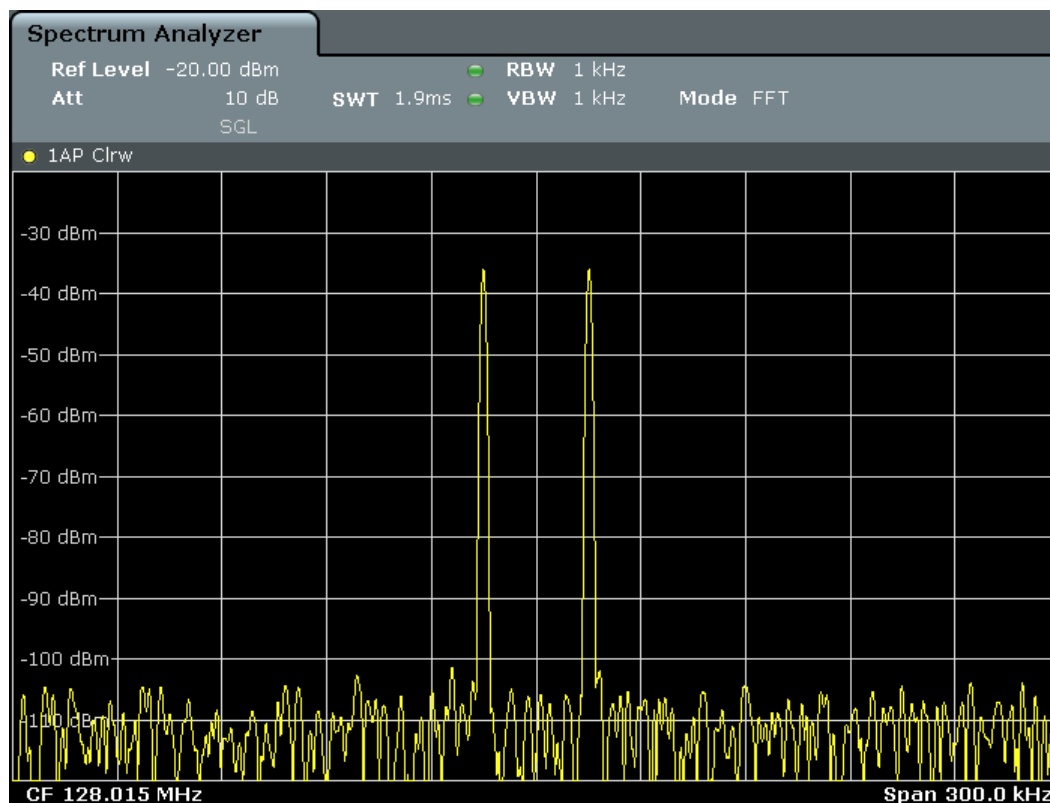


Fig. 5-8: Measurement of two equally-leveled RF sinusoidal signals with a resolution bandwidth (1 kHz) which is significantly smaller than their frequency spacing

5.2.4.2 Measuring the Modulation Depth of an AM-Modulated Carrier in the Frequency Domain

In the frequency range display, the AM side bands can be resolved with a narrow bandwidth and measured separately. The modulation depth of a carrier modulated with a sinusoidal signal can then be measured. Since the dynamic range of a signal analyzer is very large, extremely small modulation depths can also be measured precisely. For this purpose, the R&S FPS provides measurement routines that output the modulation depth numerically in percent directly.

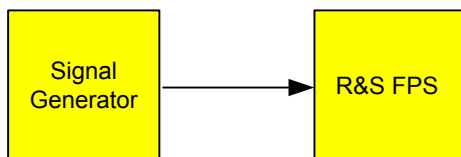


Fig. 5-9: Test setup

Table 5-4: Signal generator settings (e.g. R&S SMW)

Frequency	128 MHz
Level	-30 dBm
Modulation	50 % AM, 10 kHz AF

1. Select PRESET to reset the instrument.
2. Set the center frequency to 128 MHz.
3. Set the frequency span to 50 kHz.
4. Select MEAS > "AM Modulation Depth" to activate the modulation depth measurement.

The R&S FPS automatically sets a marker to the carrier signal in the center of the diagram and one delta marker each to the upper and lower AM sidebands. The R&S FPS calculates the AM modulation depth from the level differences of the delta markers to the main marker and outputs the numeric value in the marker information.

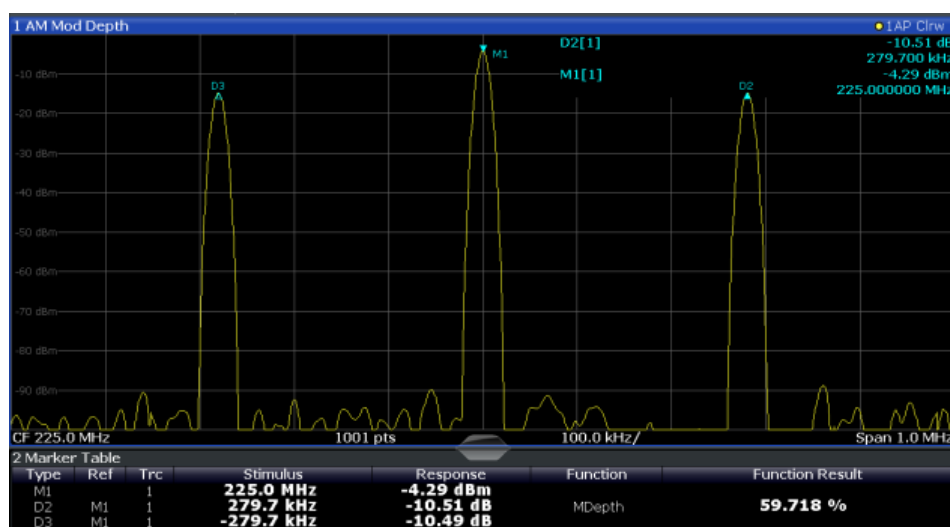


Fig. 5-10: Measurement of the AM modulation depth

The modulation depth is displayed as "MDepth". The frequency of the AF signal can be obtained from the frequency display of the delta marker.

5.2.4.3 Measuring AM-Modulated Signals

The R&S FPS rectifies the RF input signal (that is, removes the negative parts) and displays it as a magnitude spectrum. The rectification also demodulates AM-modulated signals. The AF voltage can be displayed in zero span if the modulation sidebands fall within the resolution bandwidth.

Displaying the AF of an AM-modulated signal (Zero Span)

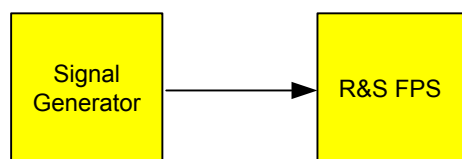


Fig. 5-11: Test setup

Table 5-5: Signal generator settings (e.g. R&S SMW)

Frequency	128 MHz
Level	-30 dBm
Modulation	50 % AM, 1 kHz AF

1. Select PRESET to reset the instrument.
2. Set the center frequency to *128 MHz*.
3. Set the frequency span to *0 Hz* or select "Zero Span".
4. Set the sweep time to *2.5 ms*.
5. Set the reference level to *6 dBm* and the display range to linear (AMPT > "Scale Config" > "Scaling: Linear Percent").
6. Define triggering in response to the AF signal using the video trigger to produce a static image.
 - a) Press the TRIG key.
 - b) Select "Video".
 - c) Set the "Trg/Gate Level" to *50%*.

The trigger level is displayed as a horizontal line across the entire measurement diagram. The R&S FPS displays the 1 kHz AF signal as a static image in zero span.

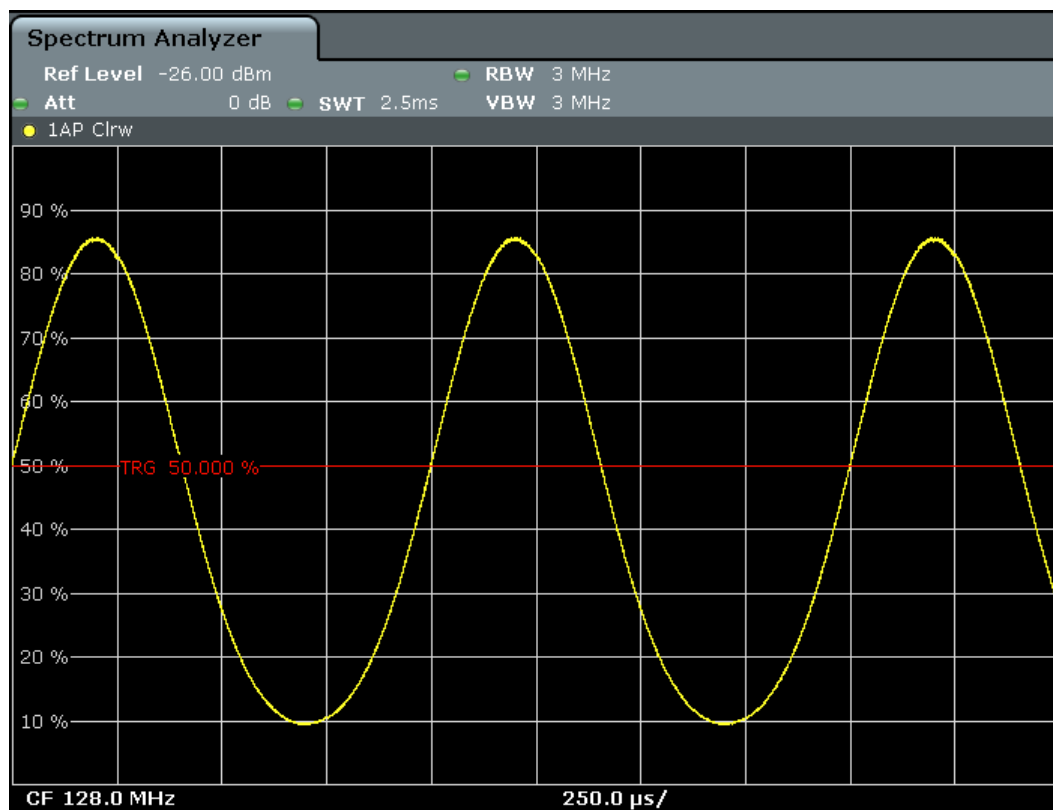


Fig. 5-12: Measurement of the AF signal of a carrier that is AM-modulated with 1 kHz

5.2.5 Measurement Examples in Zero Span

For radio transmission systems that use the TDMA method (for example, GSM), transmission quality is determined not only by spectral characteristics but also by characteristics in zero span. A timeslot is assigned to each user since several users share the same frequency. Smooth operation is ensured only if all users adhere exactly to their assigned timeslots.

Both the power during the send phase as well as the timing and duration of the TDMA burst, and rise and fall times of the burst, are important.

- [Measuring the Power Characteristic of Burst Signals](#)..... 130
- [Measuring the Signal-to-Noise Ratio of Burst Signals](#)..... 134

5.2.5.1 Measuring the Power Characteristic of Burst Signals

To measure power in zero span, the R&S FPS offers easy-to-use functions that measure the power over a predefined time.

Measuring the Power of a GSM Burst During the Activation Phase

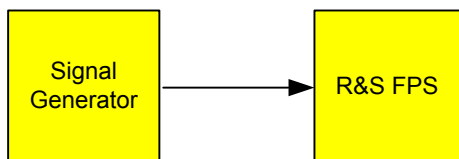


Fig. 5-13: Test setup

Table 5-6: Signal generator settings (e.g. R&S SMW)

Frequency	890 MHz
Level	0 dBm
Modulation	GSM, one timeslot activated

1. Select PRESET to reset the instrument.
2. Set the center frequency to *890 MHz* (FREQ).
3. Set the frequency span to *0 Hz* (SPAN > "Zero Span").
4. Set the reference level to *10 dBm* (= level of the signal generator +10 dB) (AMPT).
5. Set the attenuation to *20 dB* (AMPT > "Rf Atten Manual").
6. Set the resolution bandwidth to *1 MHz* (BW > "Res BW").
7. Set the sweep time to *1 ms* (SWEEP > "Sweeptime Manual").
The R&S FPS shows the GSM burst continuously across the display.
8. Using the video trigger, set triggering on the rising edge of the burst.
 - a) Press the TRIG key.
 - b) Set the "Trg/Gate Source" to "Video".
 - c) Set the "Trg/Gate Level" to *70%*.

The R&S FPS shows a static image with the GSM burst at the start of the trace.
The trigger level is displayed as a horizontal line labeled with the absolute level for the trigger threshold in the measurement diagram.
9. Activate power measurement within the activation phase of the burst in zero span.
 - a) Press the MEAS key.
 - b) Select "Time Domain Power".
 - c) Select "Time Dom Power Config".
 - d) Set the "Limits" state to "On".
 - e) Select the "Left Limit" input field.
 - f) Using the navigation keys, move the vertical line "S1" to the start of the burst.
 - g) Select the "Right Limit" input field.
 - h) Using the navigation keys, move the vertical line "S2" to the end of the burst.

The R&S FPS displays the average (mean) power during the activation phase of the burst.

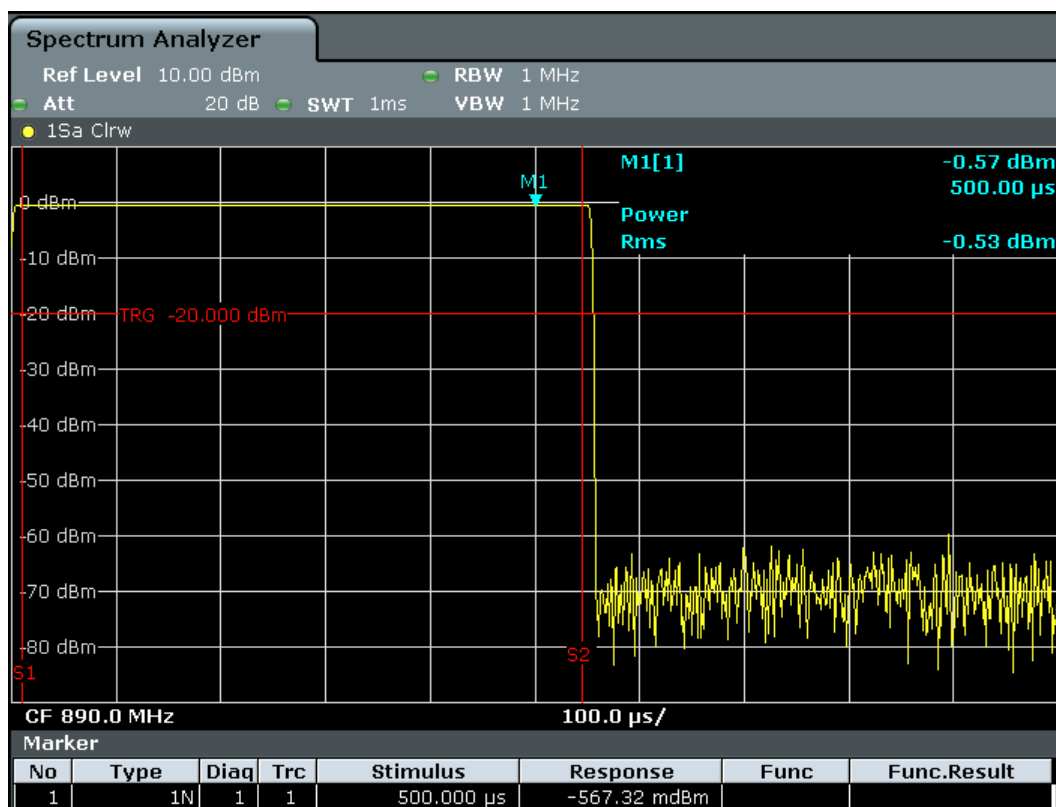


Fig. 5-14: Measurement of the average power during the burst of a GSM signal

Measuring the Edges of a GSM Burst with High Time Resolution

Due to the high time resolution of the R&S FPS at the 0 Hz display range, the edges of TDMA bursts can be measured precisely. The edges can be shifted to the display area using the trigger offset.

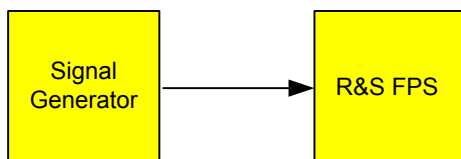


Fig. 5-15: Test setup

Table 5-7: Signal generator settings (e.g. R&S SMW)

Frequency	890 MHz
Level	0 dBm
Modulation	GSM, one timeslot activated

The measurement is based on the example ["Measuring the Power of a GSM Burst During the Activation Phase"](#) on page 131.

1. Switch off the power measurement.

- a) Press the MEAS key.
 - b) Select "All Functions Off".
2. Increase the time resolution to $100\ \mu\text{s}$ (SWEEP > "SweepTime Manual").
 3. Shift the rising edge of the GSM burst to the center of the display by defining a trigger offset.
 - a) Press the TRIG key.
 - b) Select "Trigger Offset".
 - c) Using the navigation key (Down), reduce the trigger offset until the burst edge is displayed in the center of the display, or enter $-50\ \mu\text{s}$.
The R&S FPS displays the rising edge of the GSM burst.

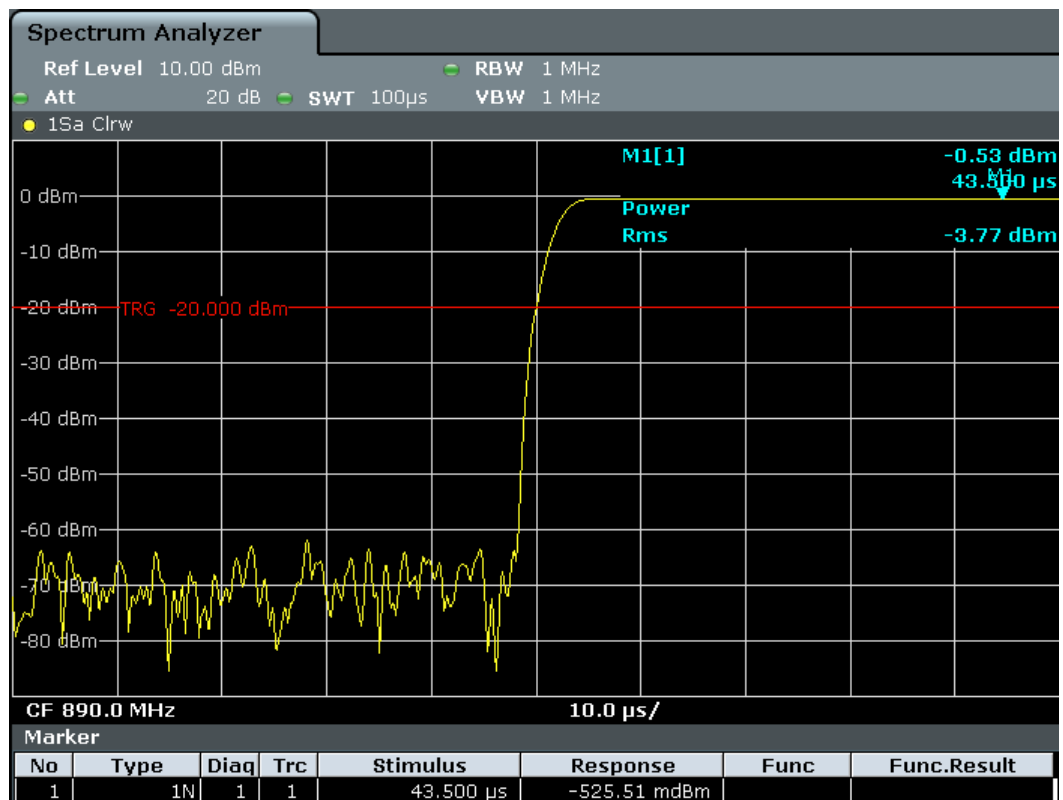


Fig. 5-16: Rising edge of the GSM burst displayed with high time resolution

4. Move the falling edge of the burst to the center of the display. To do so, switch the trigger "Slope" to "Falling" (TRIG > "Trigger/Gate Config").
The R&S FPS displays the falling edge of the GSM burst.

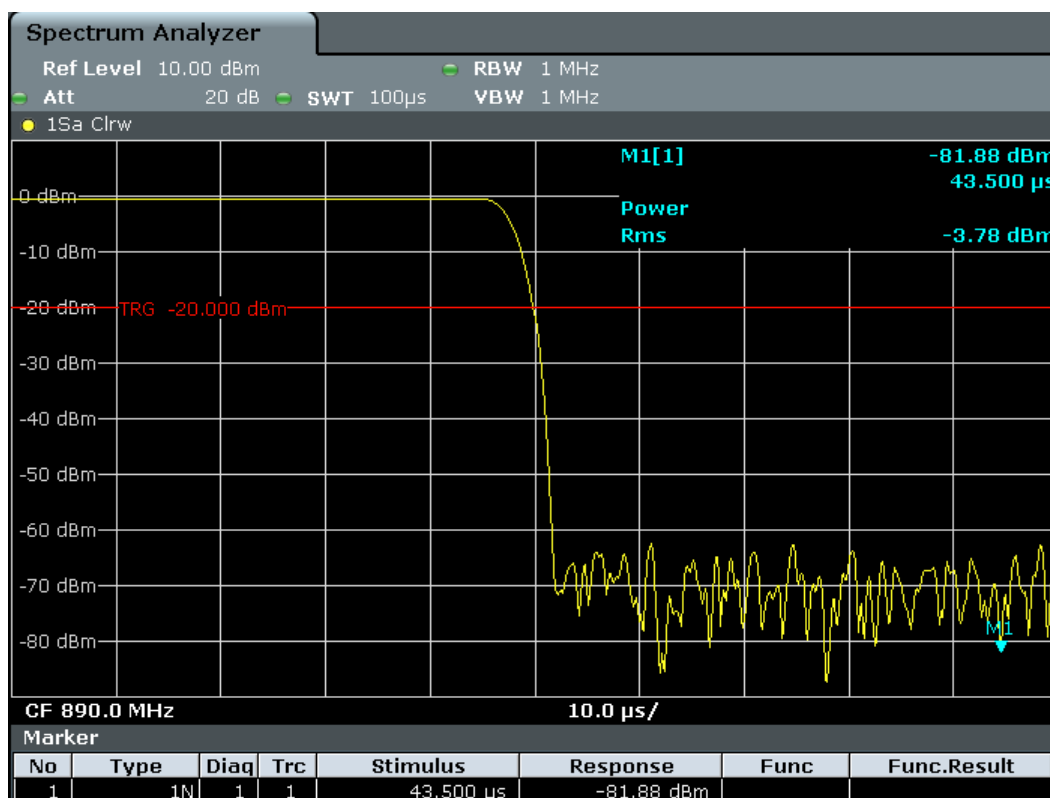


Fig. 5-17: Falling edge of the GSM burst displayed with high time resolution

5.2.5.2 Measuring the Signal-to-Noise Ratio of Burst Signals

When TDMA transmission methods are used, the signal-to-noise ratio or the dynamic range for deactivation can be measured by comparing the power values during the activation phase and the deactivation phase of the transmission burst. Therefore, the R&S FPS provides a measurement for absolute and relative power in zero span. In the following example, the measurement is performed using a GSM burst.

Signal-to-Noise Ratio of a GSM Signal

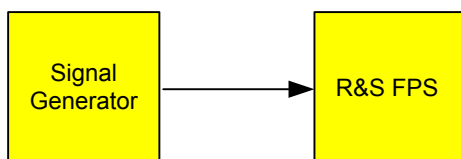


Fig. 5-18: Test setup

Table 5-8: Signal generator settings (e.g. R&S SMW)

Frequency	890 MHz
Level	0 dBm
Modulation	GSM, one time slot is switched on

1. Select PRESET to reset the instrument.
2. Set the center frequency to *890 MHz*.
3. Set the frequency span to *0 Hz*.
4. Set the resolution bandwidth to *1 MHz*.
5. Set the reference level to *0 dBm* (= level of the signal generator).
6. Set the sweep time to *2 ms* (SWEEP > "Sweeptime Manual").
The R&S FPS shows the GSM burst continuously across the display.
7. Use the trigger source "Video" and the trigger slope "Rising" to trigger on the rising edge of the burst and shift the start of the burst to the center of the display (see [step 3 in "Measuring the Edges of a GSM Burst with High Time Resolution"](#) on page 132).
8. Activate power measurement within the activation phase of the burst in zero span.
 - a) Press the MEAS key.
 - b) Select "Time Domain Power".
 - c) Select "Time Dom Power Config".
 - d) Set the "Limits" state to "On".
 - e) Select the "Left Limit" input field.
 - f) Using the navigation keys, move the vertical line "S1" to the start of the burst.
 - g) Select the "Right Limit" input field.
 - h) Using the navigation keys, move the vertical line "S2" to the end of the burst.
9. Measure the power during the deactivation phase of the burst by switching the trigger slope to "Falling" (TRIG > "Trigger/Gate Config").

The R&S FPS initiates triggering in response to the falling edge of the burst. This shifts the burst to the left-hand side of the measurement diagram. The power is measured in the deactivation phase.

Channel Power and Adjacent-Channel Power (ACLR) Measurement

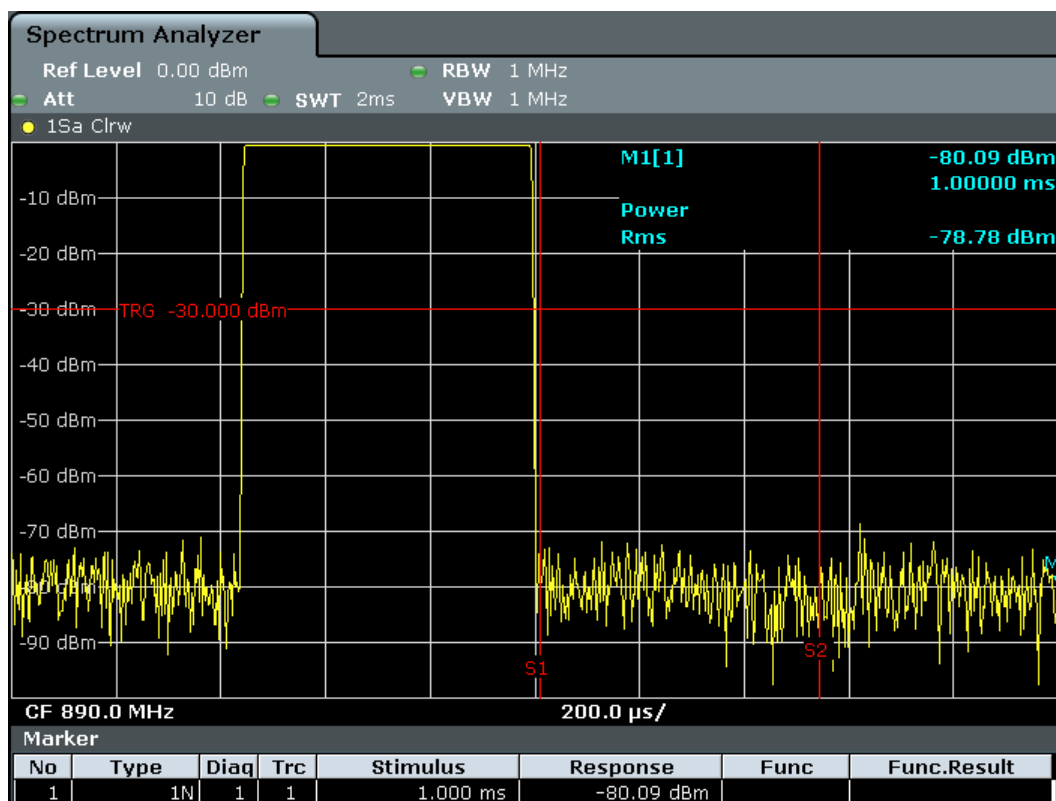


Fig. 5-19: Measurement of the signal-to-noise ratio of a GSM burst signal in zero span

5.3 Channel Power and Adjacent-Channel Power (ACLR) Measurement

Measuring the power in channels adjacent to the carrier or transmission channel is useful to detect interference. The results are displayed as a bar chart for the individual channels.

- [About Channel Power Measurements](#)..... 137
- [Channel Power Results](#)..... 137
- [Channel Power Basics](#)..... 139
- [Channel Power Configuration](#)..... 150
- [MSR ACLR Configuration](#)..... 161
- [How to Perform Channel Power Measurements](#)..... 176
- [Measurement Examples](#)..... 181
- [Optimizing and Troubleshooting the Measurement](#)..... 184
- [Reference: Predefined CP/ACLR Standards](#)..... 185
- [Reference: Predefined ACLR User Standard XML Files](#)..... 186

5.3.1 About Channel Power Measurements

Measuring channel power and adjacent channel power is one of the most important tasks for a signal analyzer with the necessary test routines in the field of digital transmission. While, theoretically, channel power could be measured at highest accuracy with a power meter, its low selectivity means that it is not suitable for measuring adjacent channel power as an absolute value or relative to the transmit channel power. The power in the adjacent channels can only be measured with a selective power meter.

A signal analyzer cannot be classified as a true power meter, because it displays the IF envelope voltage. However, it is calibrated such as to correctly display the power of a pure sine wave signal irrespective of the selected detector. This calibration cannot be applied for non-sinusoidal signals. Assuming that the digitally modulated signal has a Gaussian amplitude distribution, the signal power within the selected resolution bandwidth can be obtained using correction factors. These correction factors are normally used by the signal analyzer's internal power measurement routines in order to determine the signal power from IF envelope measurements. These factors apply if and only if the assumption of a Gaussian amplitude distribution is correct.

Apart from this common method, the R&S FPS also has a true power detector, i.e. an RMS detector. It displays the power of the test signal within the selected resolution bandwidth correctly, irrespective of the amplitude distribution, without additional correction factors being required.

The R&S FPS allows you to perform ACLR measurements on input containing multiple signals for different communication standards. A measurement standard is provided that allows you to define multiple discontinuous transmit channels at specified frequencies, independent from the selected center frequency. The ACLR measurement determines the power levels of the individual transmit, adjacent, and gap channels, as well as the total power for each sub block of transmit channels.

A detailed measurement example is provided in [chapter 5.3.7, "Measurement Examples"](#), on page 181.

5.3.2 Channel Power Results

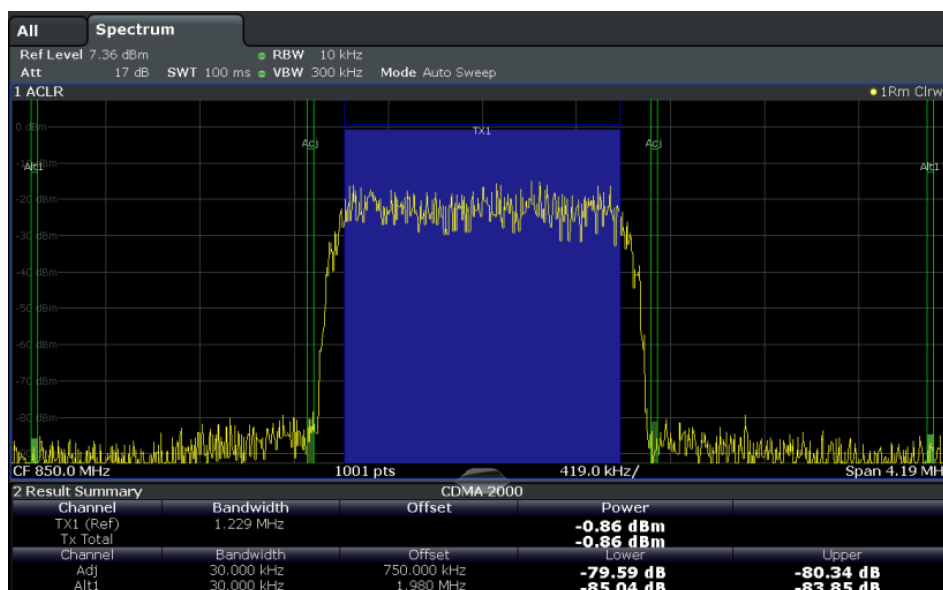
For channel or adjacent-channel power measurements, the individual channels are indicated by different colored bars in the diagram. The height of each bar corresponds to the measured power of that channel. In addition, the name of the channel ("Adj", "Alt1", "TX1", etc., or a user-defined name) is indicated above the bar (separated by a line which has no further meaning). For "Fast ACLR" measurements, which are performed in the time domain, the power versus time is shown for each channel.



Multi-standard radio (MSR) channel power results

The channel power results for MSR signals is described in [chapter 5.3.3.4, "Measurement on Multi-Standard Radio \(MSR\) Signals"](#), on page 146.

Channel Power and Adjacent-Channel Power (ACLR) Measurement



Results are provided for the TX channel and the number of defined adjacent channels *above and below* the TX channel. If more than one TX channel is defined, the carrier channel to which the relative adjacent-channel power values should be referenced must be defined. By default, this is the TX channel with the maximum power.

Table 5-9: Measurements performed depending on the number of adjacent channels

0	Only the channel powers are measured.
1	The channel powers and the power of the upper and lower adjacent channel are measured.
2	The channel powers, the power of the upper and lower adjacent channel, and of the next higher and lower channel (alternate channel 1) are measured.
3	The channel power, the power of the upper and lower adjacent channel, the power of the next higher and lower channel (alternate channel 1), and of the next but one higher and lower adjacent channel (alternate channel 2) are measured.
...	...
12	The channel power, the power of the upper and lower adjacent channel, and the power of all the higher and lower channels (alternate channels 1 to 11) are measured.



In the R&S FPS's display, only the first neighboring channel of the carrier (TX) channel is labelled "Adj" (adjacent) channel; all others are labelled "Alt" (alternate) channels. In this manual, "adjacent" refers to both adjacent and alternate channels.

The measured power values for the TX and adjacent channels are also output as a table in the Result Summary window. Which powers are measured depends on the number of configured channels.

For each channel, the following values are displayed:

Channel Power and Adjacent-Channel Power (ACLR) Measurement

Label	Description
Channel	Channel name as specified in the "Channel Settings" (see "Channel Names" on page 160).
Bandwidth	Configured channel bandwidth (see "Channel Bandwidths" on page 158)
Offset	Offset of the channel to the TX channel (configured channel spacing, see "Channel Bandwidths" on page 158)
Power (Lower/Upper)	The measured power values for the TX and lower and upper adjacent channels. The powers of the transmission channels are output in dBm or dBm/Hz, or in dBc, relative to the specified reference TX channel.

Retrieving Results via Remote Control

All or specific channel power measurement results can be retrieved using the `CALC:MARK:FUNC:POW:RES?` command from a remote computer (see `CALCulate<n>:MARKer<m>:FUNCTION:POWer<sb>:RESult?` on page 607). Alternatively, the results can be output as channel power density, i.e. in reference to the measurement bandwidth.

Furthermore, the measured power values of the displayed trace can be retrieved as usual using the `TRAC:DATA?` commands (see `TRACe<n>[:DATA]` on page 813). In this case, the measured power value for each sweep point (by default 1001) is returned.

5.3.3 Channel Power Basics

Some background knowledge on basic terms and principles used in channel power measurements is provided here for a better understanding of the required configuration settings.

- [Measurement Methods](#)..... 139
- [Measurement Repeatability](#)..... 141
- [Recommended Common Measurement Parameters](#)..... 142
- [Measurement on Multi-Standard Radio \(MSR\) Signals](#)..... 146

5.3.3.1 Measurement Methods

The channel power is defined as the integration of the power across the channel bandwidth.

The **Adjacent Channel Leakage Power Ratio (ACLR)**, also known as the **Adjacent Channel Power Ratio (ACPR)**, is defined as the ratio between the total power of the adjacent channel to the carrier channel's power. An ACLR measurement with several carrier channels (also known as transmission or TX channels) is also possible and is referred to as a "multicarrier ACLR measurement".

There are two possible methods for measuring channel and adjacent channel power with a signal analyzer:

- **IBW method** (Integration **B**and**W**idth method)

- **Fast ACLR** (Zero-span method), i.e. using a channel filter

IBW method

When measuring the channel power, the R&S FPS integrates the linear power which corresponds to the levels of the measurement points within the selected channel. The signal analyzer uses a resolution bandwidth which is far smaller than the channel bandwidth. When sweeping over the channel, the channel filter is formed by the pass-band characteristics of the resolution bandwidth.

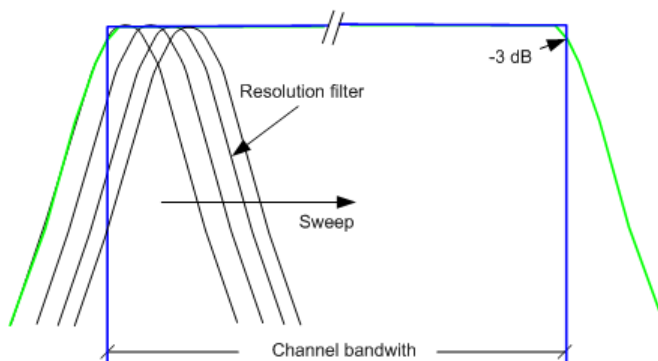


Fig. 5-20: Approximating the channel filter by sweeping with a small resolution bandwidth

The following steps are performed:

1. The linear power of all the trace points within the channel is calculated.

$$P_i = 10^{(L_i/10)}$$
 where P_i = power of the trace pixel i
 L_i = displayed level of trace point i
2. The powers of all trace points within the channel are summed up and the sum is divided by the number of trace points in the channel.
3. The result is multiplied by the quotient of the selected channel bandwidth and the noise bandwidth of the resolution filter (RBW).

Since the power calculation is performed by integrating the trace within the channel bandwidth, this method is called the IBW method (Integration **B**andwidth method).

Fast ACLR

The integrated bandwidth method (IBW) calculates channel power and ACLR from the trace data obtained during a continuous sweep over the selected span. Most parts of this sweep are neither part of the channel itself nor the defined adjacent channels. Therefore, most of the samples taken during the sweep time cannot be used for channel power or ACLR calculation.

To decrease the measurement times, the R&S FPS offers a "Fast ACLR" mode. In Fast ACLR mode, the power of the frequency range between the channels of interest is not measured, because it is not required for channel power or ACLR calculation. The

Channel Power and Adjacent-Channel Power (ACLR) Measurement

measurement time per channel is set with the sweep time. It is equal to the selected measurement time divided by the selected number of channels.

In the "Fast ACLR" mode, the R&S FPS measures the power of each channel in the time domain, with the defined channel bandwidth, at the center frequency of the channel in question. The digital implementation of the resolution bandwidths makes it possible to select filter characteristics that are precisely tailored to the signal. In case of CDMA2000, for example, the power in the useful channel is measured with a bandwidth of 1.23 MHz and that of the adjacent channels with a bandwidth of 30 kHz. Therefore the R&S FPS changes from one channel to the other and measures the power at a bandwidth of 1.23 MHz or 30 kHz using the RMS detector.

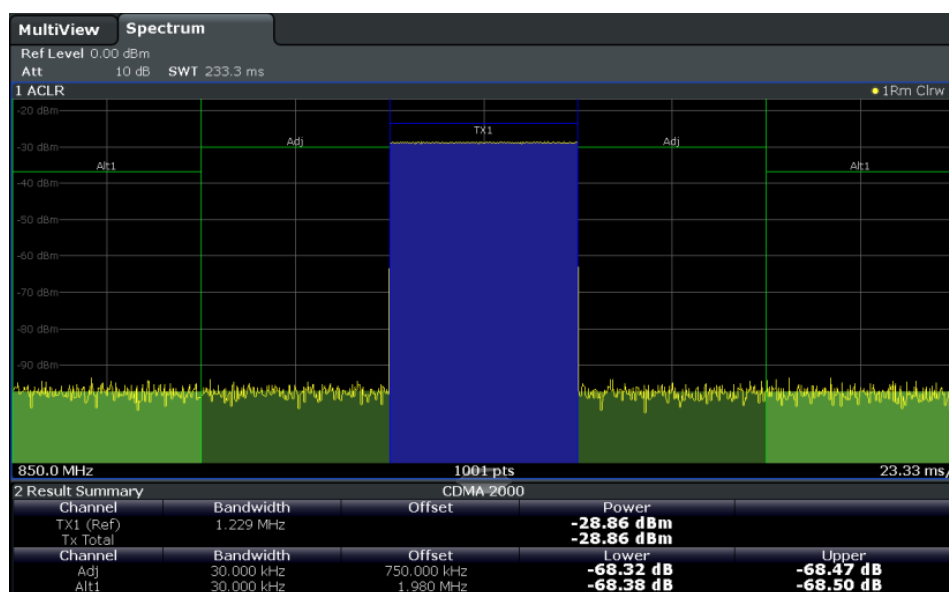


Fig. 5-21: Measuring the channel power and adjacent channel power ratio for CDMA2000 signals with zero span (Fast ACLR)

5.3.3.2 Measurement Repeatability

The repeatability of the results, especially in the narrow adjacent channels, strongly depends on the measurement time for a given resolution bandwidth. A longer sweep time may increase the probability that the measured value converges to the true value of the adjacent channel power, but obviously increases measurement time.

Assuming a measurement with five channels (1 channel plus 2 lower and 2 upper adjacent channels) and a sweep time of 100 ms, a measurement time per channel of 20 ms is required. The number of effective samples taken into account for power calculation in one channel is the product of sweep time in channel times the selected resolution bandwidth.

Assuming a sweep time of 100 ms, there are $(30 \text{ kHz} / 4.19 \text{ MHz}) * 100 \text{ ms} * 10 \text{ kHz} \approx 7$ samples. Whereas in Fast ACLR mode, there are $(100 \text{ ms} / 5) * 30 \text{ kHz} \approx 600$ samples. Comparing these numbers explains the increase of repeatability with a 95% confidence level (2σ) from $\pm 2.8 \text{ dB}$ to $\pm 0.34 \text{ dB}$ for a sweep time of 100 ms.

Channel Power and Adjacent-Channel Power (ACLR) Measurement

For the same repeatability, the sweep time would have to be set to 8.5 s with the integration method. The [figure 5-22](#) shows the standard deviation of the results as a function of the sweep time.

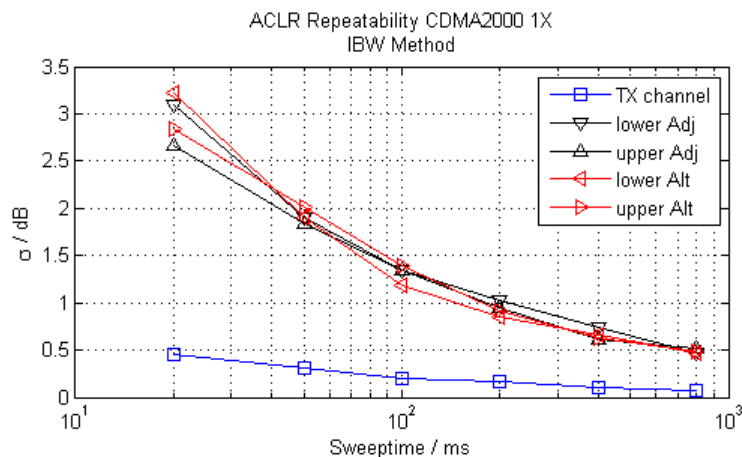


Fig. 5-22: Repeatability of adjacent channel power measurement on CDMA2000 standard signals if the integration bandwidth method is used

The [figure 5-23](#) shows the repeatability of power measurements in the transmit channel and of relative power measurements in the adjacent channels as a function of sweep time. The standard deviation of measurement results is calculated from 100 consecutive measurements. Take scaling into account if comparing power values.

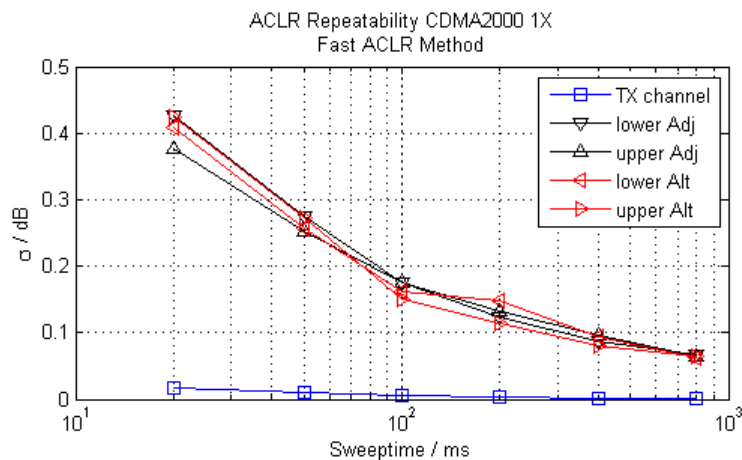


Fig. 5-23: Repeatability of adjacent channel power measurements on CDMA2000 signals in the fast ACLR mode

5.3.3.3 Recommended Common Measurement Parameters

The following sections provide recommendations on the most important measurement parameters for channel power measurements.



All instrument settings for the selected channel setup (channel bandwidth, channel spacing) can be optimized automatically using the "Adjust Settings" function (see "[Optimized Settings \(Adjust Settings\)](#)" on page 156).

The easiest way to configure a measurement is using the configuration "Overview", see [chapter 6.1, "Configuration Overview"](#), on page 291.

Sweep Time

The sweep time is selected depending on the desired reproducibility of results. Reproducibility increases with sweep time since power measurement is then performed over a longer time period. As a general approach, it can be assumed that approx. 500 non-correlated measured values are required for a reproducibility of 0.5 dB (99 % of the measurements are within 0.5 dB of the true measured value). This holds true for white noise. The measured values are considered as non-correlated if their time interval corresponds to the reciprocal of the measured bandwidth.

With IS 136 the measurement bandwidth is approx. 25 kHz, i.e. measured values at an interval of 40 µs are considered as non-correlated. A measurement time of 40 ms is thus required per channel for 1000 measured values. This is the default sweep time which the R&S FPS sets in coupled mode. Approx. 5000 measured values are required for a reproducibility of 0.1 dB (99 %), i.e. the measurement time is to be increased to 200 ms.

The number of A/D converter values, N, used to calculate the power, is defined by the sweep time. The time per trace pixel for power measurements is directly proportional to the selected sweep time.

If the sample detector is used, it is best to select the smallest sweep time possible for a given span and resolution bandwidth. The minimum time is obtained if the setting is coupled. This means that the time per measurement is minimal. Extending the measurement time does not have any advantages as the number of samples for calculating the power is defined by the number of trace points in the channel.

If the RMS detector is used, the repeatability of the measurement results can be influenced by the selection of sweep times. Repeatability is increased at longer sweep times.

If the RMS detector is used, the number of samples can be estimated as follows:

Since only uncorrelated samples contribute to the RMS value, the number of samples can be calculated from the sweep time and the resolution bandwidth.

Samples can be assumed to be uncorrelated if sampling is performed at intervals of 1/ RBW. The number of uncorrelated samples is calculated as follows:

$$N_{\text{decorr}} = \text{SWT} * \text{RBW}$$

(N_{decorr} means uncorrelated samples)

The number of uncorrelated samples per trace pixel is obtained by dividing N_{decorr} by 1001 (= pixels per trace).

The "Sweep Time" can be defined using the softkey in the "Ch Power" menu or in the "Sweep" configuration dialog box (see "[Sweep Time](#)" on page 157).

Frequency Span

The frequency span must cover at least the channels to be measured plus a measurement margin of approximately 10 %.

If the frequency span is large in comparison to the channel bandwidth (or the adjacent-channel bandwidths) being analyzed, only a few points on the trace are available per channel. This reduces the accuracy of the waveform calculation for the channel filter used, which has a negative effect on the measurement accuracy. It is therefore strongly recommended that the formulas mentioned be taken into consideration when selecting the frequency span.

The frequency span for the defined channel settings can be optimized using the "Adjust Settings" function in the "Ch Power" menu or the "General Settings" tab of the "ACLR Setup" dialog box (see ["Optimized Settings \(Adjust Settings\)"](#) on page 156). You can set the frequency span manually in the "Frequency" configuration dialog box, see [chapter 6.3.3, "How To Define the Frequency Range"](#), on page 340.

For channel power measurements the "Adjust Settings" function sets the frequency span as follows:

"(No. of transmission channels – 1) x transmission channel spacing + 2 x transmission channel bandwidth + measurement margin"

For adjacent-channel power measurements, the "Adjust Settings" function sets the frequency span as a function of the number of transmission channels, the transmission channel spacing, the adjacent-channel spacing, and the bandwidth of one of adjacent-channels ADJ, ALT1 or ALT2, whichever is furthest away from the transmission channels:

"(No. of transmission channels – 1) x transmission channel spacing + 2 x (adjacent-channel spacing + adjacent-channel bandwidth) + measurement margin"

The measurement margin is approx. 10 % of the value obtained by adding the channel spacing and the channel bandwidth.

Resolution Bandwidth (RBW)

To ensure both acceptable measurement speed and the required selection (to suppress spectral components outside the channel to be measured, especially of the adjacent channels), the resolution bandwidth must not be selected too small or too large. As a general approach, the resolution bandwidth is to be set to values between 1% and 4% of the channel bandwidth.

A larger resolution bandwidth can be selected if the spectrum within the channel to be measured and around it has a flat characteristic. In the standard setting, e.g. for standard IS95A REV at an adjacent channel bandwidth of 30 kHz, a resolution bandwidth of 30 kHz is used. This yields correct results since the spectrum in the neighborhood of the adjacent channels normally has a constant level.

The resolution bandwidth for the defined channel settings can be optimized using the "Adjust Settings" function in the "Ch Power" menu or the "General Settings" tab of the "ACLR Setup" dialog box (see ["Optimized Settings \(Adjust Settings\)"](#) on page 156). You can set the RBW manually in the "Bandwidth" configuration dialog box, see ["RBW"](#) on page 359.

Channel Power and Adjacent-Channel Power (ACLR) Measurement

With the exception of the IS95 CDMA standards, the "Adjust Settings" function sets the resolution bandwidth (RBW) as a function of the channel bandwidth:

" $RBW \leq 1/40$ of channel bandwidth"

The maximum possible resolution bandwidth (with respect to the requirement $RBW \leq 1/40$) resulting from the available RBW steps (1, 3) is selected.

Video Bandwidth (VBW)

For a correct power measurement, the video signal must not be limited in bandwidth. A restricted bandwidth of the logarithmic video signal would cause signal averaging and thus result in a too low indication of the power (-2.51 dB at very low video bandwidths). The video bandwidth should therefore be selected at least three times the resolution bandwidth:

" $VBW \geq 3 \times RBW$ "

The video bandwidth for the defined channel settings can be optimized using the "Adjust Settings" function in the "Ch Power" menu or the "General Settings" tab of the "ACLR Setup" dialog box (see ["Optimized Settings \(Adjust Settings\)"](#) on page 156). You can set the VBW manually in the "Bandwidth" configuration dialog box, see ["VBW"](#) on page 359.

The video bandwidth (VBW) is set as a function of the channel bandwidth (see formula above) and the smallest possible VBW with regard to the available step size is selected.

Detector

The RMS detector correctly indicates the power irrespective of the characteristics of the signal to be measured. The whole IF envelope is used to calculate the power for each measurement point. The IF envelope is digitized using a sampling frequency which is at least five times the resolution bandwidth which has been selected. Based on the sample values, the power is calculated for each measurement point using the following formula:

$$P_{RMS} = \sqrt{\frac{1}{N} \cdot \sum_{i=1}^N s_i^2}$$

where:

s_i = linear digitized video voltage at the output of the A/D converter

N = number of A/D converter values per measurement point

P_{RMS} = power represented by a measurement point

When the power has been calculated, the power units are converted into decibels and the value is displayed as a measurement point.

In principle, the sample detector would be possible as well. Due to the limited number of measurement points used to calculate the power in the channel, the sample detector would yield less stable results.

The RMS detector can be set for the defined channel settings automatically using the "Adjust Settings" function in the "Ch Power" menu or the "General Settings" tab of the "ACLR Setup" dialog box (see ["Optimized Settings \(Adjust Settings\)"](#) on page 156). You can set the detector manually in the "Traces" configuration dialog box, see ["Detector"](#) on page 411.

Trace Averaging

Averaging, which is often performed to stabilize the measurement results, leads to a level indication that is too low and should therefore be avoided. The reduction in the displayed power depends on the number of averages and the signal characteristics in the channel to be measured.

The "Adjust Settings" function switches off trace averaging. You can deactivate the trace averaging manually in the "Traces" configuration dialog box, see ["Average Mode"](#) on page 412.

Reference Level

To achieve an optimum dynamic range, the reference level has to be set such that the signal is as close to the reference level as possible without forcing an overload message or limiting the dynamic range by an S/N ratio that is too small. Since the measurement bandwidth for channel power measurements is significantly smaller than the signal bandwidth, the signal path may be overloaded although the trace is still significantly below the reference level.



The reference level is not influenced by the selection of a predefined standard or by the automatic setting adjustment. The reference level can be set automatically using the "Auto Level" function in the AUTO SET menu, or manually in the "Amplitude" menu.

5.3.3.4 Measurement on Multi-Standard Radio (MSR) Signals

Modern base stations may contain multiple signals for different communication standards. A new measurement standard is provided for the R&S FPS ACLR measurement that allows you to measure such MSR signals, including non-contiguous setups. Multiple (also non-)contiguous transmit channels can be specified at absolute frequencies, independent from the common center frequency selected for display.

Signal structure

Up to 18 transmit channels can be grouped in a maximum of 5 *sub blocks*. Between two sub blocks, two gaps are defined: a *lower gap* and an *upper gap*. Each gap in turn contains 2 channels (*gap channels*). The channels in the upper gap are identical to those in the lower gap, but inverted. To either side of the outermost transmit channels, lower and upper adjacent channels can be defined as in common ACLR measurement setups.

Channel Power and Adjacent-Channel Power (ACLR) Measurement

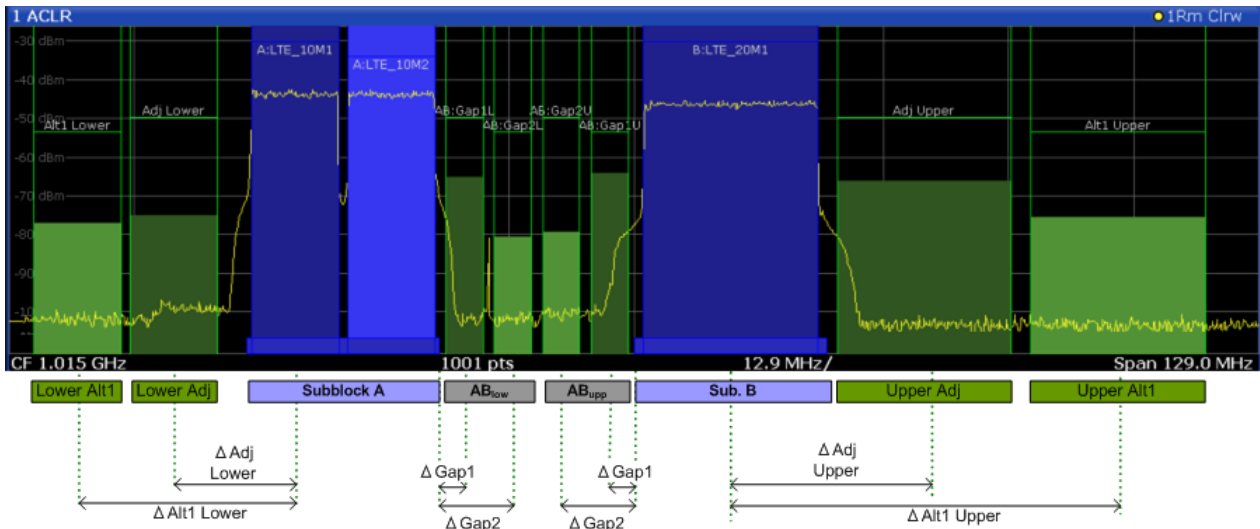


Fig. 5-24: MSR signal structure

Sub block and channel definition

The sub blocks are defined by a specified center frequency, RF bandwidth, and number of transmit channels.

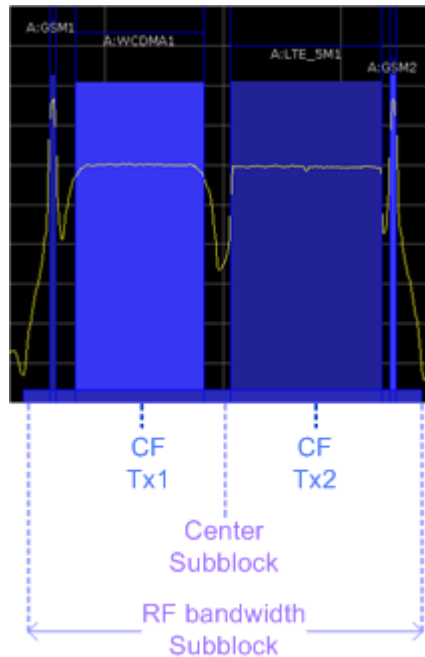


Fig. 5-25: Sub block definition

As opposed to common ACLR channel definitions, the Tx channels are defined at absolute frequencies, rather than by a spacing relative to the (common) center frequency. Each transmit channel can be assigned a different technology, used to predefine the required bandwidth.

Gap channels and CACLR

If two or more sub blocks are defined, the power in the gaps between the sub blocks must also be measured. Gap channels are defined using bandwidths and spacings, relative to the outer edges of the surrounding sub blocks. Since the upper and lower gap channels are symmetrical, only two gap channels must be configured. The required spacing can be determined according to the following formula (indicated for lower channels):

$$\text{Spacing} = [\text{CF of the gap channel}] - [\text{left sub block center}] + ([\text{RF bandwidth of left sub block}] / 2)$$

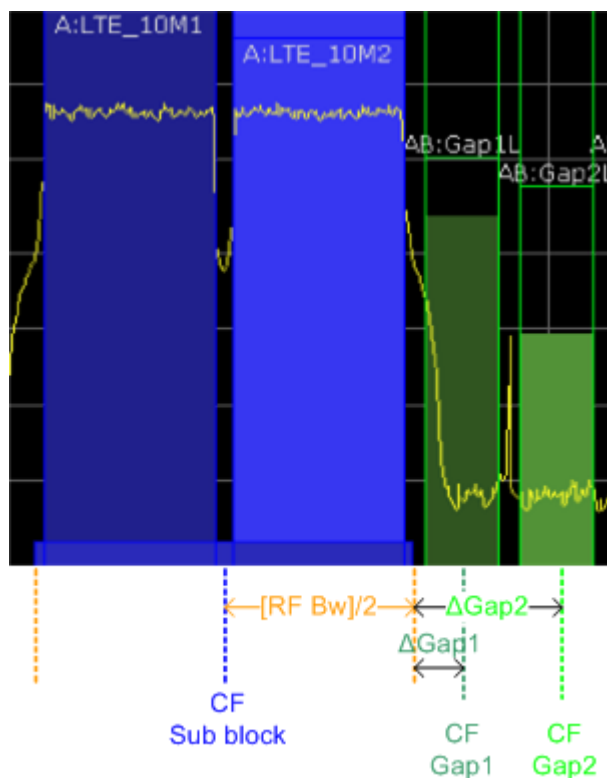


Fig. 5-26: Gap channel definition for lower gap

According to the MSR standard, the **Cumulative Adjacent Channel Leakage Ratio (CACLR)** power must be determined for the gap channels. The CACLR power is measured in the two gap channels for the upper and lower gap. The power in the gap channels is then set in relation to the power of the two closest transmission channels to either side of the gap. The CACLR power for the gap channels is indicated in the Result Summary.

In addition, the ACLR power for the individual gap channels is indicated in the Result Summary. The ACLR power of the lower gap channels refers to the TX channel to the left of the gap, while the ACLR power of the upper gap channels refers to the TX channel to the right of the gap. A separate relative limit value can be defined for the ACLR power.

Adjacent channels

Adjacent channels are defined as in common ACLR measurements using bandwidths and spacings, relative to the uppermost or lowermost transmit channels in the sub blocks (see also [figure 5-24](#)):

- The spacing of the lower adjacent channels refers to the CF of the first Tx channel in the first sub block.
- The spacing of the upper adjacent channels refers to the CF of the last Tx channel in the last sub block.



The upper and lower adjacent channels can also be defined asymmetrically (see "[Symmetrical Adjacent Setup](#)" on page 167). This is particularly useful if the lowest Tx channel and highest Tx channel use different standards and thus require different bandwidths for adjacent channel power measurement.

Channel display for MSR signals

As in common ACLR measurements, the individual channels are indicated by different colored bars in the diagram. The height of each bar corresponds to the measured power of that channel. In addition, the name of the channel is indicated above the bar. Sub blocks are named A,B,C,D,E and are also indicated by a slim blue bar along the frequency axis.

Tx channel names correspond to the specified technology (for LTE including the bandwidth), followed by a consecutive number. (If the channel is too narrow to display the channel name, it is replaced by "..." on the screen.) The assigned sub block is indicated with the channel name, e.g. "B:LTE_5M1" for the first Tx channel in sub block B that uses the LTE 5 MHz bandwidth technology.

Adjacent and alternate channels are displayed as in common ACLR measurements.

Gap channels are indicated by the names of the surrounding sub blocks (e.g. "AB" for the gap between sub blocks A and B), followed by the channel name ("Gap1" or "Gap2") and an "L" (for lower) or a "U" (for upper). Both the lower and upper gap channels are displayed.



The gap channels can be hidden if they do not reach a minimum size, or deactivated entirely. This enhances the result display, as fewer lines and bars are displayed. If gap channels are deactivated, the power results are not calculated and thus are not shown in the Result Summary table.

Furthermore, channel names for all TX, adjacent, and alternate channels are now user-definable.

Channel power results

The Result Summary for MSR signal measurements is similar to the table for common signals (see [chapter 5.3.2, "Channel Power Results"](#), on page 137). However, the Tx channel results are grouped by sub blocks, and sub block totals are provided instead of a total Tx channel power. Instead of the individual channel frequency offsets, the absolute center frequencies are indicated for the transmit channels.

Channel Power and Adjacent-Channel Power (ACLR) Measurement

The CACLR and ACLR power results for each gap channel are appended at the end of the table. The CACLR results are calculated as the power in the gap channel divided by the power sum of the two closest transmission channels to either side of it.

2 Result Summary		Multi-Standard Radio		
Channel	Bandwidth	Frequency	Power	
A-LTE_10M1	9.015 MHz	980.000 MHz	-19.11 dBm	
A-LTE_10M2	9.015 MHz	990.000 MHz	-19.21 dBm	
Sub Block A Total			-16.15 dBm	
Channel	Bandwidth	Frequency	Power	
B-LTE_20M1 (Ref)	18.015 MHz	1.025 GHz	-18.72 dBm	
Sub Block B Total			-18.72 dBm	
Adj Channels	Bandwidth	Offset	ACLR Power	
Adj Lower	9.015 MHz	12.500 MHz	-56.31 dB	
Adj Upper	18.015 MHz	20.000 MHz	-47.50 dB	
Alt1 Lower	9.015 MHz	22.500 MHz	-58.46 dB	
Alt1 Upper	18.015 MHz	40.000 MHz	-56.97 dB	
Gap Channels	Bandwidth	Offset	ACLR Power	CACLR Power
AB_Gap1L	3.840 MHz	2.500 MHz	-45.85 dB	-49.11 dB
AB_Gap1U	3.840 MHz	2.500 MHz	-45.50 dB	-48.07 dB
AB_Gap2L	3.840 MHz	7.500 MHz	-61.51 dB	-64.78 dB
AB_Gap2U	3.840 MHz	7.500 MHz	-60.62 dB	-63.39 dB

Fig. 5-27: Result summary for asymmetrical channel definition

Remote command:

CALCulate:MARKer:FUNCTION:POWER<sb>:RESult? GACLR OR
 CALCulate:MARKer:FUNCTION:POWER<sb>:RESult? MACM , see
[CALCulate<n>:MARKer<m>:FUNCTION:POWER<sb>:RESult?](#) on page 607

Restrictions and dependencies

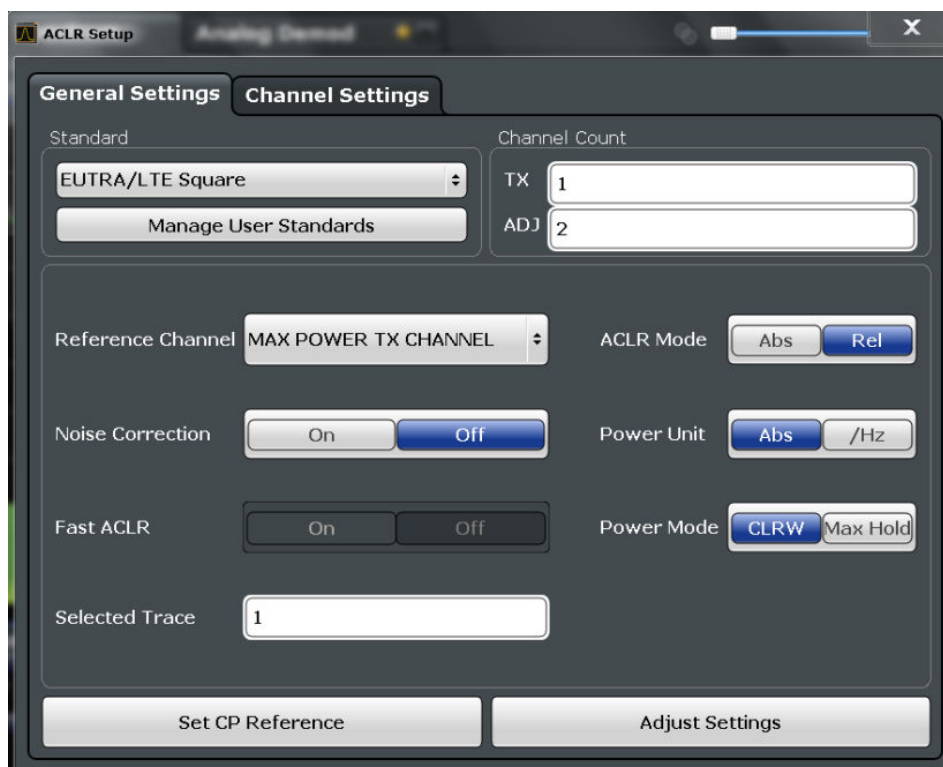
As the signal structure in multi-standard radio signals may vary considerably, the channels can be defined very flexibly for the ACLR measurement with the R&S FPS. No checks or limitations are implemented concerning the channel definitions, apart from the maximum number of channels to be defined. Thus, you will not be notified if transmit channels for a specific sub block lie outside the sub block's defined frequency range, or if transmit and gap channels overlap.

5.3.4 Channel Power Configuration

Channel Power (CP) and Adjacent-Channel Power (ACLR) measurements are selected via the "Channel Power ACLR" button in the "Select Measurement" dialog box. The measurement is started immediately with the default settings. It can be configured via the MEAS CONFIG key or in the "ACLR Setup" dialog box, which is displayed when you select the "CP/ACLR Config" softkey from the "CH Power" menu.



If the "Multi-Standard Radio" standard is selected (see ["Standard"](#) on page 152), the "ACLR Setup" dialog box is replaced by the "MSR ACLR Setup" dialog box. See [chapter 5.3.5, "MSR ACLR Configuration"](#), on page 161 for a description of these settings.



The easiest way to configure a measurement is using the configuration "Overview", see [chapter 6.1, "Configuration Overview"](#), on page 291.

The remote commands required to perform these tasks are described in [chapter 11.5.3, "Measuring the Channel Power and ACLR"](#), on page 611.

- [General CP/ACLR Measurement Settings](#)..... 151
- [Channel Setup](#)..... 157

5.3.4.1 General CP/ACLR Measurement Settings

General measurement settings are defined in the "ACLR Setup" dialog, in the "General Settings" tab.

Standard	152
L Predefined Standards	152
L User-Defined Standards	152
Number of Channels (Tx, ADJ)	154
Reference Channel	154
Noise cancellation	155
Fast ACLR	155
Selected Trace	155
Absolute and Relative Values (ACLR Mode)	155
Channel Power Levels and Density (Power Unit)	156
Power Mode	156

Setting a Fixed Reference for Channel Power Measurements (Set CP Reference)...	156
Optimized Settings (Adjust Settings).....	156
Sweep Time.....	157

Standard

The main measurement settings can be stored as a standard file. When such a standard is loaded, the required channel and general measurement settings are automatically set on the R&S FPS. However, the settings can be changed. Predefined standards are available for standard measurements, but standard files with user-defined configurations can also be created.

Note: If the "Multi-Standard Radio" standard is selected, the "ACLR Setup" dialog box is replaced by the "MSR ACLR Setup" dialog box (see [chapter 5.3.5, "MSR ACLR Configuration"](#), on page 161).

If any other predefined standard (or "NONE") is selected, the "ACLR Setup" dialog box is restored (see [chapter 5.3.4, "Channel Power Configuration"](#), on page 150).

Note that changes in the configuration are not stored when the dialog boxes are exchanged.

Predefined Standards ← Standard

Predefined standards contain the main measurement settings for standard measurements. When such a standard is loaded, the required channel settings are automatically set on the R&S FPS. However, the settings can be changed.

The predefined standards contain the following settings:

- Channel bandwidths
- Channel spacings
- Detector
- Trace Average setting
- Resolution Bandwidth (RBW)
- Weighting Filter

Predefined standards can be selected via the "CP/ACLR Standard" softkey in the "CH Power" menu or in the "General Settings" tab of the "CP/ACLR Setup" dialog box.

For details on the available standards see [chapter 5.3.9, "Reference: Predefined CP/ACLR Standards"](#), on page 185.

Remote command:

`CALCulate<n>:MARKer<m>:FUNCTION:POWER:PRESet` on page 612

User-Defined Standards ← Standard

In addition to the predefined standards you can save your own standards with your specific measurement settings in an xml file so you can use them again at a later time. User-defined standards are stored on the instrument in the `C:\R_S\instr\acp_std` directory.

A set of predefined xml files for common ACLR measurements are provided in this directory (see [chapter 5.3.10, "Reference: Predefined ACLR User Standard XML Files"](#), on page 186).

A sample file is provided for an MSR ACLR measurement (`MSR_ACLRExample.xml`). It sets up the measurement for the MSR signal generator waveform described in the file `C:\R_S\instr\user\waveform\MSRA_GSM_WCDMA_LET_GSM.wv`.

Channel Power and Adjacent-Channel Power (ACLR) Measurement

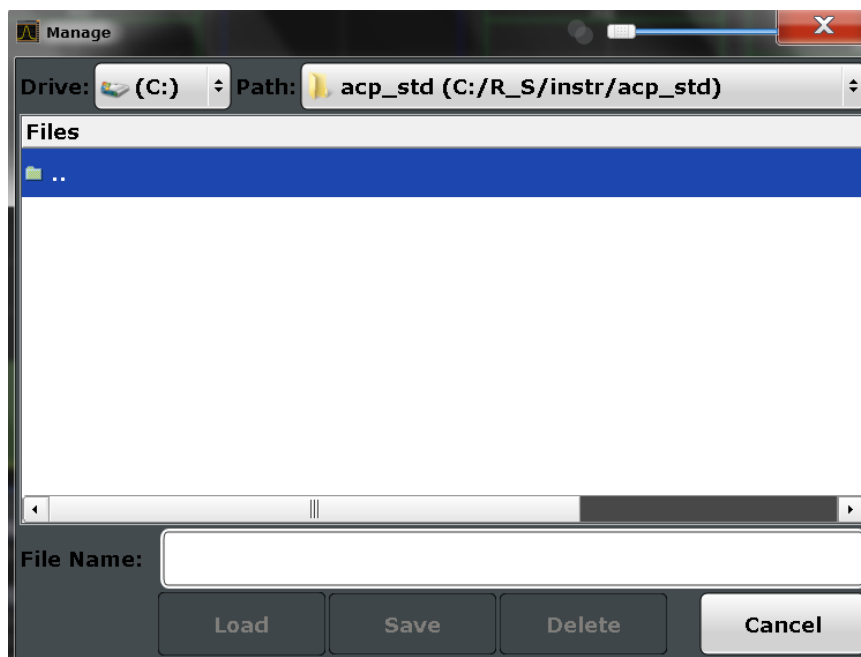
Note that ACLR user standards are not supported for Fast ACLR and multicarrier ACLR measurements.

Note: User standards created on an analyzer of the R&S FSP family are compatible to the R&S FPS. User standards created on an R&S FPS, however, are not necessarily compatible to the analyzers of the R&S FSP family and may not work there.

The following parameter definitions are saved in a user-defined standard:

- Number of adjacent channels
- Channel bandwidth of transmission (Tx), adjacent (Adj) and alternate (Alt) channels
- Channel spacings
- Weighting filters
- Resolution bandwidth
- Video bandwidth
- Detector
- ACLR limits and their state
- Sweep time and sweep time coupling
- Trace and power mode
- (MSR only: sub block and gap channel definition)

User-defined standards are managed in the "Manage" dialog box which is displayed when you select the "Manage User Standards" button in the "General Settings" tab of the "CP/ACLR Setup" dialog box.



In the "Manage" dialog box you can save the current measurement settings as a user-defined standard, or load a stored measurement configuration. Furthermore, you can delete an existing configuration file.

For details see [chapter 5.3.6.4, "How to Manage User-Defined Configurations"](#), on page 179.

Remote command:

To query all available standards:

`CALCulate<n>:MARKer<m>:FUNCTION:POWER:STANDARD:CATALOG?`

on page 612

To load a standard:

`CALCulate<n>:MARKer<m>:FUNCTION:POWER:PRESet` on page 612

To save a standard:

`CALCulate<n>:MARKer<m>:FUNCTION:POWER:STANDARD:SAVE` on page 612

To delete a standard:

`CALCulate<n>:MARKer<m>:FUNCTION:POWER:STANDARD:DELETE` on page 612

Number of Channels (Tx, ADJ)

Up to 18 carrier channels and up to 12 adjacent channels can be defined.

Results are provided for the Tx channel and the number of defined adjacent channels *above and below* the Tx channel. If more than one Tx channel is defined, the carrier channel to which the relative adjacent-channel power values should be referenced must be defined (see ["Reference Channel"](#) on page 154).

Note: If several carriers (Tx channels) are activated for the measurement, the number of sweep points is increased to ensure that adjacent-channel powers are measured with adequate accuracy.

For more information on how the number of channels affects the measured powers, see [chapter 5.3.2, "Channel Power Results"](#), on page 137.

Remote command:

Number of Tx channels:

`[SENSe:]POWER:ACHannel:TXChannel:COUNT` on page 616

Number of Adjacent channels:

`[SENSe:]POWER:ACHannel:ACPairs` on page 613

Reference Channel

The measured power values in the adjacent channels can be displayed relative to the transmission channel. If more than one Tx channel is defined, you must select which one is to be used as a reference channel.

Tx Channel 1	Transmission channel 1 is used. (Not available for MSR ACLR)
Min Power Tx Channel	The transmission channel with the lowest power is used as a reference channel.
Max Power Tx Channel	The transmission channel with the highest power is used as a reference channel (Default).
Lowest & Highest Channel	The outer left-hand transmission channel is the reference channel for the lower adjacent channels, the outer right-hand transmission channel that for the upper adjacent channels.

Remote command:

`[SENSe:]POWER:ACHannel:REFERENCE:TXChannel:MANual` on page 620

`[SENSe:]POWER:ACHannel:REFERENCE:TXChannel:AUTO` on page 619

Noise cancellation

The results can be corrected by the instrument's inherent noise, which increases the dynamic range.

In this case, a reference measurement of the instrument's inherent noise is carried out. The measured noise power is then subtracted from the power in the channel that is being analyzed (first active trace only).

The inherent noise of the instrument depends on the selected center frequency, resolution bandwidth and level setting. Therefore, the correction function is disabled whenever one of these parameters is changed. A disable message is displayed on the screen. To enable the correction function after changing one of these settings, activate it again. A new reference measurement is carried out.

Noise cancellation is also available in zero span.

Currently, noise cancellation is only available for the following trace detectors (see "Detector" on page 411):

- RMS
- Average
- Sample
- Positive Peak

Remote command:

[\[SENSe:\]POWer:NCORrection](#) on page 756

Fast ACLR

If activated, instead of using the IBW method, the R&S FPS sets the center frequency to the different channel center frequencies consecutively and measures the power with the selected measurement time (= sweep time/number of channels).

Remote command:

[\[SENSe:\]POWer:HSPEED](#) on page 626

Selected Trace

The CP/ACLR measurement can be performed on any active trace.

Remote command:

[\[SENSe:\]POWer:TRACe](#) on page 611

Absolute and Relative Values (ACLR Mode)

The powers of the adjacent channels are output in dBm or dBm/Hz (absolute values), or in dBc, relative to the specified reference Tx channel.

"Abs" The absolute power in the adjacent channels is displayed in the unit of the y-axis, e.g. in dBm, dB μ V.

"Rel" The level of the adjacent channels is displayed relative to the level of the transmission channel in dBc.

Remote command:

[\[SENSe:\]POWer:ACHannel:MODE](#) on page 642

Channel Power Levels and Density (Power Unit)

By default, the channel power is displayed in absolute values. If "/Hz" is activated, the channel power density is displayed instead. Thus, the absolute unit of the channel power is switched from dBm to dBm/Hz.

Note: The channel power density in dBm/Hz corresponds to the power inside a bandwidth of 1 Hz and is calculated as follows:

"channel power density = channel power – $\log_{10}(\text{channel bandwidth})$ "

Thus you can measure the signal/noise power density, for example, or use the additional functions [Absolute and Relative Values \(ACLR Mode\)](#) and [Reference Channel](#) to obtain the signal to noise ratio.

Remote command:

`CALCulate<n>:MARKer<m>:FUNCTION:POWER:RESult:PHZ` on page 641

Power Mode

The measured power values can be displayed directly for each trace ("Clear/Write"), or only the maximum values over a series of measurements can be displayed ("Max Hold"). In the latter case, the power values are calculated from the current trace and compared with the previous power value using a maximum algorithm. The higher value is retained. If "Max Hold" mode is activated, "Pwr Max" is indicated in the table header. Note that the *trace* mode remains unaffected by this setting.

Remote command:

`CALCulate<n>:MARKer<m>:FUNCTION:POWER:MODE` on page 607

Setting a Fixed Reference for Channel Power Measurements (Set CP Reference)

For pure channel power measurements (no adjacent channels defined) with only one Tx channel, the currently measured channel power can be used as a fixed reference value for subsequent channel power measurements.

When you select this button, the channel power currently measured on the Tx channel is stored as a fixed reference power. In the following channel power measurements, the power is indicated relative to the fixed reference power. The reference value is displayed in the "Reference" field (in relative ACLR mode); the default value is 0 dBm.

Note: In adjacent-channel power measurement, the power is always referenced to a transmission channel (see ["Reference Channel"](#) on page 154), thus, this function is not available.

Remote command:

`[SENSe:]POWER:ACHannel:REference:AUTO ONCE` on page 619

Optimized Settings (Adjust Settings)

All instrument settings for the selected channel setup (channel bandwidth, channel spacing) can be optimized automatically.

The adjustment is carried out only once. If necessary, the instrument settings can be changed later.

The following settings are optimized by "Adjust Settings":

- ["Frequency Span"](#) on page 144
- ["Resolution Bandwidth \(RBW\)"](#) on page 144
- ["Video Bandwidth \(VBW\)"](#) on page 145
- ["Detector"](#) on page 145

- ["Trace Averaging"](#) on page 146

Note: The reference level is not affected by this function. To adjust the reference level automatically, use the [Setting the Reference Level Automatically \(Auto Level\)](#) function in the AUTO SET menu.

Remote command:

`[SENSe:] POWER:ACHannel:PRESet` on page 610

Sweep Time

With the RMS detector, a longer sweep time increases the stability of the measurement results. For recommendations on setting this parameter, see ["Sweep Time"](#) on page 143.

The sweep time can be set via the softkey in the "Ch Power" menu and is identical to the general setting in the "Sweep" configuration dialog box.

Remote command:

`[SENSe:] SWEEp:TIME` on page 753

5.3.4.2 Channel Setup

The "Channel Settings" tab in the "ACLR Setup" dialog box provides all the channel settings to configure the channel power or ACLR measurement. You can define the channel settings for all channels, independent of the defined number of *used* Tx or adjacent channels (see ["Number of Channels \(Tx, ADJ\)"](#) on page 154).

For details on setting up channels, see [chapter 5.3.6.2, "How to Set up the Channels"](#), on page 177.

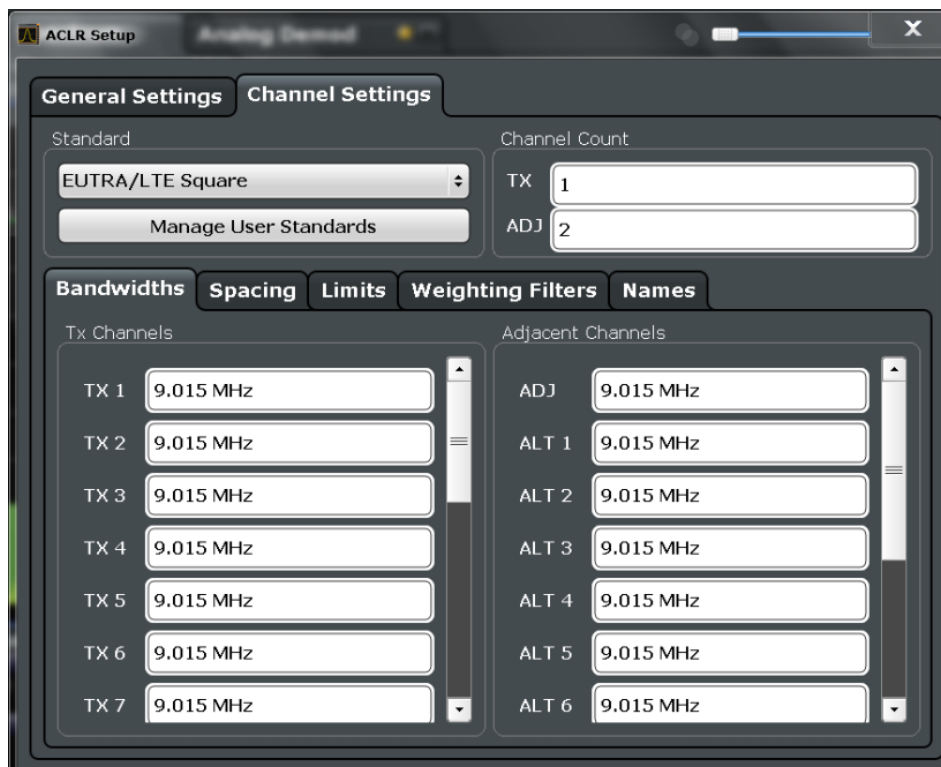


In addition to the specific channel settings, the general settings ["Standard"](#) on page 152 and ["Number of Channels \(Tx, ADJ\)"](#) on page 154 are also available in this tab.

The following settings are available in individual subtabs of the "Channel Settings" tab.

Channel Bandwidths	158
Channel Spacings	158
Limit Checking	159
Weighting Filters	160
Channel Names	160

Channel Bandwidths



The Tx channel bandwidth is normally defined by the transmission standard. The correct bandwidth is set automatically for the selected standard. The bandwidth for each channel is indicated by a colored bar in the display.

For measurements that require channel bandwidths which deviate from those defined in the selected standard, use the IBW method ("Fast ACLR Off"). With the IBW method, the channel bandwidth borders are right and left of the channel center frequency. Thus, you can visually check whether the entire power of the signal under test is within the selected channel bandwidth.

The value entered for any Tx channel is automatically also defined for all subsequent Tx channels. Thus, only one value needs to be entered if all Tx channels have the same bandwidth.

The value entered for any ADJ or ALT channel is automatically also defined for all alternate (ALT) channels. Thus, only one value needs to be entered if all adjacent channels have the same bandwidth.

Remote command:

[\[SENSe:\] POWER:ACHannel:BANDwidth|BWIDth\[:CHANnel<ch>\]](#) on page 614

[\[SENSe:\] POWER:ACHannel:BANDwidth|BWIDth:ACHannel](#) on page 613

[\[SENSe:\] POWER:ACHannel:BANDwidth|BWIDth:ALTErnate<ch>](#) on page 613

Channel Spacings

Channel spacings are normally defined by the selected standard but can be changed.

If the spacings are not equal, the channel distribution in relation to the center frequency is as follows:

Channel Power and Adjacent-Channel Power (ACLR) Measurement

Odd number of Tx channels	The middle Tx channel is centered to center frequency.
Even number of Tx channels	The two Tx channels in the middle are used to calculate the frequency between those two channels. This frequency is aligned to the center frequency.

The spacings between all Tx channels can be defined individually. When you change the spacing for one channel, the value is automatically also defined for all subsequent Tx channels in order to set up a system with equal Tx channel spacing quickly. For different spacings, a setup from top to bottom is necessary.

Tx1-2	spacing between the first and the second carrier
Tx2-3	spacing between the second and the third carrier
...	...

If you change the adjacent-channel spacing (ADJ), all higher adjacent channel spacings (ALT1, ALT2, ...) are multiplied by the same factor (new spacing value/old spacing value). Again, only one value needs to be entered for equal channel spacing. For different spacing, configure the spacings from top to bottom.

For details see [chapter 5.3.6.2, "How to Set up the Channels"](#), on page 177

Remote command:

[SENSe:] POWER:ACHannel:SPACing:CHANnel<ch> on page 616

[SENSe:] POWER:ACHannel:SPACing[:ACHannel] on page 615

[SENSe:] POWER:ACHannel:SPACing:ALternate<ch> on page 615

Limit Checking

During an ACLR measurement, the power values can be checked whether they exceed user-defined or standard-defined limits. A relative or absolute limit can be defined, or both. Both limit types are considered, regardless whether the measured levels are absolute or relative values. The check of both limit values can be activated independently. If any active limit value is exceeded, the measured value is displayed in red and marked by a preceding asterisk in the result table.

2 Result Summary		Tx Power 30.54 dBm		Tx Bandwidth 3.840 MHz		W-CDMA 3GPP DL	
Range Low	Range Up	RBW	Frequency	Power Abs	Power Rel	ΔLimit	
-12.750 MHz	-8.000 MHz	1.000 MHz	2.09053 GHz	-40.68 dBm	-71.22 dB	-17.18 dB	
-8.000 MHz	-4.000 MHz	1.000 MHz	2.09268 GHz	-40.13 dBm	-70.67 dB	-20.63 dB	
-4.000 MHz	-3.515 MHz	30.000 kHz	2.09647 GHz	-52.60 dBm	-83.14 dB	-20.10 dB	
-3.515 MHz	-2.715 MHz	30.000 kHz	2.09652 GHz	-54.30 dBm	-84.84 dB	-22.38 dB	
-2.715 MHz	-2.515 MHz	30.000 kHz	2.09728 GHz	-51.51 dBm	-82.05 dB	-31.01 dB	
-2.515 MHz	2.715 MHz	30.000 kHz	2.10270 GHz	-54.13 dBm	-84.67 dB	-33.63 dB	
2.715 MHz	3.515 MHz	30.000 kHz	2.10299 GHz*	-17.29 dBm*	-47.83 dB*	7.27 dB*	
3.515 MHz	4.000 MHz	30.000 kHz	2.10355 GHz	-51.94 dBm	-82.46 dB	-19.44 dB	
4.000 MHz	8.000 MHz	1.000 MHz	2.10725 GHz	-40.01 dBm	-70.55 dB	-20.51 dB	
8.000 MHz	12.750 MHz	1.000 MHz	2.10911 GHz	-40.28 dBm	-70.82 dB	-16.78 dB	

The results of the power limit checks are also indicated in the `STAT:QUES:ACPL` status registry (see "[STATus:QUESTionable:ACPLimit Register](#)" on page 564).

Remote command:

`CALCulate<n>:LIMit<k>:ACPower[:STATe]` on page 625

`CALCulate<n>:LIMit<k>:ACPower:ACHannel:ABSolute:STATe` on page 621

`CALCulate<n>:LIMit<k>:ACPower:ACHannel:ABSolute` on page 620

`CALCulate<n>:LIMit<k>:ACPower:ACHannel[:RELative]:STATe`
on page 622

`CALCulate<n>:LIMit<k>:ACPower:ACHannel[:RELative]` on page 621

`CALCulate<n>:LIMit<k>:ACPower:ALternate<ch>:ABSolute:STATe`
on page 623

`CALCulate<n>:LIMit<k>:ACPower:ALternate<ch>:ABSolute` on page 623

`CALCulate<n>:LIMit<k>:ACPower:ALternate<ch>[:RELative]:STATe`
on page 625

`CALCulate<n>:LIMit<k>:ACPower:ALternate<ch>[:RELative]` on page 624

`CALCulate<n>:LIMit<k>:ACPower:ACHannel:RESult?` on page 622

Weighting Filters

Weighting filters allow you to determine the influence of individual channels on the total measurement result. For each channel you can activate or deactivate the use of the weighting filter and define an individual weighting factor ("Alpha" value).

Weighting filters are not available for all supported standards and cannot always be defined manually where they are available.

Remote command:

Activating/Deactivating:

`[SENSe:]POWer:ACHannel:FILTer[:STATe]:CHANnel<ch>` on page 618

`[SENSe:]POWer:ACHannel:FILTer[:STATe]:ACHannel` on page 618

`[SENSe:]POWer:ACHannel:FILTer[:STATe]:ALternate<ch>` on page 618

Alpha value:

`[SENSe:]POWer:ACHannel:FILTer:ALPHa:CHANnel<ch>` on page 618

`[SENSe:]POWer:ACHannel:FILTer:ALPHa:ACHannel` on page 617

`[SENSe:]POWer:ACHannel:FILTer:ALPHa:ALternate<ch>` on page 617

Channel Names

In the R&S FPS's display, carrier channels are labelled "Tx" by default; the first neighboring channel is labelled "Adj" (adjacent) channel; all others are labelled "Alt" (alternate) channels. You can define user-specific channel names for each channel which are displayed in the result diagram and result table.

Remote command:

`[SENSe:]POWer:ACHannel:NAME:ACHannel` on page 614

`[SENSe:]POWer:ACHannel:NAME:ALternate<ch>` on page 614

`[SENSe:]POWer:ACHannel:NAME:CHANnel<ch>` on page 615

5.3.5 MSR ACLR Configuration

ACLR measurements can also be performed on input containing multiple signals for different communication standards. A new measurement standard is provided that allows you to define multiple discontinuous transmit channels at specified frequencies, independent from the selected center frequency. If the "Multi-Standard Radio" standard is selected (see "Standard" on page 152), the "ACLR Setup" dialog box is replaced by the "MSR ACLR Setup" dialog box.

For more information see [chapter 5.3.3.4, "Measurement on Multi-Standard Radio \(MSR\) Signals"](#), on page 146.

The remote commands required to perform these tasks are described in [chapter 11.5.3, "Measuring the Channel Power and ACLR"](#), on page 611.

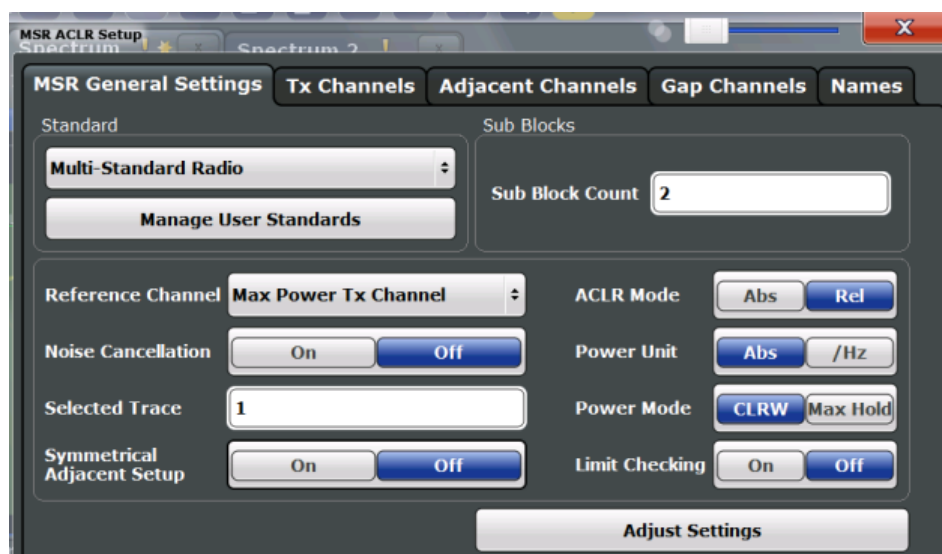
- [General MSR ACLR Measurement Settings](#)..... 161
- [MSR Sub Block and Tx Channel Definition](#)..... 167
- [MSR Adjacent Channel Setup](#)..... 170
- [MSR Gap Channel Setup](#)..... 173
- [MSR Channel Names](#)..... 175

5.3.5.1 General MSR ACLR Measurement Settings

General MSR ACLR measurement settings are defined in the "MSR ACLR Setup" dialog, in the "MSR General Settings" tab.

To display the "MSR ACLR Setup" dialog box, do one of the following:

- From the "CH Power" menu, select the "CP/ACLR Standard" softkey and then select the "Multi-Standard Radio" standard. Then select the "CP/ACLR Config" softkey.
- Select the "CP/ACLR Config" softkey from the "CH Power" menu. Then select the "Multi-Standard Radio" standard from the "Standard" selection list.



Channel Power and Adjacent-Channel Power (ACLR) Measurement

Standard.....	162
L Predefined Standards.....	162
L User-Defined Standards.....	163
Number of Sub Blocks.....	164
Reference Channel.....	164
Noise cancellation.....	165
Selected Trace.....	165
Absolute and Relative Values (ACLR Mode).....	165
Channel Power Levels and Density (Power Unit).....	166
Power Mode.....	166
Optimized Settings (Adjust Settings).....	166
Symmetrical Adjacent Setup.....	167
Limit Checking.....	167

Standard

The main measurement settings can be stored as a standard file. When such a standard is loaded, the required channel and general measurement settings are automatically set on the R&S FPS. However, the settings can be changed. Predefined standards are available for standard measurements, but standard files with user-defined configurations can also be created.

Note: If the "Multi-Standard Radio" standard is selected, the "ACLR Setup" dialog box is replaced by the "MSR ACLR Setup" dialog box (see [chapter 5.3.5, "MSR ACLR Configuration"](#), on page 161).

If any other predefined standard (or "NONE") is selected, the "ACLR Setup" dialog box is restored (see [chapter 5.3.4, "Channel Power Configuration"](#), on page 150).

Note that changes in the configuration are not stored when the dialog boxes are exchanged.

Predefined Standards ← Standard

Predefined standards contain the main measurement settings for standard measurements. When such a standard is loaded, the required channel settings are automatically set on the R&S FPS. However, the settings can be changed.

The predefined standards contain the following settings:

- Channel bandwidths
- Channel spacings
- Detector
- Trace Average setting
- Resolution Bandwidth (RBW)
- Weighting Filter

Predefined standards can be selected via the "CP/ACLR Standard" softkey in the "CH Power" menu or in the "General Settings" tab of the "CP/ACLR Setup" dialog box.

For details on the available standards see [chapter 5.3.9, "Reference: Predefined CP/ACLR Standards"](#), on page 185.

Remote command:

CALCulate<n>:MARKer<m>:FUNction:POWer:PRESet on page 612

User-Defined Standards ← Standard

In addition to the predefined standards you can save your own standards with your specific measurement settings in an xml file so you can use them again at a later time. User-defined standards are stored on the instrument in the `C:\R_S\instr\acp_std` directory.

A set of predefined xml files for common ACLR measurements are provided in this directory (see [chapter 5.3.10, "Reference: Predefined ACLR User Standard XML Files"](#), on page 186).

A sample file is provided for an MSR ACLR measurement (`MSR_ACLRExample.xml`). It sets up the measurement for the MSR signal generator waveform described in the file `C:\R_S\instr\user\waveform\MSRA_GSM_WCDMA_LET_GSM.wv`.

Note that ACLR user standards are not supported for Fast ACLR and multicarrier ACLR measurements.

Note: User standards created on an analyzer of the R&S FSP family are compatible to the R&S FPS. User standards created on an R&S FPS, however, are not necessarily compatible to the analyzers of the R&S FSP family and may not work there.

The following parameter definitions are saved in a user-defined standard:

- Number of adjacent channels
- Channel bandwidth of transmission (Tx), adjacent (Adj) and alternate (Alt) channels
- Channel spacings
- Weighting filters
- Resolution bandwidth
- Video bandwidth
- Detector
- ACLR limits and their state
- Sweep time and sweep time coupling
- Trace and power mode
- (MSR only: sub block and gap channel definition)

User-defined standards are managed in the "Manage" dialog box which is displayed when you select the "Manage User Standards" button in the "General Settings" tab of the "CP/ACLR Setup" dialog box.



In the "Manage" dialog box you can save the current measurement settings as a user-defined standard, or load a stored measurement configuration. Furthermore, you can delete an existing configuration file.

For details see [chapter 5.3.6.4, "How to Manage User-Defined Configurations"](#), on page 179.

Remote command:

To query all available standards:

`CALCulate<n>:MARKer<m>:FUNCTION:POWER:STANDARD:CATALOG?`

on page 612

To load a standard:

`CALCulate<n>:MARKer<m>:FUNCTION:POWER:PRESet` on page 612

To save a standard:

`CALCulate<n>:MARKer<m>:FUNCTION:POWER:STANDARD:SAVE` on page 612

To delete a standard:

`CALCulate<n>:MARKer<m>:FUNCTION:POWER:STANDARD:DELETE` on page 612

Number of Sub Blocks

Defines the number of sub blocks, i.e. groups of transmission channels in an MSR signal.

For more information see [chapter 5.3.3.4, "Measurement on Multi-Standard Radio \(MSR\) Signals"](#), on page 146.

Remote command:

`[SENSe:] POWER:ACHannel:SBCount` on page 628

Reference Channel

The measured power values in the adjacent channels can be displayed relative to the transmission channel. If more than one Tx channel is defined, you must select which one is to be used as a reference channel.

Channel Power and Adjacent-Channel Power (ACLR) Measurement

Tx Channel 1	Transmission channel 1 is used. (Not available for MSR ACLR)
Min Power Tx Channel	The transmission channel with the lowest power is used as a reference channel.
Max Power Tx Channel	The transmission channel with the highest power is used as a reference channel (Default).
Lowest & Highest Channel	The outer left-hand transmission channel is the reference channel for the lower adjacent channels, the outer right-hand transmission channel that for the upper adjacent channels.

Remote command:

[\[SENSe:\]POWer:ACHannel:REference:TXChannel:MANual](#) on page 620

[\[SENSe:\]POWer:ACHannel:REference:TXChannel:AUTO](#) on page 619

Noise cancellation

The results can be corrected by the instrument's inherent noise, which increases the dynamic range.

In this case, a reference measurement of the instrument's inherent noise is carried out. The measured noise power is then subtracted from the power in the channel that is being analyzed (first active trace only).

The inherent noise of the instrument depends on the selected center frequency, resolution bandwidth and level setting. Therefore, the correction function is disabled whenever one of these parameters is changed. A disable message is displayed on the screen. To enable the correction function after changing one of these settings, activate it again. A new reference measurement is carried out.

Noise cancellation is also available in zero span.

Currently, noise cancellation is only available for the following trace detectors (see ["Detector"](#) on page 411):

- RMS
- Average
- Sample
- Positive Peak

Remote command:

[\[SENSe:\]POWer:NCORrection](#) on page 756

Selected Trace

The CP/ACLR measurement can be performed on any active trace.

Remote command:

[\[SENSe:\]POWer:TRACe](#) on page 611

Absolute and Relative Values (ACLR Mode)

The powers of the adjacent channels are output in dBm or dBm/Hz (absolute values), or in dBc, relative to the specified reference Tx channel.

"Abs" The absolute power in the adjacent channels is displayed in the unit of the y-axis, e.g. in dBm, dB μ V.

Channel Power and Adjacent-Channel Power (ACLR) Measurement

"Rel" The level of the adjacent channels is displayed relative to the level of the transmission channel in dBc.

Remote command:

[SENSe:] POWER:ACHannel:MODE on page 642

Channel Power Levels and Density (Power Unit)

By default, the channel power is displayed in absolute values. If "/Hz" is activated, the channel power density is displayed instead. Thus, the absolute unit of the channel power is switched from dBm to dBm/Hz.

Note: The channel power density in dBm/Hz corresponds to the power inside a bandwidth of 1 Hz and is calculated as follows:

"channel power density = channel power – log₁₀(channel bandwidth)"

Thus you can measure the signal/noise power density, for example, or use the additional functions [Absolute and Relative Values \(ACLR Mode\)](#) and [Reference Channel](#) to obtain the signal to noise ratio.

Remote command:

CALCulate<n>:MARKer<m>:FUNCTION:POWER:RESult:PHZ on page 641

Power Mode

The measured power values can be displayed directly for each trace ("Clear/Write"), or only the maximum values over a series of measurements can be displayed ("Max Hold"). In the latter case, the power values are calculated from the current trace and compared with the previous power value using a maximum algorithm. The higher value is retained. If "Max Hold" mode is activated, "Pwr Max" is indicated in the table header. Note that the *trace* mode remains unaffected by this setting.

Remote command:

CALCulate<n>:MARKer<m>:FUNCTION:POWER:MODE on page 607

Optimized Settings (Adjust Settings)

All instrument settings for the selected channel setup (channel bandwidth, channel spacing) can be optimized automatically.

The adjustment is carried out only once. If necessary, the instrument settings can be changed later.

The following settings are optimized by "Adjust Settings":

- ["Frequency Span"](#) on page 144
- ["Resolution Bandwidth \(RBW\)"](#) on page 144
- ["Video Bandwidth \(VBW\)"](#) on page 145
- ["Detector"](#) on page 145
- ["Trace Averaging"](#) on page 146

Note: The reference level is not affected by this function. To adjust the reference level automatically, use the [Setting the Reference Level Automatically \(Auto Level\)](#) function in the AUTO SET menu.

Remote command:

[SENSe:] POWER:ACHannel:PRESet on page 610

Channel Power and Adjacent-Channel Power (ACLR) Measurement

Symmetrical Adjacent Setup

If enabled, the upper and lower adjacent and alternate channels are defined symmetrically. This is the default behaviour and corresponds to the behavior in previous firm-ware versions.

If disabled, the upper and lower channels can be configured differently. This is particularly useful if the lowest Tx channel and highest Tx channel use different standards and thus require different bandwidths for adjacent channel power measurement.

Remote command:

[SENSe:]POWER:ACHannel:SSETup on page 632

Limit Checking

Activates or deactivates limit checks globally for all adjacent and gap channels. In addition to this setting, limits must be defined and activated individually for each channel.

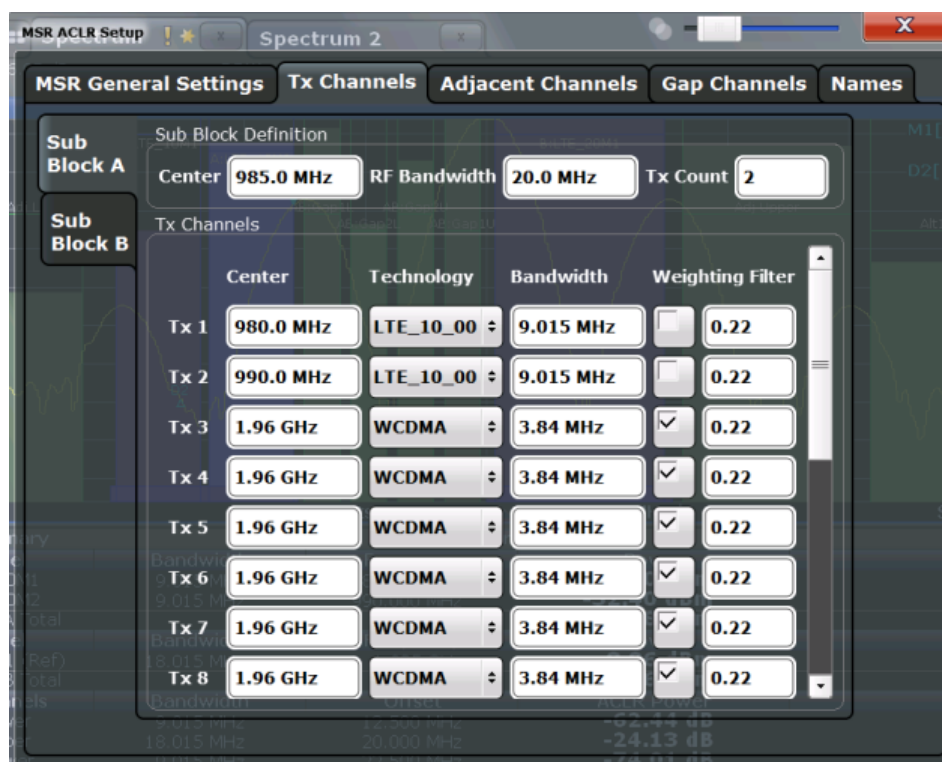
The results of the power limit checks are also indicated in the STAT:QUES:ACPL status registry (see "[STATus:QUESTIONable:ACPLimit Register](#)" on page 564).

Remote command:

CALCulate<n>:LIMit<k>:ACPower[:STATe] on page 625

5.3.5.2 MSR Sub Block and Tx Channel Definition

The "Tx Channels" tab in the "MSR ACLR Setup" dialog box provides all the channel settings to configure sub blocks and Tx channels in MSR ACLR measurements.



For details on MSR signals see [chapter 5.3.3.4, "Measurement on Multi-Standard Radio \(MSR\) Signals"](#), on page 146.

For details on setting up channels, see [chapter 5.3.6.3, "How to Configure an MSR ACLR Measurement"](#), on page 178.

The Tx channel settings for the individual sub blocks are configured in individual sub-tabs of the "Tx Channel Settings" tab.

Sub Block Definition.....	168
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L Number of Tx Channels (Tx Count).....	168
Tx Channel Definition.....	168
L Tx Center Frequency.....	169
L Technology Used for Transmission.....	169
L Tx Channel Bandwidth.....	169
L Weighting Filters.....	170

Sub Block Definition

Sub blocks are groups of transmit channels in an MSR signal. Up to 5 sub blocks can be defined. They are defined as an RF bandwidth around a center frequency with a specific number of transmit channels (max. 18).

Sub blocks are named A,B,C,D,E and are indicated by a slim blue bar along the frequency axis.

Sub Block Center Frequency ← Sub Block Definition

Defines the center of an MSR sub block. Note that the position of the sub block also affects the position of the adjacent gap channels.

Remote command:

`[SENSe:]POWer:ACHannel:SBLOCK<sb>:FREQuency:CENTer` on page 629

RF Bandwidth ← Sub Block Definition

Defines the bandwidth of the individual MSR sub block. Note that sub block ranges also affect the position of the adjacent gap channels.

Remote command:

`[SENSe:]POWer:ACHannel:SBLOCK<sb>:RFBWidth` on page 630

Number of Tx Channels (Tx Count) ← Sub Block Definition

Defines the number of transmit channels the specific sub block contains. The maximum is 18 Tx channels.

Remote command:

`[SENSe:]POWer:ACHannel:SBLOCK<sb>:TXCHannel:COUNT` on page 631

Tx Channel Definition

As opposed to common ACLR channel definitions, the Tx channels are defined at absolute frequencies, rather than by a spacing relative to the (common) center frequency. Each transmit channel can be assigned a different technology, used to predefine the required bandwidth.

The Tx channel settings for the individual sub blocks are configured in individual sub-tabs of the "Tx Channel Settings" tab.

For details on configuring MSR Tx channels see [chapter 5.3.6.3, "How to Configure an MSR ACLR Measurement"](#), on page 178.

Remote command:

`[SENSe:] POWer:ACHannel:SBLOCK<sb>:NAME[:CHANnel<ch>]` on page 640

Tx Center Frequency ← Tx Channel Definition

Defines the (absolute) center frequency of an MSR Tx channel. Each Tx channel is defined independently of the others; automatic spacing as in common ACLR measurements is not performed.

Note that the position of the first Tx channel in the first sub block and the last Tx channel in the last sub block also affect the position of the adjacent channels.

Remote command:

`[SENSe:] POWer:ACHannel:SBLOCK<sb>:CENTer[:CHANnel<ch>]` on page 629

Technology Used for Transmission ← Tx Channel Definition

The technology used for transmission by the individual channel can be defined for each channel. The required channel bandwidth and use of a weighting filter are pre-configured automatically according to the selected technology standard.

"GSM"	Transmission according to GSM standard
"W-CDMA"	Transmission according to W-CDMA standard
"LTE_xxx"	Transmission according to LTE standard for different channel bandwidths
"USER"	User-defined transmission; no automatic preconfiguration possible

Remote command:

`[SENSe:] POWer:ACHannel:SBLOCK<sb>:TECHnology[:CHANnel<ch>]`
on page 630

Tx Channel Bandwidth ← Tx Channel Definition

The Tx channel bandwidth is normally defined by the transmission technology standard. The correct bandwidth is predefined automatically for the selected technology. Each Tx channel is defined independently of the others; automatic bandwidth configuration for subsequent channels as in common ACLR measurements is not performed.

The bandwidth for each channel is indicated by a colored bar in the display.

Remote command:

`[SENSe:] POWer:ACHannel:SBLOCK<sb>:BANDwidth|BWIDth[:CHANnel<ch>]`
on page 628

Weighting Filters ← Tx Channel Definition

Weighting filters allow you to determine the influence of individual channels on the total measurement result. For each channel you can activate or deactivate the use of the weighting filter and define an individual weighting factor ("Alpha" value).

Remote command:

Activating/Deactivating:

[SENSe:]POWER:ACHannel:FILTER:STATE:SBLOCK<sb>:CHANNEL<ch>
on page 628

Alpha value:

[SENSe:]POWER:ACHannel:FILTER:ALPHA:SBLOCK<sb>:CHANNEL<ch>
on page 627

5.3.5.3 MSR Adjacent Channel Setup

The "Adjacent Channel" tab in the "MSR ACLR Setup" dialog box provides all the channel settings to configure adjacent and gap channels in MSR ACLR measurements.



For symmetrical channel definition (see "Symmetrical Adjacent Setup" on page 167) the dialog box is reduced as the upper and lower channels are identical.

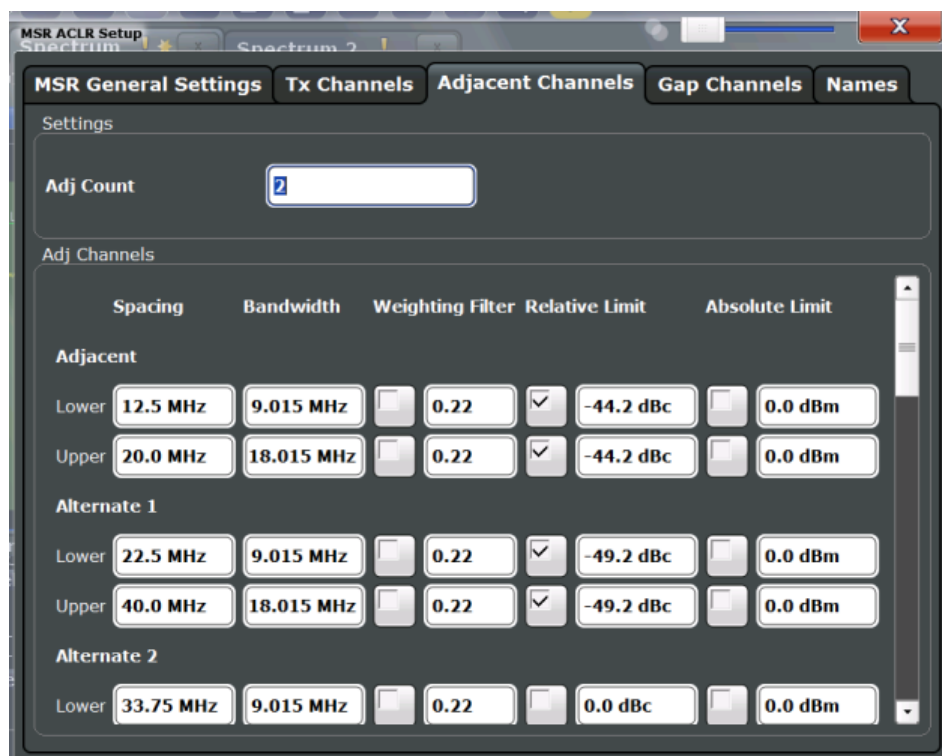


Fig. 5-28: Asymmetrical adjacent channel definition

For details on setting up channels see [chapter 5.3.6.3, "How to Configure an MSR ACLR Measurement"](#), on page 178.

Number of Adjacent Channels (ADJ Count).....	171
Adjacent Channel Definition.....	171
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Number of Adjacent Channels (ADJ Count)

Defines the number of adjacent channels *above and below* the Tx channel block in an MSR signal. The carrier channel to which the relative adjacent-channel power values should be referenced must be defined (see "[Reference Channel](#)" on page 154).

Remote command:

`[SENSe:]POWer:ACHannel:ACPairs` on page 613

Adjacent Channel Definition

Defines the channels adjacent to the transmission channel block in MSR signals. A maximum of 12 adjacent channels can be defined.

For MSR signals, adjacent channels are defined in relation to the center frequency of the first and last transmission channel in the entire block, i.e.:

- The lower adjacent channels are defined in relation to the CF of the first Tx channel in the first sub block.
- The upper adjacent channels are defined in relation to the CF of the last Tx channel in the last sub block.

Adjacent channels are named "Adj" and "Alt1" to "Alt11" by default; the names can be changed manually (see [chapter 5.3.5.5, "MSR Channel Names"](#), on page 175).

In all other respects, channel definition is identical to common ACLR measurements.

Adjacent Channel Spacings ← Adjacent Channel Definition

Channel spacings are normally predefined by the selected technology but can be changed.

For MSR signals, adjacent channels are defined in relation to the center frequency of the first and last transmission channel in the entire block, i.e.:

- The spacing of the lower adjacent channels refers to the CF of the first Tx channel in the first sub block.
- The spacing of the upper adjacent channels refers to the CF of the last Tx channel in the last sub block.

For details see [chapter 5.3.6.3, "How to Configure an MSR ACLR Measurement"](#), on page 178

Remote command:

`[SENSe:]POWer:ACHannel:SPACing[:ACHannel]` on page 615

`[SENSe:]POWer:ACHannel:SPACing:ALTernate<ch>` on page 615

`[SENSe:]POWer:ACHannel:SPACing:UACHannel` on page 631

`[SENSe:]POWer:ACHannel:SPACing:UALTernate<ch>` on page 632

Adjacent Channel Bandwidths ← Adjacent Channel Definition

The adjacent channel bandwidth is normally predefined by the transmission technology standard. The correct bandwidth is set automatically for the selected technology. The bandwidth for each channel is indicated by a colored bar in the display.

Remote command:

[SENSe:] POWer:ACHannel: BANDwidth| BWIDth:ACHannel on page 613

[SENSe:] POWer:ACHannel: BANDwidth| BWIDth:ALternate<ch> on page 613

[SENSe:] POWer:ACHannel: BANDwidth| BWIDth:UACHannel on page 632

[SENSe:] POWer:ACHannel: BANDwidth| BWIDth:UALternate<ch> on page 633

Weighting Filters ← Adjacent Channel Definition

Weighting filters allow you to determine the influence of individual channels on the total measurement result. For each channel you can activate or deactivate the use of the weighting filter and define an individual weighting factor ("Alpha" value).

Remote command:

Activating/Deactivating:

[SENSe:] POWer:ACHannel: FILTer[:STATe]:ACHannel on page 618

[SENSe:] POWer:ACHannel: FILTer[:STATe]:ALternate<ch> on page 618

[SENSe:] POWer:ACHannel: FILTer[:STATe]:UACHannel on page 634

[SENSe:] POWer:ACHannel: FILTer[:STATe]:UALternate<ch> on page 634

Alpha value:

[SENSe:] POWer:ACHannel: FILTer:ALPHa:ACHannel on page 617

[SENSe:] POWer:ACHannel: FILTer:ALPHa:ALternate<ch> on page 617

[SENSe:] POWer:ACHannel: FILTer:ALPHa:UACHannel on page 633

[SENSe:] POWer:ACHannel: FILTer:ALPHa:UALternate<ch> on page 633

Limit Checking ← Adjacent Channel Definition

During an ACLR measurement, the power values can be checked whether they exceed user-defined or standard-defined limits. A relative or absolute limit can be defined, or both, for each individual adjacent channel. Both limit types are considered, regardless whether the measured levels are absolute or relative values. The check of both limit values can be activated independently. If any active limit value is exceeded, the measured value is displayed in red and marked by a preceding asterisk in the result table.

Note that in addition to activating limit checking for individual channels, limit checking must also be activated globally for the MSR ACLR measurement (see "Limit Checking" on page 167).

Channel Power and Adjacent-Channel Power (ACLR) Measurement

2 Result Summary		Multi-Standard Radio		
Channel	Bandwidth	Frequency	Power	
B:GSM2	200.000 kHz	1.020 GHz	-80.44 dBm	
Sub Block B Total			-29.15 dBm	
Channel	Bandwidth	Offset	Lower	Upper
Adj*	3.840 MHz	5.000 MHz	-33.27 dB *	-32.63 dB *
Alt1	3.840 MHz	10.000 MHz	-49.76 dB	-50.37 dB

Remote command:

`CALCulate<n>:LIMit<k>:ACPowe[r]:STATE` on page 625

`CALCulate<n>:LIMit<k>:ACPowe[r]:ACHanne[l]:ABSolute:STATE` on page 621

`CALCulate<n>:LIMit<k>:ACPowe[r]:ACHanne[l]:ABSolute` on page 620

`CALCulate<n>:LIMit<k>:ACPowe[r]:ACHanne[l][:RELative]:STATE`

on page 622

`CALCulate<n>:LIMit<k>:ACPowe[r]:ACHanne[l][:RELative]` on page 621

`CALCulate<n>:LIMit<k>:ACPowe[r]:ALTernate<ch>:ABSolute:STATE`

on page 623

`CALCulate<n>:LIMit<k>:ACPowe[r]:ALTernate<ch>:ABSolute` on page 623

`CALCulate<n>:LIMit<k>:ACPowe[r]:ALTernate<ch>[:RELative]:STATE`

on page 625

`CALCulate<n>:LIMit<k>:ACPowe[r]:ALTernate<ch>[:RELative]` on page 624

`CALCulate<n>:LIMit<k>:ACPowe[r]:ACHanne[l]:RESult?` on page 622

5.3.5.4 MSR Gap Channel Setup

The "Gap Channels" tab in the "MSR ACLR Setup" dialog box provides all the channel settings to configure adjacent and gap channels in MSR ACLR measurements.



For details on MSR signals see [chapter 5.3.3.4, "Measurement on Multi-Standard Radio \(MSR\) Signals"](#), on page 146.

For details on setting up channels see [chapter 5.3.6.3, "How to Configure an MSR ACLR Measurement"](#), on page 178.

Activate Gaps.....	174
Minimum gap size to show gap 1/2.....	174
Gap Channel Definition.....	174
L Gap Channel Spacings.....	174
L Gap Channel Bandwidths.....	175
L Weighting Filters.....	175
L Limit Checking.....	175

Activate Gaps

If enabled, the gap channels are displayed and channel power results are calculated and displayed in the Result Summary.

Remote command:

[SENSe:] POWER:ACHannel:AGChannels on page 637

Minimum gap size to show gap 1/2

If the gap between the sub blocks does not exceed the specified bandwidth, the gap channels are not displayed in the diagram, and the gap channel results are not calculated in the result summary.

Remote command:

[SENSe:] POWER:ACHannel:GAP<gap>:MSIZE on page 638

Gap Channel Definition

Between two sub blocks in an MSR signal, two gaps are defined: a *lower gap* and an *upper gap*. Each gap in turn contains 2 channels, the *gap channels*. The channels in the upper gap are identical to those in the lower gap, but inverted. Thus, in the R&S FPS MSR ACLR measurement, only 2 gap channels are configured.

Gap channels are indicated by the names of the surrounding sub blocks (e.g. "AB" for the gap between sub blocks A and B), followed by the channel name ("Gap1" or "Gap2") and an "L" (for lower) or a "U" (for upper).

Gap Channel Spacings ← Gap Channel Definition

Gap channel spacings are normally predefined by the MSR standard but can be changed.

Gap channels are defined using bandwidths and spacings, relative to the outer edges of the surrounding sub blocks. Since the upper and lower gap channels are identical, only two channels must be configured. The required spacing can be determined according to the following formula (indicated for lower channels):

$$\text{Spacing} = [\text{CF of the gap channel}] - [\text{left sub block center}] + ([\text{RF bandwidth of left sub block}] / 2)$$

(See also [figure 5-25](#) and [figure 5-26](#).)

For details see [chapter 5.3.6.3, "How to Configure an MSR ACLR Measurement"](#), on page 178.

Remote command:

[SENSe:] POWER:ACHannel:SPACing:GAP<gap> on page 639

Gap Channel Bandwidths ← Gap Channel Definition

The gap channel bandwidth is normally predefined by the transmission technology standard. The correct bandwidth is set automatically for the selected technology. The bandwidth for each channel is indicated by a colored bar in the display (if the gap is not too narrow, see "Channel display for MSR signals" on page 149).

Remote command:

[SENSe:] POWER:ACHannel: BANDwidth| BWIDth: GAP<gap> on page 637

Weighting Filters ← Gap Channel Definition

Weighting filters allow you to determine the influence of individual channels on the total measurement result. For each channel you can activate or deactivate the use of the weighting filter and define an individual weighting factor ("Alpha" value).

Remote command:

[SENSe:] POWER:ACHannel: FILTer: STATe: GAP<gap> on page 638

[SENSe:] POWER:ACHannel: FILTer: ALPHa: GAP<gap> on page 638

Limit Checking ← Gap Channel Definition

During an ACLR measurement, the power values can be checked whether they exceed user-defined or standard-defined limits. A relative or absolute limit can be defined, or both, for each individual gap channel. Both limit types are considered, regardless whether the measured levels are absolute or relative values. The check of both limit values can be activated independently. Furthermore, relative limits can be defined and activated individually for ACLR or CACLR power levels.

If any active limit value is exceeded, the measured value is displayed in red and marked by a preceding asterisk in the result table.

Note that in addition to activating limit checking for individual channels, limit checking must also be activated globally for the MSR ACLR measurement (see "Limit Checking" on page 167).

Remote command:

CALCulate<n>: LIMit<k>: ACPower[: STATe] on page 625

CALCulate<n>: LIMit<k>: ACPower: GAP<gap>: ABSolute: STATe on page 635

CALCulate<n>: LIMit<k>: ACPower: GAP<gap>: ACLR[: RELative:] STATe on page 636

CALCulate<n>: LIMit<k>: ACPower: GAP<gap>[: CACLR] [: RELative:] STATe on page 636

CALCulate<n>: LIMit<k>: ACPower: GAP<gap>: ABSolute on page 635

CALCulate<n>: LIMit<k>: ACPower: GAP<gap>: ACLR[: RELative] on page 635

CALCulate<n>: LIMit<k>: ACPower: GAP<gap>[: CACLR] [: RELative] on page 636

CALCulate<n>: LIMit<k>: ACPower: GAP<gap>: RESult? on page 641

5.3.5.5 MSR Channel Names

As of firmware version 2.10, channel names for all TX, adjacent, and alternate channels are user-definable.

In the "Names" tab of the "MSR ACLR Setup" dialog box you can define a customized name for each channel in each sub block. Note that the names are not checked for uniqueness.

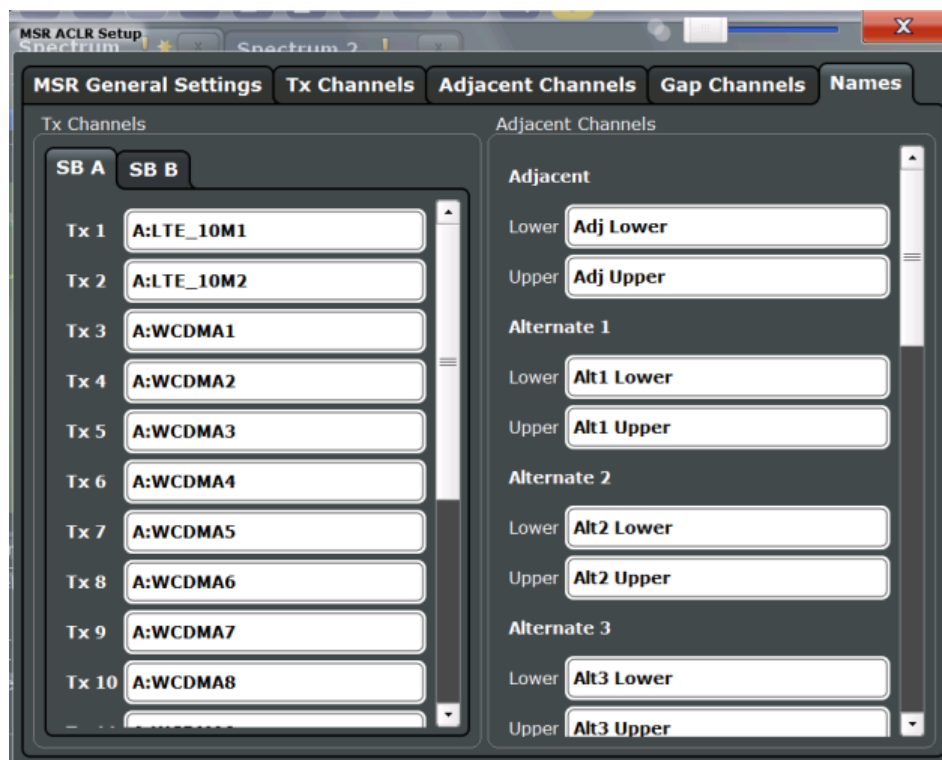


Fig. 5-29: Channel name definition for asymmetric adjacent channels

Remote command:

[SENSe:] POWER:ACHannel:SBLOCK<sb>:NAME[:CHANNEL<ch>] on page 640

[SENSe:] POWER:ACHannel:NAME:ACHannel on page 614

[SENSe:] POWER:ACHannel:NAME:ALternate<ch> on page 614

[SENSe:] POWER:ACHannel:NAME:UACHannel on page 639

[SENSe:] POWER:ACHannel:NAME:UALternate<ch> on page 639

5.3.6 How to Perform Channel Power Measurements

The following step-by-step instructions demonstrate the most common tasks when performing channel power measurements.

- [How to Perform a Standard Channel Power Measurement](#)..... 177
- [How to Set up the Channels](#)..... 177
- [How to Configure an MSR ACLR Measurement](#)..... 178
- [How to Manage User-Defined Configurations](#)..... 179
- [How to Compare the Tx Channel Power in Successive Measurements](#)..... 180

5.3.6.1 How to Perform a Standard Channel Power Measurement

Performing a channel power or ACLR measurement according to common standards is a very easy and straightforward task with the R&S FPS.

1. Press the MEAS key or select "Select Measurement" in the "Overview".
2. Select "Channel Power ACLR".
The measurement is started immediately with the default settings.
3. Select the "CP / ACLR Standard" softkey and select a standard from the list.
The measurement is restarted with the predefined settings for the selected standard.
4. If necessary, edit the settings for your specific measurement as described in [chapter 5.3.6.2, "How to Set up the Channels"](#), on page 177, or load a user-defined configuration (see ["To load a user-defined configuration"](#) on page 180).

5.3.6.2 How to Set up the Channels

Channel definition is the basis for measuring power levels in certain frequency ranges. Usually, the power levels in one or more carrier (Tx) channels and possibly the adjacent channels are of interest. Up to 18 carrier channels and up to 12 adjacent channels can be defined.

When a measurement standard is selected in the "Ch Power" menu or the "ACLR Setup" dialog box, all settings including the channel bandwidths and channel spacings are set according to the selected standard and can be adjusted afterwards.

Channel setup consists of the following settings:

- The number of transmission (Tx) and adjacent channels
- The bandwidth of each channel
- For multicarrier ACLR measurements: which Tx channel is used as a reference
- The spacing between the individual channels
- Optionally: the names of the channels displayed in the diagram and result table
- Optionally: the influence of individual channels on the total measurement result ("Weighting Filter")
- Optionally: limits for a limit check on the measured power levels



Changes to an existing standard can be stored as a user-defined standard, see [chapter 5.3.6.4, "How to Manage User-Defined Configurations"](#), on page 179.

- ▶ In the "Ch Power" menu, select the "CP / ACLR Config" softkey, then select the "Channel Settings" tab to configure the channels in the "ACLR Setup" dialog box.



In the "Channel Setup" dialog box you can define the channel settings for all channels, independent of the defined number of *used* Tx or adjacent channels.

To define channel spacings

Channel spacings are normally defined by the selected standard but can be changed.

- ▶ In the "Channel Settings" tab of the "ACLR Setup" dialog box, select the "Spacing" subtab.

The value entered for any Tx channel is automatically also defined for all subsequent Tx channels. Thus, only one value needs to be entered if all Tx channels have the same spacing.

If the channel spacing for the adjacent or an alternate channel is changed, all higher alternate channel spacings are multiplied by the same factor (new spacing value/old spacing value). The lower adjacent-channel spacings remain unchanged. Only one value needs to be entered for equal channel spacing.

Example: Defining channel spacing

In the default setting, the adjacent channels have the following spacing: 20 kHz ("ADJ"), 40 kHz ("ALT1"), 60 kHz ("ALT2"), 80 kHz ("ALT3"), 100 kHz ("ALT4"), ...

If the spacing of the first adjacent channel ("ADJ") is set to 40 kHz, the spacing of all other adjacent channels is multiplied by factor 2 to result in 80 kHz ("ALT1"), 120 kHz ("ALT2"), 160 kHz ("ALT3"), ...

If, starting from the default setting, the spacing of the 5th adjacent channel ("ALT4") is set to 150 kHz, the spacing of all higher adjacent channels is multiplied by factor 1.5 to result in 180 kHz ("ALT5"), 210 kHz ("ALT6"), 240 kHz ("ALT7"), ...

5.3.6.3 How to Configure an MSR ACLR Measurement

Performing an ACLR measurement on MSR signals is supported by a special configuration with the R&S FPS.

1. Press the MEAS key or select "Select Measurement" in the "Overview".
2. Select "Channel Power ACLR".
The measurement is started immediately with the default settings.
3. Select the "CP / ACLR Standard" softkey and select the "Multi-Standard Radio" standard from the list.
4. Select the "CP / ACLR Config" softkey to configure general MSR settings, including the number of sub blocks (up to 5).
In order to configure asymmetric adjacent channels, deactivate the "Symmetrical" option in the general MSR settings.
5. Select the "Tx Channels" tab to configure the sub blocks and transmission channels.
For each sub block:

Channel Power and Adjacent-Channel Power (ACLR) Measurement

- a) Define the (center frequency) position and bandwidth of the sub block, as well as the number of transmission channels it contains.
 - b) For each transmission channel in the sub block, define the center frequency and select the technology used for transmission. If necessary, edit the bandwidth and define the use of a weighting filter for the channel.
6. Select the "Adjacent Channels" tab to configure the adjacent channels.
 7. Define the number of adjacent channels and the settings for each channel:
 - The spacing, defined as the distance of the center frequency from the center frequency of the first transmission channel in the first sub block.
For asymmetrical channels, define the upper adjacent channel spacing as the distance from the center frequency of the last transmission channel in the last sub block.
 - The bandwidth
 - If necessary, a weighting filter
 - Optionally, define *and activate* relative or absolute limits, or both, against which the power levels of the channel are to be checked.
 8. Select the "Gap Channels" tab to configure the gap channels.
 9. Define the settings for the two (upper or lower) gap channels; since the upper and lower channels are identical, it is only necessary to configure two channels.
 - The spacing, defined as the distance of the center frequency from the outer edge of the sub block to the left or right of the gap. The required spacing can be determined as follows:
Spacing = [CF of the gap channel] - [left sub block center] + ([RF bandwidth of left sub block] / 2)
 - The bandwidth
 - If necessary, a weighting filter
 - Optionally, define *and activate* relative or absolute limits, or both, against which the power levels of the channel are to be checked.
 10. If power limits are defined and activated, activate global limit checking for the measurement on the "MSR General Settings" tab.
 11. Optionally, store the settings for the MSR ACLR measurement as a user-defined standard as described in ["To store a user-defined configuration"](#) on page 180. Otherwise the configuration will be lost when you select a different measurement standard!

5.3.6.4 How to Manage User-Defined Configurations

You can define measurement configurations independently of a predefined standard and save the current ACLR configuration as a "user standard" in an xml file. You can then load the file and thus the settings again at a later time.

User-defined standards are not supported for "Fast ACLR" and multicarrier ACLR measurements.



Compatibility to R&S FSP

User standards created on an analyzer of the R&S FSP family are compatible to the R&S FPS. User standards created on an R&S FPS, however, are not necessarily compatible to the analyzers of the R&S FSP family and may not work there.

To store a user-defined configuration

1. In the "Ch Power" menu, select the "CP / ACLR Config" softkey to display the "ACLR Setup" dialog box.
2. Configure the measurement as required (see also [chapter 5.3.6.2, "How to Set up the Channels"](#), on page 177).
3. In the "General Settings" tab, select the "Manage User Standards" button to display the "Manage" dialog box.
4. Define a file name for the user standard and select its storage location.
By default, the xml file is stored in `C:\R_S\Instr\acp_std\`. However, you can define any other storage location.
5. Select "Save".

To load a user-defined configuration

1. In the "General Settings" tab of the "ACLR Setup" dialog box, select the "Manage User Standards" button to display the "Manage" dialog box.
2. Select the user standard file.
3. Select "Load".

The stored settings are automatically set on the R&S FPS and the measurement is restarted with the new parameters.

5.3.6.5 How to Compare the Tx Channel Power in Successive Measurements

For pure channel power measurements, where no adjacent channels and only one Tx channel is defined, you can define a fixed reference power and compare subsequent measurement results to the stored reference power.

1. Configure a measurement with only one Tx channel and no adjacent channels (see also [chapter 5.3.6.2, "How to Set up the Channels"](#), on page 177).
2. Select the "Set CP Reference" softkey in the "Ch Power" menu, or the "Set CP Reference" button in the "ACLR Setup" dialog box.

The channel power currently measured on the Tx channel is stored as a fixed reference power. The reference value is displayed in the "Reference" field of the result table (in relative ACLR mode).

3. Start a new measurement.

The resulting power is indicated relative to the fixed reference power.

4. Repeat this for any number of measurements.
5. To start a new measurement without the fixed reference, temporarily define a second channel or preset the instrument.

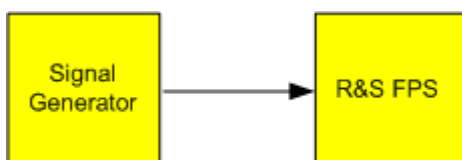
5.3.7 Measurement Examples

The R&S FPS has test routines for simple channel and adjacent channel power measurements. These routines give quick results without any complex or tedious setting procedures.

- [Measurement Example 1 – ACPR Measurement on an CDMA2000 Signal.....](#) 181
- [Measurement Example 3 – Measuring the Intrinsic Noise of the R&S FPS with the Channel Power Function.....](#) 182

5.3.7.1 Measurement Example 1 – ACPR Measurement on an CDMA2000 Signal

Test setup:



Signal generator settings (e.g. R&S SMW):

Frequency:	850 MHz
Level:	0 dBm
Modulation:	CDMA2000

Procedure:

1. Preset the R&S FPS.
2. Set the center frequency to *850 MHz*.
3. Set the span to *4 MHz*.
4. Set the reference level to *+10 dBm*.
5. Select the "Channel Power ACLR" measurement function from the "Select Measurement" dialog box.
6. Set the "CDMA2000 1X" standard for adjacent channel power measurement in the "ACLR Setup" dialog box.

Channel Power and Adjacent-Channel Power (ACLR) Measurement

The R&S FPS sets the channel configuration according to the 2000 standard with 2 adjacent channels above and 2 below the transmit channel. The spectrum is displayed in the upper part of the screen, the numeric values of the results and the channel configuration in the lower part of the screen. The various channels are represented by vertical lines on the graph.

The frequency span, resolution bandwidth, video bandwidth and detector are selected automatically to give correct results. To obtain stable results – especially in the adjacent channels (30 kHz bandwidth) which are narrow in comparison with the transmission channel bandwidth (1.23 MHz) – the RMS detector is used.

7. Set the optimal reference level and RF attenuation for the applied signal level using the "Auto Level" function in the AUTO SET menu.
8. Activate "Fast ACLR" mode in the "ACLR Setup" dialog box to increase the repeatability of results.

The R&S FPS sets the optimal RF attenuation and the reference level based on the transmission channel power to obtain the maximum dynamic range. The [figure 5-30](#) shows the result of the measurement.

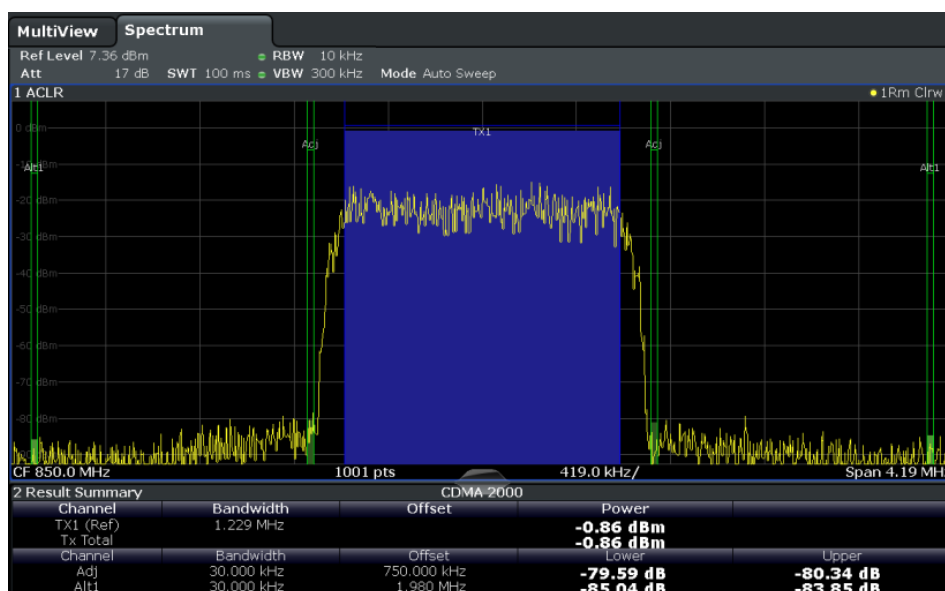


Fig. 5-30: Adjacent channel power measurement on a CDMA2000 1x signal

5.3.7.2 Measurement Example 3 – Measuring the Intrinsic Noise of the R&S FPS with the Channel Power Function

Noise in any bandwidth can be measured with the channel power measurement functions. Thus the noise power in a communication channel can be determined, for example. If the noise spectrum within the channel bandwidth is flat, the noise marker can be used to determine the noise power in the channel by considering the channel bandwidth. If, however, phase noise and noise that normally increases towards the carrier is dominant in the channel to be measured, or if there are discrete spurious signals in the

Channel Power and Adjacent-Channel Power (ACLR) Measurement

channel, the channel power measurement method must be used to obtain correct measurement results.

Test setup:

- ▶ Leave the RF input of the R&S FPS open-circuited or terminate it with 50 Ω .

Procedure:

1. Preset the R&S FPS.
2. Set the center frequency to 1 GHz and the span to 1 MHz.
3. To obtain maximum sensitivity, set RF attenuation to 0 dB and the reference level to -40 dBm.
4. Select the "Channel Power ACLR" measurement function from the "Select Measurement" dialog box.
5. In the "ACLR Setup" dialog box, set up a single Tx channel with the channel bandwidth 1.23 MHz.
6. Select the "Adjust Settings" softkey.
The settings for the frequency span, the bandwidth (RBW and VBW) and the detector are automatically set to the optimum values required for the measurement.
7. Stabilize the measurement result by increasing the sweep time.
Set the sweep time to 1 s.

The trace becomes much smoother because of the RMS detector and the channel power measurement display is much more stable.

Channel Power and Adjacent-Channel Power (ACLR) Measurement

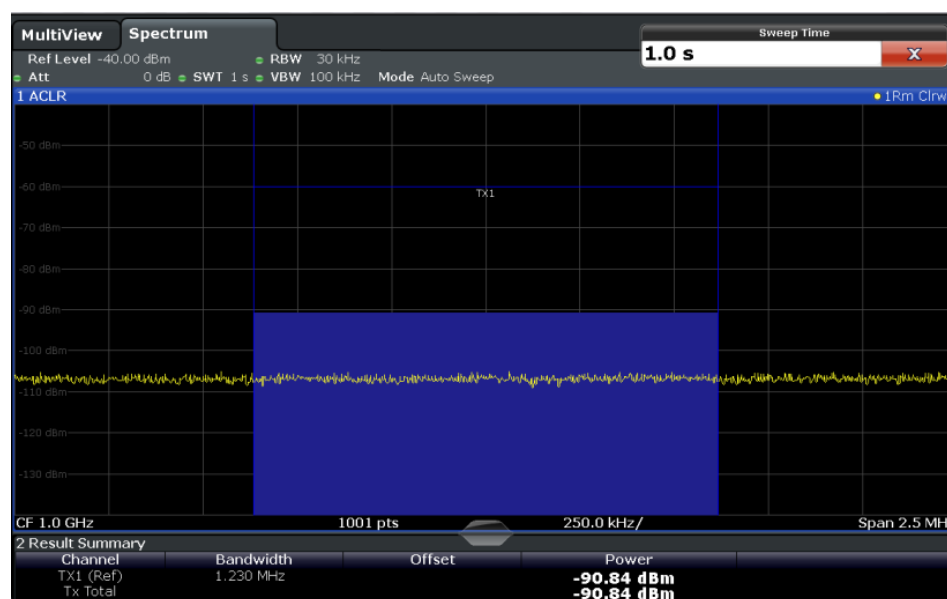


Fig. 5-31: Measurement of the R&S FPS's intrinsic noise power in a 1.23 MHz channel bandwidth.

5.3.8 Optimizing and Troubleshooting the Measurement

If the results do not meet your expectations, or if you want to minimize the measurement duration, try the following methods to optimize the measurement:

- Only activate as many **adjacent channels** as necessary in order to minimize the required span and thus the required measurement time for the measurement.
- Increase the **RBW** to minimize the measurement time; however, consider the requirements of the standard if you need to measure according to standard! The automatic settings are always according to standard.
- Take advantage of the **speed optimization mode** in the "Sweep" settings if you do not require the larger dynamic range (see "[Optimization](#)" on page 362).
- Reduce the **sweep time** and thus the amount of data to be captured and calculated; however, consider the requirements regarding the standard deviation.
- To improve the **stability of the measured results**, increase the sweep time, which also leads to more averaging steps.
- Instead of **trace averaging**, use an RMS detector with a higher sweep time to obtain better average power results in less time.
- To determine a **channel power level** quickly, use the **Time Domain Power Measurement** (TDP) rather than a Channel Power measurement. The TDP measurement is a zero span measurement where the sweep time determines the measurement time. Due to the FFT measurement, duplicate averaging is performed, providing very stable results very quickly.

Note, however, that for TDP measurements, channel filters are not available and a fixed RBW is used, so that the measurement may not be according to standard for some test cases.

5.3.9 Reference: Predefined CP/ACLR Standards

When using predefined standards for ACLR measurement, the test parameters for the channel and adjacent-channel measurements are configured automatically.

You can select a predefined standard via the "CP / ACLR Standard" softkey in the "Ch Power" menu or the selection list in the "General Settings" tab of the "ACLR Setup" dialog box (see "Standard" on page 152).

Table 5-10: Predefined CP / ACLR standards with remote command parameters

Standard	Remote parameter
None	NONE
Multi-Standard Radio	MSR
EUTRA/LTE Square	EUTRa
EUTRA/LTE Square/RRC	REUTra
W-CDMA 3GPP FWD	FW3Gppcdma
W-CDMA 3GPP REV	RW3Gppcdma
CDMA IS95A FWD	F8CDma
CDMA IS95A REV	R8CDma
CDMA IS95C Class 0 FWD*)	FIS95c0
CDMA IS95C Class 0 REV*)	RIS95c0
CDMA J-STD008 FWD	F19Cdma
CDMA J-STD008 REV	R19Cdma
CDMA IS95C Class 1 FWD*)	FIS95c1
CDMA IS95C Class 1 REV*)	RIS95c1
CDMA2000	S2CDma
TD-SCDMA FWD	FTCDma
TD-SCDMA REV	TRCDma
WLAN 802.11A	AWLAN
WLAN 802.11B	BWLAN
WIMAX	WIMax
WIBRO	WIBRo
GSM	GSM
RFID 14443	RFID14443
TETRA	TETRa
PDC	PDC
PHS	PHS
CDPD	CDPD

Standard	Remote parameter
APCO-25 P2	PAPCo25
User Standard	USER
Customized Standard	<string>



For the R&S FPS, the channel spacing is defined as the distance between the center frequency of the adjacent channel and the center frequency of the transmission channel. The definition of the adjacent-channel spacing in standards IS95C and CDMA 2000 is different. These standards define the adjacent-channel spacing from the center of the transmission channel to the closest border of the adjacent channel. This definition is also used by the R&S FPS for the standards marked with an asterisk *).

5.3.10 Reference: Predefined ACLR User Standard XML Files

In addition to the predefined standards, some user standards with specific measurement settings for common ACLR measurements are provided in xml files on the instrument in the `C:\R_S\instr\acp_std` directory.

In particular, a sample file (`MSR_ACLRExample.xml`) is provided for an MSR ACLR measurement. It sets up the measurement for the MSR signal generator waveform described in the file

`C:\R_S\instr\user\waveform\MSRA_GSM_WCDMA_LET_GSM.wv.`

Furthermore, the following xml files are provided:

LTE\DL

- LTE\DL\LTE_DL_5MHZ.XML
- LTE\DL\LTE_DL_10MHZ.XML
- LTE\DL\LTE_DL_15MHZ.XML
- LTE\DL\LTE_DL_20MHZ.XML

LTE\UL

- LTE\UL\LTE_UL_5MHZ.XML
- LTE\UL\LTE_UL_10MHZ.XML
- LTE\UL\LTE_UL_15MHZ.XML
- LTE\UL\LTE_UL_20MHZ.XML

WLAN

- WLAN\802_11ac\802_11ac_20MHZ.XML
- WLAN\802_11ac\802_11ac_40MHZ.XML
- WLAN\802_11ac\802_11ac_80MHZ.XML
- WLAN\802_11ac\802_11ac_160MHZ.XML



To load a stored measurement configuration, in the "General Settings" tab of the "ACLR Setup" dialog box, select the "Manage User Standards" button to display the "Manage" dialog box. Select the user standard file, then "Load".

The stored settings are automatically set on the R&S FPS and the measurement is restarted with the new parameters.

For details see [chapter 5.3.6.4, "How to Manage User-Defined Configurations"](#), on page 179.

5.4 Carrier-to-Noise Measurements

The R&S FPS can easily determine the carrier-to-noise ratio, also normalized to a 1 Hz bandwidth.

- [About the Measurement](#)..... 187
- [Carrier-to-Noise Results](#)..... 188
- [Carrier-to-Noise Configuration](#)..... 188
- [How to Determine the Carrier-to-Noise Ratio](#)..... 190

5.4.1 About the Measurement

The largest signal in the frequency span is the carrier. It is searched when the C/N or C/NO function is activated and is marked using a fixed reference marker ("FXD").

To determine the noise power, a channel with a defined bandwidth at the defined center frequency is analyzed. The power within this channel is integrated to obtain the noise power level. (If the carrier is within this channel, an extra step is required to determine the correct noise power level, see below.)

The noise power of the channel is subtracted from the maximum carrier signal level, and in the case of a C/N_0 measurement, it is referred to a 1 Hz bandwidth.



For this measurement, the RMS detector is activated.

The carrier-to-noise measurements are only available in the frequency domain (span >0).

Measurement process

Depending on whether the carrier is inside or outside the analyzed channel, the measurement process for the carrier-to-noise ratio varies:

- The carrier is outside the analyzed channel: In this case, it is sufficient to switch on the desired measurement function and to set the channel bandwidth. The carrier/noise ratio is displayed on the screen.
- The carrier is inside the analyzed channel: In this case, the measurement must be performed in two steps:

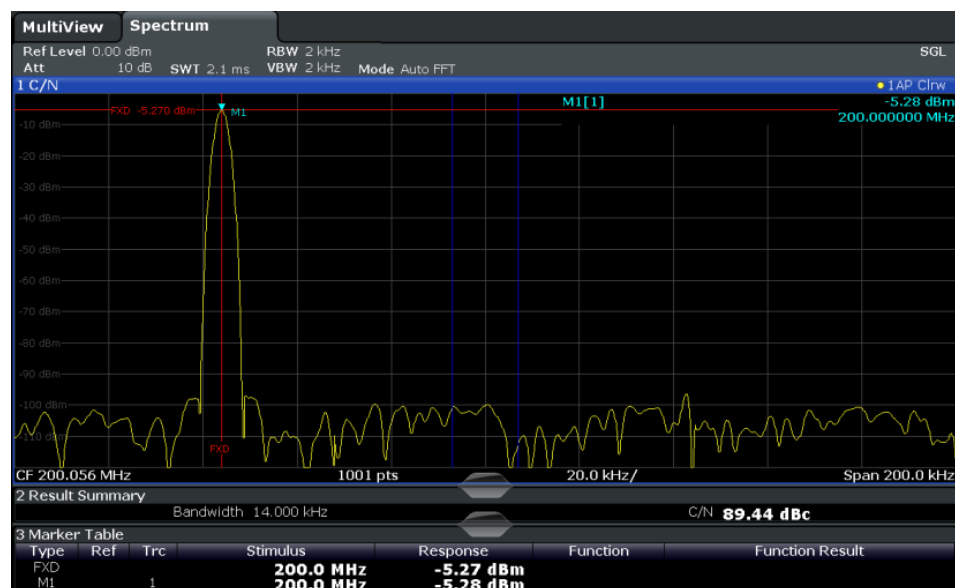
- First, perform the reference measurement by switching on either the C/N or the C/N₀ measurement and waiting for the end of the next measurement run. The fixed reference marker is set to the maximum of the measured carrier signal.
- Then, switch off the carrier so that only the noise of the test setup is active in the channel. The carrier-to-noise ratio is displayed after the subsequent measurement has been completed.

Frequency Span

The frequency span should be set to approximately 4 times the channel bandwidth in order to measure the carrier-to-noise ratio correctly. This setting is defined automatically by the "Adjust Settings" function.

5.4.2 Carrier-to-Noise Results

As a result of the carrier-to-noise measurement the evaluated bandwidth and the calculated C/N ratio are displayed in the result window. The fixed reference marker is indicated in the diagram.



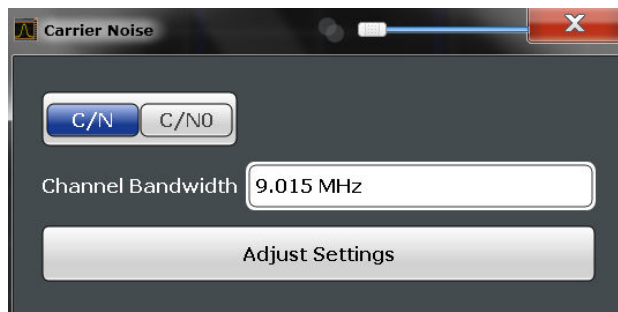
Remote command:

You can also query the determined carrier-to-noise ratio via the remote command `CALC:MARK:FUNC:POW:RES? CN` or `CALC:MARK:FUNC:POW:RES? CN0`, see [CALCulate<n>:MARKer<m>:FUNCTION:POWer<sb>:RESult?](#) on page 607.

5.4.3 Carrier-to-Noise Configuration

The Carrier-to-noise ratio (C/N) and the Carrier-to-noise ratio in relation to the bandwidth (C/N₀) measurements are selected via the corresponding button in the "Select Measurement" dialog box. The measurement is started immediately with the default

settings. It can be configured via the MEAS CONFIG key or in the "Carrier Noise" configuration dialog box, which is displayed as a tab in the "Analysis" dialog box or when you select the "Carrier Noise Config" softkey from the "Carrier Noise" menu.



Carrier-to-noise measurements are not available in zero span mode.



The easiest way to configure a measurement is using the configuration "Overview", see [chapter 6.1, "Configuration Overview"](#), on page 291.

The remote commands required to perform these tasks are described in [chapter 11.5.4, "Measuring the Carrier-to-Noise Ratio"](#), on page 647.

C/N.....	189
C/No.....	189
Channel Bandwidth.....	190
Adjust Settings.....	190

C/N

Switches the measurement of the carrier/noise ratio on or off. If no marker is active, marker 1 is activated.

The measurement is performed on the trace that marker 1 is assigned to. To shift marker 1 and measure another trace, use the "Marker to Trace" softkey in the "Marker" menu (see ["Assigning the Marker to a Trace"](#) on page 439).

Remote command:

`CALCulate<n>:MARKer<m>:FUNCTION:POWER:SElect` on page 609
`CALCulate<n>:MARKer<m>:FUNCTION:POWER<sb>:RESult?` on page 607
`CALCulate<n>:MARKer<m>:FUNCTION:POWER[:STATe]` on page 609

C/No

Switches the measurement of the carrier/noise ratio with reference to a 1 Hz bandwidth on or off. If no marker is active, marker 1 is activated.

The measurement is performed on the trace that marker 1 is assigned to. To shift marker 1 and measure another trace, use the "Marker to Trace" softkey in the "Marker" menu (see ["Assigning the Marker to a Trace"](#) on page 439).

Remote command:

`CALCulate<n>:MARKer<m>:FUNCTION:POWER:SElect` on page 609
`CALCulate<n>:MARKer<m>:FUNCTION:POWER<sb>:RESult?` on page 607
`CALCulate<n>:MARKer<m>:FUNCTION:POWER[:STATe]` on page 609

Channel Bandwidth

Defines the measurement channel bandwidth.

The default setting is 14 kHz.

Remote command:

[\[SENSe:\] POWER:ACHannel:BANDwidth|BWIDth\[:CHANnel<ch>\]](#) on page 614

Adjust Settings

Enables the RMS detector and adjusts the span to the selected channel bandwidth according to:

"4 x channel bandwidth + measurement margin"

The adjustment is performed once; if necessary, the setting can be changed later on.

Remote command:

[\[SENSe:\] POWER:ACHannel:PRESet](#) on page 610

5.4.4 How to Determine the Carrier-to-Noise Ratio

1. Press the "C/N, C/NO" softkey to configure the carrier-to-noise ratio measurement.
2. To change the channel bandwidth to be analyzed, press the "Channel Bandwidth" softkey.
3. To optimize the settings for the selected channel configuration, press the "Adjust Settings" softkey.
4. To activate the measurements without reference to the bandwidth, press the "C/N" softkey.
To activate the measurements with reference to the bandwidth, press the "C/NO" softkey .
5. If the carrier signal is located within the analyzed channel bandwidth, switch off the carrier signal so that only the noise is displayed in the channel and perform a second measurement.

The carrier-to-noise ratio is displayed after the measurement has been completed.

5.5 Occupied Bandwidth Measurement (OBW)

An important characteristic of a modulated signal is its occupied bandwidth. In a radio communications system, for instance, the occupied bandwidth must be limited to enable distortion-free transmission in adjacent channels.

- [About the Measurement](#)..... 191
- [OBW Results](#)..... 192
- [OBW Configuration](#)..... 193
- [How to Determine the Occupied Bandwidth](#)..... 195
- [Measurement Example](#)..... 196

5.5.1 About the Measurement

The occupied bandwidth is defined as the bandwidth containing a defined percentage of the total transmitted power. A percentage between 10 % and 99.9 % can be set.

Measurement principle

The bandwidth containing 99% of the signal power is to be determined, for example. The algorithm first calculates the total power of all displayed points of the trace. In the next step, the points from the right edge of the trace are summed up until 0.5 % of the total power is reached. Auxiliary marker 1 is positioned at the corresponding frequency. Then the points from the left edge of the trace are summed up until 0.5 % of the power is reached. Auxiliary marker 2 is positioned at this point. 99 % of the power is now between the two markers. The distance between the two frequency markers is the occupied bandwidth which is displayed in the marker field.



OBW within defined search limits - multicarrier OBW measurement in one sweep

The occupied bandwidth of the signal can also be determined within defined search limits instead of for the entire signal. Thus, only a single sweep is required to determine the OBW for a multicarrier signal. To do so, search limits are defined for an individual carrier and the OBW measurement is restricted to the frequency range contained within those limits. Then the search limits are adapted for the next carrier and the OBW is automatically re-calculated for the new range.



For step-by-step instructions see ["How to determine the OBW for a multicarrier signal using search limits"](#) on page 195.

Prerequisites

To ensure correct power measurement, especially for noise signals, and to obtain the correct occupied bandwidth, the following prerequisites and settings are necessary:

Occupied Bandwidth Measurement (OBW)

- Only the signal to be measured is displayed in the window, or search limits are defined to include only one (carrier) signal. An additional signal would falsify the measurement.
- $RBW \ll$ occupied bandwidth (approx. 1/20 of occupied bandwidth, for voice communication type: 300 Hz or 1 kHz)
- $VBW \geq 3 \times RBW$
- RMS detector
- $Span \geq 2$ to 3 x occupied bandwidth

Some of the measurement specifications (e.g. PDC, RCR STD-27B) require measurement of the occupied bandwidth using a peak detector. The detector setting of the R&S FPS has to be changed accordingly then.

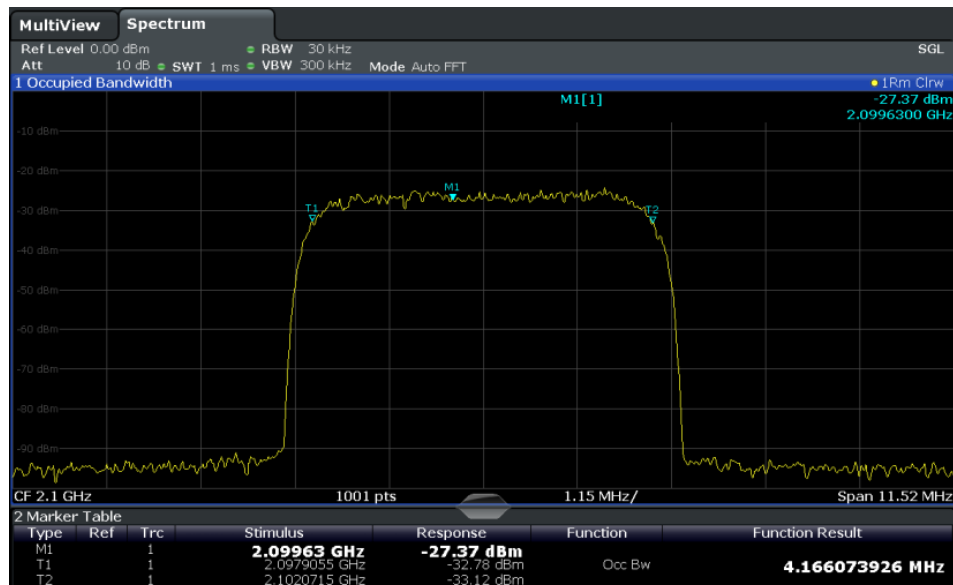
5.5.2 OBW Results

As a result of the OBW measurement the occupied bandwidth ("Occ BW") is indicated in the marker results. Furthermore, the marker at the center frequency and the temporary markers are indicated.

The measurement is performed on the trace with marker 1. In order to evaluate another trace, marker 1 must be placed on another trace (see [Assigning the Marker to a Trace](#)).



The OBW calculation is repeated if the [Search Limits](#) are changed, without performing a new sweep. Thus, the OBW for a multicarrier signal can be determined using only one sweep.



Remote command:

The determined occupied bandwidth can also be queried using the remote command `CALC:MARK:FUNC:POW:RES? OBW` or `CALC:MARK:FUNC:POW:RES? AOBW`. While the `OBW` parameter returns only the occupied bandwidth, the `AOBW` parameter also returns the position and level of the temporary markers T1 and T2 used to calculate the occupied bandwidth.

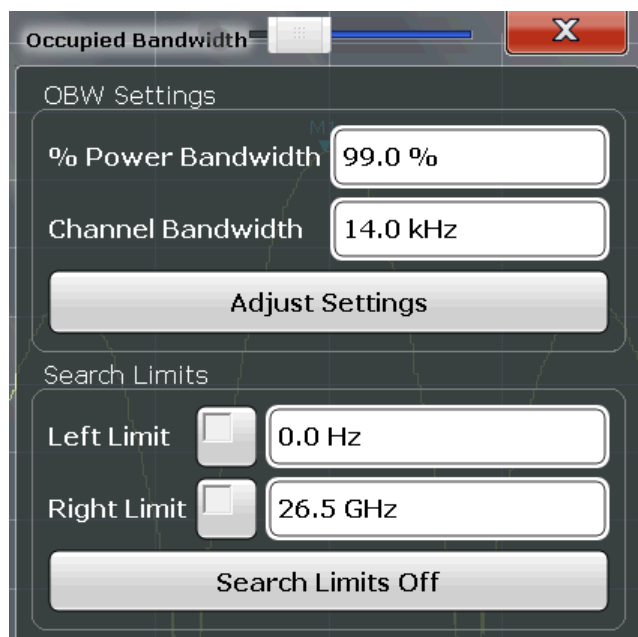
`CALC:MARK:FUNC:POW:SEL OBW`, see [CALCulate<n>:MARKer<m>:FUNction:POWer:SElect](#) on page 609

[CALCulate<n>:MARKer<m>:FUNction:POWer\[:STATe\]](#) on page 609

`CALC:MARK:FUNC:POW:RES? OBW`, see [CALCulate<n>:MARKer<m>:FUNction:POWer<sb>:RESult?](#) on page 607

5.5.3 OBW Configuration

OBW measurements are selected via the "OBW" button in the "Select Measurement" dialog box. The measurement is started immediately with the default settings. It can be configured via the MEAS CONFIG key or in the "Occupied Bandwidth" dialog box, which is displayed as a tab in the "Analysis" dialog box or when you select the "OBW Config" softkey from the "OBW" menu.



This measurement is not available in zero span.

**Configuring search limits for OBW measurement**

The OBW measurement uses the same search limits as defined for marker search (see ["Search Limits"](#) on page 444). However, only the left and right limits are considered.

The remote commands required to perform these tasks are described in [chapter 11.5.5, "Measuring the Occupied Bandwidth"](#), on page 647.

% Power Bandwidth	194
Channel Bandwidth	194
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Search Limits (Left / Right)	194
Deactivating All Search Limits	195

% Power Bandwidth

Defines the percentage of total power in the displayed frequency range which defines the occupied bandwidth. Values from 10% to 99.9% are allowed.

Remote command:

`[SENSe:]POWER:BANDwidth|BWIDth` on page 648

Channel Bandwidth

Defines the channel bandwidth for the transmission channel in single-carrier measurements. This bandwidth is used to optimize the test parameters (for details see ["Adjust Settings"](#) on page 194). The default setting is 14 kHz.

For measurements according to a specific transmission standard, define the bandwidth specified by the standard for the transmission channel.

For multicarrier measurements this setting is irrelevant.

Remote command:

`[SENSe:]POWER:ACHannel:BANDwidth|BWIDth[:CHANnel<ch>]` on page 614

Adjust Settings

Optimizes the instrument settings for the measurement of the occupied bandwidth according to the specified channel bandwidth.

This function is only useful for single carrier measurements.

All instrument settings relevant for power measurement within a specific frequency range are optimized:

- Frequency span: $3 \times$ channel bandwidth
- RBW $\leq 1/40$ of channel bandwidth
- VBW $\geq 3 \times$ RBW
- Detector: RMS

The reference level is not affected by "Adjust Settings". For an optimum dynamic range it should be selected such that the signal maximum is close to the reference level (see ["Setting the Reference Level Automatically \(Auto Level\)"](#) on page 346).

The adjustment is carried out only once. If necessary, the instrument settings can be changed later.

Remote command:

`[SENSe:]POWER:ACHannel:PRESet` on page 610

Search Limits (Left / Right)

If activated, limit lines are defined and displayed for the search. Only results within the limited search range are considered.

For details on limit lines for searches see "[Peak search limits](#)" on page 430.

Remote command:

[CALCulate<n>:MARKer<m>:X:SLIMits\[:STATe\]](#) on page 825

[CALCulate<n>:MARKer<m>:X:SLIMits:LEFT](#) on page 826

[CALCulate<n>:MARKer<m>:X:SLIMits:RIGHT](#) on page 826

Deactivating All Search Limits

Deactivates the search range limits.

Remote command:

[CALCulate<n>:MARKer<m>:X:SLIMits\[:STATe\]](#) on page 825

[CALCulate<n>:THReshold:STATe](#) on page 827

5.5.4 How to Determine the Occupied Bandwidth

How to determine the OBW for a single signal

1. Select the "OBW" measurement function from the "Select Measurement" dialog box.
2. Select the "OBW Config" softkey to display the "Occupied Bandwidth" configuration dialog box.
3. Define the percentage of power ("% Power Bandwidth") that defines the bandwidth to be determined.
4. If necessary, change the channel bandwidth for the transmission channel.
5. To optimize the settings for the selected channel configuration, select "Adjust Settings".
6. Start a sweep.

The result is displayed as OBW in the marker results.

How to determine the OBW for a multicarrier signal using search limits

1. Select the "OBW" measurement function from the "Select Measurement" dialog box.
2. Select the "OBW Config" softkey to display the "Occupied Bandwidth" configuration dialog box.
3. Define the percentage of power ("% Power Bandwidth") that defines the bandwidth to be determined.
4. Define search limits so the search area contains only the first carrier signal:
 - a) Enter values for the left or right limits, or both.
 - b) Enable the use of the required limits.
5. Start a sweep.

The result for the first carrier is displayed as OBW in the marker results.

6. Change the search limits so the search area contains the next carrier signal as described in [step 4](#).
The OBW is re-calculated and the result for the next carrier is displayed. A new sweep is not necessary!
7. Continue in this way until all carriers have been measured.

5.5.5 Measurement Example

In the following example, the bandwidth that occupies 99% of the total power of a PDC signal at 800 MHz, level 0 dBm is measured.

1. Preset the R&S FPS.
2. Set the center frequency to *800 MHz*.
3. Set the reference level to *-10 dBm*.
4. Select the "OBW" measurement function from the "Select Measurement" dialog box.
5. Set the percentage of power to *99%*.
6. Set the channel bandwidth to *21 kHz* as specified by the PDC standard.
7. Optimize the settings for the selected channel configuration by selecting "Adjust Settings".
8. Adjust the reference level to the measured total power by selecting the "Auto Level" softkey in the AUTO SET menu.
9. The PDC standard requires the peak detector for OBW measurement. In the "Traces" configuration dialog, set the trace detector to "Positive Peak".
10. Start a sweep.

The result is displayed as OBW in the marker results.

5.6 Spectrum Emission Mask (SEM) Measurement

The R&S FPS supports Spectrum Emission Mask (SEM) measurements.

- [About the Measurement](#)..... 197
- [Typical Applications](#)..... 197
- [SEM Results](#)..... 197
- [SEM Basics](#)..... 200
- [SEM Configuration](#)..... 210
- [How to Perform a Spectrum Emission Mask Measurement](#)..... 226
- [Measurement Example: Multi-SEM Measurement](#)..... 231
- [Reference: SEM File Descriptions](#)..... 232

5.6.1 About the Measurement

The Spectrum Emission Mask (SEM) measurement defines a measurement that monitors compliance with a spectral mask. The mask is defined with reference to the input signal power. The R&S FPS allows for a flexible definition of all parameters in the SEM measurement. The analyzer performs measurements in predefined frequency ranges with settings that can be specified individually for each of these ranges.

In the basic Spectrum application, spectrum emissions can be measured for multiple sub blocks of channels, where the sub blocks may include gaps or overlap, and define separate masks. Radio signals using multiple standards can also be analyzed.

SEM measurement configurations can be saved to an xml file which can then be exported to another application or loaded on the R&S FPS again at a later time. Some predefined XML files are provided that contain ranges and parameters according to the selected standard.

In order to improve the performance of the R&S FPS for spectrum emission mask measurements, a "Fast SEM" mode is available.

Monitoring compliance of the spectrum is supported by a special limit check for SEM measurements.

5.6.2 Typical Applications

Spectrum Emission Mask measurements are typically performed to ensure that modulated signals remain within the valid signal level ranges defined by a particular transmission standard, both in the transmission channel and neighboring channels. Any violations of the mask may interfere with other transmissions.

The 3GPP TS 34.122 standard, for example, defines a mask for emissions outside the transmission channel. This mask is defined relative to the input signal power. Three frequency ranges to each side of the transmission channel are defined.

5.6.3 SEM Results

As a result of the Spectrum Emission Mask measurement, the measured signal levels, the result of the limit check (mask monitoring) and the defined limit lines are displayed in a diagram (see also [chapter 5.6.4.2, "Limit Lines in SEM Measurements"](#), on page 203). Furthermore, the TX channel power "P" is indicated with the used power class.



Multi-SEM measurements

For multi-SEM measurements, that is, SEM measurements with more than one sub block, each sub block has its own power class definitions. In this case, the power class is not indicated in the graphical result displays.

Example:

For example, in [figure 5-32](#), "31 < P < 39" is indicated as the used power class is defined from 31 to 39.

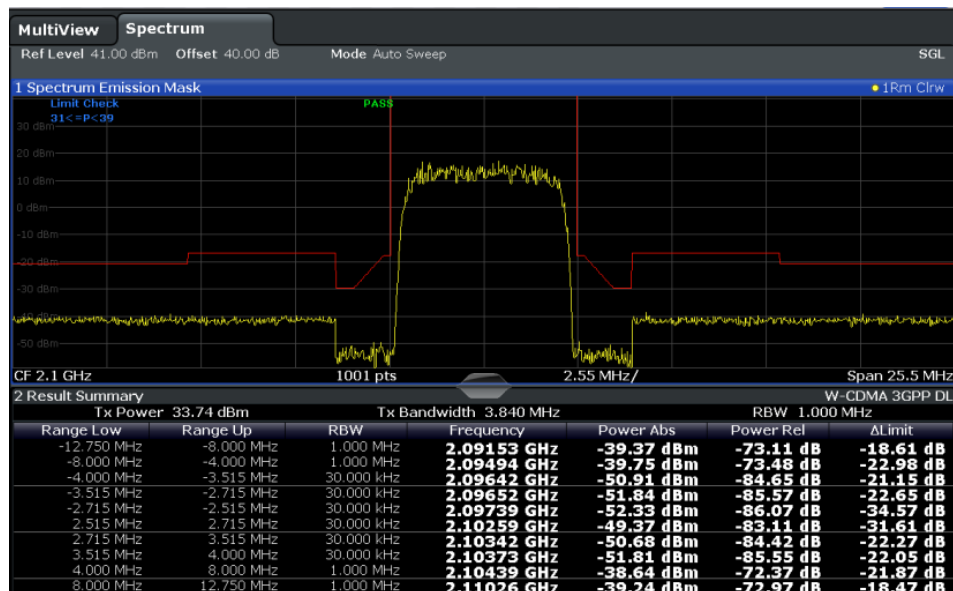


Fig. 5-32: Spectrum Emission Mask result displays

In addition to the graphical results of the SEM measurement displayed in the diagram, a result summary is displayed to evaluate the limit check results (see also [chapter 5.6.4.2, "Limit Lines in SEM Measurements"](#), on page 203).

The following information is provided in the result summary:

Label	Description
General Information	
Standard	Loaded standard settings
Tx Power	Power of the reference range
Tx Bandwidth	Tx bandwidth used by the reference range
RBW	RBW used by the reference range
Range results	
Range Low	Frequency range start the peak value was found in
Range Up	Frequency range end the peak value was found in
RBW	RBW of the range
Frequency	Frequency of the peak power level
Power Abs	Absolute peak power level within the range
Power Rel	Peak power level within the range, relative to the "Tx Power"
ΔLimit	Deviation of the peak power level from the limit line

You can define in which detail the data is displayed in the result summary in the "List Evaluation" settings (see [chapter 5.6.5.7, "List Evaluation \(Results Configuration\)"](#), on page 225). By default, one peak per range is displayed. However, you can change the settings to display only peaks that exceed a threshold ("Margin").

In addition to listing the peaks in the Result Summary, detected peaks can be indicated by blue squares in the diagram (see [Show Peaks](#) in the "List Evaluation" settings).

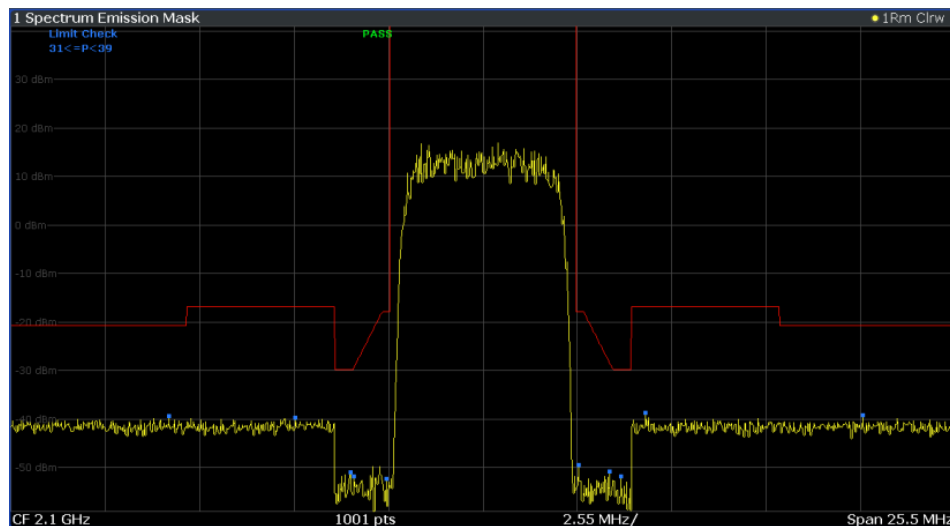


Fig. 5-33: Detected peak display in SEM measurement

Furthermore, you can export the results of the result summary to a file which can be exported to another application for further analysis.

Results for SEM with multiple sub blocks

In the Spectrum application only, spectrum emissions can be measured for multiple sub blocks of channels (see [chapter 5.6.4.5, "SEM with Multiple Sub Blocks \("Multi-SEM\)"](#), on page 206 for details). Up to three sub blocks (with two gaps) can be defined. For each sub block and each gap, the results described above are provided individually in the result summary.

Spectrum Emission Mask (SEM) Measurement

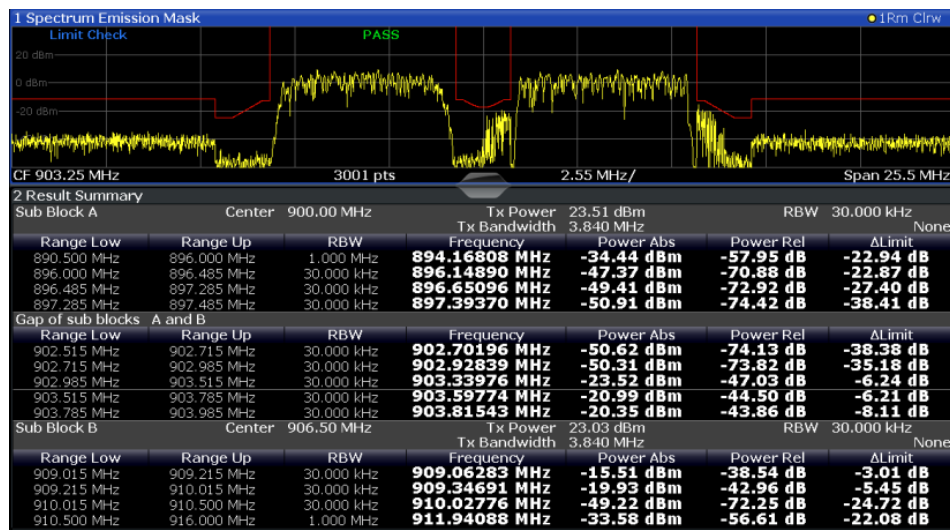


Fig. 5-34: SEM results for multiple sub blocks

Retrieving Results via Remote Control

The measurement results of the spectrum emission mask *test* can be retrieved using the `CALC:LIM:FAIL?` command from a remote computer; see `CALCulate<n>:LIMit<k>:FAIL?` on page 877 for a detailed description.

The *power* result for the reference range can be queried using `CALC:MARK:FUNC:POW:RES? CPOW;`

The *peak* power for the reference range can be queried using `CALC:MARK:FUNC:POW:RES? PPOW,` see `CALCulate<n>:MARKer<m>:FUNCTION:POWer<sb>:RESult?` on page 607.

The measured *power trace* can be queried using `TRAC:DATA?` and `TRAC:DATA:X?`, see `TRACe<n>[:DATA]` on page 813 and `TRACe<n>[:DATA]:X?` on page 815:

The measured *peak power list* can be queried using `TRAC:DATA? LIST,` see `TRACe<n>[:DATA]` on page 813.

5.6.4 SEM Basics

Some background knowledge on basic terms and principles used in SEM measurements is provided here for a better understanding of the required configuration settings.

- [Ranges and Range Settings](#).....201
- [Limit Lines in SEM Measurements](#).....203
- [Fast SEM Measurements](#).....205
- [Multi-Standard Radio \(MSR\) SEM Measurements](#).....206
- [SEM with Multiple Sub Blocks \("Multi-SEM"\)](#).....206

5.6.4.1 Ranges and Range Settings

In the Spectrum Emission Mask measurements, a range defines a segment for which you can define the following parameters separately:

- Start and stop frequency
- RBW
- VBW
- Sweep time
- Sweep points
- Reference level
- Attenuator settings
- Transducer settings
- Limit values

Via the sweep list, you define the ranges and their settings. For details on settings refer to [chapter 5.6.5.1, "Sweep List"](#), on page 210.

For details on defining the limits (masks) see [chapter 5.6.4.2, "Limit Lines in SEM Measurements"](#), on page 203.

For details on defining the limits (masks) see the base unit description "Working with Lines in SEM".

Range definition

After a preset, the sweep list contains a set of default ranges and parameters. For each range, you can change the parameters listed above. You can insert or delete ranges.

The changes of the sweep list are only kept until you load another parameter set (by pressing PRESET or by loading an XML file). If you want a parameter set to be available permanently, create an XML file for this configuration (for details refer to ["How to save a user-defined SEM settings file"](#) on page 230).

If you load one of the provided XML files, the sweep list contains ranges and parameters according to the selected standard.

Reference range

The range centered around the center frequency is defined as the reference range for all other ranges in the sweep list. All range limits are defined in relation to the reference range. The TX power used as a reference for all power level results in the result summary is also calculated for this reference range. You can define whether the power used for reference is the peak power level or the integrated power of the reference range. In the "Sweep List", the reference range is highlighted in blue and cannot be deleted.

Rules

The following rules apply to ranges:

- The minimum span of a range is 20 Hz.

- The individual ranges must not overlap (but may have gaps).
- The maximum number of ranges is 30 (in firmware versions < 1.60: 20 ranges).
- The minimum number of ranges is 3.
- The reference range cannot be deleted.
- The reference range has to be centered on the center frequency.
- The minimum span of the reference range is given by the current "TX Bandwidth" (see "[Channel Power Settings](#)" on page 218).
- Frequency values for each range have to be defined relative to the center frequency.

In order to change the start frequency of the first range or the stop frequency of the last range, select the appropriate span with the SPAN key. If you set a span that is smaller than the overall span of the ranges, the measurement includes only the ranges that lie within the defined span and have a minimum span of 20 Hz. The first and last ranges are adapted to the given span as long as the minimum span of 20 Hz is not violated.

Sweep points

You can define a minimum number of sweep points for each range. The total number of available sweep points is then distributed among the ranges in consideration of the minimum values. If the total number of sweep points is not enough to satisfy the minimum sweep point requirements in all ranges, the R&S FPS adjusts the global number of [Sweep Points](#) accordingly. By default, each range has a minimum of one sweep point.

This allows you to increase the resolution within a specific range for detailed analysis, without increasing the overall number of sweep points and thus the measurement time for the SEM measurement.

Symmetrical ranges

You can easily define a sweep list with symmetrical range settings, i.e. the ranges to the left and right of the reference range are defined symmetrically. When symmetrical setup is activated, the current sweep list configuration is changed to define a symmetrical setup regarding the reference range. The number of ranges to the left of the reference range is reflected to the right, i.e. any missing ranges on the right are inserted, while superfluous ranges are removed. The values in the ranges to the right of the reference range are adapted symmetrically to those in the left ranges.

Symmetrical ranges fulfill the conditions required for "Fast SEM" mode (see [chapter 5.6.4.3, "Fast SEM Measurements"](#), on page 205).

Power classes

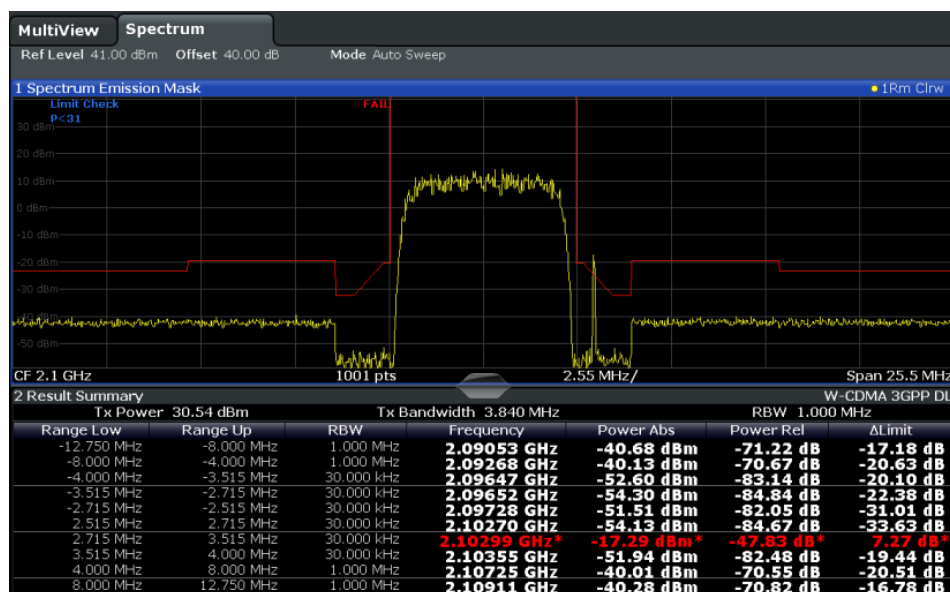
If the signal power level to be monitored may vary and the limits will vary accordingly, you can define power classes, which can then be assigned to the frequency ranges. Thus, the limits for the signal levels can be defined differently for varying input levels. For instance, for higher input levels a transmission standard may allow for higher power levels in adjacent channels, whereas for lower input levels the allowed deviation may be stricter. Up to four different power classes can be defined.

5.6.4.2 Limit Lines in SEM Measurements

On the R&S FPS, the spectrum emission mask is defined using limit lines. Limit lines allow you to check the measured data (that is, the trace results) against specified limit values. Generally, it is possible to define limit lines for any measurement in the Spectrum application using the LINES key. For SEM measurements, however, special limit lines are available via the "Sweep List", and it is strongly recommended that you use only these limit line definitions.

In the "Sweep List" you can define a limit line for each power class that varies its level according to the specified frequency ranges. Special limit lines are automatically defined for each power class according to the current "Sweep List" settings every time the settings change. These limit lines are labeled "_SEM_LINE_<xxx>_ABS<0...3>" and "_SEM_LINE_<xxx>_REL<0...3>", where <xxx> is an index to distinguish limit lines between different measurement channels.

The limit line defined for the currently used power class is indicated by a red line in the display, and the result of the limit check is indicated at the top of the diagram. Note that only "Pass" or "Fail" is indicated; a "margin" function as for general limit lines is not available.



The indicated limit line depends on the settings in the "Sweep List". Several types of limit checks are possible:

Table 5-11: Limit check types

Limit check type	Pass/fail criteria	Limit line definition
Absolute	Absolute power levels may not exceed limit line	Defined by the "Abs Limit Start"/ "Abs Limit Stop" values for each range
Relative	Power deviations relative to the TX channel power may not exceed limit line	Defined by the "Rel Limit Start"/ "Rel Limit Stop" values (relative to the TX channel power), fixed for each range.

Spectrum Emission Mask (SEM) Measurement

Limit check type	Pass/fail criteria	Limit line definition
Relative with function f(x)	If the power exceeds both the absolute and the relative limits, the check fails (see Relative limit line functions below)	Defined by the maximum of the absolute or relative start and stop limit values for each range. Thus, the start or stop point of the limit range, or both, are variable (since the maximum may vary).
Abs and Rel	If the power exceeds both the absolute and the relative limits, the check fails.	The less strict (higher) limit line is displayed for each range. If you use a function to define the relative limit start or stop value, the signal is checked against an additional condition: the power must exceed the absolute limit, as well as the absolute and relative function values.
Abs or Rel	If the power exceeds either the absolute or the relative limits, the check fails.	The stricter (lower) limit line is displayed for each range. If you use a function to define the relative limit start or stop value, the signal is checked against an additional condition: if the power exceeds the absolute limit, or the higher of the absolute and relative function values, the check fails.

Relative limit line functions

A new function allows you to define limit lines whose start or end points (or both) are variable, depending on the carrier power. Thus, the resulting limit line may change its slope within the range, depending on the carrier power. Common relative limit lines are calculated once for the defined start and end points and maintain a constant slope.

If the relative limit value function is used in combination with the "Abs and Rel" or "Abs or Rel" limit check types, an additional condition is considered for the limit check (see [table 5-11](#)).

Limit check results in the result summary

For each range, the peak measured value and the deviation of these values from the limit line are displayed in the result summary. If the limit check is passed for the range, the deviation represents the closest value to the limit line. If the limit check is passed for the range, the deviation represents the closest value to the limit line. If the limit check for the range fails, the deviation represents the maximum violation against the limit line. Furthermore, the absolute power levels and the relative deviation of the peaks from the TX channel power are displayed. Values that exceed the limit are indicated in red and by an asterisk (*).

A2 Spectrum Emission Mask				W-CDMA 3GPP (31,39)dBm DL		
Tx Power -28.10 dBm		Tx Bandwidth 3.840 MHz		RBW 1,000 MHz		
Range Low	Range Up	RBW	Frequency	Power Abs	Power Rel	ΔLimit
-12.750 MHz	-8.000 MHz	1.000 MHz	13.24173 GHz*	-47.08 dBm*	-18.98 dB*	38.52 dB*
-8.000 MHz	-4.000 MHz	1.000 MHz	13.24364 GHz*	-25.01 dBm*	3.09 dB*	53.59 dB*
-4.000 MHz	-3.515 MHz	30.000 kHz	13.24619 GHz	-100.18 dBm	-72.08 dB	-8.58 dB
-3.515 MHz	-2.715 MHz	30.000 kHz	13.24668 GHz	-105.92 dBm	-77.83 dB	-17.23 dB



Although a margin functionality is not available for the limit check, a margin (threshold) for the peak values to be displayed in the Result Summary can be defined in the "List Evaluation" settings. For details see [chapter 5.6.5.7, "List Evaluation \(Results Configuration\)"](#), on page 225.

5.6.4.3 Fast SEM Measurements

In order to improve the performance of the R&S FPS for spectrum emission mask measurements, a "Fast SEM" mode is available. If this mode is activated, several consecutive ranges with identical sweep settings are combined to one sweep internally, which makes the measurement considerably faster. The displayed results remain unchanged and still consist of several ranges. Thus, measurement settings that apply only to the results, such as limits or transducer factors, can nevertheless be defined individually for each range.

Prerequisites

"Fast SEM" mode is available if the following criteria apply:

- The frequency ranges are consecutive, without frequency gaps
- The following sweep settings are identical (for details see [chapter 5.6.5.1, "Sweep List"](#), on page 210):
 - Filter Type
 - RBW
 - VBW
 - Sweep Time Mode
 - Reference Level
 - Rf Attenuation Mode
 - RF Attenuation

Activating Fast SEM mode

"Fast SEM" mode is activated in the sweep list (see [chapter 5.6.5.1, "Sweep List"](#), on page 210) or using a remote command. Activating the mode for one range automatically activates it for all ranges in the sweep list.

Remote command:

`[SENSe:]ESpectrum<sb>:HighSPeed` on page 654

Consequences

When the "Fast SEM" mode is activated, the ranges for which these criteria apply are displayed as one single range. The sweep time is defined as the sum of the individual sweep times, initially, but can be changed.



If "Symmetrical Setup" mode is active when "Fast SEM" mode is activated, not all sweep list settings can be configured symmetrically automatically (see also ["Symmetric Setup"](#) on page 216).

Any other changes to the sweep settings of the combined range are applied to each included range and remain changed even after deactivating "Fast SEM" mode.

Example

Sweep List	Range 1	Range 2	Range 3	Range 4	Range 5
Range Start	-13.25 GHz	-12.75 MHz	-2.515 MHz	2.515 MHz	12.75 MHz
Range Stop	-12.75 MHz	-2.515 MHz	2.515 MHz	12.75 MHz	13.25 GHz
Fast SEM	On	On	On	On	On
Filter Type	Normal(3...	---	Channel	---	---
Res BW	3 MHz	---	30 kHz	---	---
Video BW	3 MHz	---	3 MHz	---	---
Sweep Time Mode	---	---	---	---	---
Sweep Time	27.5 ms	---	37.5 ms	---	---
Ref. Level	0 dBm	---	0 dBm	---	---
RF Att. Mode	Auto	---	Auto	---	---
RF Attenuator	10 dB	---	10 dB	---	---
Transducer	None	None	None	None	None
Limit Check 1	Relative	Relative	Relative	Relative	Relative
Abs Limit Start 1	-13 dBm	-13 dBm	-13 dBm	-13 dBm	-13 dBm
Abs Limit Stop 1	-13 dBm	-13 dBm	-13 dBm	-13 dBm	-13 dBm
Rel Limit Start 1	-50 dBc	-50 dBc	300 dBc	-50 dBc	-50 dBc
Rel Limit Stop 1	-50 dBc	-50 dBc	300 dBc	-50 dBc	-50 dBc

Fig. 5-35: Sweep list using Fast SEM mode

In figure 5-35, a sweep list is shown for which Fast SEM is activated. The formerly 5 separately defined ranges are combined to 2 sweep ranges internally.

5.6.4.4 Multi-Standard Radio (MSR) SEM Measurements

Multi-standard radio (MSR) measurements allow you to perform SEM tests on signals with multiple carriers using different digital standards. MSR measurements are described in the specification 3GPP TS 37.141. Various typical combinations of standards for base station tests are described, e.g. LTE FDD and W-CDMA carriers. By performing an MSR SEM measurement you can determine if or how the different carriers affect each other, i.e. if unwanted emissions occur. On the R&S FPS, the MSR SEM measurement is a standard measurement as for single carriers. The MSR settings merely provide a convenient way of configuring the sweep list for all required ranges according to the specification very quickly.

Refined settings allow the R&S FPS to calculate the SEM limits according to standard 3GPP 37.141 V12.2.0, which distinguishes between base station configurations and power values.

5.6.4.5 SEM with Multiple Sub Blocks ("Multi-SEM")

In the Spectrum application only, spectrum emissions can be measured for multiple sub blocks of channels (also referred to as a "Multi-SEM" measurement). Sub blocks

are a set of multiple ranges around a defined center frequency (carrier). Multiple sub blocks may include gaps or overlap, and each sub block defines a separate mask. The behavior in the overlapping masks is defined by multi-limit line calculation. Up to three sub blocks (with two gaps) can be defined. For each sub block, the familiar configuration settings concerning ranges, limit lines and MSR can be defined individually.

Comparison to "traditional" SEM measurement

The default SEM measurement as performed and configured in previous firmware versions is simply a special case of "*Multi-SEM*" - consisting of one single block. Only when you define a number of sub blocks larger than 1 in the basic SEM configuration, multiple sub blocks are inserted in the configuration settings and result tables.

Particular features of configuring multiple sub blocks

The sub blocks are independent of the global start, stop, center and span frequencies for the complete SEM measurement. Thus, there can be gaps that may even include other carrier ranges, but are not configured for the SEM measurement.

For each sub block, you define:

- the center frequency of the reference range of the sub block; center frequencies must be defined in ascending order for sub blocks A,B,C
- the reference range; note that although individual ranges of different sub blocks may overlap, reference ranges for different sub blocks may *not*; they must define distinct frequency ranges
- the sweep list, including the limit lines
- optionally: a standard file *or* MSR settings to be used for measurement (if one is selected, the other is disabled)



Fast SEM not supported for multiple sub blocks

For SEM with multiple sub blocks, fast SEM is not available. If more than 1 sub block is defined and a standard is loaded which contains an active fast SEM setting, this setting is disabled.

Absolute vs relative frequencies

In the default configuration with only 1 sub block, frequencies are defined relative to the center frequency; this is the familiar configuration.

For setups with more than 1 sub block, frequencies are defined relative to the center frequency of the reference ranges for the individual sub blocks. However, in the result summary, frequencies are indicated as absolute values. Relative frequencies that refer to different reference ranges would be inconvenient and difficult to analyze.

Limit check behavior for overlapping masks

Since spectrum emission masks are defined individually for each sub block, and sub blocks may overlap, the question arises what happens during the limit check in the overlapping regions? To answer this question we must distinguish the following cases:

- For the reference range, no limit checking is performed, as the reference range contains the carrier
- For other ranges, only the limit lines defined for ranges between the carriers, that is the reference ranges, to either side are significant. In other words, if a limit line definition covers the frequency area of several carriers, only the limit lines for ranges between the corresponding reference range and the next closest reference range are significant.

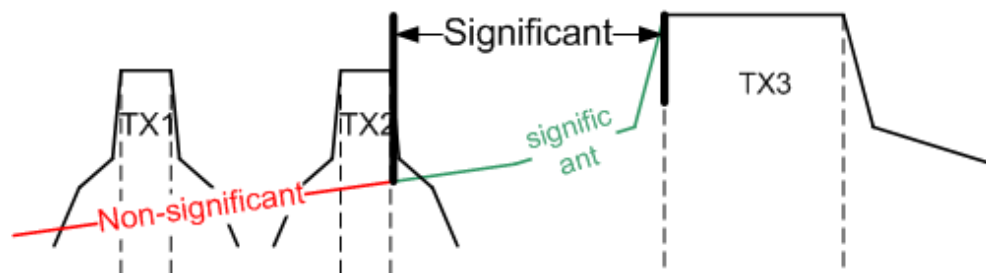


Fig. 5-36: Behavior for overlapping masks

- For these ranges, in which multiple limit lines are significant, a range-specific function determines the behavior of the limit check

Limit calculation for individual ranges

For each range a function can be defined that determines the behavior of the limit check in case of multiple limit lines:

- **"NONE"**: In reference ranges no limit check is performed; Reference ranges always use the function "NONE". For other ranges, see the combinations for overlapping ranges below.
- **"SUM"**: sum of the two limit lines (calculated for linear powers) is used
- **"MAX"**: maximum of the two limit lines is used

This leads to the following **combinations for overlapping ranges**:

- **"MAX+MAX"**: maximum of the two limit lines is used
- **"MAX+SUM"**: maximum of the two limit lines is used
- **"SUM+SUM"**: sum of the two limit lines (calculated for linear powers) is used
- **"NONE+MAX"/"NONE+SUM"**: limit line (and parameters) of the "NONE" range are ignored
- **"NONE+NONE"**: depends on the position of the overlapping ranges in relation to the mid-frequency between the two neighboring sub blocks:
 - overlap is completely *below* the mid-frequency: limits and parameters of the left sub block are used
 - overlap is completely *above* the mid-frequency: limits and parameters of the right sub block are used
 - overlap crosses the mid-frequency: new subranges are created: one to the left of the mid-frequency, one to the right of the mid-frequency. The left subrange uses the limits and parameters of the left sub block, the right subrange uses the limits and parameters of the right sub block.



Different RBWs in overlapping ranges

If different RBWs are defined for the overlapping ranges, the RBW, as well as the VBW, attenuation, reference level, transducer, filter type and (proportional) sweep time of the range with the smaller RBW are considered for both ranges. In the range with the higher RBW, the following offset is applied to the limit line:

$$-10 \cdot \log(RBW_{large} / RBW_{small})$$

Table 5-12: Limit lines in overlapping ranges crossing the mid-frequency

<p>The diagram shows a frequency spectrum with two sub-blocks, Sub block 1 and Sub block 2, separated by a mid-frequency region SB1-SB2. Two transmitters, TX1 and TX2, are shown. Range 3 (blue hatched) is in Sub block 1, Range 6 (orange hatched) is in Sub block 2, and they overlap in the mid-frequency region. Range 4 (light blue hatched) and Range 5 (yellow hatched) are also shown overlapping in the mid-frequency region but are labeled as "None".</p>	<p>The diagram shows the same setup as the initial situation, but the overlapping ranges in the mid-frequency region are now defined as Subrange 4a (light blue hatched) and Subrange 5a (yellow hatched). Subrange 4a is on the left side of the mid-frequency, and Subrange 5a is on the right side. Range 3 applies to Subrange 4a, and Range 6 applies to Subrange 5a.</p>
<p>Initial situation: overlapping ranges Range 4 ("None") + Range 5 ("None") overlap and cross the mid-frequency between sub blocks 1 and 2</p>	<p>Result: Subranges 4a and 5a are created left and right of the mid-frequency; For subrange 4a: limit line and parameters of range 4 apply For subrange 5a: limit line and parameters of range 5 apply</p>

Global SEM limit check

For the complete SEM measurement, which may consist of multiple sub blocks, only one single limit check is performed. A single limit line is calculated according to the individual range limit lines and the defined functions for overlapping ranges. The measured values are then compared with this single limit line. If the limit is exceeded in any range, the result of the limit check is "failed".

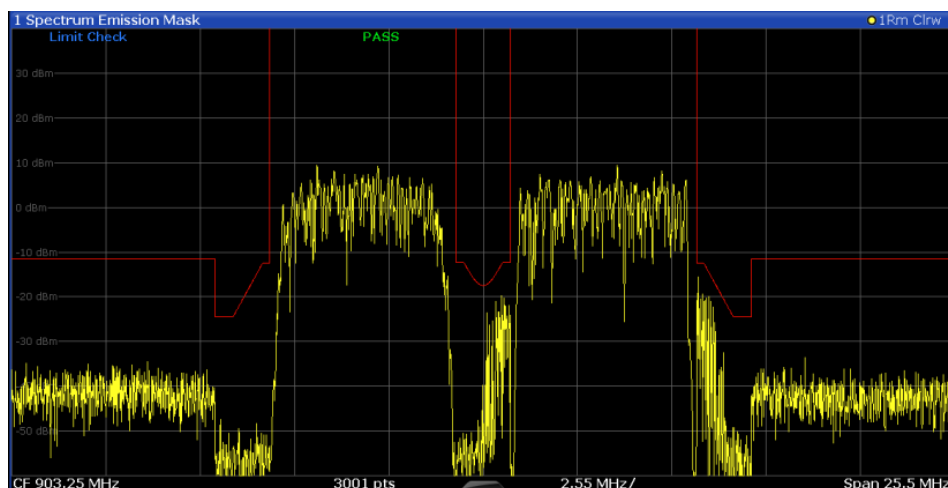


Fig. 5-37: Summarized limit line for multiple sub blocks

5.6.5 SEM Configuration

SEM measurements are selected via the "Spectrum Emission Mask" button in the "Select Measurement" dialog box. The measurement is started immediately with the default settings. It can be configured via the MEAS CONFIG key or in the "Spectrum Emission Mask" configuration dialog box, which is displayed when you select the "SEM Setup" button in the "Overview" or one of the softkeys from the "SEMask" menu.

The remote commands required to perform these tasks are described in [chapter 11.5.6, "Measuring the Spectrum Emission Mask"](#), on page 649.



Global span settings

The span of the signal to be monitored is configured in the general span settings (see [chapter 6.3.2, "Frequency and Span Settings"](#), on page 336). Only ranges within this global span are considered for the SEM measurement.

The following settings are available in individual tabs of the "Spectrum Emission Mask" configuration dialog box.

- [Sweep List](#).....210
- [Multi-SEM \(Sub Block\) Settings](#)216
- [Reference Range](#).....217
- [Power Classes](#).....219
- [MSR Settings](#).....220
- [Standard Files](#).....223
- [List Evaluation \(Results Configuration\)](#).....225

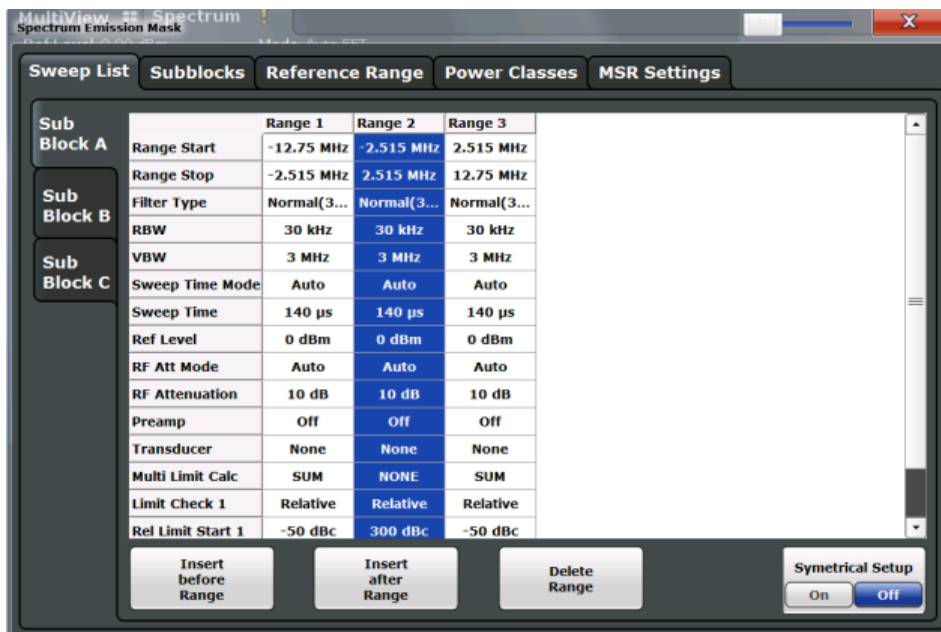
5.6.5.1 Sweep List

For SEM measurements, the input signal is split into several frequency ranges which are swept individually and for which different limitations apply. In the "Sweep List" tab

of the "Spectrum Emission Mask" dialog box you configure the individual frequency ranges and mask limits.



If you edit the sweep list, always follow the rules and consider the limitations described in [chapter 5.6.4.1, "Ranges and Range Settings"](#), on page 201.



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Rel Limit Start/Stop <n>..... 214

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Range Start / Range Stop

Sets the start frequency/stop frequency of the selected range.

In order to change the start/stop frequency of the first or last range, respectively, select the appropriate span with the SPAN key. If you set a span that is smaller than the overall span of the ranges, the measurement includes only the ranges that lie within the defined span and have a minimum span of 20 Hz. The first and last ranges are adapted to the given span as long as the minimum span of 20 Hz is not violated.

Frequency values for each range have to be defined relative to the center frequency. The reference range has to be centered on the center frequency. The minimum span of the reference range is given by the current "TX Bandwidth" (see "[Channel Power Settings](#)" on page 218).

Remote command:

[SENSe:]ESpectrum<sb>:RANGe<range>[:FREQuency]:START on page 656

[SENSe:]ESpectrum<sb>:RANGe<range>[:FREQuency]:STOP on page 657

Fast SEM

Activates "Fast SEM" mode for all ranges in the sweep list. For details see [chapter 5.6.4.3, "Fast SEM Measurements"](#), on page 205.

Note: If you deactivate "Fast SEM" mode while "Symmetrical Setup" mode is on, "Symmetrical Setup" mode is automatically also deactivated.

If you activate "Fast SEM" mode while "Symmetrical Setup" mode is on, not all range settings can be configured symmetrically automatically.

Remote command:

[SENSe:]ESpectrum<sb>:HighSPeed on page 654

Filter Type

Sets the filter type for this range.

For details on filter types see [chapter 6.5.1.6, "Which Data May Pass: Filter Types"](#), on page 355.

Remote command:

[SENSe:]ESpectrum<sb>:RANGe<range>:FILTer:TYPE on page 655

RBW

Sets the resolution bandwidth for this range.

For details on the RBW see [chapter 6.5.1.1, "Separating Signals by Selecting an Appropriate Resolution Bandwidth"](#), on page 352.

Remote command:

[SENSe:]ESpectrum<sb>:RANGe<range>:BANDwidth[:RESolution]
on page 654

VBW

Sets the video bandwidth for this range.

For details on the VBW see [chapter 6.5.1.2, "Smoothing the Trace Using the Video Bandwidth"](#), on page 353.

Remote command:

[SENSe:]ESpectrum<sb>:RANGe<range>:BANDwidth:VIDeo on page 654

Sweep Time Mode

Activates or deactivates the auto mode for the sweep time.

For details on the sweep time mode see [chapter 6.5.1.7, "How Long the Data is Measured: Sweep Time"](#), on page 356

Remote command:

`[SENSe:]ESpectrum<sb>:RANGe<range>:SWEep:TIME:AUTO` on page 666

Sweep Time

Sets the sweep time value for the range.

For details on the sweep time see [chapter 6.5.1.7, "How Long the Data is Measured: Sweep Time"](#), on page 356

Remote command:

`[SENSe:]ESpectrum<sb>:RANGe<range>:SWEep:TIME` on page 666

Ref. Level

Sets the reference level for the range.

For details on the reference level see [chapter 6.4.1.1, "Reference Level"](#), on page 342.

Remote command:

`[SENSe:]ESpectrum<sb>:RANGe<range>:RLEVel` on page 665

RF Att. Mode

Activates or deactivates the auto mode for RF attenuation.

For details on attenuation see [chapter 6.4.1.2, "RF Attenuation"](#), on page 344.

Remote command:

`[SENSe:]ESpectrum<sb>:RANGe<range>:INPut:ATTenuation:AUTO` on page 658

RF Attenuator

Sets the attenuation value for the range.

For details on attenuation see [chapter 6.4.1.3, "Scaling"](#), on page 344.

Remote command:

`[SENSe:]ESpectrum<sb>:RANGe<range>:INPut:ATTenuation` on page 657

Transd. Factor

Sets a transducer for the specified range. You can only choose a transducer that fulfills the following conditions:

- The transducer overlaps or equals the span of the range.
- The x-axis is linear.
- The unit is dB.

For details on transducers see [chapter 9.2, "Basics on Transducer Factors"](#), on page 506.

Remote command:

`[SENSe:]ESpectrum<sb>:RANGe<range>:TRANsducer` on page 667

Limit Check <n>

Sets the type of limit check for the n-th power class in the range. Up to four limits are possible.

For details on limit checks see [chapter 5.6.4.2, "Limit Lines in SEM Measurements"](#), on page 203.

The limit state affects the availability of all limit settings.

Remote command:

[SENSe:]ESpectrum<sb>:RANGe<range>:LIMit<PClass>:STATe on page 664
CALCulate<n>:LIMit<k>:FAIL? on page 877

Abs Limit Start/Stop <n>

Sets an absolute limit value for the n-th power class at the start or stop frequency of the range [dBm].

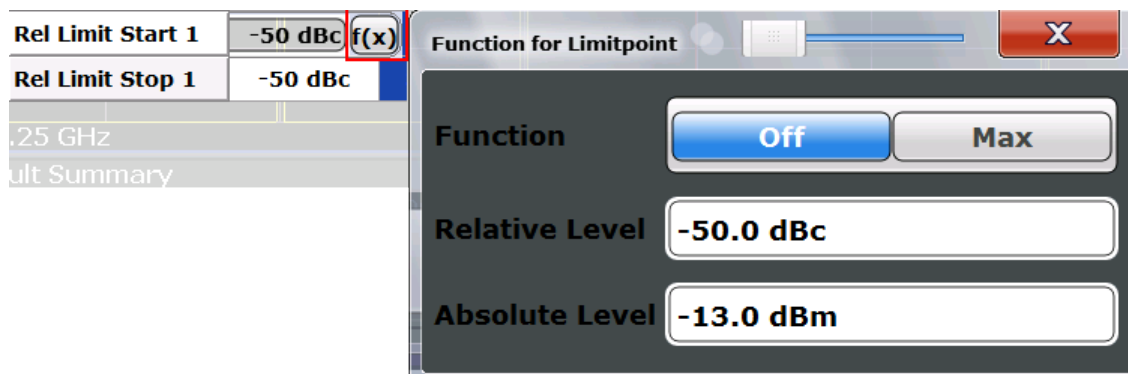
Remote command:

[SENSe:]ESpectrum<sb>:RANGe<range>:LIMit<PClass>:ABSolute:START on page 659
[SENSe:]ESpectrum<sb>:RANGe<range>:LIMit<PClass>:ABSolute:STOP on page 659

Rel Limit Start/Stop <n>

Sets a relative limit value for the n-th power class at the start or stop frequency of the range [dBc].

By default, this value is a fixed relative limit, i.e. no function is defined. To define a function for the relative limit, select the input field for "Rel Limit Start" or "Rel Limit Stop" and then the "f(x)" icon that appears.



If the function is set to "MAX", you can define a relative *and* an absolute limit level. In this case, the maximum of the two values is used as the limit level.

For more information see ["Relative limit line functions"](#) on page 204.

Remote command:

[SENSe:]ESpectrum<sb>:RANGe<range>:LIMit<PClass>:RELative:START
on page 660

[SENSe:]ESpectrum<sb>:RANGe<range>:LIMit<PClass>:RELative:STOP
on page 662

[SENSe:]ESpectrum<sb>:RANGe<range>:LIMit<PClass>:RELative:START:
FUNction on page 661

[SENSe:]ESpectrum<sb>:RANGe<range>:LIMit<PClass>:RELative:STOP:
FUNction on page 663

[SENSe:]ESpectrum<sb>:RANGe<range>:LIMit<PClass>:RELative:START:
ABS on page 660

[SENSe:]ESpectrum<sb>:RANGe<range>:LIMit<PClass>:RELative:STOP:
ABSolute on page 663

Multi-Limit Calc <n>

Defines the function used to calculate the limit line for the n-th power class for overlapping ranges in Multi-SEM measurements. For details see ["Limit calculation for individual ranges"](#) on page 208.

"NONE" (reference ranges only:) the limit of the reference range is used

"SUM" sum of the two limit lines (calculated for linear powers) is used

"MAX" maximum of the two limit lines is used

Remote command:

[SENSe:]ESpectrum<sb>:RANGe<range>:MLCalc on page 665

Minimum Sweep Points

Defines the minimum number of sweep points for the range.

If necessary to fulfill all minimum sweep point requirements in all ranges, the global [Sweep Points](#) setting is increased. By default, each range is supplied with a minimum of one sweep point.

For details see ["Sweep points"](#) on page 202

Remote command:

[SENSe:]ESpectrum<sb>:RANGe<range>:POINTs:MIN[:VALue] on page 665

Insert before/after Range

Inserts a new range to the left (before) or to the right (after) of the range in which the cursor is currently displayed. The range numbers of the currently focused range and all higher ranges are increased accordingly. The maximum number of ranges is 30.

Remote command:

[SENSe:]ESpectrum<sb>:RANGe<range>:INSert on page 658

Delete Range

Deletes the currently focused range, if possible (The reference range cannot be deleted. A minimum of 3 ranges is required.) The range numbers are updated accordingly.

Remote command:

[SENSe:]ESpectrum<sb>:RANGe<range>:DELete on page 655

Symmetric Setup

Any changes to the range settings in active "Symmetric Setup" mode lead to symmetrical changes in the other ranges (where possible). In particular, this means:

- Inserting ranges: a symmetrical range is inserted on the other side of the reference range
- Deleting ranges: the symmetrical range on the other side of the reference range is also deleted
- Editing range settings: the settings in the symmetrical range are adapted accordingly

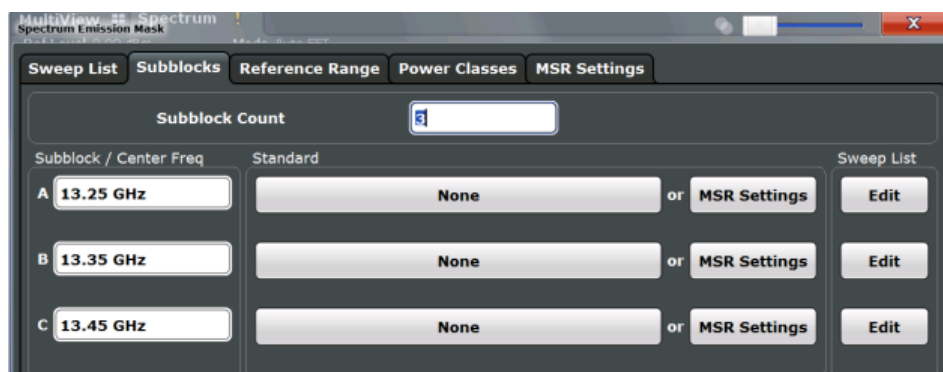
Note: If "Fast SEM" mode is deactivated while "Symmetric Setup" mode is on, "Sym Setup" mode is automatically also deactivated.

If "Fast SEM" mode is activated while "Symmetric Setup" mode is on, not all range settings can be set automatically.

5.6.5.2 Multi-SEM (Sub Block) Settings

In the Spectrum application only, spectrum emissions can be measured for multiple sub blocks of channels (see chapter 5.6.4.5, "SEM with Multiple Sub Blocks ("Multi-SEM)", on page 206). Sub blocks are a set of multiple ranges around a defined center frequency (carrier). Global settings on the sub blocks are configured in the "Sub Blocks" tab of the "Spectrum Emission Mask" configuration dialog box.

By default, a single sub block is assumed, which corresponds to the familiar SEM measurement from previous firmware versions. If more than 1 sub blocks are defined, additional tabs are inserted for each sub block in the individual tabs of the "Spectrum Emission Mask" configuration dialog box.



Sub Block Count..... 217
 Sub Block Center Frequency..... 217
 Standard / MSR Settings.....217
 Edit sweep list..... 217

Sub Block Count

Defines the number of sub blocks. By default, the familiar SEM measurement with just one single block of ranges is configured.

Remote command:

[SENSe:]ESpectrum<sb>:SBCount on page 653

Sub Block Center Frequency

Defines the center frequency for an individual sub block. The center frequency determines the reference range used for each block.

For measurements with only 1 sub block, this setting corresponds to the global setting in the "Frequency" settings (see [Center frequency](#)).

Remote command:

[SENSe:]ESpectrum<sb>:SBCenter on page 652

Standard / MSR Settings

Defines the use of a standard settings file or a multi-standard radio configuration for a particular sub block. For details see [chapter 5.6.5.6, "Standard Files"](#), on page 223 and [chapter 5.6.5.5, "MSR Settings"](#), on page 220.

Note that *either* a standard *or* an MSR setting can be selected; if one is selected, the other is disabled.

Remote command:

[SENSe:]ESpectrum<sb>:PRESet[:STANdard] on page 650

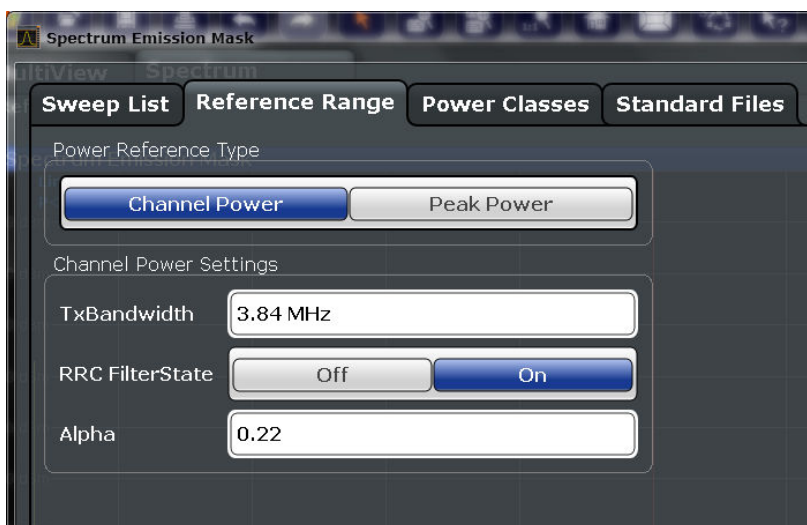
Edit sweep list

Switches to the "Sweep List" tab of the "Spectrum Emission Mask" dialog box to configure the individual frequency ranges and mask limits for the corresponding sub block. See [chapter 5.6.5.1, "Sweep List"](#), on page 210.

5.6.5.3 Reference Range

The range centered around the center frequency is defined as the reference range for all other ranges in the sweep list.

In the "Reference Range" tab of the "Spectrum Emission Mask" dialog box you define the general settings for the reference range.



Power Reference Type..... 218

Channel Power Settings..... 218

 L Tx Bandwidth..... 218

 L RRC Filter State..... 218

 L Alpha..... 219

Power Reference Type

Defines how the reference power is calculated.

"Channel Power"

Measures the channel power within the reference range using the integration bandwidth method (see also "IBW method" on page 140). Additional settings can be configured for this method.

"Peak Power"

Determines the peak power within the reference range.

Remote command:

[SENSe:]ESpectrum<sb>:RTYPE on page 668

Channel Power Settings

If the Power Reference Type "Channel Power" was selected, additional parameters can be configured.

Tx Bandwidth ← Channel Power Settings

Defines the bandwidth used for measuring the channel power, with:
 minimum span ≤ Tx Bandwidth ≤ span of reference range

Remote command:

[SENSe:]ESpectrum<sb>:BWID on page 667

RRC Filter State ← Channel Power Settings

Activates or deactivates the use of an RRC filter.

Remote command:

[SENSe:]ESpectrum<sb>:FILTer[:RRC][:STATe] on page 668

Alpha ← Channel Power Settings

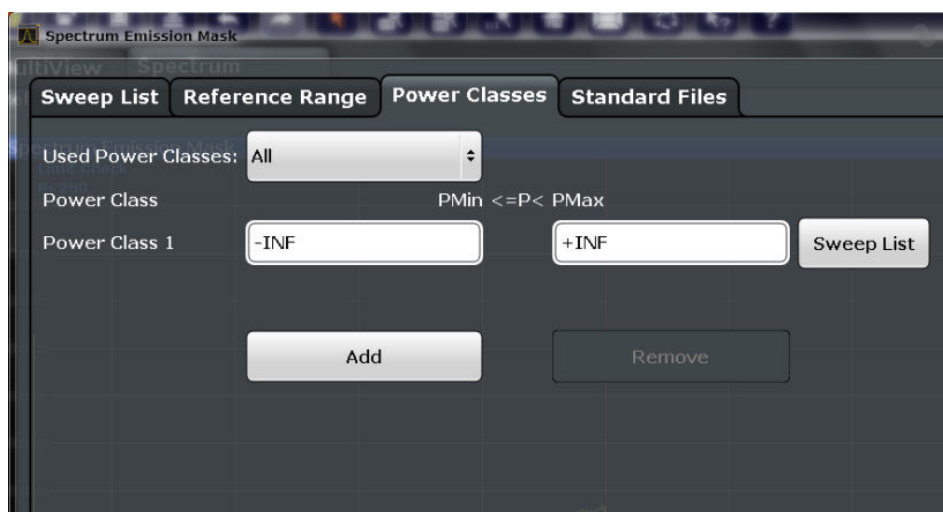
Sets the alpha value of the RRC filter (if activated).

Remote command:

[SENSe:]ESpectrum<sb>:FILTer[:RRC]:ALPHA on page 668

5.6.5.4 Power Classes

In the "Power Classes" tab of the "Spectrum Emission Mask" dialog box you configure power classes for which you can then define sweep list ranges. For details see "Power classes" on page 202.



Used Power Classes.....	219
PMin/PMax.....	220
Sweep List.....	220
Adding or Removing a Power Class.....	220

Used Power Classes

Defines which power classes are considered for the SEM measurement. Limits can be defined only for used power classes. It is only possible to select either one specific power class or all of the defined power classes.

If "All" is selected, the power class that corresponds to the currently measured power in the reference range is used for monitoring. The limits assigned to that power class are applied (see "Abs Limit Start/Stop <n>" on page 214 and "Rel Limit Start/Stop <n>" on page 214).

Remote command:

CALCulate<n>:LIMit<k>:ESpectrum<sb>:PCLass<class>[:EXCLusive]
on page 672

To define all limits in one step:

CALCulate<n>:LIMit<k>:ESpectrum<sb>:PCLass<class>:LIMit[:STATE]
on page 672

PMin/PMax

Defines the power limits for each power class. The first range always starts at -200 dBm (-INF) and the last range always stops at 200 dBm (+INF). These fields cannot be modified. If more than one power class is defined, the value of "PMin" must be equal to the value of "PMax" of the previous power class and vice versa.

Note that the power level may be equal to the lower limit(s), but must be lower than the upper limit(s):

$$P_{\min} \leq P < P_{\max}$$

Otherwise the ranges are corrected automatically.

Remote command:

`CALCulate<n>:LIMit<k>:ESpectrum<sb>:PCLass<class>:MINimum`
on page 673

`CALCulate<n>:LIMit<k>:ESpectrum<sb>:PCLass<class>:MAXimum`
on page 673

Sweep List

Switches to the "Sweep List" tab of the "Spectrum Emission Mask" dialog box and focuses the "Limit Check" setting for the corresponding power class (1-4) in the reference range (see "[Limit Check <n>](#)" on page 214).

Adding or Removing a Power Class

Adds a new power class at the end of the list or removes the last power class. After adding or removing, the last power class is adapted to end at "+INF". Note that a maximum of 4 power classes are available.

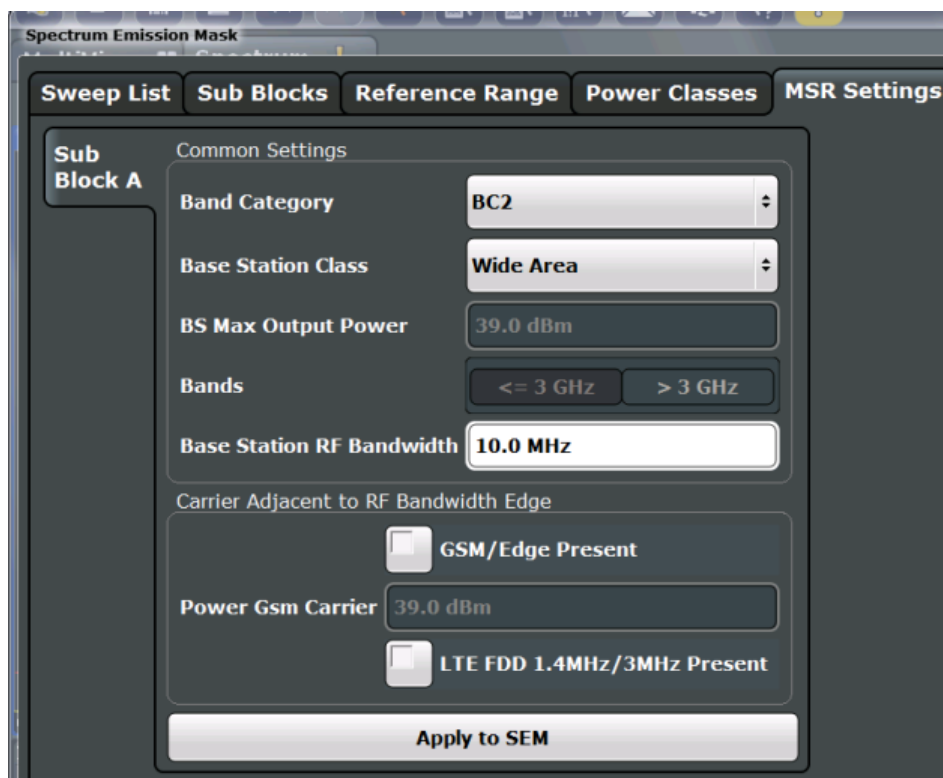
Remote command:

`CALCulate<n>:LIMit<k>:ESpectrum<sb>:PCLass:COUNT` on page 671

5.6.5.5 MSR Settings

In the "MSR Settings" tab of the "Spectrum Emission Mask" dialog box you configure multi-standard radio (MSR) measurements, which allow you to perform SEM tests on multiple carriers using different digital standards.

For details see [chapter 5.6.4.4, "Multi-Standard Radio \(MSR\) SEM Measurements"](#), on page 206.



Band Category..... 221
 Base Station Class..... 221
 Base Station Maximum Output Power..... 222
 Bands..... 222
 Base Station RF Bandwidth..... 222
 Carrier Adjacent to RF Bandwidth Edge..... 222
 Power GSM Carrier..... 222
 Apply to SEM..... 223

Band Category

Defines the band category for MSR measurements, i.e. the combination of available carriers to measure.

- "BC1" LTE FDD and W-CDMA
- "BC2" LTE FDD, W-CDMA and GSM/EDGE
- "BC3" LTE TDD and TD-SCDMA

Remote command:

[SENSe:]ESpectrum<sb>:MSR:BCATegory on page 675

Base Station Class

Defines the class of the base station according to its sending range.

This setting is required to calculate the SEM limits according to standard 3GPP 37.141 V12.2.0.

Remote command:

[SENSe:]ESpectrum<sb>:MSR:CLAS on page 676

Base Station Maximum Output Power

Defines the maximum output power of the base station. Possible values are from 0 to 100 dBm in 1 dB steps.

This setting is only available for base stations with a medium range [Base Station Class](#).

This value is required to calculate the SEM limits according to standard 3GPP 37.141 V12.2.0.

Remote command:

[\[SENSe:\]ESpectrum<sb>:MSR:MPOWer](#) on page 678

Bands

Defines the frequency range of the bands used by the base station.

This setting is only available for [Band Category](#) 1 or 3.

This setting is required to calculate the SEM limits according to standard 3GPP 37.141 V12.2.0.

Remote command:

[\[SENSe:\]ESpectrum<sb>:MSR:BAND](#) on page 674

Base Station RF Bandwidth

Defines the relevant RF bandwidth (span) required to measure all available carriers in MSR SEM measurements.

Remote command:

[\[SENSe:\]ESpectrum<sb>:MSR:RFBWidth](#) on page 679

Carrier Adjacent to RF Bandwidth Edge

For particular measurement setups the specification demands specific limits for the SEM ranges.

These settings are only available for [Band Category](#) 2.

"GSM/EDGE present"

A GSM/EDGE carrier is located at the edge of the RF band.

In this case, the power of the GSM carrier must be specified (see ["Power GSM Carrier"](#) on page 222).

"LTE FDD 1.4 MHz / 3 MHz present"

An LTE FDD 1.4 MHz or 3 MHz carrier is located at the edge of the RF band.

Remote command:

[\[SENSe:\]ESpectrum<sb>:MSR:GSM:CPResent](#) on page 677

[\[SENSe:\]ESpectrum<sb>:MSR:LTE:CPResent](#) on page 678

Power GSM Carrier

Defines the power of the GSM carrier (if available, see ["Carrier Adjacent to RF Bandwidth Edge"](#) on page 222). Possible values are from 0 to 100 dBm in 1 dB steps.

This setting is only available for [Band Category](#) 2.

This setting is required to calculate the SEM limits according to standard 3GPP 37.141 V12.2.0.

Remote command:

[SENSe:]ESpectrum<sb>:MSR:GSM:CARR on page 676

Apply to SEM

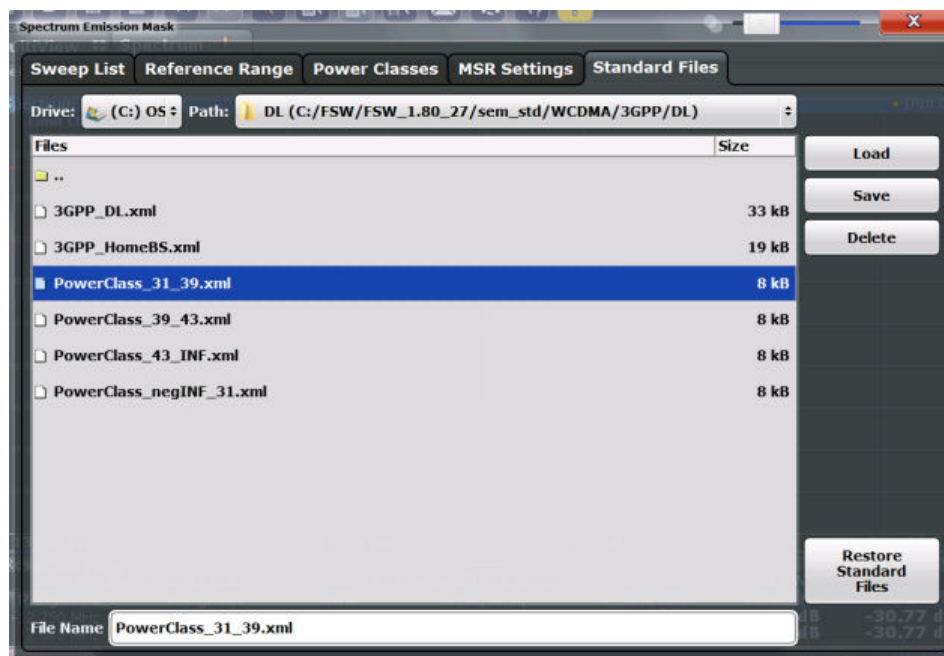
Configures the SEM sweep list according to the specified MSR settings.

Remote command:

[SENSe:]ESpectrum<sb>:MSR:APPLY on page 674

5.6.5.6 Standard Files

In the "Standard Files" tab of the "Spectrum Emission Mask" dialog box you can save the current measurement settings as a user-defined standard (xml file), or load stored measurement settings. Furthermore, you can delete an existing settings file.



For details see [chapter 5.6.6.1, "How to Manage SEM Settings Files"](#), on page 229.



Standard files for sub blocks (Multi-SEM measurements)

If more than 1 sub blocks are defined, the "Standard Files" tab and softkey are not available. To load a standard file for an individual sub block, use the [Standard / MSR Settings](#) setting in the "Sub Blocks" tab.

[Selecting the Storage Location - Drive/ Path/ Files](#).....224

[File Name](#).....224

[Load Standard](#).....224

Save Standard	225
Delete Standard	225
Restore Standard Files	225

Selecting the Storage Location - Drive/ Path/ Files

Select the storage location of the settings file on the instrument or an external drive.

The "Drive" indicates the internal (C:) or any connected external drives (e.g. a USB storage device).

The "Path" contains the drive and the complete file path to the currently selected folder.

The "Files" list contains all subfolders and files of the currently selected path.

The default storage location for the SEM settings files is: C:\R_S\instr\sem_std.

Note: Saving instrument settings in secure user mode.

In secure user mode all data is stored to volatile memory, and is only available during the current instrument session. As soon as the power is switched off on the R&S FPS, the data is cleared.

To store settings permanently, select an external storage location, such as a USB memory device.

For details see [chapter 3.1.6, "Protecting Data Using the Secure User Mode"](#), on page 30.

For details see "Protecting Data Using the Secure User Mode" in the "Data Management" section of the R&S FPS User Manual.

Remote command:

[MMEMoRY:CATalog?](#) on page 882

File Name

Contains the name of the data file without the path or extension.

By default, the name of a settings file consists of a base name followed by an underscore. Multiple files with the same base name are extended by three numbers, e.g. `limit_lines_005`.

For details on the file name and location see [chapter 8.3.2.2, "Storage Location and File Name"](#), on page 486.

Note: Secure user mode. In secure user mode, settings that are to be stored on the instrument are stored to volatile memory. To store data permanently, select an external storage location such as a USB memory device.

For details see [chapter 3.1.6, "Protecting Data Using the Secure User Mode"](#), on page 30.

For details see "Protecting Data Using the Secure User Mode" in the "Data Management" section of the R&S FPS User Manual.

Load Standard

Loads the selected measurement settings file.

Remote command:

[\[SENSe:\]ESpectrum<sb>:PRESet\[:STANdard\]](#) on page 650

Save Standard

Saves the current measurement settings for a specific standard as a file with the defined name.

Remote command:

[SENSe:]ESpectrum<sb>:PRESet:STORe on page 651

Delete Standard

Deletes the selected standard. Standards predefined by Rohde & Schwarz can also be deleted. A confirmation query is displayed to avoid unintentional deletion of the standard.

Note: Restoring predefined standard files. The standards predefined by Rohde & Schwarz available at the time of delivery can be restored using the "Restore Standards" function (see "Restore Standard Files" on page 225).

Restore Standard Files

Restores the standards predefined by Rohde & Schwarz available at the time of delivery.

The XML files from the C:\R_S\instr\sem_backup folder are copied to the C:\R_S\instr\sem_std folder.

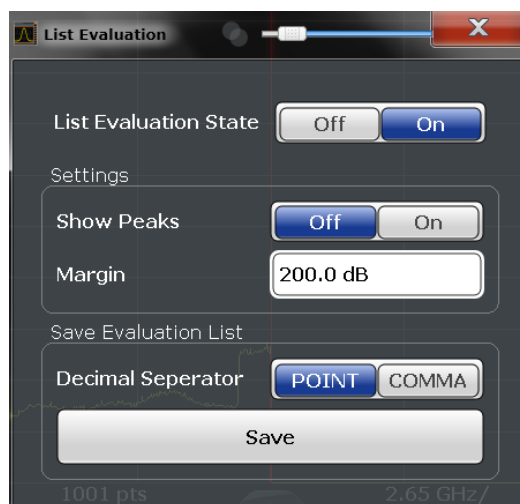
Note that this function will overwrite customized standards that have the same name as predefined standards.

Remote command:

[SENSe:]ESpectrum<sb>:PRESet:RESTore on page 650

5.6.5.7 List Evaluation (Results Configuration)

In the "List Evaluation" dialog box, which is displayed when you select the "Analysis" button in the "Overview" dialog box, or the "List Evaluation" softkey in the "SEMAsk" menu, you configure the contents and display of the SEM results.



List Evaluation (Result Summary) State.....	226
Show Peaks.....	226
Margin.....	226
Saving the Result Summary (Evaluation List) to a File.....	226

List Evaluation (Result Summary) State

Activates or deactivates the Result Summary.

Remote command:

`CALCulate<n>:ESpectrum:PEAKsearch:AUTO` on page 680

`TRACe<n>[:DATA]` on page 813

Show Peaks

If activated, all peaks that have been detected during an active SEM measurement are marked with blue squares in the Spectrum diagram.

Remote command:

`CALCulate<n>:ESpectrum:PEAKsearch:PSHow` on page 681

Margin

Although a margin functionality is not available for the limit check, a margin (threshold) for the peak values to be displayed in the result summary (and diagram, if activated) can be defined. Only peaks that exceed the margin value are displayed.

Remote command:

`CALCulate<n>:ESpectrum:PEAKsearch:MARGIN` on page 680

Saving the Result Summary (Evaluation List) to a File

Exports the Result Summary of the SEM measurement to an ASCII file for evaluation in an external application. If necessary, change the decimal separator for evaluation in other languages.

Define the file name and storage location in the file selection dialog box that is displayed when you select the "Save" function.

For details see [chapter 5.6.8.2, "ASCII File Export Format \(Spectrum Emission Mask\)"](#), on page 238.

Remote command:

`MMEMemory:STORe<n>:LIST` on page 903

`FORMat:DEXPort:DSEParator` on page 881

5.6.6 How to Perform a Spectrum Emission Mask Measurement

SEM measurements can be performed according to a specific standard or freely configured. Configuration for signals with a very regular channel definition can be configured very quickly and easily. Selecting the SEM measurement is a prerequisite for all other tasks. For multi-standard radio SEM measurements, configuration for specified scenarios can be done automatically.

For signals with multiple carriers, also in non-contiguous ranges, an SEM measurement with multiple sub blocks can be configured.

The following tasks are described:

- ["To select an SEM measurement"](#) on page 227
- ["To perform an SEM measurement according to a standard"](#) on page 227
- ["To configure a user-defined SEM measurement"](#) on page 227
- ["To perform an MSR SEM measurement"](#) on page 228
- ["To perform a Multi-SEM measurement"](#) on page 229

To select an SEM measurement

- ▶ Press the MEAS key, then select the "Spectrum Emission Mask" measurement.

To perform an SEM measurement according to a standard

- ▶ Load the settings file as described in ["How to load an SEM settings file"](#) on page 230 and start a measurement.

To configure a user-defined SEM measurement

1. Define the span of the signal to be monitored in the general span settings.
2. Split the frequency span of the measurement into ranges for signal parts with similar characteristics.
Starting from the center frequency, determine which sections of the signal to the left and right can be swept and monitored using the same parameters. Criteria for such a range definition may be, for example:
 - The signal power level
 - The required resolution bandwidth or sweep time
 - Transducer factors
 - Permitted deviation from the defined signal level, i.e. the required limit values for monitoringIf the signal consists of a transmission channel and adjacent channels, the channel ranges can usually be used for the range definition.
3. If the signal power level to be monitored may vary and the limits will vary accordingly, define power classes. For each range of levels that can be monitored in the same way, define a power class.
 - a) Select the "Overview" softkey, then select the "SEM Setup" button and switch to the "Power Classes" tab.
 - b) Add a power class by selecting the "Add" button.
 - c) Enter the start and stop power levels to define the class.
 - d) Select the power classes to be used for the current measurement: either a specific class, or all classes, to have the required class selected automatically according to the input level measured in the reference range.
4. Select the "Sweep List" tab of the "Spectrum Emission Mask" dialog box.
5. Insert the required ranges using the "Insert before Range" and "Insert after Range" buttons, which refer to the currently selected range (the reference range by default).

If the signal trace is symmetric to the center frequency, activate the "Sym Setup" option to make setup easier and quicker.

6. Define the measurement parameters for each range as required. If symmetrical setup is activated, you only have to configure the ranges to one side of the center range.
In particular, define the limits for each range of the signal, i.e. the area in which the signal level may deviate without failing the limit check. If several power classes were defined (see [step 3](#)), define limits for each power class.
 - a) Define the type of limit check, i.e. whether absolute values or relative values are to be checked, or both. The type of limit check is identical for all power classes.
 - b) Define the limit start and stop values.
7. If the sweep list settings - other than the limit and transducer values - are identical for several adjacent ranges, activate "Fast SEM" mode to speed up the measurement. You only have to activate the mode for one range, the others are adapted automatically.
8. If necessary, change the settings for the reference power to which all SEM results refer in the "Reference Range" tab.
9. To indicate the determined peaks in the display during an SEM measurement, select the "Analysis" button in the "Overview" and activate the "Show Peaks" option.
10. To save the current SEM measurement settings to a file to re-use them later, save a settings file as described in ["How to save a user-defined SEM settings file"](#) on page 230.
11. Start a sweep.
The determined powers and limit deviations for each range are indicated in the Result Summary. If activated, the peak power levels for each range are also indicated in the Spectrum diagram.
12. To save the Result Summary, export the results to a file as described in [chapter 5.6.6.2, "How to Save SEM Result Files"](#), on page 230.

To perform an MSR SEM measurement

1. Select the "MSR Config" softkey.
2. Select the band category that determines the digital standards used in the measurement setup (see ["Band Category"](#) on page 221).
3. Define the bandwidth that contains all relevant carrier signals to be measured.
4. For measurements with GSM/EDGE, LTE FDD and W-CDMA carriers (BC2), define whether a GSM/EDGE or an LTE FDD carrier, or both, are located at the edge of the bandwidth.
5. Select the "Apply to SEM" button.

The sweep list is configured according to the MSR specification, with the required number of ranges and defined limits.

6. Start a sweep.

The determined powers and limit deviations for each range are indicated in the Result Summary. If activated, the peak power levels for each range are also indicated in the Spectrum diagram.

7. To save the Result Summary, export the results to a file as described in [chapter 5.6.6.2, "How to Save SEM Result Files"](#), on page 230.

To perform a Multi-SEM measurement

1. Define the span of the signal to be monitored in the general span settings.
2. Select the "Multi-SEM Config" softkey.
3. Define the number of sub blocks (up to 3) that contain the relevant carriers.
4. For each sub block, define the center frequency, that is, the frequency of the TX carrier or a frequency in the dedicated reference range.
5. For each sub block, do one of the following:
 - a) Select a standard settings file to be used.
 - b) Select the "MSR Settings" button and define the MSR configuration as described in ["To perform an MSR SEM measurement"](#) on page 228.
 - c) Select the "Edit" button and configure the sweep list manually as defined in ["To configure a user-defined SEM measurement"](#) on page 227. Be sure to select the correct vertical tab for the corresponding sub block within each subtab of the "Spectrum Emission Mask" configuration dialog.
Define a function to be used for overlapping ranges in the "Multi-Limit Calc" field of the sweep list.
6. Start a sweep.

The determined powers and limit deviations for each sub block, each gap, and each range are indicated in the Result Summary. If activated, the peak power levels for each range are also indicated in the Spectrum diagram.
7. To save the Result Summary, export the results to a file as described in [chapter 5.6.6.2, "How to Save SEM Result Files"](#), on page 230.

5.6.6.1 How to Manage SEM Settings Files

SEM measurement settings can be saved to an xml file which can then be exported to another application or loaded on the R&S FPS again at a later time. Some predefined XML files are provided that contain ranges and parameters according to the selected standard. All XML files are stored under `C:\r_s\instr\sem_std`.

For details on the file format of the SEM settings file, see [chapter 5.6.8.1, "Format Description of SEM XML Files"](#), on page 233.

SEM settings or standard files are managed in the "Standards" tab of the "Spectrum Emission Mask" dialog box. To display this dialog box, select the "Overview" softkey and then the "SEM Setup" button.

How to load an SEM settings file

1. From the file selection dialog box, select the settings file (with an ".xml" extension).
2. Select the "Load" button.

The settings from the selected file are restored to the R&S FPS and you can repeat the SEM measurement with the stored settings.

How to save a user-defined SEM settings file

1. Configure the SEM measurement as required (see [chapter 5.6.6, "How to Perform a Spectrum Emission Mask Measurement"](#), on page 226).
2. In the "Standard Files" tab of the "Spectrum Emission Mask" dialog box, define a file name and storage location for the settings file.
3. Select the "Save" button.

The settings are stored to a file with the extension ".xml" as specified.

How to delete an SEM settings file

1. In the "Standard Files" tab of the "Spectrum Emission Mask" dialog box, select the file you want to delete.
2. Select the "Delete" button.
3. Confirm the message.

The settings file is removed from the R&S FPS.

How to restore default SEM settings files

The R&S FPS is delivered with predefined settings files which can be edited and overwritten. However, you can restore the original files.

- ▶ In the "Standard Files" tab of the "Spectrum Emission Mask" dialog box, select the "Restore Standard Files" button.

The original predefined settings files are available for selection on the R&S FPS.

5.6.6.2 How to Save SEM Result Files

The Result Summary from an SEM measurement can be saved to a file, which can be exported to another application for further analysis, for example.

For details on the file format of the SEM export file, see [chapter 5.6.8.2, "ASCII File Export Format \(Spectrum Emission Mask\)"](#), on page 238.

1. Configure and perform an SEM measurement as described in [chapter 5.6.6, "How to Perform a Spectrum Emission Mask Measurement"](#), on page 226.

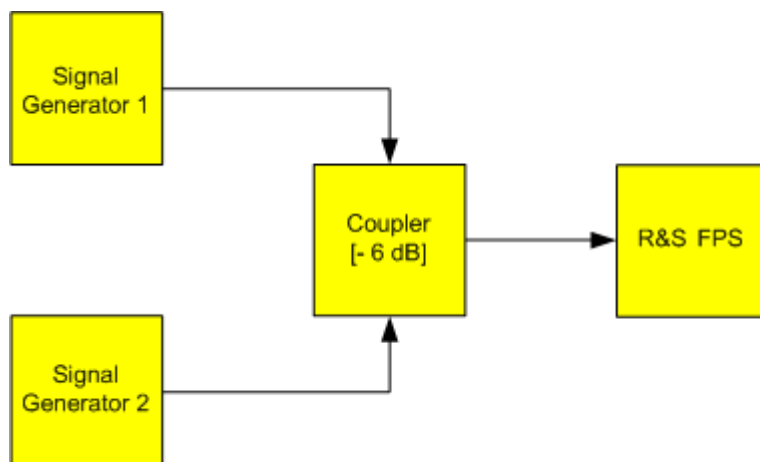
2. In the "Overview", select the "Analysis" button.
3. If necessary, change the "Decimal Separator" to "COMMA" for evaluation in other languages.
4. Select the "Save" button.
5. In the file selection dialog box, select a storage location and file name for the result file.
6. Select the "Save" button.

The file with the specified name and the extension `.dat` is stored in the defined storage location.

5.6.7 Measurement Example: Multi-SEM Measurement

The following measurement example demonstrates an SEM measurement for a signal with multiple sub blocks.

Test setup:



Signal generator settings (e.g. R&S FPS SMW):

Device	Standard	Center Frequency	Level	Test Model
SigGen 1	3GPP/FDD	900 MHz	0 dBm	1-16
SigGen 2	EUTRA/LTE	906.5 MHz	0 dBm	1_1_5MHz

Setting up the measurement

1. Preset the R&S FPS.
2. Set the center frequency to *903.25 MHz*.
3. Set the reference level to *10 dBm* with an offset of to *30 dB*.

Spectrum Emission Mask (SEM) Measurement

4. Press the MEAS key and select the "SEM" measurement function from the "Select Measurement" dialog box.
5. Select the "Sub Blocks" softkey and define a subblock count of 2.
6. For sub block A, define the settings for the 3GPP/FDD signal:
 - a) Set the center frequency to 900 MHz
 - b) Select "MSR Settings".
 - c) Set the "Base Station RF Bandwidth" to 5 MHz.
 - d) Select "Apply to SEM".
7. For sub block B, define the settings for the EUTRA/LTE signal:
 - a) Set the center frequency to 906.5 MHz
 - b) Select "MSR Settings".
 - c) Set the "Base Station RF Bandwidth" to 5 MHz.
 - d) Select "Apply to SEM".
8. Select RUN SINGLE to perform a measurement with the new settings.

The results of the measurement for each sub block are displayed in the Result Summary. The summarized limit line is indicated in the Spectrum graph.

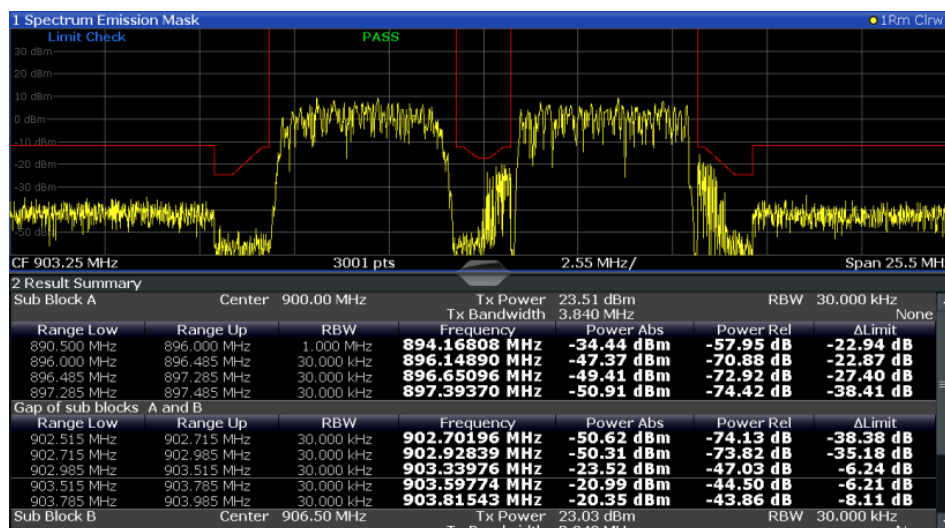


Fig. 5-38: Multi-SEM measurement: results of the measurement for each sub block

5.6.8 Reference: SEM File Descriptions

This reference provides details on the format of the SEM settings and result files.

- [Format Description of SEM XML Files](#)..... 233
- [ASCII File Export Format \(Spectrum Emission Mask\)](#)..... 238

5.6.8.1 Format Description of SEM XML Files

The SEM XML files offer a quick way to change the measurement settings. A set of ready-made XML files for different standards is already provided. You can also create and use your own XML files. Alternatively, edit the settings directly in the "Spectrum Emission Mask" dialog box and save the XML file afterwards. This way, no modifications have to be done in the XML file itself.

In addition to saving the current settings to a file, settings files can also be created independently of the R&S FPS, in an external application. When creating your own XML files, be sure to comply with the following conventions because the R&S FPS can only interpret XML files of a known structure. For sample files look in the `C:\r_s\instr\sem_std` directory of the R&S FPS.

To load a settings file, use the "Load" function in the "Standard Files" tab of the "Spectrum Emission Mask" dialog box (see ["How to load an SEM settings file"](#) on page 230). All XML files are stored under `C:\r_s\instr\sem_std`.

The files for importing range settings obey the rules of the XML standard. The child nodes, attributes, and structure defined for the data import are described here.



Be sure to follow the structure exactly as shown below or else the R&S FPS is not able to interpret the XML file and error messages are shown on the screen. It is recommended that you make a copy of an existing file and edit the copy of the file.

Basically, the file consists of three elements that can be defined:

- The "BaseFormat" element
- The "PowerClass" element
- The "Range" element

The "BaseFormat" element

It carries information about basic settings. In this element only the "ReferencePower" child node has any effects on the measurement itself. The other attributes and child nodes are used to display information about the Spectrum Emission Mask Standard on the measurement screen. The child nodes and attributes of this element are shown in [table 5-13](#).

Example:

In the sample file `PowerClass_39_43.xml` under `C:\r_s\instr\sem_std\WCDMA\3GPP`, these attributes are defined as follows:

- `Standard="W-CDMA 3GPP"`
- `LinkDirection="DL"`
- `PowerClass="(39,43)dBm"`

The "PowerClass" element

It is embedded in the "BaseFormat" element and contains settings information about the power classes. Up to four different power classes can be defined. For details refer

to [chapter 5.6.5.4, "Power Classes"](#), on page 219. The child nodes and attributes of this element are shown in [table 5-14](#).

The "Range" element

This element is embedded in the "PowerClass" element. It contains the settings information of the range. There have to be at least three defined ranges: one reference range and at least one range to either side of the reference range. The maximum number of ranges is 30. Note that the R&S FPS uses the same ranges in each power class. Therefore, the contents of the ranges of each defined power class have to be identical to the first power class. An exception are the Start and Stop values of the two Limit nodes that are used to determine the power class. Note also, that there are two Limit nodes to be defined: one that gives the limit in absolute values and one in relative values. Make sure units for the Start and Stop nodes are identical for each Limit node.

For details refer to [chapter 5.6.5.1, "Sweep List"](#), on page 210. The child nodes and attributes of this element are shown in [table 5-15](#).

The following tables show the child nodes and attributes of each element and show if a child node or attribute is mandatory for the R&S FPS to interpret the file or not. Since the hierarchy of the XML can not be seen in the tables, either view one of the default files already stored on the R&S FPS in the "C:\r_s\instr\sem_std" directory or check the structure as shown below.

Below, a basic example of the structure of the file is shown, containing all mandatory attributes and child nodes. Note that the "PowerClass" element and the range element are themselves elements of the "BaseFormat" element and are to be inserted where noted. The separation is done here simply for reasons of a better overview. Also, no example values are given here to allow a quick reference to the tables above. *Italic font* shows the placeholders for the values.

- The "BaseFormat" element is structured as follows:
 - `<RS_SEM_ACP_FileFormat Version="1.0.0.0">`
 - `<Name>"Standard"</Name>`
 - `<Instrument>`
 - `<Type>"Instrument Type"</Type>`
 - `<Application>"Application"</Application>`
 - `</Instrument>`
 - `<LinkDirection Name="Name">`
 - `<ReferencePower>`
 - `<Method>"Method"</Method>`
 - `</ReferencePower>`
 - `<PowerClass Index="n">`
 - `<!-- For contents of the PowerClass node see table 5-14 -->`
 - `<!-- Define up to four PowerClass nodes -->`
 - `</PowerClass>`
 - `</LinkDirection>`
 - `</RS_SEM_ACP_File>`
- The "PowerClass" element is structured as follows:
 - `<PowerClass Index="n">`
 - `<StartPower Unit="dBm" InclusiveFlag="true" Value="StartPowerValue"/>`
 - `<StopPower Unit="dBm" InclusiveFlag="false" Value="StopPowerValue"/>`

```

<DefaultLimitFailMode>"Limit Fail Mode"</DefaultLimitFailMode>
<Range Index="n">
<!-- For contents of the Range node see table 5-15 -->
<!-- Define up to twenty Range nodes -->
</Range>
...
</PowerClass>

```

- The "Range" element is structured as follows:

```

- <Range Index="n">
  <Name="Name">
  <ChannelType>"Channel Type"</Channel Type>
  <WeightingFilter>
  <Type>"FilterType"</Type>
  <RollOffFactor>"Factor"</RollOffFactor>
  <Bandwidth>"Bandwidth"</Bandwidth>
  </WeightingFilter>
  <FrequencyRange>
  <Start>"RangeStart"</Start>
  <Stop>"RangeStop"</Stop>
  </FrequencyRange>
  <Limit>
  <Start Unit="Unit" Value="Value"/>
  <Stop Unit="Unit" Value="Value"/>
  </Limit>
  <Limit>
  <Start Unit="Unit" Value="Value"/>
  <Stop Unit="Unit" Value="Value"/>
  </Limit>
  <RBW Bandwidth="Bandwidth" Type="FilterType"/>
  <VBW Bandwidth="Bandwidth"/>
  <Detector>"Detector"</Detector>
  <Sweep Mode="SweepMode" Time="SweepTime"/>
  <Amplitude>
  <ReferenceLevel Unit="dBm" Value="Value"/>
  <RFAttenuation Mode="Auto" Unit="dB" Value="Value"/>
  <Preamplifier State="State"/>
  </Amplitude>
  <MeasPointsMin>1</MeasPointsMin>
  <CalcRuleMulti>Sum</CalcRuleMulti>
</Range>

```

Table 5-13: Attributes and child nodes of the BaseFormat element

Child Node	Attribute	Value	Parameter Description	Mand.
	FileFormatVersion	1.0.0.0		Yes
	Date	YYYY-MM-DD HH:MM:SS	Date in ISO 8601 format	No
Name		<string>	Name of the standard	Yes
Instrument	Type	FSL	Name of the instrument	No

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Child Node	Attribute	Value	Parameter Description	Mand.
	Application	SA K72 K82	Name of the application	No
LinkDirection	Name	Downlink Uplink None		Yes
	ShortName	DL UL		No
Reference-Power				Yes
Method	TX Channel Power TX Channel Peak Power			Yes
Reference-Channel	<string>			No

Table 5-14: Attributes and child nodes of the PowerClass element

Child Node	Attribute	Value	Parameter Description	Mand.
StartPower	Value	<power in dBm>	The start power must be equal to the stop power of the previous power class. The StartPower value of the first range is -200	Yes
	Unit	dBm		Yes
	InclusiveFlag	true		Yes
StopPower	Value	<power in dBm>	The stop power must be equal to the start power of the next power class. The StopPower value of the last range is 200	Yes
	Unit	dBm		
	InclusiveFlag	false		Yes
DefaultLimitFailMode		Absolute Relative Absolute and Relative Absolute or Relative		Yes

Table 5-15: Attributes and child nodes of the Range element (normal ranges)

Child Node	Attribute	Value	Parameter Description	Mand.
	Index	0...19	Indices are continuous and have to start with 0	Yes
	Name	<string>	Name of the range	Only if ReferenceChannel contains a name and the range is the reference range
	Short-Name	<string>	Short name of the range	No
ChannelType		TX Adjacent		Yes

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Child Node	Attribute	Value	Parameter Description	Mand.
WeightingFilter				Only if ReferencePower method is TX Channel Power and the range is the reference range
Type		RRC CFilter	Type of the weighting filter	Yes
Roll Off Factor		0...1	Excess bandwidth of the filter	Only if the filter type is RRC
Bandwidth		<bandwidth in Hz>	Filter bandwidth	Only if the filter type is RRC
FrequencyRange				Yes
Start		<frequency in Hz>	Start value of the range	Yes
Stop		<frequency in Hz>	Stop value of the range	Yes
Limit		dBm/Hz dBm dBc dBr dB	A Range must contain exactly two limit nodes; one of the limit nodes has to have a relative unit (e.g. dBc), the other one must have an absolute unit (e.g. dBm)	Yes
Start	Value	<numeric_value>	Power limit at start frequency	Yes
	Unit	dBm/Hz dBm dBc dBr dB	Sets the unit of the start value	
Stop	Value	<numeric_value>	Power limit at stop frequency	
	Unit	dBm/Hz dBm dBc dBr dB	Sets the unit of the stop value	
LimitFailMode		Absolute Relative Absolute and Relative Absolute or Relative	If used, it has to be identical to DefaultLimitFailMode	No
RBW	Bandwidth	<bandwidth in Hz>	"RBW" on page 212	Yes
	Type	NORM PULS CFIL RRC		No
VBW	Bandwidth	<bandwidth in Hz>	"VBW" on page 212	Yes
Detector		NEG POS SAMP RMS AVER QUAS	If used, it has to be identical in all ranges.	No
Sweep	Mode	Manual Auto	"Sweep Time Mode" on page 213	Yes
	Time	<time in sec>	"Sweep Time" on page 213	No
Amplitude				No

Child Node	Attribute	Value	Parameter Description	Mand.
ReferenceLevel	Value	<power in dBm>	"Ref. Level" on page 213	Yes, if the ReferenceLevel child node is used
	Unit	dBm	Defines dBm as unit	Yes, if the ReferenceLevel node is used
RFAttenuation	Mode	Manual Auto	"RF Att. Mode" on page 213	Yes, if the ReferenceLevel child node is used

5.6.8.2 ASCII File Export Format (Spectrum Emission Mask)

When trace data from an SEM measurement is exported, the data is stored in ASCII format as described below. The first part of the file lists information about the signal analyzer and the general setup.

File contents	Explanation
File header	
	Model
Version;1.00;	Firmware version
Date;31.Mar 11;	Storage date of data set
Mode;ANALYZER;SEM;	Operating mode and measurement function
Center Freq;1325000000.000000;Hz	X-axis settings
Freq Offset;0.000000;Hz	
Span;25500000.000000;Hz	
x-Axis;LIN;	
Start;13237250000.000000;Hz	
Stop;13262750000.000000;Hz	
Level Offset;0.000000;dB	Y-axis settings
Ref Position;100.000000;%	
y-Axis;LOG;	
Level Range;100.000000;dB	
Trace settings	
Trace Mode;CLR/WRITE;	
Detector;RMS;	
Sweep Count;0;	
Trace 1.;	
x-Unit;Hz;	

File contents	Explanation
y-Unit;dBm;	
List evaluation settings	
Margin;200;	Peak List margin
Reference range settings	
RefType; CPOWER;	Reference power type
TxBandwidth;3840000;;Hz	Channel power settings
Filter State; ON;	
Alpha;0.22;	
PeaksPerRange;1;	Max. number of peaks per range to be detected
Values;2;	Number of detected peaks
File data section	
0;-12750000;-2515000;30000;13242367500;-43.844722747802734;-0.33028793334960938;49.669712066650391;FAIL;	Measured peak values: <range number>; <start frequency>; <stop frequency>; <resolution bandwidth of range>; <frequency of peak>; <absolute power in dBm of peak>; <relative power in dBc of peak>; (related to the channel power) <distance to the limit line in dB>; (positive value means above the limit) <limit fail (pass = 0, fail =1)>;
2;2515000;12750000;30000;13257632500;-43.844722747802734;-0.33028793334960938;49.669712066650391;FAIL;	

5.7 Spurious Emissions Measurement

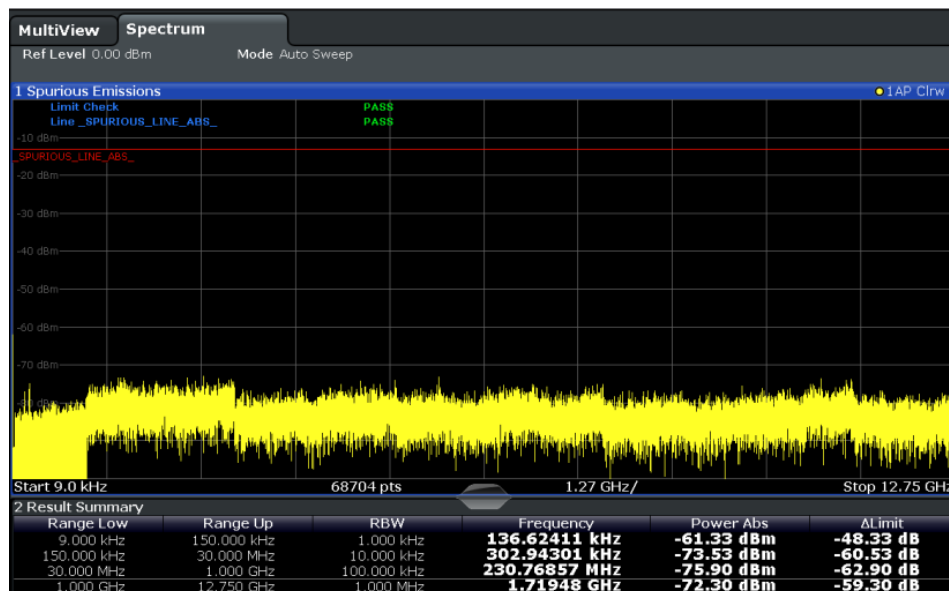
The R&S FPS supports Spurious Emissions measurements.

- [About the Measurement](#).....239
- [Spurious Emissions Measurement Results](#).....240
- [Spurious Emissions Basics](#).....241
- [Spurious Emissions Measurement Configuration](#).....243
- [How to Perform a Spurious Emissions Measurement](#).....249
- [Reference: ASCII Export File Format \(Spurious\)](#).....250

5.7.1 About the Measurement

The Spurious Emissions measurement monitors unwanted RF products outside the assigned frequency band generated by an amplifier. The spurious emissions are usually measured across a wide frequency range. The Spurious Emissions measurement

allows a flexible definition of all parameters. A result table indicates the largest deviations of the absolute power from the limit line for each range, and the results can be checked against defined limits automatically.



5.7.2 Spurious Emissions Measurement Results

The measured signal, including any spurious emissions, and optionally the detected peaks are displayed in the Spurious Emissions measurement diagram. If defined, the limit lines and the limit check results are also indicated. In addition to the graphical results, a result table can be displayed to evaluate the measured powers and limit check results (see also [chapter 5.7.3.2, "Limit Lines in Spurious Measurements"](#), on page 242). The details of the evaluation list can be configured.

Range Low	Range Up	RBW	Frequency	Power Abs	ΔLimit
9.000 kHz	150.000 kHz	1.000 kHz	136.62411 kHz	-61.33 dBm	-48.33 dB
150.000 kHz	30.000 MHz	10.000 kHz	302.94301 kHz	-73.53 dBm	-60.53 dB
30.000 MHz	1.000 GHz	100.000 kHz	230.76857 MHz	-75.90 dBm	-62.90 dB
1.000 GHz	12.750 GHz	1.000 MHz	1.71948 GHz	-72.30 dBm	-59.30 dB

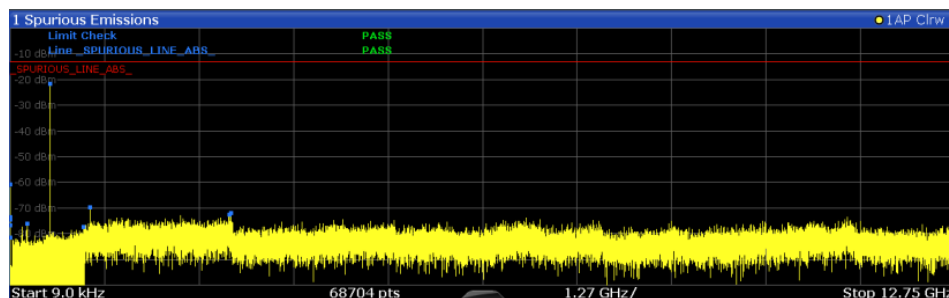
The following information is provided in the evaluation list for each range:

Column	Description
Range Low	Frequency range start for the range the peak value belongs to
Range Up	Frequency range end for the range the peak value belongs to
RBW	RBW of the range
Frequency	Frequency at the peak value
Power Abs	Absolute power level at the peak value
ΔLimit	Deviation of the absolute power level from the defined limit for the peak value

By default, one peak per range is displayed. However, you can change the settings to:

- Display all peaks
- Display a certain number of peaks per range
- Display only peaks that exceed a threshold ("Margin")

In addition to listing the peaks in the list evaluation, detected peaks can be indicated by blue squares in the diagram.



Furthermore, you can save the evaluation list to a file.

Retrieving Results via Remote Control

The measured spurious values of the displayed trace can be retrieved using the TRAC:DATA? SPUR command (see TRACe<n>[:DATA] on page 813).

5.7.3 Spurious Emissions Basics

Some background knowledge on basic terms and principles used in Spurious Emissions measurements is provided here for a better understanding of the required configuration settings.

- [Ranges and Range Settings](#)..... 241
- [Limit Lines in Spurious Measurements](#)..... 242

5.7.3.1 Ranges and Range Settings

Conditions for ranges

The following rules apply to ranges:

- The minimum span of a range is 20 Hz.
- The individual ranges must not overlap (but may have gaps).
- The maximum number of ranges is 30 (in firmware versions < 1.60: 20 ranges).
- The maximum number of sweep points in all ranges is limited to 100001.

If you set a span that is smaller than the overall span of the ranges, the measurement includes only the ranges that lie within the defined span and have a minimum span of 20 Hz.



Defining ranges by remote control

In Spurious Emissions measurements, there are no remote commands to insert new ranges between existing ranges directly. However, you can delete or re-define the existing ranges to create the required order.

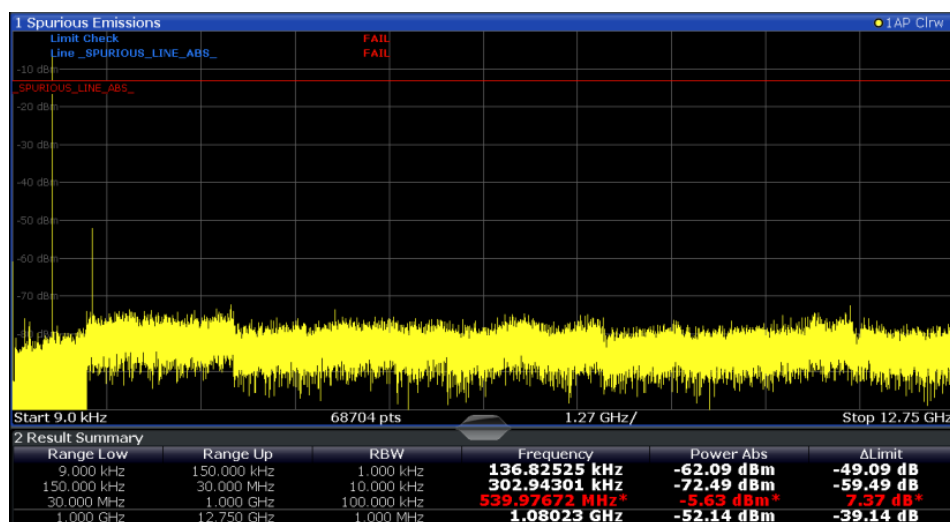
A remote command example for defining parameters and ranges in Spurious Emissions measurements is described in [chapter 11.5.7.6, "Programming Example: Spurious Emissions Measurement"](#), on page 694.

5.7.3.2 Limit Lines in Spurious Measurements

Limit lines allow you to check the measured data against specified limit values. Generally, it is possible to define limit lines for any measurement in the Spectrum application using the LINES key. For Spurious measurements, however, a special limit line is available via the "Sweep List", and it is strongly recommended that you use only this limit line definition.

In the "Sweep List" you can define a limit line that varies its level according to the specified frequency ranges. A distinguished limit line is automatically defined according to the current "Sweep List" settings every time the settings change. This limit line is labeled "_SPURIOUS_LINE_ABS_<xxx>", where <xxx> is an index to distinguish limit lines between different measurement channels.

If a limit check is activated in the "Sweep List", the "_SPURIOUS_LINE_ABS" limit line is indicated by a red line in the display, and the result of the limit check is indicated at the top of the diagram. Note that only "Pass" or "Fail" is indicated; a "margin" function as for general limit lines is not available. Also, only absolute limits can be checked, not relative ones.



As for general limit lines, the results of each limit line check are displayed (here: "_SPURIOUS_LINE_ABS"), as well as the combined result for all defined limit lines ("Limit Check").

The limit check is considered to be "failed" if any signal level outside the absolute limits is measured.

In addition to the limit line itself, the largest deviations of the absolute power from the limit line for each range are displayed in the evaluation list if the limit check is activated. Values that exceed the limit are indicated in red and by an asterisk (*).



Although a margin functionality is not available for the limit check, a margin (threshold) for the peak values to be displayed in the evaluation list can be defined in the list evaluation settings. Furthermore, you can define how many peaks per range are listed. For details see [chapter 5.7.4.3, "List Evaluation"](#), on page 247.

5.7.4 Spurious Emissions Measurement Configuration

Spurious emissions measurements are selected via the "Spurious Emissions" button in the "Select Measurement" dialog box. The measurement is started immediately with the default settings. It can be configured via the MEAS CONFIG key or in the "Spurious Emissions" dialog box, which is displayed when you select the "Spurious Setup" button in the "Overview" or the "Sweep List" softkey from the "Spurious Emissions" menu.

For details on using the configuration "Overview", see [chapter 6.1, "Configuration Overview"](#), on page 291.

The remote commands required to perform these tasks are described in [chapter 11.5.7, "Measuring Spurious Emissions"](#), on page 684.

The following settings are available in individual tabs of the "Spurious Emissions" configuration dialog box, or via softkeys in the "SpurEm" menu.

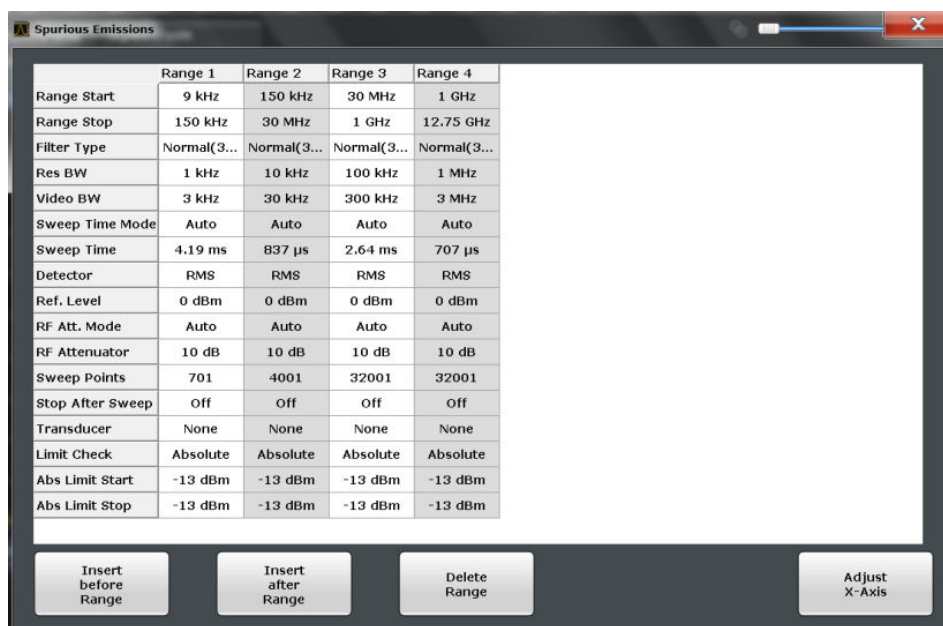
- [Sweep List](#).....243
- [Adjusting the X-Axis to the Range Definitions](#).....247
- [List Evaluation](#).....247

5.7.4.1 Sweep List

For Spurious Emissions measurements, the input signal is split into several frequency ranges which are swept individually and for which different limitations apply. In the "Sweep List" dialog box you configure the individual frequency ranges and limits.



If you edit the sweep list, always follow the rules and consider the limitations described in [chapter 5.7.3.1, "Ranges and Range Settings"](#), on page 241.



Range Start / Range Stop..... 244

Filter Type..... 244

RBW..... 245

VBW..... 245

Sweep Time Mode..... 245

Sweep Time..... 245

Detector..... 245

Ref. Level..... 245

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RF Attenuator..... 246

Sweep Points..... 246

Stop After Sweep..... 246

Transducer..... 246

Limit Check..... 246

Abs Limit Start/Stop..... 247

Insert before/after Range..... 247

Delete Range..... 247

Range Start / Range Stop

Sets the start frequency/stop frequency of the selected range.

If you set a span that is smaller than the overall span of the ranges, the measurement includes only the ranges that lie within the defined span and have a minimum span of 20 Hz.

Remote command:

[SENSe:] LIST:RANGe<range> [:FREQuency] :START on page 688

[SENSe:] LIST:RANGe<range> [:FREQuency] :STOP on page 688

Filter Type

Sets the filter type for this range.

For details on filter types see [chapter 6.5.1.6, "Which Data May Pass: Filter Types"](#), on page 355.

Remote command:

`[SENSe:]LIST:RANGe<range>:FILTer:TYPE` on page 688

RBW

Sets the RBW value for this range.

For details on the RBW see [chapter 6.5.1.1, "Separating Signals by Selecting an Appropriate Resolution Bandwidth"](#), on page 352.

Remote command:

`[SENSe:]LIST:RANGe<range>:BANDwidth[:RESolution]` on page 686

VBW

Sets the VBW value for this range.

For details on the VBW see [chapter 6.5.1.2, "Smoothing the Trace Using the Video Bandwidth"](#), on page 353.

Remote command:

`[SENSe:]LIST:RANGe<range>:BANDwidth:VIDeo` on page 686

Sweep Time Mode

Activates or deactivates the auto mode for the sweep time.

For details on the sweep time mode see [chapter 6.5.1.7, "How Long the Data is Measured: Sweep Time"](#), on page 356

Remote command:

`[SENSe:]LIST:RANGe<range>:SWEep:TIME:AUTO` on page 691

Sweep Time

Sets the sweep time value for the range.

For details on the sweep time see [chapter 6.5.1.7, "How Long the Data is Measured: Sweep Time"](#), on page 356

Remote command:

`[SENSe:]LIST:RANGe<range>:SWEep:TIME` on page 691

Detector

Sets the detector for the range.

For details refer to [chapter 7.3.1.1, "Mapping Samples to sweep Points with the Trace Detector"](#), on page 397.

Remote command:

`[SENSe:]LIST:RANGe<range>:DETector` on page 687

Ref. Level

Sets the reference level for the range.

For details on the reference level see [chapter 6.4.1.1, "Reference Level"](#), on page 342.

Remote command:

[\[SENSe:\]LIST:RANGe<range>:RLEVel](#) on page 691

RF Att. Mode

Activates or deactivates the auto mode for RF attenuation.

For details on attenuation see [chapter 6.4.1.2, "RF Attenuation"](#), on page 344.

Remote command:

[\[SENSe:\]LIST:RANGe<range>:INPut:ATTenuation:AUTO](#) on page 689

RF Attenuator

Sets the attenuation value for that range.

For details on attenuation see [chapter 6.4.1.2, "RF Attenuation"](#), on page 344.

Remote command:

[\[SENSe:\]LIST:RANGe<range>:INPut:ATTenuation](#) on page 689

Sweep Points

Sets the number of sweep points for the specified range.

For details on sweep points see [chapter 6.5.1.8, "How Much Data is Measured: Sweep Points and Sweep Count"](#), on page 356.

Remote command:

[\[SENSe:\]LIST:RANGe<range>:POINts](#) on page 690

Stop After Sweep

This command configures the sweep behavior.

"ON" The R&S FPS stops after one range is swept and continues only if you confirm (a message box is displayed).

"OFF" The R&S FPS sweeps all ranges in one go.

Remote command:

[\[SENSe:\]LIST:RANGe<range>:BREak](#) on page 686

Transducer

Sets a transducer for the specified range. You can only choose a transducer that fulfills the following conditions:

- The transducer overlaps or equals the span of the range.
- The x-axis is linear.
- The unit is dB.

For details on transducers see [chapter 9.2, "Basics on Transducer Factors"](#), on page 506.

Remote command:

[\[SENSe:\]LIST:RANGe<range>:TRANsducer](#) on page 692

Limit Check

Activates or deactivates the limit check for all ranges.

For details on limit checks see [chapter 5.7.3.2, "Limit Lines in Spurious Measurements"](#), on page 242.

"Absolute" Signal is checked against absolute limit values

"None" No limit check is performed.

Remote command:

[\[SENSe:\]LIST:RANGe<range>:LIMit:STATe](#) on page 690

[CALCulate<n>:LIMit<k>:FAIL?](#) on page 877

Abs Limit Start/Stop

Sets an absolute limit value at the start or stop frequency of the range [dBm].

Remote command:

[\[SENSe:\]LIST:RANGe<range>:LIMit:START](#) on page 690

[\[SENSe:\]LIST:RANGe<range>:LIMit:STOP](#) on page 690

Insert before/after Range

Inserts a new range to the left of the currently focused range (before) or to the right (after). The range numbers of the currently focused range and all higher ranges are increased accordingly. The maximum number of ranges is 30.

Delete Range

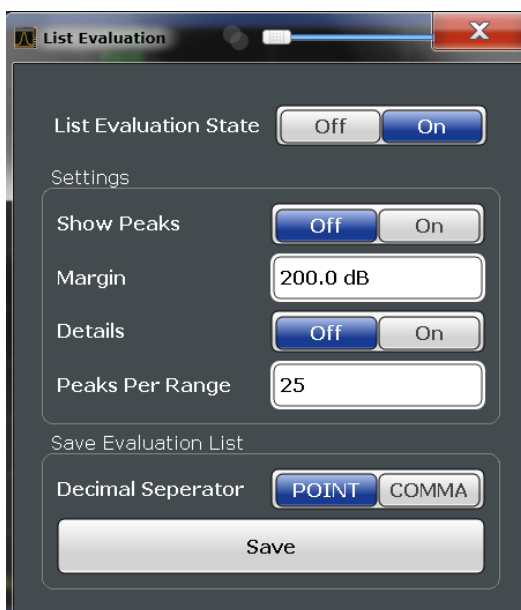
Deletes the currently focused range. The range numbers are updated accordingly.

5.7.4.2 Adjusting the X-Axis to the Range Definitions

The frequency axis of the measurement diagram can be adjusted automatically so that the span of all sweep list ranges corresponds to the displayed span. Thus, the x-axis range is set from the start frequency of the first sweep range to the stop frequency of the last sweep range.

5.7.4.3 List Evaluation

In the "List Evaluation" dialog box, which is displayed when you select the "Evaluations" button in the "Overview" or the "List Evaluation" softkey in the "Spurious Emissions" menu, you configure the contents and display of the result list.



List Evaluation State..... 248
 Show Peaks..... 248
 Margin..... 248
 Details..... 248
 Peaks per Range..... 249
 Saving the Evaluation List..... 249

List Evaluation State

Activates or deactivates the list evaluation.

Remote command:

[CALCulate<n>:ESpectrum:PEAKsearch:AUTO](#) on page 680

[TRACe<n>\[:DATA\]](#) on page 813

Show Peaks

If activated, all peaks that have been detected during an active list evaluation are marked with blue squares in the diagram.

Remote command:

[CALCulate<n>:ESpectrum:PEAKsearch:PSHow](#) on page 681

Margin

Although a margin functionality is not available for the limit check, a margin (threshold) for the peak values to be displayed in the evaluation list (and diagram, if activated) can be defined. Only peaks that exceed the margin value are displayed.

Remote command:

[CALCulate<n>:ESpectrum:PEAKsearch:MARGin](#) on page 680

Details

Configures how detailed the list in the Result Summary is.

On	Includes all detected peaks (up to a maximum defined by "Peaks per Range").
Off	Includes only one peak per range.

Remote command:

[CALCulate<n>:PEAKsearch:DEtails](#) on page 693

Peaks per Range

Defines the maximum number of peaks per range that are stored in the list. Once the selected number of peaks has been reached, the peak search is stopped in the current range and continued in the next range. The maximum value is 50.

Remote command:

[CALCulate<n>:PEAKsearch:SUBRanges](#) on page 694

Saving the Evaluation List

Exports the evaluation list of the Spurious Emissions measurement to an ASCII file for evaluation in an external application. If necessary, change the decimal separator for evaluation in other languages.

Define the file name and storage location in the file selection dialog box that is displayed when you select the "Save" function.

For details see ["How to Save the Spurious Emissions Evaluation List"](#) on page 250.

Remote command:

[MMEMory:STORe<n>:LIST](#) on page 903

[FORMat:DEXPort:DSEPARATOR](#) on page 881

5.7.5 How to Perform a Spurious Emissions Measurement

1. Press the MEAS key, then select the "Spurious Emissions" measurement.
2. Define the span of the signal to be monitored in the general span settings.
3. Select the "Overview" softkey, then select the "Spurious Setup" button.
The "Spurious Emissions" dialog box is displayed.
4. Split the frequency span of the measurement into ranges for signal parts with similar characteristics.
Define the required ranges in the "Sweep List" using the "Insert before Range" and "Insert after Range" buttons, which refer to the currently selected range.
5. Define the measurement parameters for each range as required.
6. Optionally, define a limit check.
 - a) Activate the limit check by setting "Limit Check" to "Absolute". The limit check is always activated or deactivated for all ranges simultaneously.
 - b) Define the limit line's start and stop values for each range of the signal. If a signal level higher than the defined limit is measured, the limit check fails, which may indicate a spurious emission.

7. Configure the peak detection during a Spurious Emissions measurement: select the "Evaluations" button in the "Overview".
 - To indicate the determined peaks in the display, activate the "Show Peaks" option.
 - To restrict peak detection, define a "Margin". Only peaks that exceed this value are detected.
 - To allow for more peaks per range to be detected than the default 1, increase the "Peaks Per Range" value and set "Details" to "On".
8. Start a sweep.

The determined powers and limit deviations for each range are indicated in the evaluation list. If activated, the peak power levels for each range are also indicated in the diagram.
9. To save the evaluation list, export the results to a file as described in ["How to Save the Spurious Emissions Evaluation List"](#) on page 250.

How to Save the Spurious Emissions Evaluation List

The evaluation list from a Spurious Emissions measurement can be saved to a file, which can be exported to another application for further analysis, for example.

1. Configure and perform an Spurious Emissions measurement as described in [chapter 5.7.5, "How to Perform a Spurious Emissions Measurement"](#), on page 249.
2. Select the "Evaluations" button in the "Overview".
3. If necessary, change the "Decimal Separator" to "COMMA" for evaluation in other languages.
4. Select the "Save" button.
5. In the file selection dialog box, select a storage location and file name for the result file.
6. Select the "Save" button.

The file with the specified name and the extension `.dat` is stored in the defined storage location.

5.7.6 Reference: ASCII Export File Format (Spurious)

The file has a header containing important parameters for scaling, several data sections containing the sweep settings per range, and a data section containing the peak list.

The header data is made up of three columns, separated by ';', with the syntax:
parameter name; numeric value; basic unit

File contents	Explanation
File header	
Type;FPS-13;	Model
Version;1.00;	Firmware version
Date;31.Mar 11;	Storage date of data set
Mode;ANALYZER; SPURIOUS;	Operating mode and measurement function
Center Freq;1325000000.000000;Hz	X-axis settings
Freq Offset;0.000000;Hz	
Span;26499982000.000000;Hz	
x-Axis;LIN;	
Start;9000.000000;Hz Stop;8000000000.000000;Hz	
Level Offset;0.000000;dB	Y-axis settings
Ref Position;100.000000;%	
y-Axis;LOG;	
Level Range;100.000000;dB	
Trace settings	
Trace Mode;CLR/WRITE;	
Sweep Count;1;	
TRACE 1:	
Trace Mode;CLR/WRITE;	
x-Unit;Hz;	
y-Unit;dBm;	
List evaluation settings	
Margin;6.000000;s	Peak List margin
PeaksPerRange;25;	Max. number of peaks per range to be detected
Values;3;	Number of detected peaks

File contents	Explanation
File data section	
0;9000;150000;1000;79500;-25.006643295288086;-12.006643295288086;PASS;	Measured peak values: <range number>; <start frequency>; <stop frequency>; <resolution bandwidth of range>; <frequency of peak>; <absolute power in dBm of peak>; <distance to the limit line in dB>; (positive value means above the limit) <limit fail (pass = 0, fail =1)>;
0;9000;150000;1000;101022.11126961483;-47.075111389160156;-34.075111389160156;PASS;	
0;9000;150000;1000;58380.171184022824;-47.079341888427734;-34.079341888427734;PASS;	

5.8 Statistical Measurements (APD, CCDF)

To measure the amplitude distribution, the R&S FPS has simple measurement functions to determine both the Amplitude Probability Distribution (APD) and the Complementary Cumulative Distribution Function (CCDF). Only one of the signal statistic functions can be switched on at a time.

- [About the Measurements](#)..... 252
- [Typical Applications](#)..... 253
- [APD and CCDF Results](#)..... 253
- [APD and CCDF Basics - Gated Triggering](#)..... 256
- [APD and CCDF Configuration](#)..... 257
- [How to Perform an APD or CCDF Measurement](#)..... 263
- [Examples](#)..... 264
- [Optimizing and Troubleshooting the Measurement](#)..... 267

5.8.1 About the Measurements

The probability of amplitude values can be measured with the Amplitude Probability Distribution function (APD). During a selectable measurement time all occurring amplitude values are assigned to an amplitude range. The number of amplitude values in the individual ranges is counted and the result is displayed as a histogram.

Alternatively, the Complementary Cumulative Distribution Function (CCDF) can be displayed. It shows the probability that the mean signal power amplitude will be exceeded in percent.

Only one of the signal statistic functions can be switched on at a time. When a statistic function is switched on, the R&S FPS is set into zero span mode automatically. The R&S FPS measures the statistics of the signal applied to the RF input with the defined analysis bandwidth. To avoid affecting the peak amplitudes the video bandwidth is automatically set to 10 times the analysis bandwidth. The sample detector is used for detecting the video voltage.

Statistic measurements on pulsed signals can be performed using a gated trigger. For details see [chapter 5.8.4, "APD and CCDF Basics - Gated Triggering"](#), on page 256.

5.8.2 Typical Applications

Digital modulated signals are similar to white noise within the transmit channel, but are different in their amplitude distribution. In order to transmit the modulated signal without distortion, all amplitudes of the signal have to be transmitted linearly from the output power amplifier. Most critical are the peak amplitude values. Degradation in transmit quality caused by a transmitter two port network is dependent on the amplitude of the peak values as well as on their probability.

If modulation types are used that do not have a constant envelope in zero span, the transmitter has to handle peak amplitudes that are greater than the average power. This includes all modulation types that involve amplitude modulation, QPSK for example. CDMA transmission modes in particular may have power peaks that are large compared to the average power.

For signals of this kind, the transmitter must provide large reserves for the peak power to prevent signal compression and thus an increase of the bit error rate at the receiver. The peak power or the crest factor of a signal is therefore an important transmitter design criterion. The crest factor is defined as the peak power to mean power ratio or, logarithmically, as the peak level minus the average level of the signal. To reduce power consumption and cut costs, transmitters are not designed for the largest power that could ever occur, but for a power that has a specified probability of being exceeded (e.g. 0.01 %).

The statistical functions provide information on such signal criteria.

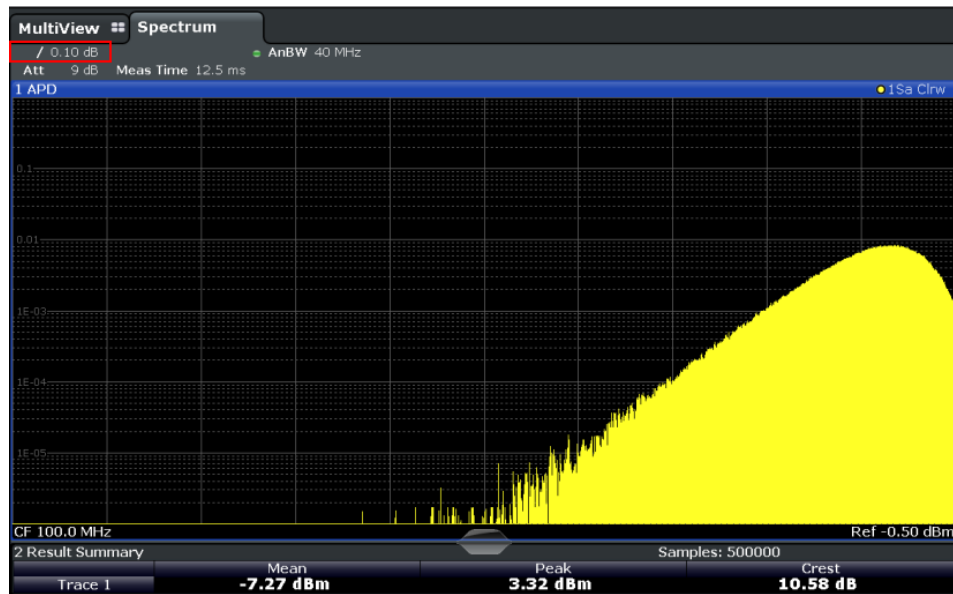
5.8.3 APD and CCDF Results

Amplitude Probability Distribution (APD)

As a result of the Amplitude Probability Distribution (APD) function, the probability of measured amplitude values is displayed. During a selectable measurement time all measured amplitude values are assigned to an amplitude range (*bin*). The number of amplitude values in the individual ranges is counted and the result is displayed as a histogram. Each bar of the histogram represents the percentage of measured amplitudes within the specific amplitude range. The x-axis represents the amplitude values and is scaled in absolute values (dBm).



The size of each amplitude range (bin) determines the resolution of the histogram and is indicated in the channel bar, for example / 0.10 dB. In this case, a single bar in the histogram represents an amplitude range of 0.10 dB.



In addition to the histogram, a result table is displayed containing the following information:

- Number of samples used for calculation
- For each displayed trace:
 - Mean amplitude
 - Peak amplitude
 - Crest factor

The crest factor is defined as the peak power to mean power ratio or, logarithmically, as the peak level minus the average level of the signal.

Complementary Cumulative Distribution Function (CCDF)

The Complementary Cumulative Distribution Function (CCDF) shows the probability that the mean signal power amplitude will be exceeded in percent. The level above the mean power is plotted along the x-axis of the graph. The origin of the axis corresponds to the mean power level. The probability that a level will be exceeded is plotted along the y-axis.



A red line indicates the ideal Gaussian distribution for the measured amplitude range.

The displayed amplitude range is indicated as "Mean Pwr + <x dB>"

In addition to the histogram, a result table is displayed containing the following information:

- Number of samples used for calculation
- For each displayed trace:

Mean	Mean power
Peak	Peak power
Crest	Crest factor (peak power – mean power)
10 %	Level values over 10 % above mean power
1 %	Level values over 1 % above mean power
0,1 %	Level values over 0,1 % above mean power
0,01 %	Level values over 0,01 % above mean power

Percent marker

In addition to the results for specific percentages in the table, a percent marker can be activated for a freely selectable percentage. This marker indicates how many level values are over <x> % above the mean power.



Percent marker

As all markers, the percent marker can be moved simply by selecting it with a finger or mouse cursor and dragging it to the desired position.

Diagram Scaling

The scaling for both the x-axis and y-axis of the statistics diagram can be configured. In particular, you can restrict the range of amplitudes to be evaluated and the probabilities to be displayed.

Remote commands:

`CALCulate<n>:STATistics:CCDF:X<t>?` on page 704

`CALCulate<n>:STATistics:RESult<t>?` on page 704

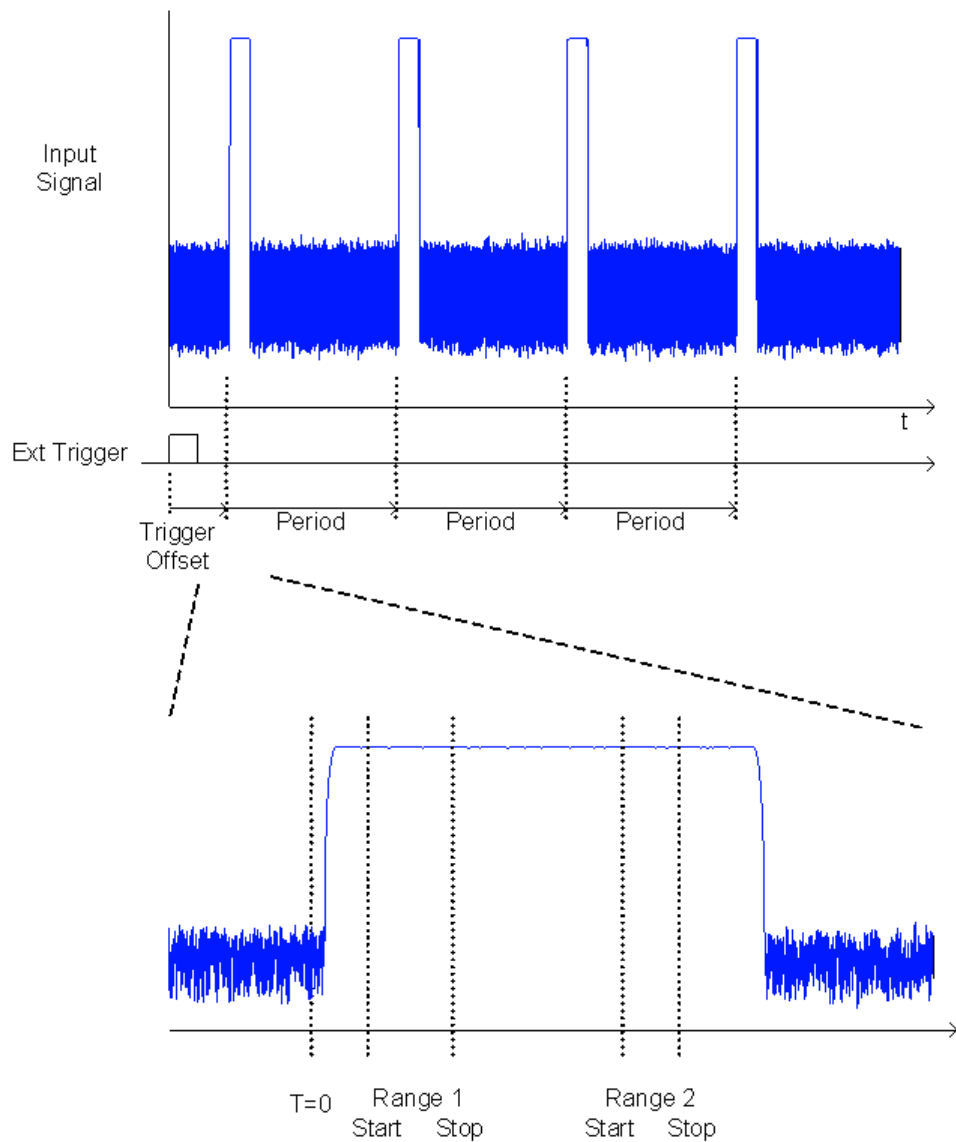
5.8.4 APD and CCDF Basics - Gated Triggering

Statistic measurements on pulsed signals can be performed using a gated trigger. An external frame trigger is required as a time (frame) reference.

The gate ranges define the part of the measured data taken into account for the statistics calculation. These ranges are defined relative to a reference point $T=0$. The gate interval is repeated for each period until the end of the capture buffer.

The reference point $T=0$ is defined by the external trigger event and the instrument's trigger offset.

For each trace you can define up to 3 separate ranges of a single period to be traced.



5.8.5 APD and CCDF Configuration

Configuration consists of the following settings:

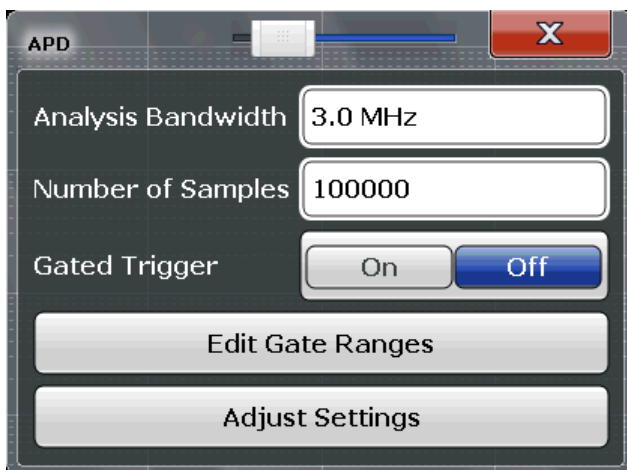
- [Basic Settings](#)..... 257
- [Gate Range Definition for APD and CCDF](#) 259
- [Scaling for Statistics Diagrams](#)..... 261

5.8.5.1 Basic Settings

APD measurements are selected via the "APD" button in the "Select Measurement" dialog box. CCDF measurements are selected via the "CCDF" button in the "Select Measurement" dialog box. The measurements are started immediately with the default settings. They can be configured via the MEAS CONFIG key or in the "APD/CCDF"

dialog boxes, which are displayed as a tab in the "Analysis" dialog box or when you select the "APD Config" softkey from the "APD" menu or the "CCDF Config" softkey from the "CCDF" menu.

The remote commands required to perform these tasks are described in [chapter 11.5.8, "Analyzing Statistics \(APD, CCDF\)"](#), on page 697.



Both dialog boxes are identical except for the "Percent Marker" setting, which is only available for CCDF measurements.

Percent Marker (CCDF only)	258
Analysis Bandwidth	258
Number of Samples	259
Gated Trigger	259
Edit Gate Ranges	259
Adjust Settings	259

Percent Marker (CCDF only)

Defines a probability value. Thus, the power which is exceeded with a given probability can be determined very easily. If marker 1 is deactivated, it is switched on automatically.

Remote command:

`CALCulate<n>:MARKer<m>:Y:PERCent` on page 698

Analysis Bandwidth

Defines the analysis bandwidth.

For correct measurement of the signal statistics, the analysis bandwidth has to be wider than the signal bandwidth in order to measure the peaks of the signal amplitude correctly. To avoid influencing the peak amplitudes, the video bandwidth is automatically set to 10 MHz. The sample detector is used for detecting the video voltage.

The calculated measurement time is displayed for reference only.

Remote command:

`[SENSe:]BANDwidth[:RESolution]` on page 747

Number of Samples

Defines the number of power measurements that are taken into account for the statistics.

For statistics measurements with the R&S FPS, the number of samples to be measured is defined instead of the sweep time. Since only statistically independent samples contribute to statistics, the sweep or measurement time is calculated automatically and displayed in the channel bar ("Meas Time"). The samples are statistically independent if the time difference is at least 1/RBW. The measurement time is, therefore, expressed as follows:

$$\text{Meas Time} = N_{\text{Samples}}/\text{RBW}$$

Remote command:

`CALCulate<n>:STATistics:NSAMples` on page 698

Gated Trigger

Activates and deactivates gating for statistics functions for the ACP and the CCDF measurements. If activated, the trigger source is changed to "External Trigger 1". The gate ranges are defined using the [Edit Gate Ranges](#) function.

Remote command:

`[SENSe:]SWEep:EGATe:TRACe<k>[:STATe<range>]` on page 700

Edit Gate Ranges

Opens a dialog box to configure up to 3 gate ranges for each trace. For details see [chapter 5.8.5.2, "Gate Range Definition for APD and CCDF"](#), on page 259.

Adjust Settings

Adjusts the level settings according to the measured difference between peak and minimum power for APD measurement or peak and mean power for CCDF measurement in order to obtain maximum power resolution. Adjusts the reference level to the current input signal.

Remote command:

`CALCulate<n>:STATistics:SCALE:AUTO ONCE` on page 702

5.8.5.2 Gate Range Definition for APD and CCDF

Gate ranges for gated triggering in statistical measurements can be configured in the "Gate Ranges" dialog box, which is displayed when you select the "Edit Gate Ranges" button in the "APD" or "CCDF" configuration dialog boxes.

For background information on defining gate ranges see [chapter 5.8.4, "APD and CCDF Basics - Gated Triggering"](#), on page 256.

The remote commands required to perform these tasks are described in [chapter 11.5.8.3, "Using Gate Ranges for Statistical Measurements"](#), on page 699.

	Trace 1	Trace 2	Trace 3	Trace 4	Trace 5	Trace 6
Comment						
Period	2 ms	2 ms	2 ms	2 ms	2 ms	2 ms
Range 1 Use	On	Off	Off	Off	Off	Off
Range 1 Start	0 s	0 s	0 s	0 s	0 s	0 s
Range 1 Stop	1 ms	1 ms	1 ms	1 ms	1 ms	1 ms
Range 2 Use	Off	Off	Off	Off	Off	Off
Range 2 Start	2 ms	2 ms	2 ms	2 ms	2 ms	2 ms
Range 2 Stop	3 ms	3 ms	3 ms	3 ms	3 ms	3 ms
Range 3 Use	Off	Off	Off	Off	Off	Off
Range 3 Start	4 ms	4 ms	4 ms	4 ms	4 ms	4 ms
Range 3 Stop	5 ms	5 ms	5 ms	5 ms	5 ms	5 ms

Up to three ranges can be defined for each of the six available traces.

[Comment](#).....260
[Period](#).....260
[Range <x> Use](#).....260
[Range <x> Start/Stop](#).....260

Comment

An optional comment can be defined for the gate range settings of each trace.

Remote command:

[SENSe:] SWEep:EGATe:TRACe<k>:COMMENT on page 699

Period

Length of the period to be traced. The period is the same for all traces. If you change the period for one trace, it is automatically changed for all traces.

Make sure the defined period is not longer than the total measurement time of the current measurement. Keep in mind that the measurement time depends on the bandwidth and the number of samples (see "Number of Samples" on page 259). The current measurement time is indicated as "Meas Time" in the channel bar.

Remote command:

[SENSe:] SWEep:EGATe:TRACe:PERiod on page 699

Range <x> Use

Activates tracing of the defined range during a gated measurement.

Remote command:

[SENSe:] SWEep:EGATe:TRACe<k>[:STATe<range>] on page 700

Range <x> Start/Stop

Defines the start and stop points of the range within the tracing period. Make sure the value for the stopping time is smaller than the length of the period.

Note: You can define the time values with a greater numerical resolution than is displayed; the values are only rounded for display.

Remote command:

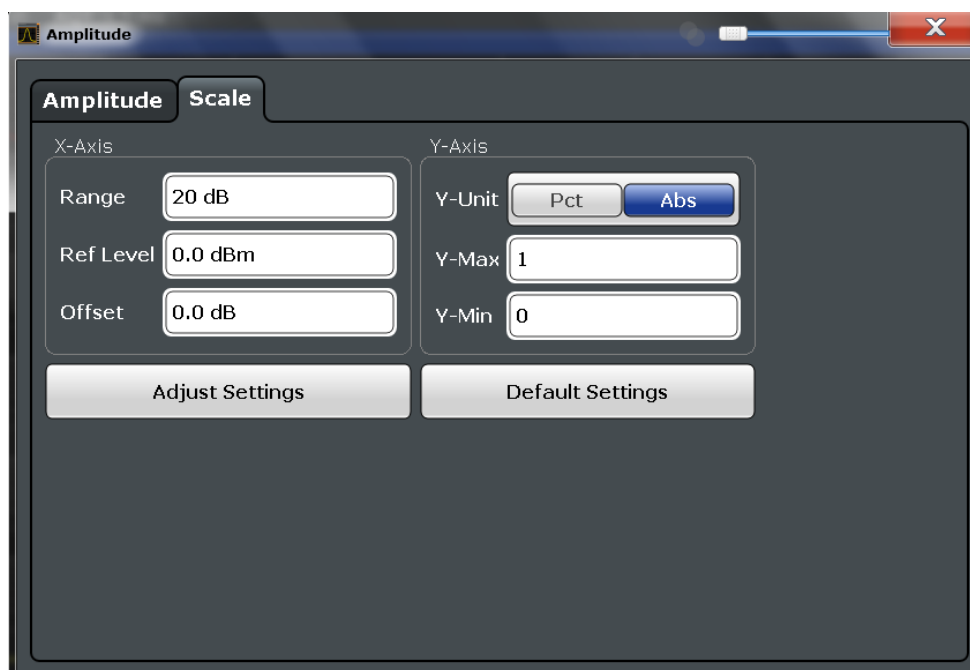
[SENSe:] SWEep:EGATe:TRACe<k>:START<range> on page 699

[SENSe:] SWEep:EGATe:TRACe<k>:STOP<range> on page 700

5.8.5.3 Scaling for Statistics Diagrams

The diagram scaling for statistical measurements can be configured in the "Scaling" dialog box, which is displayed when you select the AMPT key and then the "Scale Config" softkey.

The remote commands required to perform these tasks are described in [chapter 11.5.8.4, "Scaling the Diagram"](#), on page 701.



In statistical diagrams, the x-axis displays the signal level values (= y-axis in standard display), while the y-axis displays the probability of the values.

X-Axis.....	262
L Range.....	262
L Ref Level.....	262
L Shifting the Display (Offset).....	262
Y-Axis.....	262
L Y-Unit.....	262
L Y-Max / Y-Min.....	262
Default Settings.....	262
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X-Axis

Defines the scaling settings for signal level values.

Range ← X-Axis

Defines the level range in dB to be evaluated by the statistics measurement.

Remote command:

[CALCulate<n>:STATistics:SCALE:X:RANGe](#) on page 702

Ref Level ← X-Axis

Defines the reference level for the signal levels in the currently active unit (dBm, dBμV, etc).

For the APD function this value corresponds to the right diagram border. For the CCDF function there is no direct representation of this value on the diagram as the x-axis is scaled relatively to the measured mean power.

Remote command:

[CALCulate<n>:STATistics:SCALE:X:RLEVel](#) on page 702

Shifting the Display (Offset) ← X-Axis

Defines an arithmetic level offset. This offset is added to the measured level irrespective of the selected unit. The scaling of the x-axis is changed accordingly. The setting range is ±200 dB in 0.1 dB steps.

Remote command:

[DISPlay\[:WINDow<n>\]:TRACe<t>:Y\[:SCALE\]:RLEVel:OFFSet](#) on page 756

Y-Axis

Defines the scaling settings for the probability distribution.

Y-Unit ← Y-Axis

Defines the scaling type of the y-axis as either percentage or absolute. The default value is absolute scaling.

Remote command:

[CALCulate<n>:STATistics:SCALE:Y:UNIT](#) on page 703

Y-Max / Y-Min ← Y-Axis

Defines the upper (max) and lower (min) limit of the displayed probability range. Values on the y-axis are normalized which means that the maximum value is 1.0. The minimum value must be in the range:

$1E-9 < Y-Min < 0.1$

The distance between Y-max and Y-min must be at least one decade.

Remote command:

[CALCulate<n>:STATistics:SCALE:Y:UPPer](#) on page 703

[CALCulate<n>:STATistics:SCALE:Y:LOWer](#) on page 703

Default Settings

Resets the x- and y-axis scalings to their preset values.

x-axis ref level:	-10 dBm
x-axis range APD:	100 dB
x-axis range CCDF:	20 dB
y-axis upper limit:	1.0
y-axis lower limit:	1E-6

Remote command:

[CALCulate<n>:STATistics:PRESet](#) on page 701

Adjust Settings

Adjusts the level settings according to the measured difference between peak and minimum power for APD measurement or peak and mean power for CCDF measurement in order to obtain maximum power resolution. Adjusts the reference level to the current input signal.

Remote command:

[CALCulate<n>:STATistics:SCALE:AUTO ONCE](#) on page 702

5.8.6 How to Perform an APD or CCDF Measurement

To start a basic statistic measurement

1. Press the MEAS key, then select the "APD" or "CCDF" measurement.
2. Start a sweep.

As soon as the defined number of samples have been measured, the statistical evaluation is displayed.

To perform a statistic measurement using gate ranges

For pulsed signals, the transmission intervals should not be included in the statistical evaluation. Thus, you must define gate ranges to be included in the measurement.

1. Press the MEAS CONFIG key, then select the "APD Config" or "CCDF Config" softkey.
The "APD" or "CCDF" dialog box is displayed.
2. Select the "Edit Gate Ranges" button.
3. Define the time period for which the input signal is to be analyzed, for example the duration of 3 signal pulses.
4. For each active trace, define up to three ranges within the time period to be measured. In the example covering 3 pulses, you could define one range for each pulse.
 - a) Assuming the external trigger determines T=0 as the start of the first pulse, define the start time of range 1 at 0 s.

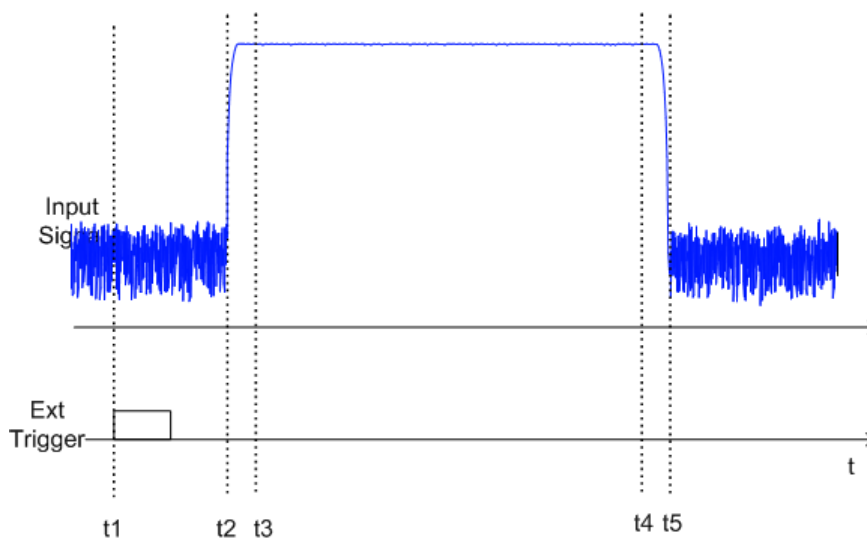
- b) Define the stop time of range 1 at the duration of the first pulse.
 - c) Activate range 1 by setting "Range 1 Use" to *On*.
 - d) Define the start time of range 2 as (duration of pulse 1 + duration of interval)
 - e) Define the stop time of range 2 as (start time of range 2 + duration of pulse 2)
 - f) Activate range 2 by setting "Range 2 Use" to *On*.
 - g) Define the third range in the same way.
5. Start a sweep.

As soon as the defined number of samples have been measured, the statistical evaluation is displayed. Only the signal levels within the pulse periods are considered.

5.8.7 Examples

5.8.7.1 Configuration Example: Gated Statistics

A statistics evaluation has to be done over the useful part of the signal between t_3 and t_4 . The period of the GSM signal is 4.61536 ms.



- t_1 : External positive trigger slope
- t_2 : Begin of burst (after 25 μs)
- t_3 : Begin of useful part, to be used for statistics (after 40 μs)
- t_4 : End of useful part, to be used for statistics (after 578 μs)
- t_5 : End of burst (after 602 μs)

The instrument has to be configured as follows:

Trigger Offset	$t_2 - t_1 = 25 \mu\text{s}$	now the gate ranges are relative to t_2
Range1 Start	$t_3 - t_2 = 15 \mu\text{s}$	start of range 1 relative to t_2
Range1 End	$t_4 - t_2 = 553 \mu\text{s}$	end of range 1 relative to t_2

5.8.7.2 Measurement Example – Measuring the APD and CCDF of White Noise Generated by the R&S FPS



Setting the RBW

When the amplitude distribution is measured, the analysis bandwidth must be set so that the complete spectrum of the signal to be measured falls within the bandwidth. This is the only way of ensuring that all the amplitudes will pass through the IF filter without being distorted. If the selected bandwidth is too small for a digitally modulated signal, the amplitude distribution at the output of the IF filter becomes a Gaussian distribution according to the central limit theorem and thus corresponds to a white noise signal. The true amplitude distribution of the signal therefore cannot be determined.

1. Preset the R&S FPS.
2. Set the reference level to -60 dBm .
The R&S FPS's intrinsic noise is displayed at the top of the screen.
3. Select the "APD" measurement function from the "Select Measurement" dialog box.
The R&S FPS sets the frequency span to 0 Hz and measures the amplitude probability distribution (APD). The number of uncorrelated level measurements used for the measurement is 100000. The mean power and the peak power are displayed in dBm. The crest factor (peak power – mean power) is output as well.

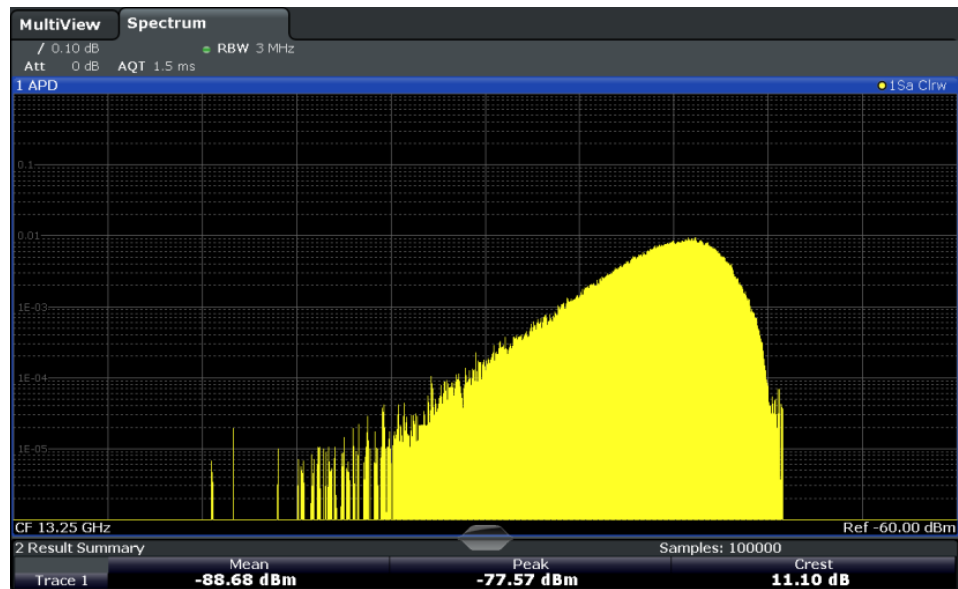


Fig. 5-39: Amplitude probability distribution of white noise

- Now select the "CCDF" measurement function from the "Select Measurement" dialog box.



Fig. 5-40: CCDF of white noise

The CCDF trace indicates the probability that a level will exceed the mean power. The level above the mean power is plotted along the x-axis of the graph. The origin of the axis corresponds to the mean power level. The probability that a level will be exceeded is plotted along the y-axis.

5.8.8 Optimizing and Troubleshooting the Measurement

If the results do not meet your expectations, try the following methods to optimize the measurement:

- Make sure the defined bandwidth is wide enough for the signal bandwidth of the device under test to be fully analyzed (see "[Analysis Bandwidth](#)" on page 258).
- If the complete signal is to be measured, increase the number of samples so that the resulting measurement time is longer than one period of a bursted signal.
- If only parts of the signal are to be examined, define a trigger source and a gate.

5.9 Time Domain Power Measurement

The R&S FPS can determine the power of a signal in the time domain using the Time Domain Power measurement function.

- [About the Measurement](#).....267
- [Time Domain Power Results](#).....267
- [Time Domain Power Basics - Range Definition Using Limit Lines](#).....268
- [Time Domain Power Configuration](#).....269
- [How to Measure Powers in the Time Domain](#).....270
- [Measurement Example](#).....270

5.9.1 About the Measurement

Using the Time Domain Power measurement function, the R&S FPS determines the power of the signal in zero span by summing up the power at the individual measurement points and dividing the result by the number of measurement points. Thus it is possible to measure the power of TDMA signals during transmission, for example, or during the muting phase. Both the mean power and the RMS power can be measured.

For this measurement, the sample detector is activated.

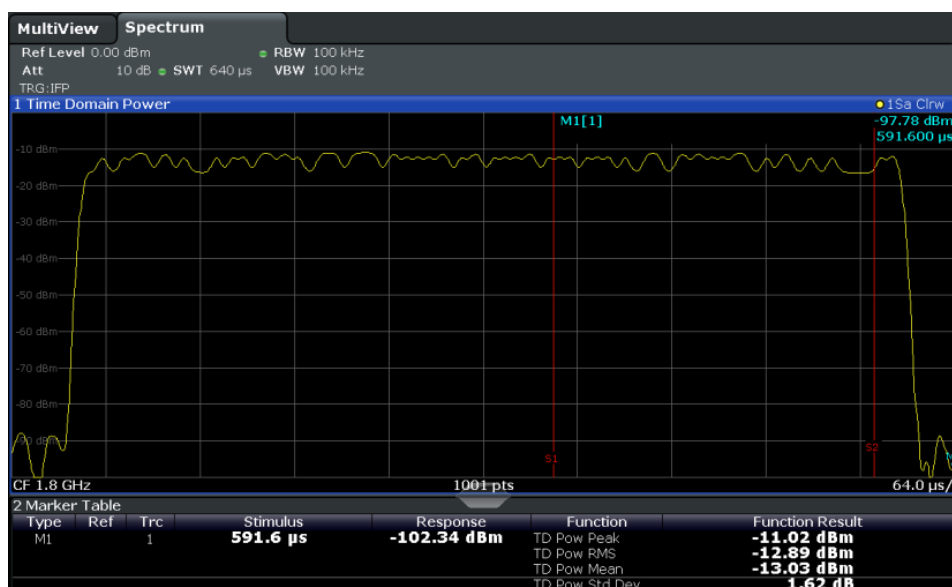
5.9.2 Time Domain Power Results

Several different power results can be determined simultaneously:

Mode	Description
Peak	Peak value from the points of the displayed trace or a segment thereof.
RMS	RMS value from the points of the displayed trace or a segment thereof.

Mode	Description
Mean	Mean value from the points of the displayed trace or a segment thereof. The linear mean value of the equivalent voltages is calculated. For example to measure the mean power during a GSM burst
Std Dev	The standard deviation of the measurement points from the mean value.

The result is displayed in the marker results, indicated by "Power" and the selected power mode, e.g. "RMS". The measured values are updated after each sweep or averaged over a user-defined number of sweeps (trace averaging).



The results can also be queried using the remote commands described in [chapter 11.5.9, "Measuring the Time Domain Power"](#), on page 706.

5.9.3 Time Domain Power Basics - Range Definition Using Limit Lines

The range of the measured signal to be evaluated for the power measurement can be restricted using limit lines. The left and right limit lines (S1, S2) define the evaluation range and are indicated by vertical red lines in the diagram. If activated, the power results are only calculated from the levels within the limit lines.

For example, if both the on and off phase of a burst signal are displayed, the measurement range can be limited to the transmission or to the muting phase. The ratio between signal and noise power of a TDMA signal for instance can be measured by using a measurement as a reference value and then varying the measurement range.



In order to get stable measurement results for a limited evaluation range, usually a trigger is required.

5.9.4 Time Domain Power Configuration

Time Domain Power measurements are selected via the "Time Domain Power" button in the "Select Measurement" dialog box. The measurement is started immediately with the default settings. It can be configured via the MEAS CONFIG key or in the "Time Domain Power" dialog box, which is displayed as a tab in the "Analysis" dialog box or when you select the "Time Dom Power Config" softkey from the "Time Dom Pwr" menu.

The remote commands required to perform these tasks are described in [chapter 11.5.9, "Measuring the Time Domain Power"](#), on page 706.

Results	269
Limit State	269
Left Limit / Right Limit	270

Results

Activates the power results to be evaluated from the displayed trace or a limited area of the trace.

"Peak"	Peak power over several measurements (uses trace averaging, Max Hold)
"RMS"	RMS value from the points of the displayed trace or a segment thereof.
"Mean"	Mean value from the points of the displayed trace or a segment thereof. The linear mean value of the equivalent voltages is calculated.
"Std Dev"	The standard deviation of the measurement points from the mean value. The measurement of the mean power is automatically switched on at the same time.

Remote command:

`CALCulate<n>:MARKer<m>:FUNCTION:SUMMARY:PPEak[:STATe]` on page 709
`CALCulate<n>:MARKer<m>:FUNCTION:SUMMARY:PPEak:RESult?` on page 711
`CALCulate<n>:MARKer<m>:FUNCTION:SUMMARY:RMS[:STATe]` on page 709
`CALCulate<n>:MARKer<m>:FUNCTION:SUMMARY:RMS:RESult?` on page 712
`CALCulate<n>:MARKer<m>:FUNCTION:SUMMARY:MEAN[:STATe]` on page 708
`CALCulate<n>:MARKer<m>:FUNCTION:SUMMARY:MEAN:RESult?` on page 710

Limit State

Switches the limitation of the evaluation range on or off. Default setting is off.

If deactivated, the entire sweep time is evaluated. If switched on, the evaluation range is defined by the left and right limit. If only one limit is set, it corresponds to the left limit and the right limit is defined by the stop frequency. If the second limit is also set, it defines the right limit.

Remote command:

`CALCulate<n>:MARKer<m>:X:SLIMits[:STATe]` on page 825

Left Limit / Right Limit

Defines a power level limit for line S1 (left) or S2 (right).

Remote command:

[CALCulate<n>:MARKer<m>:X:SLIMits:LEFT](#) on page 826

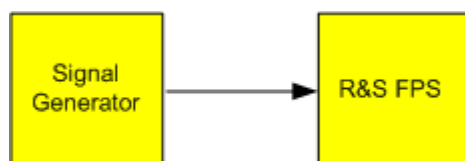
[CALCulate<n>:MARKer<m>:X:SLIMits:RIGHT](#) on page 826

5.9.5 How to Measure Powers in the Time Domain**To measure the power in the time domain**

1. Select the "Time Domain Power" measurement function from the "Select Measurement" dialog box.
2. Select the type of power measurement results to be determined by selecting the corresponding softkeys.
3. To restrict the power evaluation range, define limits:
 - a) Select the "Time Dom Power Config" softkey to display the "Time Domain Power" configuration dialog box.
 - b) Switch on the limits by setting the "Limit State" to "On".
The limit lines S1 and S2 are displayed.
 - c) Define the left limit (limit line S1), the right limit (S2), or both.
4. Start a sweep.
The measured powers are displayed in the marker results.

5.9.6 Measurement Example

This measurement example demonstrates the time domain power calculation for a GSM burst.

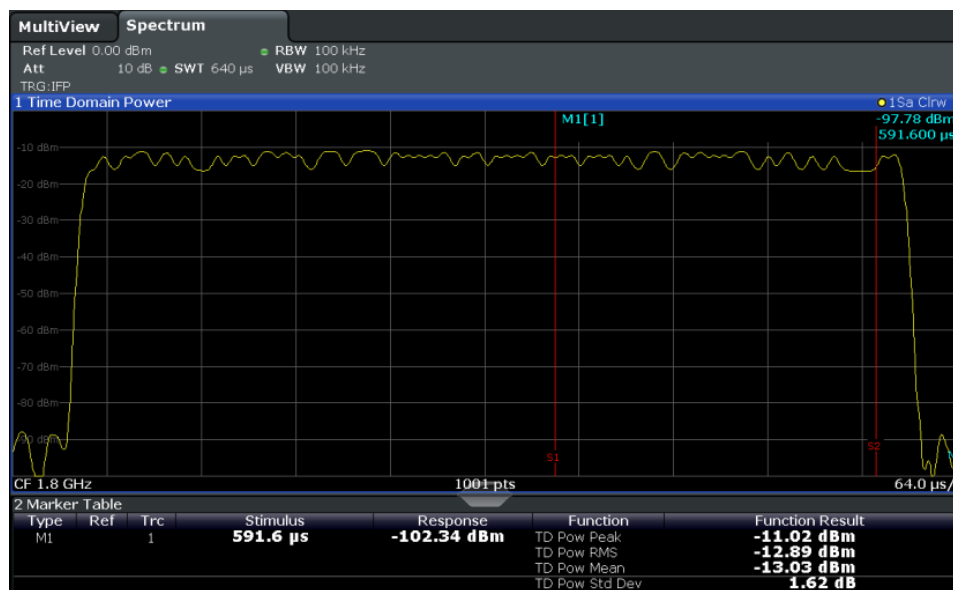
Test setup:**Signal generator settings (e.g. R&S FPS SMW):**

Frequency:	1.8 GHz
Level:	-10 dBm
Modulation:	GSM/EDGE

Procedure:

1. Preset the R&S FPS.
2. Set the center frequency to *1.8 GHz*.
3. Set the RBW to *100 kHz*.
4. Set the sweep time to *640 μs*.
5. Set the trigger source to "IF Power".
6. Define a trigger offset of *-50 μs*.
7. Select the "Time Domain Power" measurement function from the "Select Measurement" dialog box.
8. In the Time Domain Power configuration dialog box, set all four results to "ON".
9. Set the "Limit State" to "ON".
10. Define the left limit at *326 μs* and the right limit at *538 μs*.
This range corresponds to the useful part of the GSM burst.

The mean power of the useful part of the GSM burst is calculated to be *-13 dBm*.



5.10 Harmonic Distortion Measurement

The harmonics and their distortion can be measured using the "Harmonic Distortion" function.

• About the Measurement	272
• Harmonic Distortion Basics	272
• Harmonic Distortion Results	275
• Harmonic Distortion Configuration	275
• How to Determine the Harmonic Distortion	277

5.10.1 About the Measurement

With this measurement it is possible to measure the harmonics easily, for example from a VCO. In addition, the total harmonic distortion (THD) is calculated.

For measurements in the frequency domain, the Harmonic Distortion measurement starts with an automatic search for the first harmonic (= peak) within the set frequency range. The center frequency is set to this frequency and the reference level is adjusted accordingly.

For measurements in zero span, the center frequency remains unchanged.

The Harmonic Distortion measurement then performs zero span sweeps at the center frequency and at each harmonic, i.e. at frequencies that are a multiple of the center frequency.

As a result, the zero span sweeps on all harmonics are shown, as well as the RMS values and the total harmonic distortion (THD).

5.10.2 Harmonic Distortion Basics

Measuring the harmonics of a signal is a frequent problem which can be solved best using a signal analyzer. In general, every signal contains harmonics. Harmonics are generated by nonlinear characteristics, which add frequencies to a pure sinewave. They can often be reduced by low pass filters. Since the signal analyzer itself has a nonlinear characteristic, for example in its first mixer, measures must be taken to ensure that harmonics produced in the signal analyzer do not cause spurious results. If necessary, the fundamental wave must be attenuated selectively with respect to the other harmonics with a high pass filter. Harmonics are particularly critical regarding high-power transmitters such as transceivers because large harmonics can interfere with other radio services.

Harmonic distortion can be determined as the level of the individual components, or as the root mean square of all components together, the total harmonic distortion (THD). The THD is set in relation to the power of the fundamental frequency (= center frequency).

Obtainable dynamic range

When harmonics are being measured, the obtainable dynamic range depends on the second harmonic intercept of the signal analyzer. The second harmonic intercept is the virtual input level at the RF input mixer at which the level of the 2nd harmonic becomes equal to the level of the fundamental wave. In practice, however, applying a level of this magnitude would damage the mixer. Nevertheless the available dynamic range for

measuring the harmonic distance of a DUT can be calculated relatively easily using the second harmonic intercept.

As shown in figure 5-41, the level of the 2nd harmonic drops by 20 dB if the level of the fundamental wave is reduced by 10 dB.

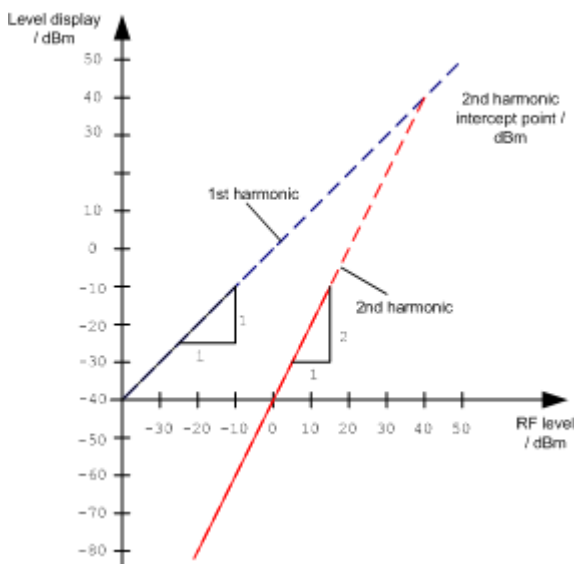


Fig. 5-41: Extrapolation of the 1st and 2nd harmonics to the 2nd harmonic intercept at 40 dBm

The following formula for the obtainable harmonic distortion d_2 in dB is derived from the straight-line equations and the given intercept point:

$$d_2 = \text{S.H.I} - P_1 \quad (1)$$

where:

d_2	=	harmonic distortion
S.H.I.	=	second harmonic intercept
P_1	=	mixer level/dBm



The mixer level is the RF level applied to the RF input minus the set RF attenuation.

The formula for the internally generated level P_1 at the 2nd harmonic in dBm is:

$$P_1 = 2 * P_i - \text{S.H.I.} \quad (2)$$

The lower measurement limit for the harmonic is the noise floor of the signal analyzer. The harmonic of the measured DUT should – if sufficiently averaged by means of a video filter – be at least 4 dB above the noise floor so that the measurement error due to the input noise is less than 1 dB.

Rules for measuring high harmonic ratios

The following rules for measuring high harmonic ratios can be derived:

- Select the smallest possible IF bandwidth for a minimal noise floor.
- Select an RF attenuation which is high enough to measure the harmonic ratio only.

The maximum harmonic distortion is obtained if the level of the harmonic equals the intrinsic noise level of the receiver. The level applied to the mixer, according to (2), is:

$$P_1 = \frac{P_{noise} / dBm + IP2}{2}$$

At a resolution bandwidth of 10 Hz (noise level -143 dBm, S.H.I. = 40 dBm), the optimum mixer level is - 51.5 dBm. According to (1) a maximum measurable harmonic distortion of 91.5 dB minus a minimum S/N ratio of 4 dB is obtained.



Detecting the origin of harmonics

If the harmonic emerges from noise sufficiently (approx. >15 dB), it is easy to check (by changing the RF attenuation) whether the harmonics originate from the DUT or are generated internally by the signal analyzer. If a harmonic originates from the DUT, its level remains constant if the RF attenuation is increased by 10 dB. Only the displayed noise is increased by 10 dB due to the additional attenuation. If the harmonic is exclusively generated by the signal analyzer, the level of the harmonic is reduced by 20 dB or is lost in noise. If both – the DUT and the signal analyzer – contribute to the harmonic, the reduction in the harmonic level is correspondingly smaller.

High-sensitivity harmonics measurements

If harmonics have very small levels, the resolution bandwidth required to measure them must be reduced considerably. The sweep time is, therefore, also increased considerably. In this case, the measurement of individual harmonics is carried out with the R&S FPS set to a small span. Only the frequency range around the harmonics will then be measured with a small resolution bandwidth.

Required measurement time

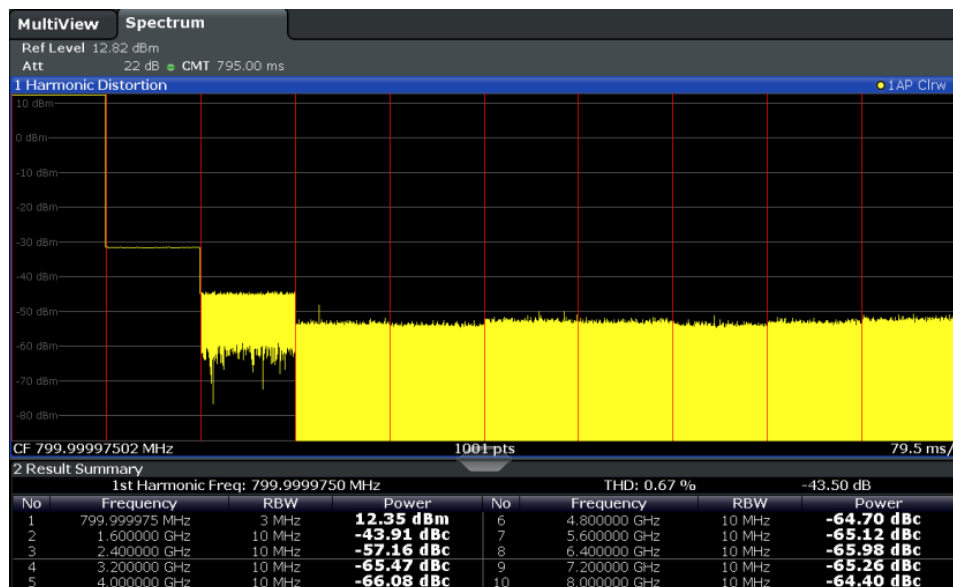
During the harmonics measurement, zero span sweeps are performed at the center frequency and at each harmonic. The duration of each sweep ("Harmonic Sweep Time", **SWT**) and the "Number of Harmonics" (n) are defined in the "Harmonic Distortion" configuration dialog box. Thus, the required measurement time for the harmonic distortion measurement (*Cumulated Measurement Time*, **CMT**) is:

$$CMT = n * SWT$$

The required measurement time is indicated as "CMT" in the channel bar.

5.10.3 Harmonic Distortion Results

As a result of the harmonics distortion measurement, the zero span sweeps of all detected harmonics are shown in the diagram, separated by red display lines. This provides a very good overview of the measurement.



In addition, a result table is displayed providing the following information:

- First harmonic frequency
- THD (total harmonic distortion), relative and absolute values
- For each detected harmonic:
 - Frequency
 - RBW
 - Power

Remote commands

The results can also be queried using remote commands.

The first harmonic frequency can be read out via the general center frequency command `[SENSE:]FREQUENCY:CENTer` on page 742.

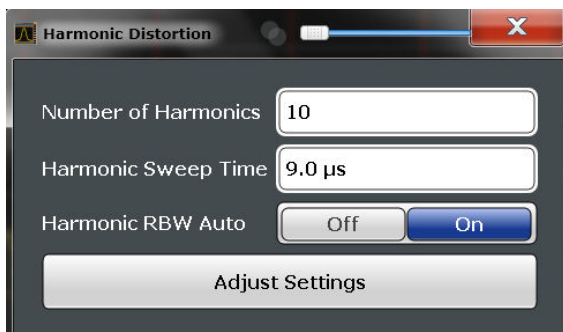
THD: `CALCulate<n>:MARKer<m>:FUNCTION:HARMonics:DISTortion?`
on page 717

List of harmonics: `CALCulate<n>:MARKer<m>:FUNCTION:HARMonics:LIST?`
on page 717

5.10.4 Harmonic Distortion Configuration

Harmonic Distortion measurements are selected via the "Harmonic Distortion" button in the "Select Measurement" dialog box. The measurement is started immediately with the default settings. It can be configured via the MEAS CONFIG key or in the "Har-

monic Distortion" dialog box, which is displayed as a tab in the "Analysis" dialog box or when you select the "Harmonic Distortion Config" softkey from the "Harm Dist" menu.



The remote commands required to perform these tasks are described in [chapter 11.5.10, "Measuring the Harmonic Distortion"](#), on page 715.

No. of Harmonics	276
Harmonic Sweep Time	276
Harmonic RBW Auto	276
Adjust Settings	277

No. of Harmonics

Defines the number of harmonics to be measured. The range is from 1 to 26. Default is 10.

Remote command:

[CALCulate<n>:MARKer<m>:FUNCTION:HARMonics:NHARmonics](#) on page 716

Harmonic Sweep Time

Defines the sweep time for the zero span measurement on each harmonic frequency. This setting is identical to the normal sweep time for zero span, see also ["Sweep Time"](#) on page 359.

Remote command:

[\[SENSe:\]SWEep:TIME:AUTO](#) on page 753

Harmonic RBW Auto

Enables/disables the automatic adjustment of the resolution bandwidth for Normal (3dB) (Gaussian) and 5-Pole filter types. The automatic adjustment is carried out according to:

$$"RBW_n = RBW_1 * n"$$

If RBW_n is not available, the next higher value is used.

Remote command:

[CALCulate<n>:MARKer<m>:FUNCTION:HARMonics:BANDwidth:AUTO](#)
on page 716

Adjust Settings

If harmonic measurement was performed in the frequency domain, a new peak search is started in the frequency range that was set before starting the harmonic measurement. The center frequency is set to this frequency and the reference level is adjusted accordingly.

If harmonic measurement was performed in the time domain, this function adjusts the reference level only.

Remote command:

`CALCulate<n>:MARKer<m>:FUNction:HARMonics:PRESet` on page 716

5.10.5 How to Determine the Harmonic Distortion

In [chapter 7.4.5, "Measurement Example: Measuring Harmonics Using Marker Functions"](#), on page 462, measuring harmonics was described using marker functions. This task can be performed much simpler using the Harmonic Distortion measurement, as described in the following procedure.

1. Select the "Harmonic Distortion" measurement function from the "Select Measurement" dialog box.
2. Define the number of harmonics to be determined using the "No. of Harmonics" softkey.
3. Perform a sweep.
The trace for the determined harmonics are displayed in the diagram, separated by red display lines. The measured power for each harmonic in relation to the fundamental is indicated in the result table.
4. If the signal changes significantly during or after the harmonics measurement, use the "Adjust Settings" function to adjust the settings automatically and restart the measurement.

5.11 Third Order Intercept (TOI) Measurement

The third order intercept point of the R&S FPS can be determined if a two-tone signal with equal carrier levels is applied to the input.

- [About the TOI Measurement](#).....278
- [TOI Basics](#).....278
- [TOI Results](#).....282
- [TOI Configuration](#).....283
- [How to Determine the Third Order Intercept](#).....284
- [Measurement Example – Measuring the R&S FPS's Intrinsic Intermodulation](#).... 285

5.11.1 About the TOI Measurement

If several signals are applied to a transmission two-port device with nonlinear characteristic, intermodulation products appear at its output at the sums and differences of the signals. The nonlinear characteristic produces harmonics of the useful signals which intermodulate at the characteristic. The intermodulation products of lower order have a special effect since their level is largest and they are near the useful signals. The intermodulation product of third order causes the highest interference. It is the intermodulation product generated from one of the useful signals and the 2nd harmonic of the second useful signal in case of two-tone modulation.

In order to measure the third order intercept point (TOI), a two-tone signal with equal carrier levels is expected at the R&S FPS input. Marker 1 and marker 2 (both normal markers) are set to the maximum of the two signals. Marker 3 and marker 4 are placed on the intermodulation products.

The R&S FPS calculates the third order intercept point from the level difference between the first 2 markers and the markers 3 and 4 and displays it in the marker field.

5.11.2 TOI Basics

If several signals are applied to a transmission two-port device with nonlinear characteristic, intermodulation products appear at its output at the sums and differences of the signals. The nonlinear characteristic produces harmonics of the useful signals which intermodulate at the characteristic.

The frequencies of the intermodulation products are above and below the useful signals. The [figure 5-42](#) shows intermodulation products P_{S1} and P_{S2} generated by the two useful signals P_{U1} and P_{U2} .

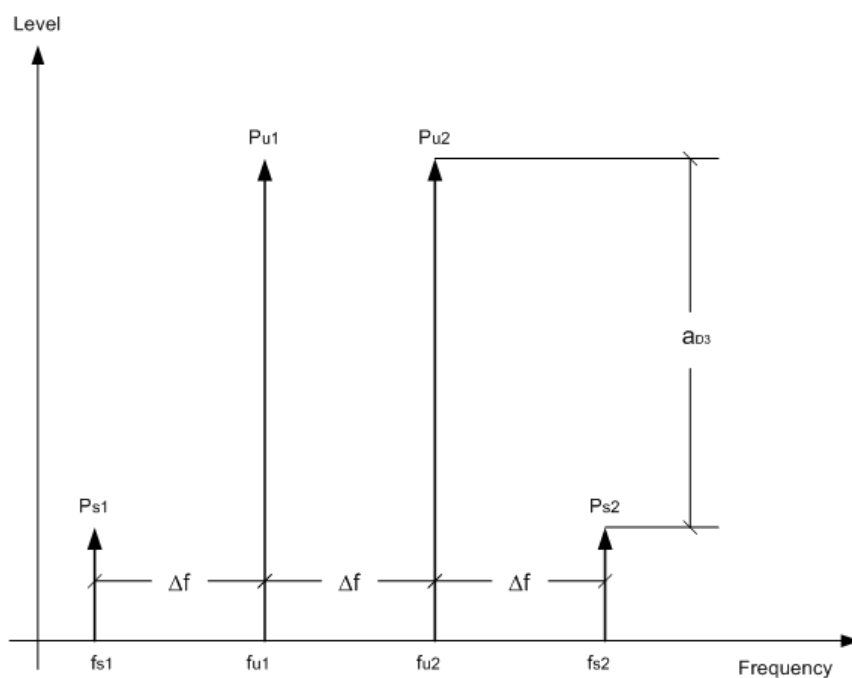


Fig. 5-42: Intermodulation products P_{s1} and P_{s2}

The intermodulation product at f_{i2} is generated by mixing the 2nd harmonic of useful signal P_{u2} and signal P_{u1} .

The intermodulation product at f_{i1} is generated by mixing the 2nd harmonic of useful signal P_{u1} and signal P_{u2} .

$$f_{i1} = 2 \times f_{u1} - f_{u2} \quad (1)$$

$$f_{i2} = 2 \times f_{u2} - f_{u1} \quad (2)$$

Dependency on level of useful signals

The level of the intermodulation products depends on the level of the useful signals. If the two useful signals are increased by 1 dB, the level of the intermodulation products increases by 3 dB, which means that the spacing a_{D3} between intermodulation signals and useful signals is reduced by 2 dB. This is illustrated in [figure 5-43](#).

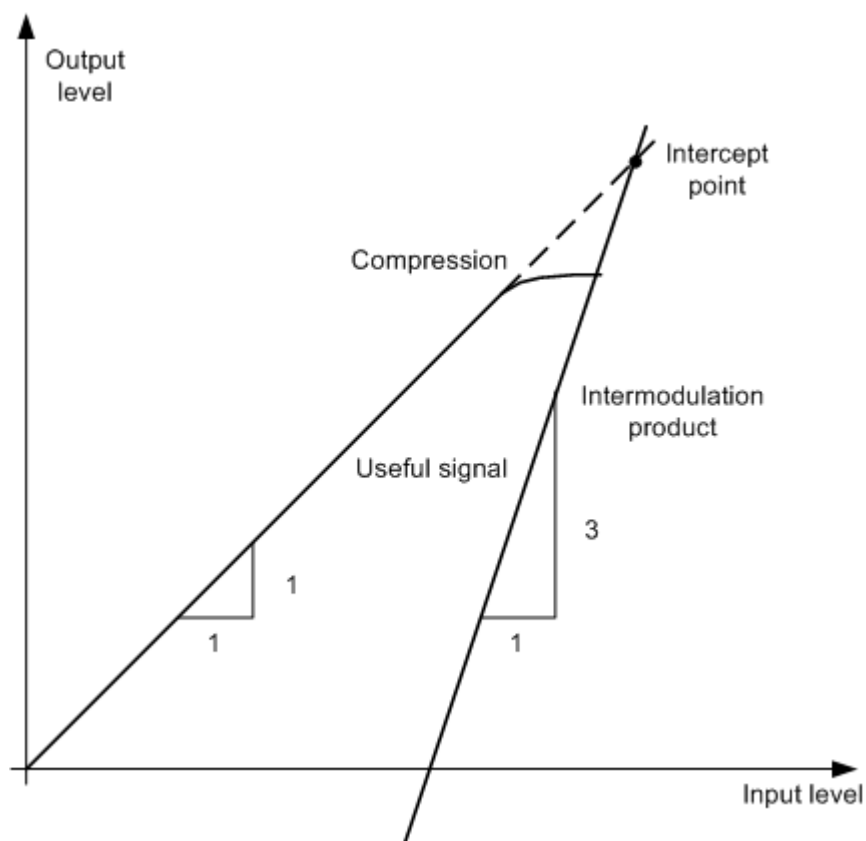


Fig. 5-43: Dependency of intermodulation products on level of useful signals

The useful signals at the two-port output increase proportionally with the input level as long as the two-port is in the linear range. A level change of 1 dB at the input causes a level change of 1 dB at the output. Beyond a certain input level, the two-port goes into compression and the output level stops increasing. The intermodulation products of the third order increase three times as quickly as the useful signals. The intercept point is the fictitious level where the two lines intersect. It cannot be measured directly since the useful level is previously limited by the maximum two-port output power.

Calculation method

However, the intercept point can be calculated from the known line slopes and the measured spacing a_{D3} at a given level according to the following formula:

$$IP3 = \frac{a_{D3}}{2} + P_N$$

The third order intercept point (TOI), for example, is calculated for an intermodulation of 60 dB and an input level P_U of -20 dBm according to the following formula:

$$IP3 = \frac{60}{2} + (-20dBm) = 10dBm$$

Intermodulation-free dynamic range

The "Intermodulation-free dynamic range", i.e. the level range in which no internal intermodulation products are generated if two-tone signals are measured, is determined by the third order intercept point, the phase noise and the thermal noise of the signal analyzer. At high signal levels, the range is determined by intermodulation products. At low signal levels, intermodulation products disappear below the noise floor, i.e. the noise floor and the phase noise of the signal analyzer determine the range. The noise floor and the phase noise depend on the resolution bandwidth that has been selected. At the smallest resolution bandwidth, the noise floor and phase noise are at a minimum and so the maximum range is obtained. However, a large increase in sweep time is required for small resolution bandwidths. It is therefore best to select the largest resolution bandwidth possible to obtain the range that is required. Since phase noise decreases as the carrier-offset increases, its influence decreases with increasing frequency offset from the useful signals.

The following diagrams illustrate the intermodulation-free dynamic range as a function of the selected bandwidth and of the level at the input mixer (= signal level – set RF attenuation) at different useful signal offsets.

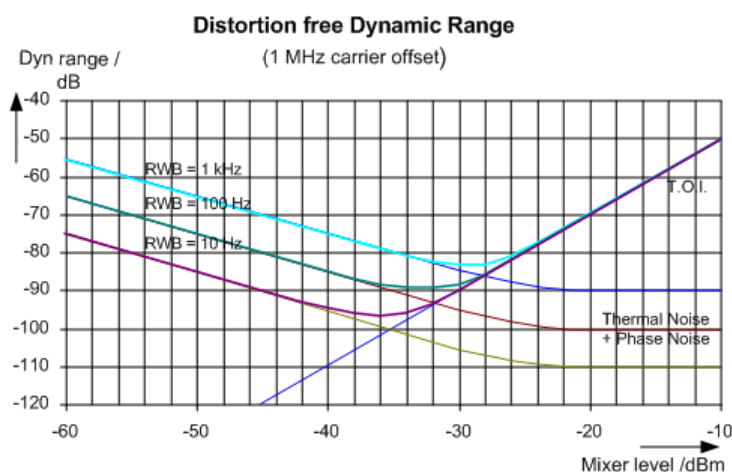


Fig. 5-44: Intermodulation-free range as a function of level at the input mixer and the set resolution bandwidth

(Useful signal offset = 1 MHz, DANL = -145 dBm/Hz, TOI = 15 dBm; typical values at 2 GHz)

The optimum mixer level, i.e. the level at which the intermodulation distance is at its maximum, depends on the bandwidth. At a resolution bandwidth of 10 Hz, it is approx. -35 dBm and at 1 kHz increases to approx. -30 dBm.

Phase noise has a considerable influence on the intermodulation-free range at carrier offsets between 10 and 100 kHz (see [figure 5-45](#)). At greater bandwidths, the influence of the phase noise is greater than it would be with small bandwidths. The optimum mixer level at the bandwidths under consideration becomes almost independent of bandwidth and is approx. -40 dBm.

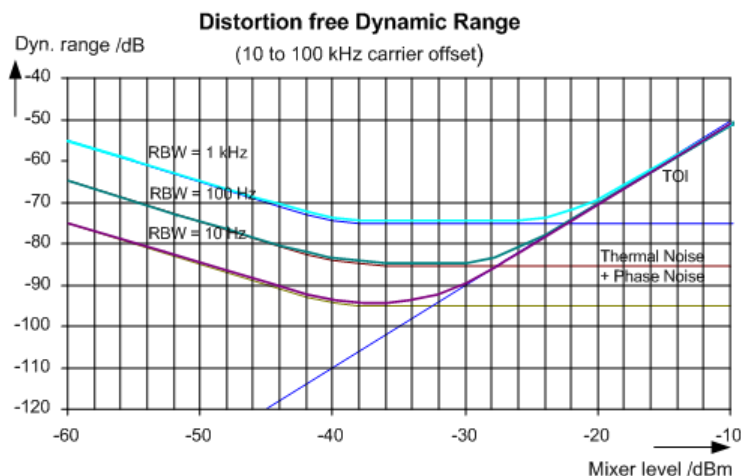


Fig. 5-45: Intermodulation-free dynamic range as a function of level at the input mixer and of the selected resolution bandwidth

(Useful signal offset = 10 to 100 kHz, DANL = -145 dBm/Hz, TOI = 15 dBm; typical values at 2 GHz).



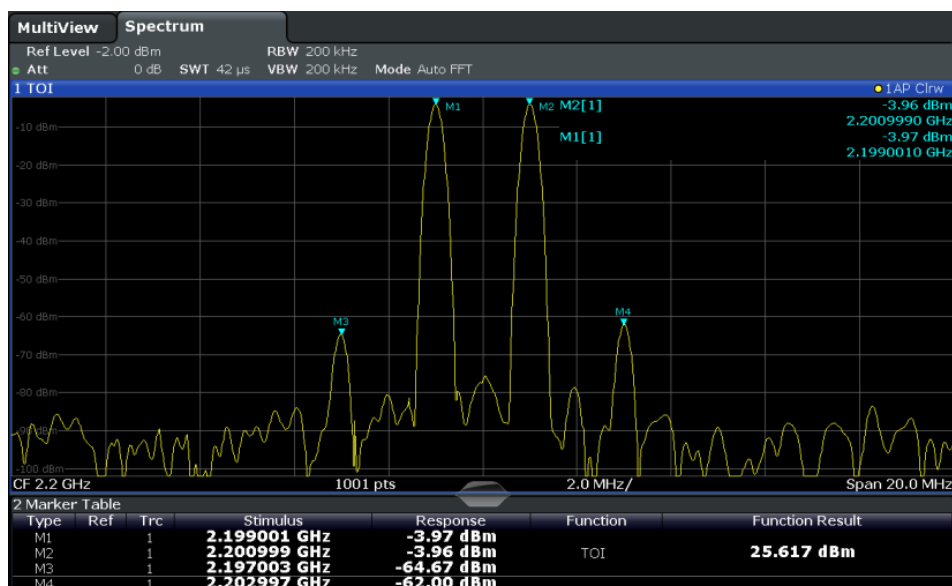
If the intermodulation products of a DUT with a very high dynamic range are to be measured and the resolution bandwidth to be used is therefore very small, it is best to measure the levels of the useful signals and those of the intermodulation products separately using a small span. The measurement time will be reduced, in particular if the offset of the useful signals is large. To find signals reliably when frequency span is small, it is best to synchronize the signal sources and the R&S FPS.

5.11.3 TOI Results

As a result of the TOI measurement, the following values are displayed in the marker area of the diagram:

Label	Description
TOI	Third-order intercept point
M1	Maximum of first useful signal
M2	Maximum of second useful signal
M3	First intermodulation product
M4	Second intermodulation product

Third Order Intercept (TOI) Measurement

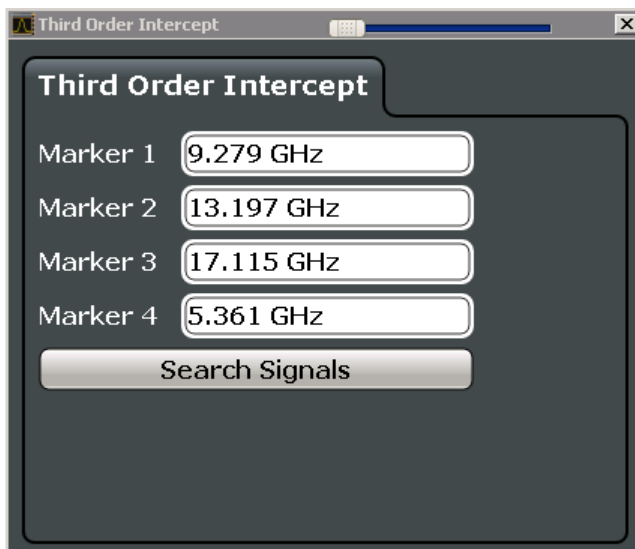


Remote command

The TOI can also be queried using the remote command `CALCulate<n>:MARKer<m>:FUNction:TOI:RESult?` on page 719.

5.11.4 TOI Configuration

Third Order Intercept (TOI) measurements are selected via the "Third Order Intercept" button in the "Select Measurement" dialog box. The measurement is started immediately with the default settings. It can be configured via the MEAS CONFIG key or in the "Third Order Intercept" dialog box, which is displayed as a tab in the "Analysis" dialog box, or when you select the "TOI Config" softkey from the "TOI" menu.



The remote commands required to perform these tasks are described in [chapter 11.5.11, "Measuring the Third Order Intercept Point"](#), on page 718.

Marker 1/2/3/4	284
Search Signals	284

Marker 1/2/3/4

Indicates the detected characteristic values as determined by the TOI measurement (see [chapter 5.11.3, "TOI Results"](#), on page 282).

The marker positions can be edited; the TOI is then recalculated according to the new marker values.

To reset all marker positions automatically, use the [Search Signals](#) function.

Remote command:

[CALCulate<n>:MARKer<m>:X](#) on page 823

[CALCulate<n>:DELTaMarker<m>:X](#) on page 822

[CALCulate<n>:DELTaMarker<m>:X:RELative?](#) on page 833

Search Signals

Performs a new search on the input signals and recalculates the TOI according to the measured values.

Remote command:

[CALCulate<n>:MARKer<m>:FUNCTION:TOI:SEARChsignal ONCE](#) on page 719

5.11.5 How to Determine the Third Order Intercept

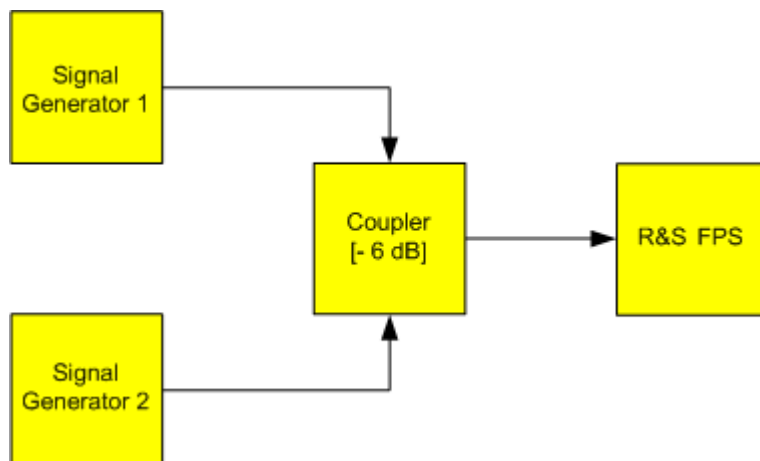


The precise TOI for the R&S FPS in relation to the input signals is provided in the data sheet.

1. Apply a two-tone signal with equal carrier levels to the R&S FPS input.
2. On the R&S FPS, press the MEAS key.
3. Select the "Third Order Intercept" measurement function from the "Select Measurement" dialog box.
The calculated TOI is indicated in the marker information. The markers required for calculation are displayed in the marker table.
4. If the signal changes significantly during or after the TOI measurement, use the "Search Signals" function to start a new signal search automatically and restart the calculation of the TOI.

5.11.6 Measurement Example – Measuring the R&S FPS's Intrinsic Intermodulation

Test setup:



Signal generator settings (e.g. R&S FPS SMW):

Device	Level	Frequency
Signal generator 1	-4 dBm	799.6 MHz
Signal generator 2	-4 dBm	800.4 MHz

Setting up the measurement

1. Preset the R&S FPS.
2. Set the center frequency to *800 MHz* and the frequency span to *3 MHz*.
3. Set the reference level to *-10 dBm* and RF attenuation to *0 dB*.
4. Set the resolution bandwidth to *10 kHz*.
The noise is reduced, the trace is smoothed further and the intermodulation products can be seen clearly.
5. Set the VBW to "1 kHz".

Measuring intermodulation using the Third Order Intercept (TOI) measurement function

1. Press the MEAS key and select the "Third Order Intercept" measurement function from the "Select Measurement" dialog box.

The R&S FPS activates four markers to measure the intermodulation distance. Two markers are positioned on the useful signals and two on the intermodulation products. The TOI is calculated from the level difference between the useful signals and the intermodulation products. It is then displayed on the screen:

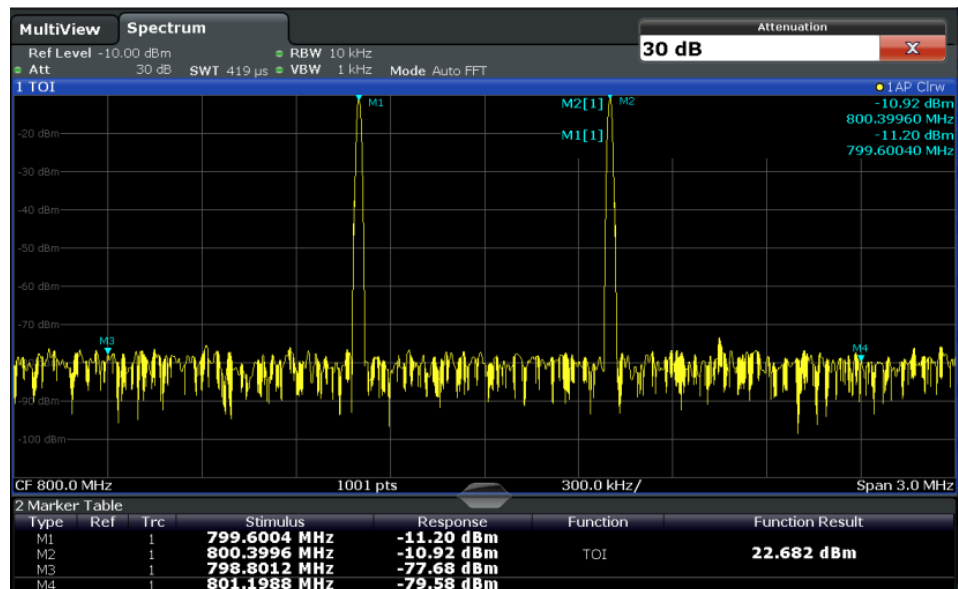
Third Order Intercept (TOI) Measurement



The third order intercept (TOI) is displayed in the marker information.

- The level of a signal analyzer's intrinsic intermodulation products depends on the RF level of the useful signals at the input mixer. When the RF attenuation is added, the mixer level is reduced and the intermodulation distance is increased. With an additional RF attenuation of 10 dB, the levels of the intermodulation products are reduced by 20 dB. The noise level is, however, increased by 10 dB. Increase the RF attenuation to 20 dB to reduce intermodulation products.

The R&S FPS's intrinsic intermodulation products disappear below the noise floor.



5.12 AM Modulation Depth Measurement

Using the R&S FPS you can measure the AM modulation depth of a modulated signal.

- [About the Measurement](#).....287
- [AM Modulation Depth Results](#).....287
- [AM Modulation Depth Configuration](#)..... 288
- [Optimizing and Troubleshooting the Measurement](#)..... 289
- [How to Determine the AM Modulation Depth](#).....290

5.12.1 About the Measurement

The AM modulation depth, also known as a modulation index, indicates how much the modulated signal varies around the carrier amplitude. It is defined as:

$$M_{\text{Depth}} = \text{peak signal amplitude} / \text{unmodulated carrier amplitude}$$

So for $M_{\text{Depth}} = 0.5$, for example, the carrier amplitude varies by 50% above and below its unmodulated level, and for $M_{\text{Depth}} = 1.0$ it varies by 100%.

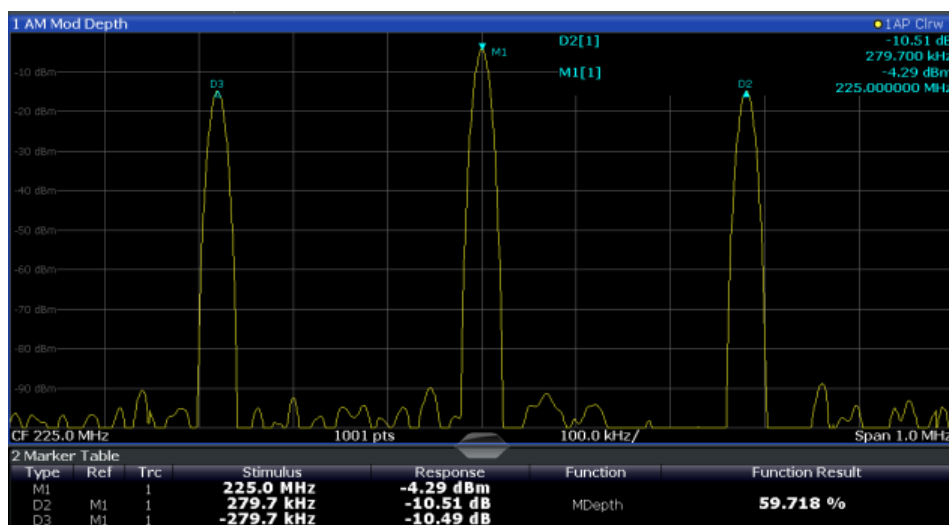
When this measurement is activated, marker 1 is set to the peak level, which is considered to be the carrier level. Delta markers 2 and 3 are automatically set symmetrically to the carrier on the adjacent peak values of the trace. The markers can be adjusted manually, if necessary.

The R&S FPS calculates the power at the marker positions from the measured levels. The AM modulation depth is calculated as the ratio between the power values at the reference marker and at the delta markers. If the powers of the two AM side bands are unequal, the mean value of the two power values is used for AM modulation depth calculation.

5.12.2 AM Modulation Depth Results

As a result of the AM Modulation Depth measurement, the following values are displayed in the marker area of the diagram:

Label	Description
MDepth	AM modulation depth in percent
M1	Maximum of the signal (= carrier level)
D2	Offset of next peak to the right of the carrier
D3	Offset of the next peak to the left of the carrier

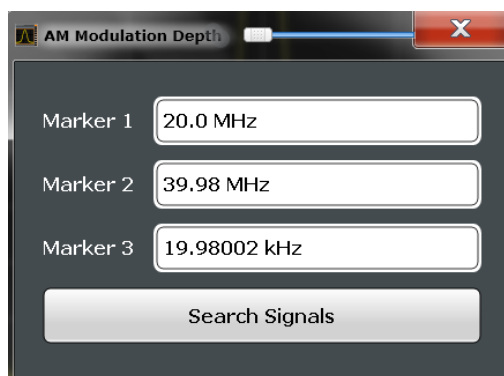


Remote command:

The AM modulation depth can also be queried using the remote command `CALCulate<n>:MARKer<m>:FUNCTION:MDEPth:RESult?` on page 721.

5.12.3 AM Modulation Depth Configuration

AM Modulation Depth measurements are selected via the "AM Modulation Depth" button in the "Select Measurement" dialog box. The measurement is started immediately with the default settings. It can be configured via the MEAS CONFIG key or in the "AM Modulation Depth" dialog box, which is displayed as a tab in the "Analysis" dialog box or when you select the "AM Mod Depth Config" softkey from the "AM Mod Depth" menu.



The remote commands required to perform these tasks are described in [chapter 11.5.12, "Measuring the AM Modulation Depth"](#), on page 720.

Marker 1/2/3	289
Search Signals	289

Marker 1/2/3

Indicates the detected characteristic values as determined by the AM Modulation Depth measurement:

Marker	Description
M1	Maximum of the signal (= carrier level)
D2	Offset of next peak to the right of the carrier
D3	Offset of the next peak to the left of the carrier

The marker positions can be edited; the modulation depth is then recalculated according to the new marker values.

To reset all marker positions automatically, use the [Search Signals](#) function.

Note: Moving the marker positions manually. When the position of delta marker 2 is changed, delta marker 3 is moved symmetrically with respect to the reference marker 1.

Delta marker 3, on the other hand, can be moved for fine adjustment independently of marker 2.

Marker 1 can also be moved manually for re-adjustment without affecting the position of the delta markers.

Remote command:

[CALCulate<n>:MARKer<m>:X](#) on page 823

[CALCulate<n>:DELTAmarker<m>:X](#) on page 822

[CALCulate<n>:DELTAmarker<m>:X:RELative?](#) on page 833

Search Signals

Performs a new search on the input signal and recalculates the AM Modulation Depth according to the measured values.

Remote command:

[CALCulate<n>:MARKer<m>:FUNCTION:MDEPTH:SEARCHsignal ONCE](#)
on page 721

5.12.4 Optimizing and Troubleshooting the Measurement

If the results do not meet your expectations, try the following methods to optimize the measurement:

- Set the center frequency to the frequency of the device under test.
- Adjust the span so the peaks to the left and right of the carrier, produced by the AM modulated signal, are clearly visible.
If the span is too wide, these signals may fall together with the carrier and the measurement can not be performed.
If the span is too narrow, these signals are outside of the measured span and the delta markers can not find these peaks.
The rule of thumb is to set the span to three times the value of the AM modulation frequency.

5.12.5 How to Determine the AM Modulation Depth

1. Apply a modulated carrier signal to the R&S FPS input.
2. On the R&S FPS, press the MEAS key.
3. Select the "AM Modulation Depth" measurement function from the "Select Measurement" dialog box.

The calculated AM Modulation Depth is indicated in the marker information. The markers required for calculation are displayed in the marker table.

4. If the signal changes significantly during or after the AM Modulation Depth measurement, use the "Search Signals" function to start a new peak search automatically and restart the calculation of the AM Modulation Depth.

6 Common Measurement Settings

Basic measurement settings that are common to many measurement tasks, regardless of the application or operating mode, are described here. If you are performing a specific measurement task, using an operating mode other than Signal and Spectrum Analyzer mode, or an application other than the Spectrum application, be sure to check the specific application or mode description for settings that may deviate from these common settings.

- [Configuration Overview](#).....291
- [Data Input and Output](#).....293
- [Frequency and Span Configuration](#).....333
- [Amplitude and Vertical Axis Configuration](#).....342
- [Bandwidth, Filter and Sweep Configuration](#).....351
- [Trigger and Gate Configuration](#).....366
- [Adjusting Settings Automatically](#).....382

6.1 Configuration Overview



Throughout the measurement channel configuration, an overview of the most important currently defined settings is provided in the configuration "Overview". The "Overview" is displayed when you select the "Overview" icon, which is available at the bottom of all softkey menus.



In addition to the main measurement settings, the "Overview" provides quick access to the main settings dialog boxes. Thus, you can easily configure an entire measurement channel from input over processing to output and analysis by stepping through the dialog boxes as indicated in the "Overview".

In particular, the "Overview" provides quick access to the following configuration dialog boxes (listed in the recommended order of processing):

1. "Select Measurement"
See [chapter 5.1, "Available Measurement Functions"](#), on page 111
2. Input
See [chapter 6.2.2, "Input Source Settings"](#), on page 294
3. Amplitude
See [chapter 6.4, "Amplitude and Vertical Axis Configuration"](#), on page 342
4. Frequency
See [chapter 6.3, "Frequency and Span Configuration"](#), on page 333
5. (Optionally:) Trigger/Gate
See [chapter 6.6, "Trigger and Gate Configuration"](#), on page 366
6. Bandwidth
See [chapter 6.5.2, "Bandwidth, Filter and Sweep Settings"](#), on page 357
(For SEM measurements: SEM Setup, see [chapter 5.6.5, "SEM Configuration"](#), on page 210)
(For Spurious measurements: Spurious Setup, see [chapter 5.7.4, "Spurious Emissions Measurement Configuration"](#), on page 243)
7. (Optionally:) Outputs
See [chapter 6.2.5, "Output Settings"](#), on page 330
8. Analysis
See [chapter 7, "Common Analysis and Display Functions"](#), on page 385
9. Display
See [chapter 7.1, "Result Display Configuration"](#), on page 385

To configure settings

- ▶ Select any button to open the corresponding dialog box.
Select a setting in the channel bar (at the top of the measurement channel tab) to change a specific setting.

Preset Channel

Select the "Preset Channel" button in the lower lefthand corner of the "Overview" to restore all measurement settings **in the current channel** to their default values.

Note that the PRESET key restores the entire instrument to its default values and thus closes **all measurement channels** on the R&S FPS (except for the default Spectrum application channel)!

For details see [chapter 8.1, "Restoring the Default Instrument Configuration \(Preset\)"](#), on page 478.

Remote command:

`SYSTem:PRESet:CHANnel[:EXECute]` on page 895

6.2 Data Input and Output

The R&S FPS can analyze signals from different input sources and provide various types of output (such as video or trigger signals).

- [Receiving Data Input and Providing Data Output](#)..... 293
- [Input Source Settings](#).....294
- [Power Sensors](#).....296
- [Optional External Generator Control](#).....305
- [Output Settings](#)..... 330

6.2.1 Receiving Data Input and Providing Data Output

The R&S FPS can analyze signals from different input sources and provide various types of output (such as noise or trigger signals).

6.2.1.1 Input from Noise Sources

The R&S FPS provides an optional NOISE SOURCE CONTROL connector with a voltage supply for an external noise source. By switching the supply voltage for an external noise source on or off in the firmware, you can activate or deactivate the device as required.

External noise sources are useful when you are measuring power levels that fall below the noise floor of the R&S FPS itself, for example when measuring the noise level of an amplifier.

In this case, you can first connect an external noise source (whose noise power level is known in advance) to the R&S FPS and measure the total noise power. From this value you can determine the noise power of the R&S FPS. Then when you measure the power level of the actual DUT, you can deduct the known noise level from the total power to obtain the power level of the DUT.

The noise source is controlled in the "Output" settings, see "[Noise Source](#)" on page 332

6.2.1.2 Receiving and Providing Trigger Signals

Using one of the TRG IN / AUX connectors of the R&S FPS, the R&S FPS can use a signal from an external reference as a trigger to capture data. Alternatively, the internal trigger signal used by the R&S FPS can be output for use by other connected devices. Using the same trigger on several devices is useful to synchronize the transmitted and received signals within a measurement.

For details on the connectors see the R&S FPS "Getting Started" manual.

External trigger as input

If the trigger signal for the R&S FPS is provided by an external reference, the reference signal source must be connected to the R&S FPS and the trigger source must be defined as "External" for the R&S FPS.

Trigger output

The R&S FPS can provide output to another device either to pass on the internal trigger signal, or to indicate that the R&S FPS itself is ready to trigger.

The trigger signal can be output by the R&S FPS automatically, or manually by the user. If it is provided automatically, a high signal is output when the R&S FPS has triggered due to a sweep start ("Device Triggered"), or when the R&S FPS is ready to receive a trigger signal after a sweep start ("Trigger Armed").

Manual triggering

If the trigger output signal is initiated manually, the length and level (high/low) of the trigger pulse is also user-definable. Note, however, that the trigger pulse level is always opposite to the constant signal level defined by the output "Level" setting, e.g. for "Level = High", a constant high signal is output to the connector until the "Send Trigger" button is selected. Then, a low pulse is provided.

6.2.1.3 IF and Video Signal Output

The measured IF signal or displayed video signal (i.e. the filtered and detected IF signal) can be provided at the IF/VIDEO output connector of the R&S FPS.

The **video output** is a signal of 1 V. It can be used, for example, to control demodulated audio frequencies.

The **IF output** is a signal of the measured level at a specified frequency.

Restrictions

Note the following restrictions for IF output:

- IF and video output is only available in the time domain (zero span).

If the hardware option R&S FPS-B160 for **bandwidth extension** is installed and activated (i.e. for bandwidths > 40 MHz), the IF output is not available at the IF/VIDEO output connector.

6.2.2 Input Source Settings

The input source determines which data the R&S FPS will analyze.

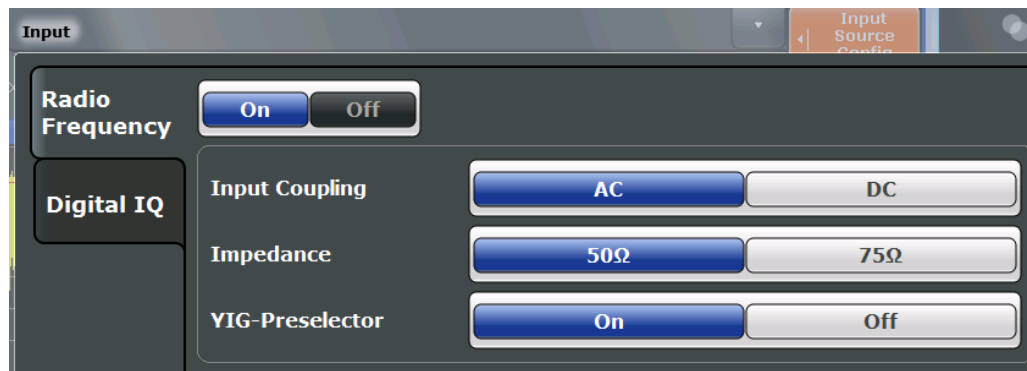
Input settings can be configured in the "Input" dialog box.

Some settings are also available in the "Amplitude" tab of the "Amplitude" dialog box.

- [Radio Frequency Input](#).....295

6.2.2.1 Radio Frequency Input

The default input source for the R&S FPS is "Radio Frequency", i.e. the signal at the RF INPUT connector of the R&S FPS. If no additional options are installed, this is the only available input source.



Radio Frequency State.....	295
Input Coupling.....	295
Impedance.....	295
YIG-Preselector.....	296

Radio Frequency State

Activates input from the RF INPUT connector.

Remote command:

[INPut:SElect](#) on page 774

Input Coupling

The RF input of the R&S FPS can be coupled by alternating current (AC) or direct current (DC).

AC coupling blocks any DC voltage from the input signal. This is the default setting to prevent damage to the instrument. Very low frequencies in the input signal may be distorted.

However, some specifications require DC coupling. In this case, you must protect the instrument from damaging DC input voltages manually. For details, refer to the data sheet.

Remote command:

[INPut:COUPling](#) on page 773

Impedance

The reference impedance for the measured levels of the R&S FPS can be set to 50 Ω or 75 Ω.

75 Ω should be selected if the 50 Ω input impedance is transformed to a higher impedance using a 75 Ω adapter of the RAZ type (= 25 Ω in series to the input impedance of the instrument). The correction value in this case is 1.76 dB = 10 log (75Ω/50Ω).

This value also affects the unit conversion (see ["Reference Level"](#) on page 345).

Remote command:

`INPut:IMPedance` on page 774

YIG-Preselector

Activates or deactivates the YIG-preselector, if available on the R&S FPS.

An internal YIG-preselector at the input of the R&S FPS ensures that image frequencies are rejected. However, this is only possible for a restricted bandwidth. In order to use the maximum bandwidth for signal analysis you can deactivate the YIG-preselector at the input of the R&S FPS, which may lead to image-frequency display.

Note that the YIG-preselector is active only on frequencies greater than 8 GHz. Therefore, switching the YIG-preselector on or off has no effect if the frequency is below that value.

Note:

For the following measurements, the YIG-Preselector is off by default (if available).

- I/Q Analyzer (and thus in all applications in MSRA operating mode)
- GSM
- VSA

Remote command:

`INPut:FILTer:YIG[:STATe]` on page 773

6.2.3 Power Sensors

The R&S FPS can also analyze data from a connected power sensor.

- [Basics on Power Sensors](#)..... 296
- [Power Sensor Settings](#).....298
- [How to Work With a Power Sensor](#).....303
- [How to Configure a Power Sensor as an External Trigger](#)..... 305

6.2.3.1 Basics on Power Sensors

For precise power measurement up to 4 power sensors can be connected to the instrument via the USB interfaces. Both manual operation and remote control are supported.



Currently, only R&S NRP-Zxy power sensors are supported. For a detailed list of supported sensors see the data sheet.

As the R&S FPS does not provide an explicit Power Sensor connector, an R&S®NRP-Z3/-Z4/ or -Z5 adaptor is required to connect the power sensor to one of the USB connectors on the R&S FPS.

Power sensors can also be used to trigger a measurement at a specified power level, e.g. from a signal generator (see ["Using a Power Sensor as an External Power Trigger"](#) on page 297).

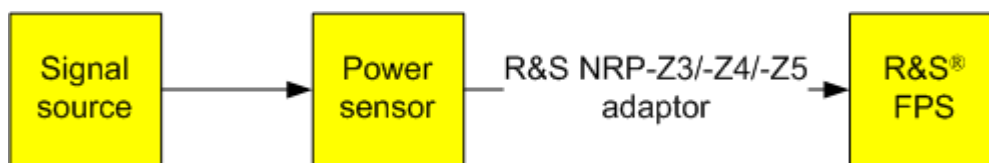


Fig. 6-1: Power sensor support – standard test setup

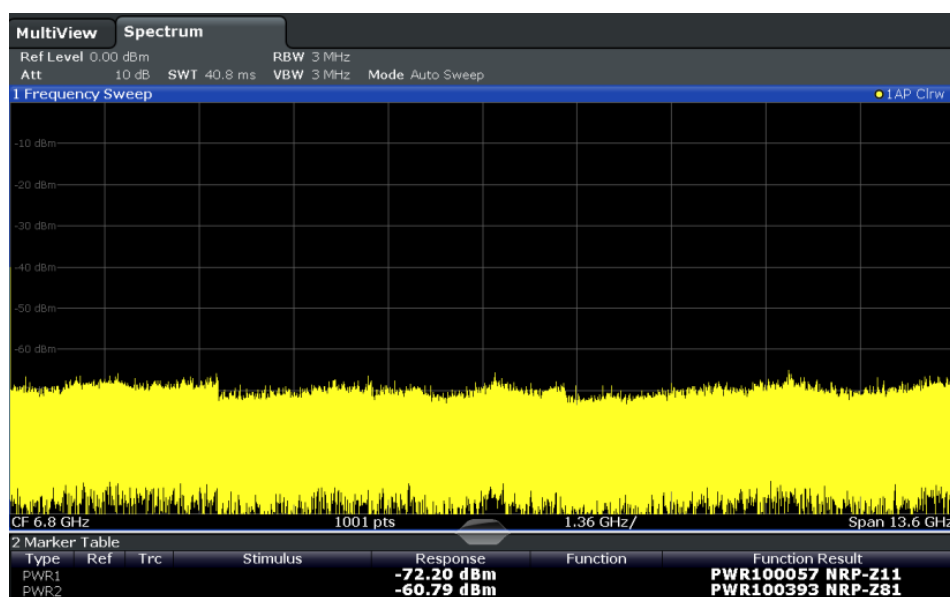


Using the power sensor with several applications

The power sensor cannot be used from the R&S FPS firmware and the R&S Power Viewer Plus (virtual power meter for displaying results of the R&S NRP power sensors) simultaneously.

Result display

The results of the power sensor measurements are displayed in the marker table. For each power sensor, a row is inserted. The sensor index is indicated in the "Type" column.



Using a Power Sensor as an External Power Trigger

Power sensors can be used to trigger a measurement at a specified power level, e.g. from a signal generator.



Currently, only the following power sensors are supported as power triggers:

- R&S NRP-Z81
- R&S NRP-Z85
- R&S NRP-Z86

With the R&S FPS, the power sensor requires a special USB adaptor which must be connected to the instrument. In addition, the power sensor must be connected to the R&S FPS's external trigger port.

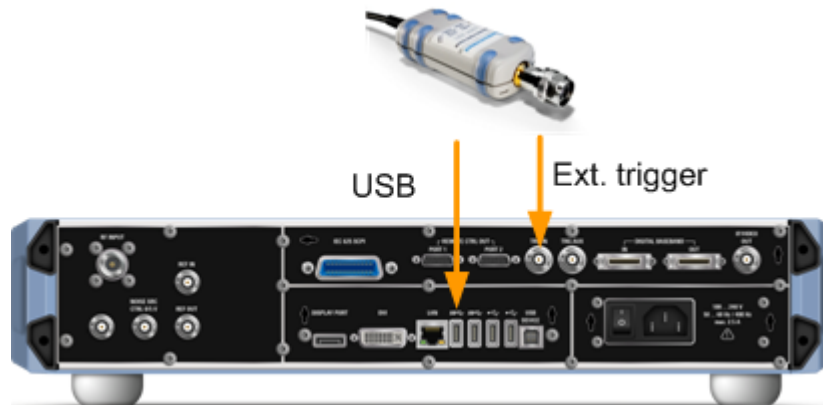


Fig. 6-2: Connecting a power sensor for use as an external trigger

The R&S FPS receives an external trigger signal when the defined trigger level is measured by the power sensor. Power measurement results are provided as usual.



The "Gate Mode" *Level* is not supported for R&S power sensors. The signal sent by these sensors merely reflects the instant the level is first exceeded, rather than a time period. However, only time periods can be used for gating in level mode. Thus, the trigger impulse from the sensors is not long enough for a fully gated measurement; the measurement cannot be completed. For details on gating see [chapter 6.6.1.2, "Gated Measurements"](#), on page 370.

For details see [chapter 6.2.3.4, "How to Configure a Power Sensor as an External Trigger"](#), on page 305.

6.2.3.2 Power Sensor Settings

Power sensor settings are available in the "Power Sensor" tab of the "Input" dialog box. Each sensor is configured on a separate tab.



State.....299

Continuous Value Update.....300

Select.....300

Zeroing Power Sensor.....300

Frequency Manual.....300

Frequency Coupling.....301

Unit/Scale.....301

Meas Time/Average.....301

Setting the Reference Level from the Measurement (Meas->Ref).....301

Reference Value.....301

Use Ref Lev Offset.....302

Average Count (Number of Readings).....302

Duty Cycle.....302

Using the power sensor as an external trigger.....302

- L External Trigger Level.....302
- L Hysteresis.....303
- L Trigger Holdoff.....303
- L Drop-Out Time.....303
- L Slope.....303

State

Switches the power measurement for all power sensors on or off. Note that in addition to this general setting, each power sensor can be activated or deactivated individually by the **Select** setting on each tab. However, the general setting overrides the individual settings.

Remote command:

[SENSe:] PMETer<p> [:STATe] on page 792

Continuous Value Update

If activated, the power sensor data is updated continuously during a sweep with a long sweep time, and even after a single sweep has completed.

This function cannot be activated for individual sensors.

If the power sensor is being used as a trigger (see ["Using the power sensor as an external trigger"](#) on page 302), continuous update is not possible; this setting is ignored.

Remote command:

[\[SENSe:\] PMETer<p>:UPDate\[:STATe\]](#) on page 792

Select

Selects the individual power sensor for usage if power measurement is generally activated ([State](#) function).

The detected **serial numbers** of the power sensors connected to the instrument are provided in a selection list. For each of the four available power sensor indexes ("Power Sensor 1"..."Power Sensor 4"), which correspond to the tabs in the configuration dialog, one of the detected serial numbers can be assigned. The physical sensor is thus assigned to the configuration setting for the selected power sensor index.

By default, serial numbers not yet assigned are automatically assigned to the next free power sensor index for which "Auto Assignment" is selected.

Alternatively, you can assign the sensors manually by deactivating the "Auto" option and selecting a serial number from the list.

Remote command:

[\[SENSe:\] PMETer<p>\[:STATe\]](#) on page 792

[SYSTem:COMMUnicate:RDEvice:PMETer<p>:DEFine](#) on page 785

[SYSTem:COMMUnicate:RDEvice:PMETer<p>:CONFigure:AUTO\[:STATe\]](#)
on page 785

[SYSTem:COMMUnicate:RDEvice:PMETer:COUNT?](#) on page 785

Zeroing Power Sensor

Starts zeroing of the power sensor.

For details on the zeroing process refer to ["How to Zero the Power Sensor"](#) on page 304.

Remote command:

[CALibration:PMETer<p>:ZERO:AUTO ONCE](#) on page 787

Frequency Manual

Defines the frequency of the signal to be measured. The power sensor has a memory with frequency-dependent correction factors. This allows extreme accuracy for signals of a known frequency.

Remote command:

[\[SENSe:\] PMETer<p>:FREQuency](#) on page 789

Frequency Coupling

Selects the coupling option. The frequency can be coupled automatically to the center frequency of the instrument or to the frequency of marker 1.

Remote command:

`[SENSe:] PMETer<p>:FREQuency:LINK` on page 790

Unit/Scale

Selects the unit with which the measured power is to be displayed. Available units are dBm, dB, W and %.

If dB or % is selected, the display is relative to the reference value that is defined with either the "Meas -> Ref" setting or the "Reference Value" setting.

Remote command:

`UNIT<n>:PMETer<p>:POWer` on page 792

`UNIT<n>:PMETer<p>:POWer:RATio` on page 793

Meas Time/Average

Selects the measurement time or switches to manual averaging mode. In general, results are more precise with longer measurement times. The following settings are recommended for different signal types to obtain stable and precise results:

"Short"	Stationary signals with high power (> -40dBm), because they require only a short measurement time and short measurement time provides the highest repetition rates.
"Normal"	Signals with lower power or modulated signals
"Long"	Signals at the lower end of the measurement range (<-50 dBm) or Signals with lower power to minimize the influence of noise
"Manual"	Manual averaging mode. The average count is set with the Average Count (Number of Readings) setting.

Remote command:

`[SENSe:] PMETer<p>:MTIME` on page 790

`[SENSe:] PMETer<p>:MTIME:AVERage[:STATe]` on page 791

Setting the Reference Level from the Measurement (Meas->Ref)

Sets the currently measured power as a reference value for the relative display. The reference value can also be set manually via the [Reference Value](#) setting.

Remote command:

`CALCulate<n>:PMETer<p>:RELative[:MAGNitude]:AUTO ONCE` on page 787

Reference Value

Defines the reference value for relative measurements in the unit dBm.

Remote command:

`CALCulate<n>:PMETer<p>:RELative[:MAGNitude]` on page 787

Use Ref Lev Offset

If activated, takes the reference level offset defined for the analyzer into account for the measured power (see ["Shifting the Display \(Offset\)"](#) on page 346). If deactivated, takes no offset into account.

Remote command:

[SENSe:] PMETer<p>:ROFFset [:STATe] on page 791

Average Count (Number of Readings)

Defines the number of readings (averages) to be performed after a single sweep has been started. This setting is only available if manual averaging is selected ([Meas Time/Average](#) setting).

The values for the average count range from 0 to 256 in binary steps (1, 2, 4, 8, ...). For average count = 0 or 1, one reading is performed. The general averaging and sweep count for the trace are independent from this setting.

Results become more stable with extended average, particularly if signals with low power are measured. This setting can be used to minimize the influence of noise in the power sensor measurement.

Remote command:

[SENSe:] PMETer<p>:MTIME:AVERage:COUNT on page 790

Duty Cycle

Sets the duty cycle to a percent value for the correction of pulse-modulated signals and activates the duty cycle correction. With the correction activated, the sensor calculates the signal pulse power from this value and the mean power.

Remote command:

[SENSe:] PMETer<p>:DCYCLE[:STATe] on page 789

[SENSe:] PMETer<p>:DCYCLE:VALue on page 789

Using the power sensor as an external trigger

If activated, the power sensor creates a trigger signal when a power higher than the defined "External Trigger Level" is measured. This trigger signal can be used as an external power trigger by the R&S FPS.

This setting is only available in conjunction with a compatible power sensor.

For details on using a power sensor as an external trigger, see ["Using a Power Sensor as an External Power Trigger"](#) on page 297.

Remote command:

[SENSe:] PMETer<p>:TRIGger[:STATe] on page 795

TRIG:SOUR EXT, see [TRIGger\[:SEQuence\]:SOURce](#) on page 764

External Trigger Level ← Using the power sensor as an external trigger

Defines the trigger level for the power sensor trigger.

For details on supported trigger levels, see the data sheet.

Remote command:

[SENSe:] PMETer<p>:TRIGger:LEVel on page 794

Hysteresis ← Using the power sensor as an external trigger

Defines the distance in dB to the trigger level that the trigger source must exceed before a trigger event occurs. Setting a hysteresis avoids unwanted trigger events caused by noise oscillation around the trigger level.

Remote command:

[\[SENSe:\] PMETer<p>:TRIGger:HYSteresis](#) on page 794

Trigger Holdoff ← Using the power sensor as an external trigger

Defines the minimum time (in seconds) that must pass between two trigger events. Trigger events that occur during the holdoff time are ignored.

Remote command:

[\[SENSe:\] PMETer<p>:TRIGger:HOLDoff](#) on page 793

Drop-Out Time ← Using the power sensor as an external trigger

Defines the time the input signal must stay below the trigger level before triggering again.

Slope ← Using the power sensor as an external trigger

Defines whether triggering occurs when the signal rises to the trigger level or falls down to it.

Remote command:

[\[SENSe:\] PMETer<p>:TRIGger:SLOPe](#) on page 795

6.2.3.3 How to Work With a Power Sensor

The following step-by-step instructions demonstrate how to set up a power sensor. For details on individual functions and settings see [chapter 6.2.3.2, "Power Sensor Settings"](#), on page 298.

The remote commands required to perform these tasks are described in [chapter 11.7.6.3, "Working with Power Sensors"](#), on page 785.



Power sensors can also be used to trigger a measurement at a specified power level, e.g. from a signal generator.

This is described in [chapter 6.2.3.4, "How to Configure a Power Sensor as an External Trigger"](#), on page 305.

How to Set Up a Power Sensor

Up to 4 external power sensors can be configured separately and used for precise power measurement. All power sensors can be activated and deactivated individually.

The following procedure describes in detail how to configure and activate power sensors.

1. To display the "Power Sensor" tab of the "Input" dialog box, do one of the following:
 - Select "Input" from the "Overview".
 - Select the INPUT/OUTPUT key and then the "Power Sensor Config" softkey.

2. Select the tab for the power sensor index you want to configure, e.g. "Sensor 1".
3. Press "Select" to analyze the power sensor data according to the current configuration when power measurement is activated.
4. From the selection list with serial numbers of connected power sensors, select the sensor you want to configure.
To have newly connected power sensors assigned to a tab automatically (default), select "Auto".
5. Define the frequency of the signal whose power you want to measure.
 - a) To define the frequency manually, select "Frequency Manual" and enter a frequency.
 - b) To determine the frequency automatically, select "Frequency Coupling" and then either "Center", to use the center frequency, or "Marker", to use the frequency defined by marker 1.
6. Select the unit for the power result display.
7. Select the measurement time for which the average is calculated, or define the number of readings to average. To define the number of readings to be taken into account manually, select "Manual" and enter the number in the "Number of Readings" field.
8. To activate the duty cycle correction, select "DutyCycle" and enter a percentage as the correction value.
9. If you selected "dB" or "%" as units (relative display), define a reference value:
 - a) To set the currently measured power as a reference value, press the "Meas -> Ref" button.
 - b) Alternatively, enter a value manually in the "Reference Value" field.
 - c) Optionally, select the "Use Ref Level Offset" option to take the reference level offset set for the analyzer into account for the measured power.
10. If necessary, repeat steps 3-10 for another power sensor.
11. Set the "Power Sensor State" at the top of the "Power Sensor" tab to "On" to activate power measurement for the selected power sensors.

The results of the power measurement are displayed in the marker table (Function: "Sensor<1...4>").

How to Zero the Power Sensor

1. To display the "Power Sensor" tab of the "Input" dialog box, do one of the following:
 - Select "Input" from the "Overview".
 - Select the INPUT/OUTPUT key and then the "Power Sensor Config" softkey.
2. Select the tab that is assigned to the power sensor you want to zero.
3. Press the "Zeroing Power Sensor" button.

A dialog box is displayed that prompts you to disconnect all signals from the input of the power sensor.

4. Disconnect all signals sending input to the power sensor and press ENTER to continue.
5. Wait until zeroing is complete.
A corresponding message is displayed.

6.2.3.4 How to Configure a Power Sensor as an External Trigger

The following step-by-step instructions demonstrate how to configure a power sensor to be used as an external power sensor trigger.

To configure a power sensor as an external trigger

1. Connect a compatible power sensor to one of the USB interfaces on the rear panel of the R&S FPS. (For details on supported sensors see ["Using a Power Sensor as an External Power Trigger"](#) on page 297).
2. Set up the power sensor as described in ["How to Set Up a Power Sensor"](#) on page 303.
3. In the "Power Sensor" tab of the "Input" dialog box, select the "External Power Trigger" option.
4. Enter the power level at which a trigger signal is to be generated ("External Trigger Level") and the other trigger settings for the power sensor trigger.
5. Press the TRIG key and then select "Trigger /Gate Config".
6. In the "Trigger and Gate" dialog box, select "Signal Source" = "External Trigger 1/2".

The R&S FPS is configured to trigger when the defined conditions for the power sensor occur.

6.2.4 Optional External Generator Control

If the R&S FPS optional External Generator Control is installed, you can operate various commercially available generators as an external generator with the R&S FPS. Thus, scalar network analysis with the R&S FPS is possible.

- [About External Generator Control](#).....306
- [Basics on External Generator Control](#).....306
- [External Generator Control Settings](#)..... 315
- [How to Work With External Generator Control](#)..... 323
- [Measurement Example: Calibration with an External Generator](#)..... 325

6.2.4.1 About External Generator Control

A common measurement setup includes a signal generator, a device under test (DUT), and a signal and spectrum analyzer, for example the R&S FPS. In this setup, the signal analyzer can control which signal the generator is to send, which is in turn measured by the analyzer. This process is referred to as *external generator control*. The generator in this setup is referred to as a *tracking generator*.

A measurement with a tracking generator is useful to measure any effects on the power level caused by the cables and connectors from the signal generator and the signal analyzer in advance. The known effects can then be removed from the measurement results in order to obtain accurate information on the DUT.

6.2.4.2 Basics on External Generator Control

Some background knowledge on basic terms and principles used for external generator control is provided here for a better understanding of the required configuration settings.



External generator control is only available in the Spectrum, I/Q Analyzer, Analog Demodulation and Noise Figure applications.

- [External Generator Connections](#).....306
- [Overview of Supported Generators](#).....308
- [Generator Setup Files](#).....308
- [Calibration Mechanism](#).....309
- [Normalization](#).....309
- [Reference Trace, Reference Line and Reference Level](#).....311
- [Coupling the Frequencies](#).....312
- [Displayed Information and Errors](#).....314

External Generator Connections

The external generator is controlled either via a LAN connection or via the PCIe interface of the R&S FPS supplied with the option.



Controlling R&S SGS or R&S SGT as External Generators via PCIe

In order to control R&S SGS or R&S SGT signal generators as external generators via the R&S FPS's PCIe interface, special drivers must be installed on the R&S FPS (in addition to the optional External Generator Control). The required drivers are available from the R&S SGS / R&S SGT Signal Generator CDs.

For more information on configuring interfaces see [chapter 3.4.1, "Remote Control Interfaces and Protocols"](#), on page 48.

Transmission Measurement

This measurement yields the transmission characteristics of a two-port network. The external generator is used as a signal source. It is connected to the input connector of

the DUT. The input of the R&S FPS is fed from the output of the DUT. A calibration can be carried out to compensate for the effects of the test setup (e.g. frequency response of connecting cables).

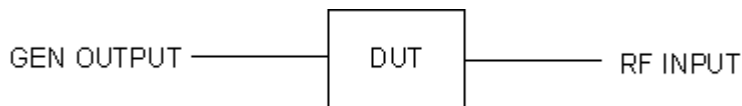


Fig. 6-3: Test setup for transmission measurement

Reflection Measurement

Scalar reflection measurements can be carried out using a reflection-coefficient measurement bridge.

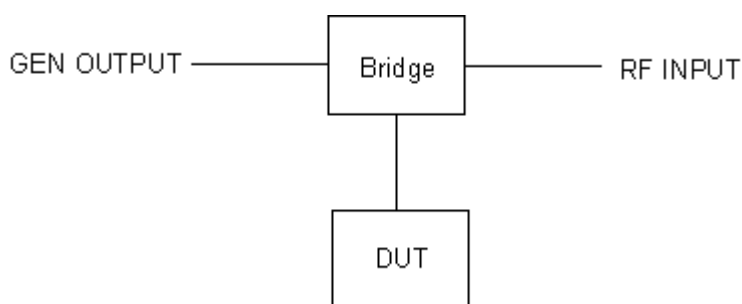


Fig. 6-4: Test setup for reflection measurement

Generated signal input

In order to use the functions of the external generator, an appropriate generator must be connected and configured correctly. In particular, the generator output must be connected to the RF input of the R&S FPS.

External reference frequency

In order to enhance measurement accuracy, a common reference frequency should be used for both the R&S FPS and the generator. If no independent 10 MHz reference frequency is available, it is recommended that you connect the reference output of the generator with the reference input of the R&S FPS and that you enable usage of the external reference on the R&S FPS via "SETUP" > "Reference" > "External Reference".

For more information on external references see ["Reference Frequency Input"](#) on page 508.

Connection errors

If no external generator is connected, if the connection address is not correct, or the generator is not ready for operation, an error message is displayed (e.g. "Ext. Generator TCPIP Handshake Error!", see ["Displayed Information and Errors"](#) on page 314).

Overview of Supported Generators

Generator type	Generator type
SGS100A12	SMF100A
SGS100A6	SMF22
SGT100A3 ³⁾	SMF22B2
SGT100A6 ³⁾	SMF43
SMA01A ¹⁾	SMF43B2
SMA100A3 ¹⁾	SMJ03
SMA100A6 ¹⁾	SMJ06
SMB100A1	SMU02 ²⁾
SMB100A12	SMU02B31 ²⁾
SMB100A2	SMU03 ²⁾
SMB100A20	SMU03B31 ²⁾
SMB100A3	SMU04 ²⁾
SMB100A40	SMU04B31 ²⁾
SMB100A6	SMU06 ²⁾
SMBV100A3	SMU06B31 ²⁾
SMBV100A6	SMW03
SMC100A1	SMW06
SMC100A3	
1) Requires firmware version V2.10.x or higher on the signal generator 2) Requires firmware version V1.10.x or higher on the signal generator 3) only for R&S FPS version 1.21 and higher	

Generator Setup Files

For each signal generator type to be controlled by the R&S FPS a generator setup file must be configured and stored on the R&S FPS. The setup file defines the frequency and power ranges supported by the generator, as well as information required for communication. For the signal generators listed in ["Overview of Supported Generators"](#) on page 308, default setup files are provided. If necessary, these files can be edited or duplicated for varying measurement setups or other instruments.

The existing setup files can be displayed in an editor in read-only mode directly from the "External Generator" configuration dialog box. From there, they can be edited and stored under a different name, and are then available on the R&S FPS.

(For details see ["To define a new generator setup file"](#) on page 324).

Calibration Mechanism

A common measurement setup includes a signal generator, a device under test (DUT), and a signal and spectrum analyzer. Therefore, it is useful to measure the attenuation or gain caused by the cables and connectors from the signal generator and the signal analyzer in advance. The known level offsets can then be removed from the measurement results in order to obtain accurate information on the DUT.

Calculating the difference between the currently measured power and a reference trace is referred to as *calibration*. Thus, the measurement results from the controlled external generator - including the inherent distortions - can be used as a reference trace to calibrate the measurement setup.

The inherent frequency and power level distortions can be determined by connecting the R&S FPS to the signal generator. The R&S FPS sends a predefined list of frequencies to the signal generator (see also "[Coupling the Frequencies](#)" on page 312). The signal generator then sends a signal with the specified level at each frequency in the predefined list. The R&S FPS measures the signal and determines the level offsets to the expected values.

Saving calibration results

A reference dataset for the calibration results is stored internally as a table of value pairs (frequency/level), one for each sweep point. The measured offsets can then be used as calibration factors for subsequent measurement results.

The calibration can be performed using either transmission or reflection measurements. The selected type of measurement used to determine the reference trace is included in the reference dataset.

Normalization

Once the measurement setup has been calibrated and the reference trace is available, subsequent measurement results can be corrected according to the calibration factors, if necessary. This is done by subtracting the reference trace from the measurement results. This process is referred to as *normalization* and can be activated or deactivated as required. If normalization is activated, "NOR" is displayed in the channel bar, next to the indication that an external generator is being used ("Ext.Gen"). The normalized trace from the calibration sweep is a constant 0 dB line, as $\text{<calibration trace> - <reference trace> = 0}$.

As long as the same settings are used for measurement as for calibration, the normalized measurement results should not contain any inherent frequency or power distortions. Thus, the measured DUT values are very accurate.

Approximate normalization

As soon as any of the calibration measurement settings are changed, the stored reference trace will no longer be identical to the new measurement results. However, if the measurement settings do not deviate too much, the measurement results can still be normalized *approximately* using the stored reference trace. This is indicated by the "APX" label in the channel bar (instead of "NOR").

This is the case if one or more of the following values deviate from the calibration settings:

- coupling (RBW, VBW, SWT)
- reference level, RF attenuation
- start or stop frequency
- output level of external generator
- detector (max. peak, min. peak, sample, etc.)
- frequency deviation at a maximum of 1001 points within the set sweep limits (corresponds to a doubling of the span)

Differences in level settings between the reference trace and the current instrument settings are taken into account automatically. If the span is reduced, a linear interpolation of the intermediate values is applied. If the span increases, the values at the left or right border of the reference dataset are extrapolated to the current start or stop frequency, i.e. the reference dataset is extended by constant values.

Thus, the instrument settings can be changed in a wide area without giving up normalization. This reduces the necessity to carry out a new normalization to a minimum.

If approximation becomes too poor, however, normalization is aborted and an error message is displayed (see ["Displayed Information and Errors"](#) on page 314).

The normalized trace in the display

The normalized reference trace is also displayed in the spectrum diagram, by default at the top of the diagram (= 100% of the window height). It is indicated by a red line labeled "NOR", followed by the current reference value. However, it can be shifted vertically to reflect an attenuation or gain caused by the measured DUT (see also ["Shifting the reference line \(and normalized trace\)"](#) on page 311).

Restoring the calibration settings

If the measurement settings no longer match the instrument settings with which the calibration was performed (indicated by the "APX" or no label next to "Ext.TG" in the channel bar), you can restore the calibration settings, which are stored with the reference dataset on the R&S FPS.

Storing the normalized reference trace as a transducer factor

The (inverse) normalized reference trace can also be stored as a *transducer factor* for use in other R&S FPS applications that do not support external generator control. The normalized trace data is converted to a transducer with unit dB and stored in a file with the specified name and the suffix `.trd` under `c:\r_s\instr\trd`. The frequency points are allocated in equidistant steps between the start and stop frequency.

This is useful, for example, to determine the effects of a particular device component and then remove these effects from a subsequent measurement which includes this component.

For an example see ["How to Remove the Effects of a Particular Component from Measurement Results Using Calibration"](#) on page 324.



Note that the *normalized* measurement data is stored, not the original *reference* trace! Thus, if you store the normalized trace directly after calibration, without changing any settings, the transducer factor will be 0 dB for the entire span (by definition of the normalized trace).

Reference Trace, Reference Line and Reference Level

Reference trace

The calibration results are stored internally on the R&S FPS as a *reference trace*. For each measured sweep point the offset to the expected values is determined. If normalization is activated, the offsets in the reference trace are removed from the current measurement results to compensate for the inherent distortions.

Reference line

The reference line is defined by the [Reference Value](#) and [Reference Position](#) in the "External Generator" > "Source Calibration" settings. It is similar to the [Reference Level](#) defined in the "Amplitude" settings. However, as opposed to the reference *level*, this reference *line* only affects the y-axis scaling in the diagram, it has no effect on the expected input power level or the hardware settings.

The reference line determines the range and the scaling of the y-axis, just as the reference level does.

The normalized reference trace (0 dB directly after calibration) is displayed on this reference line, indicated by a red line in the diagram. By default, the reference line is displayed at the top of the diagram. If you shift the reference line, the normalized trace is shifted, as well.

Shifting the reference line (and normalized trace)

You can shift the reference line - and thus the normalized trace - in the result display by changing the [Reference Position](#) or the [Reference Value](#).

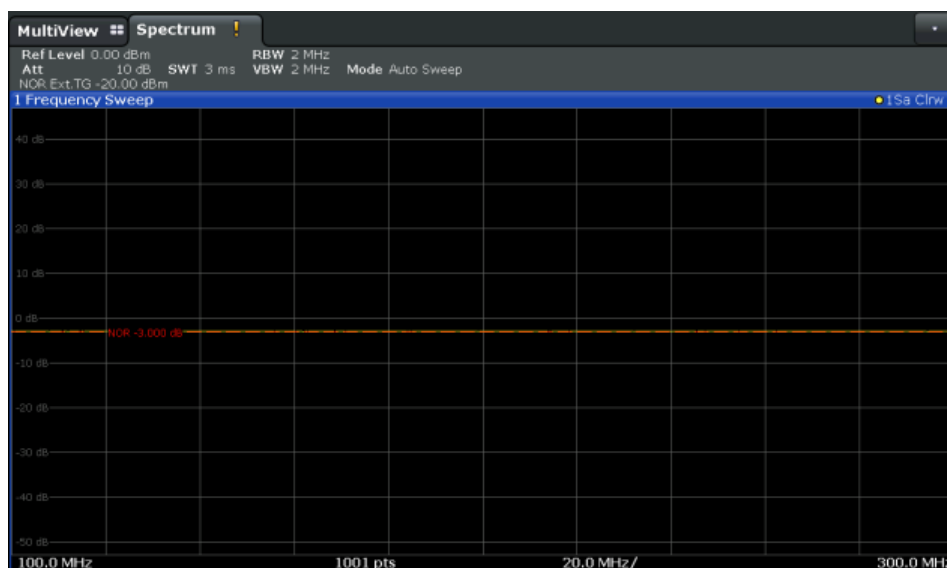


Fig. 6-5: Shifted reference line

If the DUT inserts a gain or an attenuation in the measurement, this effect can be reflected in the result display on the R&S FPS. To reflect a power offset in the measurement trace, change the [Reference Value](#).

For a detailed example see [chapter 6.2.4.5, "Measurement Example: Calibration with an External Generator"](#), on page 325.

Coupling the Frequencies

As described in ["Normalization"](#) on page 309, normalized measurement results are very accurate *as long as the same settings are used as for calibration*. Although approximate normalization is possible, it is important to consider the required frequencies for calibration in advance. The frequencies and levels supported by the connected signal generator are provided for reference with the interface configuration.

Two different methods are available to define the frequencies for calibration, that is to couple the frequencies of the R&S FPS with those of the signal generator:

- **Manual coupling:** a single frequency is defined
- **Automatic coupling:** a series of frequencies is defined (one for each sweep point), based on the current frequency at the RF input of the R&S FPS; the RF frequency range covers the currently defined span of the R&S FPS (unless limited by the range of the signal generator)

Automatic coupling

If automatic coupling is used, the output frequency of the generator (source frequency) is calculated as follows:

$$\text{Source Freq} = \text{RF} \cdot \frac{\text{Numerator}}{\text{Denominator}} + \text{Offset}$$

Output frequency of the generator (6 - 1)

where:

$F_{\text{Generator}}$ = output frequency of the generator

F_{Analyzer} = current frequency at the RF input of the R&S FPS

Numerator = multiplication factor for the current analyzer frequency

Denominator = division factor for the current analyzer frequency

F_{Offset} = frequency offset for the current analyzer frequency, for example for frequency-converting measurements or harmonics measurements

The value range for the offset depends on the selected generator. The default setting is 0 Hz. Offsets other than 0 Hz are indicated by the "FRQ" label in the channel bar (see also "[Displayed Information and Errors](#)" on page 314).

Swept frequency range

The F_{Analyzer} values for the calibration sweep start with the start frequency and end with the stop frequency defined in the "Frequency" settings of the R&S FPS. The resulting output frequencies ([Result Frequency Start](#) and [Result Frequency Stop](#)) are displayed in the "External Generator" > "Measurement Configuration" for reference.

If the resulting frequency range exceeds the allowed ranges of the signal generator, an error message is displayed (see "[Displayed Information and Errors](#)" on page 314) and the [Result Frequency Start](#) and [Result Frequency Stop](#) values are corrected to comply with the range limits.



The calibration sweep nevertheless covers the entire span defined by the R&S FPS; however, no input is received from the generator outside the generator's defined limits.

Reverse sweep

The frequency offset for automatic coupling can be used to sweep in the reverse direction. To do so, define a negative offset in the external generator measurement configuration. (Note that the frequency is defined as the unsigned value of the equation, thus a negative frequency is not possible.)

Example: Example for reverse sweep

$F_{\text{AnalyzerStart}} = 100 \text{ MHz}$

$F_{\text{AnalyzerStop}} = 200 \text{ MHz}$

$F_{\text{Offset}} = -300 \text{ MHz}$

Numerator = Denominator = 1

→ $F_{\text{GeneratorStart}} = 200 \text{ MHz}$

→ $F_{\text{GeneratorStop}} = 100 \text{ MHz}$

If the offset is adjusted so that the sweep of the generator crosses the minimum generator frequency, a message is displayed in the status bar ("Reverse Sweep via min. Ext. Generator Frequency!").

Example: Example for reverse sweep via minimum frequency

$$F_{\text{AnalyzerStart}} = 100 \text{ MHz}$$

$$F_{\text{AnalyzerStop}} = 200 \text{ MHz}$$

$$F_{\text{Offset}} = -150 \text{ MHz}$$

$$F_{\text{min}} = 20 \text{ MHz}$$

$$\text{Numerator} = \text{Denominator} = 1$$

$$\rightarrow F_{\text{GeneratorStart}} = 50 \text{ MHz}$$

$$\rightarrow F_{\text{GeneratorStop}} = 50 \text{ MHz via } F_{\text{min}}$$

Displayed Information and Errors**Channel bar**

If external generator control is active, some additional information is displayed in the channel bar.

Label	Description
EXT TG: <source power>	External generator active; signal sent with <source power> level
LVL	Power Offset (see " Source Offset " on page 318)
FRQ	Frequency Offset (see " (Automatic) Source Frequency (Numerator/Denominator/Offset) " on page 319)
NOR	Normalization on; No difference between reference setting and measurement
APX (approximation)	Normalization on; Deviation from the reference setting occurs
-	Aborted normalization or no calibration performed yet

Error and status messages

The following status and error messages may occur during external generator control.

Message	Description
"Ext. Generator TCP/IP Handshake Error!" /	Connection to the generator is not possible, e.g. due to a cable damage or loose connection or wrong address.
"Ext. Generator Limits Exceeded!"	The allowed frequency or power ranges for the generator were exceeded.
"Reverse Sweep via min. Ext. Generator Frequency!"	Reverse sweep is performed; frequencies are reduced to the minimum frequency, then increased again; see " Reverse sweep " on page 313
"Ext. Generator File Syntax Error!"	Syntax error in the generator setup file (see " Generator Setup Files " on page 308)

Message	Description
"Ext. Generator Command Error!"	Missing or wrong command in the generator setup file (see "Generator Setup Files" on page 308)
"Ext. Generator Visa Error!!"	Error with Visa driver provided with installation (very unlikely)

NOTICE

Overloading

At a reference level of -10 dBm and at an external generator output level of the same value, the R&S FPS operates without overrange reserve. That means the R&S FPS is in danger of being overloaded if a signal is applied whose amplitude is higher than the reference level. In this case, either the message "RF OVLD" for overload or "IF OVLD" for exceeded display range (clipping of the trace at the upper diagram border = overrange) is displayed in the status line.

Overloading can be avoided as follows:

- Reducing the output level of the external generator ("[Source Power](#)" on page 318 in "External Generator > Measurement Configuration")
- Increasing the reference level ([Reference Level](#) in the "Amplitude" menu)

6.2.4.3 External Generator Control Settings

The "External Generator" settings are available in the "Input" dialog box if the R&S FPS External Generator Control option is installed. For each measurement channel one external generator can be configured. To switch between different configurations define multiple measurement channels.

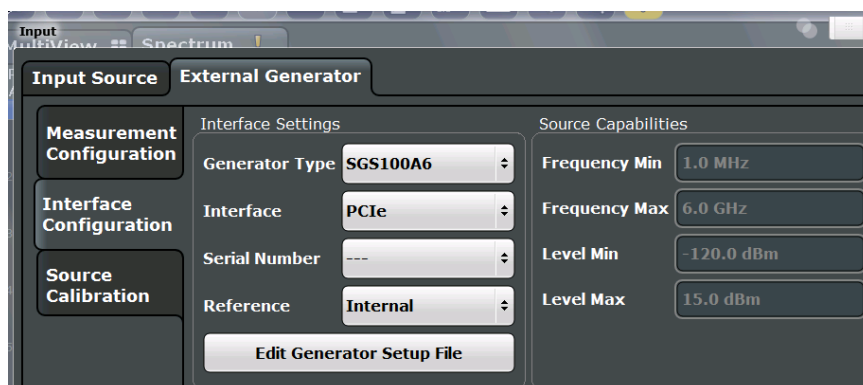
To display this dialog box, press the INPUT/OUTPUT key and then select "External Generator Config".

For more information on external generator control see [chapter 6.2.4.2, "Basics on External Generator Control"](#), on page 306.

- [Interface Configuration Settings](#).....315
- [Measurement Settings](#).....317
- [Source Calibration Functions](#).....320

Interface Configuration Settings

The interface settings for the connection to the external generator are defined in the "Interface Configuration" subtab of the "External Generator" tab.



For more information on configuring interfaces see [chapter 3.4.1, "Remote Control Interfaces and Protocols"](#), on page 48.

Generator Type	316
Interface	316
TCP/IP Address	316
Serial Number	317
Reference	317
Edit Generator Setup File	317
Rescan	317
Frequency Min. / Frequency Max	317
Level Min. / Level Max	317

Generator Type

Selects the generator type and thus defines the generator setup file to use.

For an overview of supported generators see ["Overview of Supported Generators"](#) on page 308. For information on generator setup files see ["Generator Setup Files"](#) on page 308.

Remote command:

[SYSTem:COMMunicate:RDEvice:GENerator:TYPE](#) on page 779

Interface

Type of interface connection used. The following interfaces are currently supported:

- TCP/IP (not by all generators)
- PCIe

For details on which signal generators support which interfaces, see the documentation of the corresponding signal generator.

Remote command:

[SYSTem:COMMunicate:RDEvice:GENerator:INTerface](#) on page 779

TCP/IP Address

For LAN connections only: TCP/IP address of the signal generator

Remote command:

[SYSTem:COMMunicate:TCPIP:RDEvice:GENerator:ADDRess](#) on page 780

Serial Number

For PCIe connections only: Displays the serial numbers of the detected signal generators. If more than one signal generator is found, select the one to use as the external tracking generator.

Remote command:

`SYSTem:COMMunicate:PEXPress:RDEvice:GENerator:ADDress:CATalog?`
on page 779

`SYSTem:COMMunicate:PEXPress:RDEvice:GENerator:ADDress` on page 778

Reference

Selects the internal R&S FPS or an external frequency reference to synchronize the R&S FPS with the generator (default: internal).

Remote command:

`SOURce:EXTernal:ROSCillator[:SOURce]` on page 778

Edit Generator Setup File

Displays the setup file for the currently selected **Generator Type** in read-only mode in an editor.

Although the existing setup files are displayed in read-only mode in the editor, they can be saved under a different name (using "File > SaveAs").

Be careful, however, to adhere to the required syntax and commands. Errors will only be detected and displayed when you try to use the new generator (see also "**Displayed Information and Errors**" on page 314).

For details see "**Generator Setup Files**" on page 308.

Rescan

Repeats a scan for external generators connected to the R&S FPS. This is useful if new generators were connected recently and are not yet displayed in the list of serial numbers.

Remote command:

`SYSTem:COMMunicate:PEXPress:RESCan` on page 779

Frequency Min. / Frequency Max.

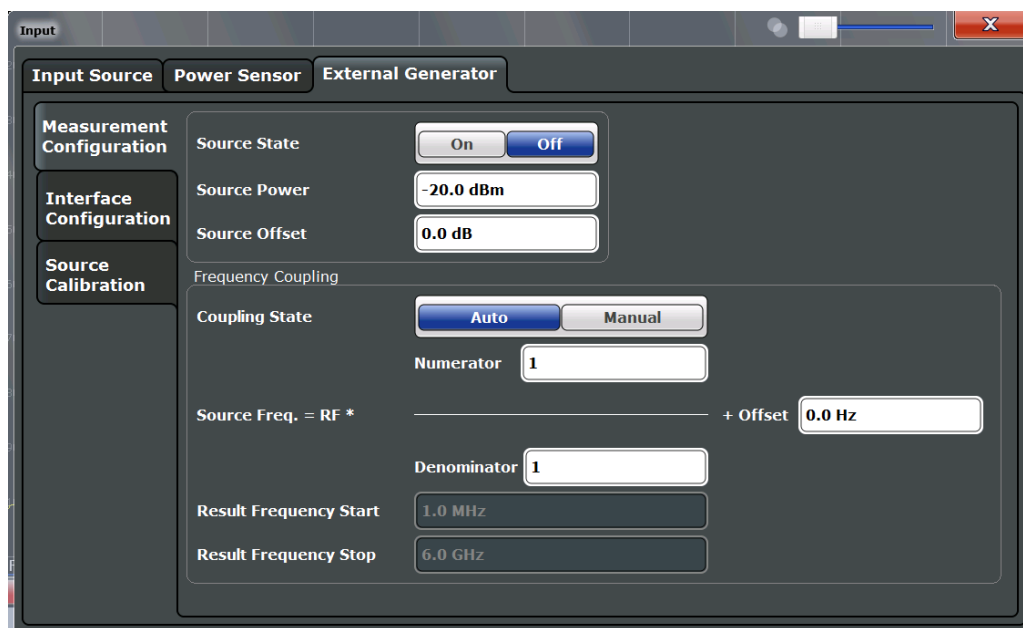
For reference only: Lower and upper frequency limit for the generator.

Level Min. / Level Max.

For reference only: Lower and upper power limit for the generator.

Measurement Settings

The measurement settings for external generator control are configured in the "Measurement Configuration" subtab of the "External Generator" tab.



Source State..... 318
 Source Power.....318
 Source Offset..... 318
 Source Frequency Coupling.....319
 (Manual) Source Frequency.....319
 (Automatic) Source Frequency (Numerator/Denominator/Offset)..... 319
 Result Frequency Start..... 320
 Result Frequency Stop.....320

Source State

Activates or deactivates control of an external generator.

Remote command:

[SOURce:EXTernal\[:STATe\]](#) on page 777

Source Power

The output power of the external generator. The default output power is -20 dBm. The range is specified in the data sheet.

Remote command:

[SOURce:EXTernal:POWER\[:LEVEL\]](#) on page 777

Source Offset

Constant level offset for the external generator. Values from -200 dB to +200 dB in 1 dB steps are allowed. The default setting is 0 dB. Offsets are indicated by the "LVL" label in the channel bar (see also ["Displayed Information and Errors"](#) on page 314).

With this offset, attenuators or amplifiers at the output connector of the external generator can be taken into account for the displayed output power values on screen or during data entry, for example. Positive offsets apply to an amplifier and negative offsets to an attenuator subsequent to the external generator.

Remote command:

`SOURce:POWer[:LEVel][:IMMediate]:OFFSet` on page 777

Source Frequency Coupling

Defines the frequency coupling mode between the R&S FPS and the generator.

For more information on coupling frequencies see "[Coupling the Frequencies](#)" on page 312.

- | | |
|----------|--|
| "Auto" | Default setting: a series of frequencies is defined (one for each sweep point), based on the current frequency at the RF input of the R&S FPS (see " (Automatic) Source Frequency (Numerator/Denominator/Offset) " on page 319); the RF frequency range covers the currently defined span of the R&S FPS (unless limited by the range of the signal generator) |
| "Manual" | The generator uses a single fixed frequency, defined by (Manual) Source Frequency which is displayed when you select "Manual" coupling. |

Remote command:

`SOURce:EXTernal:FREQuency:COUPling[:STATe]` on page 775

(Manual) Source Frequency

Defines the fixed frequency to be used by the generator.

Remote command:

`SOURce:EXTernal:FREQuency` on page 775

(Automatic) Source Frequency (Numerator/Denominator/Offset)

With automatic frequency coupling, a series of frequencies is defined (one for each sweep point), based on the current frequency at the RF input of the R&S FPS.

However, the frequency used by the generator may differ from the input from the R&S FPS. The RF frequency may be multiplied by a specified factor, or a frequency offset can be added, or both.

Note: The input for the generator frequency is not validated, i.e. you can enter any values. However, if the allowed frequency ranges of the generator are exceeded, an error message is displayed on the R&S FPS and the values for [Result Frequency Start](#) and [Result Frequency Stop](#) are corrected to comply with the range limits.

The value range for the offset depends on the selected generator. The default setting is 0 Hz. Offsets \neq 0 Hz are indicated by the "FRQ" label in the channel bar. Negative offsets can be used to define reverse sweeps.

For more information on coupling frequencies and reverse sweeps see ["Coupling the Frequencies"](#) on page 312. For more information on error messages and the channel bar see ["Displayed Information and Errors"](#) on page 314.

Remote command:

[SOURCE:EXTERNAL:FREQUENCY\[:FACTOR\]:DENominator](#) on page 776

[SOURCE:EXTERNAL:FREQUENCY\[:FACTOR\]:NUMerator](#) on page 776

[SOURCE:EXTERNAL:FREQUENCY:OFFSet](#) on page 777

Result Frequency Start

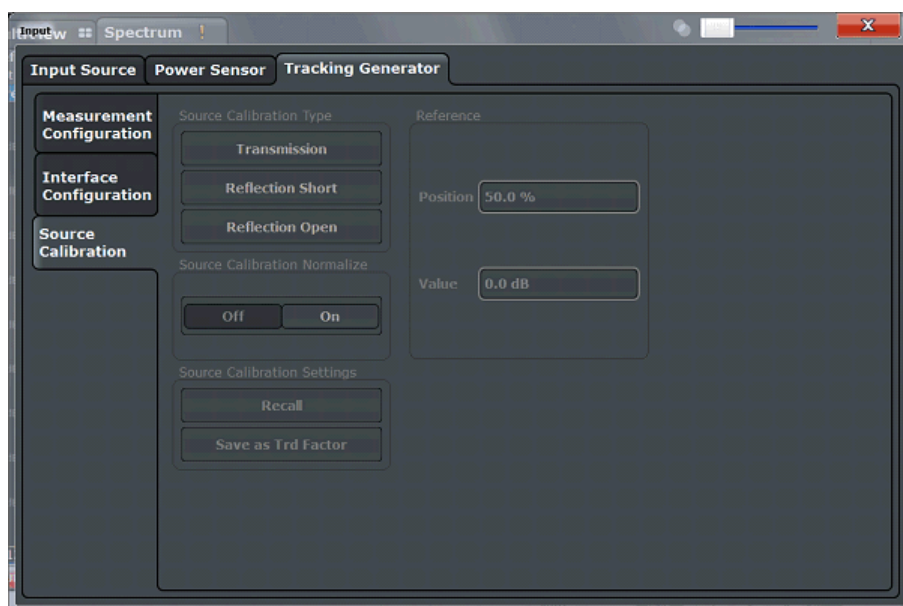
For reference only: The start frequency for the generator, calculated from the configured generator frequency and the start value defined for the R&S FPS.

Result Frequency Stop

For reference only: The stop frequency for the generator, calculated from the configured generator frequency and the stop value defined for the R&S FPS.

Source Calibration Functions

The calibration functions of the external generator are available in the "Source Calibration" subtab of the "External Generator" tab, but *only if external generator control is active* (see ["Source State"](#) on page 318).



Calibrate Transmission	321
Calibrate Reflection Short	321
Calibrate Reflection Open	321
Source Calibration Normalize	321
Recall	321
Save As Trd Factor	322
Reference Position	322
Reference Value	322

Calibrate Transmission

Starts a transmission type measurement to determine a reference trace. This trace is used to calculate the difference for the normalized values.

For details see "[Calibration Mechanism](#)" on page 309.

Remote command:

`[SENSe:]CORRection:METhod` on page 781

Calibrate Reflection Short

Starts a short-circuit reflection type measurement to determine a reference trace for calibration.

If both calibrations (open circuit, short circuit) are carried out, the calibration trace is calculated by averaging the two measurements. The order of the two calibration measurements is irrelevant.

Remote command:

`[SENSe:]CORRection:METhod` on page 781

Selects the reflection method.

`[SENSe:]CORRection:COLLect[:ACQuire]` on page 781

Starts the sweep for short-circuit calibration.

Calibrate Reflection Open

Starts an open-circuit reflection type measurement to determine a reference trace for calibration.

If both reflection-type calibrations (open circuit, short circuit) are carried out, the reference trace is calculated by averaging the two measurements. The order of the two calibration measurements is irrelevant.

Remote command:

`[SENSe:]CORRection:METhod` on page 781

Selects the reflection method.

`[SENSe:]CORRection:COLLect[:ACQuire]` on page 781

Starts the sweep for open-circuit calibration.

Source Calibration Normalize

Switches the normalization of measurement results on or off. This function is only available if the memory contains a reference trace, that is, after a calibration has been performed.

For details on normalization see "[Normalization](#)" on page 309.

Remote command:

`[SENSe:]CORRection[:STATe]` on page 782

Recall

Restores the settings that were used during source calibration. This can be useful if instrument settings were changed after calibration (e.g. center frequency, frequency deviation, reference level, etc).

Remote command:

`[SENSe:]CORRection:RECall` on page 782

Save As Trd Factor

Uses the normalized measurement data to generate a transducer factor. The trace data is converted to a transducer with unit dB and stored in a file with the specified name and the suffix `.trd` under `"c:\r_s\instr\trd"`. The frequency points are allocated in equidistant steps between start and stop frequency. The generated transducer factor can be further adapted using the "Transducer" softkey in the SETUP menu.

For more information on transducers see [chapter 9.2, "Basics on Transducer Factors"](#), on page 506.

This function is only available if [Source Calibration Normalize](#) is switched on.

Note: Note that the *normalized* measurement data is used, not the *reference* trace! Thus, if you store the normalized trace directly after calibration, without changing any settings, the transducer factor will be 0 dB for the entire span (by definition of the normalized trace).

Remote command:

`[SENSe:]CORRection:TRANsducer:GENerator` on page 783

Reference Position

Defines the position of the [Result Frequency Stop](#) in percent of the total y-axis range. The top of the diagram is 100%, the bottom is 0%. By default, the 0 dB line is displayed at the top of the diagram (100%).

This setting is only available if normalization is on (see ["Source Calibration Normalize"](#) on page 321).

The reference line defined by the reference value and reference position is similar to the [Reference Level](#) defined in the "Amplitude" settings. However, this reference line only affects the y-axis scaling in the diagram, it has no effect on the expected input power level or the hardware settings.

The normalized trace (0 dB directly after calibration) is displayed on this reference line, indicated by a red line in the diagram. If you shift the reference line, the normalized trace is shifted, as well.

Remote command:

`DISPlay[:WINDow<n>]:TRACe<t>:Y[:SCALe]:RPOSition` on page 760

Reference Value

Defines the reference value to be displayed at the specified [Result Frequency Start](#).

This setting can be used to shift the reference line and thus the normalized trace, similar to the [Shifting the Display \(Offset\)](#) defined in the "Amplitude" settings shifts the reference level *in the display*.

Shifting the normalized trace is useful, for example, to reflect an attenuation or gain caused by the measured DUT. If you then zoom into the diagram around the normalized trace, the measured trace still remains fully visible.

Remote command:

`DISPlay[:WINDow<n>]:TRACe<t>:Y[:SCALe]:RVALue` on page 780

6.2.4.4 How to Work With External Generator Control

The following step-by-step instructions demonstrate how to work with the optional External Generator Control.

- [How to Calibrate a Measurement Setup using an External Generator](#)..... 323
- [How to Remove the Effects of a Particular Component from Measurement Results Using Calibration](#).....324
- [How to Compensate for Additional Gain or Attenuation after Calibration](#)..... 325

How to Calibrate a Measurement Setup using an External Generator

1. Connect the signal generator's LAN interface connector to the LAN connector on the rear panel of the R&S FPS.
2. Connect the signal generator output to the RF INPUT connector of the R&S FPS.
3. If the measurement setup does not require the full span of the R&S FPS, change the "Frequency Start" and "Frequency Stop" values (FREQ key > "Frequency Config" softkey).
4. Press the INPUT/OUTPUT key and select "External Generator Config".
5. In the "Interface Configuration" subtab, select the "Generator Type" connected to the R&S FPS.
If the required generator type is not available, define a new setup file as described in ["To define a new generator setup file"](#) on page 324.
6. Select the type of interface and the address used to connect the generator to the R&S FPS.
7. Select "Reference: External" to synchronize the analyzer with the generator.
8. Switch to the "Measurement Configuration" subtab.
9. Set the "Source State" to "On".
10. Define the generator output level as the "Source Power".
11. Optionally, to define a constant level offset for the external generator, define a "Source Offset".
12. The default frequency list for the calibration sweep contains 1001 values, divided in equi-distant frequencies between the R&S FPS's start and stop frequency. For most cases, this automatic coupling should be correct. Check the "Result Frequency Start" and "Result Frequency Stop" values to make sure the required measurement span is covered. If necessary, change the frequency settings on the R&S FPS (FREQ key > "Frequency Config" softkey), or use a different generator type.
13. Switch to the "Source Calibration" subtab.
14. Select the "Source Calibration Type": "Transmission" to perform a calibration sweep and store a reference trace for the measurement setup.

15. Select "Source Calibration Normalize": "On".
16. Optionally, shift the reference line further down in the result display by decreasing the "Reference": "Position".

The measurement setup is now calibrated. Subsequent measurement results are normalized, so that any unwanted effects from the cables and connectors are removed.

To define a new generator setup file

1. Press the INPUT/OUTPUT key and select "External Generator Config".
2. In the "Interface Configuration" subtab, select a generator type that has similar characteristics (frequency and power ranges).
3. Select "Edit Generator Setup File".
The configuration file for the selected generator type is displayed (read-only) in an editor.
4. Edit the configuration values according to your generator. Be sure not to change the syntax of the file - only change the *values* of the parameters.
Errors will only be detected and displayed when you try to use the new generator (see also "[Displayed Information and Errors](#)" on page 314).
5. Save the file under a different name with the extension `.gen`:
 - a) In the editor, select "File > SaveAs".
 - b) Select "Save as type: All Files (*.*)".
 - c) Specify a name with the extension `.gen`.
6. In the R&S FPS firmware, close the "External Generator Config" dialog and re-open it.

Now you can select the new generator type from the selection list on the "Interface Configuration" tab.

How to Remove the Effects of a Particular Component from Measurement Results Using Calibration

1. Set up the measurement, including the component, and perform a calibration as described in "[How to Calibrate a Measurement Setup using an External Generator](#)" on page 323.
2. After setting "Source Calibration Normalize": "On", select "Save as Trd Factor" to store the normalized reference trace as a transducer factor.
3. If necessary, switch to another measurement channel for a different R&S FPS application.
4. Press the SETUP key, then select the "Transducer" softkey.
5. Select the stored transducer in the list of available transducers and select the "Active" setting for it.

6. Perform any measurement with the setup that contains the calibrated component.
The measurement results do not include the effects from the component.

How to Compensate for Additional Gain or Attenuation after Calibration

If a gain or an attenuation is inserted in the measurement after calibration, this effect can be reflected in the display of the normalized trace on the R&S FPS. Thus, the measured trace and the normalized trace are not so far apart in the display, so that you can zoom into the normalized trace without cropping the measurement trace.

Prerequisite: a calibration has been performed for the original measurement setup, except for the component causing an additional gain or attenuation (as described in ["How to Calibrate a Measurement Setup using an External Generator"](#) on page 323)

1. Insert the additional component in the calibrated measurement setup and perform a new measurement.
2. Press the INPUT/OUTPUT key and select "External Generator Config".
3. Switch to the "Source Calibration" subtab.
4. With active normalization, set the "Reference": "Value" to the same value as the gain or attenuation the inserted component causes.
5. Optionally, shift the reference line further down in the result display by decreasing the "Reference": "Position".
The normalized reference trace moves to the position of the measured trace.
6. Optionally, zoom into the measured trace by changing the y-axis scaling (or the range: "AMPT > Scale Config > Range").

The measured trace is still fully visible, and the absolute values are still valid.

6.2.4.5 Measurement Example: Calibration with an External Generator

The following measurement example demonstrates the most common functions using an external generator. This example requires the External Generator Control option.

The example assumes an SMW100A generator is connected to the R&S FPS via TCP/IP. A band elimination filter is the device under test. After calibration, an additional attenuator is inserted between the DUT and the R&S FPS.

The following procedures are described:

- ["Calibrating the measurement setup"](#) on page 325
- ["Measuring the effects of the DUT"](#) on page 327
- ["Compensating the effects of additional attenuation after calibration"](#) on page 329

Calibrating the measurement setup

1. Connect the signal generator to the R&S FPS using a LAN cable.
2. Connect the signal generator output to the RF INPUT connector of the R&S FPS.

3. Adapt the measurement range of the R&S FPS to the filter to be tested. In this measurement, define the following settings:
 - a) Press the **FREQ** key, select "Frequency Config" and enter "Frequency Start": *100 MHz*.
 - b) Enter "Frequency Stop": *300 MHz*
4. Press the **INPUT/OUTPUT** key and select "External Generator Config".
5. In the "Interface Configuration" sub-tab, select "Generator Type": "SMW06".
6. Enter the TCP/IP address of the signal generator: *130.094.122.195*
7. Select "Reference: External" to synchronize the analyzer with the generator.
8. Switch to the "Measurement Configuration" sub-tab.
9. Set the "Source State" to "On".
10. Define the generator output level as the "Source Power": *-20 dBm*.
11. Set the "Coupling State" to "Auto".

The "Result Frequency Start" value for the generator is indicated as *100.0 MHz*.
The "Result Frequency Stop" value is indicated as *300.0 MHz*.
12. Switch to the "Source Calibration" sub-tab.
13. Select the "Source Calibration Type": "Transmission" to perform a calibration sweep and store a reference trace for the measurement setup.



Fig. 6-6: Measurement results from generator, analyzer and connecting cables

14. Select "Source Calibration Normalize": "On" to set the measurement results for the current setup to 0, thus eliminating all effects from the generator, the analyzer and

the connecting cables from subsequent measurements with the band elimination filter.

The reference line is displayed at 0 dB at the top of the diagram (100%).



Fig. 6-7: Normalized measurement results after calibration

Measuring the effects of the DUT

After calibration we can insert the band elimination filter (our DUT) in the measurement setup.

1. Connect the signal generator output to the band elimination filter.
2. Connect the band elimination filter output to the RF INPUT connector of the R&S FPS.

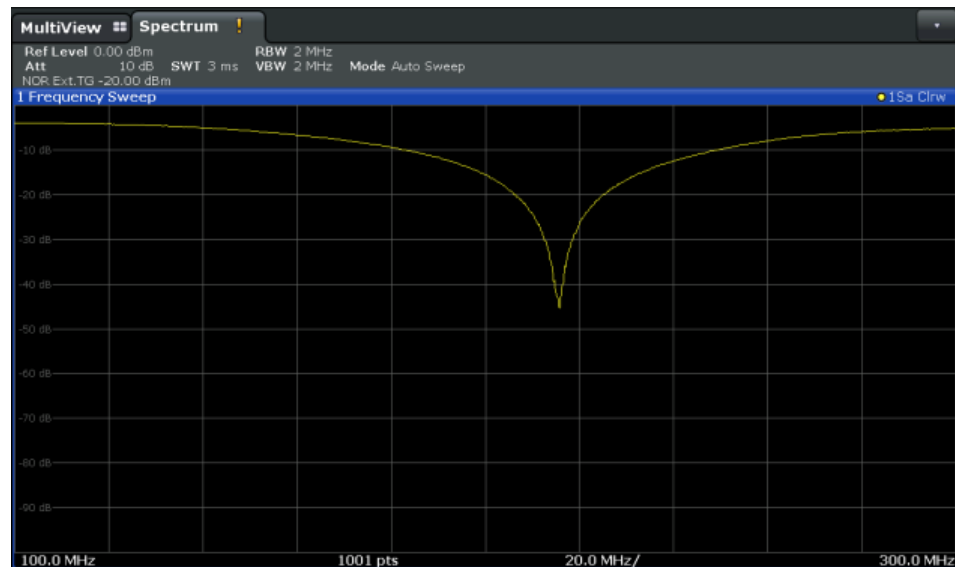


Fig. 6-8: Band elimination filter results

- Shift the reference line from the top of the diagram to the middle of the diagram by changing the position of the reference point 0.0 dB to 50% .
In the "Source Calibration" tab, enter "Position": 50% .

At the same time, the range of the displayed y-axis moves from $[-100.0\text{ dB to }0\text{ dB}]$ to $[-50\text{ dB to }+50\text{ dB}]$.

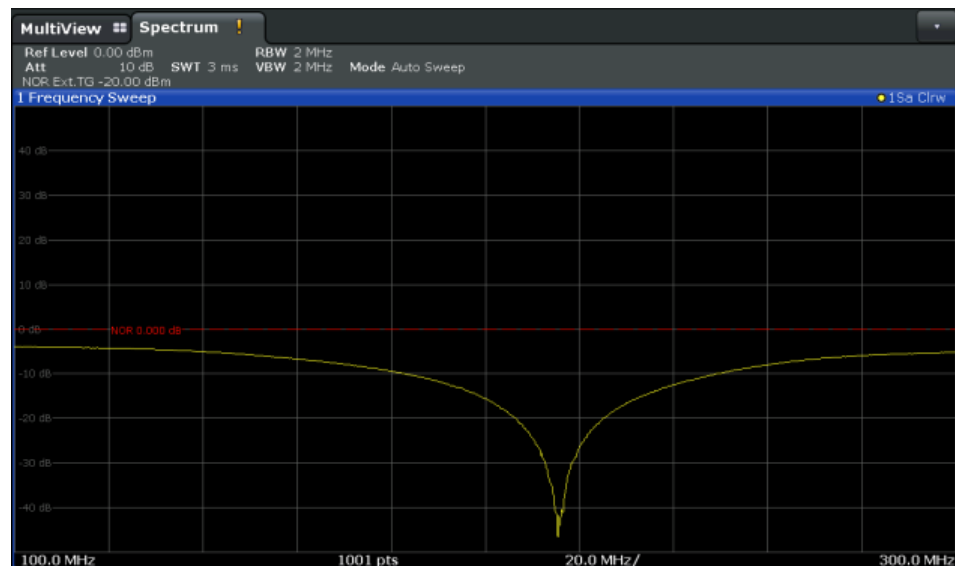


Fig. 6-9: Reference line shifted to middle of diagram (50%)

Compensating the effects of additional attenuation after calibration

After calibration, an additional attenuator is inserted between the DUT and the R&S FPS. This may be necessary, for example, to protect the analyzer's input connector. Nevertheless, we are only interested in the effects of the DUT, not those of the additional protective attenuator. Thus, we will compensate these effects in the result display on the R&S FPS by moving the reference line.

1. Connect a 3 dB attenuator between the band elimination filter output and the RF INPUT connector on the R&S FPS.

The measurement results are now 3 dB lower.

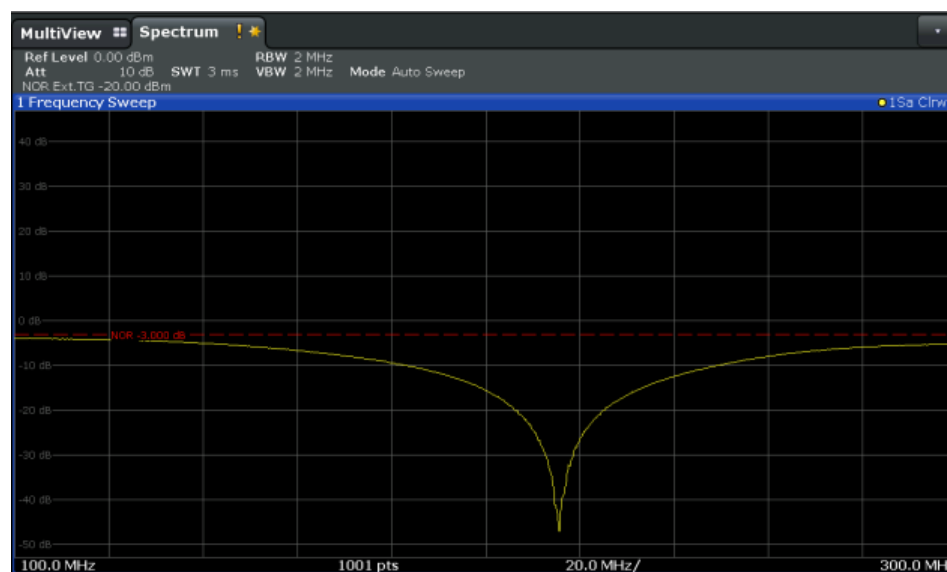


Fig. 6-10: Measurement results with additional attenuator

2. In the "Source Calibration" tab, enter "Reference Value": -3 dB.

The reference line is shifted down by 3 dB so that the measurement trace is displayed on the reference line again.

At the same time, the scaling of the y-axis is changed: -3 dB are now shown at 50% of the diagram; the range is [-53 dB to +47 dB].

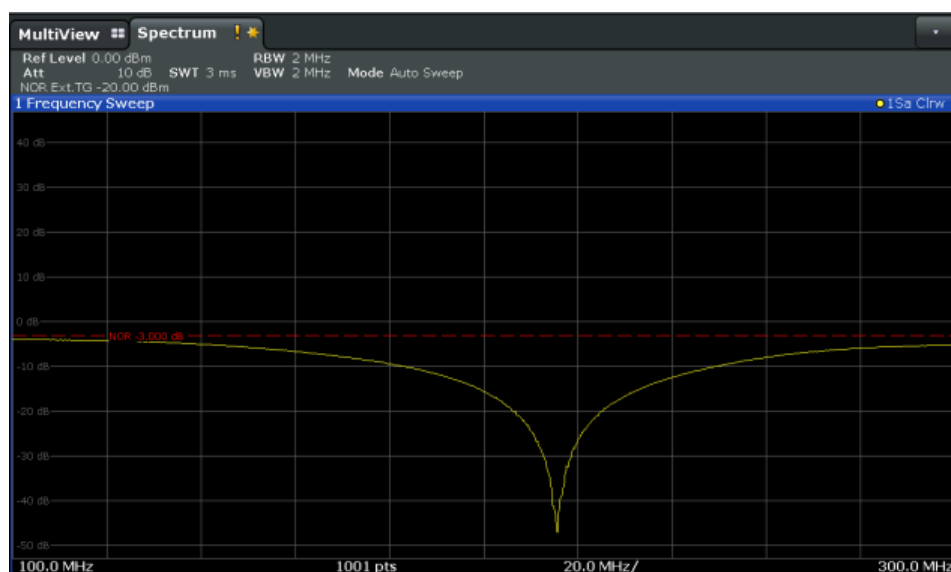


Fig. 6-11: Reference line with an offset of -3 dB and shifted to middle of diagram (50%)

3. After the reference trace has been shifted, you can zoom into the measured trace to determine the offsets to the reference line, which represent the effects of the band elimination filter in the measurement setup. Change the y-axis scaling to 1 dB/div (or the range to 10 dB).
 - a) Press the AMPT key, then select "Scale Config" > "Range".
 - b) Enter 10 dB.

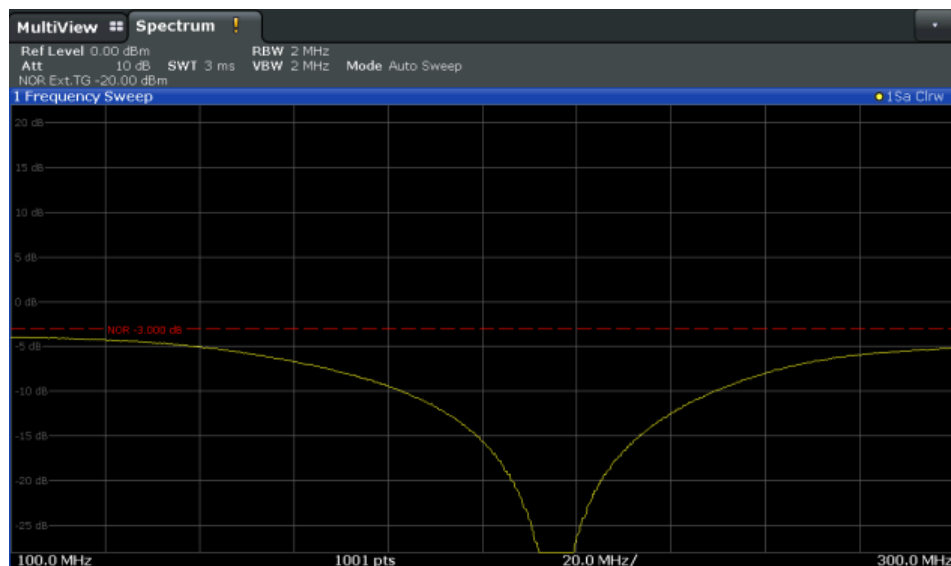


Fig. 6-12: Reference line with measurement results using larger scale

6.2.5 Output Settings

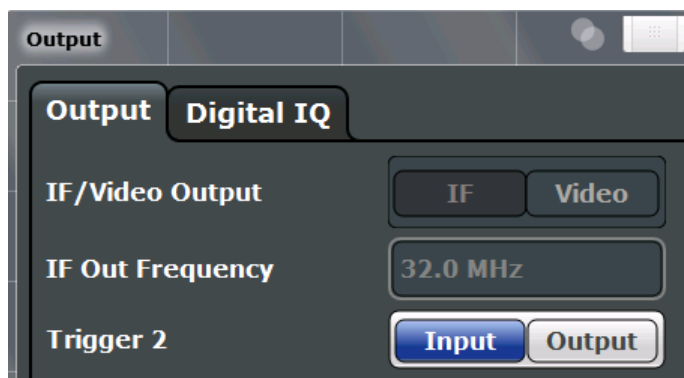
The R&S FPS can provide output to special connectors for other devices.

For details on connectors refer to the R&S FPS Getting Started manual, "Front / Rear Panel View" chapters.



Providing trigger signals as output is described in [chapter 6.6.4, "How to Output a Trigger Signal"](#), on page 382.

Output settings can be configured via the INPUT/OUTPUT key or in the "Outputs" dialog box.



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 L Send Trigger..... 333

IF/Video Output

Defines the type of signal available at the IF/VIDEO output on the rear panel of the R&S FPS.

For restrictions and additional information see [chapter 6.2.1.3, "IF and Video Signal Output"](#), on page 294.

For restrictions and additional information see the R&S FPS I/Q Analyzer and I/Q Input User Manual.

"IF" The measured IF value is available at the IF/VIDEO output connector.

"VIDEO" The displayed video signal (i.e. the filtered and detected IF signal) is available at the IF/VIDEO output connector.
This setting is required to provide demodulated audio frequencies at the output.

Remote command:
`OUTPut: IF[:SOURce]` on page 796

IF Out Frequency

Defines or indicates the frequency at which the IF signal level is provided at the IF/VIDEO connector if [IF/Video Output](#) is set to "IF".

For more information see [chapter 6.2.1.3, "IF and Video Signal Output"](#), on page 294.

Noise Source

Switches the supply voltage for an external noise source on the R&S FPS on or off, if available.

External noise sources are useful when you are measuring power levels that fall below the noise floor of the R&S FPS itself, for example when measuring the noise level of a DUT.

For details see [chapter 6.2.1.1, "Input from Noise Sources"](#), on page 293

Remote command:

[DIAGnostic:SERvice:NSource](#) on page 796

Trigger 2

Defines the usage of the variable TRIGGER AUX connector on the rear panel.

(Trigger 1 is INPUT only.)

"Input" The signal at the connector is used as an external trigger source by the R&S FPS. No further trigger parameters are available for the connector.

"Output" The R&S FPS sends a trigger signal to the output connector to be used by connected devices.
Further trigger parameters are available for the connector.

Remote command:

[OUTPut:TRIGger<port>:LEVel](#) on page 768

[OUTPut:TRIGger<port>:DIRection](#) on page 768

Output Type ← Trigger 2

Type of signal to be sent to the output

"Device Triggered" (Default) Sends a trigger when the R&S FPS triggers.

"Trigger Armed" Sends a (high level) trigger when the R&S FPS is in "Ready for trigger" state.
This state is indicated by a status bit in the `STATUS:OPERation` register (bit 5).
For details see ["STATUS:OPERation Register"](#) on page 562 and the R&S FPS Getting Started manual.

"User Defined" Sends a trigger when user selects "Send Trigger" button.
In this case, further parameters are available for the output signal.

Remote command:

[OUTPut:TRIGger<port>:OTYPe](#) on page 769

Level ← Output Type ← Trigger 2

Defines whether a constant high (1) or low (0) signal is sent to the output connector.

Remote command:

[OUTPut:TRIGger<port>:LEVel](#) on page 768

Pulse Length ← Output Type ← Trigger 2

Defines the length of the pulse sent as a trigger to the output connector.

Remote command:

`OUTPut:TRIGger<port>:PULSe:LENGth` on page 769

Send Trigger ← Output Type ← Trigger 2

Sends a user-defined trigger to the output connector immediately. Note that the trigger pulse level is always opposite to the constant signal level defined by the output "Level" setting, e.g. for "Level = High", a constant high signal is output to the connector until the "Send Trigger" button is selected. Then, a low pulse is sent.

Which pulse level will be sent is indicated by a graphic on the button.

Remote command:

`OUTPut:TRIGger<port>:PULSe:IMMediate` on page 769

6.3 Frequency and Span Configuration

The frequency and span settings define the scope of the signal and spectrum to be analyzed with the R&S FPS.

- [Impact of the Frequency and Span Settings](#)..... 333
- [Frequency and Span Settings](#).....336
- [How To Define the Frequency Range](#).....340
- [How to Move the Center Frequency through the Frequency Range](#)..... 341
- [How to Keep the Center Frequency Stable](#).....341

6.3.1 Impact of the Frequency and Span Settings

Some background knowledge on the impact of the described settings is provided here for a better understanding of the required configuration.

- [Defining the Scope of the Measurement - Frequency Range](#)..... 333
- [Stepping Through the Frequency Range - Center Frequency Stepsize](#)..... 334
- [Keeping the Center Frequency Stable - Signal Tracking](#)..... 334
- [Coping with Large Frequency Ranges - Logarithmic Scaling](#)..... 335

6.3.1.1 Defining the Scope of the Measurement - Frequency Range

The frequency range defines the scope of the signal and spectrum to be analyzed. It can either be defined as a span around a center frequency, or as a range from a start to a stop frequency. Furthermore, the full span comprising the entire possible frequency range can be selected, or a zero span. The full span option allows you to perform an overview measurement over the entire span. Using the "Last Span" function you can easily switch back to the detailed measurement of a specific frequency range.

For sinusoidal signals, the center frequency can be defined automatically by the R&S FPS as the highest frequency level in the frequency span (see ["Adjusting the Center Frequency Automatically \(Auto Freq\)"](#) on page 383).

6.3.1.2 Stepping Through the Frequency Range - Center Frequency Stepsize

Using the arrow keys you can move the center frequency in discrete steps through the available frequency range. The step size by which the center frequency is increased or decreased is defined by the "Center Frequency Stepsize".



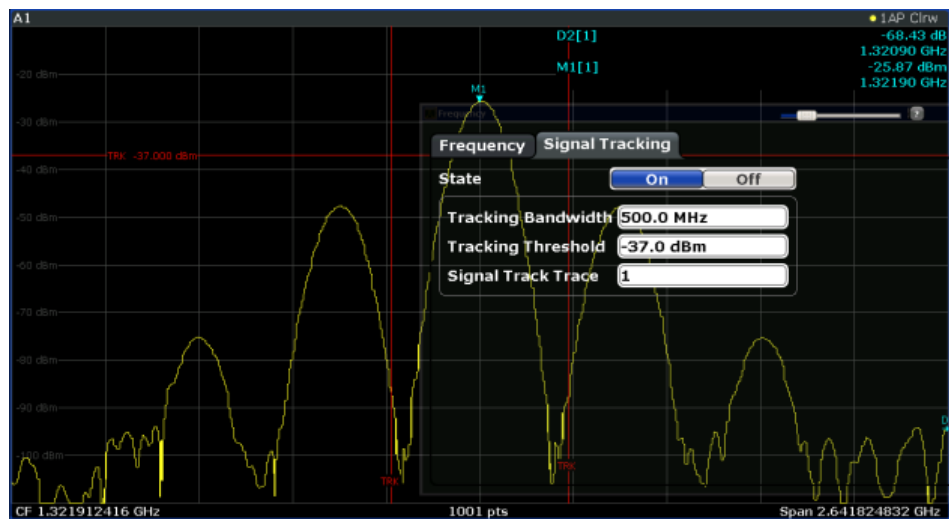
The "Center Frequency Stepsize" also defines the step size by which the value is increased or decreased when you use the rotary knob to change the center frequency; however, the **rotary knob** moves in steps of only **1/10 of the "Center Frequency Stepsize"** to allow for a more precise setting.

By default, the step size is set in relation to the selected span or resolution bandwidth (for zero span measurements). In some cases, however, it may be useful to set the step size to other values.

For example, to analyze signal harmonics, you can define the step size to be equal to the center frequency. In this case, each stroke of the arrow key selects the center frequency of another harmonic. Similarly, you can define the step size to be equal to the current marker frequency.

6.3.1.3 Keeping the Center Frequency Stable - Signal Tracking

If the signal drifts on the display but you want to keep the center frequency on the signal peak, the center frequency can be adjusted automatically using **signal tracking**. In this case, the signal trace is surveyed in a specified bandwidth around the expected center frequency. After each sweep, the center frequency is set to the maximum signal found within the searched bandwidth. If no maximum signal above a defined threshold value is found in the searched bandwidth, the center frequency remains unchanged. The search bandwidth and the threshold value are shown in the diagram by red lines which are labeled as "TRK".



6.3.1.4 Coping with Large Frequency Ranges - Logarithmic Scaling

In a linear display, the frequencies are distributed linearly across the x-axis. That means the entire frequency range is divided by the number of sweep points, and the distance between sweep points is equal. Linear scaling is useful to determine precise frequencies within a small range.



Fig. 6-13: Linear x-axis scaling: the distance between the sweep points is equal, e.g. 200 kHz

However, if high and low frequencies appear in the same display, it is difficult to determine individual frequencies precisely or to distinguish frequencies that are close together.

In a logarithmic display, lower frequencies are distributed among a much larger area of the display, while high frequencies are condensed to a smaller area. Now it is much easier to distinguish several lower frequencies, as they are spread over a wider area. Logarithmic scaling is useful for overview measurements when a large frequency range must be displayed in one diagram.

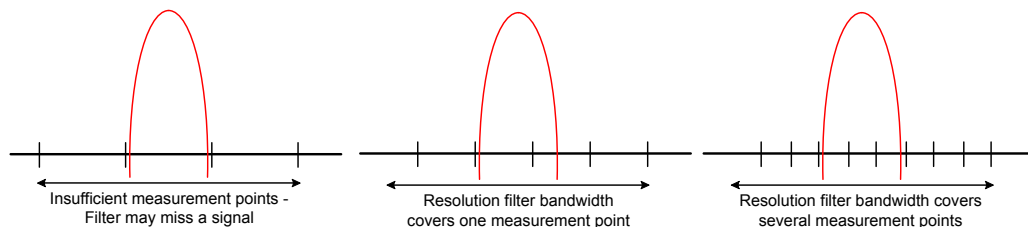
However, with logarithmic scaling, the frequency resolution between two sweep points deteriorates with higher frequencies.



Fig. 6-14: Logarithmic x-axis scaling: the distance between sweep points is variable

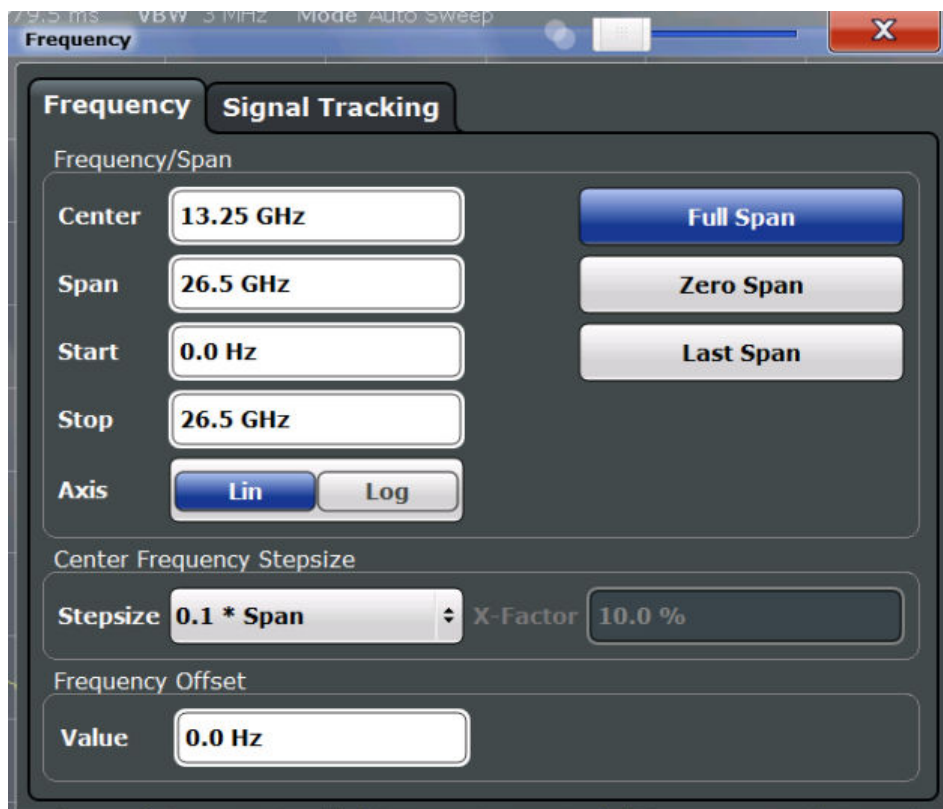
In the spectrum from 10 Hz to 100 Hz, the distance is a few Hz. Between 100 MHz and 1 GHz, the distance is several MHz.

Thus, for logarithmic x-axis scaling, the number of sweep points must be sufficiently high in order to distinguish high frequencies precisely. The resolution bandwidth should cover at least one sweep point (that means: the distance between two sweep points should not exceed the RBW). If this condition is not met, signals or interferers could be missed, especially narrowband interferers.



6.3.2 Frequency and Span Settings

Frequency and span settings can be configured via the "Frequency" dialog box. Signal tracking is configured in the "Signal Tracking" tab of this dialog box. For details see [chapter 6.3.3, "How To Define the Frequency Range"](#), on page 340.





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- └ Tracking Threshold.....340
- └ Signal Track Trace.....340

Center frequency

Defines the normal center frequency of the signal.

The allowed range of values for the center frequency depends on the frequency span.

span > 0: $span_{min}/2 \leq f_{center} \leq f_{max} - span_{min}/2$

zero span: $0 \text{ Hz} \leq f_{center} \leq f_{max}$

f_{max} and $span_{min}$ depend on the instrument and are specified in the data sheet.

Remote command:

[SENSe:] FREQuency:CENTer on page 742

Span

Defines the frequency span. The center frequency is kept constant. The following range is allowed:

span = 0: 0 Hz

span >0:

$$\text{span}_{\min} \leq f_{\text{span}} \leq f_{\max}$$

f_{\max} and span_{\min} are specified in the data sheet.

For more information see [chapter 6.3.1.1, "Defining the Scope of the Measurement - Frequency Range"](#), on page 333.

Remote command:

[\[SENSe:\] FREQuency: SPAN](#) on page 744

Start / Stop

Defines the start and stop frequencies. The following range of values is allowed:

$$f_{\min} \leq f_{\text{start}} \leq f_{\max} - \text{span}_{\min}$$

$$f_{\min} + \text{span}_{\min} \leq f_{\text{stop}} \leq f_{\max}$$

f_{\min} , f_{\max} and span_{\min} are specified in the data sheet.

Remote command:

[\[SENSe:\] FREQuency: START](#) on page 745

[\[SENSe:\] FREQuency: STOP](#) on page 745

Frequency Axis Scaling

Switches between linear and logarithmic scaling for the frequency axis.

By default, the frequency axis has linear scaling. Logarithmic scaling of the frequency axis, however, is common for measurements over large frequency ranges as it enhances the resolution of the lower frequencies. On the other hand, high frequencies get more crowded and become harder to distinguish.

For more information see [chapter 6.3.1.4, "Coping with Large Frequency Ranges - Logarithmic Scaling"](#), on page 335.

Remote command:

[DISPlay\[:WINDow<n>\]:TRACe:X:SPACing](#) on page 742

Full Span

Sets the span to the full frequency range of the R&S FPS specified in the data sheet. This setting is useful for overview measurements.

Remote command:

[\[SENSe:\] FREQuency: SPAN: FULL](#) on page 745

Zero Span

Sets the span to 0 Hz (zero span). The x-axis becomes the time axis with the grid lines corresponding to 1/10 of the current sweep time ("SWT").

For details see [chapter 5.2, "Basic Measurements"](#), on page 116.

Remote command:

[FREQ: SPAN 0Hz](#), see [\[SENSe:\] FREQuency: SPAN](#) on page 744

Last Span

Sets the span to the previous value. With this function you can switch between an overview measurement and a detailed measurement quickly.

Remote command:

[\[SENSe:\] FREQuency:SPAN](#) on page 744

Center Frequency Stepsize

Defines the step size by which the center frequency is increased or decreased when the arrow keys are pressed. When you use the rotary knob the center frequency changes in steps of only 1/10 of the "Center Frequency Stepsize".

The step size can be coupled to the span (span > 0) or the resolution bandwidth (span = 0), or it can be manually set to a fixed value.

For more details see [chapter 6.3.1.2, "Stepping Through the Frequency Range - Center Frequency Stepsize"](#), on page 334.

"0.1 * Span / RBW"

Sets the step size for the center frequency to 10 % of the span / RBW.

This is the default setting.

"0.5 * Span / RBW"

Sets the step size for the center frequency to 50 % of the span / RBW.

"X * Span / RBW"

Sets the step size for the center frequency to a manually defined factor of the span / RBW. The "X-Factor" defines the percentage of the span / RBW.

Values between 1 and 100 % in steps of 1 % are allowed. The default setting is 10 %.

"= Center"

Sets the step size to the value of the center frequency and removes the coupling of the step size to span or resolution bandwidth. The used value is indicated in the "Value" field.

"= Marker"

This setting is only available if a marker is active.

Sets the step size to the value of the current marker and removes the coupling of the step size to span or resolution bandwidth. The used value is indicated in the "Value" field.

"Manual"

Defines a fixed step size for the center frequency. Enter the step size in the "Value" field.

Remote command:

[\[SENSe:\] FREQuency:CENTer:STEP:LINK](#) on page 743

[\[SENSe:\] FREQuency:CENTer:STEP:LINK:FACTor](#) on page 744

[\[SENSe:\] FREQuency:CENTer:STEP](#) on page 742

Frequency Offset

Shifts the displayed frequency range along the x-axis by the defined offset.

This parameter has no effect on the instrument's hardware, or on the captured data or on data processing. It is simply a manipulation of the final results in which absolute frequency values are displayed. Thus, the x-axis of a spectrum display is shifted by a constant offset if it shows absolute frequencies, but not if it shows frequencies relative to the signal's center frequency.

A frequency offset can be used to correct the display of a signal that is slightly distorted by the measurement setup, for example.

The allowed values range from -100 GHz to 100 GHz. The default setting is 0 Hz.

Note: In MSRA mode, this function is only available for the MSRA Master.

Remote command:

`[SENSe:] FREQuency: OFFSet` on page 744

Signal Tracking

Defines the settings for signal tracking. These settings are only available for spans > 0.

For more details see [chapter 6.3.1.3, "Keeping the Center Frequency Stable - Signal Tracking"](#), on page 334.

Signal Tracking State ← Signal Tracking

Activates or deactivates signal tracking. This function is only available for spans > 0.

If activated, after each sweep, the center frequency is set to the maximum level of the specified trace found within the searched bandwidth.

Remote command:

`CALCulate<n>: MARKer<m>: FUNCTion: STRack[: STATE]` on page 746

Tracking Bandwidth ← Signal Tracking

Defines the search bandwidth for signal tracking around the center frequency.

Remote command:

`CALCulate<n>: MARKer<m>: FUNCTion: STRack: BANDwidth` on page 746

Tracking Threshold ← Signal Tracking

Defines the threshold value for signal tracking. If the signal level does not pass the threshold, the center frequency is not changed.

Remote command:

`CALCulate<n>: MARKer<m>: FUNCTion: STRack: THReshold` on page 746

Signal Track Trace ← Signal Tracking

Defines the trace to be tracked.

Remote command:

`CALCulate<n>: MARKer<m>: FUNCTion: STRack: TRACe` on page 746

6.3.3 How To Define the Frequency Range

The following step-by-step instructions demonstrate how to configure the frequency and span settings. For details on individual functions and settings see [chapter 6.3.2, "Frequency and Span Settings"](#), on page 336.

The remote commands required to perform these tasks are described in [chapter 11.7.1, "Defining the Frequency and Span"](#), on page 741.

To configure the frequency and span

Frequency and span settings can be configured via the "Frequency" dialog box. Signal tracking is configured in the "Signal Tracking" tab of this dialog box.

1. To display the "Frequency" dialog box, do one of the following:
 - Select "Frequency" from the "Overview".
 - Select the FREQ key and then the "Frequency Config" softkey.
 - Select the SPAN key and then the "Frequency Config" softkey.
2. Define the frequency range using one of the following methods:
 - Define the "Center frequency" and "Span".
 - Define the "Start frequency" and "Stop frequency".
 - To perform a measurement in the time domain, define the "Center frequency" and select the "Zero span" button.
 - To perform a measurement over the entire available frequency range, select the "Full span" button.
 - To return to the previously set frequency range, select the "Last span" button.

6.3.4 How to Move the Center Frequency through the Frequency Range

In some cases it may be useful to move the center frequency through a larger frequency range, for example from one harmonic to another.

1. In the "Frequency" dialog box, define the "Center Frequency Stepsize". This is the size by which the center frequency is to be increased or decreased in each step. Enter a manual or relative value, or set the step size to the current center frequency or marker value. To move from one harmonic to the next, use the center frequency or marker value.
2. Select the "Center Frequency" dialog field.
3. Use the arrow keys to move the center frequency in discrete steps through the available frequency range.

6.3.5 How to Keep the Center Frequency Stable

If the signal is slightly instable on the display but you want to keep the center frequency on the signal peak, the center frequency can be adjusted automatically using **signal tracking**.

1. In the "Frequency" dialog box, select the "Signal Tracking" tab.
2. Define the following settings:

- "Signal Tracking Bandwidth": the frequency range around the center frequency to be tracked
 - "Signal Tracking Threshold": the minimum level the trace must reach to be detected as a maximum
 - "Signal Tracking Trace": the trace to be tracked
3. Activate signal tracking by selecting "State: ON".

After each sweep, the center frequency is set to the maximum signal found within the searched bandwidth. If no maximum signal above the defined threshold value is found in the searched bandwidth, the center frequency remains unchanged. The search bandwidth and the threshold value are shown in the diagram by red lines which are labeled as "TRK".

6.4 Amplitude and Vertical Axis Configuration

In the Spectrum application, measurement results usually consist of the measured signal levels (amplitudes) displayed on the vertical (y-)axis for the determined frequency spectrum or for the measurement time (horizontal, x-axis). The settings for the vertical axis, regarding amplitude and scaling, are described here.

- [Impact of the Vertical Axis Settings](#).....342
- [Amplitude Settings](#)..... 345
- [Scaling the Y-Axis](#)..... 349
- [How to Optimize the Amplitude Display](#)..... 350

6.4.1 Impact of the Vertical Axis Settings

Some background knowledge on the impact of the described settings is provided here for a better understanding of the required configuration.

- [Reference Level](#).....342
- [RF Attenuation](#)..... 344
- [Scaling](#)..... 344

6.4.1.1 Reference Level

The reference level value is the maximum value the AD converter can handle without distortion of the measured value. Signal levels above this value will not be measured correctly, which is indicated by the "IF OVLD" status display.

Internally, the reference level is also used to determine the optimum hardware settings for the R&S FPS. The defined reference level should correspond with the maximum expected RF input level.



When determining the expected input level, consider that the power from *all* input signals contribute to the total power. The reference level must be higher than the total power from all signals.

The optimum reference level for the current measurement settings can be set automatically by the R&S FPS (see "Reference Level" on page 345).

The reference level determines the amplitude represented by the topmost grid line in the display. When you change the reference level, the measurement is not restarted; the results are merely shifted in the display. Only if the reference level changes due to a coupled RF attenuation (see "Attenuation Mode / Value" on page 347), the measurement is restarted.

In general, the R&S FPS measures the signal voltage at the RF input. The level display is calibrated in RMS values of an unmodulated sine wave signal. In the default state, the level is displayed at a power of 1 mW (= dBm). Via the known input impedance (50 Ω or 75 Ω, see "Impedance" on page 295), conversion to other units is possible.

Reference level offset

If the signal is attenuated or amplified before it is fed into the R&S FPS, you can define an (arithmetic) offset to the reference level so the application shows correct power results. All displayed power level results are shifted by this value, and the scaling of the y-axis is changed accordingly.

To determine the required offset, consider the external attenuation or gain applied to the input signal. For attenuation, define a positive offset so the R&S FPS increases the displayed power values.

If an external gain is applied, define a negative offset so the R&S FPS decreases the displayed power values.

Note, however, that the *internal* reference level (used to adjust the hardware settings to the expected signal optimally) ignores any "Reference Level Offset". Thus, it is important to keep in mind the actual power level the R&S FPS must handle, and not to rely on the displayed reference level.

internal reference level = displayed reference level - offset

Example

1. The initial reference level is 2 dBm with no offset.

Both the displayed reference level and the internal reference level are 2 dBm.

2. An offset of 3 dB is defined.

The displayed reference level is adjusted to 5 dBm.

The internal reference level remains at 2 dBm.

$(5 \text{ dBm (displayed ref level)} - 3 \text{ dB (offset)}) = 2 \text{ dBm}$

3. Now the user decreases the reference level to 1 dBm.

The displayed reference level is adjusted to 1 dBm.

The internal reference level is adjusted to:

$1 \text{ dBm (displayed ref level)} - 3 \text{ dB (offset)} = -2 \text{ dBm}$.

6.4.1.2 RF Attenuation

The attenuation is meant to protect the input mixer from high RF input levels. The level at the input mixer is determined by the set RF attenuation according to the formula:

$$\text{level}_{\text{mixer}} = \text{level}_{\text{input}} - \text{RF attenuation}$$

The maximum mixer level allowed is 0 dBm. Mixer levels above this value may lead to incorrect measurement results, which is indicated by the "RF OVLD" status display. Furthermore, higher input levels may damage the instrument. Therefore, the required RF attenuation is determined automatically according to the reference level by default.

High attenuation levels also avoid intermodulation. On the other hand, attenuation must be compensated for by re-amplifying the signal levels after the mixer. Thus, high attenuation values cause the inherent noise (i.e. the noise floor) to rise and the sensitivity of the analyzer decreases.

The sensitivity of a signal analyzer is directly influenced by the selected RF attenuation. The highest sensitivity is obtained at an RF attenuation of 0 dB. Each additional 10 dB step reduces the sensitivity by 10 dB, i.e. the displayed noise is increased by 10 dB. To measure a signal with an improved signal-to-noise ratio, decrease the RF attenuation.



For ideal sinusoidal signals, the displayed signal level is independent of the RF attenuation.

Depending on the type of measurement evaluation that is required, a compromise must be found between a low noise floor and high intermodulation levels, and protecting the instrument from high input levels. This is best done by letting the R&S FPS determine the optimum level automatically (see ["Attenuation Mode / Value"](#) on page 347).



Electronic attenuation

If the optional electronic attenuation hardware is installed on the R&S FPS, you can also activate an electronic attenuator. For details see ["Using Electronic Attenuation"](#) on page 347.

6.4.1.3 Scaling

In a linear display, the measurement values are distributed linearly throughout the grid. That means the entire range of measured values is divided by the number of rows in the grid (10) and each row corresponds to 1/10 of the total range. Linear scaling is useful to determine precise levels for a small range of values. However, if large and small values appear in the same display, it is difficult to determine individual values precisely or to distinguish values that are close together.

In a logarithmic display, smaller values are distributed among a much larger area of the display, while large values are condensed to a smaller area. Now it is much easier to distinguish several lower values, as they are spread over a wider area. Logarithmic scaling is useful when large ranges of values must be combined in one display. Loga-

rithmetic scaling is best applied to measurement values in logarithmic units (dB, dBm etc.).

In addition to linear or logarithmic scaling, the vertical axis can be set to display either absolute or relative values. Absolute values show the measured levels, while relative values show the difference between the measured level and the defined reference level. Relative values are indicated in percent for linear scaling, and in dB for logarithmic scaling.

6.4.2 Amplitude Settings

Amplitude settings determine how the R&S FPS must process or display the expected input power levels.

To configure the amplitude settings

Amplitude settings can be configured via the AMPT key or in the "Amplitude" dialog box.

- ▶ To display the "Amplitude" dialog box, do one of the following:
 - Select "Amplitude" from the "Overview".
 - Select "Input/Frontend" from the "Overview" and then switch to the "Amplitude" tab.
 - Select the AMPT key and then the "Amplitude Config" softkey.

The remote commands required to define these settings are described in [chapter 11.7.3.1, "Amplitude Settings"](#), on page 755.

Reference Level.....	345
└ Shifting the Display (Offset).....	346
└ Unit.....	346
└ Setting the Reference Level Automatically (Auto Level).....	346
RF Attenuation.....	347
└ Attenuation Mode / Value.....	347
Using Electronic Attenuation.....	347
Input Settings.....	348
└ Preamplifier (option B22/B24).....	348
Noise cancellation.....	348

Reference Level

Defines the expected maximum reference level. Signal levels above this value may not be measured correctly, which is indicated by the "IF OVLD" status display ("OVLD" for digital baseband input).

Defines the expected maximum reference level. Signal levels above this value may not be measured correctly, which is indicated by the "IF OVLD" status display.

The reference level is also used to scale power diagrams; the reference level is then used as the maximum on the y-axis.

Since the hardware of the R&S FPS is adapted according to this value, it is recommended that you set the reference level close above the expected maximum signal level to ensure an optimum measurement (no compression, good signal-to-noise ratio).

For details see [chapter 6.4.1.1, "Reference Level"](#), on page 342.

Remote command:

`DISPlay[:WINDow<n>]:TRACe<t>:Y[:SCALe]:RLEVel` on page 755

Shifting the Display (Offset) ← Reference Level

Defines an arithmetic level offset. This offset is added to the measured level. The scaling of the y-axis is changed accordingly.

Define an offset if the signal is attenuated or amplified before it is fed into the R&S FPS so the application shows correct power results. All displayed power level results will be shifted by this value.

The setting range is ± 200 dB in 0.01 dB steps.

Note, however, that the *internal* reference level (used to adjust the hardware settings to the expected signal optimally) ignores any "Reference Level Offset". Thus, it is important to keep in mind the actual power level the R&S FPS must handle, and not to rely on the displayed reference level (internal reference level = displayed reference level - offset).

For details see ["Reference level offset"](#) on page 343.

Remote command:

`DISPlay[:WINDow<n>]:TRACe<t>:Y[:SCALe]:RLEVel:OFFSet` on page 756

Unit ← Reference Level

The R&S FPS measures the signal voltage at the RF input. In the default state, the level is displayed at a power of 1 mW (= dBm). Via the known input impedance (50 Ω or 75 Ω , see ["Impedance"](#) on page 295), conversion to other units is possible. The following units are available and directly convertible:

- dBm
- dBmV
- dB μ V
- dB μ A
- dBpW
- Volt
- Ampere
- Watt

Remote command:

`INPut:IMPedance` on page 774

`CALCulate<n>:UNIT:POWer` on page 755

Setting the Reference Level Automatically (Auto Level) ← Reference Level

Automatically determines the optimal reference level for the current input data. At the same time, the internal attenuators are adjusted so the signal-to-noise ratio is optimized, while signal compression, clipping and overload conditions are minimized.

To determine the optimal reference level, a level measurement is performed on the R&S FPS.

You can change the measurement time for the level measurement if necessary (see "[Changing the Automatic Measurement Time \(Meastime Manual\)](#)" on page 384).

Remote command:

[SENSe:]ADJust:LEVel on page 772

RF Attenuation

Defines the attenuation applied to the RF input of the R&S FPS.

Attenuation Mode / Value ← RF Attenuation

The RF attenuation can be set automatically as a function of the selected reference level (Auto mode). This ensures that the optimum RF attenuation is always used. It is the default setting.

By default and when [Using Electronic Attenuation](#) is not available, mechanical attenuation is applied.

In "Manual" mode, you can set the RF attenuation in 1 dB steps (down to 0 dB). Other entries are rounded to the next integer value. The range is specified in the data sheet. If the defined reference level cannot be set for the defined RF attenuation, the reference level is adjusted accordingly and the warning "Limit reached" is displayed.

NOTICE! Risk of hardware damage due to high power levels. When decreasing the attenuation manually, ensure that the power level does not exceed the maximum level allowed at the RF input, as an overload may lead to hardware damage.

For details see [chapter 6.4.1.2, "RF Attenuation"](#), on page 344.

Remote command:

INPut:ATTenuation on page 756

INPut:ATTenuation:AUTO on page 757

Using Electronic Attenuation

If the (optional) Electronic Attenuation hardware is installed on the R&S FPS, you can also activate an electronic attenuator.

In "Auto" mode, the settings are defined automatically; in "Manual" mode, you can define the mechanical and electronic attenuation separately.

Note: Electronic attenuation is not available for stop frequencies (or center frequencies in zero span) >7 GHz.

In "Auto" mode, RF attenuation is provided by the electronic attenuator as much as possible to reduce the amount of mechanical switching required. Mechanical attenuation may provide a better signal-to-noise ratio, however.

When you switch off electronic attenuation, the RF attenuation is automatically set to the same mode (auto/manual) as the electronic attenuation was set to. Thus, the RF attenuation may be set to automatic mode, and the full attenuation is provided by the mechanical attenuator, if possible.

Both the electronic and the mechanical attenuation can be varied in 1 dB steps. Other entries are rounded to the next lower integer value.

If the defined reference level cannot be set for the given attenuation, the reference level is adjusted accordingly and the warning "Limit reached" is displayed in the status bar.

Remote command:

`INPut:EATT:STATe` on page 758

`INPut:EATT:AUTO` on page 758

`INPut:EATT` on page 757

Input Settings

Some input settings affect the measured amplitude of the signal, as well.

The parameters "Input Coupling" and "Impedance" are identical to those in the "Input" settings.

See [chapter 6.2.2, "Input Source Settings"](#), on page 294.

Preamplifier (option B22/B24) ← Input Settings

Switches the preamplifier on and off. If activated, the input signal is amplified by 20 dB.

If option R&S FPS-B22 is installed, the preamplifier is only active below 7 GHz.

If option R&S FPS-B24 is installed, the preamplifier is active for all frequencies.

When measuring Spurious Emissions, using this softkey automatically opens the "Sweep List" dialog, see [chapter 5.7.4.1, "Sweep List"](#), on page 243.

Remote command:

`INPut:GAIN:STATe` on page 758

Noise cancellation

The results can be corrected by the instrument's inherent noise, which increases the dynamic range.

In this case, a reference measurement of the instrument's inherent noise is carried out. The measured noise power is then subtracted from the power in the channel that is being analyzed (first active trace only).

The inherent noise of the instrument depends on the selected center frequency, resolution bandwidth and level setting. Therefore, the correction function is disabled whenever one of these parameters is changed. A disable message is displayed on the screen. To enable the correction function after changing one of these settings, activate it again. A new reference measurement is carried out.

Noise cancellation is also available in zero span.

Currently, noise cancellation is only available for the following trace detectors (see ["Detector"](#) on page 411):

- RMS
- Average
- Sample
- Positive Peak

Remote command:

`[SENSe:]POWer:NCORrection` on page 756

6.4.3 Scaling the Y-Axis

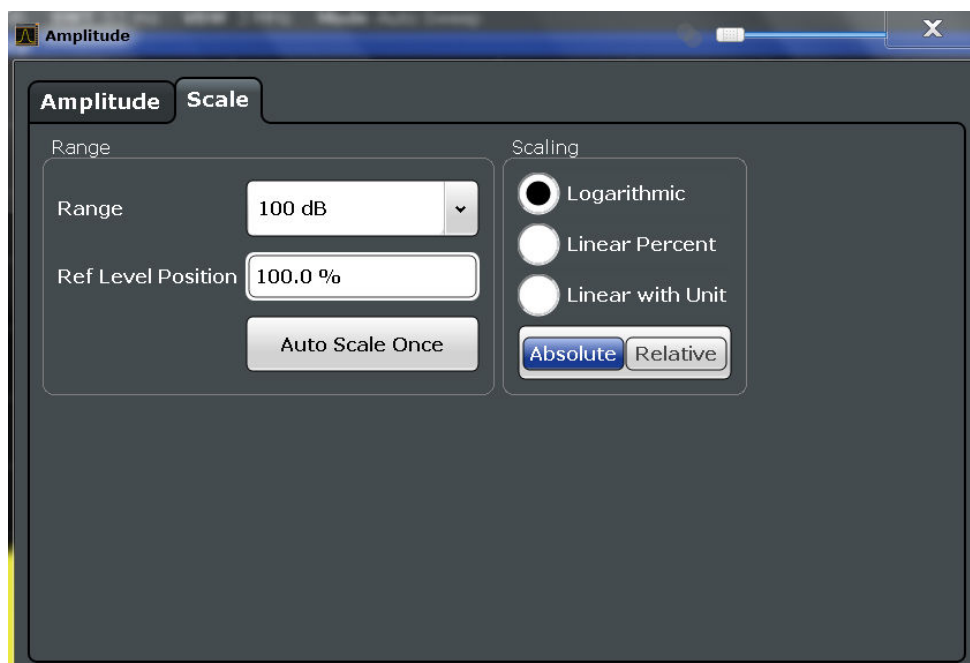
The individual scaling settings that affect the vertical axis are described here.

To configure the y-axis scaling settings

Vertical Axis settings can be configured via the AMPT key or in the "Amplitude" dialog box.

- ▶ To display the "Amplitude" dialog box, do one of the following:
 - Select "Amplitude" from the "Overview".
 - Select the AMPT key and then the "Scale Config" softkey.

The remote commands required to define these settings are described in [chapter 11.7.3, "Configuring the Vertical Axis \(Amplitude, Scaling\)"](#), on page 754.



Range	349
Ref Level Position	350
Auto Scale Once	350
Scaling	350

Range

Defines the displayed y-axis range in dB.

The default value is 100 dB.

Remote command:

`DISPlay[:WINDow<n>]:TRACe<t>:Y[:SCALe]` on page 759

Ref Level Position

Defines the reference level position, i.e. the position of the maximum AD converter value on the level axis in %, where 0 % corresponds to the lower and 100 % to the upper limit of the diagram.

For spectrograms, this value defines the position of the reference level value within the span covered by the color map. In this case, the value is given in %, where 0 % corresponds to the maximum (right end) and 100 % to the minimum (left end) of the color map.

Remote command:

`DISPlay[:WINDow<n>]:TRACe<t>:Y[:SCALe]:RPOSition` on page 760

Auto Scale Once

Automatically determines the optimal range and reference level position to be displayed for the current measurement settings.

The display is only set once; it is not adapted further if the measurement settings are changed again.

Remote command:

`DISPlay[:WINDow<n>]:TRACe<t>:Y[:SCALe]:AUTO ONCE` on page 759

Scaling

Defines the scaling method for the y-axis.

For more information see [chapter 6.4.1.3, "Scaling"](#), on page 344.

"Logarithmic"	Logarithmic scaling (only available for logarithmic units - dB..., and A, V, Watt)
"Linear Unit"	Linear scaling in the unit of the measured signal
"Linear Percent"	Linear scaling in percentages from 0 to 100
"Absolute"	The labeling of the level lines refers to the absolute value of the reference level (not available for "Linear Percent")
"Relative"	The scaling is in dB, relative to the reference level (only available for logarithmic units - dB...). The upper line of the grid (reference level) is always at 0 dB.

Remote command:

`DISPlay[:WINDow<n>]:TRACe<t>:Y:SPACing` on page 760

`DISPlay[:WINDow<n>]:TRACe<t>:Y[:SCALe]:MODE` on page 759

6.4.4 How to Optimize the Amplitude Display

This section gives you some advice on how to optimize the display of the measured signal amplitudes depending on the required evaluation.

1. Perform a measurement with the default settings to get an impression of the values to be expected.
2. Use the "Auto Level" function (AUTO menu) to optimize the reference level.

3. Use the "Auto Scale" function (AUTO menu) to optimize the scaling.
4. **To determine a precise level at a specific point in the signal:**
 - Reduce the "Range" of the y-axis to a small area around the required level. If necessary, change the "Ref Level Position" so the required range remains visible.
 - Select "Linear Unit" scaling.

Now you can set a marker at the point in question and read the result.

5. **To detect a spurious signal close to the noise floor:**
 - Set the "RF attenuation" to "Manual" mode and reduce the "Value" to lower the noise floor.
 - Select "Relative - Logarithmic" scaling.

Now you can determine if any spurious levels of a certain size are visible.

6.5 Bandwidth, Filter and Sweep Configuration

The basic bandwidth, filter and sweep settings that apply to most measurements are described here. These parameters define how the data is measured: how much data is collected internally and which filters are used.

- [Impact of the Bandwidth, Filter and Sweep Settings](#).....351
- [Bandwidth, Filter and Sweep Settings](#)..... 357
- [Reference: List of Available RRC and Channel Filters](#)..... 365

6.5.1 Impact of the Bandwidth, Filter and Sweep Settings

The bandwidth, filter and sweep settings are closely related and interdependent. The values available for resolution bandwidth and video bandwidth depend on the selected filter type. In addition, these settings have an impact on other measurement parameters. The following equation shows the interdependency of these settings:

$$T_{\text{sweepMIN}} = K * \text{Span} / \text{RBW}^2$$

where K = Filter constant

By default, a Gaussian filter is used. The resolution bandwidth, the video bandwidth and the sweep time are set automatically according to the set span, and default coupling is used. Thus, the following settings are applied:

$$\text{RBW} = 100 * \text{Span}$$

$$\text{VBW} = \text{RBW} = 100 * \text{Span}$$

$$\text{Sweep time} = T_{\text{min}} \text{ for set Span, RBW, VBW}$$

When defining the bandwidth and filter settings, consider the impact of the individual settings on the other settings and the measurement result, as described in more detail in the following sections.

• Separating Signals by Selecting an Appropriate Resolution Bandwidth.....	352
• Smoothing the Trace Using the Video Bandwidth.....	353
• Coupling VBW and RBW.....	353
• Coupling Span and RBW.....	353
• How Data is Measured: the Sweep Type.....	354
• Which Data May Pass: Filter Types.....	355
• How Long the Data is Measured: Sweep Time.....	356
• How Much Data is Measured: Sweep Points and Sweep Count.....	356
• How Often Data is Measured: Sweep Mode.....	356

6.5.1.1 Separating Signals by Selecting an Appropriate Resolution Bandwidth

The resolution bandwidth defines the 3 dB bandwidth of the resolution filter to be used. An RF sinusoidal signal is displayed according to the passband characteristic of the resolution filter (RBW), i.e. the signal display reflects the shape of the filter.

A basic feature of a signal analyzer is being able to separate the spectral components of a mixture of signals. The resolution at which the individual components can be separated is determined by the resolution bandwidth. Selecting a resolution bandwidth that is too large may make it impossible to distinguish between spectral components, i.e. they are displayed as a single component. Smaller resolution bandwidths, however, increase the required measurement time.

Two signals with the same amplitude can be resolved if the resolution bandwidth is smaller than or equal to the frequency spacing of the signal. If the resolution bandwidth is equal to the frequency spacing, the spectrum display screen shows a level drop of 3 dB precisely in the center of the two signals. Decreasing the resolution bandwidth makes the level drop larger, which thus makes the individual signals clearer.

The highest sensitivity is obtained at the smallest bandwidth (1 Hz). If the bandwidth is increased, the reduction in sensitivity is proportional to the change in bandwidth. Increasing the bandwidth by a factor of 3 increases the displayed noise by approx. 5 dB (4.77 dB precisely). If the bandwidth is increased by a factor of 10, the displayed noise increases by a factor of 10, i.e. 10 dB.

If there are large level differences between signals, the resolution is determined by selectivity as well as by the resolution bandwidth that has been selected. The measure of selectivity used for signal analyzers is the ratio of the 60 dB bandwidth to the 3 dB bandwidth (= shape factor).

For the R&S FPS, the shape factor for bandwidths is < 5 , i.e. the 60 dB bandwidth of the 30 kHz filter is < 150 kHz.

The higher spectral resolution with smaller bandwidths is won by longer sweep times for the same span. The sweep time has to allow the resolution filters to settle during a sweep at all signal levels and frequencies to be displayed.

If the RBW is too large, signal parts that are very far away (e.g. from a different signal) are considered in the measurement and distort the results. The noise increases.

If the RBW is too small, parts of the signal are lost. As the displayed signal always reflects the shape of the filter, select a bandwidth large enough so the displayed signal reflects the entire shape of the filter.

6.5.1.2 Smoothing the Trace Using the Video Bandwidth

The video filters are responsible for smoothing the displayed trace. Using video bandwidths that are small compared to the resolution bandwidth, only the signal average is displayed and noise peaks and pulsed signals are repressed. If pulsed signals are to be measured, it is advisable to use a video bandwidth that is large compared to the resolution bandwidth ($VBW = 10 \times RBW$) for the amplitudes of pulses to be measured correctly.

The level of a sine wave signal is not influenced by the video bandwidth. A sine wave signal can therefore be freed from noise by using a video bandwidth that is small compared with the resolution bandwidth, and thus be measured more accurately.



RMS/Average detector and VBW

If an RMS or average detector is used, the video bandwidth in the hardware is bypassed. Thus, duplicate trace averaging with small VBWs and RMS or average detector no longer occurs. However, the VBW is still considered when calculating the sweep time. This leads to a longer sweep time for small VBW values. Thus, you can reduce the VBW value to achieve more stable trace curves even when using an RMS or average detector. Normally, if the RMS or average detector is used the sweep time should be increased to get more stable traces.

6.5.1.3 Coupling VBW and RBW

The video bandwidth can be coupled to the resolution bandwidth automatically. In this case, if the resolution bandwidth is changed, the video bandwidth is automatically adjusted.

Coupling is recommended if a minimum sweep time is required for a selected resolution bandwidth. Narrow video bandwidths require longer sweep times due to the longer settling time. Wide bandwidths reduce the signal/noise ratio.

Table 6-1: Overview of RBW/VBW ratios and recommendations for use

Ratio RBW/VBW	Recommendation for use
1/1	Recommended for sinusoidal signals This is the default setting for automatic coupling.
0.1	Recommended when the amplitudes of pulsed signals are to be measured correctly. The IF filter is exclusively responsible for the pulse shape. No additional evaluation is performed by the video filter.
10	Recommended to suppress noise and pulsed signals in the video domain.
Manually set (0.001 to 1000)	Recommended for other measurement requirements

6.5.1.4 Coupling Span and RBW

The resolution bandwidth can be coupled to the span setting, either by a manually defined factor or automatically. If the span is changed, the resolution bandwidth is

automatically adjusted. The automatic coupling adapts the resolution bandwidth to the currently set frequency span/100.

With a span/RBW ratio of 100 and a screen resolution of 1000 pixels, each frequency in the spectrum is displayed by 10 pixels. A span/RBW ratio of 1000 provides the highest resolution.

A higher span/RBW ratio (i.e. low RBW values and large frequency spans), however, results in large amounts of data.

6.5.1.5 How Data is Measured: the Sweep Type

In a standard analog **frequency sweep**, the local oscillator of the analyzer sweeps the applied signal quasi analog from the start to the stop frequency to determine the frequency spectrum.

Alternatively, the analyzer can sample signal levels over time at a defined frequency and transform the data to a spectrum by Fast Fourier Transformation (**FFT**). Although this measurement method requires additional calculations, it can provide results much faster than the frequency sweep, in particular for small RBWs.

Which sweep mode is appropriate for the current measurement depends on the span, RBW, VBW and sweep time settings. By default ("Auto" sweep type), the R&S FPS automatically uses the sweep type with the highest sweep rate depending on these measurement settings.



Restrictions for FFT mode

FFT mode is not available when using 5-Pole filters, Channel filters or RRC filters. In this case, sweep mode is used.

The same applies when an external generator is active (with the optional External Generator Control).

Optimization

In FFT mode, FFT analysis is performed to determine a spectrum of frequencies. Several analysis steps are required to cover the entire span. The partial span which is covered by one FFT analysis depends on the RBW. The partial span cannot be defined directly, but it can be optimized according to measurement requirements.

Narrow partial spans provide a higher dynamic range, and also allow you to perform measurements near a carrier with a reduced reference level. With a wide partial span, the carrier and the useful signal are likely to be measured at the same time, in which case the powers of both signals are summarized, so the reference level must be high enough to consider this factor. With a narrow partial span, this is less likely to happen, so the reference level can be reduced.

For an optimal dynamic range, the narrowest possible partial span (depending on the RBW) is used. Furthermore, the autorange function for the internal IF gain calculation is activated to obtain the best control range of the A/D converter.

On the other hand, the narrower the partial span, the more steps are required to cover the entire span, thus increasing analysis and calculation time. To **optimize the sweep rate**, the widest possible partial span (depending on the RBW) is used.



For an optimal sweep rate, it is recommended that you set the sweep time to "Auto", as well.

For general purpose measurements, an "Auto" mode is available, which provides a **compromise between a large dynamic range and a fast sweep**. In this case, a medium-sized partial span is used.

Optimization for zero span sweeps

For normal sweeps in the time domain (zero span), the optimization mode determines the selection of the A/D converter prefilter, which depends on the RBW.

In **"Dynamic" mode**, the narrowest possible prefilter is used.

In **"Speed" mode**, the widest possible prefilter is used.

In **"Auto" mode**, a medium-sized prefilter is used.

6.5.1.6 Which Data May Pass: Filter Types

While the filter is irrelevant when measuring individual narrowband signals (as long as the signal remains within the RBW), the measurement result for broadband signals is very dependant on the selected filter type and its shape. If the filter is too narrow, the signal is distorted by the filter. If the filter is too wide, multiple signals can no longer be distinguished. Generally, the smaller the filter width and the steeper its edges, the longer the settling time and thus the longer the sweep time must be.

All resolution bandwidths are realized with digital filters. Normal (3dB) Gaussian filters are set by default. Some communication standards require different filters.

For a list of available filter types, see [chapter 6.5.3, "Reference: List of Available RRC and Channel Filters"](#), on page 365.

Normal (3 dB) Gaussian filters

Gaussian filters provide a good compromise between steep edges and a short settling time. This filter is suitable for most measurement tasks and is used by default.

The available Gaussian (3 dB) sweep filters are listed in the R&S FPS data sheet.

Channel filters

Channel filters are fairly steep but require a long settling time; they are useful for pulse measurements in the time domain.

RRC filters

Root raised cosine filters are similar in shape to channel filters and are required by some measurement standards.

5-Pole filters

5-Pole filters are very broad and allow for a large bandwidth to pass.

6.5.1.7 How Long the Data is Measured: Sweep Time

Each filter has a settling time that must be awaited in order to obtain correct results. Since the resolution bandwidth and video bandwidth define the filter, the smaller of the two determines the minimum sweep time required for the measurement. Allowed values depend on the ratio of span to RBW and RBW to VBW.

If the selected sweep time is too short for the selected bandwidth and span, level measurement errors will occur. In this case, the R&S FPS displays the error message "Sweep time too low" and marks the indicated sweep time with a red bullet. Furthermore, a status bit indicates an error (see "[STATus:QUESTIONable:TIME Register](#)" on page 569).

The sweep time can be coupled to the span (not zero span), video bandwidth (VBW) and resolution bandwidth (RBW) automatically. If the span, resolution bandwidth or video bandwidth is changed, the sweep time is automatically adjusted.

6.5.1.8 How Much Data is Measured: Sweep Points and Sweep Count

By default, 1001 data points are determined in a single sweep. During the next sweep, 1001 new data points are collected, and so on. The number of **sweep points** defines how much of the entire span is covered by a single data point. By increasing the number of sweep points you can increase the reliability of the individual data points and thus the accuracy of the analyzed results. However, these data points are all stored on the instrument, occupying a large amount of memory, and each sweep point increases the overall measurement time. Up to 200 000 points can be swept at once.

The number of sweeps to be performed in single sweep mode is defined by the "Sweep Count". Values from 0 to 200000 are allowed. If the values 0 or 1 are set, one sweep is performed. The sweep count is applied to all the traces in a diagram.

If the trace configurations "Average", "Max Hold" or "Min Hold" are set, the "sweep/average count" also determines the number of averaging or maximum search procedures (see [chapter 7.3.1.2, "Analyzing Several Traces - Trace Mode"](#), on page 399).

For details on how the number of sweep points and the sweep count affect the trace results on the screen, see [chapter 7.3.1.1, "Mapping Samples to sweep Points with the Trace Detector"](#), on page 397.

6.5.1.9 How Often Data is Measured: Sweep Mode

How often the spectrum is swept depends on the sweep mode. Either a certain number of sweeps can be defined ("Sweep Count") which are performed in "Single Sweep" mode, or the sweep is repeated continuously ("Continuous Sweep" mode).

By default, the data is collected for the specified number of sweeps and the corresponding trace is displayed. When the next sweep is started, the previous trace is deleted.

However, the data from a single sweep run can also be retained and displayed together with the new data ("Continue Single Sweep" mode). This is particularly of interest when using the trace configurations "Average" or "Max Hold" to take previously recorded measurements into account for averaging/maximum search (see [chapter 7.3.1.2, "Analyzing Several Traces - Trace Mode"](#), on page 399).

6.5.2 Bandwidth, Filter and Sweep Settings

To configure the bandwidth, filter and sweep

Bandwidth and filter settings can be configured via the "Bandwidth" tab of the "Bandwidth" dialog box.

Sweep settings can be configured in the Sweep dialog box or via the "Sweep" tab of the "Bandwidth" dialog box.

1. To display the "Bandwidth" dialog box, do one of the following:
 - Select "Bandwidth" from the "Overview".
 - Select the BW key and then the "Bandwidth Config" softkey.
 - Select the SWEEP key and then the "Sweep Config" softkey.
2. To display the "Sweep" dialog box, do one of the following:
 - Select "Bandwidth" from the "Overview" and switch to the "Sweep" tab in the "Bandwidth" dialog box.
 - Select the SWEEP key and then the "Sweep Config" softkey.

The remote commands required to define these settings are described in [chapter 11.7.2, "Configuring Bandwidth and Sweep Settings"](#), on page 747.

How to perform a basic sweep measurement is described in [chapter 5.2.1, "How to Perform a Basic Sweep Measurement"](#), on page 116.

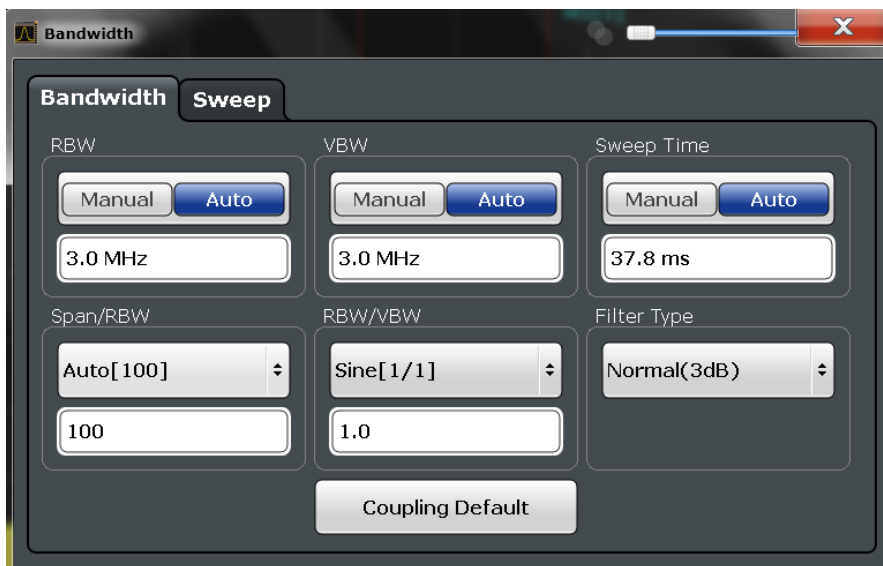


Fig. 6-15: Bandwidth dialog box

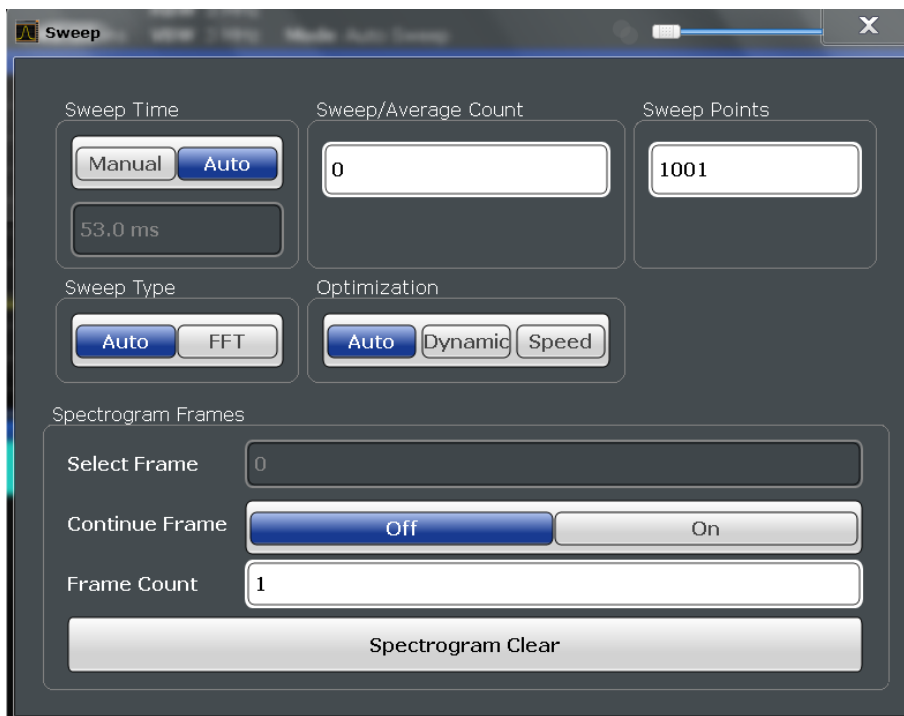


Fig. 6-16: Sweep dialog box for spectrogram display

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RBW

Defines the resolution bandwidth. The available resolution bandwidths are specified in the data sheet. Numeric input is always rounded to the nearest possible bandwidth.

If "AUTO" is selected, the resolution bandwidth is coupled to the selected span (for span > 0). If the span is changed, the resolution bandwidth is automatically adjusted.

If the resolution bandwidth is defined manually, a green bullet is displayed next to the "RBW" display in the channel bar.

For more information see [chapter 6.5.1.1, "Separating Signals by Selecting an Appropriate Resolution Bandwidth"](#), on page 352.

For measurements on I/Q data in the frequency domain, the maximum RBW is 1 MHz.

Remote command:

`[SENSe:]BANDwidth[:RESolution]` on page 747

`[SENSe:]BANDwidth[:RESolution]:AUTO` on page 748

VBW

Defines the video bandwidth automatically or manually.

For more information see [chapter 6.5.1.2, "Smoothing the Trace Using the Video Bandwidth"](#), on page 353.

"Auto" The video bandwidth is coupled to the resolution bandwidth. If the resolution bandwidth is changed, the video bandwidth is automatically adjusted.

"Manual" For manual mode, define the bandwidth value. The available video bandwidths are specified in the data sheet. Numeric input is always rounded to the nearest possible bandwidth.
If the video bandwidth is defined manually, a green bullet is displayed next to the "VBW" display in the channel bar.

Remote command:

`[SENSe:]BANDwidth:VIDeo:AUTO` on page 749

`[SENSe:]BANDwidth:VIDeo` on page 749

Sweep Time

Defines the duration of a single sweep, during which the defined number of sweep points are measured. The sweep time can be defined automatically or manually.

The allowed sweep times depend on the device model; refer to the data sheet.

For more information see [chapter 6.5.1.7, "How Long the Data is Measured: Sweep Time"](#), on page 356.

- "Auto" The sweep time is coupled to the span (not zero span), video bandwidth (VBW) and resolution bandwidth (RBW). If the span, resolution bandwidth or video bandwidth is changed, the sweep time is automatically adjusted.
- "Manual" For manual mode, define the sweep time. Allowed values depend on the ratio of span to RBW and RBW to VBW. For details refer to the data sheet. Numeric input is always rounded to the nearest possible sweep time.

Remote command:

[\[SENSe:\] SWEep:TIME:AUTO](#) on page 753

[\[SENSe:\] SWEep:TIME](#) on page 753

Span/RBW

Sets the coupling ratio if [RBW](#) is set to auto mode.

For more information see [chapter 6.5.1.4, "Coupling Span and RBW"](#), on page 353.

- "Auto [100]" "resolution bandwidth = span/100"
This coupling ratio is the default setting of the R&S FPS.
- "Manual" The coupling ratio is defined manually.
The span/resolution bandwidth ratio can be set in the range from 1 to 10000.

Remote command:

[\[SENSe:\] BANDwidth\[:RESolution\]:RATio](#) on page 748

RBW/VBW

Sets the coupling ratio between the resolution bandwidth and the video bandwidth.

This setting is only effective if [VBW](#) is set to auto mode.

For more information see [chapter 6.5.1.3, "Coupling VBW and RBW"](#), on page 353.

- "Sine [1/1]" "video bandwidth = resolution bandwidth"
This is the default setting for the coupling ratio RBW/VBW and is recommended if sinusoidal signals are to be measured.
- "Pulse [.1]" "video bandwidth = 10 × resolution bandwidth"
or
"video bandwidth = 10 MHz (= max. VBW)"
Recommended for pulse signals
- "Noise [10]" "video bandwidth = resolution bandwidth/10"
Recommended for noise measurements
- "Manual" The coupling ratio is defined manually.
The RBW/VBW ratio can be set in the range of 0.001 to 1000.

Remote command:

[\[SENSe:\] BANDwidth:VIDeo:AUTO](#) on page 749

[\[SENSe:\] BANDwidth:VIDeo:RATio](#) on page 750

Filter Type

Defines the filter type.

The following filter types are available:

- Normal (3dB)
- Channel
- RRC
- 5-Pole (not available for sweep type "FFT")

For more information see [chapter 6.5.1.6, "Which Data May Pass: Filter Types"](#), on page 355.

Remote command:

`[SENSe:]BANDwidth[:RESolution]:TYPE` on page 748

Default Coupling

Sets all coupled functions to the default state ("AUTO"). In addition, the ratio "RBW/VBW" is set to "SINE [1/1]" and the ratio "SPAN/RBW" to 100.

For more information see [chapter 6.5.1.3, "Coupling VBW and RBW"](#), on page 353.

Remote command:

`[SENSe:]BANDwidth[:RESolution]:AUTO` on page 748

`[SENSe:]BANDwidth:VIDeo:AUTO` on page 749

`[SENSe:]SWEep:TIME:AUTO` on page 753

Sweep / Average Count

Defines the number of sweeps to be performed in the single sweep mode. Values from 0 to 200000 are allowed. If the values 0 or 1 are set, one sweep is performed.

The sweep count is applied to all the traces in all diagrams.

If the trace modes "Average", "Max Hold" or "Min Hold" are set, this value also determines the number of averaging or maximum search procedures.

In continuous sweep mode, if sweep count = 0 (default), averaging is performed over 10 sweeps. For sweep count = 1, no averaging, maxhold or minhold operations are performed.

For more information see [chapter 6.5.1.8, "How Much Data is Measured: Sweep Points and Sweep Count"](#), on page 356.

For spectrogram displays, the sweep count determines how many sweeps are combined in one frame in the spectrogram, i.e. how many sweeps the R&S FPS performs to plot one trace in the spectrogram result display. For more details see ["Time Frames"](#) on page 404.

Remote command:

`[SENSe:]SWEep:COUNT` on page 751

`[SENSe:]AVERage<n>:COUNT` on page 802

Sweep Points

Defines the number of measured values to be collected during one sweep.

For details see [chapter 6.5.1.8, "How Much Data is Measured: Sweep Points and Sweep Count"](#), on page 356.

All values from 101 to 32001 can be set. The default value is 1001 sweep points.

Remote command:

[SENSe:] SWEep: POINTs on page 752

Optimization

In FFT mode, several FFT analysis steps are required to cover the entire measurement span. The span which is covered by one FFT analysis step is called *partial span*. The partial span cannot be defined directly, but it can be optimized according to measurement requirements.

Table 6-2: Optimization parameters in FFT mode

Optimization mode	Description
Dynamic	Optimizes the dynamic range by using the narrowest possible partial span (depending on the RBW).
Speed	Optimizes the sweep rate by using the widest possible partial span (depending on the RBW). It is recommended that you set the Sweep Time to "Auto" to optimize the sweep rate.
Auto	Uses a medium-sized partial span to obtain a compromise between a large dynamic range and a fast sweep rate.

Zero span mode

For zero span measurements, the optimization mode defines the selection of the A/D converter prefilter.

Table 6-3: Optimization parameters in zero span mode

Optimization mode	Description
Dynamic	The narrowest filter possible (depending on the RBW) is used.
Speed	The widest filter possible (depending on the RBW) is used.
Auto	A medium-sized prefilter is used.

Remote command:

[SENSe:] SWEep: OPTimize on page 751

Sweep Type

Defines the sweep type.

"Auto" Automatically sets the fastest available sweep type for the current measurement (Frequency or FFT). Auto mode is set by default.

"FFT" The FFT sweep samples on a defined frequency value and transforms it to the spectrum by fast Fourier transformation (FFT) (see also [chapter 6.5.1.5, "How Data is Measured: the Sweep Type"](#), on page 354).

FFT is not available in the following cases:

- when using 5-Pole filters, Channel filters or RRC filters

In these cases, frequency sweep is used.

Remote command:

`[SENSe:]SWEep:TYPE` on page 753

Single Sweep/ RUN SINGLE

After triggering, starts the number of sweeps set in "Sweep Count". The measurement stops after the defined number of sweeps has been performed.

While the measurement is running, the "Single Sweep" softkey and the RUN SINGLE key are highlighted. The running measurement can be aborted by selecting the highlighted softkey or key again.

Remote command:

`INITiate<n>[:IMMediate]` on page 606

`CALCulate<n>:SPECTrogram:CONT` on page 805

Continuous Sweep/RUN CONT

After triggering, starts the measurement and repeats it continuously until stopped.

While the measurement is running, the "Continuous Sweep" softkey and the RUN CONT key are highlighted. The running measurement can be aborted by selecting the highlighted softkey or key again. The results are not deleted until a new measurement is started.

Note: Sequencer. If the Sequencer is active, the "Continuous Sweep" softkey only controls the sweep mode for the currently selected channel; however, the sweep mode only has an effect the next time the Sequencer activates that channel, and only for a channel-defined sequence. In this case, a channel in continuous sweep mode is swept repeatedly.

Furthermore, the RUN CONT key controls the Sequencer, not individual sweeps. RUN CONT starts the Sequencer in continuous mode.

For details on the Sequencer, see [chapter 4.5.1, "The Sequencer Concept"](#), on page 107.

Remote command:

`INITiate<n>:CONTinuous` on page 605

Continue Single Sweep

After triggering, repeats the number of sweeps set in "Sweep Count", without deleting the trace of the last measurement.

While the measurement is running, the "Continue Single Sweep" softkey and the RUN SINGLE key are highlighted. The running measurement can be aborted by selecting the highlighted softkey or key again.

Remote command:

`INITiate<n>:CONMeas` on page 604

Spectrogram Frames

These settings are only available if spectrogram display is active.

For more information see [chapter 7.3.3.2, "How to Display and Configure a Spectrogram"](#), on page 422.

Selecting a frame to display ← Spectrogram Frames

Selects a specific frame, loads the corresponding trace from the memory, and displays it in the Spectrum window.

Note that activating a marker or changing the position of the active marker automatically selects the frame that belongs to that marker.

This function is only available in single sweep mode or if the sweep is stopped, and only if a spectrogram is selected.

The most recent frame is number 0, all previous frames have a negative number.

For more information see ["Time Frames"](#) on page 404.

Remote command:

`CALCulate<n>:SPECTrogram:FRAMe:SElect` on page 806

Continue Frame ← Spectrogram Frames

Determines whether the results of the previous sweeps are included in the analysis of the next sweeps for trace modes "Max Hold", "Min Hold", and "Average".

This function is available in single sweep mode only.

- **On**

When the average or peak values are determined for the new sweep, the results of the previous sweeps in the spectrogram are also taken into account.

- **Off**

The average or peak values are determined from the results of the newly swept frames only.

Remote command:

`CALCulate<n>:SPECTrogram:CONT` on page 805

Frame Count ← Spectrogram Frames

Determines how many frames are plotted during a single sweep measurement (as opposed to a continuous sweep). The maximum number of possible frames depends on the history depth (see ["History Depth"](#) on page 419).

For more details see ["Time Frames"](#) on page 404.

Remote command:

`CALCulate<n>:SPECTrogram:FRAMe:COUNT` on page 806

Clear Spectrogram ← Spectrogram Frames

Resets the spectrogram result display and clears the history buffer.

This function is only available if a spectrogram is selected.

Remote command:

`CALCulate<n>:SPECTrogram:CLEAr[:IMMEDIATE]` on page 805

6.5.3 Reference: List of Available RRC and Channel Filters

For power measurement a number of especially steep-edged channel filters are available (see the following table). The indicated filter bandwidth is the 3 dB bandwidth. For RRC filters, the fixed roll-off factor (α) is also indicated.



The available Gaussian 3 dB sweep filters are listed in the R&S FPS data sheet.

Table 6-4: Filter types

Filter Bandwidth	Filter Type	Application
100 Hz	CFILter	
200 Hz	CFILter	A0
300 Hz	CFILter	
500 Hz	CFILter	
1 kHz	CFILter	
1.5 kHz	CFILter	
2 kHz	CFILter	
2.4 kHz	CFILter	SSB
2.7 kHz	CFILter	
3 kHz	CFILter	
3.4 kHz	CFILter	
4 kHz	CFILter	DAB, Satellite
4.5 kHz	CFILter	
5 kHz	CFILter	
6 kHz	CFILter	
6 kHz, $\alpha=0.2$	RRC	APCO
8.5 kHz	CFILter	ETS300 113 (12.5 kHz channels)
9 kHz	CFILter	AM Radio
10 kHz	CFILter	
12.5 kHz	CFILter	CDMAone
14 kHz	CFILter	ETS300 113 (20 kHz channels)
15 kHz	CFILter	
16 kHz	CFILter	ETS300 113 (25 kHz channels)
18 kHz, $\alpha=0.35$	RRC	TETRA

Filter Bandwidth	Filter Type	Application
20 kHz	CFILter	
21 kHz	CFILter	PDC
24.3 kHz, a=0.35	RRC	IS 136
25 kHz	CFILter	
30 kHz	CFILter	CDPD, CDMAone
50 kHz	CFILter	
100 kHz	CFILter	
150 kHz	CFILter	FM Radio
192 kHz	CFILter	PHS
200 kHz	CFILter	
300 kHz	CFILter	
500 kHz	CFILter	J.83 (8-VSB DVB, USA)
1 MHz	CFILter	CDMAone
1.228 MHz	CFILter	CDMAone
1.28 MHz, a=0.22	RRC	
1.5 MHz	CFILter	DAB
2 MHz	CFILter	
3 MHz	CFILter	
3.75 MHz	CFILter	
3.84 MHz, a=0.22	RRC	W-CDMA 3GPP
4.096 MHz, a=0.22	RRC	W-CDMA NTT DOCoMo
5 MHz	CFILter	
20 MHz	CFILter	
28 MHz	CFILter	
40 MHz	CFILter	

6.6 Trigger and Gate Configuration

Triggering means to capture the interesting part of the signal. Choosing the right trigger type and configuring all trigger settings correctly allows you to detect various incidents in your signals.

Gating allows you to restrict measurement analysis to the important part or parts of the signal, for example bursts.

- [Basics of Triggering and Gated Measurements](#).....367
- [Trigger and Gate Settings](#).....372
- [How to Configure a Triggered and Gated Measurement](#).....379
- [How to Output a Trigger Signal](#).....382

6.6.1 Basics of Triggering and Gated Measurements

Some background knowledge on triggering and gated measurements is provided here for a better understanding of the required configuration settings.

- [Triggered Measurements](#).....367
- [Gated Measurements](#).....370
- [Determining the Parameters in Preview Mode](#).....372

6.6.1.1 Triggered Measurements

In a basic measurement with default settings, the sweep is started immediately. However, sometimes you want the measurement to start only when a specific condition is fulfilled, for example a signal level is exceeded, or in certain time intervals. For these cases you can define a trigger for the measurement. In FFT sweep mode, the trigger defines when the data acquisition starts for the FFT conversion.

An "Offset" can be defined to delay the measurement after the trigger event, or to include data before the actual trigger event in time domain measurements (pre-trigger offset).

For complex tasks, advanced trigger settings are available:

- Hysteresis to avoid unwanted trigger events caused by noise
- Holdoff to define exactly which trigger event will cause the trigger in a jittering signal
- [Trigger Source](#).....367
- [Trigger Offset](#).....368
- [Trigger Hysteresis](#).....368
- [Trigger Drop-Out Time](#).....368
- [Trigger Holdoff](#).....369

Trigger Source

The trigger source defines which source must fulfill the condition that triggers the measurement. Basically, this can be:

- Power: an input signal is checked for a defined power level
The trigger signal can be an internal one (the input signal at one of various stages in the signal analysis process - before or after the input mixer, after the video filter etc.) or it may come from an external device via one of the TRG IN / AUX connectors on the instrument.

For details on the available trigger sources see ["Trigger Source"](#) on page 374.

Trigger Offset

An offset can be defined to delay the measurement after the trigger event, or to include data before the actual trigger event in time domain measurements (pre-trigger offset). Pre-trigger offsets are possible because the R&S FPS captures data continuously in the time domain, even before the trigger occurs.

See ["Trigger Offset"](#) on page 377.

Trigger Hysteresis

Setting a hysteresis for the trigger helps avoid unwanted trigger events caused by noise, for example. The hysteresis is a threshold to the trigger level that the signal must fall below on a rising slope or rise above on a falling slope before another trigger event occurs.

Example:

In the following example, the second possible trigger event is ignored as the signal does not exceed the hysteresis (threshold) before it reaches the trigger level again on the rising edge. On the falling edge, however, two trigger events occur as the signal exceeds the hysteresis before it falls to the trigger level the second time.

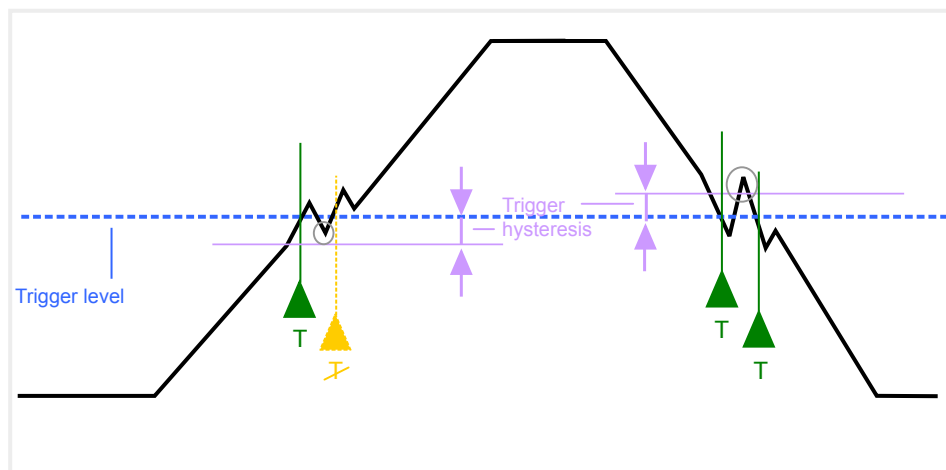


Fig. 6-17: Effects of the trigger hysteresis

See ["Hysteresis"](#) on page 377

Trigger Drop-Out Time

If a modulated signal is instable and produces occasional "drop-outs" during a burst, you can define a minimum duration that the input signal must stay below the trigger level before triggering again. This is called the "drop-out" time. Defining a dropout time helps you stabilize triggering when the analyzer is triggering on undesired events.

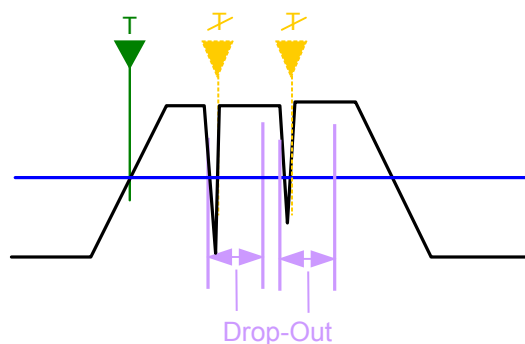


Fig. 6-18: Effect of the trigger drop-out time

See "Drop-Out Time" on page 376.



Drop-out times for falling edge triggers

If a trigger is set to a falling edge ("Slope" = "Falling", see "Slope" on page 377) the measurement is to start when the power level falls below a certain level. This is useful, for example, to trigger at the end of a burst, similar to triggering on the rising edge for the beginning of a burst.

If a drop-out time is defined, the power level must remain below the trigger level at least for the duration of the drop-out time (as defined above). However, if a drop-out time is defined that is longer than the pulse width, this condition cannot be met before the final pulse, so a trigger event will not occur until the pulsed signal is over!

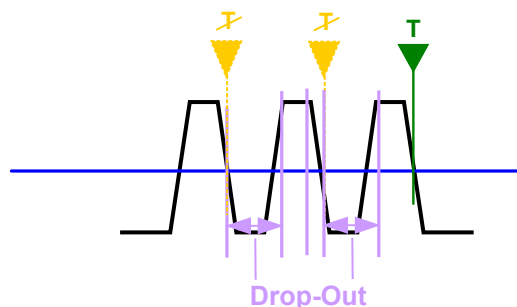


Fig. 6-19: Trigger drop-out time for falling edge trigger

For gated measurements, a combination of a falling edge trigger and a drop-out time is generally not allowed.

Trigger Holdoff

The trigger holdoff defines a waiting period before the next trigger after the current one will be recognized.

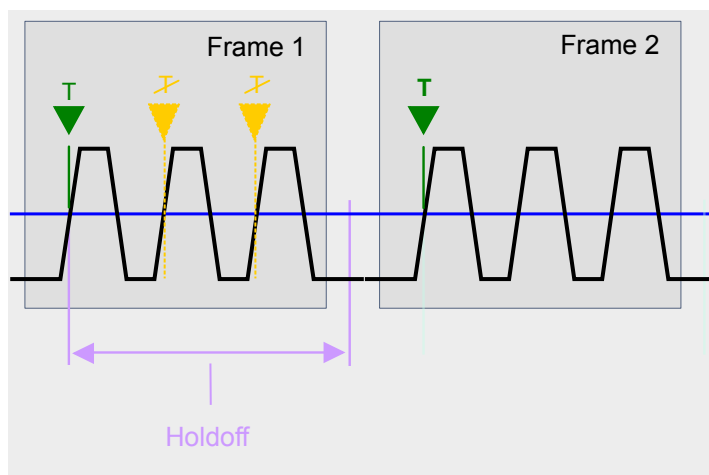


Fig. 6-20: Effect of the trigger holdoff

See "Trigger Holdoff" on page 377.

6.6.1.2 Gated Measurements

Like a gate provides an opening in a fence, a gated measurement lets data from the input signal pass in defined areas only. The *gate* controls exactly when data is included in the measurement results and when not. The gate is opened by the trigger source, which is also the gate source. Gates can be used in two different modes:

- **Level:** The gate opens and the measurement starts when a defined level in the gate source is exceeded and stops when the gate source drops below the "Gate Level".
Using a pulsed gate signal in level mode, the following behaviour can be achieved: When the gate source signal is active, the input signal data is collected; when the gate signal is inactive, the input signal is ignored.
- **Edge:** The gate opens and the measurement starts when a defined level in the gate source is exceeded and stops when the defined "Gate Length" is reached.

Additionally, a delay time can be defined so that the first few measurement points after the gate opening are ignored.

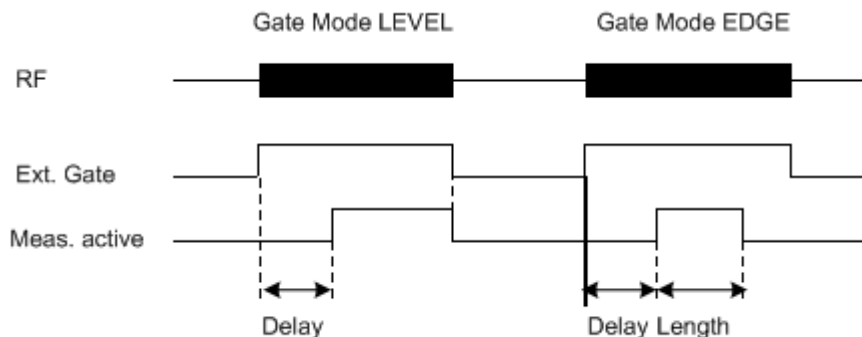


Fig. 6-21: Effects of Gate mode, Gate delay and Gate length

Example:

By using a gate in sweep mode and stopping the measurement while the gate signal is inactive, the spectrum for pulsed RF carriers can be displayed without the superposition of frequency components generated during switching. Similarly, the spectrum can also be analyzed for an inactive carrier. The sweep can be controlled by an external gate or by the internal power trigger.

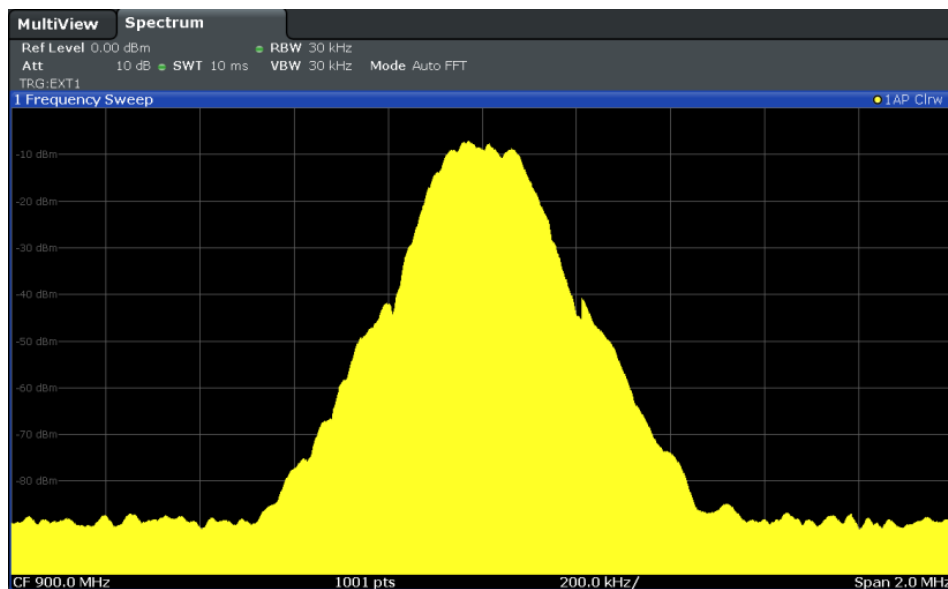


Fig. 6-22: GSM signal with GATE OFF

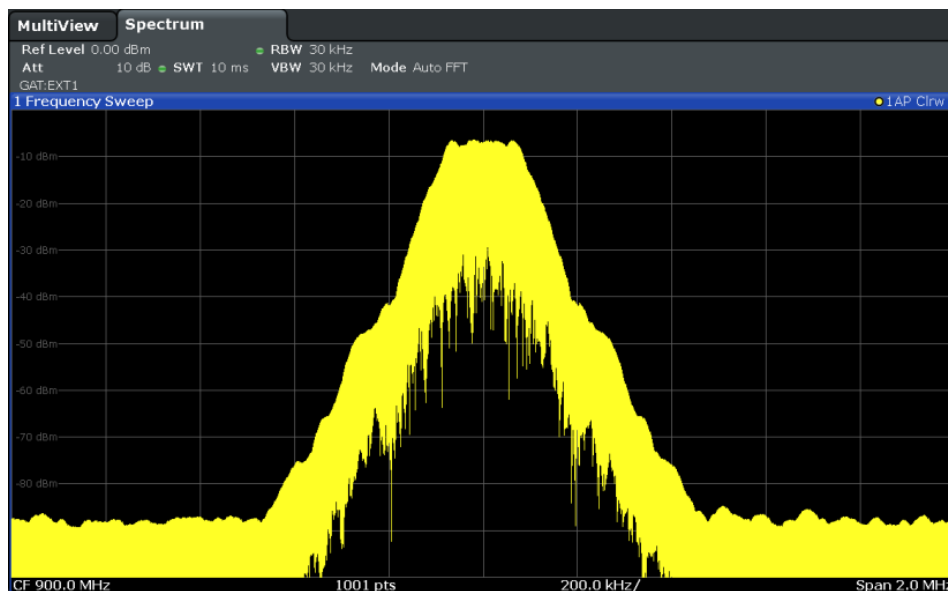


Fig. 6-23: GSM signal with GATE ON

Gated sweep operation is also possible for zero span measurements. This allows you to display level variations of individual slots, for instance in burst signals, versus time.

To indicate that a gate is used for the sweep, "GAT" and the gate source is displayed in the channel bar.

6.6.1.3 Determining the Parameters in Preview Mode

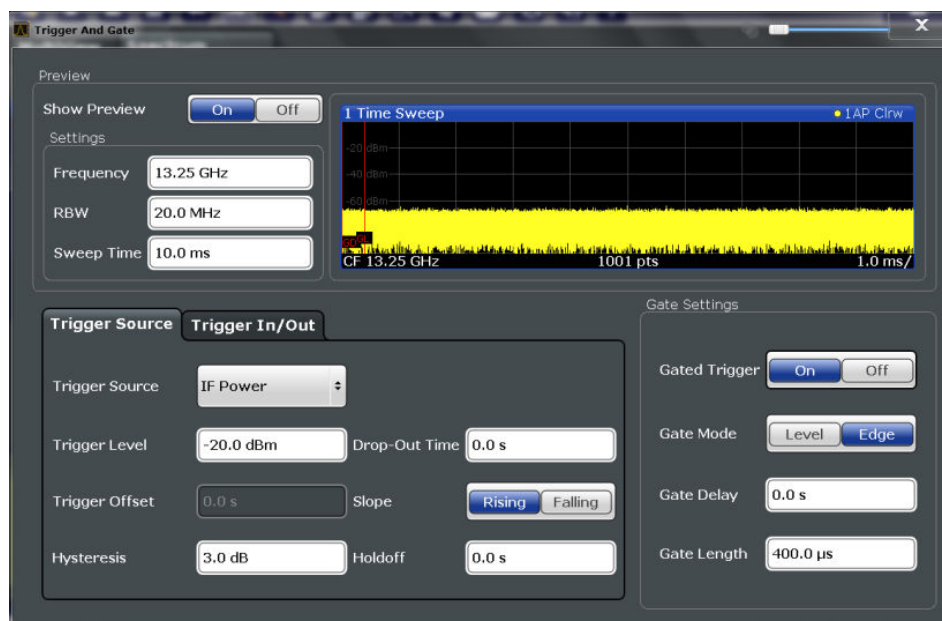
The preview mode allows you to try out trigger and gate settings before actually applying them to the current measurement. When the preview diagram shows the correct results, you can "Update the Main Diagram" and check the results in the background before closing the dialog box.

If preview mode is switched off, changes to the trigger and gate settings are applied to the measurement diagram directly.

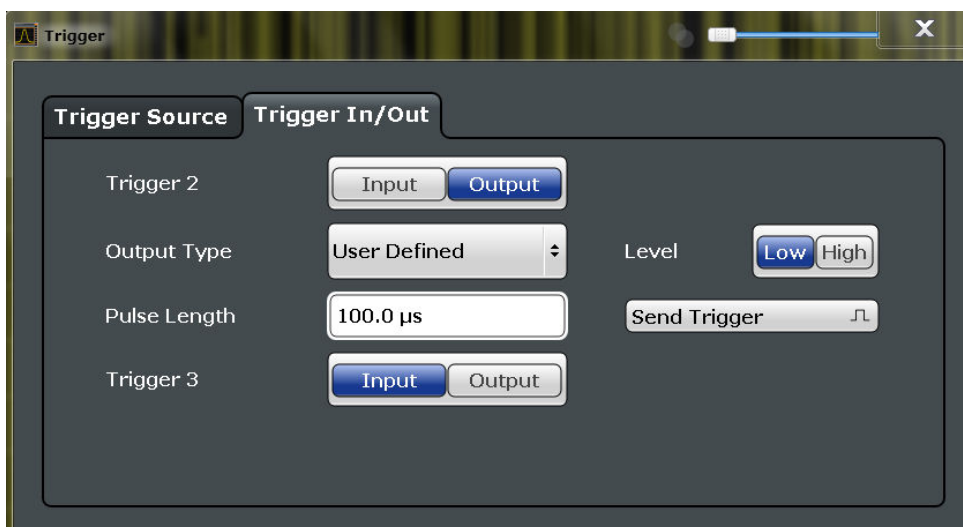
The preview diagram displays a zero span measurement at the center frequency with the defined RBW and sweep time. This is useful to analyze bursts, for example, to determine the required gate settings. The main diagram remains unchanged concerning the zero span settings. Only the trigger and gate settings are applied to the measurement.

6.6.2 Trigger and Gate Settings

Trigger and gate settings can be configured via the TRIG key or in the "Trigger and Gate" dialog box, which is displayed when you select the "Trigger/Gate" button in the "Overview".



External triggers from one of the TRG IN / AUX connectors on the R&S FPS are configured in a separate tab of the dialog box.



For step-by-step instructions on configuring triggered and gated measurements, see chapter 6.6.3, "How to Configure a Triggered and Gated Measurement", on page 379.

- Preview..... 373
 - L Frequency..... 374
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Preview

The preview diagram displays a zero span measurement at the center frequency with the defined RBW and sweep time.

For details see [chapter 6.6.1.3, "Determining the Parameters in Preview Mode"](#), on page 372.

Note: The zero span settings refer only to the preview diagram. The main diagram remains unchanged.

The trigger and gate settings are applied to the measurement when the dialog box is closed or "Update Main Diagram" is selected.

If preview mode is switched off, any changes to the settings in this dialog box are applied to the measurement diagram directly. In this case, the zero span settings for the preview diagram are not displayed.

For information on the zero span settings see:

- ["Center frequency"](#) on page 337
- ["RBW"](#) on page 359
- ["Sweep Time"](#) on page 359

Frequency ← Preview

Defines the center frequency.

Remote command:

[\[SENSe:\] FREQuency:CENTer](#) on page 742

RBW ← Preview

Defines the bandwidth value. The available resolution bandwidths are specified in the data sheet. Numeric input is always rounded to the nearest possible bandwidth.

Remote command:

[\[SENSe:\] BANDwidth\[:RESolution\]](#) on page 747

Sweep Time ← Preview

Defines the sweep time. Allowed values depend on the ratio of span to RBW and RBW to VBW. For details refer to the data sheet. Numeric input is always rounded to the nearest possible sweep time.

Remote command:

[\[SENSe:\] SWEEp:TIME](#) on page 753

Trigger Settings

The trigger settings define the beginning of a measurement.

Trigger Source ← Trigger Settings

Selects the trigger source. If a trigger source other than "Free Run" is set, "TRG" is displayed in the channel bar and the trigger source is indicated.

For gated measurements, this setting also selects the gating source.

For more information see ["Trigger Source"](#) on page 367.

Remote command:

[TRIGger\[:SEQuence\]:SOURce](#) on page 764

[\[SENSe:\] SWEEp:EGATE:SOURce](#) on page 767

Free Run ← Trigger Source ← Trigger Settings

No trigger source is considered. Data acquisition is started manually or automatically and continues until stopped explicitly.

In the Spectrum application, this is the default setting.

Remote command:

TRIG:SOUR IMM, see [TRIGger\[:SEquence\]:SOURce](#) on page 764

External Trigger 1/2 ← Trigger Source ← Trigger Settings

Data acquisition starts when the TTL signal fed into the specified input connector meets or exceeds the specified trigger level.

(See ["Trigger Level"](#) on page 376).

Note: The "External Trigger 1" softkey automatically selects the trigger signal from the TRG IN connector.

For details see the "Instrument Tour" chapter in the R&S FPS Getting Started manual.

"External Trigger 1"

Trigger signal from the TRG IN connector.

"External Trigger 2"

Trigger signal from the TRG AUX connector.

Note: Connector must be configured for "Input" in the "Outputs" configuration (see ["Trigger 2"](#) on page 332).

Remote command:

TRIG:SOUR EXT, TRIG:SOUR EXT2

See [TRIGger\[:SEquence\]:SOURce](#) on page 764

SWE:EGAT:SOUR EXT for gated triggering, see [\[SENSe:\]SWEep:EGATe:SOURce](#) on page 767

Video ← Trigger Source ← Trigger Settings

Defines triggering by the video signal, i.e. the filtered and detected version of the input signal (the envelope of the IF signal), as displayed on the screen.

Define a trigger level from 0 % to 100 % of the diagram height. The absolute trigger level is indicated by a horizontal trigger line in the diagram, which you can also move graphically to change the trigger level.

Video mode is only available in the time domain, and not for I/Q-based data.

Remote command:

TRIG:SOUR VID, see [TRIGger\[:SEquence\]:SOURce](#) on page 764

SWE:EGAT:SOUR VID for gated triggering, see [\[SENSe:\]SWEep:EGATe:SOURce](#) on page 767

IF Power ← Trigger Source ← Trigger Settings

The R&S FPS starts capturing data as soon as the trigger level is exceeded around the third intermediate frequency.

For frequency sweeps, the third IF represents the start frequency. The trigger bandwidth at the third IF depends on the RBW and sweep type.

For measurements on a fixed frequency (e.g. zero span or I/Q measurements), the third IF represents the center frequency.

This trigger source is only available for RF input.

The available trigger levels depend on the RF attenuation and preamplification. A reference level offset, if defined, is also considered.

For details on available trigger levels and trigger bandwidths see the data sheet.

Note: Be aware that in auto sweep type mode, due to a possible change in sweep types, the trigger bandwidth may vary considerably for the same RBW setting.

Remote command:

TRIG:SOUR IFP, see [TRIGger\[:SEquence\]:SOURce](#) on page 764

SWE:EGAT:SOUR IFP for gated triggering, see [\[SENSe:\]SWEep:EGATe:SOURce](#) on page 767

RF Power ← Trigger Source ← Trigger Settings

Defines triggering of the measurement via signals which are outside the displayed measurement range.

For this purpose the instrument uses a level detector at the first intermediate frequency.

The input signal must be in the frequency range between 500 MHz and 7 GHz.

The resulting trigger level at the RF input depends on the RF attenuation and preamplification. For details on available trigger levels see the instrument's data sheet.

Note: If the input signal contains frequencies outside of this range (e.g. for fullspan measurements), the sweep may be aborted and a message indicating the allowed input frequencies is displayed in the status bar.

A "Trigger Offset", "Trigger Polarity" and "Trigger Holdoff" (to improve the trigger stability) can be defined for the RF trigger, but no "Hysteresis".

Remote command:

TRIG:SOUR RFP, see [TRIGger\[:SEquence\]:SOURce](#) on page 764

SWE:EGAT:SOUR RFP for gated triggering, see [\[SENSe:\]SWEep:EGATe:SOURce](#) on page 767

Trigger Level ← Trigger Settings

Defines the trigger level for the specified trigger source.

For gated measurements, this setting also defines the gate level.

For details on supported trigger levels, see the data sheet.

Remote command:

[TRIGger\[:SEquence\]:LEVel:IFPower](#) on page 763

[TRIGger\[:SEquence\]:LEVel:IQPower](#) on page 763

[TRIGger\[:SEquence\]:LEVel\[:EXternal<port>\]](#) on page 762

[TRIGger\[:SEquence\]:LEVel:VIDeo](#) on page 764

[TRIGger\[:SEquence\]:LEVel:RFPower](#) on page 763

Drop-Out Time ← Trigger Settings

Defines the time the input signal must stay below the trigger level before triggering again.

For more information on the drop-out time see "[Trigger Drop-Out Time](#)" on page 368.

Remote command:

[TRIGger\[:SEquence\]:DTIME](#) on page 761

Trigger Offset ← Trigger Settings

Defines the time offset between the trigger event and the start of the sweep .

For more information see "[Trigger Offset](#)" on page 368.

offset > 0:	Start of the sweep is delayed
offset < 0:	Sweep starts earlier (pre-trigger) Only possible for zero span (e.g. I/Q Analyzer application) and gated trigger switched off Maximum allowed range limited by the sweep time: $\text{pretrigger}_{\text{max}} = \text{sweep time}_{\text{max}}$

Remote command:

[TRIGger\[:SEquence\]:HOLDoff\[:TIME\]](#) on page 761

Hysteresis ← Trigger Settings

Defines the distance in dB to the trigger level that the trigger source must exceed before a trigger event occurs. Setting a hysteresis avoids unwanted trigger events caused by noise oscillation around the trigger level.

This setting is only available for "IF Power" trigger sources. The range of the value is between 3 dB and 50 dB with a step width of 1 dB.

For more information see "[Trigger Hysteresis](#)" on page 368.

Remote command:

[TRIGger\[:SEquence\]:IFPower:HYSteresis](#) on page 762

Trigger Holdoff ← Trigger Settings

Defines the minimum time (in seconds) that must pass between two trigger events. Trigger events that occur during the holdoff time are ignored.

For more information see "[Trigger Holdoff](#)" on page 369.

Remote command:

[TRIGger\[:SEquence\]:IFPower:HOLDoff](#) on page 762

Slope ← Trigger Settings

For all trigger sources except time you can define whether triggering occurs when the signal rises to the trigger level or falls down to it.

For gated measurements in "Edge" mode, the slope also defines whether the gate starts on a falling or rising edge.

Remote command:

[TRIGger\[:SEquence\]:SLOPe](#) on page 764

[\[SENSe:\]SWEep:EGATE:POLarity](#) on page 766

Trigger 2

Defines the usage of the variable TRIGGER AUX connector on the rear panel.

(Trigger 1 is INPUT only.)

"Input" The signal at the connector is used as an external trigger source by the R&S FPS. No further trigger parameters are available for the connector.

"Output" The R&S FPS sends a trigger signal to the output connector to be used by connected devices.
Further trigger parameters are available for the connector.

Remote command:

[OUTPut:TRIGger<port>:LEVel](#) on page 768

[OUTPut:TRIGger<port>:DIRection](#) on page 768

Output Type ← Trigger 2

Type of signal to be sent to the output

"Device Triggered" (Default) Sends a trigger when the R&S FPS triggers.

"Trigger Armed" Sends a (high level) trigger when the R&S FPS is in "Ready for trigger" state.
This state is indicated by a status bit in the `STATUS:OPERation` register (bit 5).
For details see "[STATUS:OPERation Register](#)" on page 562 and the R&S FPS Getting Started manual.

"User Defined" Sends a trigger when user selects "Send Trigger" button.
In this case, further parameters are available for the output signal.

Remote command:

[OUTPut:TRIGger<port>:OTYPe](#) on page 769

Level ← Output Type ← Trigger 2

Defines whether a constant high (1) or low (0) signal is sent to the output connector.

Remote command:

[OUTPut:TRIGger<port>:LEVel](#) on page 768

Pulse Length ← Output Type ← Trigger 2

Defines the length of the pulse sent as a trigger to the output connector.

Remote command:

[OUTPut:TRIGger<port>:PULSe:LENGth](#) on page 769

Send Trigger ← Output Type ← Trigger 2

Sends a user-defined trigger to the output connector immediately. Note that the trigger pulse level is always opposite to the constant signal level defined by the output "Level" setting, e.g. for "Level = High", a constant high signal is output to the connector until the "Send Trigger" button is selected. Then, a low pulse is sent.

Which pulse level will be sent is indicated by a graphic on the button.

Remote command:

[OUTPut:TRIGger<port>:PULSe:IMMediate](#) on page 769

Gate Settings

Gate settings define one or more extracts of the signal to be measured.

Note: Gating is not available for measurements on I/Q-based data.

Gated Trigger ← Gate Settings

Switches gated triggering on or off.

If the gate is switched on, a gate signal applied to one of the "TRIGGER INPUT" connectors or the internal IF power detector controls the sweep of the analyzer.

Gate Mode ← Gate Settings

Sets the gate mode.

For more information see [chapter 6.6.1.2, "Gated Measurements"](#), on page 370

"Edge" The gate opens and the measurement starts when a defined level in the gate source is exceeded and stops when the defined "Gate Length" is reached.

"Lvl" The gate opens and the measurement starts when a defined level in the gate source is exceeded and stops when the gate source drops below the "Trigger Level".

Remote command:

[SENSe:] SWEep:EGATe:TYPE on page 767

Gate Delay ← Gate Settings

Defines the delay time between the gate signal and the continuation of the measurement. The delay position on the time axis in relation to the sweep is indicated by a line labeled "GD".

For more information see [chapter 6.6.1.2, "Gated Measurements"](#), on page 370

Remote command:

[SENSe:] SWEep:EGATe:HOLDoff on page 766

Gate Length ← Gate Settings

Defines how long the gate is open when it is triggered. The gate length can only be set in the edge-triggered gate mode. In the level-triggered mode the gate length depends on the level of the gate signal.

The gate length in relation to the sweep is indicated by a line labeled "GL".

For more information see [chapter 6.6.1.2, "Gated Measurements"](#), on page 370

Remote command:

[SENSe:] SWEep:EGATe:LENGth on page 766

6.6.3 How to Configure a Triggered and Gated Measurement

The following step-by-step instructions demonstrate how to configure a triggered and gated measurement manually.

For remote operation see [chapter 11.7.4, "Configuring Triggered and Gated Measurements"](#), on page 760.

Trigger and gate settings are configured in the "Trigger and Gate" dialog box.

To display the "Trigger and Gate" dialog box, do one of the following:

- Select "Trigger/Gate" from the "Overview".
- Select the TRIG key and then the "Trigger/Gate Config" softkey.

The following tasks are described:

6.6.3.1	How to Determine the Required Trigger/Gate Parameters.....	380
6.6.3.2	How to Configure a Triggered Measurement.....	380
6.6.3.3	How to Configure a Gated Measurement.....	381

6.6.3.1 How to Determine the Required Trigger/Gate Parameters

1. In the "Trigger and Gate" dialog box, switch on "Show Preview".
A zero span measurement for the currently defined center frequency is displayed.
2. Set the "Frequency", "RBW" and "Sweep Time" such that the relevant part of the signal is displayed, for example a complete burst.
3. Determine the parameters you want to use to define the trigger and gate conditions from the preview diagram, for example:
 - the length of a burst or slot
 - the upper or lower power level of a pulse
 - the maximum noise level
 - the power level or time at which a certain incident occurs
4. Try out different trigger and gate settings as described in [How to Configure a Triggered Measurement](#) and [How to Configure a Gated Measurement](#), then select "Update Main Diagram" to see the effect of the current settings on the main measurement in the background.
5. If the results are as expected, close the dialog box to keep the changes permanently. Otherwise, correct the settings as necessary.

6.6.3.2 How to Configure a Triggered Measurement

To define an external trigger:

1. Connect an external device that will provide the trigger signal to one of the TRG IN / AUX connectors on the R&S FPS (for details see the R&S FPS "Getting Started" manual).
2. In the "Trigger and Gate" dialog box, define the "Trigger Source" = "External".
3. If you are using the variable TRG AUX connector, you must define its use as an input connector. In the "Trigger In/Out" tab of the "Trigger and Gate" dialog box, set the corresponding trigger to "Input".
4. Configure the external trigger as described for the other power triggers.

To define a power trigger:

1. In the "Trigger and Gate" dialog box, define the "Trigger Source" = "IF Power" or "Video". Note that the video signal corresponds to the envelope of the IF signal: it has been processed by the resolution and video filters and the selected detector.
2. Define the "Trigger Level": the power level at which the measurement will start. For a "Video" trigger source you can move the level line graphically to define the level. If you define the value numerically, you must enter a percentage of the full diagram height as the level.
3. Define whether the signal must cross the trigger level on a falling or on a rising edge ("Slope") to trigger the measurement.
4. To start the measurement with a time delay, define a "Trigger Offset".
5. To reject triggers due to noise or jittering in the signal, define a "Hysteresis" that is larger than the expected noise or jittering. After the previous trigger, the signal must exceed this threshold before the next level crossing triggers a new measurement.
6. To skip multiple triggers in a burst, define a "Holdoff" time that must pass between two triggers. The holdoff time should be slightly larger than the burst.

6.6.3.3 How to Configure a Gated Measurement

1. Determine the required parameters as described in [chapter 6.6.3.1, "How to Determine the Required Trigger/Gate Parameters"](#), on page 380.
2. The gate is opened by a trigger event, which must be based on a power source. Define the trigger as described in [chapter 6.6.3.2, "How to Configure a Triggered Measurement"](#), on page 380. As the "Trigger Source", use "IF Power", "Video" or "External".
3. Define how long the gate is to remain open:
To measure the signal as long as the trigger level is exceeded, for example for one or more pulses, define "Gate Mode" = "Level".
To measure the signal for a certain time after a level is exceeded, for example during a burst:
 - a) Define "Gate Mode" = "Edge".
 - b) Define the time to measure for each gate: "Gate Length".
4. To open the gate with a time delay, for example to ignore an overshoot, define a "Gate Delay".
5. Select "Gated Trigger" = "On".

6.6.4 How to Output a Trigger Signal

Using the variable TRG AUX connector of the R&S FPS, the internal trigger signal can be output for use by other connected devices. For details on the connectors see the R&S FPS "Getting Started" manual.

To output a trigger to a connected device

1. In the "Trigger In/Out" tab of the "Trigger and Gate" dialog box, set the trigger to be used to "Output".
2. Define whether the trigger signal is to be output automatically ("Output Type" = "Device triggered" or "Trigger Armed") or whether you want to start output manually ("Output Type" = "User-defined").
3. For manual output: Specify the constant signal level and the length of the trigger pulse to be output. Note that the level of the trigger pulse is opposite to the constant output "Level" setting (compare the graphic on the "Send Trigger" button).
4. Connect a device that will receive the trigger signal to the configured TRG AUX connector.
5. Start a measurement and wait for an internal trigger, or select the "Send Trigger" button.

The configured trigger is output to the connector.

6.7 Adjusting Settings Automatically

Some settings can be adjusted by the R&S FPS automatically according to the current measurement settings. In order to do so, a measurement is performed. The duration of this measurement can be defined automatically or manually.

To activate the automatic adjustment of a setting, select the corresponding function in the AUTO SET menu or in the configuration dialog box for the setting, where available.



MSRA operating mode

In MSRA operating mode, settings related to data acquisition can only be adjusted automatically for the MSRA Master, not the applications.



Adjusting settings automatically during triggered measurements

When you select an auto adjust function a measurement is performed to determine the optimal settings. If you select an auto adjust function for a triggered measurement, you are asked how the R&S FPS should behave:

- (default:) The measurement for adjustment waits for the next trigger
- The measurement for adjustment is performed without waiting for a trigger. The trigger source is temporarily set to "Free Run". After the measurement is completed, the original trigger source is restored. The trigger level is adjusted as follows:
 - For IF Power and RF Power triggers:
Trigger Level = Reference Level - 15 dB
 - For Video trigger:
Trigger Level = 85 %

Remote command:

[SENSe:]ADJust:CONFigure:TRIG on page 772

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Adjusting all Determinable Settings Automatically (Auto All)

Activates all automatic adjustment functions for the current measurement settings.

This includes:

- [Auto Frequency](#)
- [Auto Level](#)

This function is only available for the MSRA Master, not for the applications.

Remote command:

[SENSe:]ADJust:ALL on page 770

Adjusting the Center Frequency Automatically (Auto Freq)

The R&S FPS adjusts the center frequency automatically.

The optimum center frequency is the frequency with the highest S/N ratio in the frequency span. As this function uses the signal counter, it is intended for use with sinusoidal signals.

At the same time, the optimal reference level is also set (see "[Setting the Reference Level Automatically \(Auto Level\)](#)" on page 346).

Remote command:

[SENSe:]ADJust:FREquency on page 772

Setting the Reference Level Automatically (Auto Level)

Automatically determines the optimal reference level for the current input data. At the same time, the internal attenuators are adjusted so the signal-to-noise ratio is optimized, while signal compression, clipping and overload conditions are minimized.

To determine the optimal reference level, a level measurement is performed on the R&S FPS.

You can change the measurement time for the level measurement if necessary (see "[Changing the Automatic Measurement Time \(Meastime Manual\)](#)" on page 384).

Remote command:

`[SENSe:]ADJust:LEVel` on page 772

Resetting the Automatic Measurement Time (Meastime Auto)

Resets the measurement duration for automatic settings to the default value.

(Spectrum application: 1 ms)

Remote command:

`[SENSe:]ADJust:CONFigure:DURation:MODE` on page 771

Changing the Automatic Measurement Time (Meastime Manual)

This function allows you to change the measurement duration for automatic setting adjustments. Enter the value in seconds.

Remote command:

`[SENSe:]ADJust:CONFigure:DURation:MODE` on page 771

`[SENSe:]ADJust:CONFigure:DURation` on page 770

Upper Level Hysteresis

When the reference level is adjusted automatically using the [Auto Level](#) function, the internal attenuators and the preamplifier are also adjusted. In order to avoid frequent adaptation due to small changes in the input signal, you can define a hysteresis. This setting defines an upper threshold the signal must exceed (compared to the last measurement) before the reference level is adapted automatically.

Remote command:

`[SENSe:]ADJust:CONFigure:HYSTeresis:UPPer` on page 771

Lower Level Hysteresis

When the reference level is adjusted automatically using the [Auto Level](#) function, the internal attenuators and the preamplifier are also adjusted. In order to avoid frequent adaptation due to small changes in the input signal, you can define a hysteresis. This setting defines a lower threshold the signal must fall below (compared to the last measurement) before the reference level is adapted automatically.

Remote command:

`[SENSe:]ADJust:CONFigure:HYSTeresis:LOWer` on page 771

7 Common Analysis and Display Functions

General methods and basic settings to display and analyze measurements, regardless of the operating mode, are described here. If you are performing a specific measurement task, using an operating mode other than Signal and Spectrum Analyzer mode, or an application other than the Spectrum application, be sure to check the specific application or mode description for settings and functions that may deviate from these common settings.



The analysis settings and functions are available via the "Analysis" dialog box, which is displayed when you select the "Analysis" button in the "Overview". Additional measurement-specific analysis functions may be available in separate tabs in the "Analysis" dialog box. These are described with the individual measurements.

See [chapter 5, "Measurements"](#), on page 111.

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7.1 Result Display Configuration

Measurement results can be evaluated in many different ways, for example graphically, as summary tables, statistical evaluations etc. Thus, the result display is highly configurable to suit your specific requirements and optimize analysis. Here you can find out how to optimize the display for your measurement results.

Basic operations concerning the R&S FPS display, for example how to use the Smart-Grid, are described in the R&S FPS Getting Started manual.

General display settings that are usually configured during initial instrument setup, independently of the current measurement, e.g. which items or colors are displayed on the screen, are described in [chapter 9.4, "Display Settings"](#), on page 528.

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7.1.1 Basic Evaluation Methods

Measurement results can be displayed and evaluated using various different methods, also at the same time. Depending on the currently selected measurement, in particular when using optional firmware applications, not all evaluation methods are available.

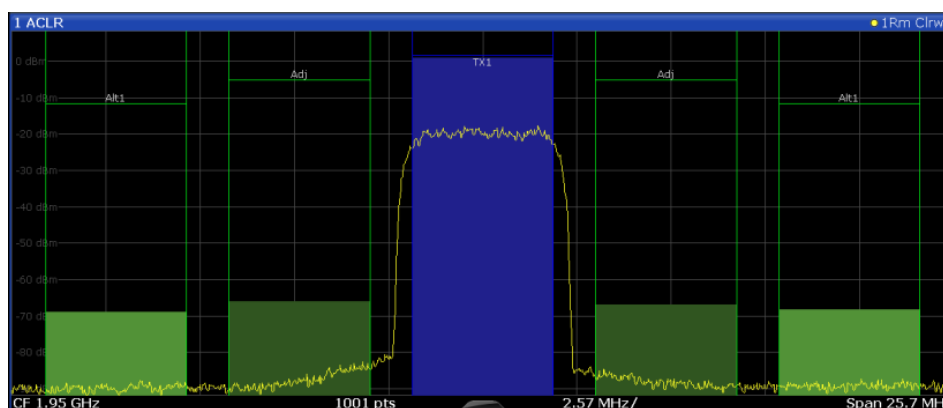
The evaluation methods described here are available for most measurements in the Spectrum application.

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Diagram

Displays a basic level vs. frequency or level vs. time diagram of the measured data to evaluate the results graphically. This is the default evaluation method. Which data is displayed in the diagram depends on the "Trace" settings. Scaling for the y-axis can be configured.

See chapter 7.3, "Trace Configuration", on page 396 and chapter 6.4.3, "Scaling the Y-Axis", on page 349.



Remote command:

LAY:ADD? '1',RIGH, DIAG, see LAYout:ADD[:WINDow]? on page 733

Marker Table

Displays a table with the current marker values for the active markers.

This table may be displayed automatically if configured accordingly (see "Marker Table Display" on page 441).

2 Marker							
Type	Ref	Trc	Stimulus	Response	Function	Function Result	
N1		1	13.197 GHz	-25.87 dBm	Count	13.19705	
D1	N1	1	-7.942 GHz	-49.41 dB			
D2	N1	2	-3.918 GHz	-21.90 dB			
D3	N1	3	4.024 GHz	-21.99 dB			

Remote command:

LAY:ADD? '1',RIGH, MTAB, see LAYout:ADD[:WINDow]? on page 733

Results:

CALCulate<n>:MARKer<m>:X on page 823

CALCulate<n>:MARKer<m>:Y? on page 834

Marker Peak List

The marker peak list determines the frequencies and levels of peaks in the spectrum or time domain. How many peaks are displayed can be defined, as well as the sort order. In addition, the detected peaks can be indicated in the diagram. The peak list can also be exported to a file for analysis in an external application.

You can define search and sort criteria to influence the results of the analysis (See ["Marker Search Settings"](#) on page 442).

2 Marker Peak List		
No	Stimulus	Response
1	64.400000 MHz	-30.352 dBm
2	128.400000 MHz	-51.896 dBm
3	192.300000 MHz	-40.227 dBm
4	257.200000 MHz	-60.699 dBm
5	320.200000 MHz	-44.273 dBm
6	384.100000 MHz	-53.494 dBm
7	448.100000 MHz	-47.460 dBm
8	513.000000 MHz	-55.603 dBm

Remote command:

LAY:ADD? '1',RIGH, PEAK, see [LAYout:ADD\[:WINDow\]?](#) on page 733

Results:

[CALCulate<n>:MARKer<m>:X](#) on page 823

[CALCulate<n>:MARKer<m>:Y?](#) on page 834

Result Summary

Result summaries provide the results of specific measurement functions in a table for numerical evaluation. The contents of the result summary vary depending on the selected measurement function. See the description of the individual measurement functions for details.

2 Result Summary				
Channel	Bandwidth	Offset	Power	
Tx1 (Ref)	1.229 MHz		-0.86 dBm	
Tx Total			-0.86 dBm	
Channel	Bandwidth	Offset	Lower	Upper
Adj	30.000 kHz	750.000 kHz	-79.59 dB	-80.34 dB
Alt1	30.000 kHz	1.980 MHz	-85.04 dB	-83.85 dB

Remote command:

LAY:ADD? '1',RIGH, RSUM, see [LAYout:ADD\[:WINDow\]?](#) on page 733

Spectrogram

A spectrogram shows how the spectral density of a signal varies over time. The x-axis shows the frequency or sweep time, the y-axis shows the measurement time. A third dimension, the power level, is indicated by different colors. Thus you can see how the strength of the signal varies over time for different frequencies.

The spectrogram display consists of two diagrams: the standard spectrum result display (upper diagram) and the spectrogram result display (lower diagram).

For details see [chapter 7.3.1.7, "Working with Spectrograms"](#), on page 403.

Remote command:

LAY:ADD? '1',RIGH, SGR, see [LAYout:ADD\[:WINDow\]?](#) on page 733

7.1.2 Laying out the Result Display with the SmartGrid

Measurement results can be evaluated in many different ways, for example graphically, as summary tables, statistical evaluations etc. Each type of evaluation is displayed in a separate window in the channel tab. Up to 16 individual windows can be displayed per measurement channel (i.e. per tab). To arrange the diagrams and tables on the screen, the Rohde & Schwarz SmartGrid function helps you find the target position simply and quickly.

Principally, the layout of the windows on the screen is based on an underlying grid, the SmartGrid. However, the SmartGrid is dynamic and flexible, allowing for many different layout possibilities. The SmartGrid functionality provides the following basic features:

- Windows can be arranged in columns or in rows, or in a combination of both.
 - Windows can be arranged in up to four rows and four columns.
 - Windows are moved simply by dragging them to a new position on the screen, possibly changing the layout of the other windows, as well.
 - All evaluation methods available for the currently selected measurement are displayed as icons in the evaluation bar. If the evaluation bar contains more icons than can be displayed at once on the screen, it can be scrolled vertically. The same evaluation method can be displayed in multiple windows simultaneously.
 - New windows are added by dragging an evaluation icon from the evaluation bar to the screen. The position of each new window depends on where you drop the evaluation icon in relation to the existing windows.
 - All display configuration actions are only possible in SmartGrid mode. When SmartGrid mode is activated, the evaluation bar replaces the current softkey menu display. When the SmartGrid mode is deactivated again, the previous softkey menu display is restored.
- [Background Information: The SmartGrid Principle](#).....388
 - [How to Activate SmartGrid Mode](#).....390
 - [How to Add a New Result Window](#)..... 390
 - [How to Close a Result Window](#).....391
 - [How to Arrange the Result Windows](#)..... 391

7.1.2.1 Background Information: The SmartGrid Principle

SmartGrid display

During any positioning action, the underlying SmartGrid is displayed. Different colors and frames indicate the possible new positions. The position in the SmartGrid where you drop the window determines its position on the screen.

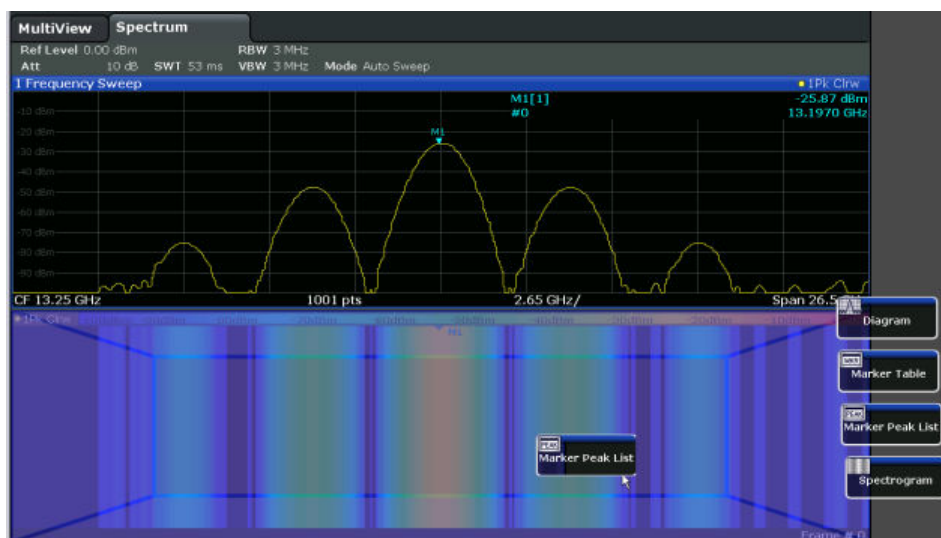


Fig. 7-1: Moving a window in SmartGrid mode

The brown area indicates the possible "drop area" for the window, i.e. the area in which the window can be placed. A blue area indicates the (approximate) layout of the window as it would be if the icon were dropped at the current position. The frames indicate the possible destinations of the new window with respect to the existing windows: above/below, right/left or replacement (as illustrated in figure 3-7). If an existing window would be replaced, the drop area is highlighted in a darker color shade.

Positioning the window

The screen can be divided into up to four rows. Each row can be split into up to four columns, where each row can have a different number of columns. However, rows always span the entire width of the screen and may not be interrupted by a column. A single row is available as the drop area for the window in the SmartGrid. The row can be split into columns, or a new row can be inserted above or below the existing row (if the maximum of 4 has not yet been reached).

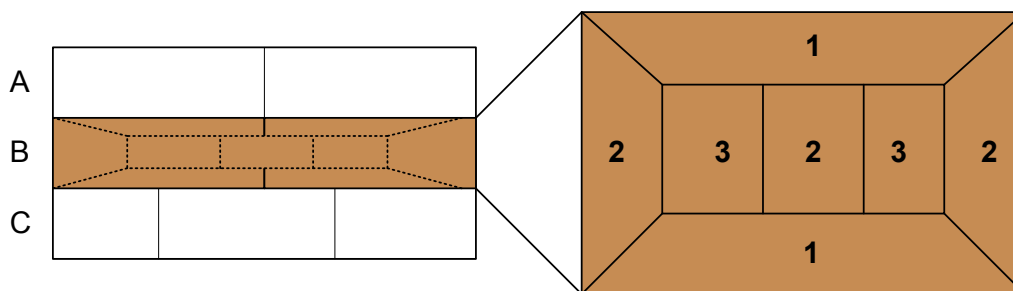


Fig. 7-2: SmartGrid window positions

- 1 = Insert row above or below the existing row
- 2 = Create a new column in the existing row
- 3 = Replace a window in the existing row

SmartGrid functions

Once the evaluation icon has been dropped, icons in each window provide delete and move functions.



The "Move" icon allows you to move the position of the window, possibly changing the size and position of the other displayed windows.



The "Delete" icon allows you to close the window, enlarging the display of the remaining windows.

7.1.2.2 How to Activate SmartGrid Mode

All display configuration actions are only possible in SmartGrid mode. In SmartGrid mode the evaluation bar replaces the current softkey menu display. When the SmartGrid mode is deactivated again, the previous softkey menu display is restored.

► To activate SmartGrid mode, do one of the following:



Select the "SmartGrid" icon from the toolbar.

- Select the "Display Config" button in the configuration "Overview".
- Select the "Display Config" softkey from the MEAS CONFIG menu.

The SmartGrid functions and the evaluation bar are displayed.



To close the SmartGrid mode and restore the previous softkey menu select the "Close" icon in the right-hand corner of the toolbar, or press any key.

7.1.2.3 How to Add a New Result Window

Each type of evaluation is displayed in a separate window. Up to 16 individual windows can be displayed per measurement channel (i.e. per tab).

1. Activate SmartGrid mode.

All evaluation methods available for the currently selected measurement are displayed as icons in the evaluation bar.

2. Select the icon for the required evaluation method from the evaluation bar.

If the evaluation bar contains more icons than can be displayed at once on the screen, it can be scrolled vertically. Set the mouse pointer in the evaluation bar between the icons and move it up or down until the required icon appears.

3. Drag the required icon from the evaluation bar to the SmartGrid, which is displayed in the diagram area, and drop it at the required position. (See ["How to Arrange the Result Windows"](#) on page 94 for more information on positioning the window).

Remote command:

[LAYout:ADD\[:WINDow\]? on page 733](#) / [LAYout:WINDow<n>:ADD? on page 737](#)

7.1.2.4 How to Close a Result Window

- ▶ To close a window, activate SmartGrid mode and select the "Delete" icon for the window.

**Remote command:**

[LAYout:REMove\[:WINDow\] on page 735](#) / [LAYout:WINDow<n>:REMove on page 738](#)

7.1.2.5 How to Arrange the Result Windows

1. Select an icon from the evaluation bar or the "Move" icon for an existing evaluation window.



2. Drag the evaluation over the SmartGrid.
A blue area shows where the window will be placed.
3. Move the window until a suitable area is indicated in blue.
4. Drop the window in the target area.
The windows are rearranged to the selected layout, and "Delete" and "Move" icons are displayed in each window.
5. To close a window, select the corresponding "Delete" icon.

**Remote command:**

[LAYout:REPLace\[:WINDow\] on page 735](#) / [LAYout:WINDow<n>:REPLace on page 738](#)

7.2 Zoomed Displays

You can zoom into the diagram to visualize the measurement results in greater detail. Using a mouse pointer you can easily define the area to be enlarged.



Zoom and the number of sweep points

Note that zooming is merely a visual tool, it does not change any measurement settings, such as the number of sweep points!

You should increase the number of sweep points before zooming, as otherwise the function has no real effect (see [chapter 6.5.1.8, "How Much Data is Measured: Sweep Points and Sweep Count"](#), on page 356).

- [Single Zoom Versus Multiple Zoom](#)..... 392
- [Zoom Functions](#)..... 393
- [How to Zoom Into a Diagram](#)..... 394

7.2.1 Single Zoom Versus Multiple Zoom

Two different (graphical) zoom modes are available: single zoom and multiple zoom. A single zoom replaces the current diagram by a new diagram which displays an enlarged extract of the trace. This function can be used repetitively until the required details are visible. In multiple zoom mode, you can enlarge up to four different areas of the trace simultaneously. An overview window indicates the zoom areas in the original trace, while the zoomed trace areas are displayed in individual windows. The zoom areas can be moved and resized any time. The zoom area that corresponds to the individual zoom display is indicated in the lower right corner, between the scrollbars.

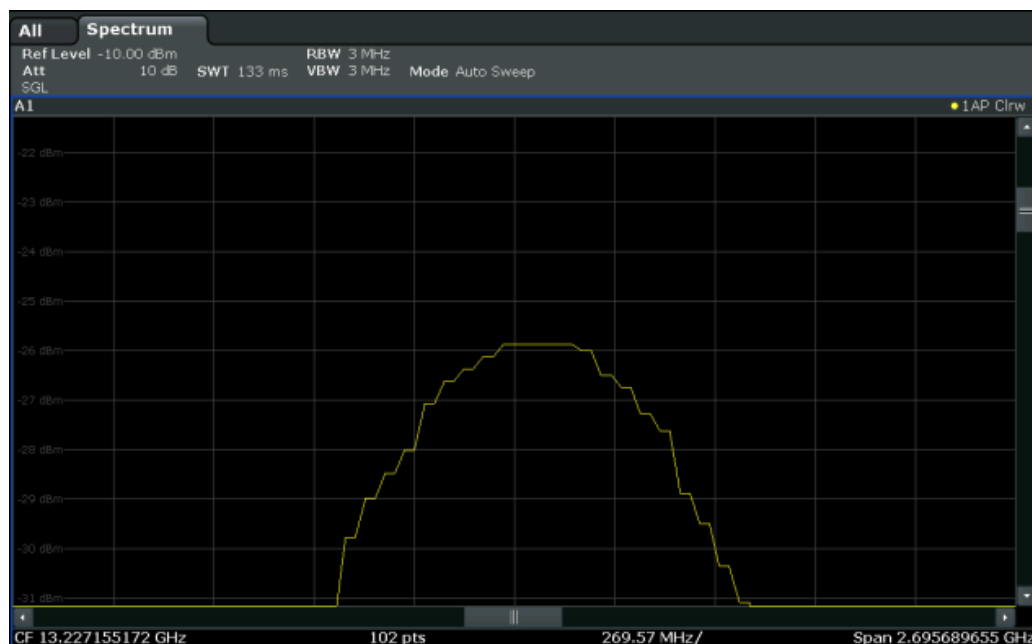


Fig. 7-3: Single zoom

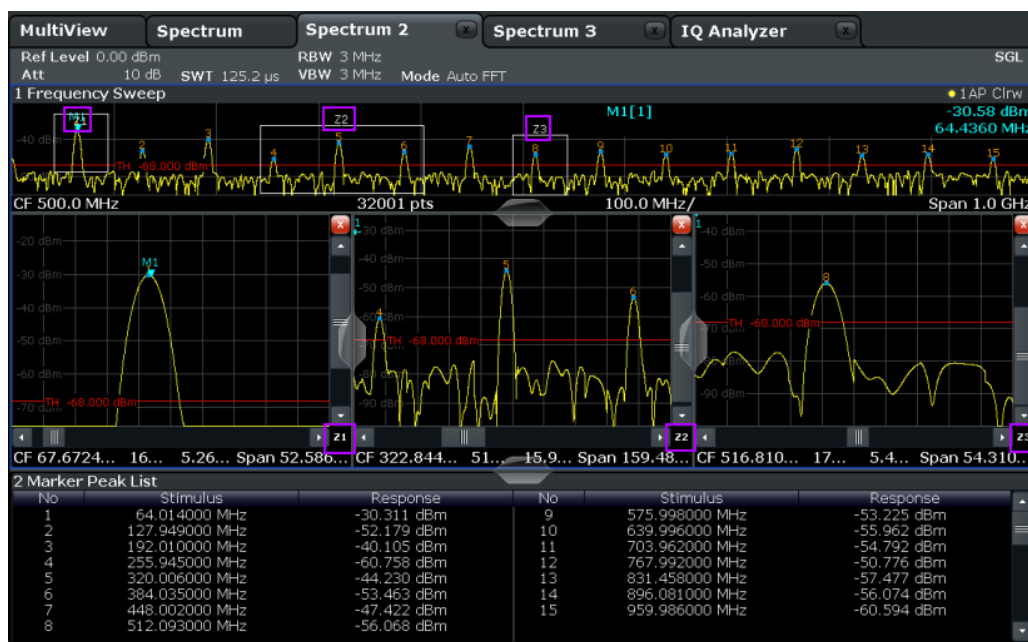


Fig. 7-4: Multiple zoom



Using the zoom area to restrict a peak search

The selected zoom area can be used to restrict the search range for a peak search, but only in single zoom mode (see "Using Zoom Limits" on page 444).

7.2.2 Zoom Functions

The zoom functions are only available from the toolbar.

Single Zoom..... 393

Multiple Zoom.....394

Restore Original Display..... 394

Deactivating Zoom (Selection mode)..... 394

Single Zoom



A single zoom replaces the current diagram by a new diagram which displays an enlarged extract of the trace. This function can be used repetitively until the required details are visible.

Remote command:

DISPlay[:WINDow<n>]:ZOOM:STATE on page 797

DISPlay[:WINDow<n>]:ZOOM:AREA on page 797

Multiple Zoom



In multiple zoom mode, you can enlarge several different areas of the trace simultaneously. An overview window indicates the zoom areas in the original trace, while the zoomed trace areas are displayed in individual windows. The zoom area that corresponds to the individual zoom display is indicated in the lower right corner, between the scrollbars.

Remote command:

`DISPlay[:WINDow<n>]:ZOOM:MULTiple<zoom>:STATe` on page 798

`DISPlay[:WINDow<n>]:ZOOM:MULTiple<zoom>:AREA` on page 798

Restore Original Display



Restores the original display and closes all zoom windows.

Remote command:

`DISPlay[:WINDow<n>]:ZOOM:STATe` on page 797 (single zoom)

`DISPlay[:WINDow<n>]:ZOOM:MULTiple<zoom>:STATe` on page 798 (for each multiple zoom window)

Deactivating Zoom (Selection mode)

Deactivates any zoom mode.

Selecting a point in the display no longer invokes a zoom, but selects an object.

Remote command:

`DISPlay[:WINDow<n>]:ZOOM:STATe` on page 797 (single zoom)

`DISPlay[:WINDow<n>]:ZOOM:MULTiple<zoom>:STATe` on page 798 (for each multiple zoom window)

7.2.3 How to Zoom Into a Diagram

The remote commands required to zoom into a display are described in [chapter 11.8.1, "Zooming into the Display"](#), on page 797.

The following tasks are described here:

- ["To zoom into the diagram at one position"](#) on page 394
- ["To return to selection mode in the diagram"](#) on page 395
- ["To return to original display"](#) on page 395
- ["To zoom into multiple positions in the diagram"](#) on page 396

To zoom into the diagram at one position

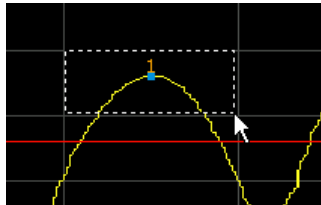
1.



Click on the "Single Zoom" icon in the toolbar.

Zoom mode is activated.

2. Select the area in the diagram to be enlarged using the mouse pointer. The selected area is indicated by a dotted rectangle.



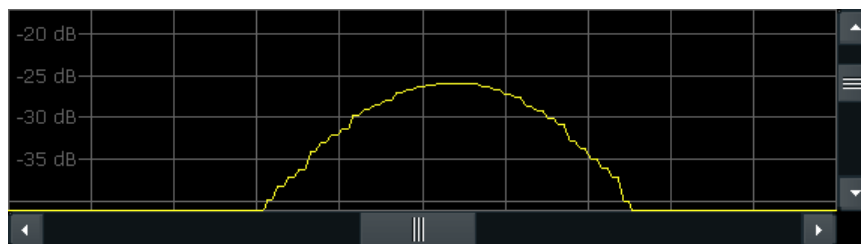
When you drop the mouse pointer, the diagram is replaced by the zoomed trace area.

3. Repeat these steps, if necessary, to enlarge the diagram further.



Scrolling in the zoomed display

You can scroll the diagram area to display the entire diagram using the scrollbars at the right and at the bottom of the diagram.



To return to selection mode in the diagram

While you are in zoom mode, selecting points in the display changes the zoom area. In order to select or move a trace or marker, you must switch back to selection mode:



Select the "Selection mode" icon in the toolbar.

To return to original display



Click on the "Zoom Off" icon in the toolbar.

The original trace display is restored. Zoom mode remains active, however.

To switch off zoom mode and return to selection mode, select the "Selection mode" icon in the toolbar.

To zoom into multiple positions in the diagram

1. 

Click on the "Multiple Zoom" icon in the toolbar.

Multiple zoom mode is activated.

2. Select the first area in the diagram to be enlarged as described in ["To zoom into the diagram at one position"](#) on page 394. The selected area is indicated by a dotted rectangle.

When you have completed your selection, the original trace is shown in an overview diagram with the selected area indicated by a dotted rectangle. The zoomed trace area is displayed in a separate window (see [figure 7-4](#)).

3. In the overview diagram, select the next area to be enlarged.
The second zoom area is indicated in the overview diagram, and a second zoom window is displayed.
4. Repeat these steps, if necessary, to zoom into further trace areas (up to four).

To move or change zoom areas

In multiple zoom mode, you can change the size or position of the individual zoom areas easily at any time.

1. If necessary, switch off zoom mode and return to selection mode by selecting the "Selection mode" icon in the toolbar.
2. To resize a zoom area, set the mouse pointer directly **on** the corresponding frame in the overview window and drag the line to change the size of the frame.
To move a zoom area, set the mouse pointer **inside** the corresponding frame in the overview window and drag the frame to the new position.
The contents of the zoom windows are adapted accordingly.

7.3 Trace Configuration

A trace is a collection of measured data points. The trace settings determine how the measured data is analyzed and displayed on the screen.

- [Basics on Setting up Traces](#)..... 396
- [Trace Configuration](#).....409
- [How to Configure Traces](#)..... 421

7.3.1 Basics on Setting up Traces

Some background knowledge on traces is provided here for a better understanding of the required configuration settings.

- [Mapping Samples to sweep Points with the Trace Detector](#).....397
- [Analyzing Several Traces - Trace Mode](#)..... 399
- [How Many Traces are Averaged - Sweep Count + Sweep Mode](#).....400
- [How Trace Data is Averaged - the Averaging Mode](#).....401
- [Combining Several Trace Results - Trace Math Evaluation](#)..... 402
- [Trace Smoothing](#).....402
- [Working with Spectrograms](#)..... 403

7.3.1.1 Mapping Samples to sweep Points with the Trace Detector

A trace displays the values measured at the sweep points. The number of samples taken during a sweep may be much larger than the number of sweep points that are displayed in the measurement trace.

Example:

Assume the following measurement parameters:

- Sample rate: 32 MSamples / s
- sweep points: 1000
- sweep time: 100 ms
- Span: 5 GHz

During a single sweep , $3.2 * 10^6$ samples are collected and distributed to 1000 sweep points, i.e. 3200 samples are collected per sweep point. For each sweep point, the measured data for a frequency span of 5 MHz ($\text{span}/\langle \text{sweep points} \rangle$) is analyzed.

Note that if you increase the number of sweep points, the frequency span analyzed for each point in the trace decreases, making the result more stable.

See also [chapter 6.5.1.8, "How Much Data is Measured: Sweep Points and Sweep Count"](#), on page 356.

Obviously, a data reduction must be performed to determine which of the samples are displayed for each sweep point. This is the trace detector's task.

The trace detector can analyze the measured data using various methods:



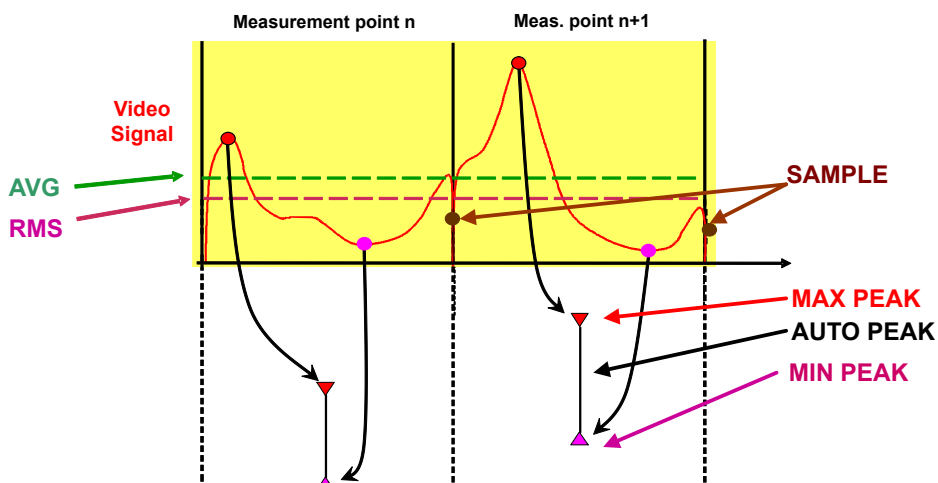
The detector activated for the specific trace is indicated in the corresponding trace information by an abbreviation.

Table 7-1: Detector types

Detector	Abbrev.	Description
Positive Peak	Pk	Determines the largest of all positive peak values of the levels measured at the individual frequencies which are displayed in one sample point
Negative Peak	Mi	Determines the smallest of all negative peak values of the levels measured at the individual frequencies which are displayed in one sample point
Auto Peak	Ap	Combines the peak detectors; determines the maximum and the minimum value of the levels measured at the individual frequencies which are displayed in one sample point (not available for SEM)

Detector	Abbrev.	Description
RMS	Rm	<p>Calculates the root mean square of all samples contained in a sweep point.</p> <p>To this effect, R&S FPS uses the linear voltage after envelope detection. The sampled linear values are squared, summed and the sum is divided by the number of samples (= root mean square). For logarithmic display the logarithm is formed from the square sum. For linear display the root mean square value is displayed. Each sweep point thus corresponds to the power of the measured values summed up in the sweep point.</p> <p>The RMS detector supplies the power of the signal irrespective of the waveform (CW carrier, modulated carrier, white noise or impulsive signal). Correction factors as needed for other detectors to measure the power of the different signal classes are not required.</p>
Average	Av	<p>Calculates the linear average of all samples contained in a sweep point.</p> <p>To this effect, R&S FPS uses the linear voltage after envelope detection. The sampled linear values are summed up and the sum is divided by the number of samples (= linear average value). For logarithmic display the logarithm is formed from the average value. For linear display the average value is displayed. Each sweep point thus corresponds to the average of the measured values summed up in the sweep point.</p> <p>The average detector supplies the average value of the signal irrespective of the waveform (CW carrier, modulated carrier, white noise or impulsive signal).</p>
Sample	Sa	<p>Selects the last measured value of the levels measured at the individual frequencies which are displayed in one sample point; all other measured values for the frequency range are ignored</p>

The result obtained from the selected detector for a sweep point is displayed as the value at this frequency point in the trace.



The trace detector for the individual traces can be selected manually by the user or set automatically by the R&S FPS.

The detectors of the R&S FPS are implemented as pure digital devices. All detectors work in parallel in the background, which means that the measurement speed is independent of the detector combination used for different traces.



RMS detector and VBW

If the RMS detector is selected, the video bandwidth in the hardware is bypassed. Thus, duplicate trace averaging with small VBWs and RMS detector no longer occurs. However, the VBW is still considered when calculating the sweep time. This leads to a longer sweep time for small VBW values. Thus, you can reduce the VBW value to achieve more stable trace curves even when using an RMS detector. Normally, if the RMS detector is used the sweep time should be increased to get more stable traces.

Auto detector

If the R&S FPS is set to define the appropriate detector automatically, the detector is set depending on the selected trace mode:

Trace mode	Detector
Clear Write	Auto Peak
Max Hold	Positive Peak
Min Hold	Negative Peak
Average	Sample Peak
View	–
Blank	–

7.3.1.2 Analyzing Several Traces - Trace Mode

If several sweep are performed one after the other, or continuous sweep are performed, the trace mode determines how the data for subsequent traces is processed. After each sweep, the trace mode determines whether:

- the data is frozen (View)
- the data is hidden (Blank)
- the data is replaced by new values (Clear Write)
- the data is replaced selectively (Max Hold, Min Hold, Average)



Each time the trace mode is changed, the selected trace memory is cleared. The trace mode also determines the detector type if the detector is set automatically, see [chapter 7.3.1.1, "Mapping Samples to sweep Points with the Trace Detector"](#), on page 397.


The R&S FPS supports the following trace modes:

Table 7-2: Overview of available trace modes

Trace Mode	Description
Blank	Hides the selected trace.
Clear Write	Overwrite mode: the trace is overwritten by each sweep. This is the default setting. All available detectors can be selected.

Trace Mode	Description
Max Hold	<p>The maximum value is determined over several measurements and displayed. The R&S FPS saves the sweep result in the trace memory only if the new value is greater than the previous one.</p> <p>This mode is especially useful with modulated or pulsed signals. The signal spectrum is filled up upon each sweep until all signal components are detected in a kind of envelope.</p> <p>This mode is not available for statistics measurements.</p>
Min Hold	<p>The minimum value is determined from several measurements and displayed. The R&S FPS saves the sweep result in the trace memory only if the new value is lower than the previous one.</p> <p>This mode is useful for example for making an unmodulated carrier in a composite signal visible. Noise, interference signals or modulated signals are suppressed, whereas a CW signal is recognized by its constant level.</p> <p>This mode is not available for statistics measurements.</p>
Average	<p>The average is formed over several measurements and displayed.</p> <p>The Sweep / Average Count determines the number of averaging procedures.</p> <p>This mode is not available for statistics measurements.</p>
View	The current contents of the trace memory are frozen and displayed.



If a trace is frozen ("View" mode), the measurement settings, apart from level range and reference level (see below), can be changed without impact on the displayed trace. The fact that the displayed trace no longer matches the current measurement settings is indicated by the  icon on the tab label.

If the level range or reference level is changed, the R&S FPS automatically adapts the trace data to the changed display range. This allows an amplitude zoom to be made after the measurement in order to show details of the trace.

7.3.1.3 How Many Traces are Averaged - Sweep Count + Sweep Mode

In "Average" trace mode, the sweep count and sweep mode determine how many traces are averaged. The more traces are averaged, the smoother the trace is likely to become.

The algorithm for averaging traces depends on the sweep mode and sweep count.

- **sweep count = 0** (default)
 - In "**Continuous**" sweep mode, a continuous average is calculated for 10 sweep s, according to the following formula:

$$Trace = \frac{9 * Trace_{old} + MeasValue}{10}$$

Fig. 7-5: Equation 1

Due to the weighting between the current trace and the average trace, past values have practically no influence on the displayed trace after about ten sweep

s. With this setting, signal noise is effectively reduced without need for restarting the averaging process after a change of the signal.

- In **"Single"** sweep mode, the current trace is averaged with the previously stored averaged trace. No averaging is carried out for the first sweep but the measured value is stored in the trace memory. The next time a sweep is performed, the trace average is calculated according to the following formula:

$$Trace = \frac{Trace_{old} + MeasValue}{2}$$

The averaged trace is then stored in the trace memory.

- **sweep count = 1**

The currently measured trace is displayed and stored in the trace memory. No averaging is performed.

- **sweep count > 1**

For both **"Single"** sweep mode and **"Continuous"** sweep mode, averaging takes place over the selected number of sweep s. In this case the displayed trace is determined during averaging according to the following formula:

$$Trace_n = \frac{1}{n} \cdot \left[\sum_{i=1}^{n-1} (T_i) + MeasValue_n \right]$$

Fig. 7-6: Equation 2

where n is the number of the current sweep (n = 2 ... Sweep Count).

No averaging is carried out for the first sweep but the measured value is stored in the trace memory. With increasing n, the displayed trace is increasingly smoothed since there are more individual sweep s for averaging.

After the selected number of sweep s the average trace is saved in the trace memory. Until this number of sweep s is reached, a preliminary average is displayed.

When the averaging length defined by the "Sweep Count" is attained, averaging is continued in continuous sweep mode or for "Continue Single Sweep" according to the following formula:

$$Trace = \frac{(N-1) * Trace_{old} + MeasValue}{N}$$

where N is the sweep count

7.3.1.4 How Trace Data is Averaged - the Averaging Mode

When the trace is averaged over several sweeps (Trace mode: "Average"), different methods are available to determine the trace average.

With logarithmic averaging, the dB values of the display voltage are averaged or subtracted from each other with trace mathematical functions.

With linear averaging, the level values in dB are converted into linear voltages or powers prior to averaging. Voltage or power values are averaged or offset against each other and reconverted into level values.

For stationary signals the two methods yield the same result.

Logarithmic averaging is recommended if sinewave signals are to be clearly visible against noise since with this type of averaging noise suppression is improved while the sinewave signals remain unchanged.

For noise or pseudo-noise signals the positive peak amplitudes are decreased in logarithmic averaging due to the characteristic involved and the negative peak values are increased relative to the average value. If the distorted amplitude distribution is averaged, a value is obtained that is smaller than the actual average value. The difference is -2.5 dB.

This low average value is usually corrected in noise power measurements by a 2.5 dB factor. Therefore the R&S FPS offers the selection of linear averaging. The trace data is linearized prior to averaging, then averaged and logarithmized again for display on the screen. The average value is always displayed correctly irrespective of the signal characteristic.

7.3.1.5 Combining Several Trace Results - Trace Math Evaluation

If you have several traces with different modes, for example an average trace and a maximum trace, it may be of interest to compare the results of both traces. In this example, you could analyze the maximum difference between the average and maximum values. To analyze the span of result values, you could subtract the minimum trace from the maximum trace. For such tasks, mathematical functions on trace results are provided.

7.3.1.6 Trace Smoothing

(Software-based) **smoothing** is a way to visually remove anomalies in the trace that may distort the results. The smoothing process is based on a moving average over the complete measurement range. The number of samples included in the averaging process (the *aperture* size) is variable and is a percentage of all samples that the trace consists of.

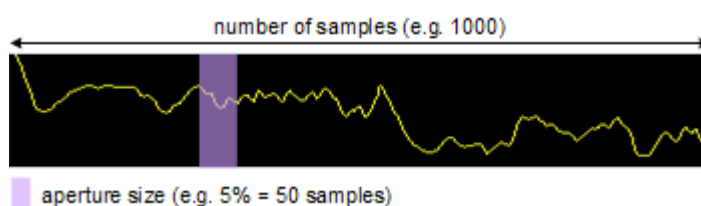


Fig. 7-7: Sample size included in trace smoothing



Effects of smoothing on post-processing functions

Note that in Spectrum mode, all functions performed after the sweep, such as limit checks, markers, or channel power measurements, are based on the smoothed trace data. Thus, the results will differ from results based on the original trace.

You can turn trace smoothing on and off for all traces individually and compare, for example, the raw and the smooth trace.

Linear smoothing is based on the following algorithm:

$$y'(s) = \frac{1}{n} \left(\sum_{x=s-\frac{n-1}{2}}^{x=s+\frac{n-1}{2}} y(x) \right)$$

Linear trace smoothing (7 - 1)

with:

s = sample number

x = sample offset from s

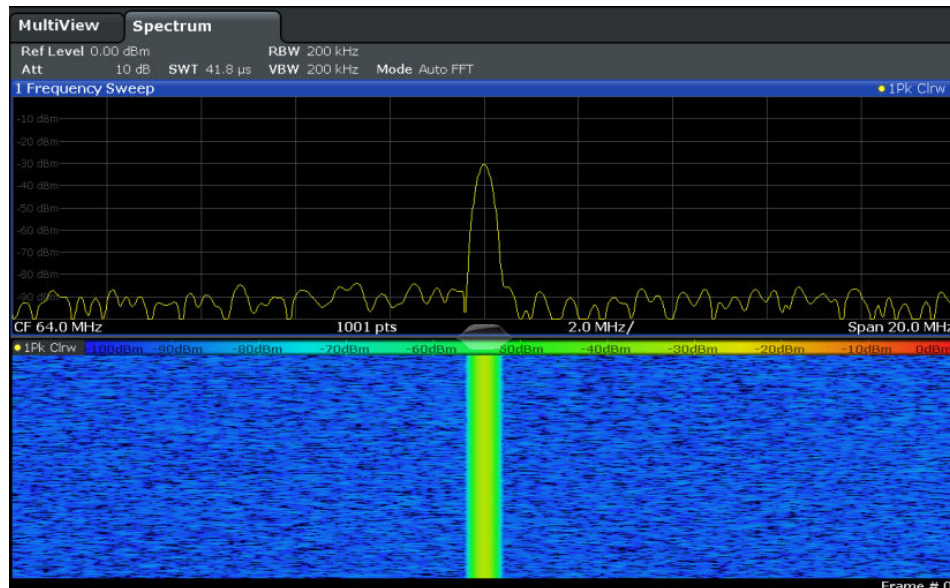
n = aperture size

7.3.1.7 Working with Spectrograms

In addition to the standard "level versus frequency" or "level versus time" traces, the R&S FPS also provides a spectrogram display of the measured data.

A spectrogram shows how the spectral density of a signal varies over time. The x-axis shows the frequency, the y-axis shows the time. A third dimension, the power level, is indicated by different colors. Thus you can see how the strength of the signal varies over time for different frequencies.

Example:



In this example you see the spectrogram for the calibration signal of the R&S FPS, compared to the standard spectrum display. Since the signal does not change over time, the color of the frequency levels does not change over time, i.e. vertically. The legend above the spectrogram display describes the power levels the colors represent.

Result display

The spectrogram result can consist of the following elements:

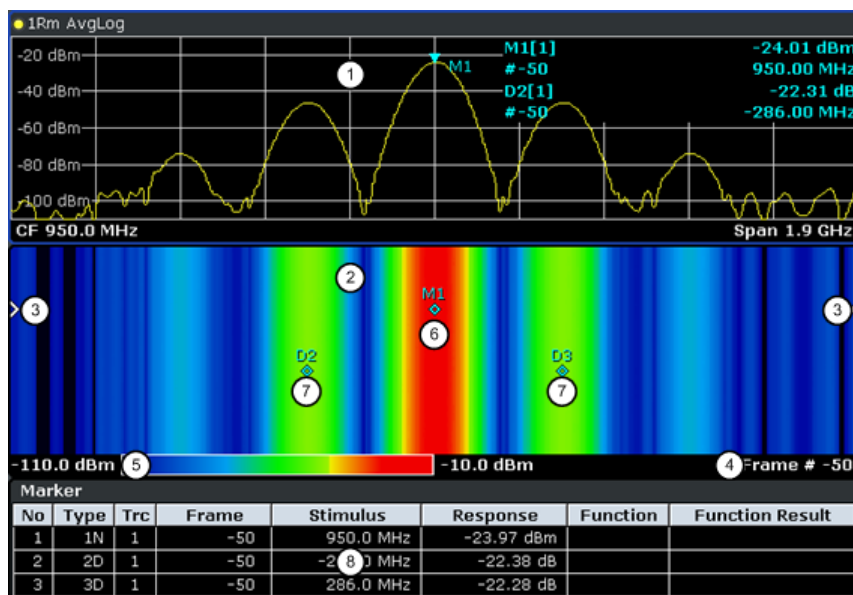


Fig. 7-8: Screen layout of the spectrogram result display

- 1 = Spectrum result display
- 2 = Spectrogram result display
- 3 = Current frame indicator
- 4 = Timestamp / frame number
- 5 = Color map
- 6 = Marker
- 7 = Delta marker
- 8 = Marker list

For more information about spectrogram configuration see [chapter 7.3.2.4, "Spectrogram Settings"](#), on page 417.

Remote commands:

Activating and configuring spectrograms:

[chapter 11.8.2.2, "Configuring Spectrograms"](#), on page 804

Storing results:

[MMEMory:STORe<n>:SPECTrogram](#) on page 904

- [Time Frames](#).....404
- [Color Maps](#).....406
- [Markers in the Spectrogram](#).....408

Time Frames

The time information in the spectrogram is displayed vertically, along the y-axis. Each line (or trace) of the y-axis represents one or more captured sweep and is called a **time frame** or simply "frame". As with standard spectrum traces, several measured values are combined in one sweep point using the selected detector.

(See [chapter 7.3.1.1, "Mapping Samples to sweep Points with the Trace Detector"](#), on page 397).

Frames are sorted in chronological order, beginning with the most recently recorded frame at the top of the diagram (frame number 0). With the next sweep, the previous frame is moved further down in the diagram, until the maximum number of captured frames is reached. The display is updated continuously during the measurement, and the measured trace data is stored. Spectrogram displays are continued even after single measurements unless they are cleared manually.

The maximum number of frames that you can capture is summarized in [table 7-3](#).

Table 7-3: Correlation between number of sweep points and number of frames stored in the history buffer

Sweep Points	Max. History Depth
≤1250	20000
2001	12488
4001	6247
8.001	3124
16.001	1562
32.001	781



The scaling of the time axis (y-axis) is not configurable. However, you can enlarge the spectrogram display by maximizing the window using the "Split/Maximize" key.



Frame analysis - Frame count vs. sweep count

As described for standard spectrum sweeps, the sweep count defines how many sweeps are analyzed to create a single trace. Thus, for a trace in "Average" mode, for example, a sweep count of 10 means that 10 sweeps are averaged to create a single trace, or frame.

The frame count, on the other hand, determines how many frames are plotted during a single sweep measurement (as opposed to a continuous sweep). For a frame count of 2, for example, 2 frames will be plotted during each single sweep. For continuous sweep mode, the frame count is irrelevant; one frame is plotted per sweep until the measurement is stopped.

If you combine the two settings, 20 sweeps will be performed for each single sweep measurement. The first 10 will be averaged to create the first frame, the next 10 will be averaged to create the second frame.

As you can see, increasing the sweep count increases the accuracy of the individual traces, while increasing the frame count increases the number of traces in the diagram.

Especially for "Average" or "Min hold" and "Max hold" trace modes, the number of sweeps that are analyzed to create a single trace has an effect on the accuracy of the

results. Thus, you can also define whether the results from frames in previous traces are considered in the analysis for each new trace ("Continue frame").

Tracking absolute time - timestamps

Alternatively to the frame count, the absolute time (that is: a *timestamp*) at which a frame was captured can be displayed. While the measurement is running, the timestamp shows the system time. In single sweep mode or if the sweep is stopped, the timestamp shows the time and date at the end of the sweep. Thus, the individual frames can be identified by their timestamp or their frame count.

When active, the timestamp replaces the display of the frame number in the diagram footer (see [figure 7-8](#)).

Displaying individual frames

The spectrogram diagram contains all stored frames since it was last cleared. Arrows on the left and right border of the spectrogram indicate the currently selected frame. The spectrum diagram always displays the spectrum for the currently selected frame.

The current frame number is indicated in the diagram footer, or alternatively a timestamp, if activated. The current frame, displayed at the top of the diagram, is frame number 0. Older frames further down in the diagram are indicated by a negative index, e.g. "-10". You can display the spectrum diagram of a previous frame by changing the current frame number.

Color Maps

Spectrograms assign power levels to different colors in order to visualize them. The legend above the spectrogram display describes the power levels the colors represent.

The color display is highly configurable to adapt the spectrograms to your needs. You can define:

- Which colors to use (Color scheme)
- Which value range to apply the color scheme to
- How the colors are distributed within the value range, i.e. where the focus of the visualization lies (shape of the color curve)

The individual colors are assigned to the power levels automatically by the R&S FPS.

The Color Scheme

You can select which colors are assigned to the measured values. Four different color ranges or "schemes" are available:

- **Hot**



Uses a color range from blue to red. Blue colors indicate low levels, red colors indicate high ones.

- **Cold**



Uses a color range from red to blue. Red colors indicate low levels, blue colors indicate high ones.

The "Cold" color scheme is the inverse "Hot" color scheme.

- **Radar**



Uses a color range from black over green to light turquoise with shades of green in between. Dark colors indicate low levels, light colors indicate high ones.

- **Grayscale**



Shows the results in shades of gray. Dark gray indicates low levels, light gray indicates high ones.

The Value Range of the Color Map

If the measured values only cover a small area in the spectrogram, you can optimize the displayed value range so it becomes easier to distinguish between values that are close together, and only parts of interest are displayed at all.

The Shape and Focus of the Color Curve

The color mapping function assigns a specified color to a specified power level in the spectrogram display. By default, colors on the color map are distributed evenly. However, if a certain area of the value range is to be visualized in greater detail than the rest, you can set the focus of the color mapping to that area. Changing the focus is performed by changing the shape of the color curve.

The color curve is a tool to shift the focus of the color distribution on the color map. By default, the color curve is linear. If you shift the curve to the left or right, the distribution becomes non-linear. The slope of the color curve increases or decreases. One end of the color palette then covers a large amount of results, while the other end distributes several colors over a relatively small result range.

You can use this feature to put the focus on a particular region in the diagram and to be able to detect small variations of the signal.

Example:



Fig. 7-9: Linear color curve shape = 0; colors are distributed evenly over the complete result range

In the color map based on the linear color curve, the range from -105.5 dBm to -60 dBm is covered by blue and a few shades of green only. The range from -60 dBm to -20 dBm is covered by red, yellow and a few shades of green.

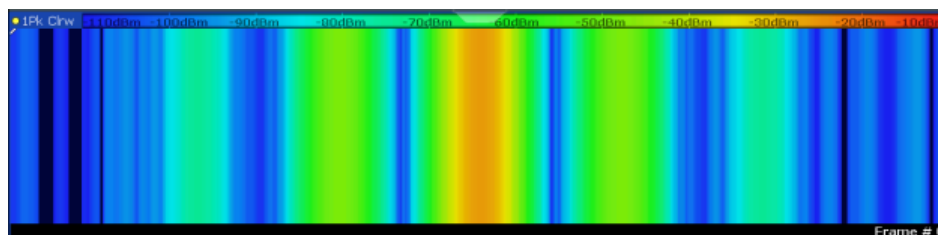


Fig. 7-10: Spectrogram with default color curve

The sample spectrogram is dominated by blue and green colors. After shifting the color curve to the left (negative value), more colors cover the range from -105.5 dBm to -60 dBm (blue, green and yellow), which occurs more often in the example. The range from -60 dBm to -20 dBm, on the other hand, is dominated by various shades of red only.



Fig. 7-11: Non-linear color curve shape = -0.5

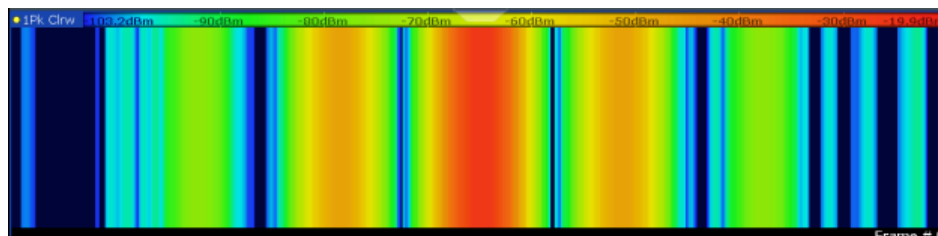
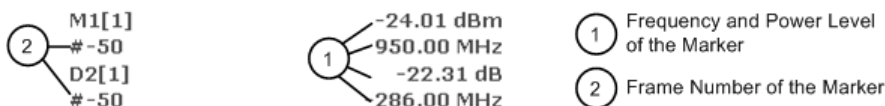


Fig. 7-12: Spectrogram with shifted color curve

Markers in the Spectrogram

Markers and delta markers are shaped like diamonds in the spectrogram. They are only displayed in the spectrogram if the marker position is inside the visible area of the spectrogram. If more than two markers are active, the marker values are displayed in a separate marker table.

In the spectrum result display, the markers and their frequency and level values (1) are displayed as usual. Additionally, the frame number is displayed to indicate the position of the marker in time (2).



In the spectrogram result display, you can activate up to 16 markers or delta markers at the same time. Each marker can be assigned to a different frame. Therefore, in addition to the frequency you also define the frame number when activating a new marker. If no frame number is specified, the marker is positioned on the currently selected frame. All markers are visible that are positioned on a visible frame. Special search functions are provided for spectrogram markers.

In the spectrum result display, only the markers positioned on the currently selected frame are visible. In "Continuous Sweep" mode this means that only markers positioned on frame 0 are visible. To view markers that are positioned on a frame other than frame 0 in the spectrum result display, you must stop the measurement and select the corresponding frame.

7.3.2 Trace Configuration

Trace configuration includes the following settings and functions:

- [Trace Settings](#).....409
- [Trace Math](#).....414
- [Trace / Data Export Configuration](#).....415
- [Spectrogram Settings](#).....417

7.3.2.1 Trace Settings

You can configure the settings for up to 6 individual traces.

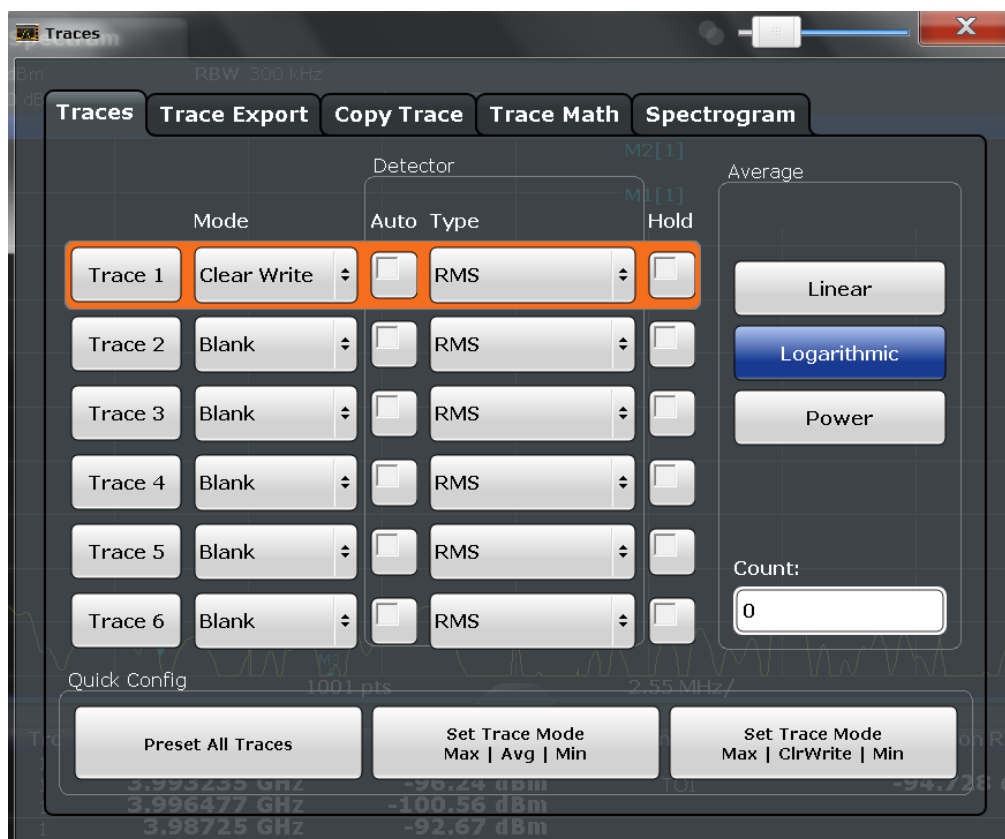
The trace settings are configured in the "Traces" dialog box which is displayed when you do one of the following:

- Press the TRACE key, then select "Trace Config".
- In the "Overview", select "Analysis", then switch to the vertical "Traces" tab.

For settings on spectrograms, see [chapter 7.3.2.4, "Spectrogram Settings"](#), on page 417.



Trace data can also be exported to an ASCII file for further analysis. For details see [chapter 7.3.2.3, "Trace / Data Export Configuration"](#), on page 415.



Trace 1/Trace 2/Trace 3/Trace 4/Trace 5/Trace 6..... 410

Trace Mode..... 410

Detector..... 411

Hold..... 411

Smoothing..... 412

Average Mode..... 412

Average Count..... 412

Predefined Trace Settings - Quick Config..... 413

Trace 1/Trace 2/Trace 3/Trace 4 (Softkeys)..... 413

Copy Trace..... 413

Trace 1/Trace 2/Trace 3/Trace 4/Trace 5/Trace 6

Selects the corresponding trace for configuration. The currently selected trace is highlighted.

For details see [chapter 7.3.3.1, "How to Configure a Standard Trace"](#), on page 421.

Remote command:

Selected via numeric suffix of:TRACe<1 . . . 6> commands

Trace Mode

Defines the update mode for subsequent traces.

For details see [chapter 7.3.1.2, "Analyzing Several Traces - Trace Mode"](#), on page 399.

"Clear Write"	Overwrite mode: the trace is overwritten by each sweep . This is the default setting. The "Detector" is automatically set to "Auto Peak".
"Max Hold"	The maximum value is determined over several sweep s and displayed. The R&S FPS saves each trace point in the trace memory only if the new value is greater than the previous one. The "Detector" is automatically set to "Positive Peak". This mode is not available for statistics measurements.
"Min Hold"	The minimum value is determined from several measurements and displayed. The R&S FPS saves each trace point in the trace memory only if the new value is lower than the previous one. The "Detector" is automatically set to "Negative Peak". This mode is not available for statistics measurements.
"Average"	The average is formed over several sweep s. The Sweep / Average Count determines the number of averaging procedures. The "Detector" is automatically set to "Sample". This mode is not available for statistics measurements.
"View"	The current contents of the trace memory are frozen and displayed.
"Blank"	Removes the selected trace from the display.

Remote command:

[DISPlay\[:WINDow<n>\]:TRACe<t>:MODE](#) on page 799

Detector

Defines the trace detector to be used for trace analysis.

For details see [chapter 7.3.1.1, "Mapping Samples to sweep Points with the Trace Detector"](#), on page 397.

"Auto"	Selects the optimum detector for the selected trace and filter mode. This is the default setting.
"Type"	Defines the selected detector type.

Remote command:

[\[SENSe:\] \[WINDow<n>:\] DETector<t>\[:FUNction\]](#) on page 803

[\[SENSe:\] \[WINDow<n>:\] DETector<t>\[:FUNction\]:AUTO](#) on page 803

Hold

If activated, traces in "Min Hold", "Max Hold" and "Average" mode are not reset after specific parameter changes have been made.

Normally, the measurement is started again after parameter changes, before the measurement results are analyzed (e.g. using a marker). In all cases that require a new measurement after parameter changes, the trace is reset automatically to avoid false results (e.g. with span changes). For applications that require no reset after parameter changes, the automatic reset can be switched off.

The default setting is off.

Remote command:

[DISPlay\[:WINDow<n>\]:TRACe<t>:MODE:HCONTinuous](#) on page 800

Smoothing

If enabled, the trace is smoothed by the specified value (between 1 % and 50 %). The smoothing value is defined as a percentage of the display width. The larger the smoothing value, the greater the smoothing effect.

Note: Effects of smoothing on post-processing functions. Note that in Spectrum mode, all functions performed after the sweep, such as limit checks, markers, or channel power measurements, are based on the smoothed trace data. Thus, the results will differ from results based on the original trace.

For more information see [chapter 7.3.1.6, "Trace Smoothing"](#), on page 402.

Remote command:

`DISPlay[:WINDow<n>]:TRACe<t>:SMOothing[:STATe]` on page 801

`DISPlay[:WINDow<n>]:TRACe<t>:SMOothing:APERTure` on page 801

Average Mode

Defines the mode with which the trace is averaged over several sweep s. A different averaging mode can be defined for each trace.

This setting is only applicable if trace mode "Average" is selected.

How many sweep s are averaged is defined by the ["Sweep / Average Count"](#) on page 361.

For details see [chapter 7.3.1.4, "How Trace Data is Averaged - the Averaging Mode"](#), on page 401.

"Linear"	The power level values are converted into linear units prior to averaging. After the averaging, the data is converted back into its original unit.
"Logarithmic"	For logarithmic scaling, the values are averaged in dBm. For linear scaling, the behavior is the same as with linear averaging.
"Power"	Activates linear power averaging. The power level values are converted into unit Watt prior to averaging. After the averaging, the data is converted back into its original unit. Use this mode to average power values in Volts or Amperes correctly.

Remote command:

`[SENSe:] AVERAge<n>:TYPE` on page 802

Average Count

Determines the number of averaging or maximum search procedures If the trace modes "Average", "Max Hold" or "Min Hold" are set.

In continuous sweep mode, if sweep count = 0 (default), averaging is performed over 10 sweep s. For sweep count =1, no averaging, maxhold or minhold operations are performed.

This value is identical to the [Sweep / Average Count](#) setting in the "Sweep" settings.

Remote command:

`[SENSe:] AVERAge<n>:COUNT` on page 802

Predefined Trace Settings - Quick Config

Commonly required trace settings have been predefined and can be applied very quickly by selecting the appropriate button.

Function	Trace Settings	
Preset All Traces	Trace 1:	Clear Write Auto Detector (Auto Peak)
	Traces 2-6:	Blank Auto Detector
Set Trace Mode Max Avg Min	Trace 1:	Max Hold Auto Detector (Positive Peak)
	Trace 2:	Average Auto Detector (Sample)
	Trace 3:	Min Hold Auto Detector (Negative Peak)
	Traces 4-6:	Blank Auto Detector
Set Trace Mode Max ClrWrite Min	Trace 1:	Max Hold Auto Detector (Positive Peak)
	Trace 2:	Clear Write Auto Detector (Auto Peak)
	Trace 3:	Min Hold Auto Detector (Negative Peak)
	Traces 4-6:	Blank Auto Detector

Trace 1/Trace 2/Trace 3/Trace 4 (Softkeys)

Displays the "Traces" settings and focuses the "Mode" list for the selected trace.

For details see [chapter 7.3.3.1, "How to Configure a Standard Trace"](#), on page 421.

Remote command:

`DISPlay[:WINDow<n>]:TRACe<t>[:STATe]` on page 801

Copy Trace

Opens the "Copy Trace" tab of the "Trace Configuration" dialog box.

The "Copy Trace" tab contains functionality to copy trace data to another trace.

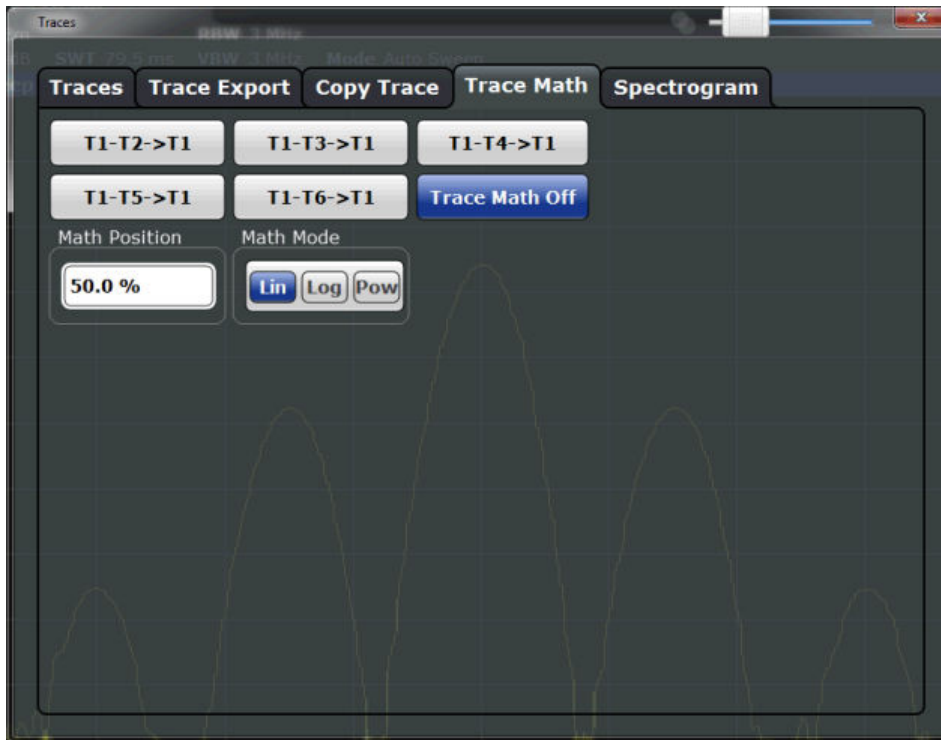
The first group of buttons (labelled "Trace 1" to "Trace 6") select the source trace. The second group of buttons (labelled "Copy to Trace 1" to "Copy to Trace 6") select the destination.

Remote command:

`TRACe<n>:COPY` on page 804

7.3.2.2 Trace Math

Trace math settings can be configured via the TRACE key, in the "Trace Math" tab of the "Traces" dialog box.



Trace Math Function..... 414
 Trace Math Off..... 415
 Trace Math Position..... 415
 Trace Math Mode..... 415

Trace Math Function

Defines which trace is subtracted from trace 1. The result is displayed in trace 1 and refers to the zero point defined with the [Trace Math Position](#) setting. The following subtractions can be performed:

"T1-T2 -> T1"	Subtracts trace 2 from trace 1.
"T1-T3 -> T1"	Subtracts trace 3 from trace 1
"T1-T4 -> T1"	Subtracts trace 4 from trace 1
"T1-T5 -> T1"	Subtracts trace 5 from trace 1
"T1-T6 -> T1"	Subtracts trace 6 from trace 1

To switch off the trace math, use the [Trace Math Off](#) button.

Remote command:

[CALCulate<n>:MATH\[:EXpression\]\[:DEFine\]](#) on page 810

[CALCulate<n>:MATH:STATe](#) on page 811

Trace Math Off

Deactivates any previously selected trace math functions.

Remote command:

CALC:MATH:STAT OFF, see CALCulate<n>:MATH:STATe on page 811

Trace Math Position

Defines the zero point on the y-axis of the resulting trace in % of the diagram height. The range of values extends from -100 % to +200 %.

Remote command:

CALCulate<n>:MATH:POSition on page 811

Trace Math Mode

Defines the mode for the trace math calculations.

- | | |
|---------|--|
| "Lin" | <p>Activates linear subtraction, which means that the power level values are converted into linear units prior to subtraction. After the subtraction, the data is converted back into its original unit. This setting takes effect if the grid is set to a linear scale. In this case, subtraction is done in two ways (depending on the set unit):</p> <ul style="list-style-type: none"> • The unit is set to either W or dBm: the data is converted into W prior to subtraction, i.e. averaging is done in W. • The unit is set to either V, A, dBmV, dBμV, dBμA or dBpW: the data is converted into V prior to subtraction, i.e. subtraction is done in V. |
| "Log" | <p>Activates logarithmic subtraction. This subtraction method only takes effect if the grid is set to a logarithmic scale, i.e. the unit of the data is dBm. In this case the values are subtracted in dBm. Otherwise (i.e. with linear scaling) the behavior is the same as with linear subtraction.</p> |
| "Power" | <p>Activates linear power subtraction. The power level values are converted into unit Watt prior to subtraction. After the subtraction, the data is converted back into its original unit. Unlike the linear mode, the subtraction is always done in W.</p> |

Remote command:

CALCulate<n>:MATH:MODE on page 811

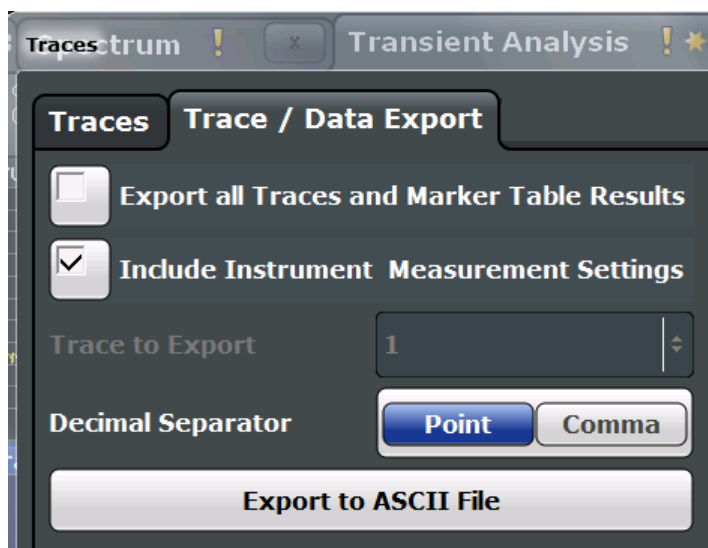
7.3.2.3 Trace / Data Export Configuration

The R&S FPS provides various evaluation methods for the results of the performed measurements. However, you may want to evaluate the data with other, external applications. In this case, you can export the measurement data to an ASCII file.



The standard data management functions (e.g. saving or loading instrument settings) that are available for all R&S FPS applications are not described here.

Trace and data export settings can be configured in the "Traces" dialog box ("Trace/ Data Export" tab).



[Export all Traces and all Table Results](#).....416
[Include Instrument Measurement Settings](#).....416
[Trace to Export](#).....416
[Decimal Separator](#)..... 417
[Export Trace to ASCII File](#)..... 417

Export all Traces and all Table Results

Selects all displayed traces and result tables (e.g. Result Summary, marker table etc.) in the current application for export to an ASCII file.

Alternatively, you can select one specific trace only for export (see [Trace to Export](#)).

The results are output in the same order as they are displayed on the screen: window by window, trace by trace, and table row by table row.

Remote command:

[FORMat:DEXPort:TRACes](#) on page 902

Include Instrument Measurement Settings

Includes additional instrument and measurement settings in the header of the export file for result data.

See [chapter 8.4.4, "Reference: ASCII File Export Format"](#), on page 497 for details.

Remote command:

[FORMat:DEXPort:HEADer](#) on page 902

Trace to Export

Defines an individual trace that will be exported to a file.

This setting is not available if [Export all Traces and all Table Results](#) is selected.

Decimal Separator

Defines the decimal separator for floating-point numerals for the data export files. Evaluation programs require different separators in different languages.

Remote command:

`FORMat:DEXPort:DSEParator` on page 881

Export Trace to ASCII File

Opens a file selection dialog box and saves the selected trace in ASCII format (`.dat`) to the specified file and directory.

The results are output in the same order as they are displayed on the screen: window by window, trace by trace, and table row by table row.

If the spectrogram display is selected when you perform this function, the entire histogram buffer with all frames is exported to a file. The data corresponding to a particular frame begins with information about the frame number and the time that frame was recorded. For large history buffers the export operation may take some time.

For details on the file format see [chapter 8.4.4, "Reference: ASCII File Export Format"](#), on page 497.

Note: Secure user mode.

In secure user mode, settings that are to be stored on the instrument are stored to volatile memory, which is restricted to 256 MB. Thus, a "Memory full" error may occur although the hard disk indicates that storage space is still available.

To store data permanently, select an external storage location such as a USB memory device.

For details see [chapter 3.1.6, "Protecting Data Using the Secure User Mode"](#), on page 30.

For details see "Protecting Data Using the Secure User Mode" in the "Data Management" section of the R&S FPS User Manual.

Remote command:

`MMEMory:STORe<n>:TRACe` on page 905

`MMEMory:STORe<n>:SPECTrogram` on page 904

7.3.2.4 Spectrogram Settings

The individual settings available for spectrogram display are described here. For settings on color mapping, see ["Color Map Settings"](#) on page 420.

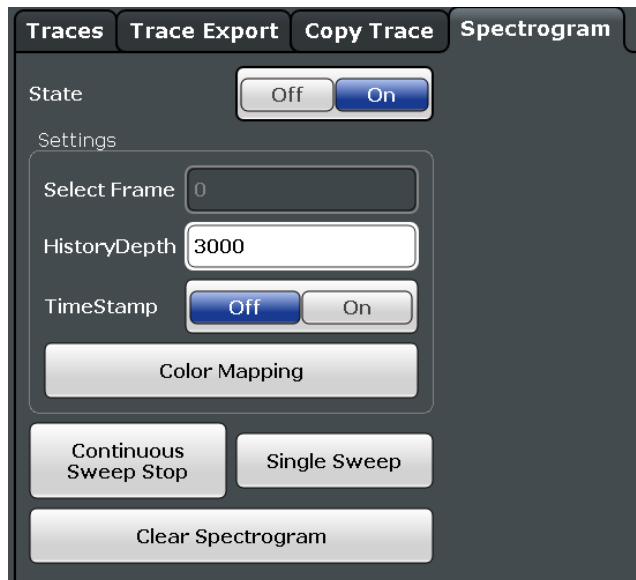
Settings concerning the frames and how they are handled during a sweep are provided as additional sweep settings for spectrogram display, see ["Spectrogram Frames"](#) on page 364.

Search functions for spectrogram markers are described in ["Marker Search Settings for Spectrograms"](#) on page 445.

- [General Spectrogram Settings](#).....418
- [Color Map Settings](#).....420

General Spectrogram Settings

This section describes general settings for spectrogram display. They are available when you press the TRACE key and then select the "Spectrogram Config" softkey.



State.....	418
Selecting a frame to display.....	418
History Depth.....	419
Timestamp.....	419
Color Mapping.....	419
Continuous Sweep/RUN CONT.....	419
Single Sweep/ RUN SINGLE.....	419
Clear Spectrogram.....	420

State

Activates and deactivates the spectrogram result display

Remote command:

`CALCulate<n>:SPECTrogram[:STATe]` on page 808

Selecting a frame to display

Selects a specific frame, loads the corresponding trace from the memory, and displays it in the Spectrum window.

Note that activating a marker or changing the position of the active marker automatically selects the frame that belongs to that marker.

This function is only available in single sweep mode or if the sweep is stopped, and only if a spectrogram is selected.

The most recent frame is number 0, all previous frames have a negative number.

For more information see "Time Frames" on page 404.

Remote command:

`CALCulate<n>:SPECTrogram:FRAMe:SElect` on page 806

History Depth

Sets the number of frames that the R&S FPS stores in its memory.

The maximum number of frames depends on the [Sweep Points](#). For an overview of the maximum number of frames depending on the number of sweep points, see [table 7-3](#).

If the memory is full, the R&S FPS deletes the oldest frames stored in the memory and replaces them with the new data.

Remote command:

`CALCulate<n>:SPECTrogram:HDEPth` on page 806

Timestamp

Activates and deactivates the timestamp. The timestamp shows the system time while the measurement is running. In single sweep mode or if the sweep is stopped, the timestamp shows the time and date of the end of the sweep .

When active, the timestamp replaces the display of the frame number.

Remote command:

`CALCulate<n>:SPECTrogram:TSTamp[:STATe]` on page 808

`CALCulate<n>:SPECTrogram:TSTamp:DATA?` on page 807

Color Mapping

Opens the "Color Map" dialog.

For details see ["Color Maps"](#) on page 406.

Continuous Sweep/RUN CONT

After triggering, starts the measurement and repeats it continuously until stopped.

While the measurement is running, the "Continuous Sweep" softkey and the RUN CONT key are highlighted. The running measurement can be aborted by selecting the highlighted softkey or key again. The results are not deleted until a new measurement is started.

Note: Sequencer. If the Sequencer is active, the "Continuous Sweep" softkey only controls the sweep mode for the currently selected channel; however, the sweep mode only has an effect the next time the Sequencer activates that channel, and only for a channel-defined sequence. In this case, a channel in continuous sweep mode is swept repeatedly.

Furthermore, the RUN CONT key controls the Sequencer, not individual sweeps. RUN CONT starts the Sequencer in continuous mode.

For details on the Sequencer, see [chapter 4.5.1, "The Sequencer Concept"](#), on page 107.

Remote command:

`INITiate<n>:CONTinuous` on page 605

Single Sweep/ RUN SINGLE

After triggering, starts the number of sweeps set in "Sweep Count". The measurement stops after the defined number of sweeps has been performed.

While the measurement is running, the "Single Sweep" softkey and the RUN SINGLE key are highlighted. The running measurement can be aborted by selecting the highlighted softkey or key again.

Remote command:

[INITiate<n>\[:IMMEDIATE\]](#) on page 606

[CALCulate<n>:SPECTrogram:CONT](#) on page 805

Clear Spectrogram

Resets the spectrogram result display and clears the history buffer.

This function is only available if a spectrogram is selected.

Remote command:

[CALCulate<n>:SPECTrogram:CLEar\[:IMMEDIATE\]](#) on page 805

Color Map Settings

The settings for color mapping are displayed in the "Color Mapping" dialog box that is displayed when you press the "Color Mapping" softkey in the "Spectrogram" menu, or select the color map in the spectrogram display.

For more information on color maps see ["Color Maps"](#) on page 406.

For details on changing color mapping settings see ["How to Configure the Color Mapping"](#) on page 424.

In addition to the available color settings, the dialog box displays the current color map and provides a preview of the display with the current settings.

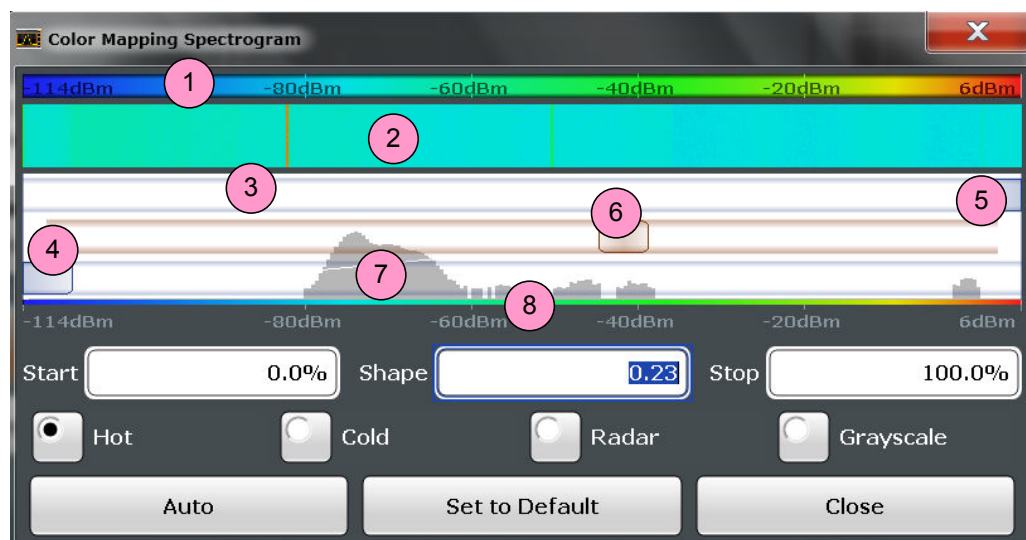


Fig. 7-13: Color Mapping dialog box

- 1 = Color map: shows the current color distribution
- 2 = Preview pane: shows a preview of the spectrogram with any changes that you make to the color scheme
- 3 = Color curve pane: graphical representation of all settings available to customize the color scheme
- 4/5 = Color range start and stop sliders: define the range of the color map or amplitudes for the spectrogram
- 6 = Color curve slider: adjusts the focus of the color curve
- 7 = Histogram: shows the distribution of measured values
- 8 = Scale of the horizontal axis (value range)

Start / Stop

Defines the lower and upper boundaries of the value range of the spectrogram.

Remote command:

[DISPlay\[:WINDow<n>\]:SPECTrogram:COLor:LOWer](#) on page 809

[DISPlay\[:WINDow<n>\]:SPECTrogram:COLor:UPPer](#) on page 809

Shape

Defines the shape and focus of the color curve for the spectrogram result display.

"-1 to <0" More colors are distributed among the lower values

"0" Colors are distributed linearly among the values

">0 to 1" More colors are distributed among the higher values

Remote command:

[DISPlay\[:WINDow<n>\]:SPECTrogram:COLor:SHAPE](#) on page 809

Hot/Cold/Radar/Grayscale

Sets the color scheme for the spectrogram.

Remote command:

[DISPlay\[:WINDow<n>\]:SPECTrogram:COLor\[:STYLE\]](#) on page 810

Auto

Defines the color range automatically according to the existing measured values for optimized display.

Set to Default

Sets the color mapping to the default settings.

Remote command:

[DISPlay\[:WINDow<n>\]:SPECTrogram:COLor:DEFAULT](#) on page 809

7.3.3 How to Configure Traces

The following step-by-step procedures describe the following tasks:

- [How to Configure a Standard Trace](#).....421
- [How to Display and Configure a Spectrogram](#).....422
- [How to Copy Traces](#).....426

7.3.3.1 How to Configure a Standard Trace

Step-by-step instructions on configuring the trace settings are provided here. For details on individual functions and settings see [chapter 7.3.2.1, "Trace Settings"](#), on page 409.

Trace settings are configured in the "Traces" dialog box.

To display the "Traces" dialog box, do one of the following:

- Press the TRACE key and then select the "Trace Config" softkey.
- Select "Analysis" from the "Overview", then select the "Traces" tab.

1. For each trace, select the "Trace Mode" and "Trace Detector". Traces with the trace mode "Blank" are not displayed.
2. To configure several traces to predefined display modes in one step, press the button for the required function:
 - "Preset All Traces"
 - "Set Trace Mode Avg | Max | Min"
 - "Set Trace Mode Max | ClrWrite | Min"

For details see [chapter 7.3.2.1, "Trace Settings"](#), on page 409.

3. For "Average" trace mode, define the number of sweeps to be averaged in the "Count" field.
4. If linear scaling is used, select the "Average Mode: Linear".
5. To improve the trace stability, increase the number of "Sweep Points" or the "Sweep Time" (in the "Sweep" settings).

All configured traces (not set to "Blank") are displayed after the next sweep .

How to Copy Traces

1. A trace copy function is provided in a separate tab of the "Traces" dialog box. To display this tab do one of the following:
 - Select the TRACE key and then the "Trace Copy" softkey.
 - Select "Analysis" from the "Overview", then select the "Trace Copy" tab.
2. Select the "Source" trace to be copied.
3. Select the "Copy to trace..." button for the trace to which the settings are to be applied.

The settings from the source trace are applied to the destination trace. The newly configured trace (if not set to "Blank") is displayed after the next sweep .

7.3.3.2 How to Display and Configure a Spectrogram

Step-by-step instructions on how to display and configure a spectrogram are provided here. For details on individual functions and settings see [chapter 7.3.2.4, "Spectrogram Settings"](#), on page 417.

The remote commands required to perform these tasks are described in [chapter 11.8.2.2, "Configuring Spectrograms"](#), on page 804.

The following tasks are described here:

- ["To display a spectrogram"](#) on page 423
- ["To remove the spectrogram display"](#) on page 423
- ["To set a marker in the spectrogram"](#) on page 423
- ["To configure a spectrogram"](#) on page 423
- ["To select a color scheme"](#) on page 424
- ["To set the value range graphically using the color range sliders"](#) on page 425

- ["To set the value range numerically"](#) on page 425
- ["To set the color curve shape graphically using the slider"](#) on page 426
- ["To set the color curve shape numerically"](#) on page 426

To display a spectrogram

1. In the "Overview", select "Display", then drag the evaluation type "Spectrogram" to the diagram area.
Alternatively:
 - a) Select the TRACE key and then the "Spectrogram Config" softkey.
 - b) Toggle "Spectrogram" to "ON".
2. To clear an existing spectrogram display, select "Clear Spectrogram".
3. Start a new measurement using RUN SINGLE or RUN CONT.
The spectrogram is updated continuously with each new sweep.
4. To display the spectrum diagram for a specific time frame:
 - a) Stop the continuous measurement or wait until the single sweep is completed.
 - b) Select the frame number in the diagram footer.
 - c) Enter the required frame number in the edit dialog box.
Note that the most recent sweep is frame number 0, all previous frames have negative numbers.

To remove the spectrogram display

1. Select the TRACE key and then the "Spectrogram Config" softkey.
2. Toggle "Spectrogram" to "OFF".
The standard spectrum display is restored.

To set a marker in the spectrogram

1. While a spectrogram is displayed, select the MARKER key.
2. Select a "Marker" softkey.
3. Enter the frequency or time (x-value) of the marker or delta marker.
4. Enter the frame number for which the marker is to be set, for example 0 for the current frame, or -2 for the second to last frame. Note that the frame number is always 0 or a negative value!
The marker is only visible in the spectrum diagram if it is defined for the currently selected frame. In the spectrogram result display all markers are visible that are positioned on a visible frame.

To configure a spectrogram

1. Configure the spectrogram frames:
 - a) Select the SWEEP key.
 - b) Select the "Sweep Config" softkey.

- c) In the "Sweep/Average Count" field, define how many sweeps are to be analyzed to create a single frame.
 - d) In the "Frame Count" field, define how many frames are to be plotted during a single sweep measurement.
 - e) To include frames from previous sweeps in the analysis of the new frame (for "Max Hold", "Min Hold" and "Average" trace modes only), select "Continue Frame" = "ON".
2. Define how many frames are to be stored in total:
 - a) Select the TRACE key and then the "Spectrogram Config" softkey.
 - b) Select the "History Depth" softkey.
 - c) Enter the maximum number of frames to store.
 3. Optionally, replace the frame number by a time stamp by toggling the "Timestamp" softkey to "On".
 4. If necessary, adapt the color mapping for the spectrogram to a different value range or color scheme as described in ["How to Configure the Color Mapping"](#) on page 424.

How to Configure the Color Mapping

The color display is highly configurable to adapt the spectrograms to your needs.

The settings for color mapping are defined in the "Color Mapping" dialog box. To display this dialog box, do one of the following:

- Select the color map in the spectrogram display.
- Select the "Color Mapping" softkey in the "Spectrogram" menu.

To select a color scheme

You can select which colors are assigned to the measured values.

- ▶ In the "Color Mapping" dialog box, select the option for the color scheme to be used.

Editing the value range of the color map

The distribution of the measured values is displayed as a histogram in the "Color Mapping" dialog box. To cover the entire measurement value range, make sure the first and last bar of the histogram are included.

To ignore noise in a spectrogram, for example, exclude the lower power levels from the histogram.

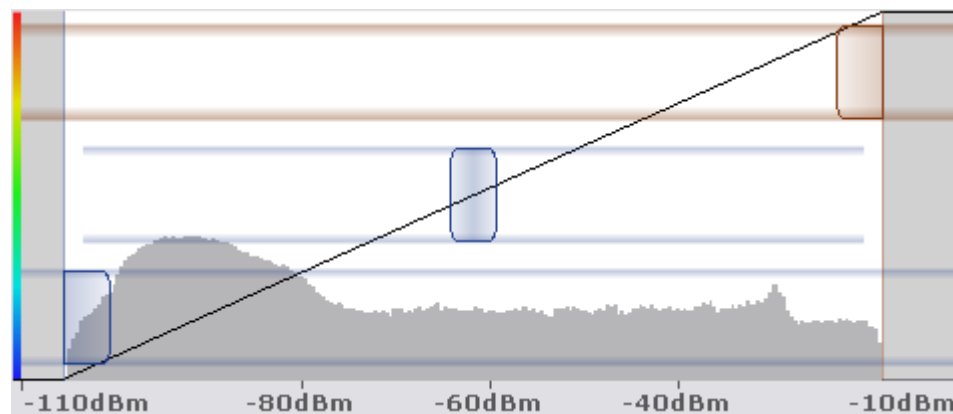


The value range of the color map must cover at least 10% of the value range on the horizontal axis of the diagram, that means, the difference between the start and stop values must be at least 10%.

The value range can be set numerically or graphically.

To set the value range graphically using the color range sliders

1. Select and drag the bottom color curve slider (indicated by a gray box at the left of the color curve pane) to the lowest value you want to include in the color mapping.
2. Select and drag the top color curve slider (indicated by a gray box at the right of the color curve pane) to the highest value you want to include in the color mapping.



To set the value range numerically

1. In the "Start" field, enter the percentage from the left border of the histogram that marks the beginning of the value range.
2. In the "Stop" field, enter the percentage from the right border of the histogram that marks the end of the value range.

Example:

The color map starts at -100 dBm and ends at 0 dBm (i.e. a range of 100 dB). In order to suppress the noise, you only want the color map to start at -90 dBm. Thus, you enter 10% in the "Start" field. The R&S FPS shifts the start point 10% to the right, to -90 dBm.



Adjusting the reference level and level range

Note that changing the reference level and level range of the measurement also affects the color mapping in the spectrogram.

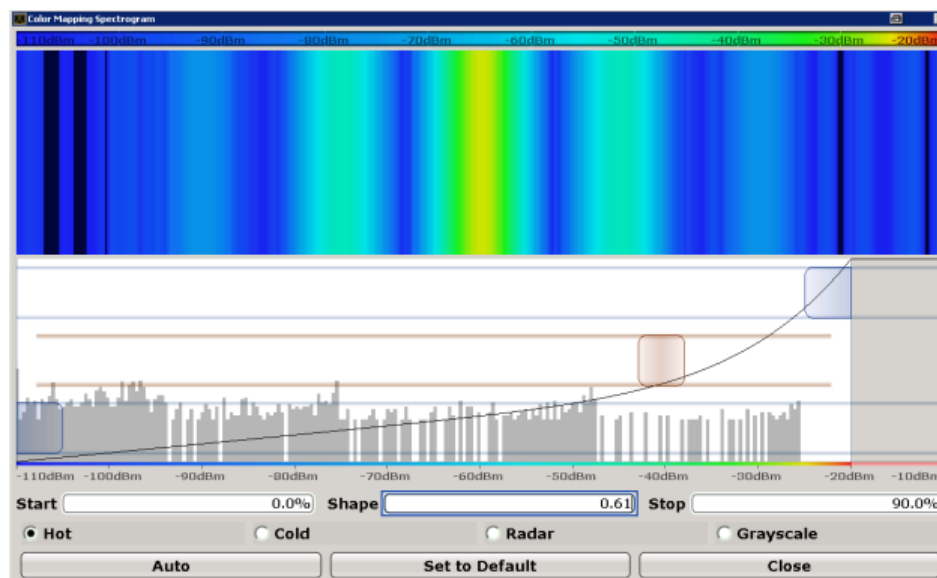
Editing the shape of the color curve

The color curve is a tool to shift the focus of the color distribution on the color map. By default, the color curve is linear, i.e. the colors on the color map are distributed evenly. If you shift the curve to the left or right, the distribution becomes non-linear. The slope of the color curve increases or decreases. One end of the color palette then covers a large amount of results, while the other end distributes several colors over a relatively small result range.

The color curve shape can be set numerically or graphically.

To set the color curve shape graphically using the slider

- ▶ Select and drag the color curve shape slider (indicated by a gray box in the middle of the color curve) to the left or right. The area beneath the slider is focussed, i.e. more colors are distributed there.



To set the color curve shape numerically

- ▶ In the "Shape" field, enter a value to change the shape of the curve:
 - A negative value (-1 to <0) focusses the lower values
 - 0 defines a linear distribution
 - A positive value (>0 to 1) focusses the higher values

7.3.3.3 How to Copy Traces

You can copy the trace settings from one trace to another in the "Copy Trace" tab of the "Traces" dialog box.

- ▶ Select the "Source" trace and then the button for the "Copy to" trace.

Remote command:

`TRACe<n>:COPY` on page 804

7.4 Marker Usage

Markers help you analyze your measurement results by determining particular values in the diagram. Thus you can extract numeric values from a graphical display both in the time and frequency domain. In addition to basic markers, sophisticated marker functions are provided for special results such as noise or demodulation.



Markers in Spectrogram Displays

In the spectrogram result display, you can activate up to 16 markers or delta markers at the same time. Each marker can be assigned to a different frame. Therefore, in addition to the frequency you also define the frame number when activating a new marker. If no frame number is specified, the marker is positioned on the currently selected frame. All markers are visible that are positioned on a visible frame.

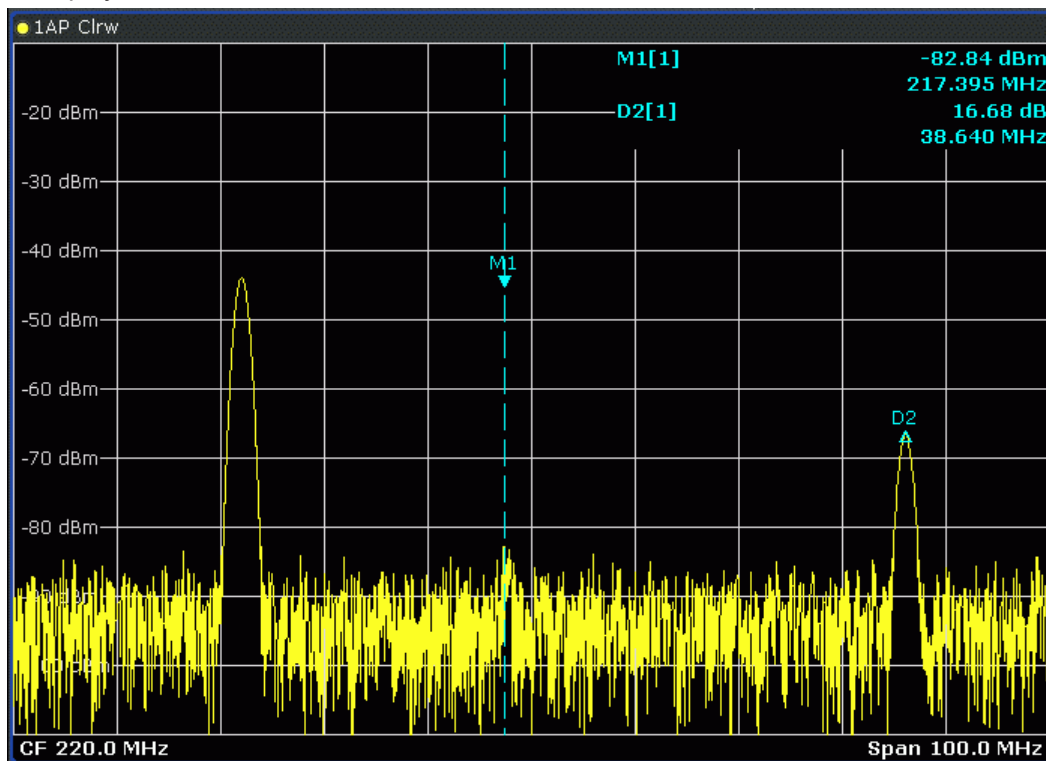
- [Basics on Markers and Marker Functions](#).....427
- [Marker Configuration](#).....436
- [Marker Function Configuration](#).....450
- [How to Work With Markers](#).....460
- [Measurement Example: Measuring Harmonics Using Marker Functions](#).....462

7.4.1 Basics on Markers and Marker Functions

Some background knowledge on marker settings and functions is provided here for a better understanding of the required configuration settings.

Markers are used to mark points on traces, to read out measurement results and to select a display section quickly. R&S FPS provides 16 markers per display window. In the Spectrum application, the same markers are displayed in all windows.

- The easiest way to work with markers is using a mouse. Simply drag the marker and drop it at the required position. When a marker label is selected, a vertical line is displayed which indicates the marker's current x-value.



- You can also set an active marker to a new position by defining its x-position numerically. When you select the softkey for a marker, an edit dialog box is displayed.
- The most commonly required marker settings and functions are also available as softkeys.
Softkeys for active markers (displayed on the screen) are highlighted blue. The softkey for the currently selected marker (for which functions are performed) is highlighted orange.
- To set individual markers very quickly, use the softkeys in the "Marker" menu.
- To set up several markers at once, use the "Marker" dialog box.
- To position the selected marker to a special value, use the softkeys in the "Marker To" menu.
- To determine more sophisticated marker results, use the special functions in the "Marker Function" dialog box.

In addition to basic markers, sophisticated marker functions are provided for special results such as noise or demodulation.

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• Performing a Highly Accurate Frequency Measurement (Signal Count)	432
• Defining a Fixed Reference Marker	432
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• Measuring Characteristic Bandwidths (n dB Down Marker)	434
• Measuring the Power in a Channel (Band)	435

7.4.1.1 Marker Types

All markers can be used either as normal markers or delta markers. A normal marker indicates the absolute signal value at the defined position in the diagram. A delta marker indicates the value of the marker relative to the specified reference marker (by default marker 1).

In addition, special functions can be assigned to the individual markers. The availability of special marker functions depends on whether the measurement is performed in the frequency or time domain, and on the type of measurement.

Temporary markers are used in addition to the markers and delta markers to analyze the measurement results for special marker functions. They disappear when the associated function is deactivated.

7.4.1.2 Activating Markers

Only active markers are displayed in the diagram and in the marker table.

Active markers are indicated by a highlighted softkey.

By default, marker 1 is active and positioned on the maximum value (peak) of trace 1 as a normal marker. If several traces are displayed, the marker is set to the maximum value of the trace which has the lowest number and is not frozen (View mode). The next marker to be activated is set to the frequency of the next lower level (next peak) as a delta marker; its value is indicated as an offset to marker 1.

A marker can only be activated when at least one trace in the corresponding window is visible. If a trace is switched off, the corresponding markers and marker functions are also deactivated. If the trace is switched on again, the markers along with coupled functions are restored to their original positions, provided the markers have not been used on another trace.

7.4.1.3 Marker Results

Normal markers point to a sweep point on the time or frequency axis and display the associated numeric value for that sweep point. Delta markers indicate an offset between the level at the delta marker position and the level at the position of the assigned reference marker, in dB.

Signal count markers determine the frequency of a signal at the marker position very accurately.

The results can be displayed directly within the diagram area or in a separate table. By default, the first two active markers are displayed in the diagram area. If more markers are activated, the results are displayed in a marker table.

Marker information in diagram area

By default, the results of the last two markers or delta markers that were activated are displayed in the diagram area.

D2[1]	-21.90 dB
	-3.9180 GHz
M1[1]	-25.87 dBm
	13.1970 GHz

The following information is displayed there:

- The marker type (M for normal, D for delta, or special function name)
- The marker number (1 to 16)
- The assigned trace number in square brackets []
- The marker value on the y-axis, or the result of the marker function
- The marker position on the x-axis

For n dB down markers, additional information is displayed, see [chapter 7.4.1.9, "Measuring Characteristic Bandwidths \(n dB Down Marker\)"](#), on page 434.

Marker information in marker table

In addition to the marker information displayed within the diagram area, a separate marker table may be displayed beneath the diagram. This table provides the following information for all active markers:

Type	Marker type: N (normal), D (delta), T (temporary, internal) and number
Ref	Reference marker for delta markers
Trc	Trace to which the marker is assigned
Frame	Spectrogram frame the marker is positioned in. Displayed only when the Spectrogram is displayed.
X-value	X-value of the marker
Y-value	Y-value of the marker
Function	Activated marker or measurement function
Function Result	Result of the active marker or measurement function

7.4.1.4 Searching for Signal Peaks

A common measurement task is to determine peak values, i.e. maximum or minimum signal levels. The R&S FPS provides various peak search functions and applications:

- Setting a marker to a peak value once (Peak Search)
- Searching for a peak value within a restricted search area (Search Limits)
- Creating a marker table with all or a defined number of peak values for one sweep (Marker Peak List)
- Updating the marker position to the current peak value automatically after each sweep (Auto Peak Search)
- Creating a fixed reference marker at the current peak value of a trace (Fixed Reference)

Peak search limits

The peak search can be restricted to a search area. The search area is defined by limit lines which are also indicated in the diagram. In addition, a minimum value (threshold) can be defined as a further search condition.

When is a peak a peak? - Peak excursion

During a peak search, for example when a marker peak table is displayed, noise values may be detected as a peak if the signal is very flat or does not contain many peaks. Therefore, you can define a relative threshold ("Peak excursion"). The signal level must increase by the threshold value before falling again before a peak is detected. To avoid identifying noise peaks as maxima or minima, enter a peak excursion value that is higher than the difference between the highest and the lowest value measured for the displayed inherent noise.

Effect of peak excursion settings (example)

The following figure shows a trace to be analyzed.

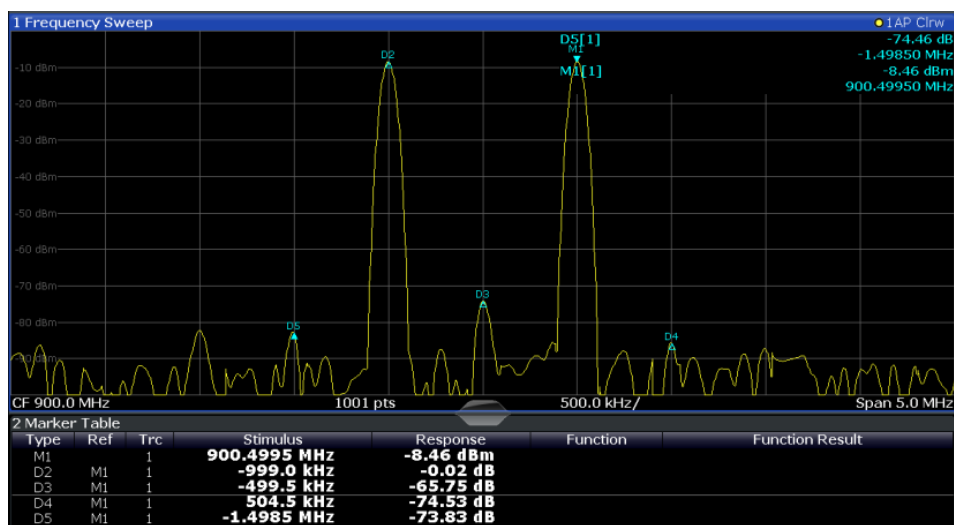


Fig. 7-14: Trace example

The following table lists the peaks as indicated by the marker numbers in the diagram above, as well as the minimum decrease in amplitude to either side of the peak:

Marker #	Min. amplitude decrease to either side of the signal
1	30 dB
2	29.85 dB
3	20 dB
4	10 dB
5	18 dB

In order to eliminate the smaller peaks M3,M4 and M5 in the example above, a peak excursion of at least 20 dB is required. In this case, the amplitude must rise at least 20 dB before falling again before a peak is detected.

Marker peak list

The marker peak list determines the frequencies and levels of peaks in the spectrum. It is updated automatically after each sweep . How many peaks are displayed can be defined, as well as the sort order. In addition, the detected peaks can be indicated in the diagram. The peak list can also be exported to a file for analysis in an external application.

Automatic peak search

A peak search can be repeated automatically after each sweep in order to keep the maximum value as the reference point for a phase noise measurement. This is useful to track a drifting source. The delta marker 2, which shows the phase noise measurement result, keeps the delta frequency value. Therefore the phase noise measurement leads to reliable results in a certain offset although the source is drifting.

Using a peak as a fixed reference marker

Some results are analyzed in relation to a peak value, for example a carrier frequency level. In this case, the maximum level can be determined by an initial peak search and then be used as a reference point for further measurement results.

7.4.1.5 Performing a Highly Accurate Frequency Measurement (Signal Count)

A normal marker determines the position of the point on the trace and indicates the signal frequency at this position. The trace, however, contains only a limited number of points. Depending on the selected span, each trace point may contain many measurement values. Thus, the frequency resolution of each trace point is limited (see also [chapter 6.5.1.8, "How Much Data is Measured: Sweep Points and Sweep Count"](#), on page 356). Frequency resolution is further restricted by the RBW and sweep time settings.

In order to determine the frequency of a signal point accurately without changing the sweep settings, the R&S FPS is equipped with a signal counter. The signal counter sets the RF to the current marker position, then counts the zero crossings of the IF (thus the term signal *counter*) and derives the precise frequency value.

Signal counting can be performed explicitly at the current marker position ("Signal Count" marker function), or implicitly by the R&S FPS for certain functions.

Signal counting is only possible while the instrument is not sweeping. Thus, to perform a signal count for a marker, the sweep is stopped at the marker position. The frequency is determined with the desired resolution and then the sweep is allowed to continue.

7.4.1.6 Defining a Fixed Reference Marker

Instead of using a reference marker that may vary its position depending on the measurement results, a fixed reference marker can be defined for trace analysis. Once positioned, the reference marker does not move during subsequent sweeps unless you explicitly move it manually.

7.4.1.7 Measuring Noise Density

Using the noise measurement marker function, the noise power density is measured at the position of the marker. In the time domain mode, all points of the trace are used to determine the noise power density. When measurements are performed in the frequency domain, two points to the right and left of the marker are used for the measurement to obtain a stable result.

Result display

Noise density is the noise referred to a bandwidth of 1 Hz. With logarithmic amplitude units (dBm, dBmV, dBm μ V, dB μ A), the noise power density is output in dBm/Hz, i.e. as level in 1 Hz bandwidth with reference to 1 mW. With linear amplitude units (V, A, W), the noise voltage density is analyzed in μ V/ \sqrt Hz, the noise current density in μ A/ \sqrt Hz or the noise power density in μ W/ \sqrt Hz.

The result is indicated as the **function result in the Marker Table**.

Prerequisite settings

The following settings have to be made to obtain correct values:

- Detector: Sample or RMS
- Video bandwidth:
 - ≤ 0.1 resolution bandwidth with sample detector
 - ≥ 3 x resolution bandwidth with RMS detector
- Trace averaging:

In the default setting, the R&S FPS uses the sample detector for the noise function. With the sample detector, the trace can additionally be set to "Average" mode to stabilize the measured values. When the RMS detector is used, trace averaging should not be used since in this case it produces too low noise levels which cannot be corrected. Instead, the sweep time can be increased to obtain stable measurement results.

Correction factors

The R&S FPS uses the following correction factors to analyze the noise density from the marker level:

- Since the noise power is indicated with reference to 1 Hz bandwidth, the bandwidth correction value is deducted from the marker level. It is $10 \times \lg(1 \text{ Hz}/\text{BW}_{\text{Noise}})$, where BW_{Noise} is the noise or power bandwidth of the set resolution filter (RBW).
- RMS detector: With the exception of bandwidth correction, no further corrections are required since this detector already indicates the power for each point of the trace.
- Sample detector: As a result of video filter averaging and trace averaging, 1.05 dB is added to the marker level. This is the difference between the average value and the RMS value of white noise. With a logarithmic level axis, 1.45 dB is added additionally. Logarithmic averaging is thus fully taken into account which yields a value that is 1.45 dB lower than that of linear averaging.
- To allow a more stable noise display the adjacent (symmetric to the measurement frequency) points of the trace are averaged.
- For span > 0, the measured values are averaged versus time (after a sweep).



The R&S FPS noise figure can be calculated from the measured power density level. It is calculated by deducting the set RF attenuation (RF Att) from the displayed noise level and adding 174 to the result.

7.4.1.8 Measuring Phase Noise

Phase noise is unintentional modulation of a carrier; it creates frequencies next to the carrier frequency. A phase noise measurement consists of noise density measurements at defined offsets from the carrier; the results are given in relation to the carrier level (dBc). The phase noise marker function measures the noise power at the delta markers referred to 1 Hz bandwidth. Marker 1 is used as the reference for the phase

noise measurement. By default, the current frequency and level of marker 1 are used as the fixed reference marker. However, a peak search can be started to use the current signal peak as the reference point, or a reference point can be defined manually.

Since the reference point is fixed, the reference level or the center frequency can be set so that the carrier is outside the displayed frequency range after phase noise measurement is started. Or a notch filter can be switched on to suppress the carrier.

Alternatively, the reference point can be determined automatically by a peak search after each sweep. This function can be used to track a drifting source during a phase noise measurement. The delta marker 2, which shows the phase noise measurement result, keeps the delta frequency value. Therefore the phase noise measurement leads to reliable results in a certain offset although the source is drifting. Only if the marker 2 reaches the border of the span, the delta marker value is adjusted to be within the span. In these cases, select a larger span.

The result of the phase noise measurement is the difference in level between the reference point and the noise power density. It is indicated as the function result of the phase noise marker in the Marker Table.

The sample detector is automatically used and the video bandwidth set to 0.1 times the resolution bandwidth (RBW). The two settings are taken into account in the correction values used for the noise power measurement. To obtain stable results, two pixels on the right and the left of the delta marker position are taken for the measurement.

The procedure for determining the noise power is identical to the method used for the noise power measurement (see [chapter 7.4.1.7, "Measuring Noise Density"](#), on page 432).

7.4.1.9 Measuring Characteristic Bandwidths (n dB Down Marker)

When characterizing the shape of a signal, the bandwidth at a specified offset from its peak level is often of interest. The offset is specified as a relative decrease in amplitude of n dB. In order to measure this bandwidth, you could use several markers and delta markers and determine the bandwidth manually. However, using the n dB down marker function makes the task very simple and quick.

The n dB down marker function uses the current value of marker 1 as the reference point. It activates two temporary markers T1 and T2 located on the signal, whose level is n dB below the level of the reference point. Marker T1 is placed to the left and marker T2 to the right of the reference marker. The default setting for n is 3 dB, but it can be changed.

If a positive offset is entered, the markers T1 and T2 are placed below the active reference point. If a negative value is entered (for example for notch filter measurements), the markers T1 and T2 are placed above the active reference point.

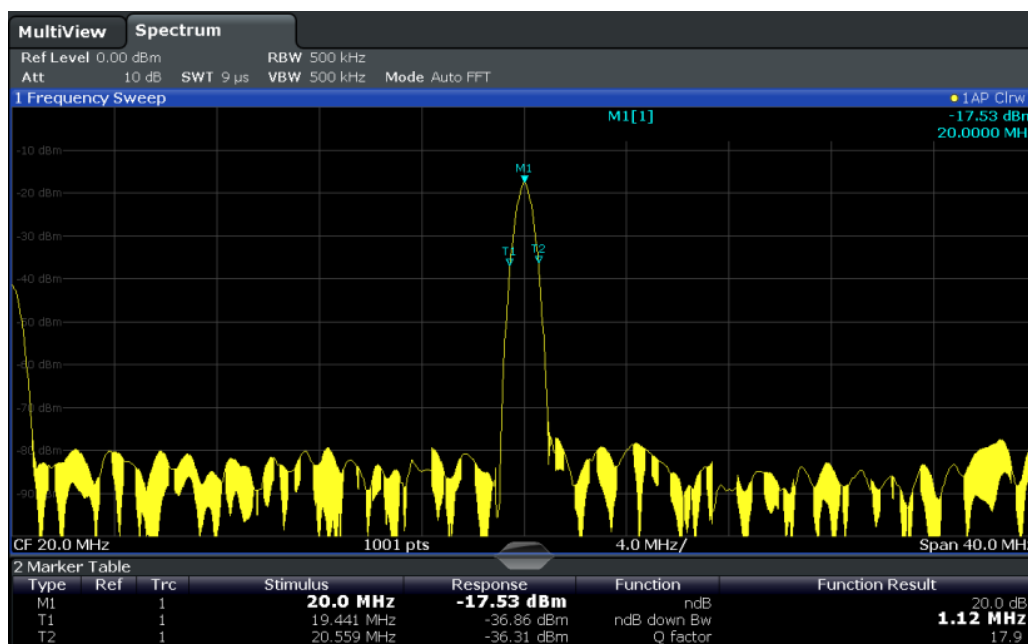


Fig. 7-15: n dB down marker function

The following marker function results are displayed:

Table 7-4: n dB down marker function results

Label	Description
M1	Current position and level of marker 1
ndB	Offset value (n dB down)
ndB down Bw / PWid	Determined bandwidth or pulse width (zero span) at the offset
Q-factor	Quality factor of the determined bandwidth (characteristic of damping or resonance)
T1, T2	Current position and level of the temporary markers

If the required position for the temporary markers cannot be determined uniquely, for example due to noise, dashes are displayed as a result.

7.4.1.10 Measuring the Power in a Channel (Band)

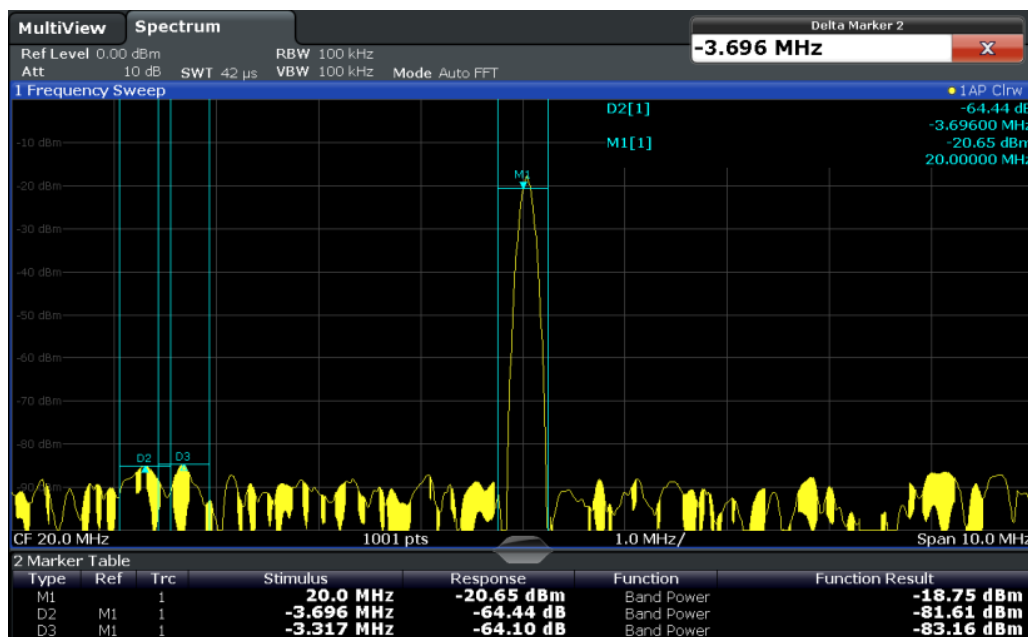
When you want to determine the noise power in a transmission channel, you could use a noise marker and multiply the result with the channel bandwidth. However, the results would only be accurate for flat noise.

Band power markers allow you to measure the integrated power for a defined span (band) around a marker (similar to ACP measurements). By default, 5 % of the current span is used. The span is indicated by limit lines in the diagram. The results can be displayed either as a power (dBm) or density (dBm/Hz) value and are indicated in the marker table for each band power marker.



Band power markers are only available for standard frequency measurements (not zero span) in the Spectrum application.

The entire band must lie within the display. If it is moved out of the display, the result cannot be calculated (indicated by "- -" as the "Function Result"). However, the width of the band is maintained so that the band power can be calculated again when it returns to the display.



All markers can be defined as band power markers, each with a different span. When a band power marker is activated, if no marker is active yet, marker 1 is activated. Otherwise, the currently active marker is used as a band power marker (all other marker functions for this marker are deactivated).

If the detector mode for the marker trace is set to "Auto", the RMS detector is used.

7.4.2 Marker Configuration

When working with markers, the following configuration settings and functions are available:

- [Marker Settings](#)..... 436
- [Marker Search Settings and Positioning Functions](#)..... 442

7.4.2.1 Marker Settings

Marker settings can be configured via the MARKER menu or in the "Marker" dialog box.

To display the "Marker" dialog box, do one of the following:

- Press the MKR key, then select the "Marker Config" softkey.

- In the "Overview", select "Analysis", and switch to the vertical "Marker" tab.

The remote commands required to define these settings are described in [chapter 11.8.3.1, "Setting Up Individual Markers"](#), on page 819.

- [Individual Marker Setup](#)..... 437
- [General Marker Settings](#)..... 440

Individual Marker Setup

Up to 17 markers or delta markers can be activated for each window simultaneously. Initial marker setup is performed using the "Marker" dialog box.



The markers are distributed among 3 tabs for a better overview. By default, the first marker is defined as a normal marker, whereas all others are defined as delta markers with reference to the first marker. All markers are assigned to trace 1, but only the first marker is active.

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- [Marker State](#)..... 438
- [Marker Position \(X-value\)](#)..... 438
- [Frame \(Spectrogram only\)](#)..... 438
- [Marker Type](#)..... 438
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Selected Marker

Marker name. The marker which is currently selected for editing is highlighted orange.

Remote command:

Marker selected via suffix <m> in remote commands.

Marker State

Activates or deactivates the marker in the diagram.

Remote command:

[CALCulate<n>:MARKer<m>\[:STATe\]](#) on page 823

[CALCulate<n>:DELTAmarker<m>\[:STATe\]](#) on page 821

Marker Position (X-value)

Defines the position (x-value) of the marker in the diagram.

Remote command:

[CALCulate<n>:MARKer<m>:X](#) on page 823

[CALCulate<n>:DELTAmarker<m>:X](#) on page 822

Frame (Spectrogram only)

Spectrogram frame the marker is assigned to.

Remote command:

[CALCulate<n>:MARKer<m>:SPECTrogram:FRAME](#) on page 836

[CALCulate<n>:DELTAmarker<m>:SPECTrogram:FRAME](#) on page 840

Marker Type

Toggles the marker type.

The type for marker 1 is always "Normal", the type for delta marker 1 is always "Delta". These types cannot be changed.

Note: If normal marker 1 is the active marker, switching the "Mkr Type" activates an additional delta marker 1. For any other marker, switching the marker type does not activate an additional marker, it only switches the type of the selected marker.

"Normal" A normal marker indicates the absolute value at the defined position in the diagram.

"Delta" A delta marker defines the value of the marker relative to the specified reference marker (marker 1 by default).

Remote command:

[CALCulate<n>:MARKer<m>\[:STATe\]](#) on page 823

[CALCulate<n>:DELTAmarker<m>\[:STATe\]](#) on page 821

Reference Marker

Defines a marker as the reference marker which is used to determine relative analysis results (delta marker values).

If the reference marker is deactivated, the delta marker referring to it is also deactivated.

If a fixed reference point is configured (see "Defining a Fixed Reference" on page 441), the reference point ("FXD") can also be selected instead of another marker.

Remote command:

`CALCulate<n>:DELTaMarker<m>:MREF` on page 821

Linking to Another Marker

Links the current marker to the marker selected from the list of active markers. If the x-axis value of the initial marker is changed, the linked marker follows on the same x-position. Linking is off by default.

Using this function you can set two markers on different traces to measure the difference (e.g. between a max hold trace and a min hold trace or between a measurement and a reference trace).

Remote command:

`CALCulate<n>:MARKer<m>:LINK:TO:MARKer<m>` on page 822

`CALCulate<n>:DELTaMarker<m>:LINK:TO:MARKer<m>` on page 820

`CALCulate<n>:DELTaMarker<m>:LINK` on page 820

Assigning the Marker to a Trace

The "Trace" setting assigns the selected marker to an active trace. The trace determines which value the marker shows at the marker position. If the marker was previously assigned to a different trace, the marker remains on the previous frequency or time, but indicates the value of the new trace.

The marker can also be assigned to the currently active trace using the "Marker to Trace" softkey in the "Marker" menu.

If a trace is turned off, the assigned markers and marker functions are also deactivated.

Remote command:

`CALCulate<n>:MARKer<m>:TRACe` on page 823

Select Marker

The "Select Marker" function opens a dialog box to select and activate or deactivate one or more markers quickly.



Remote command:
 Marker selected via suffix <m> in remote commands.

All Markers Off

Deactivates all markers in one step.

Remote command:

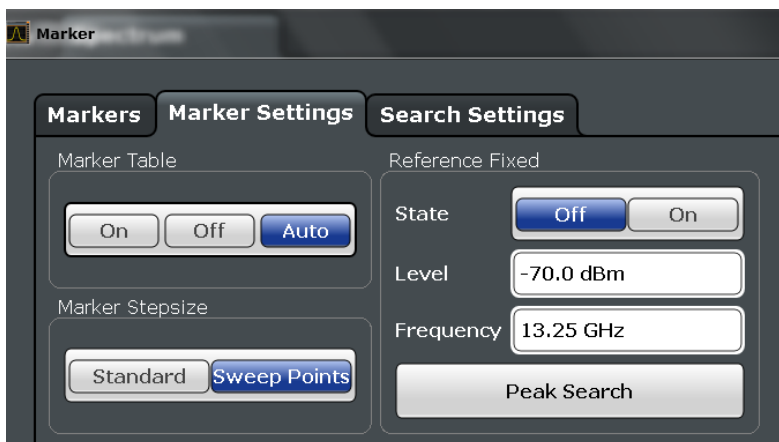
[CALCulate<n>:MARKer<m>:AOFF](#) on page 822

General Marker Settings

Some general marker settings allow you to influence the marker behavior for all markers.

These settings are located in the "Marker Settings" tab of the "Marker" dialog box. To display this tab, do one of the following:

- Press the MKR key, then select the "Marker Config" softkey.
- In the "Overview", select "Analysis", and switch to the vertical "Marker" tab. Then select the horizontal "Marker Settings" tab.



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Marker Table Display

Defines how the marker information is displayed.

"On"	Displays the marker information in a table in a separate area beneath the diagram.
"Off"	Displays the marker information within the diagram area.
"Auto"	(Default) Up to two markers are displayed in the diagram area. If more markers are active, the marker table is displayed automatically.

Remote command:

`DISPlay:MTABLE` on page 824

Marker Stepsize

Defines the size of the steps that the marker position is moved using the rotary knob.

"Standard"	The marker position is moved in (Span/1000) steps, which corresponds approximately to the number of pixels for the default display of 1001 sweep points. This setting is most suitable to move the marker over a larger distance.
"Sweep Points"	The marker position is moved from one sweep point to the next. This setting is required for a very precise positioning if more sweep points are collected than the number of pixels that can be displayed on the screen. It is the default mode.

Remote command:

`CALCulate<n>:MARKer<m>:X:SSIZE` on page 824

Defining a Fixed Reference

Instead of using a reference marker that may vary its position depending on the measurement results, a fixed reference marker can be defined for trace analysis.

When you set the "State" to "On", a vertical and a horizontal red display line are displayed, marked as "FXD". The normal marker 1 is activated and set to the peak value of the trace assigned to marker 1, and a delta marker to the next peak. The fixed reference marker is set to the position of marker 1 at the peak value. The delta marker refers to the fixed reference marker.

If activated, the fixed reference marker ("FXD") can also be selected as a "Reference Marker" instead of another marker.

The "Level" and "Frequency" or "Time" settings define the position and value of the reference marker.

Alternatively, a **Peak Search** can be performed to set the current maximum value of the trace assigned to marker 1 as the fixed reference marker.

Remote command:

`CALCulate<n>:DELTamarker<m>:FUNction:FIXed[:STATe]` on page 844

`CALCulate<n>:DELTamarker<m>:FUNction:FIXed:RPoint:Y` on page 844

`CALCulate<n>:DELTamarker<m>:FUNction:FIXed:RPoint:X` on page 843

`CALCulate<n>:DELTamarker<m>:FUNction:FIXed:RPoint:MAXimum[:PEAK]`
on page 843

7.4.2.2 Marker Search Settings and Positioning Functions

Several functions are available to set the marker to a specific position very quickly and easily, or to use the current marker position to define another characteristic value. In order to determine the required marker position, searches may be performed. The search results can be influenced by special settings.

Most marker positioning functions and the search settings are available in the MKR -> menu.

Search settings are also available via the MARKER key or in the vertical "Marker Config" tab of the "Analysis" dialog box (horizontal "Search Settings" tab).

For more information on searching for signal peaks see [chapter 7.4.1.4, "Searching for Signal Peaks"](#), on page 430.

The remote commands required to define these settings are described in [chapter 11.8.3.4, "Positioning the Marker"](#), on page 828.

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Marker Search Settings

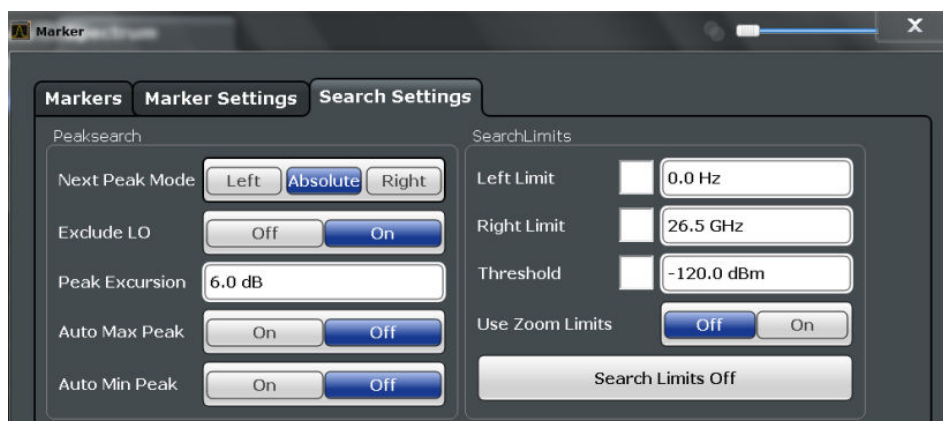
Markers are commonly used to determine peak values, i.e. maximum or minimum values, in the measured signal. Configuration settings allow you to influence the peak search results.



For Spectrograms, special marker settings are available, see ["Marker Search Settings for Spectrograms"](#) on page 445.

These settings are available as softkeys in the "Marker To" menu, or in the "Search Settings" tab of the "Marker" dialog box. To display this tab, do one of the following:

- Press the MKR key, then select the "Marker Config" softkey. Then select the horizontal "Search Settings" tab.
- In the "Overview", select "Analysis", and switch to the vertical "Marker Config" tab. Then select the horizontal "Search Settings" tab.



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 L Search Threshold..... 444

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Search Mode for Next Peak

Selects the search mode for the next peak search.

- "Left" Determines the next maximum/minimum to the left of the current peak.
- "Absolute" Determines the next maximum/minimum to either side of the current peak.
- "Right" Determines the next maximum/minimum to the right of the current peak.

Remote command:
[chapter 11.8.3.4, "Positioning the Marker"](#), on page 828

Exclude LO

If activated, restricts the frequency range for the marker search functions.

- "ON" The minimum frequency included in the peak search range is $\geq 5 \times$ resolution bandwidth (RBW).
 Due to the interference by the first local oscillator to the first intermediate frequency at the input mixer, the LO is represented as a signal at 0 Hz. To avoid the peak marker jumping to the LO signal at 0 Hz, this frequency is excluded from the peak search.
- "OFF" No restriction to the search range. The frequency 0 Hz is included in the marker search functions.

Remote command:
[CALCulate<n>:MARKer<m>:LOEXclude](#) on page 825

Peak Excursion

Defines the minimum level value by which a signal must rise or fall so that it will be identified as a maximum or a minimum by the search functions.

Entries from 0 dB to 80 dB are allowed; the resolution is 0.1 dB. The default setting for the peak excursion is 6 dB.

For more information see [chapter 7.4.1.4, "Searching for Signal Peaks"](#), on page 430.

Remote command:

`CALCulate<n>:MARKer<m>:PEXCursion` on page 825

Auto Max / Min Peak Search

If activated, a maximum or minimum peak search is performed automatically for marker 1 after each sweep .

For spectrogram displays, define which frame the peak is to be searched in.

Remote command:

`CALCulate<n>:MARKer<m>:MAXimum:AUTO` on page 828

`CALCulate<n>:MARKer<m>:MINimum:AUTO` on page 829

Search Limits

The search results can be restricted by limiting the search area or adding search conditions.

Search Limits (Left / Right) ← Search Limits

If activated, limit lines are defined and displayed for the search. Only results within the limited search range are considered.

For details on limit lines for searches see ["Peak search limits"](#) on page 430.

Remote command:

`CALCulate<n>:MARKer<m>:X:SLIMits[:STATe]` on page 825

`CALCulate<n>:MARKer<m>:X:SLIMits:LEFT` on page 826

`CALCulate<n>:MARKer<m>:X:SLIMits:RIGHT` on page 826

Search Threshold ← Search Limits

Defines an absolute threshold as an additional condition for the peak search. Only peaks that exceed the threshold are detected.

Remote command:

`CALCulate<n>:THReshold` on page 827

Using Zoom Limits ← Search Limits

If activated, the peak search is restricted to the active zoom area defined for a single zoom (see ["Single Zoom"](#) on page 393).

Remote command:

`CALCulate<n>:MARKer<m>:X:SLIMits:ZOOM[:STATe]` on page 827

Deactivating All Search Limits ← Search Limits

Deactivates the search range limits.

Remote command:

CALCulate<n>:MARKer<m>:X:SLIMits[:STATe] on page 825

CALCulate<n>:THReshold:STATe on page 827

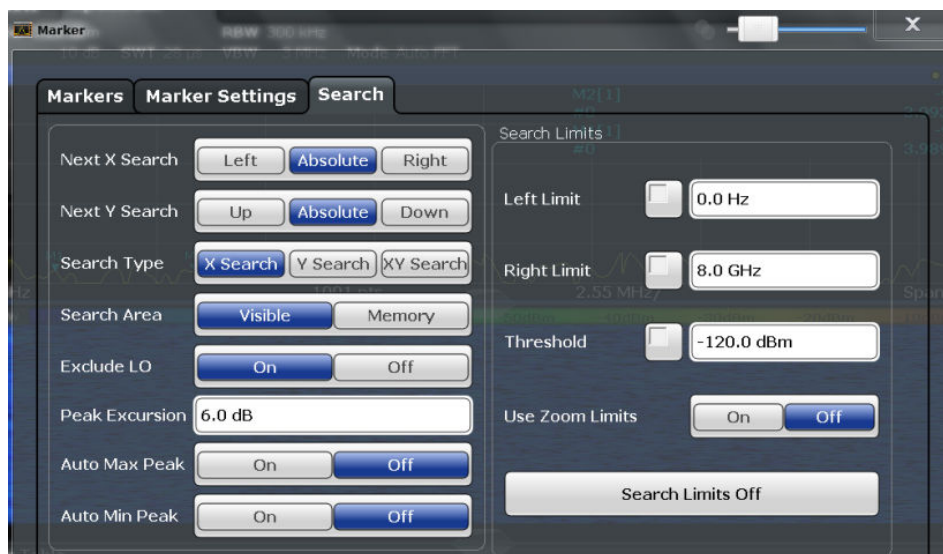
Marker Search Settings for Spectrograms

Spectrograms show not only the current sweep results, but also the sweep history. Thus, when searching for peaks, you must define the search settings within a single time frame (x-direction) and within several time frames (y-direction).

These settings are only available for spectrogram displays.

These settings are available in the "Search Settings" tab of the "Marker" dialog box. To display this tab, do one of the following:

- Press the MKR key, then select the "Marker Config" softkey. Then select the horizontal "Search Settings" tab.
- In the "Overview", select "Analysis", and switch to the vertical "Marker Config" tab. Then select the horizontal "Search Settings" tab.



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 L Deactivating All Search Limits.....448

Search Mode for Next Peak in X Direction

Selects the search mode for the next peak search within the currently selected frame.

"Left"	Determines the next maximum/minimum to the left of the current peak.
"Absolute"	Determines the next maximum/minimum to either side of the current peak.
"Right"	Determines the next maximum/minimum to the right of the current peak.

Remote command:

[chapter 11.8.3.4, "Positioning the Marker"](#), on page 828

Search Mode for Next Peak in Y Direction

Selects the search mode for the next peak search within all frames at the current marker position.

"Up"	Determines the next maximum/minimum above the current peak (in more recent frames).
"Absolute"	Determines the next maximum/minimum above or below the current peak (in all frames).
"Down"	Determines the next maximum/minimum below the current peak (in older frames).

Remote command:

[CALCulate<n>:MARKer<m>:SPECTrogram:Y:MAXimum:ABOVE](#) on page 837

[CALCulate<n>:DELTamarker<m>:SPECTrogram:Y:MAXimum:ABOVE](#)
on page 841

[CALCulate<n>:MARKer<m>:SPECTrogram:Y:MAXimum:BELOW](#) on page 837

[CALCulate<n>:DELTamarker<m>:SPECTrogram:Y:MAXimum:BELOW](#)
on page 841

[CALCulate<n>:MARKer<m>:SPECTrogram:Y:MAXimum:NEXT](#) on page 837

[CALCulate<n>:DELTamarker<m>:SPECTrogram:Y:MAXimum:NEXT](#) on page 841

[CALCulate<n>:MARKer<m>:SPECTrogram:Y:MINimum:ABOVE](#) on page 838

[CALCulate<n>:DELTamarker<m>:SPECTrogram:Y:MINimum:ABOVE](#)
on page 842

[CALCulate<n>:MARKer<m>:SPECTrogram:Y:MINimum:BELOW](#) on page 838

[CALCulate<n>:DELTamarker<m>:SPECTrogram:Y:MINimum:BELOW](#)
on page 842

[CALCulate<n>:MARKer<m>:SPECTrogram:Y:MINimum:NEXT](#) on page 838

[CALCulate<n>:DELTamarker<m>:SPECTrogram:Y:MINimum:NEXT](#) on page 842

Marker Search Type

Defines the type of search to be performed in the spectrogram.

"X-Search"	Searches only within the currently selected frame.
"Y-Search"	Searches within all frames but only at the current frequency position.

"XY-Search" Searches in all frames at all positions.

Remote command:

[CALCulate<n>:MARKer<m>:SPECTrogram:XY:MAXimum\[:PEAK\]](#) on page 837

[CALCulate<n>:DELTamarker<m>:SPECTrogram:XY:MAXimum\[:PEAK\]](#)

on page 841

[CALCulate<n>:MARKer<m>:SPECTrogram:XY:MINimum\[:PEAK\]](#) on page 837

[CALCulate<n>:DELTamarker<m>:SPECTrogram:XY:MINimum\[:PEAK\]](#)

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[CALCulate<n>:MARKer<m>:SPECTrogram:Y:MAXimum\[:PEAK\]](#) on page 838

[CALCulate<n>:DELTamarker<m>:SPECTrogram:Y:MAXimum\[:PEAK\]](#)

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[CALCulate<n>:MARKer<m>:SPECTrogram:Y:MINimum\[:PEAK\]](#) on page 839

[CALCulate<n>:DELTamarker<m>:SPECTrogram:Y:MINimum\[:PEAK\]](#)

on page 843

[CALCulate<n>:MARKer<m>:MAXimum\[:PEAK\]](#) on page 829

[CALCulate<n>:DELTamarker<m>:MAXimum\[:PEAK\]](#) on page 831

[CALCulate<n>:MARKer<m>:MINimum\[:PEAK\]](#) on page 830

[CALCulate<n>:DELTamarker<m>:MINimum\[:PEAK\]](#) on page 832

Marker Search Area

Defines which frames the search is performed in.

"Visible" Only the visible frames are searched.

"Memory" All frames stored in the memory are searched.

Remote command:

[CALCulate<n>:MARKer<m>:SPECTrogram:SARea](#) on page 836

[CALCulate<n>:DELTamarker<m>:SPECTrogram:SARea](#) on page 840

Exclude LO

If activated, restricts the frequency range for the marker search functions.

"ON" The minimum frequency included in the peak search range is $\geq 5 \times$ resolution bandwidth (RBW).
Due to the interference by the first local oscillator to the first intermediate frequency at the input mixer, the LO is represented as a signal at 0 Hz. To avoid the peak marker jumping to the LO signal at 0 Hz, this frequency is excluded from the peak search.

"OFF" No restriction to the search range. The frequency 0 Hz is included in the marker search functions.

Remote command:

[CALCulate<n>:MARKer<m>:LOEXclude](#) on page 825

Peak Excursion

Defines the minimum level value by which a signal must rise or fall so that it will be identified as a maximum or a minimum by the search functions.

Entries from 0 dB to 80 dB are allowed; the resolution is 0.1 dB. The default setting for the peak excursion is 6 dB.

For more information see [chapter 7.4.1.4, "Searching for Signal Peaks"](#), on page 430.

Remote command:

[CALCulate<n>:MARKer<m>:PEXCursion](#) on page 825

Auto Max / Min Peak Search

If activated, a maximum or minimum peak search is performed automatically for marker 1 after each sweep .

For spectrogram displays, define which frame the peak is to be searched in.

Remote command:

[CALCulate<n>:MARKer<m>:MAXimum:AUTO](#) on page 828

[CALCulate<n>:MARKer<m>:MINimum:AUTO](#) on page 829

Search Limits

The search results can be restricted by limiting the search area or adding search conditions.

Search Limits (Left / Right) ← Search Limits

If activated, limit lines are defined and displayed for the search. Only results within the limited search range are considered.

For details on limit lines for searches see ["Peak search limits"](#) on page 430.

Remote command:

[CALCulate<n>:MARKer<m>:X:SLIMits\[:STATe\]](#) on page 825

[CALCulate<n>:MARKer<m>:X:SLIMits:LEFT](#) on page 826

[CALCulate<n>:MARKer<m>:X:SLIMits:RIGHT](#) on page 826

Search Threshold ← Search Limits

Defines an absolute threshold as an additional condition for the peak search. Only peaks that exceed the threshold are detected.

Remote command:

[CALCulate<n>:THReshold](#) on page 827

Using Zoom Limits ← Search Limits

If activated, the peak search is restricted to the active zoom area defined for a single zoom (see ["Single Zoom"](#) on page 393).

Remote command:

[CALCulate<n>:MARKer<m>:X:SLIMits:ZOOM\[:STATe\]](#) on page 827

Deactivating All Search Limits ← Search Limits

Deactivates the search range limits.

Remote command:

[CALCulate<n>:MARKer<m>:X:SLIMits\[:STATe\]](#) on page 825

[CALCulate<n>:THReshold:STATe](#) on page 827

Positioning Functions

The following functions set the currently selected marker to the result of a peak search or set other characteristic values to the current marker value.

These functions are available as softkeys in the "Marker To" menu, which is displayed when you press the MKR -> key.

Peak Search.....	449
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Search Minimum.....	449
Search Next Minimum.....	449
Center Frequency = Marker Frequency.....	449
Reference Level = Marker Level.....	450

Peak Search

Sets the selected marker/delta marker to the maximum of the trace. If no marker is active, marker 1 is activated.

For spectrogram displays, define which frame the peak is to be searched in.

Remote command:

[CALCulate<n>:MARKer<m>:MAXimum\[:PEAK\]](#) on page 829

[CALCulate<n>:DELTAmarker<m>:MAXimum\[:PEAK\]](#) on page 831

Search Next Peak

Sets the selected marker/delta marker to the next (lower) maximum of the assigned trace. If no marker is active, marker 1 is activated.

For spectrogram displays, define which frame the next peak is to be searched in.

Remote command:

[CALCulate<n>:MARKer<m>:MAXimum:NEXT](#) on page 828

[CALCulate<n>:DELTAmarker<m>:MAXimum:NEXT](#) on page 831

Search Minimum

Sets the selected marker/delta marker to the minimum of the trace. If no marker is active, marker 1 is activated.

For spectrogram displays, define which frame the minimum is to be searched in.

Remote command:

[CALCulate<n>:MARKer<m>:MINimum\[:PEAK\]](#) on page 830

[CALCulate<n>:DELTAmarker<m>:MINimum\[:PEAK\]](#) on page 832

Search Next Minimum

Sets the selected marker/delta marker to the next (higher) minimum of the selected trace. If no marker is active, marker 1 is activated.

For spectrogram displays, define which frame the next minimum is to be searched in.

Remote command:

[CALCulate<n>:MARKer<m>:MINimum:NEXT](#) on page 830

[CALCulate<n>:DELTAmarker<m>:MINimum:NEXT](#) on page 832

Center Frequency = Marker Frequency

Sets the center frequency to the selected marker or delta marker frequency. A peak can thus be set as center frequency, for example to analyze it in detail with a smaller span.

This function is not available for zero span measurements.

Remote command:

[CALCulate<n>:MARKer<m>:FUNCTION:CENTer](#) on page 741

Reference Level = Marker Level

Sets the reference level to the selected marker level.

Remote command:

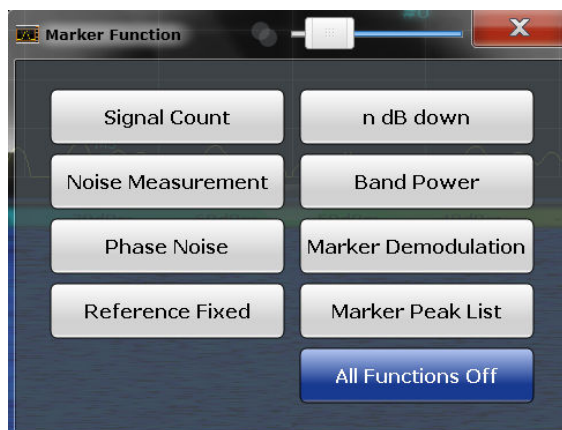
[CALCulate<n>:MARKer<m>:FUNCTION:REFerence](#) on page 755

7.4.3 Marker Function Configuration

Special marker functions can be selected via the "Marker Function" dialog box.

To display this dialog box, do one of the following:

- Press the MKR FUNC key, then select the "Select Marker Function" softkey.
- In the "Overview", select "Analysis", and switch to the vertical "Marker Function Config" tab.



The remote commands required to define these settings are described in [chapter 11.8.3, "Working with Markers"](#), on page 819.

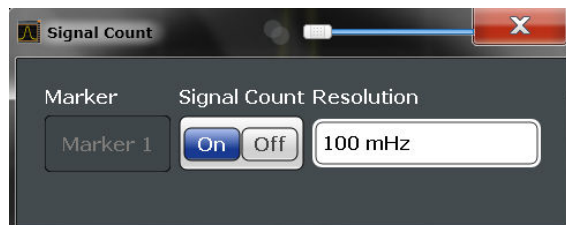
- [Precise Frequency \(Signal Count\) Marker](#).....450
- [Noise Measurement Marker](#).....451
- [Phase Noise Measurement Marker](#).....453
- [n dB Down Marker](#).....455
- [Reference Fixed](#).....456
- [Band Power Marker](#).....456
- [Marker Peak List Configuration](#).....458
- [Deactivating All Marker Functions](#).....460

7.4.3.1 Precise Frequency (Signal Count) Marker

A special marker can be used to determine a particular frequency or time in a measured signal very accurately. Signal counters are configured in the "Signal Count Config" dialog box.

To display the "Signal Count Config" dialog box, do one of the following:

- Press the MKR FUNC key, then select the "Select Marker Function" softkey. Then select the "Signal Count" button. Select the "Signal Count Config" softkey.
- In the "Overview", select "Analysis", and switch to the vertical "Marker Function Config" tab. Then select the "Signal Count" button. Select the "Signal Count Config" softkey.



For details see [chapter 7.4.1.5, "Performing a Highly Accurate Frequency Measurement \(Signal Count\)"](#), on page 432. A measurement example is described in [chapter 5.2.2.2, "Measuring the Signal Frequency Using the Signal Counter"](#), on page 119.



Signal counters are not available for measurements on I/Q-based data.

Signal Count Marker State	451
Resolution	451

Signal Count Marker State

Activates or deactivates the special signal count marker function.

When activated, the sweep stops at the reference marker until the signal counter has delivered a result.

Remote command:

[CALCulate<n>:MARKer<m>:COUNT](#) on page 856

[CALCulate<n>:MARKer<m>:COUNT:FREQuency?](#) on page 856

Resolution

Defines the resolution with which the signal is analyzed around the reference marker 1.

Remote command:

[CALCulate<n>:MARKer<m>:COUNT:RESolution](#) on page 857

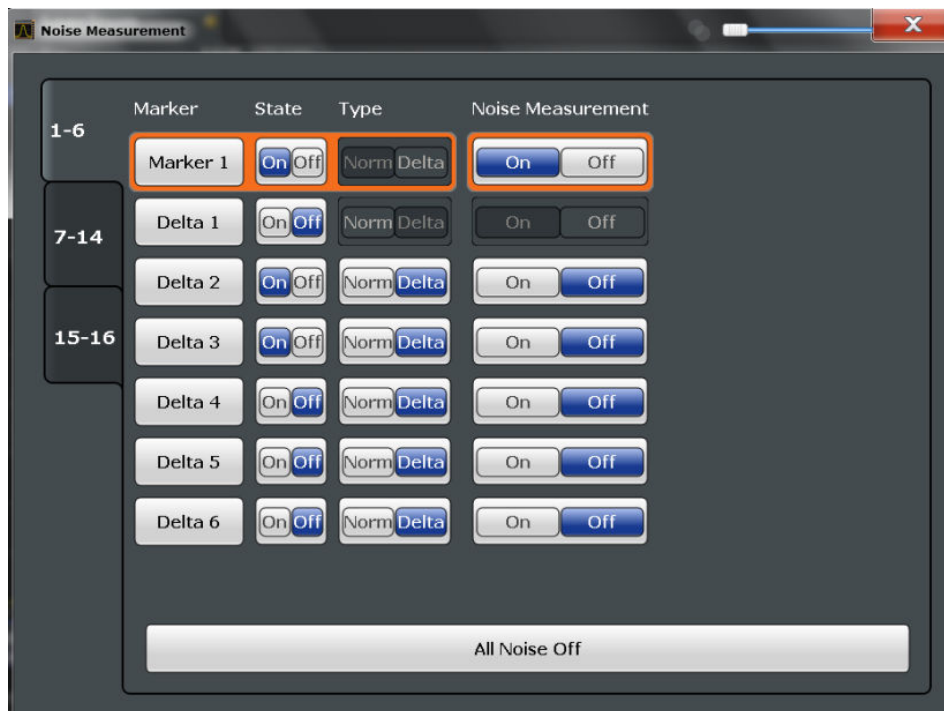
7.4.3.2 Noise Measurement Marker

For each of the 16 markers noise measurement can be activated. Noise measurement markers are configured in the "Noise Measurement Config" dialog box, using the "Noise Measurement" function.

The individual marker settings correspond to those defined in the "Marker" dialog box (see ["Individual Marker Setup"](#) on page 437). Any settings to the marker state or type changed in the "Marker Function" dialog box are also changed in the "Marker" dialog box and vice versa.

To display the "Noise Measurement Config" dialog box, do one of the following:

- Press the MKR FUNC key, then select the "Select Marker Function" softkey. Then select the "Noise Measurement" button. Select the "Noise Meas Config" softkey.
- In the "Overview", select "Analysis", and switch to the vertical "Marker Function Config" tab. Then select the "Noise Measurement" button. Select the "Noise Meas Config" softkey.



For details see [chapter 7.4.1.7, "Measuring Noise Density"](#), on page 432.

[Marker State](#).....452

[Marker Type](#).....452

[Noise Measurement State](#).....453

[Switching All Noise Measurements Off](#).....453

Marker State

Activates or deactivates the marker in the diagram.

Remote command:

[CALCulate<n>:MARKer<m>\[:STATe\]](#) on page 823

[CALCulate<n>:DELTAmarker<m>\[:STATe\]](#) on page 821

Marker Type

Toggles the marker type.

The type for marker 1 is always "Normal", the type for delta marker 1 is always "Delta". These types cannot be changed.

Note: If normal marker 1 is the active marker, switching the "Mkr Type" activates an additional delta marker 1. For any other marker, switching the marker type does not activate an additional marker, it only switches the type of the selected marker.

"Normal" A normal marker indicates the absolute value at the defined position in the diagram.

"Delta" A delta marker defines the value of the marker relative to the specified reference marker (marker 1 by default).

Remote command:

`CALCulate<n>:MARKer<m>[:STATe]` on page 823

`CALCulate<n>:DELTAmarker<m>[:STATe]` on page 821

Noise Measurement State

Activates or deactivates noise measurement for the marker in the diagram.

This function is only available for normal markers.

If activated, the marker displays the noise power density measured at the position of the marker.

For details see [chapter 7.4.1.7, "Measuring Noise Density"](#), on page 432.

Remote command:

`CALCulate<n>:MARKer<m>:FUNCTION:NOISe[:STATe]` on page 848

`CALCulate<n>:MARKer<m>:FUNCTION:NOISe:RESult?` on page 848

Switching All Noise Measurements Off

Deactivates noise measurement for all markers.

Remote command:

`CALCulate<n>:MARKer<m>:FUNCTION:NOISe[:STATe]` on page 848

7.4.3.3 Phase Noise Measurement Marker

For each of the 16 markers phase noise measurement can be activated. Phase noise measurement markers are configured in the "Phase Noise Config" dialog box, using the "Phase Noise" function.

The individual marker settings correspond to those defined in the "Marker" dialog box. Any settings to the marker state or type changed in the "Marker Function" dialog box are also changed in the "Marker" dialog box and vice versa.

To display the "Phase Noise Config" dialog box, do one of the following:

- Press the MKR FUNC key, then select the "Select Marker Function" softkey. Then select the "Phase Noise" button. Select the "Phase Noise Config" softkey.
- In the "Overview", select "Analysis", and switch to the vertical "Marker Function Config" tab. Then select the "Phase Noise" button. Select "Phase Noise Config".



For more information see [chapter 7.4.1.8, "Measuring Phase Noise"](#), on page 433.

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[Defining a Reference Point](#)..... 454
[Switching All Phase Noise Measurements Off](#).....455

Phase Noise Measurement State

Activates or deactivates phase noise measurement for the reference point in the diagram.

This function is only available for delta markers.

If activated, the delta markers display the phase noise measured at defined offsets from the reference position.

Remote command:

`CALCulate<n>:DELTAmarker<m>:FUNCTION:PNOise[:STATE]` on page 849

`CALCulate<n>:DELTAmarker<m>:FUNCTION:PNOise:RESult?` on page 849

Defining a Reference Point

Instead of using marker 1 as the reference marker, a fixed reference marker can be defined for phase noise measurement.

Instead of using marker 1 as the reference marker, a fixed reference marker can be defined for phase noise measurement in RF Spectrum analysis.

The "Level" and "Frequency" or "Time" settings define the position and value of the reference point.

Alternatively, a **Peak Search** can be performed to set the maximum value of the selected trace as the reference point.

If "Automatic Peak Search" is activated, a peak search is started automatically after each sweep and the result is used as the reference point.

Remote command:

`CALCulate<n>:DELTaMarker<m>:FUNCTION:FIXed:RPOINT:Y` on page 844

`CALCulate<n>:DELTaMarker<m>:FUNCTION:FIXed:RPOINT:X` on page 843

`CALCulate<n>:DELTaMarker<m>:FUNCTION:FIXed:RPOINT:MAXimum[:PEAK]`
on page 843

`CALCulate<n>:DELTaMarker<m>:FUNCTION:PNOise:AUTO` on page 849

Switching All Phase Noise Measurements Off

Deactivates phase noise measurement for all markers.

Remote command:

`CALCulate<n>:DELTaMarker<m>:FUNCTION:PNOise[:STATE]` on page 849

7.4.3.4 n dB Down Marker

A special marker can be defined to determine a characteristic bandwidth or time span in a measured signal. n dB down markers are configured in the "N dB Down Config" dialog box, using the "n dB down" function.

To display the "N dB Down Config" dialog box, do one of the following:

- Press the MKR FUNC key, then select the "Select Marker Function" softkey. Then select the "n dB down" button. Select the "N dB Down Config" softkey.
- In the "Overview", select "Analysis", and switch to the vertical "Marker Function Config" tab. Then select the "n dB down" button. Select "N dB Down Config".



For details see [chapter 7.4.1.9, "Measuring Characteristic Bandwidths \(n dB Down Marker\)"](#), on page 434.

[n dB down Marker State](#).....455

[n dB down Delta Value](#).....456

n dB down Marker State

Activates or deactivates the special n dB down marker function.

Remote command:

`CALCulate<n>:MARKer<m>:FUNCTION:NDBDown:STATE` on page 855

`CALCulate<n>:MARKer<m>:FUNCTION:NDBDown:RESULT?` on page 854

n dB down Delta Value

Defines the delta level from the reference marker 1 used to determine the bandwidth or time span.

Remote command:

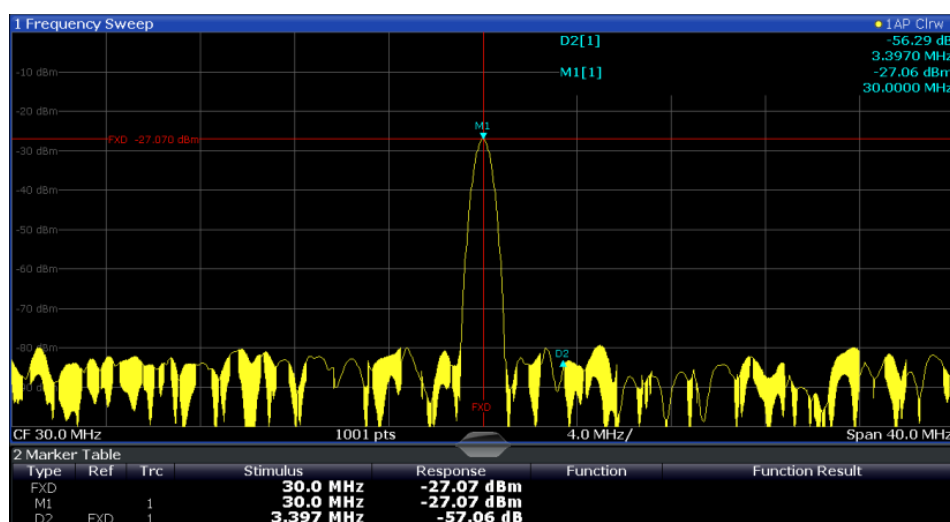
`CALCulate<n>:MARKer<m>:FUNCTION:NDBDown:FREQuency?` on page 853

`CALCulate<n>:MARKer<m>:FUNCTION:NDBDown:TIME?` on page 855

7.4.3.5 Reference Fixed

Instead of using a reference marker that may vary its position depending on the measurement results, a fixed reference marker can be defined for trace analysis. Once positioned, the reference marker does not move during subsequent sweeps unless you explicitly move it manually.

When you select this marker function, a vertical and a horizontal red display line are displayed, marked as "FXD". A normal marker is activated and set to the peak value and a delta marker to the next peak. The fixed reference marker is set to the position of the normal marker at the peak value. The delta marker refers to the fixed reference marker.



You can move the position of the fixed reference marker graphically by dragging the display lines, or numerically by entering values for the marker position and level.

For more information see [chapter 7.4.1.6, "Defining a Fixed Reference Marker"](#), on page 432.

7.4.3.6 Band Power Marker

For each of the 16 markers band power measurement can be activated. Band power measurement markers are configured in the "Band Power Config" dialog box, using the "Band Power" function.

The individual marker settings correspond to those defined in the "Marker" dialog box (see ["Individual Marker Setup"](#) on page 437). Any settings to the marker state or type

changed in the "Marker Function" dialog box are also changed in the "Marker" dialog box and vice versa.

To display the "Band Power Config" dialog box, do one of the following:

- Press the MKR FUNC key, then select the "Select Marker Function" softkey. Then select the "Band Power" button. Select the "Band Power Config" softkey.
- In the "Overview", select "Analysis", and switch to the vertical "Marker Function Config" tab. Then select the "Band Power" button. Select "Band Power Config".



For more information see [chapter 7.4.1.10, "Measuring the Power in a Channel \(Band\)"](#), on page 435.

Band Power Measurement State	457
Span	458
Power Mode	458
Switching All Band Power Measurements Off	458

Band Power Measurement State

Activates or deactivates band power measurement for the marker in the diagram.

Band power markers are only available for standard frequency measurements (not zero span) in the Spectrum application.

If activated, the markers display the power or density measured in the band around the current marker position.

For details see [chapter 7.4.1.10, "Measuring the Power in a Channel \(Band\)"](#), on page 435.

Remote command:

`CALCulate<n>:MARKer<m>:FUNction:BPowEr[:STATe]` on page 851

Span

Defines the span (band) around the marker for which the power is measured. The span is indicated by lines in the diagram.

Remote command:

`CALCulate<n>:MARKer<m>:FUNction:BPowEr:SPAN` on page 851

Power Mode

Defines the mode of the power measurement result.

"Power" The result is an absolute power level displayed in dBm.

"Density" The result is a power level in relation to the bandwidth, displayed in dBm/Hz.

Remote command:

`CALCulate<n>:MARKer<m>:FUNction:BPowEr:MODE` on page 850

Switching All Band Power Measurements Off

Deactivates band power measurement for all markers.

Remote command:

`CALCulate<n>:MARKer<m>:FUNction:BPowEr[:STATe]` on page 851

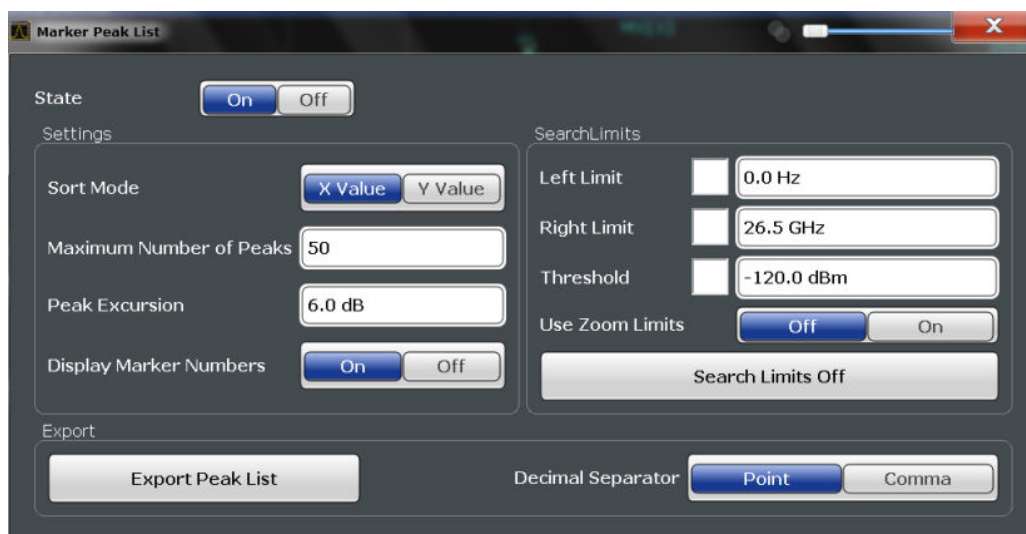
7.4.3.7 Marker Peak List Configuration

The marker peak list provides an overview of all marker peaks in the measurement. You can define search and sort criteria to influence the results of the analysis. The general marker search settings also apply to the marker peak list.

For more information see [chapter 7.4.1.4, "Searching for Signal Peaks"](#), on page 430 and ["Marker Search Settings"](#) on page 442.

To display the "Marker Peak List" dialog, do one of the following:

- Press the MKR FUNC key, then select the "Marker Peak List" softkey.
- In the "Overview", select "Analysis", and switch to the vertical "Peak List" tab.



Peak List State..... 459
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 Peak Excursion..... 459
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 Exporting the Peak List..... 460

Peak List State

Activates/deactivates the marker peak list. If activated, the peak list is displayed and the peaks are indicated in the trace display.

For each listed peak the frequency/time ("X-value") and level ("Y-value") values are given.

Remote command:

`CALCulate<n>:MARKer<m>:FUNction:FPEaks:STATe` on page 847

Sort Mode

Defines whether the peak list is sorted according to the x-values or y-values. In either case the values are sorted in ascending order.

Remote command:

`CALCulate<n>:MARKer<m>:FUNction:FPEaks:SORT` on page 846

Maximum Number of Peaks

Defines the maximum number of peaks to be determined and displayed.

Remote command:

`CALCulate<n>:MARKer<m>:FUNction:FPEaks:LIST:SIZE` on page 846

Peak Excursion

Defines the minimum level value by which a signal must rise or fall so that it will be identified as a maximum or a minimum by the search functions.

Entries from 0 dB to 80 dB are allowed; the resolution is 0.1 dB. The default setting for the peak excursion is 6 dB.

For more information see [chapter 7.4.1.4, "Searching for Signal Peaks"](#), on page 430.

Remote command:

[CALCulate<n>:MARKer<m>:PEXCursion](#) on page 825

Displaying Marker Numbers

By default, the marker numbers are indicated in the diagram so you can find the peaks from the list. However, for large numbers of peaks the marker numbers may decrease readability; in this case, deactivate the marker number display.

Remote command:

[CALCulate<n>:MARKer<m>:FUNCTION:FPEaks:ANNOtation:LABel\[:STATe\]](#) on page 845

Exporting the Peak List

The peak list can be exported to an ASCII file (.DAT) for analysis in an external application.

Remote command:

[MMEMory:STORe<n>:PEAK](#) on page 903

[FORMat:DEXPort:DSEParator](#) on page 881

7.4.3.8 Deactivating All Marker Functions

All special marker functions can be deactivated in one step.

Use the "All Functions Off" button in the "Marker Functions" dialog box.

7.4.4 How to Work With Markers

The following step-by-step instructions demonstrate in detail how to work with markers.

- [How to Analyze a Signal Point in Detail](#)..... 460
- [How to Use a Fixed Reference Marker](#)..... 461

7.4.4.1 How to Analyze a Signal Point in Detail



Step-by-step instructions on working with markers are provided here. For details on individual functions and settings see [chapter 7.4.2.1, "Marker Settings"](#), on page 436.

The remote commands required to perform these tasks are described in [chapter 11.8.3, "Working with Markers"](#), on page 819.

When you need to analyze a characteristic point in the signal in more detail, the following procedure can be helpful:

1. Perform a peak search to determine the characteristic point roughly by pressing the PEAK SEARCH key.

2. If the required signal point is not the maximum, continue the peak search to one of the subsequent maxima or minima:
 - a) Press the MKR -> key.
 - b) Select the "Next Peak" or "Next Min" key.
 - c) If necessary, change the search settings by selecting the "Search Config" softkey.
3. Center the display around the determined signal point by setting the marker value to the center frequency. Select the "Center = Mkr Freq" softkey.
4. Determine the precise frequency of the signal point:
 - a) Select the "Select Marker Function" softkey.
 - b) Select the "Signal Count" button.
 - c) Select the "Signal Count Resolution" softkey.
 - d) Select the resolution depending on how precise the result needs to be.

7.4.4.2 How to Use a Fixed Reference Marker

By default, delta markers refer to marker 1. However, they can also refer to a fixed reference marker.

How to Define and Move a Fixed Reference Marker

1. To display a fixed reference marker, do one of the following:
 - Press the MKR FUNC key, then select the "Reference Fixed" marker function.
 - In the "Marker" dialog box, in the "Reference Fixed" area of the "Marker Config" tab, set the "State" to "On".

A vertical and a horizontal red display line are displayed, marked as "FXD". The normal marker 1 is activated and set to the peak value of the trace assigned to marker 1, and a delta marker to the next peak. The fixed reference marker is set to the position of marker 1 at the peak value.

2. To move the fixed reference marker, do one of the following:
 - Change the "Level" and "Frequency" of the reference point in the "Marker Config" tab of the "Marker" dialog box, . By default, the current peak value of trace 1 is set.
 - Set the fixed reference marker to the current peak value by selecting the "Peak Search" button in the "Marker Config" tab of the "Marker" dialog box.
 - Move the "FXD" display lines that define the position of the fixed reference marker by dragging them on the screen.

How to Assign a Fixed Reference Marker to Delta Markers

1. In the "Marker" dialog box, select the horizontal "Markers" tab.

- For the active delta marker that is to refer to the fixed reference marker, select "FXD" from the "Ref. Marker" list.

The delta marker indicates the offset of the current trace value at the marker position from the fixed reference value.

7.4.5 Measurement Example: Measuring Harmonics Using Marker Functions

This measurement example describes how to measure harmonics using the provided marker functions. Note that this task can be performed much simpler using the Harmonic Distortion measurement (see [chapter 5.10, "Harmonic Distortion Measurement"](#), on page 271).

Signal generator settings (e.g. R&S FPS SMW):

Frequency:	128 MHz
Level:	- 25 dBm

Procedure:

- Preset the R&S FPS.
- Set the center frequency to *128 MHz*.
- Set the span to *100 kHz*.
The R&S FPS displays the reference signal with a span of 100 kHz and resolution bandwidth of 1 kHz.
- Switch on the marker by pressing the MKR key.
The marker is positioned on the trace maximum.
- Set the measured signal frequency and the measured level as reference values:
 - Press the MKR FUNC key
 - Press the "Reference Fixed" softkey.

The position of the marker becomes the reference point. The reference point level is indicated by a horizontal line, the reference point frequency with a vertical line. At the same time, the delta marker 2 is switched on.

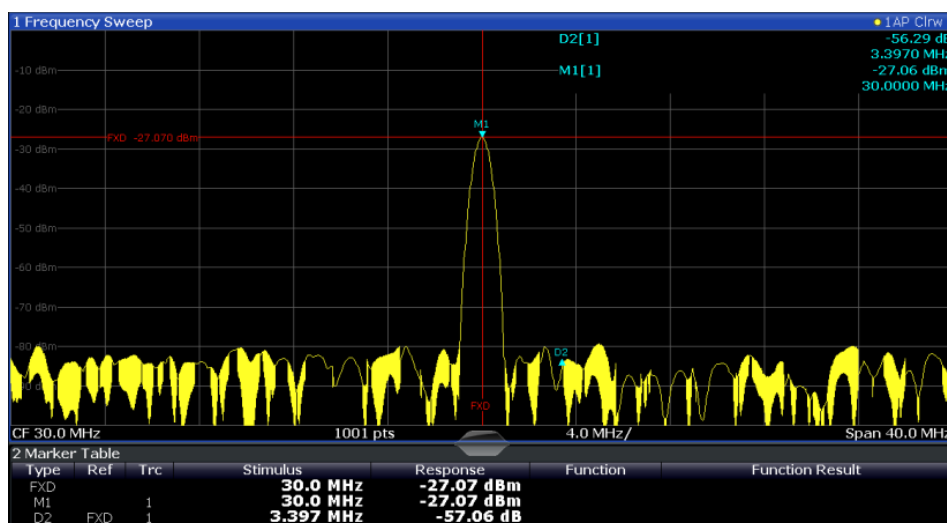


Fig. 7-16: Fundamental wave and the frequency and level reference point

6. Make the step size for the center frequency correspond to the signal frequency: in the "Frequency" configuration dialog box, select "Center Frequency Stepsize = Marker".

The step size for the center frequency is now equal to the marker frequency.

7. Move the center frequency to the 2nd harmonic of the signal by pressing the UP (↑) key.

The center frequency is set to the 2nd harmonic.

8. Place the delta marker on the 2nd harmonic: in the "Marker To" menu, select the "Peak" softkey.

The delta marker moves to the maximum of the 2nd harmonic. The displayed level result is relative to the reference point level (= fundamental wave level).

The other harmonics are measured by repeating steps [step 7](#) and [step 8](#), with the center frequency being incremented or decremented in steps of 128 MHz using the UP or DOWN keys.

7.5 Display and Limit Lines

Display and limit lines help you analyze a measurement trace.

- [Basics on Display Lines](#)..... 464
- [Basics on Limit Lines](#)..... 464
- [Settings and Functions for Display and Limit Lines](#) 468
- [How to Work with Display and Limit Lines](#)..... 474

7.5.1 Basics on Display Lines

Display lines help you analyze a trace – as do markers. The function of a display line is comparable to that of a ruler that can be shifted on the trace in order to mark absolute values. They are used exclusively to visually mark relevant frequencies or points in time (zero span), as well as constant level values. It is not possible to check automatically whether the points are below or above the marked level values - use limit lines for that task (see [chapter 7.5.2, "Basics on Limit Lines"](#), on page 464).

Two different types of display lines are provided:

- Two horizontal level lines for marking levels – Display Line 1 and 2
The level lines are continuous horizontal lines across the entire width of a diagram and can be shifted in y direction.
- Two vertical frequency or time lines for marking frequencies or points in time – Frequency/Time Line 1 and 2
The frequency or time lines are continuous vertical lines across the entire height of the diagram and can be shifted in x direction.

Labels

Each line is identified by one of the following abbreviations in the diagrams:

- D1: Display Line 1
- D2: Display Line 2
- F1: Frequency Line 1
- F2: Frequency Line 2
- T1: Time Line 1
- T2: Time Line 2

7.5.2 Basics on Limit Lines

Limit lines are used to define amplitude curves or spectral distribution boundaries in the result diagram which are not to be exceeded. They indicate, for example, the upper limits for interference radiation or spurious waves which are allowed from a device under test (DUT). When transmitting information in TDMA systems (e.g. GSM), the amplitude of the bursts in a time slot must adhere to a curve that falls within a specified tolerance band. The lower and upper limits may each be specified by a limit line. Then, the amplitude curve can be controlled either visually or automatically for any violations of the upper or lower limits (GO/NOGO test).

The R&S FPS supports limit lines with a maximum of 200 data points. Eight of the limit lines stored in the instrument can be activated simultaneously. The number of limit lines stored in the instrument is only limited by the capacity of the storage device used.

Compatibility

Limit lines are compatible with the current measurement settings, if the following applies:

- The x unit of the limit line has to be identical to the current setting.

- The y unit of the limit line has to be identical to the current setting with the exception of dB based units; all dB based units are compatible with each other.

Validity

Only limit lines that fulfill the following conditions can be activated:

- Each limit line must consist of a minimum of 2 and a maximum of 200 data points.
- The frequencies/times for each data point must be defined in ascending order; however, for any single frequency or time, two data points may be entered (to define a vertical segment of a limit line).
- Gaps in frequency or time are not allowed. If gaps are desired, two separate limit lines must be defined and then both enabled.
- The entered frequencies or times need not necessarily be selectable in R&S FPS. A limit line may also exceed the specified frequency or time range. The minimum frequency for a data point is -200 GHz, the maximum frequency is 200 GHz. For the time range representation, negative times may also be entered. The allowed range is -1000 s to +1000 s.

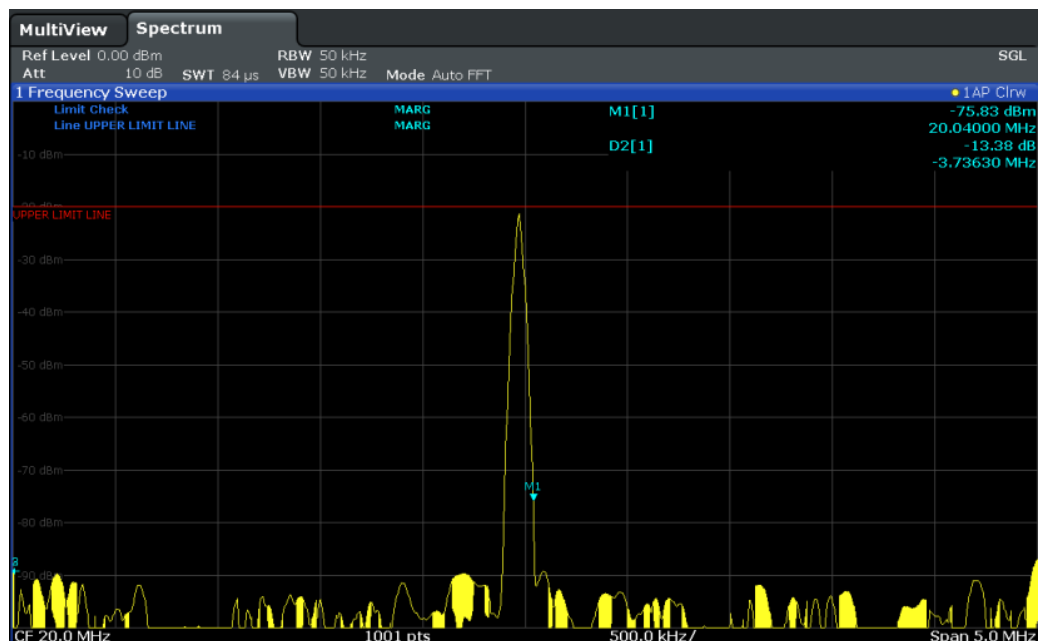


Fig. 7-17: Example for an upper limit line

Limits and Margins

Limit lines define strict values that must not be exceeded by the measured signal. A **margin** is similar to a limit, but less strict and it still belongs to the valid data range. It can be used as a warning that the limit is almost reached. The margin is not indicated by a separate line in the display, but if it is violated, a warning is displayed. Margins are defined as lines with a fixed distance to the limit line.

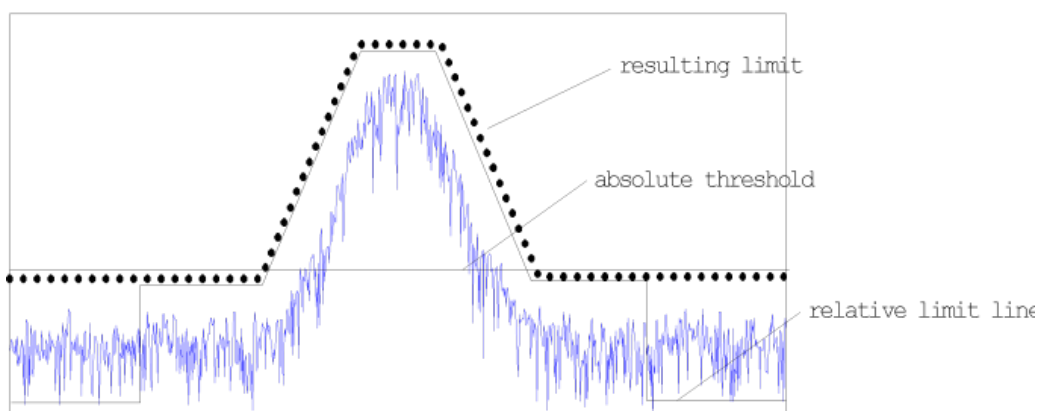
To check the signal for maximum levels you must define an **upper limit**, whereas to check the signal for minimum levels you must define a **lower limit**.

Limits can be defined relative to the reference level, the beginning of the time scale, or the center frequency, or as absolute values.

Relative scaling is suitable, for example, if masks for bursts are to be defined in zero span, or if masks for modulated signals are required in the frequency domain.

Thresholds

If the y-axis for the limit line data points uses relative scaling, an additional absolute **threshold** can be defined for the limit check. In this case, both the threshold value and the relative limit line must be exceeded before a violation occurs.



Offsets and Shifting

A configured limit line can easily be moved vertically or horizontally. Two different methods to do so are available:

- An **offset** moves the entire line in the diagram without editing the configured values or positions of the individual data points. This option is only available if relative scaling is used. Thus, a new limit line can be easily generated based upon an existing limit line which has been shifted horizontally or vertically.
- Defining a **shift** width for the values or position of the individual data points changes the line configuration, thus changing the position of the line in the diagram.

Limit Check Results

A limit check is automatically performed as soon as any of the limit lines is activated ("Visibility" setting). Only the specified "Traces to be Checked" are compared with the active limit lines. The status of the limit check for each limit line is indicated in the diagram. If a violation occurs, the limit check status is set to "MARG" for a margin violation, or to "FAIL" for a limit violation.

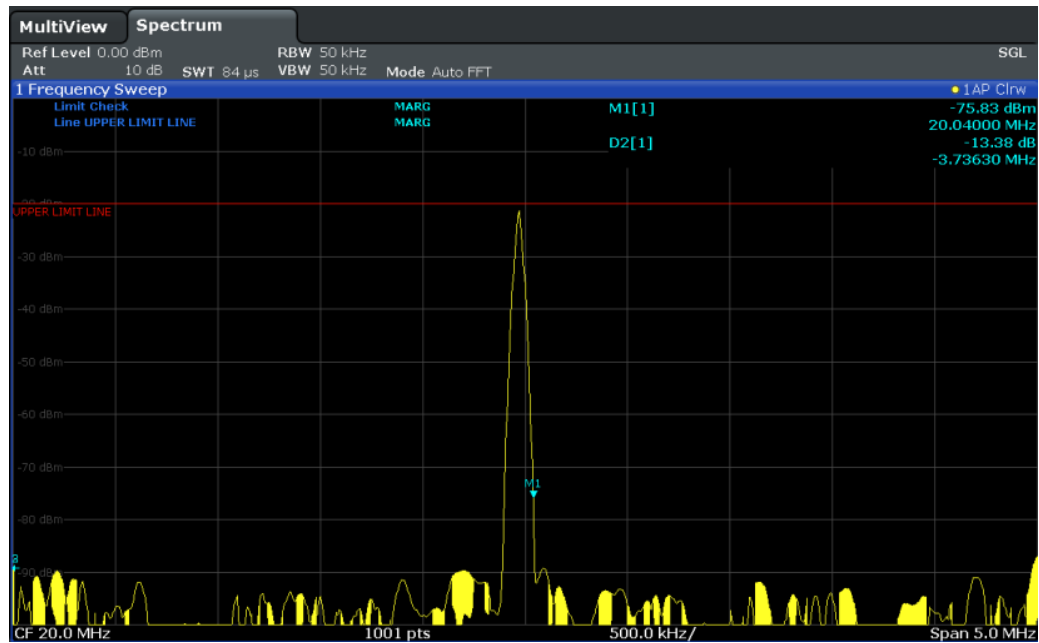


Fig. 7-18: Margin violation for limit check

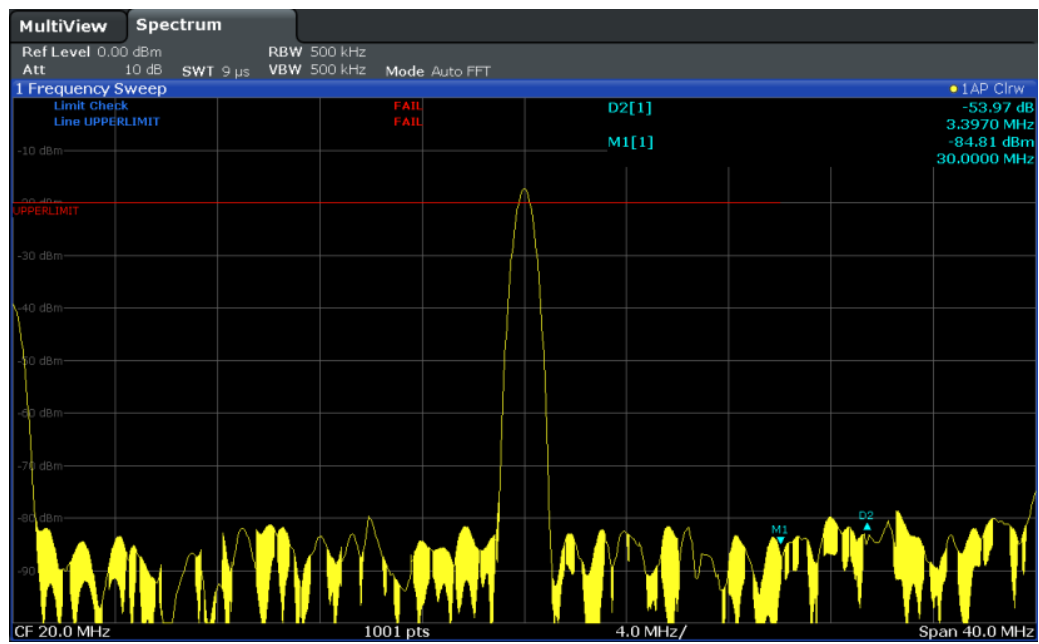


Fig. 7-19: Limit violation for limit check

7.5.3 Settings and Functions for Display and Limit Lines

For remote operation, see [chapter 11.8.4, "Configuring Display and Limit Lines"](#), on page 864.

- [Display Line Settings](#).....468
- [Limit Line Settings and Functions](#).....468

7.5.3.1 Display Line Settings

Two vertical and two horizontal lines can be defined in the display.



- [Vertical Line 1/2](#).....468
- [Horizontal Line 1/2](#).....468

Vertical Line 1/2

Activates a vertical display line (F1/F2 or T1/T2) in the diagram at the specified frequency or point in time, depending on the frequency span.

Remote command:

- [CALCulate<n>:FLINE<k>](#) on page 865
- [CALCulate<n>:FLINE<k>](#) on page 865
- [CALCulate<n>:TLINE<k>](#) on page 866
- [CALCulate<n>:TLINE<k>](#) on page 866

Horizontal Line 1/2

Activates a horizontal display line (D1/D2) in the diagram at the specified level.

Remote command:

- [CALCulate<n>:DLINE<k>](#) on page 865
- [CALCulate<n>:DLINE<k>](#) on page 865

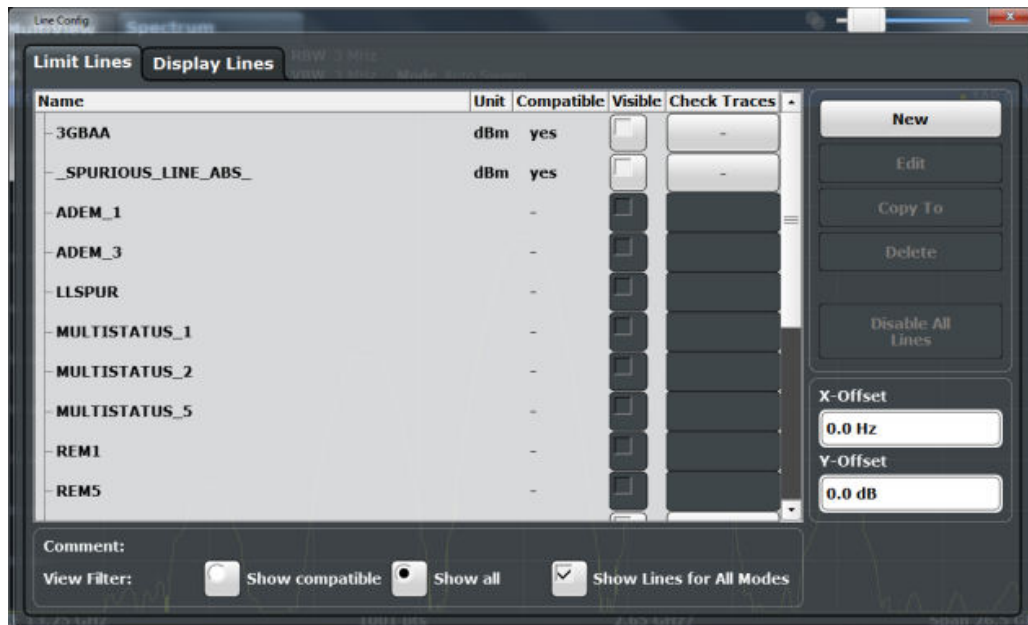
7.5.3.2 Limit Line Settings and Functions

Up to 8 limit lines can be displayed simultaneously in the R&S FPS. Many more can be stored on the instrument.

- [Limit Line Management](#).....469
- [Limit Line Details](#).....471

Limit Line Management

Limit lines are managed in the "Line Config" dialog box which is displayed when you press the LINES key and then "Lines Config" softkey.



For the limit line overview, the R&S FPS searches for all stored limit lines with the file extension .LIN in the limits subfolder of the main installation folder. The overview allows you to determine which limit lines are available and can be used for the current measurement.

For details on settings for individual lines see ["Limit Line Details"](#) on page 471.

For more basic information on limit lines see [chapter 7.5.2, "Basics on Limit Lines"](#), on page 464.

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Name

The name of the stored limit line.

Unit

The unit in which the y-values of the data points of the limit line are defined.

Compatibility

Indicates whether the limit line definition is compatible with the current measurement settings.

For more information on which conditions a limit line must fulfill to be compatible, see "[Compatibility](#)" on page 464.

Visibility

Displays or hides the limit line in the diagram. Up to 8 limit lines can be visible at the same time. Inactive limit lines can also be displayed in the diagram.

Remote command:

[CALCulate<n>:LIMit<k>:LOWer:STATe](#) on page 871

[CALCulate<n>:LIMit<k>:UPPer:STATe](#) on page 874

[CALCulate<n>:LIMit<k>:ACTive?](#) on page 875

Traces to be Checked

Defines which traces are automatically checked for conformance with the limit lines. As soon as a trace to be checked is defined, the assigned limit line is active. One limit line can be activated for several traces simultaneously. If any of the "Traces to be Checked" violate any of the active limit lines, a message is indicated in the diagram.

Remote command:

[CALCulate<n>:LIMit<k>:TRACe<t>:CHECK](#) on page 876

Comment

An optional description of the limit line.

Included Lines in Overview (View Filter)

Defines which of the stored lines are included in the overview.

- | | |
|-------------------|--|
| "Show compatible" | Only compatible lines
Whether a line is compatible or not is indicated in the Compatibility setting. |
| "Show all" | All stored limit lines with the file extension <code>.LIN</code> in the <code>limits</code> subfolder of the main installation folder (if not restricted by "Show lines for all modes" setting). |

Show lines for all modes ← Included Lines in Overview (View Filter)

If activated (default), limit lines from all applications are displayed. Otherwise, only lines that were created in the Spectrum application are displayed.

Note that limit lines from some applications may include additional properties that are lost when the limit lines are edited in the Spectrum application. In this case a warning is displayed when you try to store the limit line.

X-Offset

Shifts a limit line that has been specified for relative frequencies or times (x-axis) horizontally.

This setting does not have any effect on limit lines that are defined by absolute values for the x-axis.

Remote command:

[CALCulate<n>:LIMit<k>:CONTRol:OFFSet](#) on page 868

Y-Offset

Shifts a limit line that has relative values for the y-axis (levels or linear units such as volt) vertically.

This setting does not have any effect on limit lines that are defined by absolute values for the y-axis.

Remote command:

[CALCulate<n>:LIMit<k>:LOWer:OFFSet](#) on page 870

[CALCulate<n>:LIMit<k>:UPPer:OFFSet](#) on page 873

Create New Line

Creates a new limit line.

Edit Line

Edit an existing limit line configuration.

Copy Line

Copy the selected limit line configuration to create a new line.

Remote command:

[CALCulate<n>:LIMit<k>:COPY](#) on page 875

Delete Line

Delete the selected limit line configuration.

Remote command:

[CALCulate<n>:LIMit<k>:DELeTe](#) on page 875

Disable All Lines

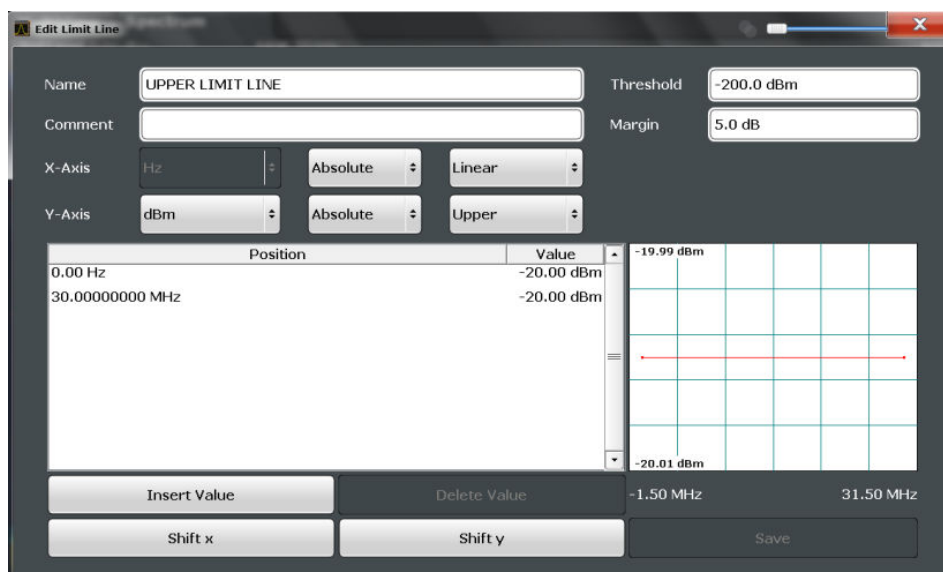
Disable all limit lines in one step.

Remote command:

[CALCulate<n>:LIMit<k>:STATe](#) on page 876

Limit Line Details

Limit lines details are configured in the "Edit Line" dialog box which is displayed when you select the "New", "Edit" or "Copy To" buttons in the "Line Config" dialog box.



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Name

Defines the limit line name. All names must be compatible with Windows conventions for file names. The limit line data is stored under this name (with a .LIN extension).

Remote command:

CALCulate<n>:LIMit<k>:NAME on page 872

Comment

Defines an optional comment for the limit line. The text may contain up to 40 characters.

Remote command:

CALCulate<n>:LIMit<k>:COMMeNt on page 867

Threshold

Defines an absolute threshold value (only for relative scaling of the y-axis).

For details on thresholds see "Thresholds" on page 466.

Remote command:

CALCulate<n>:LIMit<k>:LOWer:THReshold on page 871

CALCulate<n>:LIMit<k>:UPPer:THReshold on page 874

Margin

Defines a margin for the limit line. The default setting is 0 dB (i.e. no margin).

For details on margins see "[Limits and Margins](#)" on page 465.

Remote command:

[CALCulate<n>:LIMit<k>:LOWer:MARGin](#) on page 870

[CALCulate<n>:LIMit<k>:UPPer:MARGin](#) on page 872

X-Axis

Describes the horizontal axis on which the data points of the limit line are defined.

Includes the following settings:

- Domain:
 - "Hz": for frequency domain
 - "s": for time domain
- Scaling mode: absolute or relative (Hz/s/%) values
For relative values, the frequencies are referred to the currently set center frequency. In the zero span mode, the left boundary of the diagram is used as the reference.
- Scaling: linear or logarithmic

Remote command:

[CALCulate<n>:LIMit<k>:LOWer:SPACing](#) on page 871

[CALCulate<n>:LIMit<k>:UPPer:SPACing](#) on page 874

[CALCulate<n>:LIMit<k>:LOWer:MODE](#) on page 870

[CALCulate<n>:LIMit<k>:UPPer:MODE](#) on page 873

[CALCulate<n>:LIMit<k>:CONTrol:DOMain](#) on page 868

Y-Axis

Describes the vertical axis on which the data points of the limit line are defined.

Includes the following settings:

- Level unit
- Scaling mode: absolute or relative (dB/%) values
Relative limit values refer to the reference level.
- Limit type: upper or lower limit; values must stay above the lower limit and below the upper limit to pass the limit check

Remote command:

[CALCulate<n>:LIMit<k>:UNIT](#) on page 872

[CALCulate<n>:LIMit<k>:LOWer:SPACing](#) on page 871

[CALCulate<n>:LIMit<k>:UPPer:SPACing](#) on page 874

Data points

Each limit line is defined by a minimum of 2 and a maximum of 200 data points. Each data point is defined by its position (x-axis) and value (y-value). Data points must be defined in ascending order. The same position can have two different values.

Remote command:

[CALCulate<n>:LIMit<k>:CONTrol\[:DATA\]](#) on page 867

[CALCulate<n>:LIMit<k>:LOWer\[:DATA\]](#) on page 869

[CALCulate<n>:LIMit<k>:UPPer\[:DATA\]](#) on page 872

Insert Value

Inserts a data point in the limit line above the selected one in the "Edit Limit Line" dialog box.

Delete Value

Deletes the selected data point in the "Edit Limit Line" dialog box.

Shift x

Shifts the x-value of each data point horizontally by the defined shift width (as opposed to an additive offset defined for the entire limit line, see "X-Offset" on page 470).

Remote command:

`CALCulate<n>:LIMit<k>:CONTRol:SHIFt` on page 869

Shift y

Shifts the y-value of each data point vertically by the defined shift width (as opposed to an additive offset defined for the entire limit line, see "Y-Offset" on page 471).

Remote command:

`CALCulate<n>:LIMit<k>:LOWer:SHIFt` on page 870

`CALCulate<n>:LIMit<k>:UPPer:SHIFt` on page 873

Save

Saves the currently edited limit line under the name defined in the "Name" field.

7.5.4 How to Work with Display and Limit Lines

Step-by-step instructions on configuring display and limit lines are provided here. For details on individual functions and settings see [chapter 7.5.3, "Settings and Functions for Display and Limit Lines"](#), on page 468.

The remote commands required to perform these tasks are described in [chapter 11.8.4, "Configuring Display and Limit Lines"](#), on page 864.

7.5.4.1 Defining Display Lines

1. Display lines are configured in the "Lines Config" dialog box. To display this dialog box, press the LINES key and then "Lines Config".
2. Select the "Display Lines" tab.
3. To define a vertical line, select "Vertical Line 1" or 2 and enter the x-value at which the line is to be displayed.
To define a horizontal line, select "Horizontal Line 1" or 2 and enter the y-value at which the line is to be displayed.

7.5.4.2 Defining Limit Lines

Limit lines are configured in the "Lines Config" dialog box. To display this dialog box, do one of the following:

- Press the LINES key and then the "Lines Config" softkey, then select the "Lines Config" tab.
- In the "Overview", select "Analysis" and then the vertical "Limit Lines Config" tab.



Limit lines for spurious and SEM measurements

Note that for spurious and SEM measurements, special limit lines can be defined for each frequency range, see [chapter 5.6.4.2, "Limit Lines in SEM Measurements"](#), on page 203 and [chapter 5.7.3.2, "Limit Lines in Spurious Measurements"](#), on page 242. It is strongly recommended that you define limits only via the "Sweep list" dialog for these measurements, not using the LINES key.

Any changes to the special limit lines are automatically overwritten when the sweep list settings are changed.

The following tasks are described here:

- ["How to find compatible limit lines"](#) on page 475
- ["How to activate and deactivate a limit check"](#) on page 475
- ["How to edit existing limit lines"](#) on page 476
- ["How to copy an existing limit line"](#) on page 476
- ["How to delete an existing limit line"](#) on page 476
- ["How to configure a new limit line"](#) on page 476
- ["How to move the limit line vertically or horizontally"](#) on page 477

How to find compatible limit lines

- ▶ In the "Line Config" dialog box, select the "View filter" option: "Show compatible".
All stored limit lines with the file extension `.LIN` in the `limits` subfolder of the main installation folder of the instrument that are compatible to the current measurement settings are displayed in the overview.

How to activate and deactivate a limit check

A limit check is automatically performed as soon as any of the limit lines is activated.

1. To activate a limit check:
Select the "Check Traces" setting for a limit line in the overview and select the trace numbers to be included in the limit check. One limit line can be assigned to several traces.
The specified traces to be checked are compared with the active limit lines. The status of the limit check is indicated in the diagram.
2. To deactivate a limit line, deactivate all "Traces to check" for it.
To deactivate all limit lines at once, select the "Disable All Lines" button.

The limit checks for the deactivated limit lines are stopped and the results are removed from the display.

How to edit existing limit lines

Existing limit line configurations can be edited.

1. In the "Line Config" dialog box, select the limit line.
2. Select the "Edit" button.
3. Edit the line configuration as described in ["How to configure a new limit line"](#) on page 476.
4. Save the new configuration by selecting the "Save" button.

If the limit line is active, the edited limit line is displayed in the diagram.

How to copy an existing limit line

1. In the "Line Config" dialog box, select the limit line.
2. Select the "Copy To" button.
3. Define a new name to create a new limit with the same configuration as the source line.
4. Edit the line configuration as described in ["How to configure a new limit line"](#) on page 476.
5. Save the new configuration by selecting the "Save" button.

The new limit line is displayed in the overview and can be activated.

How to delete an existing limit line

1. In the "Line Config" dialog box, select the limit line.
2. Select the "Delete" button.
3. Confirm the message.

The limit line and the results of the limit check are deleted.

How to configure a new limit line

1. In the "Line Config" dialog box, select the "New" button.

The "Edit Limit Line" dialog box is displayed. The current line configuration is displayed in the preview area of the dialog box. The preview is updated after each change to the configuration.

2. Define a "Name" and, optionally, a "Comment" for the new limit line.
3. Define the x-axis configuration:
 - Time domain or frequency domain
 - Absolute or relative limits
 - Linear or logarithmic scaling

4. Define the y-axis configuration:
 - Level unit
 - Absolute or relative limits
 - Upper or lower limit line
5. Define the data points: minimum 2, maximum 200:
 - a) Select "Insert Value".
 - b) Define the x-value ("Position") and y-value ("Value") of the first data point.
 - c) Select "Insert Value" again and define the second data point.
 - d) Repeat this to insert all other data points.
 - To insert a data point before an existing one, select the data point and then "Insert Value".
 - To insert a new data point at the end of the list, move the focus to the line after the last entry and then select "Insert Value".
 - To delete a data point, select the entry and then "Delete Value".
6. Check the current line configuration in the preview area of the dialog box. If necessary, correct individual data points or add or delete some.

If necessary, shift the entire line vertically or horizontally by selecting the "Shift x" or "Shift y" button and defining the shift width.
7. Optionally, define a "Margin" at a fixed distance to the limit line.

The margin must be within the valid value range and is not displayed in the diagram or preview area.
8. Optionally, if the y-axis uses relative scaling, define an absolute "Threshold" as an additional criteria for a violation.
9. Save the new configuration by selecting the "Save" button.

The new limit line is displayed in the overview and can be activated.

How to move the limit line vertically or horizontally

A configured limit line can easily be moved vertically or horizontally. Thus, a new limit line can be easily generated based upon an existing limit line which has been shifted horizontally.

1. In the "Line Config" dialog box, select the limit line.
2. To shift the complete limit line parallel in the horizontal direction, select the "X-Offset" button and enter an offset value.

To shift the complete limit line parallel in the vertical direction, select the "Y-Offset" button and enter an offset value.
3. To shift the individual data points of a limit line by a fixed value (all at once):
 - a) Select the "Edit" button.
 - b) In the "Edit Limit Line" dialog box, select the "Shift x" or "Shift y" button and define the shift width.
 - c) Save the shifted data points by selecting the "Save" button.

If activated, the limit line is shifted in the diagram.

8 Data Management

The R&S FPS allows you to store and load instrument settings, as well as import and export measurement data for analysis at a later time. Finally, you can store or print the measurement results displayed on the screen.

General storage and import/export functions are available via the toolbar. Some special storage functions are (also) available via softkeys or dialog boxes in the corresponding menus, e.g. trace data or marker peak lists.

- [Restoring the Default Instrument Configuration \(Preset\)](#)..... 478
- [Protecting Data Using the Secure User Mode](#)..... 480
- [Storing and Recalling Instrument Settings and Measurement Data](#)..... 482
- [Importing and Exporting Measurement Results for Evaluation](#)..... 493
- [Creating Screenshots of Current Measurement Results and Settings](#)..... 500

8.1 Restoring the Default Instrument Configuration (Preset)

When delivered, the R&S FPS has a default configuration. You can restore this defined initial state at any time as a known starting point for measurements. This is often recommendable as a first step in troubleshooting when unusual measurement results arise.

To restore the default instrument configuration for all channels at once

- ▶ Press the PRESET key.

Alternatively to the factory default settings, you can define user-specific recall settings to be restored after a preset or reboot, see "[To recall settings automatically after preset or reboot](#)" on page 493.



After you use the PRESET function, the history of previous actions is deleted, i.e. any actions performed previously cannot be undone or redone using the UNDO/REDO keys.

Remote command:

*RST or SYSTem:PRESet

To restore the default configuration for a single channel

The default measurement settings can also be reset for an individual channel only, rather than resetting the entire instrument.

- ▶ In the "Overview", select the "Preset Channel" button.

The factory default settings are restored to the current channel. Note that a user-defined recall settings file is **NOT** restored.

Remote command:

`SYSTem:PRESet:CHANnel[:EXECute]` on page 895

8.1.1 Factory Default Configuration

The factory default configuration is selected such that the RF input is always protected against overload, provided that the applied signal levels are in the allowed range for the instrument.

Table 8-1: Factory default configuration

Parameter	Setting
mode	Spectrum
sweep mode	auto
center frequency	$f_{\max}/2$
center frequency step size	0.1 * span
span	maximum possible (depends on instrument model)
RF attenuation	10 dB
reference level	0 dBm
level range	100 dB log
level unit	dBm
sweep time	auto
resolution bandwidth	auto (3 MHz)
video bandwidth	auto (3 MHz)
FFT filters	off
span/RBW	100
RBW/VBW	1
sweep	single
trigger	free run
trace mode	1: clr write; 2/3/4/5/6: blank
detector	auto peak
frequency offset	0 Hz
reference level offset	0 dB
reference level position	100 %
grid	abs
cal correction	on

Parameter	Setting
noise source	off
input	RF

8.2 Protecting Data Using the Secure User Mode

During normal operation, the R&S FPS uses a solid-state drive to store its operating system, instrument firmware, instrument self-alignment data, and any user data created during operation. If necessary, the solid-state drive can be removed from the R&S FPS and locked in a secure place to protect any classified data it may contain.

Redirecting storage to volatile memory

Alternatively, to avoid storing any sensitive data on the R&S FPS permanently, the *secure user mode* was introduced (option R&S FPS-K33). In secure user mode the instrument's solid-state drive is write-protected so that no information can be written to memory permanently. Data that the R&S FPS normally stores on the solid-state drive is redirected to volatile memory instead, which remains available only until the instrument is switched off. This data includes:

- Windows 7 operating system files
- Firmware shutdown files containing information on last instrument state
- Self-alignment data
- General instrument settings such as the IP address
- Measurement settings
- User data created during operation (see also [table 8-2](#))
- Any data created by other applications installed on the R&S FPS, for example text editors (Notepad), the Clipboard, drawing tools etc.

Data that is stored in volatile memory can be accessed by the user just as in normal operation; however, when the instrument's power is switched off, all data in this memory is cleared. Thus, in secure user mode, the instrument always starts in a defined, fixed state when switched on.

In order to store data such as measurement results permanently, it must be stored to an external storage device, such as a memory stick.



Limited storage space

The volatile memory used to store data in secure user mode is restricted to 256 MB. Thus, a "Memory full" error may occur although the hard disk indicates that storage space is still available.

Storing required data permanently

Any data that is to be available for subsequent sessions with the R&S FPS, such as predefined instrument settings, transducer factors or self-alignment data, must be stored on the instrument permanently, *prior to activating the secure user mode*.



Self-alignment data

Note that self-alignment data becomes invalid with time and due to temperature changes. Therefore, to achieve optimal accuracy, it may be preferable to perform a new self-alignment at the start of each new session on the R&S FPS.

Restricted operation

Due to the fact that permanent storage is not possible, the following functions are not available in secure user mode:

- Firmware update
- Activating a new option key

Furthermore, since the "SecureUser" used in secure user mode does not have administrator rights, **administrative tasks** such as LAN configuration and some general instrument settings are not available. Refer to the description of the basic instrument setup (SETUP menu) to find out which functions are affected.



RemoteDesktop restricted for "SecureUser" by default

For security reasons, the "SecureUser" is not allowed Remote Desktop access to the R&S FPS by default. You must explicitly add the "SecureUser" to the Remote Desktop group (see [chapter 3.4.6.5, "How to Add or Remove Users to the Remote Desktop Users Group"](#), on page 67). If you do not allow this user RemoteDesktop access, the "SecureUser" will only be able to operate the R&S FPS using remote commands or via the miniature display.

Activating and deactivating secure user mode

Only a user with administrator rights can activate (and deactivate) the secure user mode. Once activated, a restart is required. The special user "SecureUser" is then logged on to the R&S FPS automatically (using the automatic login function, see ["The Automatic Login Function"](#) on page 25). While the secure user mode is active, a message is displayed in the status bar at the bottom of the screen, and in the miniature display "SecUsr" is displayed.

In order to deactivate the secure user mode, the "SecureUser" must log off and the "Instrument" user (administrator) must log on.



Switching users when using the automatic login function

In the "Start" menu, select the arrow next to the "Shut down" button and then "Log off".

The "Login" dialog box is displayed, in which you can enter the different user account name and password.

The secure user mode setting and automatic login is automatically deactivated when the "Instrument" user logs on. The "SecureUser" is no longer available.

For administrators ("Instrument" user), the secure user mode setting is available in the general system configuration settings (see [chapter 9.3.4.5, "General Configuration Settings"](#), on page 520).

Alternatively, you can activate or deactivate the secure user function via the miniature display (see ["Enable SecureUser / Disable SecureUser"](#) on page 43. In this case, you must enter the administrator ("Instrument" user) password.

Remote control

Initially after installation of the R&S FPS-K33 option, secure user mode must be enabled manually once before remote control is possible.

(See `SYSTEM:SECURITY[:STATE].`)

8.3 Storing and Recalling Instrument Settings and Measurement Data

Possibly you would like to restore or repeat a measurement you performed under specific conditions on the instrument. Or you want to evaluate imported data in another application on the R&S FPS and would like to restore the measurement settings applied during measurement. In these cases, you can store and recall instrument and measurement settings, and possibly other related measurement data.

Two different methods are available for managing instrument settings:

- Quick Save/Quick Recall - a defined set of instrument or channel settings are stored or recalled quickly in just one step
- Configurable Save/Recall - a user-defined set of instrument or channel settings are stored to a definable storage location



Restrictions when recalling measurement settings

When recalling a saved configuration file, the following restrictions apply:

- The frequency range defined in the configuration file must be supported by the R&S FPS on which the file is to be recalled.
 - Configuration files created on a R&S FPS with certain options in use will not work on an R&S FPS without these options
 - Files created with newer firmware versions may not work with a previous version
-



Saving instrument settings in secure user mode

Be sure to store instrument settings that you require beyond the current session before [Secure User Mode](#) is enabled; see [chapter 3.1.6, "Protecting Data Using the Secure User Mode"](#), on page 30.

Settings that are saved via QuickSave in secure user mode are only available during the current session. As soon as the power is switched off on the R&S FPS, the data is cleared.

- [Quick Save/Quick Recall](#).....483
- [Configurable Storage and Recall](#)..... 485
- [How to Save and Load Instrument Settings](#).....491

8.3.1 Quick Save/Quick Recall

The Quick Save and Quick Recall functions allow you to store instrument or channel settings very easily and quickly in one step. Up to 10 different sets of settings can be stored to or recalled from "save sets". Each save set is identified by its storage date and type (instrument or specific channel) in the display. The save sets are stored in the C:\r_s\instr\user\QuickSave directory, in files named QuickSave1.dfl to QuickSave10.dfl. The storage file names and locations cannot be changed.

During recall, save sets of type "Instrument" replace the settings of the entire instrument. All other save sets start a new measurement channel with the stored settings.



If a measurement channel with the same name as the channel to be restored is already active, the channel name for the new channel is extended by a consecutive number:



8.3.1.1 Quick Save / Quick Recall Settings

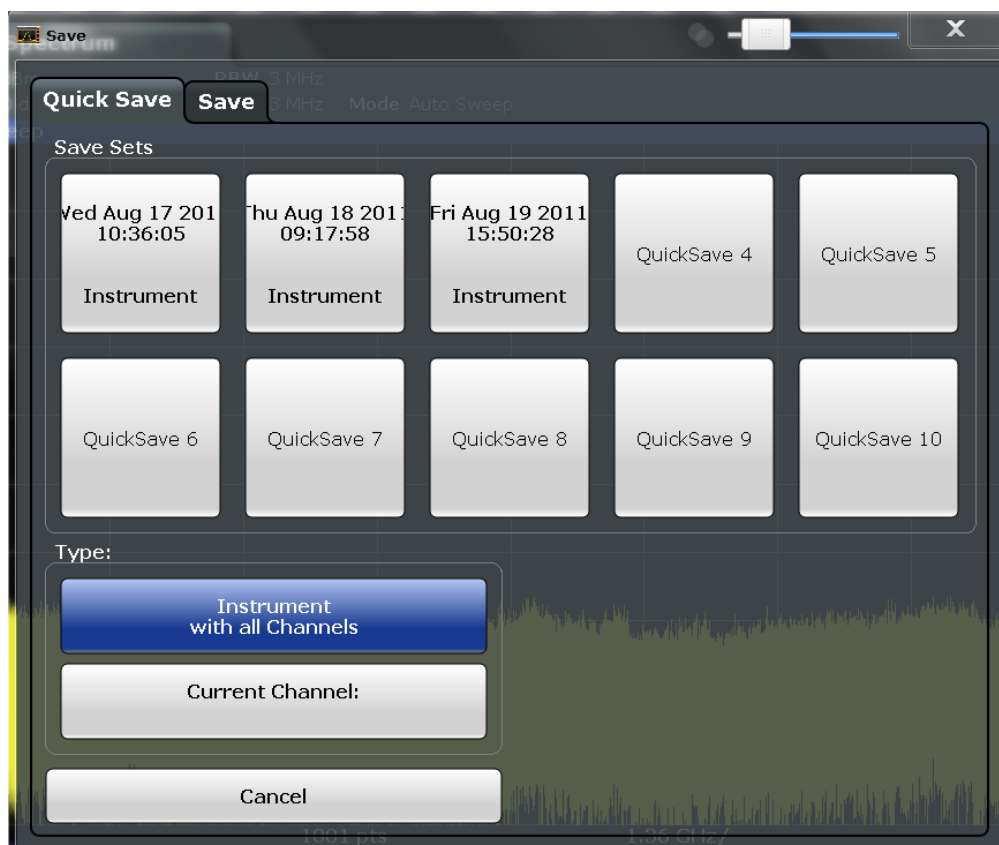


The "QuickSave" dialog box is displayed when you select the "Save" icon in the toolbar.



The "Quick Recall" dialog box is displayed when you select the "Open" icon in the toolbar, or select the "Quick Recall" tab in the "Recall" dialog box.

Both dialog boxes are very similar and closely related.



QuickSave 1 / ... / QuickSave 10.....	484
Storage Type (Save only).....	484
Recall.....	485
Cancel.....	485

QuickSave 1 / ... / QuickSave 10

Selects one of the save sets to store the current settings in or to be recalled. At the time of storage, the "QuickSave 1 / ... / QuickSave 10" placeholder is replaced by a label indicating the storage date and time and the storage type.

During recall, save sets of type "Instrument" replace the settings of the entire instrument. All other save sets start a new measurement channel with the stored settings.

Storage Type (Save only)

Defines which type of settings is to be stored in the save set.

"Instrument with all channels" The instrument settings for all currently active channels are stored.

"Current Channel" Only the instrument settings for the currently selected measurement channel are stored.

Recall

Restores the instrument settings as saved in the selected settings file. If the settings file contains settings for a specific channel only a new channel with the stored settings is activated, otherwise the entire instrument settings are loaded.

Note: After you use the "Recall" function, the history of previous actions is deleted, i.e. any actions performed previously cannot be undone or redone using the UNDO/REDO keys.

Note: If a measurement channel with the same name as the channel to be restored (in a new channel) is already active, the channel name for the new channel is extended by a consecutive number:



In remote commands, you must append this number to the channel name, as well.

Remote command:

[MMEMoRY:LOAD:STATe](#) on page 891

Cancel

Closes the dialog box without saving the settings.

8.3.2 Configurable Storage and Recall

The more sophisticated storage and recall functions allow you to define which settings are stored, and where the settings file is stored to. Any settings file can be selected for recall.

- [Stored Data Types](#)..... 485
- [Storage Location and File Name](#).....486
- [Save and Recall Dialog Boxes](#).....486
- [Startup Recall Settings](#).....489

8.3.2.1 Stored Data Types

The following types of data can be stored to and loaded from files via the "Save" dialog box on the R&S FPS:

Table 8-2: Items that can be stored to files

Item	Description
Current Settings	Current instrument and measurement settings
All Transducers	Transducer factors for all active transducers.
All Traces	All active traces;
All Limit Lines	All limit lines (Note: information on which limit lines are active is stored with the "Current Settings")
Spectrograms	Spectrogram trace data (only available if spectrogram display is currently active)

8.3.2.2 Storage Location and File Name

The data is stored on the internal flash disk or, if selected, on a memory stick or network drive. The operating system, firmware and stored instrument settings are located on drive C. All other folders and drives can be used to store measurement data.



Saving instrument settings in secure user mode

In secure user mode all data is stored to the SDRAM, and is only available during the current session. As soon as the power is switched off on the R&S FPS, the data is cleared (see [chapter 3.1.6, "Protecting Data Using the Secure User Mode"](#), on page 30).

Other storage locations cannot be selected in this mode.

The storage location and file name are selected in a file selection dialog box which is displayed when you perform a storage function.

By default, the name of a settings file consists of a base name followed by an underscore and three numbers, e.g. `limit_lines_005`. In the example, the base name is `limit_lines`. The base name can contain characters, numbers and underscores. The file extension `df1` is added automatically. The default folder for settings files is `C:\r_s\instr\user`.

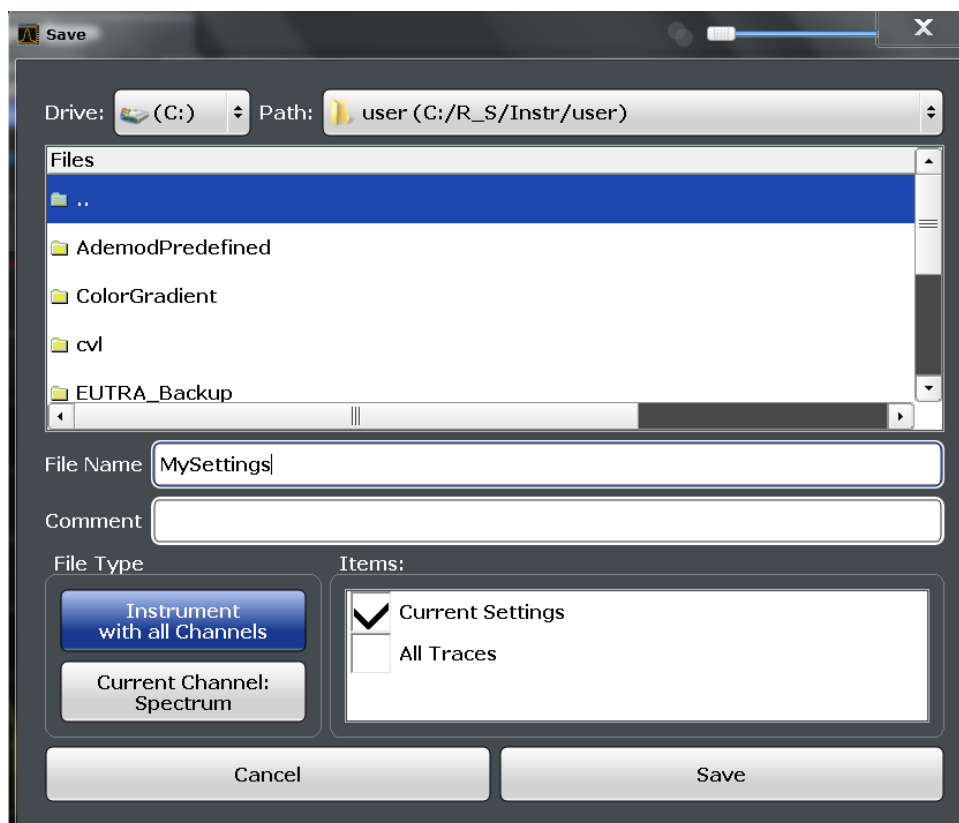
8.3.2.3 Save and Recall Dialog Boxes



The following dialog boxes are available via softkeys in the "Save/Recall" menu which is displayed when you select the "Save" or "Open" icon in the toolbar. Both dialog



boxes are very similar and closely related.



Selecting the Storage Location - Drive/ Path/ Files.....487
 File Name.....488
 Comment.....488
 File Type..... 488
 Items..... 488
 Save File..... 488
 Recall in New Channel / Recall in Current Channel.....489
 Cancel.....489

Selecting the Storage Location - Drive/ Path/ Files

Select the storage location of the settings file on the instrument or an external drive. The "Drive" indicates the internal (C:) or any connected external drives (e.g. a USB storage device).

The "Path" contains the drive and the complete file path to the currently selected folder.

The "Files" list contains all subfolders and files of the currently selected path.

The default storage location for the SEM settings files is: C:\R_S\instr\sem_std.

Note: Saving instrument settings in secure user mode.

In secure user mode all data is stored to volatile memory, and is only available during the current instrument session. As soon as the power is switched off on the R&S FPS, the data is cleared.

To store settings permanently, select an external storage location, such as a USB memory device.

For details see [chapter 3.1.6, "Protecting Data Using the Secure User Mode"](#), on page 30.

For details see "Protecting Data Using the Secure User Mode" in the "Data Management" section of the R&S FPS User Manual.

Remote command:

`MMEMemory:CATalog?` on page 882

File Name

Contains the name of the data file without the path or extension.

By default, the name of a settings file consists of a base name followed by an underscore. Multiple files with the same base name are extended by three numbers, e.g. `limit_lines_005`.

For details on the file name and location see [chapter 8.3.2.2, "Storage Location and File Name"](#), on page 486.

Note: Secure user mode. In secure user mode, settings that are to be stored on the instrument are stored to volatile memory. To store data permanently, select an external storage location such as a USB memory device.

For details see [chapter 3.1.6, "Protecting Data Using the Secure User Mode"](#), on page 30.

For details see "Protecting Data Using the Secure User Mode" in the "Data Management" section of the R&S FPS User Manual.

Comment

An optional description for the data file. A maximum of 60 characters can be displayed.

Remote command:

`MMEMemory:COMMent` on page 883

File Type

Determines whether the global instrument settings with all channels will be stored or recalled, or the current channel settings only.

Items

Defines which data and settings are stored or will be recalled. Depending on the "File Type", only channel settings or global settings are available. Which items are available also depends on the installed options (see also [chapter 8.3.2.1, "Stored Data Types"](#), on page 485).

Remote command:

`MMEMemory:SElect[:ITEM]:ALL` on page 888

`MMEMemory:SElect[:ITEM]:DEFault` on page 888

`MMEMemory:SElect[:ITEM]:HWSettings` on page 888

`MMEMemory:SElect[:ITEM]:LINes:ALL` on page 889

`MMEMemory:SElect[:ITEM]:NONE` on page 889

`MMEMemory:SElect[:ITEM]:TRACe[:ACTive]` on page 890

`MMEMemory:SElect[:ITEM]:TRANsducer:ALL` on page 890

Save File

Saves the settings file with the defined file name.

Note: Secure user mode. In secure user mode, settings that are to be stored on the instrument are stored to volatile memory, which is restricted to 256 MB. Thus, a "Memory full" error may occur although the hard disk indicates that storage space is still available.

For details see [chapter 3.1.6, "Protecting Data Using the Secure User Mode"](#), on page 30.

Remote command:

`MMEMory:STORe<n>:STATe` on page 893

`MMEMory:STORe<n>:STATe:NEXT` on page 894

Recall in New Channel / Recall in Current Channel

Restores the instrument settings as saved in the selected settings file. If the settings file contains settings for a specific channel only, select "Recall in New Channel" to activate a new channel with the stored settings, or "Recall in Current Channel" to replace the current channel settings.

Note: After you use the "Recall" function, the history of previous actions is deleted, i.e. any actions performed previously cannot be undone or redone using the UNDO/REDO keys.

Note: If a measurement channel with the same name as the channel to be restored (in a new channel) is already active, the channel name for the new channel is extended by a consecutive number:



In remote commands, you must append this number to the channel name, as well.

Remote command:

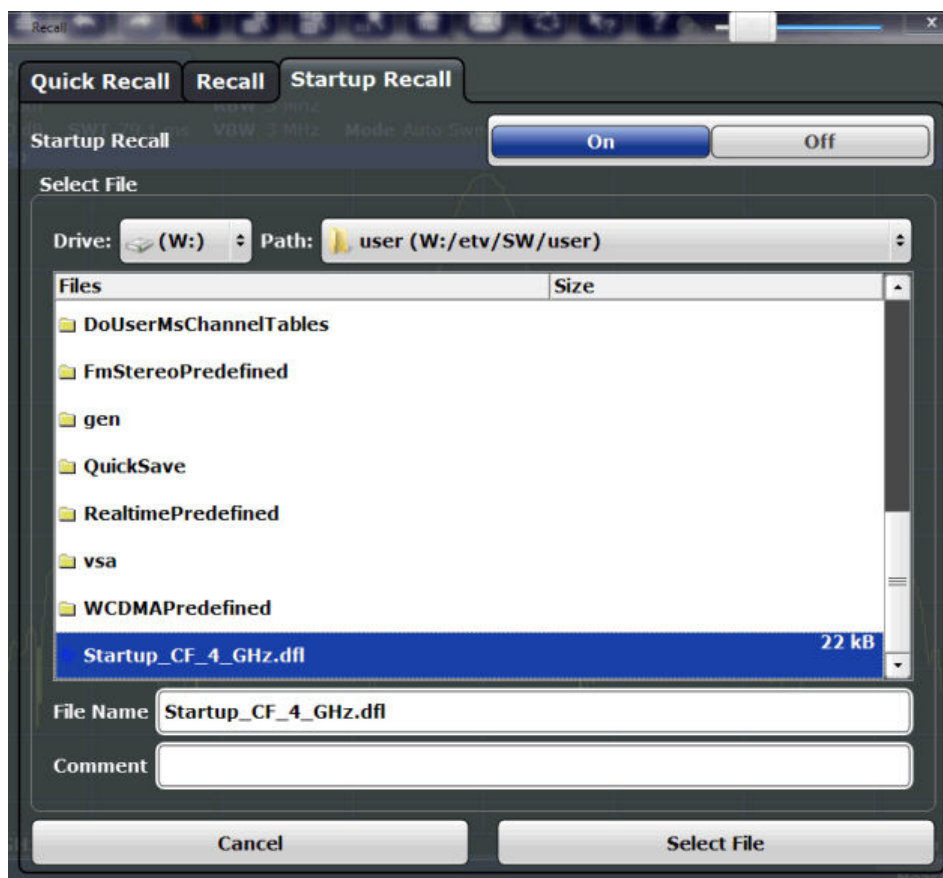
`MMEMory:LOAD:STATe` on page 891

Cancel

Closes the dialog box without saving the settings.

8.3.2.4 Startup Recall Settings

The "Startup Recall" softkey opens the "Startup Recall" tab of the "Recall" dialog box.



Startup Recall.....490
 Selecting the Storage Location - Drive/ Path/ Files.....490
 File Name.....491
 Comment.....491
 Cancel.....491

Startup Recall

Activates or deactivates the startup recall function. If activated, the settings stored in the selected file are loaded each time the instrument is started or preset. If deactivated, the default settings are loaded.

Note that only *instrument* settings files can be selected for the startup recall function, not channel settings files.

Remote command:

[MMEMoRY:LOAD:AUTO](#) on page 891

Selecting the Storage Location - Drive/ Path/ Files

Select the storage location of the settings file on the instrument or an external drive.

The "Drive" indicates the internal (C:) or any connected external drives (e.g. a USB storage device).

The "Path" contains the drive and the complete file path to the currently selected folder.

The "Files" list contains all subfolders and files of the currently selected path.

The default storage location for the SEM settings files is: C:\R_S\instr\sem_std.

Note: Saving instrument settings in secure user mode.

In secure user mode all data is stored to volatile memory, and is only available during the current instrument session. As soon as the power is switched off on the R&S FPS, the data is cleared.

To store settings permanently, select an external storage location, such as a USB memory device.

For details see [chapter 3.1.6, "Protecting Data Using the Secure User Mode"](#), on page 30.

For details see "Protecting Data Using the Secure User Mode" in the "Data Management" section of the R&S FPS User Manual.

Remote command:

[MMEMoRY:CATalog?](#) on page 882

File Name

Contains the name of the data file without the path or extension.

By default, the name of a settings file consists of a base name followed by an underscore. Multiple files with the same base name are extended by three numbers, e.g. `limit_lines_005`.

For details on the file name and location see [chapter 8.3.2.2, "Storage Location and File Name"](#), on page 486.

Note: Secure user mode. In secure user mode, settings that are to be stored on the instrument are stored to volatile memory. To store data permanently, select an external storage location such as a USB memory device.

For details see [chapter 3.1.6, "Protecting Data Using the Secure User Mode"](#), on page 30.

For details see "Protecting Data Using the Secure User Mode" in the "Data Management" section of the R&S FPS User Manual.

Comment

An optional description for the data file. A maximum of 60 characters can be displayed.

Remote command:

[MMEMoRY:COMMeNt](#) on page 883



Cancel

Closes the dialog box without saving the settings.


8.3.3 How to Save and Load Instrument Settings

Instrument settings can be saved to a file and loaded again later, so that you can repeat the measurement with the same settings. Optionally, user-defined measurement settings can automatically be restored each time you start or preset the instrument.


To save and recall instrument settings using the Quick Save function

1. Select the  "Save" icon from the toolbar.
2. Select whether the instrument settings for **all** channels are to be stored, or only those for the **current** channel.
3. Select one of the save sets in which the settings are to be stored ("QuickSaveX").
The selected settings are stored to the file
`C:\r_s\instr\user\QuickSave\QuickSaveX.dfl.`
4. To restore the settings, select the  "Open" icon from the toolbar.
5. Select the save set in which the settings were stored ("QuickSaveX").
The selected settings are restored to the instrument or channel.

To save configurable instrument settings

1. Select the  "Save" icon from the toolbar.
2. In the "Save" dialog box, switch to the "Save" tab.
3. In the file selection dialog box, select a file name and storage location for the settings file.
4. Optionally, define a comment to describe the stored settings.
5. Select whether the instrument settings for **all** channels are to be stored, or only those for the **current** channel.
6. Select the items to be saved with the settings. Either the settings for the currently selected channel only or for all channels can be stored, and various other items such as lines or traces etc. can be stored as well (see [chapter 8.3.2.1, "Stored Data Types"](#), on page 485).
7. Select "Save".
A file with the defined name and path and the extension `.dfl` is created.

To recall configurable instrument settings

1. Select the  "Open" icon from the toolbar.
2. In the "Recall" dialog box, switch to the "Recall" tab.
3. In the file selection dialog box, select the file name and storage location of the settings file.
Note: The "File Type" indicates whether the file contains instrument settings for **all** channels, or only those for the current channel.
4. If several items were saved, select which items are to be restored.
5. If channel settings were saved, select whether the settings will replace the settings in the current channel, or whether a new channel with the saved settings will be opened.

6. Select "Recall".

The settings and selected items from the saved measurement are restored and you can repeat the measurement with the same settings.

To recall settings automatically after preset or reboot

You can define the settings that are restored when you preset or reboot the instrument.

1. Configure the settings as required and save them as described in ["To save configurable instrument settings"](#) on page 492.

2. In the "Save/Recall" menu, select the "Startup Recall" softkey.

3. If the file selection dialog box is not displayed automatically, select the "Select Dataset" softkey.

4. Select the recall settings that are to be restored.

5. Select "Select".

6. Toggle the "Startup Recall" softkey to "On".

Now when you press the PRESET key or reboot the instrument, the defined settings will be restored.

7. To restore the factory preset settings, toggle the "Startup Recall" softkey to "Off".

8.4 Importing and Exporting Measurement Results for Evaluation

The R&S FPS provides various evaluation methods for the results of the performed measurements. However, you may want to evaluate the data with further, external applications. In this case, you can export the measurement data to a standard format file (ASCII or XML). Some of the data stored in these formats can also be re-imported to the R&S FPS for further evaluation at a later time, for example in other applications.

The following data types can be exported:

- Trace data
- Table results, such as result summaries, marker peak lists etc.
- I/Q data

The following data types can be imported:

- I/Q data



I/Q data can only be imported and exported in applications that process I/Q data, such as the I/Q Analyzer or optional applications.

See the corresponding user manuals for those applications for details.

- [Import/Export Functions](#).....494
- [How to Export Trace Data and Numerical Results](#).....495
- [How to Export a Peak List](#).....496
- [Reference: ASCII File Export Format](#).....497

8.4.1 Import/Export Functions



The following import and export functions are available via softkeys in the "Save/Recall" menu which is displayed when you select the "Save" or "Open" icon in the tool-bar.



Some functions for particular data types are (also) available via softkeys or dialog boxes in the corresponding menus, e.g. trace data or marker peak lists.



For a description of the other functions in the "Save/Recall" menu see the R&S FPS User Manual.

Import	494
Export	494
L Export Trace to ASCII File	494
L Trace Export Configuration	495
L I/Q Export	495

Import

Provides functions to import data.

Currently, only I/Q data can be imported, and only by applications that process I/Q data.

See the R&S FPS I/Q Analyzer User Manual for more information.

Export

Opens a submenu to configure data export.

Export Trace to ASCII File ← Export

Opens a file selection dialog box and saves the selected trace in ASCII format (.dat) to the specified file and directory.

The results are output in the same order as they are displayed on the screen: window by window, trace by trace, and table row by table row.

If the spectrogram display is selected when you perform this function, the entire histogram buffer with all frames is exported to a file. The data corresponding to a particular frame begins with information about the frame number and the time that frame was recorded. For large history buffers the export operation may take some time.

For details on the file format see [chapter 8.4.4, "Reference: ASCII File Export Format"](#), on page 497.

Note: Secure user mode.

In secure user mode, settings that are to be stored on the instrument are stored to volatile memory, which is restricted to 256 MB. Thus, a "Memory full" error may occur although the hard disk indicates that storage space is still available.

To store data permanently, select an external storage location such as a USB memory device.

For details see [chapter 3.1.6, "Protecting Data Using the Secure User Mode"](#), on page 30.

For details see "Protecting Data Using the Secure User Mode" in the "Data Management" section of the R&S FPS User Manual.

Remote command:

`MMEMory:STORe<n>:TRACe` on page 905

`MMEMory:STORe<n>:SPECTrogram` on page 904

Trace Export Configuration ← Export

Opens the "Traces" dialog box to configure the trace and data export settings.

See [chapter 7.3.2.3, "Trace / Data Export Configuration"](#), on page 415.

I/Q Export ← Export

Opens a file selection dialog box to select an export file to which the IQ data will be stored. This function is only available in single sweep mode, and only in applications that process I/Q data, such as the I/Q Analyzer or optional applications.

For details see the description in the R&S FPS I/Q Analyzer User Manual ("Importing and Exporting I/Q Data").

Note: Secure user mode.

In secure user mode, settings that are to be stored on the instrument are stored to volatile memory, which is restricted to 256 MB. Thus, a "Memory full" error may occur although the hard disk indicates that storage space is still available.

To store data permanently, select an external storage location such as a USB memory device.

For details see [chapter 3.1.6, "Protecting Data Using the Secure User Mode"](#), on page 30.

For details see "Protecting Data Using the Secure User Mode" in the "Data Management" section of the R&S FPS User Manual.

8.4.2 How to Export Trace Data and Numerical Results


The measured trace data and numerical measurement results in tables can be exported to an ASCII file. For each sweep point the measured trace position and value are output. The file is stored with a `.DAT` extension. For details on the storage format see [chapter 8.4.4, "Reference: ASCII File Export Format"](#), on page 497.



For the results of a Spectrum Emission Mask (SEM) or Spurious Emissions measurement, special file export functions are available, see [chapter 5.6.6.2, "How to Save SEM Result Files"](#), on page 230 (SEM) and ["Saving the Evaluation List"](#) on page 249 (Spurious).

To export trace data and table results

Trace data can be exported either from the "Trace" menu, or from the "Save/Recall" menu.

1. Press the TRACE key, then select the "Trace Config" softkey and switch to the "Trace/Data Export" tab.
Or:
Select the  "Save" icon in the toolbar, then select the "Export" softkey.
2. Select the "Export Config" softkey to configure the export settings.
 - a) Select "Export all Traces and all Table Results" to export all available measurement result data for the current application, or select a specific "Trace to Export".
 - b) Optionally, select the "Include Instrument Measurement Settings" option to insert additional information in the export file header.
 - c) If necessary, change the decimal separator to be used for the ASCII export file.
3. Select the "Export Trace to ASCII file" button.
4. In the file selection dialog box, select the storage location and file name for the export file.
5. Select "Save" to close the dialog box and export the data to the file.

8.4.3 How to Export a Peak List

You can save the results of a marker peak list to an ASCII file.

1. Press the MKR FUNCT key.
2. Select the "Marker Peak List" softkey.
3. Configure the peak search and list settings as described in [chapter 7.4.3.7, "Marker Peak List Configuration"](#), on page 458.
4. Set the marker peak list "State" to "On".
5. Press the RUN SINGLE key to perform a single sweep measurement and create a marker peak list.
6. Select the "Marker Peak List" softkey to display the "Marker Peak List" dialog box again.
7. If necessary, change the decimal separator to be used for the ASCII export file.
8. Select the "Export Peak List" button.
9. In the file selection dialog box, select the storage location and file name for the export file.
10. Select "Save" to close the dialog box and export the peak list data to the file.

8.4.4 Reference: ASCII File Export Format

Trace data can be exported to a file in ASCII format for further evaluation in other applications. This reference describes in detail the format of the export files for result data.

(For details see [chapter 8.4.2, "How to Export Trace Data and Numerical Results"](#), on page 495).



For a description of the file formats for spectrum emission mask (SEM) measurement settings and results, see [chapter 5.6.8, "Reference: SEM File Descriptions"](#), on page 232.

The file format for Spurious Emissions measurement results is described in [chapter 5.7.6, "Reference: ASCII Export File Format \(Spurious\)"](#), on page 250.

The file consists of the header containing important scaling parameters and a data section containing the trace data. Optionally, the header can be excluded from the file (see ["Include Instrument Measurement Settings"](#) on page 416).

The data of the file header consist of three columns, each separated by a semicolon: parameter name; numeric value; basic unit. The data section starts with the keyword "Trace <n>" (<n> = number of stored trace), followed by the measured data in one or several columns (depending on the measurement) which are also separated by a semicolon.

The results are output in the same order as they are displayed on the screen: window by window, trace by trace, and table row by table row.

Generally, the format of this ASCII file can be processed by spreadsheet calculation programs, e.g. MS-Excel. Different language versions of evaluation programs may require a different handling of the decimal point. Thus you can define the decimal separator to be used (decimal point or comma, see ["Decimal Separator"](#) on page 417).

If the spectrogram display is selected when you select the "ASCII Trace Export" soft-key, the entire histogram buffer with all frames is exported to a file. The data corresponding to a particular frame begins with information about the frame number and the time that frame was recorded.

Table 8-3: ASCII file format for trace export

File contents	Description
Header data	
Type;R&S FPS;	Instrument model
Version;5.00;	Firmware version
Date;01.Oct 2006;	Date of data set storage
Mode;ANALYZER;	Operating mode
Preamplifier;OFF	Preamplifier status
Transducer; OFF	Transducer status
Center Freq;55000;Hz	Center frequency

Importing and Exporting Measurement Results for Evaluation

File contents	Description
Freq Offset;0;Hz	Frequency offset
Start;10000;Hz Stop;100000;Hz	Start/stop of the display range. Unit: Hz for span > 0, s for span = 0, dBm/dB for statistics measurements
Span;90000;Hz	Frequency range (0 Hz in zero span and statistics measurements)
Ref Level;-30;dBm	Reference level
Level Offset;0;dB	Level offset
Rf Att;20;dB	Input attenuation
EI Att;2.0;dB	Electrical attenuation
RBW;100000;Hz	Resolution bandwidth
VBW;30000;Hz	Video bandwidth
SWT;0.005;s	Sweep time
Sweep Count;20;	Number of sweeps set
Ref Position;75;%	Position of reference level referred to diagram limits (0 % = lower edge)
Level Range;100;dB	Display range in y direction. Unit: dB with x-axis LOG, % with x-axis LIN
x-Axis;LIN;	Scaling of x-axis linear (LIN) or logarithmic (LOG)
y-Axis;LOG;	Scaling of y-axis linear (LIN) or logarithmic (LOG)
x-Unit;Hz;	Unit of x values: Hz with span > 0; s with span = 0; dBm/dB with statistics measurements
y-Unit;dBm;	Unit of y values: dB*/V/A/W depending on the selected unit with y-axis LOG or % with y-axis LIN
Data section for individual window	
Window;1;Frequency Sweep	Window number and name
Trace 1;;	Selected trace
Trace Mode;AVERAGE;	Display mode of trace: CLR/WRITE,AVERAGE,MAXHOLD,MINHOLD
Detector;AUTOPEAK;	Detector set: AUTOPEAK,MAXPEAK,MINPEAK,AVERAGE,RMS,SAMPLE,QUASPEAK
Values; 1001;	Number of measurement points
10000;-10.3;-15.7 10130;-11.5;-16.9 10360;-12.0;-17.4 ...;...;	Measured values: <x value>, <y1>, <y2>; <y2> being available only with detector AUTOPEAK and containing in this case the smallest of the two measured values for a measurement point.
Data section for individual trace	
Trace 2;;	Next trace in same window

Importing and Exporting Measurement Results for Evaluation

File contents	Description
...	
Data section for individual window	
Window;2 ..;	Name of next window
Data section for individual trace	
Trace 1;;	First trace
...	

Table 8-4: ASCII file format for spectrogram trace export

File contents	Description
Header	
Type;R&S FPS;	Instrument model
Version;5.00;	Firmware version
Date;01.Oct 2006;	Date of data set storage
Mode;ANALYZER; SPECTROGRAM	Operating mode
Center Freq;55000;Hz	Center frequency
Freq Offset;0;Hz	Frequency offset
Span;90000;Hz	Frequency range (0 Hz in zero span and statistics measurements)
x-Axis;LIN;	Scaling of x-axis linear (LIN) or logarithmic (LOG)
Start;10000;Hz Stop;100000;Hz	Start/stop of the display range. Unit: Hz for span > 0, s for span = 0, dBm/dB for statistics measurements
Ref Level;-30;dBm	Reference level
Level Offset;0;dB	Level offset
Ref Position;75; %	Position of reference level referred to diagram limits (0 % = lower edge)
y-Axis;LOG;	Scaling of y-axis linear (LIN) or logarithmic (LOG)
Level Range;100;dB	Display range in y direction. Unit: dB with x-axis LOG, % with x-axis LIN
Rf Att;20;dB	Input attenuation
RBW;100000;Hz	Resolution bandwidth
VBW;30000;Hz	Video bandwidth
SWT;0.005;s	Sweep time
Trace Mode;AVERAGE;	Display mode of trace: CLR/WRITE,AVERAGE,MAXHOLD,MINHOLD
Detector;AUTOPEAK;	Detector set: AUTOPEAK,MAXPEAK,MINPEAK,AVERAGE,RMS,SAMPLE,QUASPEAK

File contents	Description
Sweep Count;20;	Number of sweeps set
Data section	
Trace 1;;	Selected trace
x-Unit;Hz;	Unit of x values: Hz with span > 0; s with span = 0; dBm/dB with statistics measurements
y-Unit;dBm;	Unit of y values: dB*/V/A/W depending on the selected unit with y-axis LOG or % with y-axis LIN
Values; 1001;	Number of measurement points
Frames;2;	Number of exported frames
Frame;0;	Most recent frame number
Timestamp;17.Mar 11;11:27:05.990	Timestamp of this frame
10000;-10.3;-15.7 10130;-11.5;-16.9 10360;-12.0;-17.4 ...;...;	Measured values, identical to spectrum data: <x value>, <y1>, <y2>; <y2> being available only with detector AUTOPEAK and containing in this case the smallest of the two measured values for a measurement point.
Frame;-1;	Next frame
Timestamp;17.Mar 11;11:27:05.342	Timestamp of this frame
...	

8.5 Creating Screenshots of Current Measurement Results and Settings

In order to document the graphical results and the most important settings for the currently performed measurement, you can create a hardcopy or screenshot of the current display. Screenshots can either be printed or stored to a file.

- [Print and Screenshot Settings](#).....500
- [How to Store or Print Screenshots of the Display](#)..... 504

8.5.1 Print and Screenshot Settings



The settings for saving and printing screenshots are configured via the "Print" menu which is displayed when you select the "Print" icon in the toolbar.

For step-by-step instructions see [chapter 8.5.2, "How to Store or Print Screenshots of the Display"](#), on page 504.

Remote commands for these settings are described in [chapter 11.9.4, "Storing or Printing Screenshots"](#), on page 895.



To print a screenshot of the current display with the current settings immediately, without switching to the "Print" menu, use the "Print immediately" icon at the right-hand side of the toolbar.

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Device Setup.....	501
L Output Medium.....	502
L Print Date and Time.....	502
L Print Logo.....	502
L Suppress File Name Dialog.....	503
L Print Dialog.....	503
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L Orientation.....	503
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Printing or Storing a Screenshot (Print Screen)

Starts to print out or store all measurement results displayed on the screen: diagrams, traces, markers, marker lists, limit lines, etc., including the channel and status bars. Optionally, comments and the date and time are included at the bottom margin of the printout. All displayed items belonging to the software user interface (e.g. softkeys or dialog boxes) are not printed out.

Whether the output is sent to the printer or stored in a file or the clipboard depends on the selected device and the device settings.

If the output is stored to a file, a file selection dialog box is opened to select the file name and location. The default path is `C:\r_s\instr\user`.

The "Print" menu is displayed to configure printing.

Remote command:

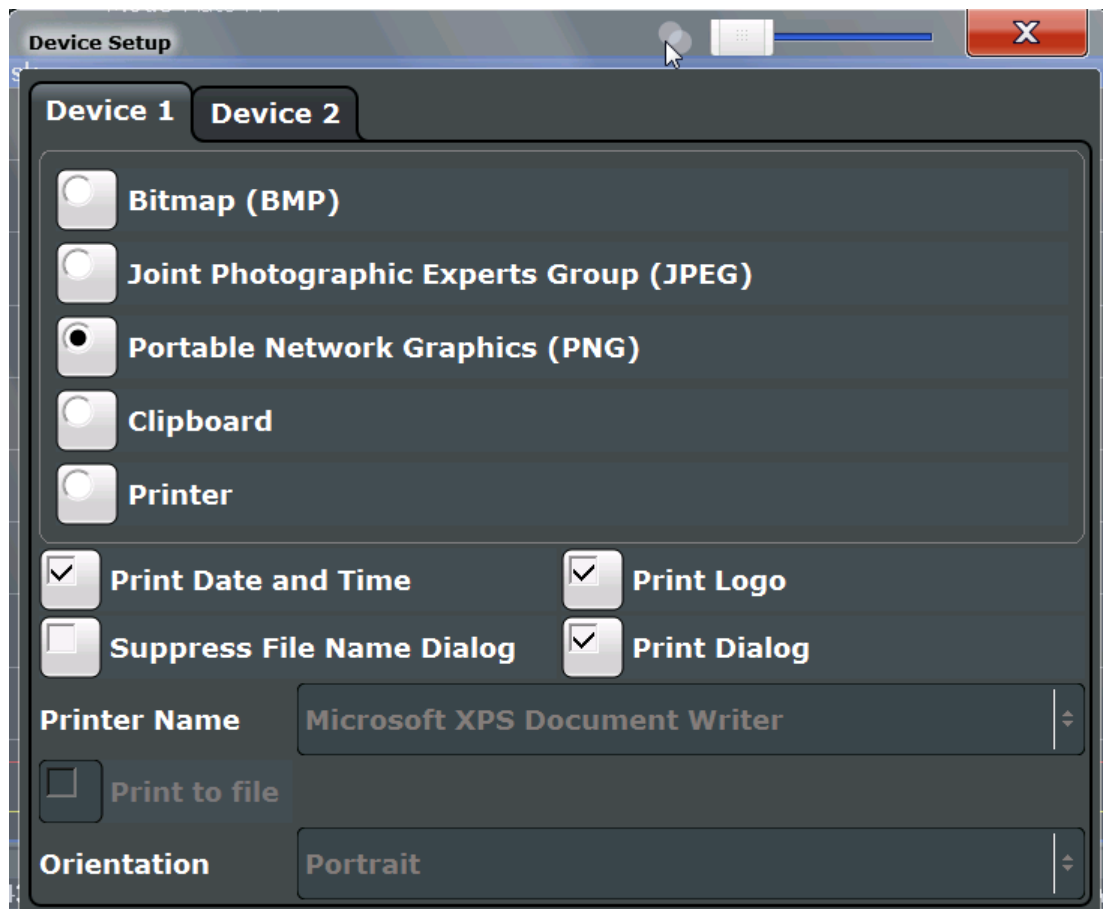
`HCOPY:ITEM:ALL` on page 900

`HCOPY[:IMMEDIATE<device>]` on page 899

`HCOPY[:IMMEDIATE<device>]:NEXT` on page 899

Device Setup

Defines the behavior of the "Print Screen" function, depending on which device is selected. Two different devices can be configured, e.g. one for printing and one for storage to a file.



Output Medium ← Device Setup

Defines the medium to which the screenshot is printed or stored.

"File formats" Stores the screenshot to a file in the selected format. The file name is queried at the time of storage.

"Clipboard" Stores the screenshot to the clipboard.

"Printer" Prints the screenshot on the printer selected from the "Name" list.

Remote command:

[HCOPY:DEVIce:LANGuage<device>](#) on page 899

Print Date and Time ← Device Setup

Activates/deactivates the printout of the current date and time at the bottom of the screenshot.

Remote command:

[HCOPY:TDSTamp:STATe<device>](#) on page 900

Print Logo ← Device Setup

Activates/deactivates the printout of the Rohde & Schwarz company logo in the upper left corner.

Remote command:

[DISPlay:LOGO](#) on page 896

Suppress File Name Dialog ← Device Setup

When the screenshot is stored to a file, the file selection dialog box is not displayed. Instead, the current storage location and file name are used (default: C:\r_S\instr\user). Each new the file name is extended by a consecutive number, e.g. File002, File003 etc.

Print Dialog ← Device Setup

Includes any currently displayed dialog in the screenshot.

Printer Name ← Device Setup

Defines the printer to print to.

Remote command:

[SYSTem:COMMunicate:PRINter:ENUMerate\[:NEXT\]? on page 901](#)

[SYSTem:COMMunicate:PRINter:ENUMerate:FIRSt? on page 901](#)

[SYSTem:COMMunicate:PRINter:SElect<device> on page 901](#)

Print to File ← Device Setup

If a printer is selected as the output medium, use this option to store the data in a .prn file using the selected printer driver.

Orientation ← Device Setup

Selects the page orientation of the printout: portrait or landscape (printer only)

Remote command:

[HCOpy:PAGE:ORientation<device> on page 900](#)

Device

Two different printout devices can be configured, e.g. one for printing and one for storage to a file. When the "Print Screen" function is executed, the selected device and its settings determine the behavior.

Remote command:

[HCOpy:DESTination<device> on page 898](#)

Colors

Opens the "Print Color" dialog box to configure the colors for printing screenshots. For details see ["Print colors"](#) on page 534.

Comment

Defines an optional comment to be printed with the screenshot of the display. Maximum 120 characters are allowed. 60 characters fit in one line. In the first line, at any point a manual line-feed can be forced by entering "@".

Date and time are inserted automatically. The comment is printed below the diagram area, but not displayed on the screen. If a comment should not be printed, it must be deleted.

Remote command:

[HCOpy:ITEM:WINDow:TEXT on page 900](#)


Install Printer

Opens the standard Windows dialog box to install a new printer. All printers that are already installed are displayed.

Only user accounts with administrator rights can install a printer.


For further information refer to the Microsoft Windows documentation.

8.5.2 How to Store or Print Screenshots of the Display

- ▶ If the R&S FPS has already been set up according to your current requirements, simply press the "Print immediate" icon () at the far right end of the toolbar.
A screenshot of the current measurement display is printed or stored to a file, as configured.

To set up screenshot outputs

This configuration assumes a printer has already been installed. To install a new printer, use the [Install Printer](#) softkey.

1. Select the  "Printer" tool in the toolbar.
2. Select the "Device Setup" softkey.
3. Select the tab for Device 1 or Device 2 to configure a device.
4. To set up the print function to store a screenshot to a file, select the required file format as the output medium.
To set up the print function to store a screenshot to the clipboard, select "Clipboard" as the output medium.
To set up the print function to print a screenshot on a printer, select "Printer" as the output medium and an installed printer from the "Name" list.
5. For printout, select the page orientation.
6. Optionally, deactivate the date and time or the logo so they are not added to the screenshot.
7. Select "OK" to close the "Device Setup" dialog box.
8. Toggle the "Device" softkey to the device configuration you want to use.
9. Optionally, configure the colors to be used for printout, e.g. as displayed on the screen instead of inversed.
10. Optionally, add a comment to be included with the screenshot.
11. Select the "Print Screen" softkey or the "Printer" or "Screenshot" tool in the toolbar to execute the print function and check the results.
12. If you configured the print function to store the screenshot to a file, enter a file name in the file selection dialog box.

9 General Instrument Setup

Some basic instrument settings can be configured independently of the selected operating mode or application. Usually, you will configure most of these settings initially when you set up the instrument according to your personal preferences or requirements and then only adapt individual settings to special circumstances when necessary. Some special functions are provided for service and basic system configuration.

- [Basics on Alignment](#).....505
- [Basics on Transducer Factors](#)..... 506
- [General Instrument Settings](#)..... 507
- [Display Settings](#)..... 528
- [External Monitor Settings](#).....536
- [How to Configure the Basic Instrument Settings](#).....537

9.1 Basics on Alignment

When you put the instrument into operation for the first time or when strong temperature changes occur, it may be necessary to align the data to a reference source (see also "[Temperature check](#)" on page 506).



During instrument start, the installed hardware is checked against the current firmware version to ensure the hardware is supported. If not, an error message is displayed ("WRONG_FW") and you are asked to update the firmware. Until the firmware version is updated, self-alignment fails.

The correction data and characteristics required for the alignment are determined by comparison of the results at different settings with the known characteristics of the high-precision calibration signal source at 64 MHz.

Alignment results

The alignment results are displayed and contain the following information:

- date and time of last correction data record
- overall results of correction data record
- list of found correction values according to function/module

The results are classified as follows:

PASSED	Calibration successful without any restrictions
CHECK	Deviation of correction value larger than expected, correction could however be performed
FAILED	Deviations of correction value too large, no correction was possible. The found correction data is not applicable.

The results are available until the next self-alignment process is started or the instrument is switched off.

Temperature check

During self-alignment, the instrument's (frontend) temperature is also measured (as soon as the instrument has warmed up completely). This temperature is used as a reference for a continuous temperature check during operation. If the current temperature deviates from the stored self-alignment temperature by a certain degree, a warning is displayed in the status bar indicating the resulting deviation in the measured power levels. A status bit in the `STATUS:QUESTIONABLE:TEMPERATURE` register indicates a possible deviation. The current temperature of the RF Frontend can be queried using a remote command (see `SOURCE:TEMPERATURE:FRONTEND?` on page 914).

9.2 Basics on Transducer Factors

The transducer allows you to manipulate the trace at discrete trace points to correct the signal coming from an input device. Transducers are often used to correct the frequency response for antennas, for example. The transducer is configured by defining transducer factors for specific trace points. A set of transducer factors defines an interpolated transducer line and can be stored on the instrument.

In the Spectrum application, the correction factor from all active transducers is calculated for each displayed trace point once in advance and is added to the result of the level measurement during the sweep. If the sweep range changes, the correction values are calculated again. If several measured values are combined in one point, only one value is taken into consideration. If the active transducer line is not defined for the entire sweep range, the missing values are replaced by zeroes.

When a transducer is used, the trace is shifted by a calculated factor. However, an upward shift reduces the dynamic range for the displayed values. Thus, the reference level can be adapted automatically to restore the original dynamic range. The reference level is shifted by the maximum transducer factor. By default, if transducers are active the reference level function is adapted automatically to obtain the best dynamic performance.

If a transducer factor is active, "TDF" is displayed in the channel bar.

Y-Axis Unit

The individual transducer factors can be defined as absolute values or relative (dB) values. However, all factors for one transducer line use the same unit. As soon as a transducer is activated, the unit of the transducer is automatically used for all the level settings and outputs. The unit cannot be changed in the amplitude settings since the R&S FPS and the active transducer are regarded as one measuring instrument. Only for relative transducer factors (unit dB), the unit originally set on the instrument is maintained and can be changed.

When all transducers have been switched off, the R&S FPS returns to the unit that was used before a transducer was activated.

Configuration

The R&S FPS supports transducer lines with a maximum of 1001 data points. Eight of the transducer lines stored in the instrument can be activated simultaneously. The number of transducer lines stored in the instrument is only limited by the capacity of the storage device used.

A transducer line consists of the following data:

- A maximum of 1001 data points with a position and value
- A unit for the values
- A name to distinguish the transducer lines

Validity

The transducer factors must comply with the following rules to ensure correct operation:

- The frequencies for the data points must always be defined in ascending order. Otherwise the entry will not be accepted and an error message is displayed.
- The frequencies of the data points may exceed the valid frequency range of the R&S FPS since only the set frequency range is taken into account for measurements. The minimum frequency of a data point is 0 Hz, the maximum frequency 200 GHz.
- The value range for the transducer factor is ± 200 dB.
- Gain has to be entered as a negative value, and attenuation as a positive value.

9.3 General Instrument Settings

Instrument settings can be configured via the SETUP key.



Network and Remote Settings, Display Settings

Settings for network and remote operation are described in [chapter 10, "Network and Remote Operation"](#), on page 543.

Display settings are described in [chapter 9.4, "Display Settings"](#), on page 528.

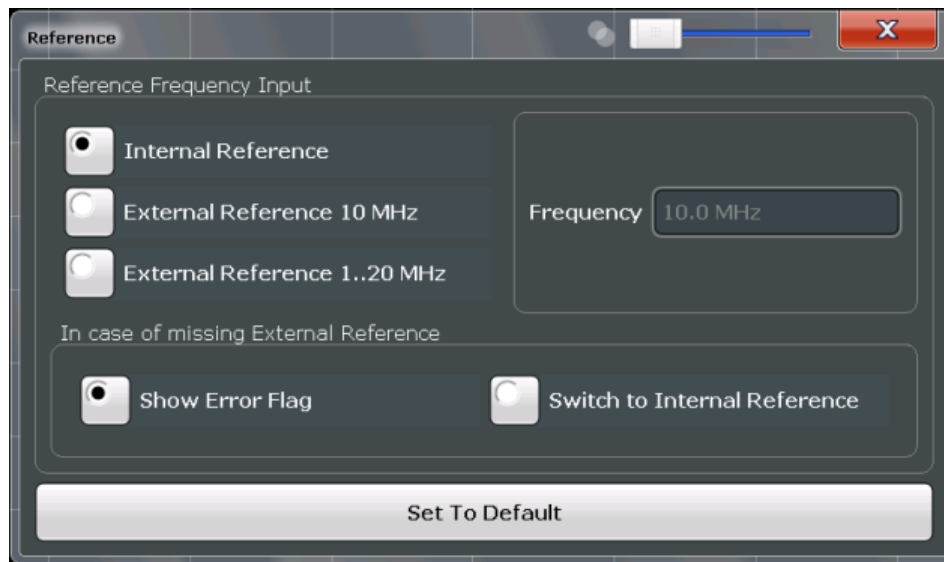


Some of the following settings and functions are also available directly on the R&S FPS, via the miniature display. See [chapter 3.3, "Miniature Display"](#), on page 39.

- [Reference Frequency Settings](#).....508
- [Transducer Settings](#).....509
- [Alignment Settings](#).....514
- [System Configuration Settings](#).....515
- [Service Functions](#).....522

9.3.1 Reference Frequency Settings

The reference frequency settings are defined in the "Reference" dialog box which is displayed when you press the SETUP key and then select "Reference".



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 L Behavior in case of missing external reference..... 509
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Reference Frequency Input

The R&S FPS can use the internal reference source or an external reference source as the frequency standard for all internal oscillators. A 10 MHz crystal oscillator is used as the internal reference source. In the external reference setting, all internal oscillators of the R&S FPS are synchronized to the external reference frequency.

External references are connected to one of the REF INPUT connectors on the rear panel. For details see the "Getting Started" manual.

The default setting is the internal reference. When an external reference is used, "EXT REF" is displayed in the status bar.

The following reference inputs are available:

Table 9-1: Available Reference Frequency Input

Source	Frequency	Tuning Range	Loop Band-width	Description
Internal	10 MHz	-	1-100 Hz	Internal reference signal
External Reference 10 MHz	10 MHz	+/- 6 ppm	1-100 Hz	External reference from REF INPUT 1..20 MHz connector; Fixed external 10 MHz reference frequency. Good phase noise performance

Source	Frequency	Tuning Range	Loop Bandwidth	Description
External Reference 1..20 MHz	1..20 MHz in 1 Hz steps	+/- 0.5 ppm	0.1 Hz (fixed)	Variable external reference frequency in 0.1 Hz steps from REF INPUT 1..20 MHz connector; Good external phase noise suppression. Small tuning range.
		+/- 6 ppm	1-30 Hz	Variable external reference frequency in 0.1 Hz steps from REF INPUT 1..20 MHz connector; Wide tuning range.

Remote command:

[\[SENSe:\]ROSCillator:SOURce](#) on page 909

[SOURce:EXternal:ROSCillator:EXternal:FREQuency](#) on page 909

Behavior in case of missing external reference ← Reference Frequency Input

If an external reference is selected but none is available, there are different ways the instrument can react.

"Show Error Flag" The message "NO REF" is displayed to indicate that no synchronization is performed.

"Switch to internal reference" The instrument automatically switches back to the internal reference if no external reference is available. Note that you must re-activate the external reference if it becomes available again at a later time.

Remote command:

[\[SENSe:\]ROSCillator:SOURce](#) on page 909

[\[SENSe:\]ROSCillator:SOURce:EAUTO?](#) on page 910

Frequency ← Reference Frequency Input

Defines the external reference frequency to be used (for variable connectors only).

Resetting the Default Values

The values for the "Tuning Range", "Frequency" and "Loop Bandwidth" are stored for each source of "Reference Frequency Input". Thus, when you switch the input source, the previously defined settings are restored. You can restore the default values for all input sources using the "Preset Channel" function.

9.3.2 Transducer Settings

Up to 8 transducer lines can be activated simultaneously in the R&S FPS. Many more can be stored on the instrument.

The transducer settings are defined in the "Transducer" dialog box which is displayed when you press the SETUP key and then select "Transducer".



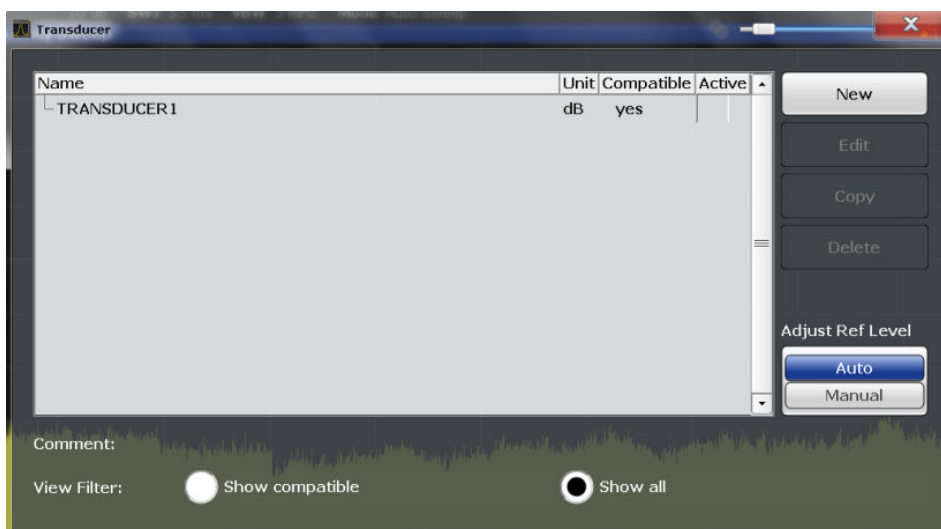
Transducer settings in secure user mode

Be sure to store transducer files before [Secure User Mode](#) is enabled; see [chapter 3.1.6, "Protecting Data Using the Secure User Mode"](#), on page 30.

- [Transducer Management](#)..... 510
- [Transducer Factors](#)..... 512

9.3.2.1 Transducer Management

The settings required to manage all transducer lines on the instrument are described here.



For the transducer line overview, the R&S FPS searches for all stored transducer lines with the file extension `.TDF` in the `trd` subfolder of the main installation folder. The overview allows you to determine which transducer lines are available and can be used for the current measurement.

For details on settings for individual lines see [chapter 9.3.2.2, "Transducer Factors"](#), on page 512.

For instructions on configuring and working with transducers see [chapter 9.6.5, "How to Configure the Transducer"](#), on page 539.

- [Name](#)..... 511
- [Unit](#)..... 511
- [Compatibility](#)..... 511
- [Activating/Deactivating](#)..... 511
- [Comment](#)..... 511
- [Included Transducer Lines in Overview \(View Filter\)](#)..... 511
- [Adjusting the Reference Level](#)..... 511
- [Create New Line](#)..... 512
- [Edit Line](#)..... 512
- [Copy Line](#)..... 512
- [Delete Line](#)..... 512

Name

The name of the stored transducer line.

Unit

The unit in which the y-values of the data points of the transducer line are defined.

The following units are available:

- dB
- dBm
- dBmV
- dB μ V
- dB μ V/m
- dB μ A
- dB μ A/m
- dBpW
- dBpT

Compatibility

Indicates whether the transducer factors are compatible with the current measurement settings.

For more information on which conditions a transducer line must fulfill to be compatible, see [chapter 9.2, "Basics on Transducer Factors"](#), on page 506.

Activating/Deactivating

Activates/deactivates the transducer line. Up to 8 transducer lines can be active at the same time.

Remote command:

[\[SENSe:\]CORRection:TRANsdUcer:SELEct](#) on page 916

[\[SENSe:\]CORRection:TRANsdUcer\[:STATe\]](#) on page 916

Comment

An optional description of the transducer line.

Included Transducer Lines in Overview (View Filter)

Defines which of the stored transducer lines are included in the overview. The view can be restricted to compatible transducer lines only or include all transducer lines found. Whether a line is compatible or not is indicated in the [Compatibility](#) setting.

Adjusting the Reference Level

Activates or deactivates the automatic adjustment of the reference level to the selected transducer factor.

"Auto" Activates the automatic adjustment. The original dynamic range is restored by shifting the reference level by the maximum transducer factor.

"Man" Deactivates the automatic adjustment. Adjust the reference level via the "Amplitude" menu.

Remote command:

[\[SENSe:\]CORRection:TRANsdUcer:ADJust:RLEVel\[:STATe\]](#) on page 915

Create New Line

Create a new transducer line.

Remote command:

[SENSe:]CORRection:TRANsducer:SELEct on page 916

Edit Line

Edit an existing transducer line configuration.

Copy Line

Copy the selected transducer line configuration to create a new line.

Delete Line

Delete the selected transducer line.

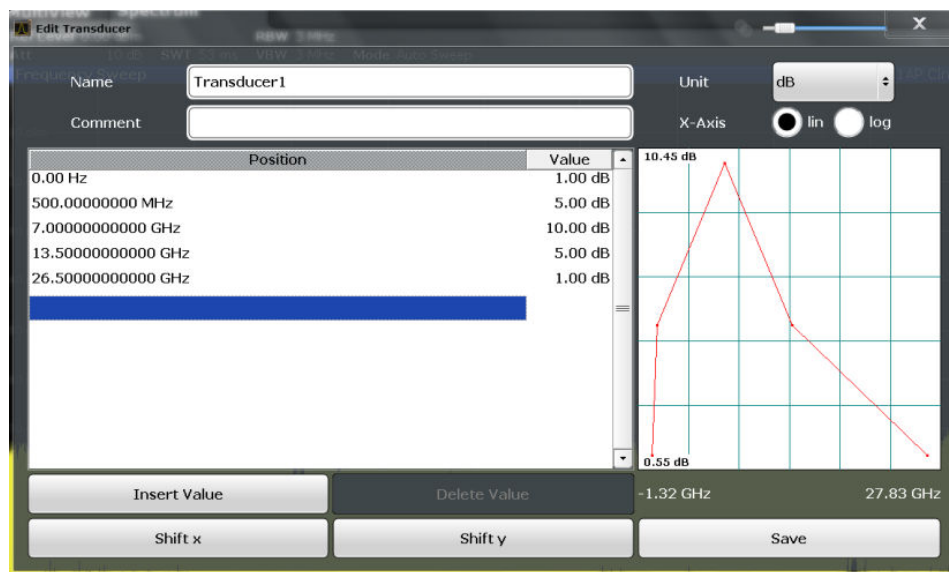
Remote command:

[SENSe:]CORRection:TRANsducer:DELEte on page 916

9.3.2.2 Transducer Factors

The settings and functions available for individual transducer lines are described here.

For instructions on creating and editing transducer lines see [chapter 9.6.5, "How to Configure the Transducer"](#), on page 539.



Name.....513

Comment.....513

Unit.....513

X-Axis Scaling.....513

Data points.....513

Insert Value.....514

Delete Value.....514

Shift x.....	514
Shift y.....	514
Save.....	514

Name

Defines the transducer line name. All names must be compatible with the Windows 7 conventions for file names. The transducer data is stored under this name (with a `.TDF` extension) in the `trd` subfolder of the main installation folder.

Remote command:

`[SENSe:]CORRection:TRANsducer:SELeCt` on page 916

Comment

Defines an optional comment for the transducer line. The text may contain up to 40 characters.

Remote command:

`[SENSe:]CORRection:TRANsducer:COMMeNt` on page 915

Unit

The unit in which the y-values of the data points of the transducer line are defined.

As soon as a transducer is activated, the unit of the transducer is automatically used for all the level settings and outputs. The unit cannot be changed in the amplitude settings unless dB is used.

Remote command:

`[SENSe:]CORRection:TRANsducer:UNIT` on page 916

X-Axis Scaling

Describes the scaling of the horizontal axis on which the data points of the transducer line are defined. Scaling can be linear or logarithmic.

Remote command:

`[SENSe:]CORRection:TRANsducer:SCALIng` on page 916

Data points

Each transducer line is defined by a minimum of 2 and a maximum of 50 data points. Each data point is defined by its position (x-axis) and value (y-value).

The data points must comply with the following rules to ensure correct operation:

- The frequencies for the data points must always be defined in ascending order. Otherwise the entry will not be accepted and an error message is displayed.
- The frequencies of the data points may exceed the valid frequency range of the R&S FPS since only the set frequency range is taken into account for measurements. The minimum frequency of a data point is 0 Hz, the maximum frequency 200 GHz.
- The value range for the transducer factor is ± 200 dB.
- Gain has to be entered as a negative value, and attenuation as a positive value.

Remote command:

`[SENSe:]CORRection:TRANsducer:DATA` on page 915

Insert Value

Inserts a data point in the transducer line above the selected one in the "Edit Transducer" dialog box.

Delete Value

Deletes the selected data point in the "Edit Transducer" dialog box.

Shift x

Shifts the x-value of each data point horizontally by the defined shift width.

Shift y

Shifts the y-value of each data point vertically by the defined shift width.

Save

Saves the currently edited transducer line under the name defined in the "Name" field.

Remote command:

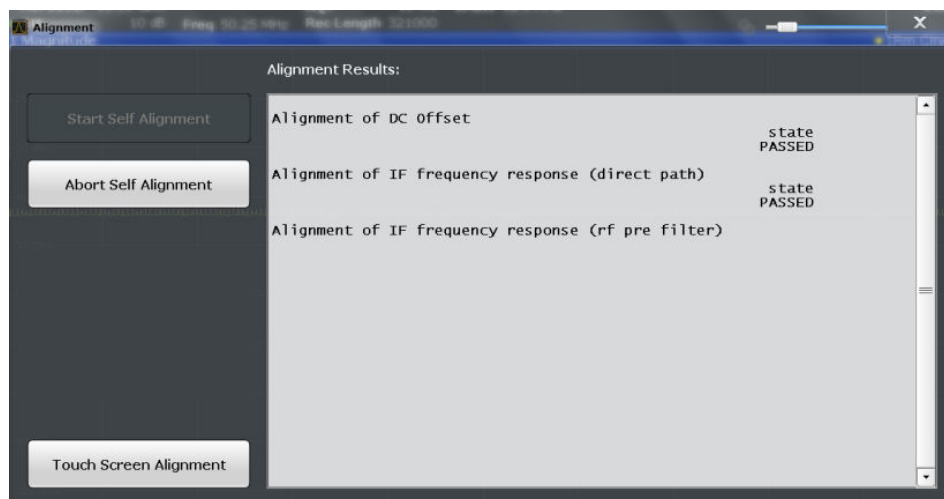
[MMEMory:SELEct\[:ITEM\]:TRANsducer:ALL](#) on page 890

[MMEMory:STORe<n>:STATe](#) on page 893

9.3.3 Alignment Settings

The instrument can be aligned when necessary (see [chapter 9.1, "Basics on Alignment"](#), on page 505).

The alignment settings are defined in the "Alignment" dialog box which is displayed when you press the SETUP key and then select "Alignment".





Self-alignment results in secure user mode

Be sure to store self-alignment results before [Secure User Mode](#) is enabled; see [chapter 3.1.6, "Protecting Data Using the Secure User Mode"](#), on page 30.

If the currently stored self-alignment results are not suitable, you must perform a self-alignment each time you switch on the R&S FPS in secure user mode, as the results are not stored permanently in this case.

Starting a Self-alignment	515
Aborting the Self-alignment	515
Alignment Results	515

Starting a Self-alignment

Starts recording correction data for the instrument. If the correction data acquisition fails or if the correction values are deactivated, a corresponding message is displayed in the status field.

For details see [chapter 9.1, "Basics on Alignment"](#), on page 505.

Note:

A running Sequencer operation is aborted when you start a self-alignment.

Remote command:

[*CAL?](#) on page 589, see also [CALibration\[:ALL\]?](#) on page 911

Aborting the Self-alignment

As long as the self-alignment data is being collected the procedure can be cancelled using the "Abort Self-alignment" button.

Alignment Results

Information on whether the alignment was performed successfully and on the applied correction data is displayed. The results are available until the next self-alignment process is started or the instrument is switched off.

Remote command:

[CALibration:RESult?](#) on page 911

9.3.4 System Configuration Settings

The system configuration information and settings are provided in the "System Configuration" dialog box which is displayed when you press the SETUP key and then select "System Configuration".

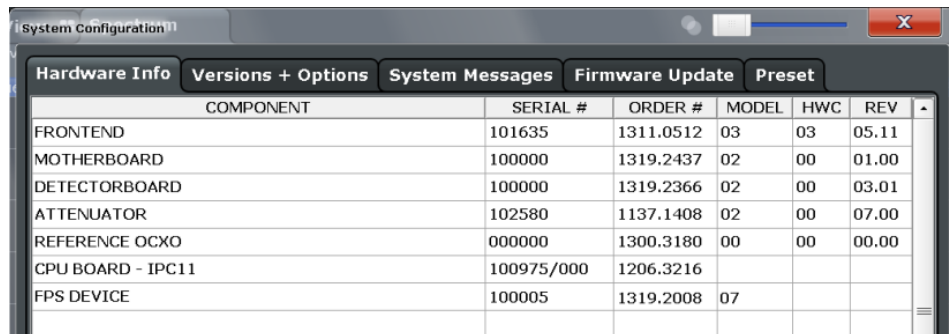
• Hardware Information	516
• Information on Versions and Options	516
• System Messages	518
• Firmware Updates	519
• General Configuration Settings	520

9.3.4.1 Hardware Information

An overview of the installed hardware in your R&S FPS is provided in the "Hardware Info" tab of the "System Configuration" dialog box.

Every listed component is described by its serial number, order number, model information, hardware code, and hardware revision.

This information can be useful when problems occur with the instrument and you require support from Rohde & Schwarz.



COMPONENT	SERIAL #	ORDER #	MODEL	HWC	REV
FRONTEND	101635	1311.0512	03	03	05.11
MOTHERBOARD	100000	1319.2437	02	00	01.00
DETECTORBOARD	100000	1319.2366	02	00	03.01
ATTENUATOR	102580	1137.1408	02	00	07.00
REFERENCE OCXO	000000	1300.3180	00	00	00.00
CPU BOARD - IPC11	100975/000	1206.3216			
FPS DEVICE	100005	1319.2008	07		



You can obtain basic information on the instrument's hardware directly via the R&S FPS's mini display: navigate to "Info" and select the required information.

Remote command:

`DIAGnostic:SERVice:HWINfo?` on page 927

9.3.4.2 Information on Versions and Options

Information on the firmware version and options installed on your instrument is provided in the "Versions Options" tab of the "System Configuration" dialog box. The unique R&S device ID is also indicated here, as it is required for license and option administration.

You can also install new firmware options in this dialog box.



Installing options in secure user mode

Be sure to install any new options before [Secure User Mode](#) is enabled; see [chapter 3.1.6, "Protecting Data Using the Secure User Mode"](#), on page 30.

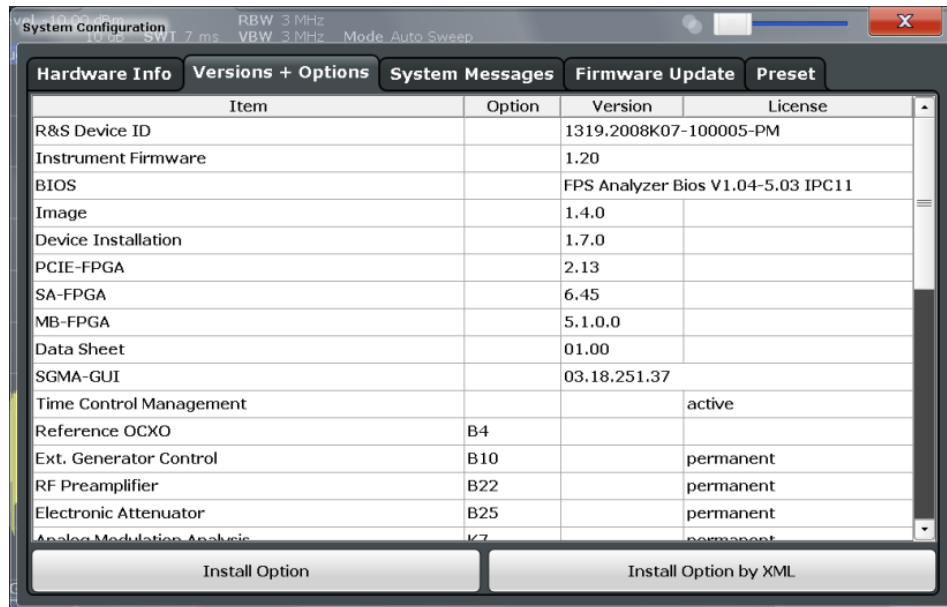
For restricted users in secure user mode, this function is not available!



Expired option licenses

If an option is about to expire, a message box is displayed to inform you. You can then use the "Install Option" function to enter a new license key.

If an option has already expired, a message box appears for you to confirm. In this case, all instrument functions are unavailable (including remote control) until the R&S FPS is rebooted. You must then use the "Install Option" function to enter the new license key.



For details on options refer to the "Getting Started" manual, "Checking the Supplied Items".

Remote commands:

[SYSTem:FORMat:IDENT](#) on page 930

[DIAGnostic:SERvice:BIOSinfo?](#) on page 927

[DIAGnostic:SERvice:VERSinfo?](#) on page 928

Install Option

Opens an edit dialog box to enter the license key for the option that you want to install. Only user accounts with administrator rights are able to install options.

Install Option by XML

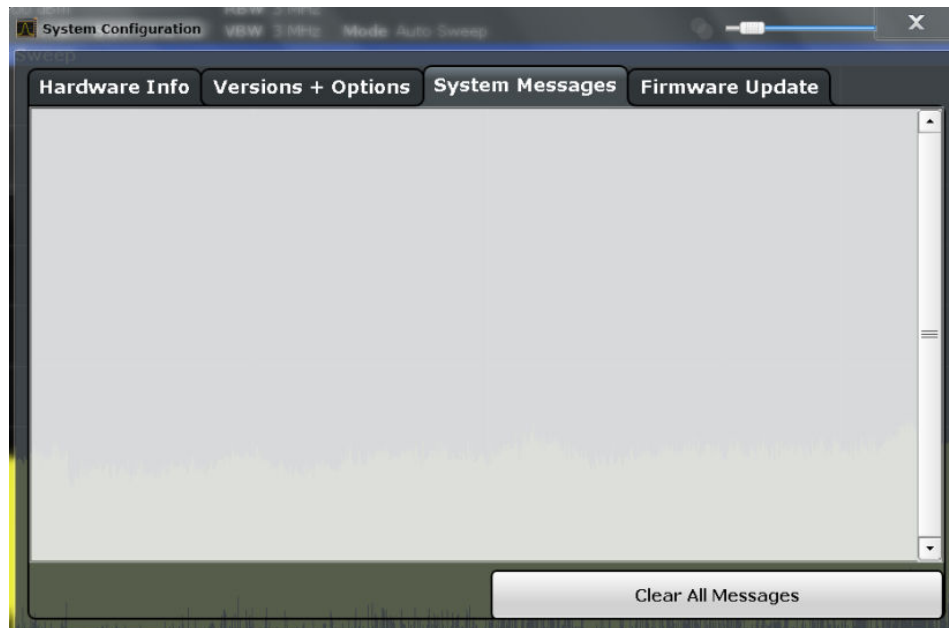
Opens a file selection dialog box to install an additional option to the R&S FPS using an XML file. Enter or browse for the name of an XML file that contains the option key and press "Select".

Only user accounts with administrator rights are able to install options.

9.3.4.3 System Messages

The system messages generated by the R&S FPS are displayed in the "System Messages" tab of the "System Configuration" dialog box.

The messages are displayed in the order of their occurrence; the most recent messages are placed at the top of the list. Messages that have occurred since you last visited the system messages tab are marked with an asterisk '*'.
 *'.



You can view the system messages directly via the R&S FPS's mini display: navigate to "System messages".

To clear the messages, navigate to "System commands" > "Clear messages".

If the number of error messages exceeds the capacity of the error buffer, "Message buffer overflow" is displayed. To clear the message buffer use the "Clear All Messages" button.

The following information is available:

No	device-specific error code
Message	brief description of the message
Component	hardware messages: name of the affected module
	software messages: name of the affected software
Date/Time	date and time of the occurrence of the message

Remote command:

`SYSTEM:ERRor:LIST?` on page 929

9.3.4.4 Firmware Updates

During instrument start, the installed hardware is checked against the current firmware version to ensure the hardware is supported. If not, an error message is displayed ("WRONG_FW") and you are asked to update the firmware. Until the firmware version is updated, self-alignment fails. To see which components are not supported, see the [System Messages](#).

The firmware on your R&S FPS may also need to be updated in order to enable additional new features or if reasons for improvement come up. Ask your sales representative or check the Rohde&Schwarz website for availability of firmware updates. A firmware update package includes at least a setup file and release notes.



Before updating the firmware on your instrument, read the release notes delivered with the firmware version.

As of firmware version 1.60, administrator rights are no longer required to perform a firmware update.

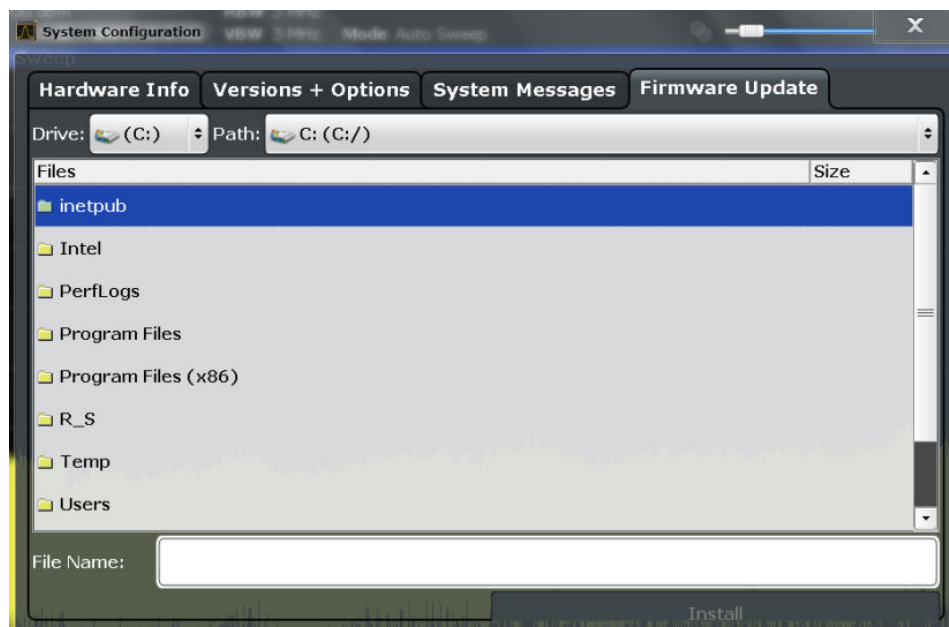


Installing options in secure user mode

Be sure to perform any firmware updates before [Secure User Mode](#) is enabled; see [chapter 3.1.6, "Protecting Data Using the Secure User Mode"](#), on page 30.

For restricted users in secure user mode, this function is not available!

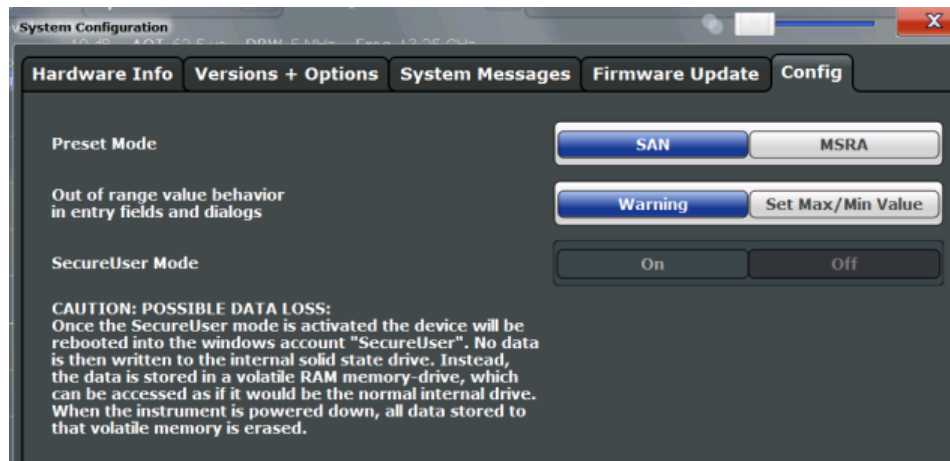
The firmware can be updated in the "Firmware Update" tab of the "System Configuration" dialog box.



Enter the name or browse for the firmware installation file and press the "Install" button.

9.3.4.5 General Configuration Settings

General system settings, for example concerning the initial behaviour of the R&S FPS after booting, are configured in the "Config" tab of the "System Configuration" dialog box.



Preset Mode.....	520
Out-of-range value behavior.....	520
Secure User Mode.....	520
└ Changing the password.....	521

Preset Mode

The default operating mode is Signal and Spectrum Analyzer mode, however, the pre-setting can be changed. The defined operating mode is activated when you switch on the R&S FPS or press the PRESET key.

The presettings can be defined in the "Config" tab of the "System Configuration" dialog box.

For details on operating modes see [chapter 4, "Applications and Operating Modes"](#), on page 99.

- "SAN" Signal and Spectrum Analyzer mode
- "MSRA" Multi-Standard Radio Analysis mode

Remote command:
[SYSTem:PRESet:COMPAtible](#) on page 930

Out-of-range value behavior

By default, if you enter a value that is outside the valid range in an input field for a setting, a warning is displayed and the value is not accepted. Alternatively, entries below the minimum value can automatically be set to the minimum possible entry, and entries above the maximum value set to the maximum possible entry. This behavior avoids errors and facilitates setting correct values.

Secure User Mode

If activated, the R&S FPS requires a reboot and then automatically logs in using the "SecureUser" account.

Data that the R&S FPS normally stores on the solid-state drive is redirected to volatile memory instead. Data that is stored in volatile memory can be accessed by the user during the current instrument session; however, when the instrument's power is removed, all data in volatile memory is erased.

The Secure User Mode can only be activated or deactivated by a user with administrator rights.

Note: Storing instrument settings permanently. Before you activate secure user mode, store any instrument settings that are required beyond the current session, such as predefined instrument settings, transducer files, or self-alignment data.

For details on the secure user mode see [chapter 3.1.6, "Protecting Data Using the Secure User Mode"](#), on page 30.

Remote command:

`SYSTEM:SECURITY[:STATe]` on page 931

Note: Initially after installation of the R&S FPS-K33 option, secure user mode must be enabled manually once before remote control is possible.

Changing the password ← Secure User Mode

When the secure user mode is activated the first time after installation, you are prompted to change the passwords for all user accounts in order to improve system security.

To save the new password, select "Save". The password dialog for the next user is displayed, until you have been prompted to change the password all user accounts.

If you cancel the dialog without changing the password, the password dialog for the next user is displayed, until you have been prompted to change the password all user accounts. Although it is possible to continue in secure user mode without changing the passwords (and you will not be prompted to do so again), it is strongly recommended that you do define a more secure password for all users.

By default, the password characters are not displayed to ensure confidentiality during input. To display the characters, select "Show password".

To display the onscreen keyboard, select "Keyboard".

9.3.5 Service Functions

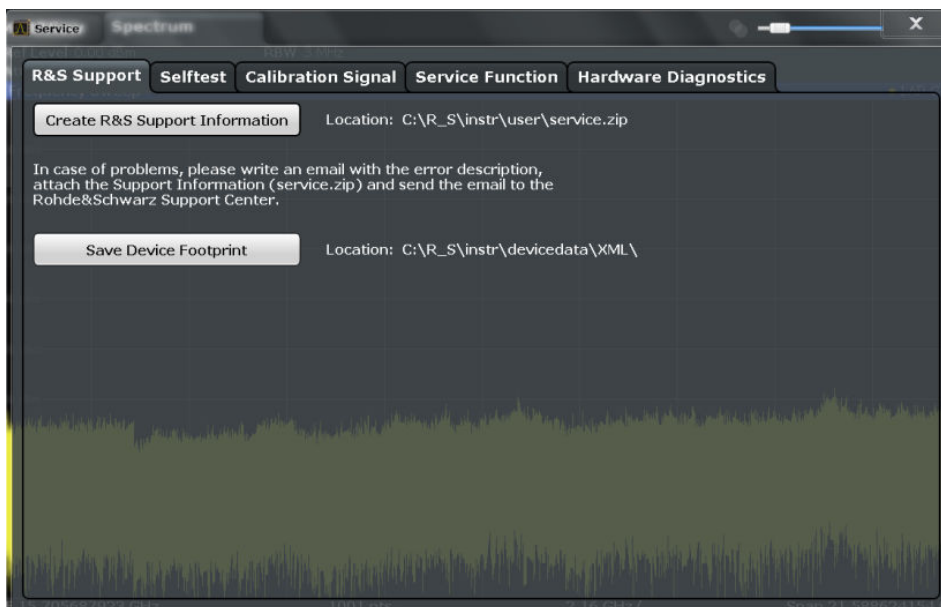
When unexpected problems arise with the R&S FPS some service functions may help you solve them.

The service functions are available in the "Service" dialog box which is displayed when you press the SETUP key and then select "Service".

- [R&S Support Information](#)..... 522
- [Selftest Settings and Results](#)..... 523
- [Calibration Signal Display](#)..... 524
- [Service Functions](#)..... 526
- [Hardware Diagnostics](#)..... 527

9.3.5.1 R&S Support Information

In case of errors you can store useful information for troubleshooting and send it to your Rohde & Schwarz support center.



- [Creating R&S Support Information](#)..... 522
- [Save Device Footprint](#)..... 523

Creating R&S Support Information

Creates a *.zip file with important support information. The *.zip file contains the system configuration information ("device footprint"), the current eeprom data and a screenshot of the screen display.

This data is stored to the C:\R_S\Instr\user\ directory on the instrument.

The file name consists of the unique device ID and the current date and time of the file creation.

If you contact the Rohde&Schwarz support to get help for a certain problem, send these files to the support in order to identify and solve the problem faster.

Remote command:

[DIAGnostic:SERvice:SINfo?](#) on page 933

Save Device Footprint

Creates an *.xml file with information on installed hardware, software, image and FPGA versions. The *.xml file is stored under `C:\R_S\Instr\devicedata\xml\` on the instrument. It is also included in the `service.zip` file.

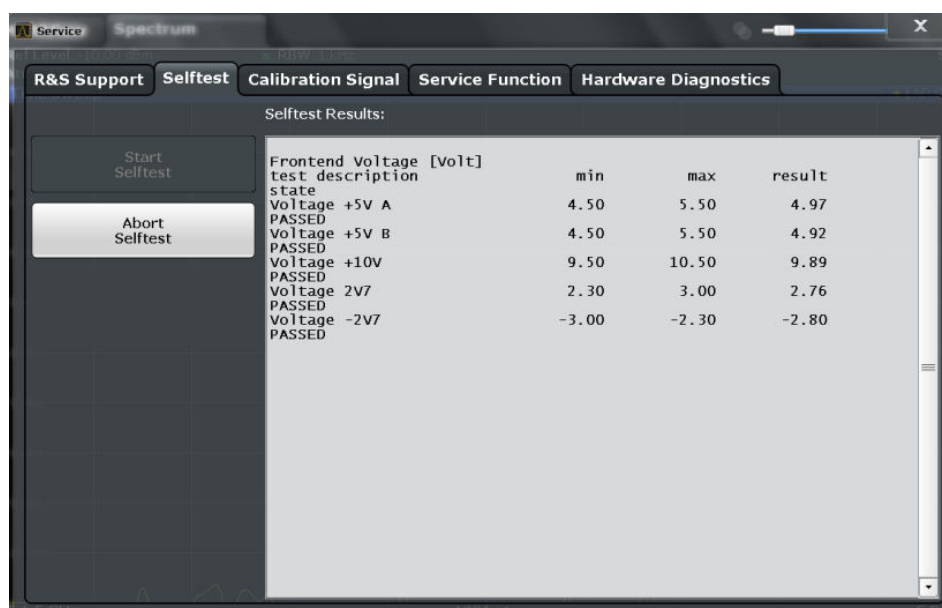
9.3.5.2 Selftest Settings and Results

If the R&S FPS fails you can perform a self test of the instrument to identify any defective modules.

The selftest settings and results are available in the "Selftest" tab of the "Service" dialog box.



You can perform a selftest directly via the R&S FPS's mini display: navigate to "System commands" > "Selftest".



Once the self test is started, all modules are checked consecutively and the test result is displayed. You can abort a running test.

In case of failure a short description of the failed test, the defective module, the associated value range and the corresponding test results are indicated.



A running Sequencer process is aborted when you start a self-alignment.

Remote command:

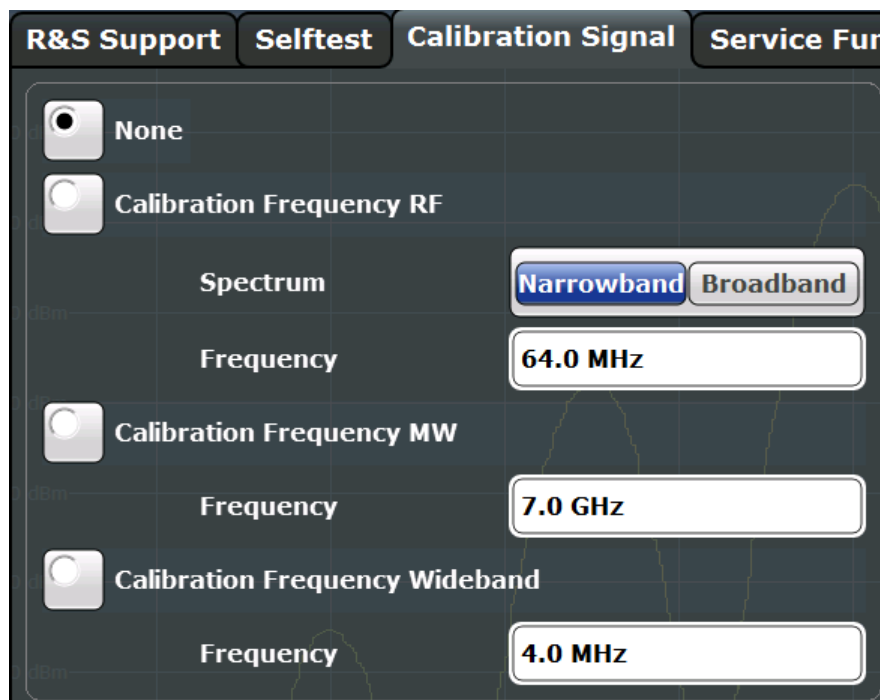
*TST? on page 592

DIAGnostic:SERVice:STEst:RESult? on page 913

9.3.5.3 Calibration Signal Display

Alternatively to the RF input signal from the front panel connector you can use the instrument's calibration signal as the input signal, for example to perform service functions on.

The calibration signal settings are available in the "Calibration Signal" tab of the "Service" dialog box.



None.....	524
Calibration Frequency RF.....	525
L Spectrum.....	525
L Frequency.....	525
Calibration Frequency MW.....	525
Calibration Frequency Wideband.....	525

None

Uses the current RF signal at the input, i.e. no calibration signal (default).

Remote command:

DIAGnostic:SERVice:INPut[:SElect] on page 913

Calibration Frequency RF

Uses the internal calibration signal as the RF input signal.

Remote command:

[DIAGnostic:SERVice:INPut\[:SElect\]](#) on page 913

[DIAGnostic:SERVice:INPut:PULSed:CFrequency](#) on page 912

Spectrum ← Calibration Frequency RF

Defines whether a broadband or narrowband calibration signal is sent to the RF input.

"Narrowband" Used to calibrate the absolute level of the frontend at 64 MHz.

"Broadband" Used to calibrate the IF filter.

Remote command:

[DIAGnostic:SERVice:INPut:RF:SPECTrum](#) on page 913

Frequency ← Calibration Frequency RF

Defines the frequency of the internal broadband calibration signal to be used for IF filter calibration (max. 64 MHz). For narrowband signals, 64 MHz is sent.

Calibration Frequency MW

Uses the microwave calibration signal as the RF input (for frequencies greater than 7 GHz; for R&S FPS13/30/40 only). The microwave calibration signal is pulsed. This function is used to calibrate the YIG-filter on the microwave converter.

Remote command:

[DIAGnostic:SERVice:INPut\[:SElect\]](#) on page 913

[DIAGnostic<n>:SERVice:INPut:PULSed:MCFrequency](#) on page 912

Calibration Frequency Wideband

Defines the frequency of the internal broadband calibration signal to be used for IF filter calibration.

If you define a frequency that is not available, the R&S FPS uses the next available frequency.

Tip: Use the arrow keys to step through the available frequencies.

This function is only available if the bandwidth extension option R&S FPS-B160 is installed and no other restrictions for its use apply.

See the R&S FPS I/Q Analyzer and I/Q Input User Manual

Remote command:

[DIAGnostic:SERVice:INPut\[:SElect\]](#) on page 913

[DIAGnostic:SERVice:INPut:PULSed:WBFrequency](#) on page 912

9.3.5.4 Service Functions

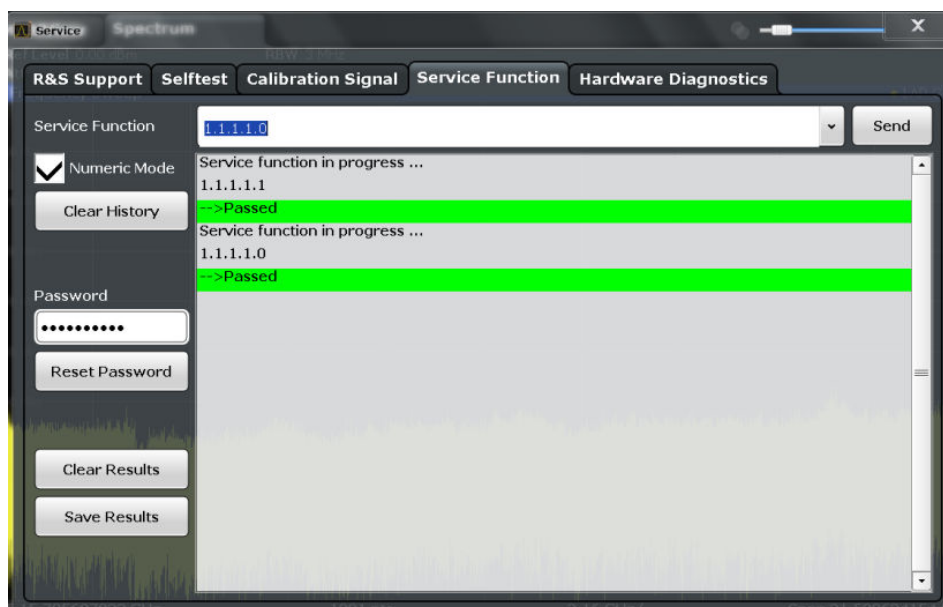
NOTICE

Using service functions

The service functions are not necessary for normal measurement operation. Incorrect use can affect correct operation and/or data integrity of the R&S FPS.

Therefore, only user accounts with administrator rights can use service functions and many of the functions can only be used after entering a password. These functions are described in the instrument service manual.

The service functions are available in the "Service Function" tab of the "Service" dialog box.



Service Function.....	526
Numeric Mode.....	527
Send.....	527
Clear History.....	527
Password.....	527
Clear Results.....	527
Save Results.....	527
Result List.....	527

Service Function

Selects the service function by its numeric code or textual name.

The selection list includes all functions previously selected (since the last "Clear History" action).

Remote command:

`DIAGnostic:SERvice:SFUNction` on page 932

Numeric Mode

If activated, the service function is selected by its numeric code. Otherwise, the function is selected by its textual name.

Send

Starts the selected service function.

Remote command:

[DIAGnostic:SERVice:SFUNction](#) on page 932

Clear History

Deletes the list of previously selected service functions.

Password

Most service functions require a special password as they may disrupt normal operation of the R&S FPS. There are different levels of service functions, depending on how restrictive their use is handled. Each service level has a different password.

"Reset Password" returns to the lowest (least restrictive) service level.

Clear Results

Clears the result display for all previously performed service functions.

Remote command:

[DIAGnostic:SERVice:SFUNction:RESults:DELeTe](#) on page 932

Save Results

Opens a file selection dialog box to save the results of all previously performed service functions to a file.

Remote command:

[DIAGnostic:SERVice:SFUNction:RESults:SAVE](#) on page 932

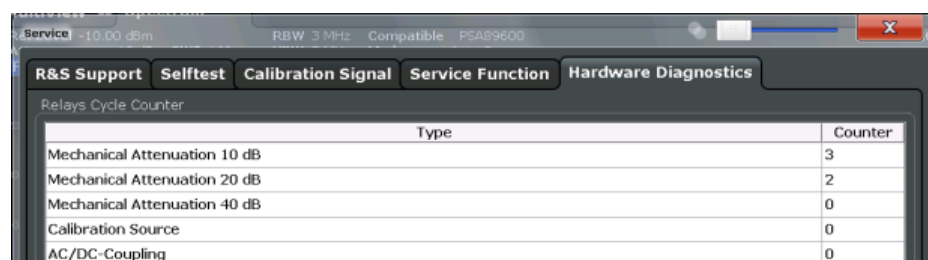
Result List

The Results List indicates the status and results of the executed service functions.

9.3.5.5 Hardware Diagnostics

In case problems occur with the instrument hardware, some diagnostic tools provide information that may support troubleshooting.

The hardware diagnostics tools are available in the "Hardware Diagnostics" tab of the "Service" dialog box.



Type	Counter
Mechanical Attenuation 10 dB	3
Mechanical Attenuation 20 dB	2
Mechanical Attenuation 40 dB	0
Calibration Source	0
AC/DC-Coupling	0

9.4 Display Settings

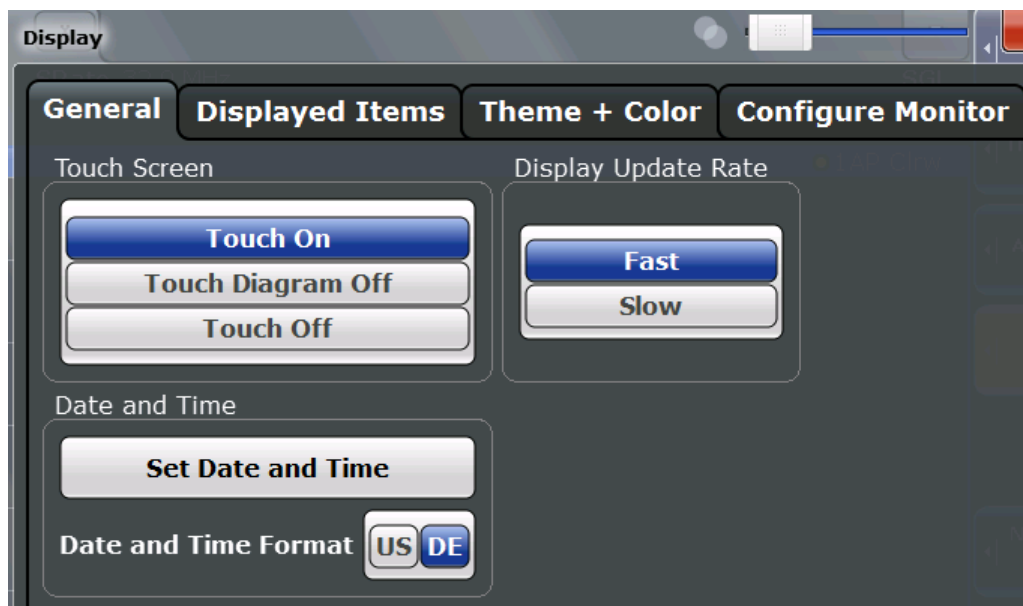
Some general display settings are available regardless of the current application or operating mode. For information on optimizing your display for measurement results see [chapter 7.1, "Result Display Configuration"](#), on page 385.

The general display settings are defined in the "Display" dialog box which is displayed when you press the SETUP key and then select "Display".

- [General Display Settings](#).....528
- [Displayed Items](#).....529
- [Display Theme and Colors](#).....532

9.4.1 General Display Settings

This section includes general screen display behavior and date and time display. These settings are available in the "General" tab of the "Display" dialog box.



- [Display Update Rate](#)..... 528
- [Setting the Date and Time](#)..... 529
- [Date and Time Format](#)..... 529

Display Update Rate

By default, a fast update rate ensures the most recent measurement results on the display. However, when performance is poor due to slow data transfer (for example during remote control), it may be helpful to decrease the frequency with which the screen display is updated.

Setting the Date and Time

The current date and time on the instrument is set using the standard Windows "Date and Time Properties" dialog box which is displayed when you select the "Set Date and Time" button in the "Display" dialog box, or when you select the date and time display in the status bar.

Date and Time Format

Switches the time and date display on the screen between US and German (DE) format.

Remote command:

`DISPlay[:WINDow]:TIME:FORMat` on page 919

9.4.2 Displayed Items

Several elements on the screen display can be hidden or shown as required, for example to enlarge the display area for the measurement results. These settings are available in the "Displayed Items" tab of the "Display" dialog box.



Toolbar.....	530
Status Bar.....	530
Softkey Bar.....	530
Channel Bar.....	530
Diagram Footer (Annotation).....	530

Date and Time.....	530
Front Panel.....	531
Mini Front Panel.....	531

Toolbar

The toolbar provides access to frequently used functions via icons at the top of the screen. Some functions, such as zooming, finding help, printing screenshots or storing and loading files are not accessible at all without the toolbar.

Remote command:

`DISPlay:TBAR[:STATe]` on page 919

Status Bar

The status bar beneath the diagram indicates the global instrument settings, the instrument status and any irregularities during measurement or display.

Some of the information displayed in the status bar can be queried from the status registry via remote commands, see [chapter 11, "Remote Commands"](#), on page 587.

Remote command:

`DISPlay:SBAR[:STATe]` on page 918

Softkey Bar

Softkeys are virtual keys provided by the software. Thus, more functions can be provided than those that can be accessed directly via the function keys on the device.

The functions provided by the softkeys are often also available via dialog boxes. However, some functions may not be accessible at all without the softkey bar.

Note: The softkey bar is hidden while the SmartGrid is displayed and restored automatically when the SmartGrid is closed.

Remote command:

`DISPlay:SKEYs[:STATe]` on page 918

Channel Bar

The channel bar provides information on firmware and measurement settings for a specific measurement channel.

Remote command:

`DISPlay:ANNotation:CBAR` on page 918

Diagram Footer (Annotation)

The diagram footer beneath the diagram contains information on the x-axis of the diagram display, such as the current center frequency and span settings, the displayed span per division and the number of sweep points.

Remote command:

`DISPlay:ANNotation:FREQuency` on page 918

Date and Time

The date and time display can be switched off independently of the status bar.

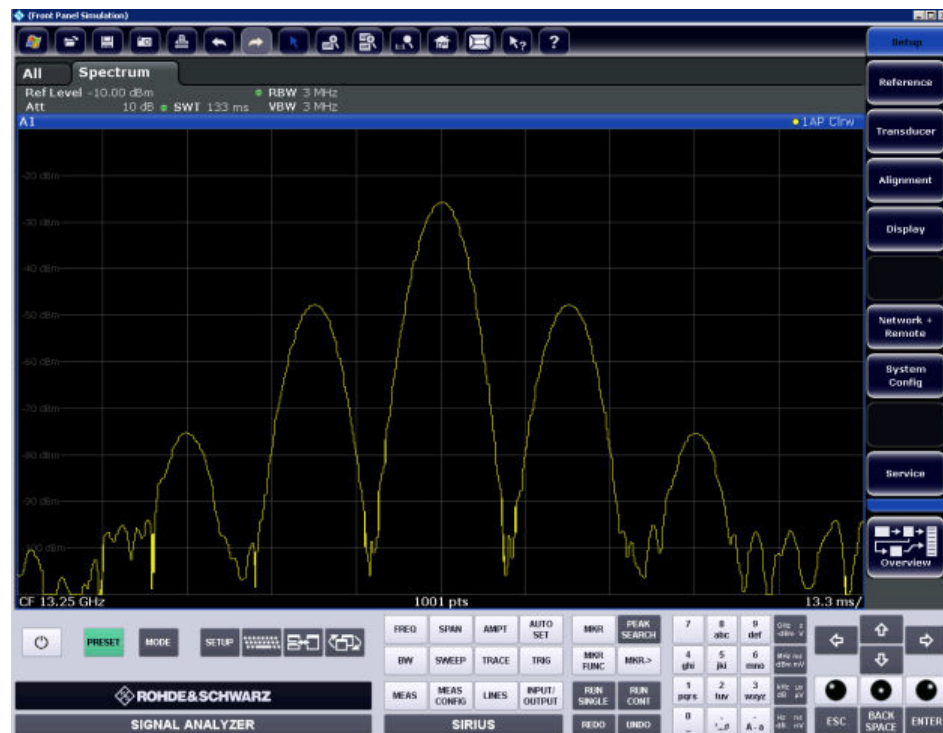
You can set the current date and time and configure the display format in the "General" tab of the "Display" dialog box.

Remote command:

[DISPlay\[:WINDow\]:TIME](#) on page 919

Front Panel

The "Front Panel" display simulates the entire front panel of the device (except for the external connectors) on the screen. This allows you to interact with the R&S FPS without requiring the keypad and keys located on the front panel of the device. This is useful, for example, when working with an external monitor or operating via remote control from a computer.



To activate or deactivate the front panel temporarily, press the F6 key on the external keyboard (if available) or the remote computer.

For more information see [chapter 3.5.1.3, "Front Panels"](#), on page 73.

Remote command:

[SYSTem:DISPlay:FPANel\[:STATe\]](#) on page 919

Mini Front Panel

If you require a front panel display but do not want to lose too much space for results in the display area, a mini front panel is available. The mini version displays only the main function hardkeys in a separate window in the display area.



For more information see [chapter 3.5.1.3, "Front Panels"](#), on page 73.

Note:

You can also activate the Mini Front Panel using the key combination "ALT + m" (be aware of the keyboard language defined in the operating system!). This is useful when you are working from a remote PC and the Front Panel function is not active.

Remote command:

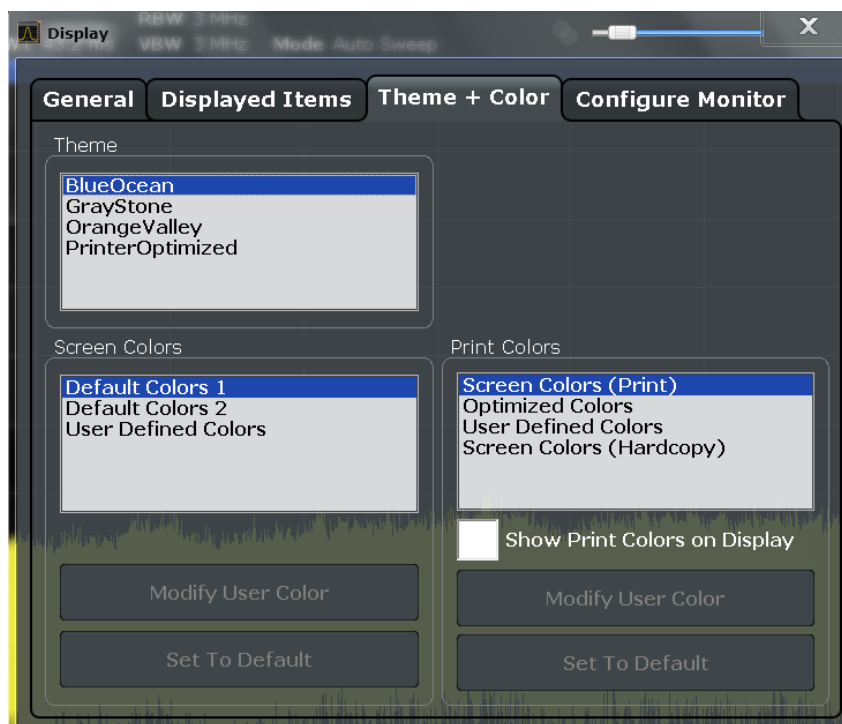
[SYSTEM:DISPlay:FPANel\[:STATe\]](#) on page 919

9.4.3 Display Theme and Colors

You can configure the used colors and styles of display elements on the screen.

These settings are available in the "Theme + Color" tab of the "Display" dialog box.

For step-by-step instructions see [chapter 9.6.6, "How to Configure the Colors for Display and Printing"](#), on page 541.



Theme..... 533

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Theme

The theme defines the colors and style used to display softkeys and other screen objects.

The default theme is "BlueOcean".

Remote command:

`DISPlay:THEMe:SElect` on page 921

Screen colors

Two different color sets are provided by the instrument, a third user-defined set can be configured.

The default color schemes provide optimum visibility of all screen objects when regarding the screen from above or below. Default setting is "Default Colors 1".

If "User Defined Colors" is selected, a user-defined color set can be defined (see ["Defining User-specific Colors"](#) on page 535).

Remote command:

`DISPlay:CMAP<item>:DEFault<colors>` on page 920

Print colors

Defines the color settings used for printout. In addition to the predefined settings, a user-defined color set can be configured (see ["Defining User-specific Colors"](#) on page 535).

If "Show Print Colors on Display" is activated, the currently selected print colors are displayed as a preview for your selection.

Optimized Colors	Selects an optimized color setting for the printout to improve the visibility of the colors (default setting). Trace 1 is blue, trace 2 black, trace 3 green, and the markers are turquoise. The background is always printed in white and the grid in black.
Screen Colors (Print)	Selects the current screen colors for the printout. The background is always printed in white and the grid in black.
Screen Colors (Hardcopy)	Selects the current screen colors without any changes for a hard-copy.
User Defined Colors	Selects the user-defined color setting.

Remote command:

`HCOPY:CMAP<item>:DEFault<colors>` on page 896

Showing Print Colors on Display

Temporarily shows the currently selected print colors on the screen display. This function can be used as a preview for printing.

Modifying User-Defined Color Assignments

You can configure the colors used to display and print individual screen objects according to your specific requirements.

The colors are configured in the (identical) "Screen Color Setup"/"Printer Color Setup" dialog boxes.



Selecting the Object ← Modifying User-Defined Color Assignments

Selects the object for which the color is to be defined. Colors can be defined for the following objects:

- Background
- Grid
- Individual traces
- Display lines
- Limit lines and check results
- Markers and marker information

Remote command:

Each object is assigned to a specific suffix of the CMAP commands, see [chapter 11.10.4.3, "CMAP Suffix Assignment"](#), on page 922.

Predefined Colors ← Modifying User-Defined Color Assignments

Displays the available colors from the predefined color set that can be used for the selected object.

Remote command:

[HCOPY:CMAP<item>:PDEFined](#) on page 897

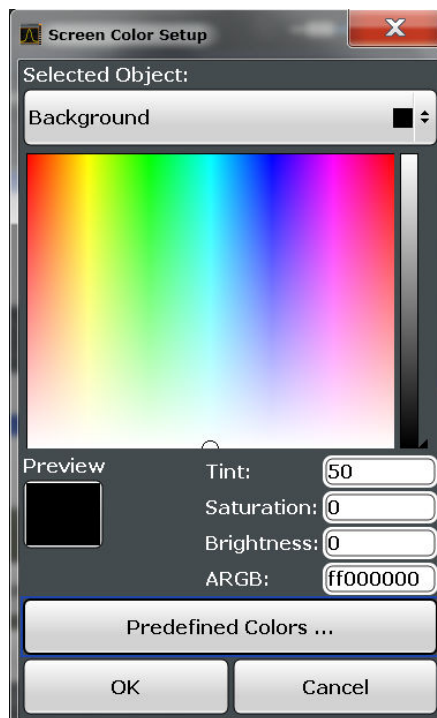
Preview ← Modifying User-Defined Color Assignments

Indicates the currently selected color that will be used for the selected object.

Defining User-specific Colors

In addition to the colors in the predefined color set you can configure a user-specific color to be used for the selected object.

When you select "Userdefined Colors", the set of predefined colors is replaced by a color palette and color configuration settings.



The color palette allows you to select the color directly. The color settings allow you to define values for tint, saturation and brightness.

Remote command:

[HCOpy:CMAP<item>:HSL](#) on page 897

Restoring the User Settings to Default Colors

In addition to the predefined color settings, a user-defined setting can be configured. By default, the same settings as defined in "Default Colors 1" are used. They can then be modified according to user-specific requirements (see "[Modifying User-Defined Color Assignments](#)" on page 534).

The "Set to Default" function restores the original default settings for the user-defined color set. You can select which of the three default settings are restored.

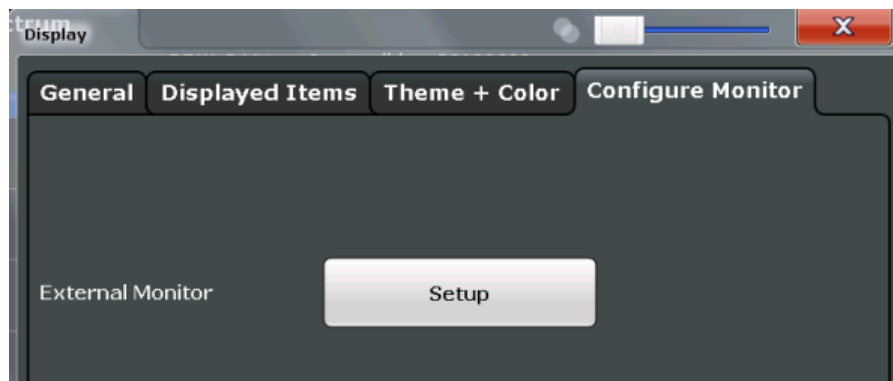
Remote command:

[DISPlay:CMAP<item>:PDEFined](#) on page 921

9.5 External Monitor Settings

You can connect an external monitor (or projector) to the DVI or DISPLAY PORT connector on the instrument's rear panel (see the R&S FPS Getting Started manual).

Which display device is used by the instrument is configured in the "Configure Monitor" tab of the "Display" dialog box.



[External Monitor Setup](#).....537

External Monitor Setup

Opens the standard Windows configuration dialog box for external monitors.

9.6 How to Configure the Basic Instrument Settings

The following step-by-step instructions demonstrate how to configure the basic instrument settings. For details on individual functions and settings see [chapter 9.3, "General Instrument Settings"](#), on page 507.



Some of the following settings and functions are also available directly on the R&S FPS, via the miniature display. See [chapter 3.3, "Miniature Display"](#), on page 39.

The remote commands required to perform these tasks are described in [chapter 9.3, "General Instrument Settings"](#), on page 507.

9.6.1 How to Perform a Self Test

The self test does not need to be repeated every time the instrument is switched on. It is only necessary when instrument malfunction is suspected.



Operating temperature

Before performing this functional test, make sure that the instrument has reached its operating temperature (for details, refer to the data sheet).

1. Press the SETUP key.
2. Press the "Service" softkey.

3. Press the "Selftest" softkey.

Once the instrument modules have been checked successfully, a message is displayed.

9.6.2 How to Align the Instrument



Operating temperature

Before performing this functional test, make sure that the instrument has reached its operating temperature (for details, refer to the data sheet).

To perform a self-alignment

1. Press the SETUP key.
2. Select the "Alignment" softkey.
3. Select the "Start Self-alignment" button.
4. To abort the self-alignment process, select the "Abort Self-alignment" button.

Once the system correction values have been calculated successfully, a message is displayed.



To display the alignment results again later

- Press the SETUP key.
- Press the "Alignment" softkey.

9.6.3 How to Install an R&S FPS Option

Additional options for the R&S FPS can be enabled using a license key. To obtain the license key, consult your sales representative. You need the device ID and serial number of your instrument to get a license key (see [chapter 9.3.4, "System Configuration Settings"](#), on page 515). No additional installation is required.

9.6.4 How to Update the Instrument Firmware

1. Download the update package from the Rohde&Schwarz website and store it on a memory stick, on the instrument, or on a server network drive that can be accessed by the instrument.
2. **NOTICE!** Stop measurement. The firmware update must not be performed during a running measurement.

If a measurement is running, stop it by pressing the highlighted RUN CONT or RUN SINGLE key.

3. Press the SETUP key.
4. Select the "Firmware Update" tab.
5. In the file selection dialog box select the `FPSSetup*.exe` file.
6. Select "Install" to start the update.
7. After the firmware update, the R&S FPS reboots automatically.
8. Depending on the previous firmware version, a reconfiguration of the hardware might be required during the first startup of the firmware. The reconfiguration starts automatically, and a message box informs you about the process. When the reconfiguration has finished, the instrument again reboots automatically.

Note: Do not switch off the instrument during the reconfiguration process!

Now the firmware update is complete. It is recommended that you perform a self-alignment after the update (see [chapter 9.6.2, "How to Align the Instrument"](#), on page 538).

9.6.5 How to Configure the Transducer

Configuring the transducer is very similar to configuring limit lines.

The transducer settings are defined in the "Transducer" dialog box which is displayed when you press the SETUP key and then select "Transducer".

The following tasks are described:

- ["How to find compatible transducer lines"](#) on page 539
- ["How to activate and deactivate a transducer"](#) on page 539
- ["How to edit existing transducer lines"](#) on page 540
- ["How to copy an existing transducer line"](#) on page 540
- ["How to delete an existing transducer line"](#) on page 540
- ["How to configure a new transducer line"](#) on page 540
- ["How to move the transducer line vertically or horizontally"](#) on page 541

How to find compatible transducer lines

- ▶ In the "Transducer" dialog box, select the "View filter" option: "Show compatible".

All transducer lines stored on the instrument that are compatible to the current measurement settings are displayed in the overview.

How to activate and deactivate a transducer

1. To activate a transducer select a transducer line in the overview and select the "Active" setting for it.

The trace is automatically recalculated for the next sweep after a transducer line is activated.

2. To deactivate a transducer line, deactivate the "Active" setting for it.

After the next sweep, the originally measured values are displayed.

How to edit existing transducer lines

Existing transducer line configurations can be edited.

1. In the "Transducer" dialog box, select the transducer line.
2. Select the "Edit" button.
3. Edit the line configuration as described in ["How to configure a new transducer line"](#) on page 540.
4. Save the new configuration by selecting the "Save" button.

The trace is automatically recalculated for the next sweep if the transducer line is active.

How to copy an existing transducer line

1. In the "Transducer" dialog box, select the transducer line.
2. Select the "Copy" button.
The "Edit Transducer" dialog box is opened with the configuration of the selected transducer.
3. Define a new name to create a new transducer with the same configuration as the source line.
4. Edit the line configuration as described in ["How to configure a new transducer line"](#) on page 540.
5. Save the new configuration by selecting the "Save" button.

The new transducer line is displayed in the overview and can be activated.

How to delete an existing transducer line

1. In the "Transducer" dialog box, select the transducer line.
2. Select the "Delete" button.
3. Confirm the message.

The transducer line is deleted. After the next sweep, the originally measured values are displayed.

How to configure a new transducer line

1. In the "Transducer" dialog box, select the "New" button.
The "Edit Transducer" dialog box is displayed. The current line configuration is displayed in the preview area of the dialog box. The preview is updated after each change to the configuration.
2. Define a "Name" and, optionally, a "Comment" for the new transducer line.
3. Define the scaling for the x-axis.

4. Define the data points: minimum 2, maximum 50:
 - a) Select "Insert Value".
 - b) Define the x-value ("Position") and y-value ("Value") of the first data point.
 - c) Select "Insert Value" again and define the second data point.
 - d) Repeat this to insert all other data points.
 - To insert a data point before an existing one, select the data point and then "Insert Value".
 - To insert a new data point at the end of the list, move the focus to the line after the last entry and then select "Insert Value".
 - To delete a data point, select the entry and then "Delete Value".
5. Check the current line configuration in the preview area of the dialog box. If necessary, correct individual data points or add or delete some.
 - If necessary, shift the entire line vertically or horizontally by selecting the "Shift x" or "Shift y" button and defining the shift width.
6. Save the new configuration by selecting the "Save" button.
 - The new transducer line is displayed in the overview and can be activated.

How to move the transducer line vertically or horizontally

A configured transducer line can easily be moved vertically or horizontally. Thus, a new transducer line can be easily generated based upon an existing transducer line which has been shifted.

1. In the "Line Config" dialog box, select the transducer line.
2. Select the "Edit" button.
3. In the "Edit transducer Line" dialog box, select the "Shift x" or "Shift y" button and define the shift width.
4. Save the shifted data points by selecting the "Save" button.
 - If activated, the trace is recalculated after the next sweep.

9.6.6 How to Configure the Colors for Display and Printing

You can configure the style and colors with which various screen objects are displayed or printed.

To select a color set

1. Press the SETUP key and select the "Display" softkey.
2. Select the "Theme + Color" tab.
3. In the "Screen Colors" area, select a predefined set of colors to be used for screen display, or select "User Defined Colors" to configure the color set yourself.
4. In the "Print Colors" area, select a predefined set of colors to be used for printing screenshots, or select "User Defined Colors" to configure the color set yourself.

Activate the "Show Print Colors on Display" option to see a preview of the print colors.

To configure a user-defined color set

1. In the "Theme + Color" tab of the "Display" dialog box select "User Defined Colors" either for the screen or the print colors.
2. Select "Modify User Color".
The "Screen Color Setup" dialog box is opened.
3. From the "Selected Object" list, select the object to which you want to assign a color.
4. Select a color from the "Predefined Colors" or select the "Userdefined Colors..." button to define a different color.
The "Preview" area indicates the currently selected color.
5. To assign a user-specific color to the selected object, do one of the following:
 - Select the color from the palette.
 - Enter values for the "Tint", "Saturation", and "Brightness".
Note: In the continuous color spectrum ("Tint") red is represented by 0% and blue by 100%.
 - Enter an "ARGB" value in hexadecimal format.
6. Select the next object to which you want to assign a color from the "Selected Object" list and assign a color as described.
Repeat these steps until all objects you want to configure have been assigned a color.
7. Select "OK" to close the dialog box and apply the colors to the assigned objects.

10 Network and Remote Operation

In addition to working with the R&S FPS interactively, located directly at the instrument, it is also possible to operate and control it from a remote PC. Various methods for remote control are supported:

- Connecting the instrument to a (LAN) network
- Using the LXI browser interface in a LAN network
- Using the Windows Remote Desktop application in a LAN network
- Connecting a PC via the GPIB interface

How to configure the remote control interfaces is described in [chapter 3.4, "Controlling the R&S FPS Remotely"](#), on page 47.

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10.1 Remote Control Basics

Basic information on operating an instrument via remote control is provided here. This information applies to all applications and operating modes on the R&S FPS.

See also [chapter 3.4.1, "Remote Control Interfaces and Protocols"](#), on page 48.

10.1.1 SCPI (Standard Commands for Programmable Instruments)

SCPI commands - messages - are used for remote control. Commands that are not taken from the SCPI standard follow the SCPI syntax rules. The R&S FPS supports the SCPI version 1999. The SCPI standard is based on standard IEEE 488.2 and aims at the standardization of device-specific commands, error handling and the status registers. The tutorial "Automatic Measurement Control - A tutorial on SCPI and IEEE 488.2" from John M. Pieper (R&S order number 0002.3536.00) offers detailed information on concepts and definitions of SCPI.

Tables provide a fast overview of the bit assignment in the status registers. The tables are supplemented by a comprehensive description of the status registers.

10.1.2 Messages

The messages transferred on the data lines are divided into the following categories:

- Interface messages
Interface messages are transmitted to the instrument on the data lines, with the attention line being active (LOW). They are used to communicate between the controller and the instrument. Interface messages can only be sent by instruments that have GPIB bus functionality. For details see the sections for the required interface.

- Instrument messages
Instrument messages are employed in the same way for all interfaces, if not indicated otherwise in the description. Structure and syntax of the instrument messages are described in [chapter 10.1.3, "SCPI Command Structure"](#), on page 544. A detailed description of all messages available for the instrument is provided in the chapter "Remote Control Commands".
There are different types of instrument messages, depending on the direction they are sent:
 - Commands
 - Instrument responses

Commands

Commands (program messages) are messages the controller sends to the instrument. They operate the instrument functions and request information. The commands are subdivided according to two criteria:

- According to the effect they have on the instrument:
 - **Setting commands** cause instrument settings such as a reset of the instrument or setting the frequency.
 - **Queries** cause data to be provided for remote control, e.g. for identification of the instrument or polling a parameter value. Queries are formed by directly appending a question mark to the command header.
- According to their definition in standards:
 - **Common commands**: their function and syntax are precisely defined in standard IEEE 488.2. They are employed identically on all instruments (if implemented). They refer to functions such as management of the standardized status registers, reset and self test.
 - **Instrument control commands** refer to functions depending on the features of the instrument such as frequency settings. Many of these commands have also been standardized by the SCPI committee. These commands are marked as "SCPI confirmed" in the command reference chapters. Commands without this SCPI label are device-specific; however, their syntax follows SCPI rules as permitted by the standard.

Instrument responses

Instrument responses (response messages and service requests) are messages the instrument sends to the controller after a query. They can contain measurement results, instrument settings and information on the instrument status.

10.1.3 SCPI Command Structure

SCPI commands consist of a so-called header and, in most cases, one or more parameters. The header and the parameters are separated by a "white space" (ASCII code 0 to 9, 11 to 32 decimal, e.g. blank). The headers may consist of several mnemonics (keywords). Queries are formed by appending a question mark directly to the header.

The commands can be either device-specific or device-independent (common commands). Common and device-specific commands differ in their syntax.

10.1.3.1 Syntax for Common Commands

Common (=device-independent) commands consist of a header preceded by an asterisk (*) and possibly one or more parameters.

Examples:

*RST	RESET	Resets the instrument.
*ESE	EVENT STATUS ENABLE	Sets the bits of the event status enable registers.
*ESR?	EVENT STATUS QUERY	Queries the contents of the event status register.
*IDN?	IDENTIFICATION QUERY	Queries the instrument identification string.

10.1.3.2 Syntax for Device-Specific Commands



Not all commands used in the following examples are necessarily implemented in the instrument.

For demonstration purposes only, assume the existence of the following commands for this section:

- DISPLAY[:WINDow<1...4>]:MAXimize <Boolean>
- FORMAT:READings:DATA <type>[,<length>]
- HCOpy:DEvice:COLor <Boolean>
- HCOpy:DEvice:CMAP:COLor:RGB <red>,<green>,<blue>
- HCOpy[:IMMediate]
- HCOpy:ITEM:ALL
- HCOpy:ITEM:LABel <string>
- HCOpy:PAGE:DIMensions:QUADrant [<N>]
- HCOpy:PAGE:ORientation LANDscape | PORTrait
- HCOpy:PAGE:SCALE <numeric value>
- MMEMory:COpy <file_source>,<file_destination>
- SENSE:BANDwidth|BWIDth[:RESolution] <numeric_value>
- SENSE:FREQuency:STOP <numeric value>
- SENSE:LIST:FREQuency <numeric_value>{,<numeric_value>}

Long and short form

The mnemonics feature a long form and a short form. The short form is marked by upper case letters, the long form corresponds to the complete word. Either the short form or the long form can be entered; other abbreviations are not permitted.

Example:

HCOPY:DEVIce:COLor ON is equivalent to HCOP:DEV:COL ON.

**Case-insensitivity**

Upper case and lower case notation only serves to distinguish the two forms in the manual, the instrument itself is case-insensitive.

Numeric suffixes

If a command can be applied to multiple instances of an object, e.g. specific channels or sources, the required instances can be specified by a suffix added to the command. Numeric suffixes are indicated by angular brackets (<1...4>, <n>, <i>) and are replaced by a single value in the command. Entries without a suffix are interpreted as having the suffix 1.

Example:

Definition: HCOpy:PAGE:DImentions:QUADrant [<N>]

Command: HCOP:PAGE:DIM:QUAD2

This command refers to the quadrant 2.

**Different numbering in remote control**

For remote control, the suffix may differ from the number of the corresponding selection used in manual operation. SCPI prescribes that suffix counting starts with 1. Suffix 1 is the default state and used when no specific suffix is specified.

Some standards define a fixed numbering, starting with 0. If the numbering differs in manual operation and remote control, it is indicated for the corresponding command.

Optional mnemonics

Some command systems permit certain mnemonics to be inserted into the header or omitted. These mnemonics are marked by square brackets in the description. The instrument must recognize the long command to comply with the SCPI standard. Some commands are considerably shortened by these optional mnemonics.

Example:

Definition: HCOpy[:IMMediate]

Command: HCOP:IMM is equivalent to HCOP



Optional mnemonics with numeric suffixes

Do not omit an optional mnemonic if it includes a numeric suffix that is relevant for the effect of the command.

Example:

Definition: `DISPlay[:WINDow<1...4>]:MAXimize <Boolean>`

Command: `DISP:MAX ON` refers to window 1.

In order to refer to a window other than 1, you must include the optional `WINDow` parameter with the suffix for the required window.

`DISP:WIND2:MAX ON` refers to window 2.

Parameters

Parameters must be separated from the header by a "white space". If several parameters are specified in a command, they are separated by a comma (.). For a description of the parameter types, refer to [chapter 10.1.3.3, "SCPI Parameters"](#), on page 548.

Example:

Definition: `HCOPy:DEVice:CMAP:COLor:RGB <red>,<green>,<blue>`

Command: `HCOP:DEV:CMAP:COL:RGB 3,32,44`

Special characters

	<p>Parameters</p> <p>A vertical stroke in parameter definitions indicates alternative possibilities in the sense of "or". The effect of the command differs, depending on which parameter is used.</p> <p>Example:</p> <p>Definition:HCOPy:PAGE:ORIENTATION LANDscape PORTRait</p> <p>Command HCOP:PAGE:ORI LAND specifies landscape orientation</p> <p>Command HCOP:PAGE:ORI PORT specifies portrait orientation</p> <p>Mnemonics</p> <p>A selection of mnemonics with an identical effect exists for several commands. These mnemonics are indicated in the same line; they are separated by a vertical stroke. Only one of these mnemonics needs to be included in the header of the command. The effect of the command is independent of which of the mnemonics is used.</p> <p>Example:</p> <p>DefinitionSENSE:BANDwidth BWIDTH[:RESolution] <numeric_value></p> <p>The two following commands with identical meaning can be created:</p> <p>SENS:BAND:RES 1</p> <p>SENS:BWID:RES 1</p>
[]	<p>Mnemonics in square brackets are optional and may be inserted into the header or omitted.</p> <p>Example: HCOPy[:IMMEDIATE]</p> <p>HCOP:IMM is equivalent to HCOP</p>
{ }	<p>Parameters in curly brackets are optional and can be inserted once or several times, or omitted.</p> <p>Example: SENSE:LIST:FREQUENCY <numeric_value>{,<numeric_value>}</p> <p>The following are valid commands:</p> <p>SENS:LIST:FREQ 10</p> <p>SENS:LIST:FREQ 10,20</p> <p>SENS:LIST:FREQ 10,20,30,40</p>

10.1.3.3 SCPI Parameters

Many commands are supplemented by a parameter or a list of parameters. The parameters must be separated from the header by a "white space" (ASCII code 0 to 9, 11 to 32 decimal, e.g. blank). Allowed parameters are:

- Numeric values
- Special numeric values
- Boolean parameters
- Text
- Character strings
- Block data

The parameters required for each command and the allowed range of values are specified in the command description.

Numeric values

Numeric values can be entered in any form, i.e. with sign, decimal point and exponent. Values exceeding the resolution of the instrument are rounded up or down. The mantissa may comprise up to 255 characters, the exponent must lie inside the value range -32000 to 32000. The exponent is introduced by an "E" or "e". Entry of the exponent alone is not allowed. In the case of physical quantities, the unit can be entered.

Allowed unit prefixes are G (giga), MA (mega), MOHM and MHZ (also allowed), K (kilo), M (milli), U (micro) and N (nano). If the unit is missing, the basic unit is used.

Example: `SENS:FREQ:STOP 1.5GHz = SENS:FREQ:STOP 1.5E9`

Units

For physical quantities, the unit can be entered. Allowed unit prefixes are:

- G (giga)
- MA (mega), MOHM, MHZ
- K (kilo)
- M (milli)
- U (micro)
- N (nano)

If the unit is missing, the basic unit is used.

Example:

`SENSe:FREQ:STOP 1.5GHz = SENSe:FREQ:STOP 1.5E9`

Some settings allow relative values to be stated in percent. According to SCPI, this unit is represented by the `PCT` string.

Example:

`HCOP:PAGE:SCAL 90PCT`

Special numeric values

The texts listed below are interpreted as special numeric values. In the case of a query, the numeric value is provided.

- **MIN/MAX**
MINimum and MAXimum denote the minimum and maximum value.
- **DEF**
DEFault denotes a preset value which has been stored in the EPROM. This value conforms to the default setting, as it is called by the `*RST` command.
- **UP/DOWN**
UP, DOWN increases or reduces the numeric value by one step. The step width can be specified via an allocated step command for each parameter which can be set via UP, DOWN.
- **INF/NINF**

INFinity, Negative INFinity (NINF) represent the numeric values 9.9E37 or -9.9E37, respectively. INF and NINF are only sent as instrument responses.

- **NAN**

Not A Number (NAN) represents the value 9.91E37. NAN is only sent as a instrument response. This value is not defined. Possible causes are the division of zero by zero, the subtraction of infinite from infinite and the representation of missing values.

Example:

Setting command: `SENSe:LIST:FREQ MAXimum`

Query: `SENS:LIST:FREQ?`, Response: `3.5E9`



Queries for special numeric values

The numeric values associated to `MAXimum`/`MINimum`/`DEFault` can be queried by adding the corresponding mnemonics to the command. They must be entered following the quotation mark.

Example: `SENSe:LIST:FREQ? MAXimum`

Returns the maximum numeric value as a result.

Boolean Parameters

Boolean parameters represent two states. The "ON" state (logically true) is represented by "ON" or a numeric value 1. The "OFF" state (logically untrue) is represented by "OFF" or the numeric value 0. The numeric values are provided as the response for a query.

Example:

Setting command: `HCOpy:DEV:COL ON`

Query: `HCOpy:DEV:COL?`

Response: `1`

Text parameters

Text parameters observe the syntactic rules for mnemonics, i.e. they can be entered using a short or long form. Like any parameter, they have to be separated from the header by a white space. In the case of a query, the short form of the text is provided.

Example:

Setting command: `HCOpy:PAGE:ORientation LANDscape`

Query: `HCOp:PAGE:ORI?`

Response: `LAND`

Character strings

Strings must always be entered in quotation marks (' or ").

Example:

```
HCOP:ITEM:LABel "Test1" or HCOP:ITEM:LABel 'Test1'
```

Block data

Block data is a format which is suitable for the transmission of large amounts of data. A command using a block data parameter has the following structure:

Example:

```
FORMat:READings:DATA #45168xxxxxxxx
```

The ASCII character # introduces the data block. The next number indicates how many of the following digits describe the length of the data block. In the example the 4 following digits indicate the length to be 5168 bytes. The data bytes follow. During the transmission of these data bytes all end or other control signs are ignored until all bytes are transmitted.

#0 specifies a data block of indefinite length. The use of the indefinite format requires a `NL^END` message to terminate the data block. This format is useful when the length of the transmission is not known or if speed or other considerations prevent segmentation of the data into blocks of definite length.

10.1.3.4 Overview of Syntax Elements

The following table provides an overview of the syntax elements:

:	The colon separates the mnemonics of a command. In a command line the separating semicolon marks the uppermost command level.
;	The semicolon separates two commands of a command line. It does not alter the path.
,	The comma separates several parameters of a command.
?	The question mark forms a query.
*	The asterisk marks a common command.
''	Quotation marks introduce a string and terminate it (both single and double quotation marks are possible).
#	The hash symbol introduces binary, octal, hexadecimal and block data. <ul style="list-style-type: none"> • Binary: #B10110 • Octal: #O7612 • Hexa: #HF3A7 • Block: #21312
	A "white space" (ASCII-Code 0 to 9, 11 to 32 decimal, e.g. blank) separates the header from the parameters.

10.1.3.5 Structure of a command line

A command line may consist of one or several commands. It is terminated by one of the following:

- a <New Line>
- a <New Line> with EOI
- an EOI together with the last data byte

Several commands in a command line must be separated by a semicolon ";". If the next command belongs to a different command system, the semicolon is followed by a colon.

Example:

```
MMEM: COPY "Test1", "MeasurementXY"; :HCOP: ITEM ALL
```

This command line contains two commands. The first command belongs to the MMEM system, the second command belongs to the HCOP system.

If the successive commands belong to the same system, having one or several levels in common, the command line can be abbreviated. To this end, the second command after the semicolon starts with the level that lies below the common levels. The colon following the semicolon must be omitted in this case.

Example:

```
HCOP: ITEM ALL; :HCOP: IMM
```

This command line contains two commands. Both commands are part of the HCOP command system, i.e. they have one level in common.

When abbreviating the command line, the second command begins with the level below HCOP. The colon after the semicolon is omitted. The abbreviated form of the command line reads as follows:

```
HCOP: ITEM ALL; IMM
```

A new command line always begins with the complete path.

Example:

```
HCOP: ITEM ALL
```

```
HCOP: IMM
```

10.1.3.6 Responses to Queries

A query is defined for each setting command unless explicitly specified otherwise. It is formed by adding a question mark to the associated setting command. According to SCPI, the responses to queries are partly subject to stricter rules than in standard IEEE 488.2.

- The requested parameter is transmitted without a header.
Example: `HCOP: PAGE: ORI?`, **Response:** `LAND`
- Maximum values, minimum values and all other quantities that are requested via a special text parameter are returned as numeric values.
Example: `SENSe: FREQuency: STOP? MAX`, **Response:** `3.5E9`

- Numeric values are output without a unit. Physical quantities are referred to the basic units or to the units set using the `Unit` command. The response `3.5E9` in the previous example stands for 3.5 GHz.
- Truth values (Boolean values) are returned as 0 (for OFF) and 1 (for ON).

Example:

Setting command: `HCOPY:DEV:COL ON`

Query: `HCOPY:DEV:COL?`

Response: 1

- Text (character data) is returned in a short form.

Example:

Setting command: `HCOPY:PAGE:ORIENTATION LANDscape`

Query: `HCOPY:PAGE:ORI?`

Response: LAND

10.1.4 Command Sequence and Synchronization

IEEE 488.2 defines a distinction between overlapped and sequential commands:

- A sequential command is one which finishes executing before the next command starts executing. Commands that are processed quickly are usually implemented as sequential commands.
- An overlapping command is one which does not automatically finish executing before the next command starts executing. Usually, overlapping commands take longer to process and allow the program to do other tasks while being executed. If overlapping commands do have to be executed in a defined order, e.g. in order to avoid wrong measurement results, they must be serviced sequentially. This is called synchronization between the controller and the instrument.

Setting commands within one command line, even though they may be implemented as sequential commands, are not necessarily serviced in the order in which they have been received. In order to make sure that commands are actually carried out in a certain order, each command must be sent in a separate command line.

Example: Commands and queries in one message

The response to a query combined in a program message with commands that affect the queried value is not predictable.

The following commands always return the specified result:

```
:FREQ:STAR 1GHZ;SPAN 100;:FREQ:STAR?
```

Result:

```
1000000000 (1 GHz)
```

Whereas the result for the following commands is not specified by SCPI:

```
:FREQ:STAR 1GHz;STAR?;SPAN 1000000
```

The result could be the value of `STARt` before the command was sent since the instrument might defer executing the individual commands until a program message terminator is received. The result could also be 1 GHz if the instrument executes commands as they are received.



As a general rule, send commands and queries in different program messages.

Example: Overlapping command with *OPC

The instrument implements `INITiate[:IMMEDIATE]` as an overlapped command. Assuming that `INITiate[:IMMEDIATE]` takes longer to execute than `*OPC`, sending the following command sequence results in initiating a sweep and, after some time, setting the `OPC` bit in the `ESR`:

```
INIT; *OPC.
```

Sending the following commands still initiates a sweep:

```
INIT; *OPC; *CLS
```

However, since the operation is still pending when the instrument executes `*CLS`, forcing it into the "Operation Complete Command Idle" State (OCIS), `*OPC` is effectively skipped. The `OPC` bit is not set until the instrument executes another `*OPC` command.

10.1.4.1 Preventing Overlapping Execution

To prevent an overlapping execution of commands, one of the commands `*OPC`, `*OPC?` or `*WAI` can be used. All three commands cause a certain action only to be carried out after the hardware has been set. By suitable programming, the controller can be forced to wait for the corresponding action to occur.

Table 10-1: Synchronization using *OPC, *OPC? and *WAI

Com-mand	Action	Programming the controller
*OPC	Sets the Operation Complete bit in the ESR after all previous commands have been executed.	<ul style="list-style-type: none"> Setting bit 0 in the ESE Setting bit 5 in the SRE Waiting for service request (SRQ)
*OPC?	Stops command processing until 1 is returned. This is only the case after the Operation Complete bit has been set in the ESR. This bit indicates that the previous setting has been completed.	Sending *OPC? directly after the command whose processing should be terminated before other commands can be executed.
*WAI	Stops further command processing until all commands sent before *WAI have been executed.	Sending *WAI directly after the command whose processing should be terminated before other commands are executed.

Command synchronization using `*WAI` or `*OPC?` appended to an overlapped command is a good choice if the overlapped command takes only little time to process. The two synchronization techniques simply block overlapped execution of the command.

For time consuming overlapped commands it is usually desirable to allow the controller or the instrument to do other useful work while waiting for command execution. Use one of the following methods:

*OPC with a service request

1. Set the OPC mask bit (bit no. 0) in the ESE: `*ESE 1`

2. Set bit no. 5 in the SRE: *SRE 32 to enable ESB service request.
3. Send the overlapped command with *OPC
4. Wait for a service request

The service request indicates that the overlapped command has finished.

***OPC? with a service request**

1. Set bit no. 4 in the SRE: *SRE 16 to enable MAV service request.
2. Send the overlapped command with *OPC?
3. Wait for a service request

The service request indicates that the overlapped command has finished.

Event Status Register (ESE)

1. Set the OPC mask bit (bit no. 0) in the ESE: *ESE 1
2. Send the overlapped command without *OPC, *OPC? or *WAI
3. Poll the operation complete state periodically (by means of a timer) using the sequence: *OPC; *ESR?

A return value (LSB) of 1 indicates that the overlapped command has finished.

***OPC? with short timeout**

1. Send the overlapped command without *OPC, *OPC? or *WAI
2. Poll the operation complete state periodically (by means of a timer) using the sequence: <short timeout>; *OPC?
3. A return value (LSB) of 1 indicates that the overlapped command has finished. In case of a timeout, the operation is ongoing.
4. Reset timeout to former value
5. Clear the error queue with `SYStem:ERRor?` to remove the "-410, Query interrupted" entries.

Using several threads in the controller application

As an alternative, provided the programming environment of the controller application supports threads, separate threads can be used for the application GUI and for controlling the instrument(s) via SCPI.

A thread waiting for a *OPC? thus will not block the GUI or the communication with other instruments.

10.1.5 Status Reporting System

The status reporting system stores all information on the current operating state of the instrument, and on errors which have occurred. This information is stored in the status registers and in the error queue. Both can be queried via GPIB bus or LAN interface (STATus... commands, see [chapter 11.11, "Using the Status Register"](#), on page 933).

- [Hierarchy of Status Registers](#)..... 556
- [Structure of a SCPI Status Register](#).....558
- [Contents of the Status Registers](#)..... 559
- [Application of the Status Reporting System](#).....570
- [Reset Values of the Status Reporting System](#).....572

10.1.5.1 Hierarchy of Status Registers

As shown in the following figure, the status information is of hierarchical structure.

& logic AND
 ⊕ logic OR of all bits
 *) one register for each channel

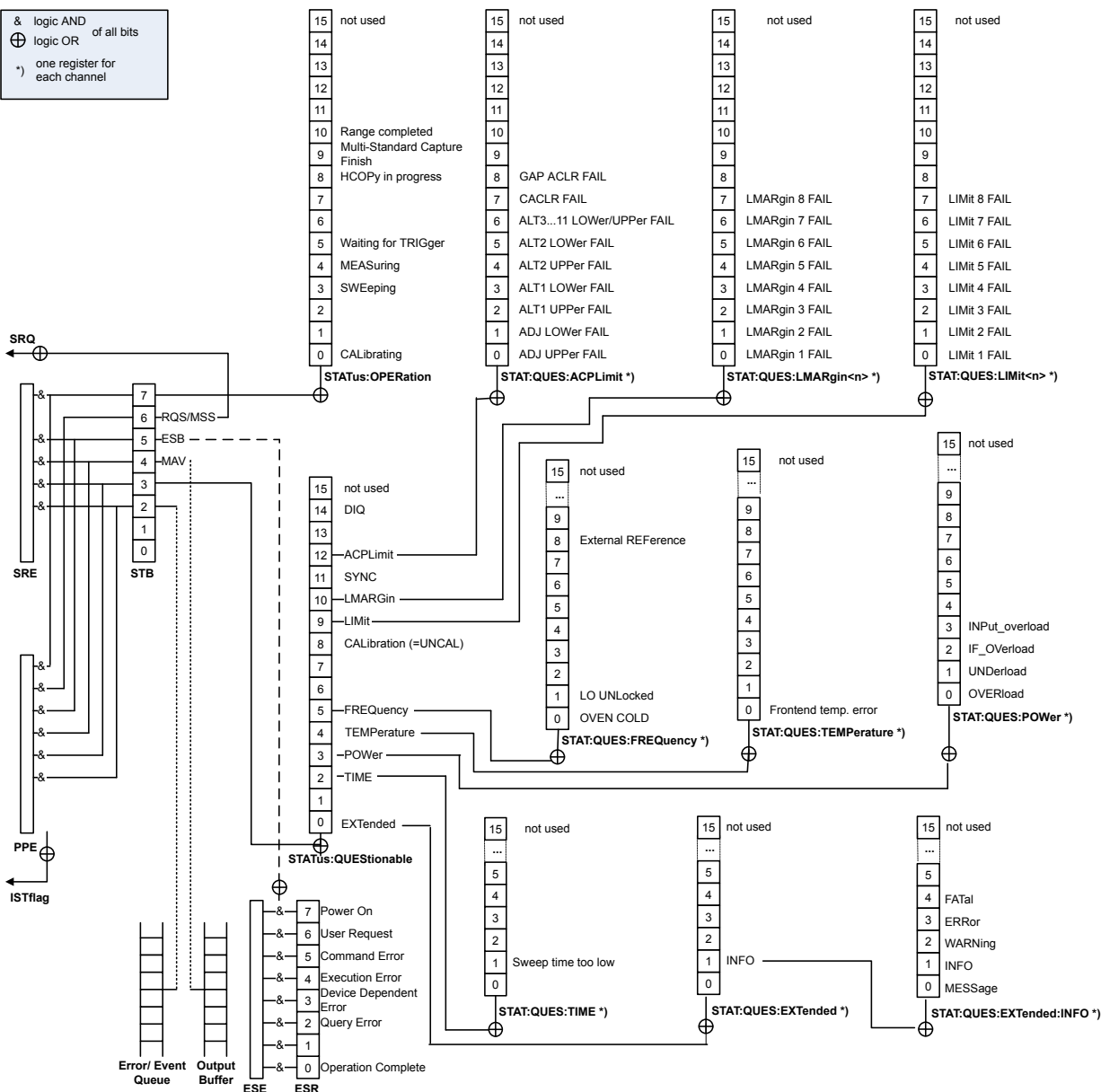


Fig. 10-1: Graphical overview of the R&S FPS status registers hierarchy

- **STB, SRE**
 The STatus Byte (STB) register and its associated mask register Service Request Enable (SRE) form the highest level of the status reporting system. The STB provides a rough overview of the instrument status, collecting the information of the lower-level registers.
- **ESR, SCPI registers**
 The STB receives its information from the following registers:
 - The Event Status Register (ESR) with the associated mask register standard Event Status Enable (ESE).
 - The STATus:OPERation and STATus:QUESTionable registers which are defined by SCPI and contain detailed information on the instrument.

- **IST, PPE**

The **IST** flag ("Individual Status"), like the **SRQ**, combines the entire instrument status in a single bit. The **PPE** fulfills the same function for the **IST** flag as the **SRE** for the service request.

- **Output buffer**

The output buffer contains the messages the instrument returns to the controller. It is not part of the status reporting system but determines the value of the **MAV** bit in the **STB** and thus is represented in the overview.

All status registers have the same internal structure.



SRE, ESE

The service request enable register **SRE** can be used as **ENABLE** part of the **STB** if the **STB** is structured according to **SCPI**. By analogy, the **ESE** can be used as the **ENABLE** part of the **ESR**.

10.1.5.2 Structure of a SCPI Status Register

Each standard SCPI register consists of 5 parts. Each part has a width of 16 bits and has different functions. The individual bits are independent of each other, i.e. each hardware status is assigned a bit number which is valid for all five parts. Bit 15 (the most significant bit) is set to zero for all parts. Thus the contents of the register parts can be processed by the controller as positive integers.

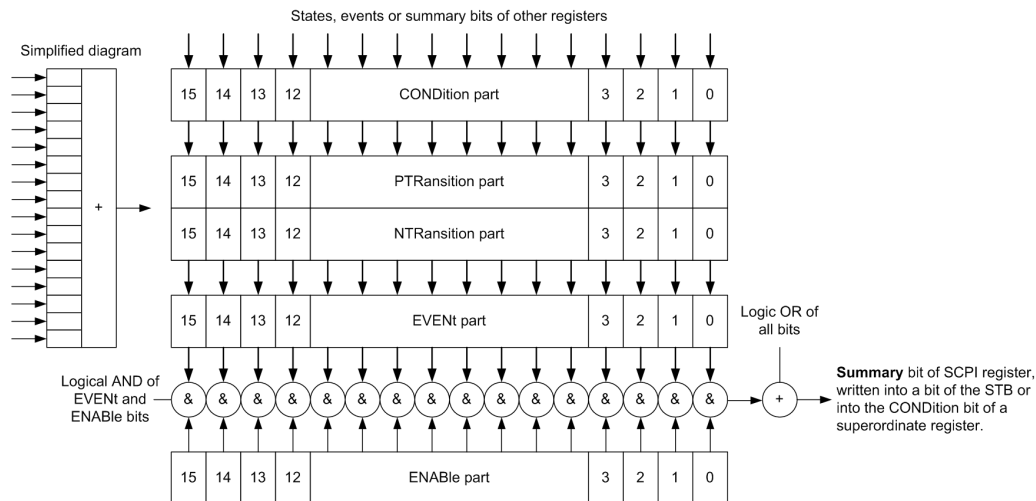


Fig. 10-2: The status-register model

Description of the five status register parts

The five parts of a SCPI register have different properties and functions:

- **COND**

The **COND** part is written into directly by the hardware or the sum bit of the next lower register. Its contents reflect the current instrument status. This register

part can only be read, but not written into or cleared. Its contents are not affected by reading.

- **Ptransition / NTransition**

The two transition register parts define which state transition of the `CONDition` part (none, 0 to 1, 1 to 0 or both) is stored in the `EVENT` part.

The **Positive-Transition** part acts as a transition filter. When a bit of the `CONDition` part is changed from 0 to 1, the associated `PTR` bit decides whether the `EVENT` bit is set to 1.

- `PTR` bit =1: the `EVENT` bit is set.
- `PTR` bit =0: the `EVENT` bit is not set.

This part can be written into and read as required. Its contents are not affected by reading.

The **Negative-Transition** part also acts as a transition filter. When a bit of the `CONDition` part is changed from 1 to 0, the associated `NTR` bit decides whether the `EVENT` bit is set to 1.

- `NTR` bit =1: the `EVENT` bit is set.
- `NTR` bit =0: the `EVENT` bit is not set.

This part can be written into and read as required. Its contents are not affected by reading.

- **EVENT**

The `EVENT` part indicates whether an event has occurred since the last reading, it is the "memory" of the condition part. It only indicates events passed on by the transition filters. It is permanently updated by the instrument. This part can only be read by the user. Reading the register clears it. This part is often equated with the entire register.

- **ENABLE**

The `ENABLE` part determines whether the associated `EVENT` bit contributes to the sum bit (see below). Each bit of the `EVENT` part is "ANDed" with the associated `ENABLE` bit (symbol '&'). The results of all logical operations of this part are passed on to the sum bit via an "OR" function (symbol '+').

`ENABLE` bit = 0: the associated `EVENT` bit does not contribute to the sum bit

`ENABLE` bit = 1: if the associated `EVENT` bit is "1", the sum bit is set to "1" as well.

This part can be written into and read by the user as required. Its contents are not affected by reading.

Sum bit

The sum bit is obtained from the `EVENT` and `ENABLE` part for each register. The result is then entered into a bit of the `CONDition` part of the higher-order register.

The instrument automatically generates the sum bit for each register. Thus an event can lead to a service request throughout all levels of the hierarchy.

10.1.5.3 Contents of the Status Registers

In the following sections, the contents of the status registers are described in more detail.



STATus:QUEStionable:SYNC register

The STATus:QUEStionable:SYNC register is used by the R&S FPS applications and is described in the individual sections (manuals) for each application.

- Status Byte (STB) and Service Request Enable Register (SRE).....560
- IST Flag and Parallel Poll Enable Register (PPE)..... 561
- Event Status Register (ESR) and Event Status Enable Register (ESE)..... 561
- STATus:OPERation Register.....562
- STATus:QUEStionable Register.....563
- STATus:QUEStionable:ACPLimit Register.....564
- STATus:QUEStionable:EXTended Register.....565
- STATus:QUEStionable:EXTended:INFO Register..... 565
- STATus:QUEStionable:FREQuency Register..... 566
- STATus:QUEStionable:LIMit Register..... 567
- STATus:QUEStionable:LMARgin Register..... 567
- STATus:QUEStionable:POWer Register..... 568
- STATus:QUEStionable:TEMPerature Register.....569
- STATus:QUEStionable:TIME Register.....569

Status Byte (STB) and Service Request Enable Register (SRE)

The STATus Byte (STB) is already defined in IEEE 488.2. It provides a rough overview of the instrument status by collecting the pieces of information of the lower registers. A special feature is that bit 6 acts as the sum bit of the remaining bits of the status byte.

The STB can thus be compared with the CONDition part of an SCPI register and assumes the highest level within the SCPI hierarchy.

The STB is read using the command `*STB?` or a serial poll.

The STATus Byte (STB) is linked to the Service Request Enable (SRE) register. Each bit of the STB is assigned a bit in the SRE. Bit 6 of the SRE is ignored. If a bit is set in the SRE and the associated bit in the STB changes from 0 to 1, a service request (SRQ) is generated. The SRE can be set using the command `*SRE` and read using the command `*SRE?`.

Table 10-2: Meaning of the bits used in the status byte

Bit No.	Meaning
0...1	Not used
2	Error Queue not empty The bit is set when an entry is made in the error queue. If this bit is enabled by the SRE, each entry of the error queue generates a service request. Thus an error can be recognized and specified in greater detail by polling the error queue. The poll provides an informative error message. This procedure is to be recommended since it considerably reduces the problems involved with remote control.
3	QUEStionable status register summary bit The bit is set if an EVENT bit is set in the QUEStionable status register and the associated ENABLE bit is set to 1. A set bit indicates a questionable instrument status, which can be specified in greater detail by querying the STATus:QUEStionable status register.

Bit No.	Meaning
4	MAV bit (message available) The bit is set if a message is available in the output queue which can be read. This bit can be used to enable data to be automatically read from the instrument to the controller.
5	ESB bit Sum bit of the event status register. It is set if one of the bits in the event status register is set and enabled in the event status enable register. Setting of this bit indicates a serious error which can be specified in greater detail by polling the event status register.
6	MSS bit (master status summary bit) The bit is set if the instrument triggers a service request. This is the case if one of the other bits of this registers is set together with its mask bit in the service request enable register SRE.
7	STATUS:OPERation status register summary bit The bit is set if an EVENT bit is set in the OPERATION status register and the associated ENABLE bit is set to 1. A set bit indicates that the instrument is just performing an action. The type of action can be determined by querying the STATUS:OPERation status register.

IST Flag and Parallel Poll Enable Register (PPE)

As with the SRQ, the IST flag combines the entire status information in a single bit. It can be read by means of a parallel poll (see "Parallel Poll" on page 571) or using the command `*IST?`.

The parallel poll enable register (PPE) determines which bits of the STB contribute to the IST flag. The bits of the STB are "ANDed" with the corresponding bits of the PPE, with bit 6 being used as well in contrast to the SRE. The IST flag results from the "ORing" of all results. The PPE can be set using commands `*PRE` and read using command `*PRE?`.

Event Status Register (ESR) and Event Status Enable Register (ESE)

The ESR is defined in IEEE 488.2. It can be compared with the EVENT part of a SCPI register. The event status register can be read out using command `*ESR?`.

The ESE corresponds to the ENABLE part of a SCPI register. If a bit is set in the ESE and the associated bit in the ESR changes from 0 to 1, the ESB bit in the STB is set. The ESE register can be set using the command `*ESE` and read using the command `*ESE?`.

Table 10-3: Meaning of the bits used in the event status register

Bit No.	Meaning
0	Operation Complete This bit is set on receipt of the command <code>*OPC</code> exactly when all previous commands have been executed.
1	Not used
2	Query Error This bit is set if either the controller wants to read data from the instrument without having sent a query, or if it does not fetch requested data and sends new instructions to the instrument instead. The cause is often a query which is faulty and hence cannot be executed.

Bit No.	Meaning
3	Device-dependent Error This bit is set if a device-dependent error occurs. An error message with a number between -300 and -399 or a positive error number, which denotes the error in greater detail, is entered into the error queue.
4	Execution Error This bit is set if a received command is syntactically correct but cannot be performed for other reasons. An error message with a number between -200 and -300, which denotes the error in greater detail, is entered into the error queue.
5	Command Error This bit is set if a command is received, which is undefined or syntactically incorrect. An error message with a number between -100 and -200, which denotes the error in greater detail, is entered into the error queue.
6	User Request This bit is set when the instrument is switched over to manual control.
7	Power On (supply voltage on) This bit is set on switching on the instrument.

STATus:OPERation Register

The `STATus:OPERation` register contains information on current activities of the R&S FPS. It also contains information on activities that have been executed since the last read out.

You can read out the register with `STATus:OPERation:CONDition?` or `STATus:OPERation[:EVENT]?`.

Table 10-4: Meaning of the bits used in the `STATus:OPERation` register

Bit No.	Meaning
0	<code>CALibrating</code> This bit is set as long as the instrument is performing a calibration.
1-2	Not used
3	<code>SWEeping</code> Sweep is being performed in base unit (applications are not considered); identical to bit 4 In applications, this bit is not used.
4	<code>MEASuring</code> Measurement is being performed in base unit (applications are not considered); identical to bit 3 In applications, this bit is not used.
5	<code>Waiting for TRigger</code> Instrument is ready to trigger and waiting for trigger signal.
6-7	Not used
8	<code>HardCOpy in progress</code> This bit is set while the instrument is printing a hardcopy.

Bit No.	Meaning
9	For data acquisition in MSRA mode only: Multi-Standard capture finish This bit is set if a data acquisition measurement was completed successfully in MSRA operating mode and data is available for evaluation. For details on the MSRA operating mode see the R&S FPS MSRA User Manual.
10	Range completed This bit is set when a range in the sweep list has been completed if "Stop after Range" has been activated.
11-14	Not used
15	This bit is always 0.

STATus:QUEStionable Register

The STATus:QUEStionable register contains information on instrument states that do not meet the specifications.



The `STAT:QUES:SYNC` register is used by the applications and is thus described in the individual applications' User Manuals.

You can read out the register with `STAT:QUES:COND` or `STAT:QUES:EVEN`.



The `STATus:QUEStionable` register "sums up" the information from all subregisters (e.g. bit 2 sums up the information for all `STATus:QUEStionable:TIME` registers). For some subregisters, there may be separate registers for each active channel. Thus, if a status bit in the `STATus:QUEStionable` register indicates an error, the error may have occurred in any of the channel-specific subregisters. In this case, you must check the subregister of each channel to determine which channel caused the error. By default, querying the status of a subregister always returns the result for the currently selected channel.

Table 10-5: Meaning of the bits used in the STATus:QUEStionable register

Bit No.	Meaning
0 - 1	Unused
2	TIME This bit is set if a time error occurs in any of the active channels. The STATus:QUEStionable:TIME Register provides more information on the error type.
3	POWer This bit is set if the measured power level in any of the active channels is questionable. The STATus:QUEStionable:POWer Register provides more information on the error type.
4	TEMPerature This bit is set if the temperature is questionable.

Bit No.	Meaning
5	<p>FREquency</p> <p>This bit is set if there is anything wrong with the frequency of the local oscillator or the reference frequency in any of the active channels.</p> <p>The STATus:QUEStionable:FREquency Register provides more information on the error type.</p>
6 - 7	Unused
8	<p>CALibration</p> <p>This bit is set if the R&S FPS is unaligned ("UNCAL" display)</p>
9	<p>LIMit (device-specific)</p> <p>This bit is set if a limit value is violated in any of the active channels in any window.</p> <p>The STATus:QUEStionable:LIMit Register provides more information on the error type.</p>
10	<p>LMARgin (device-specific)</p> <p>This bit is set if a margin is violated in any of the active channels in any window.</p> <p>The STATus:QUEStionable:LMARgin Register provides more information on the error type.</p>
11	<p>SYNC (device-specific)</p> <p>This bit is set if the R&S FPS is not synchronized to the signal that is applied.</p> <p>The R&S FPS is not synchronized if:</p> <ul style="list-style-type: none"> • it cannot synchronize to midamble during a measurement or premeasurement • it cannot find a burst during a measurement or premeasurement • the results deviate too much from the expected value during premeasurements
12	<p>ACPLimit (device-specific)</p> <p>This bit is set if a limit during ACLR measurements is violated in any of the active channels.</p> <p>The STATus:QUEStionable:ACPLimit Register provides more information on the error type.</p>
13-14	Unused
15	This bit is always 0.

STATus:QUEStionable:ACPLimit Register

The STATus:QUEStionable:ACPLimit register contains information about the results of a limit check during ACLR measurements. A separate ACPLimit register exists for each active channel.

You can read out the register with [STATus:QUEStionable:ACPLimit:CONDition?](#) or [STATus:QUEStionable:ACPLimit\[:EVENT\]?](#)

Table 10-6: Meaning of the bits used in the STATus:QUEStionable:ACPLimit register

Bit No.	Meaning
0	<p>ADJ UPPer FAIL</p> <p>This bit is set if the limit is exceeded in the upper adjacent channel</p>
1	<p>ADJ LOWer FAIL</p> <p>This bit is set if the limit is exceeded in the lower adjacent channel.</p>
2	<p>ALT1 UPPer FAIL</p> <p>This bit is set if the limit is exceeded in the upper 1st alternate channel.</p>

Bit No.	Meaning
3	ALT1 LOWEr FAIL This bit is set if the limit is exceeded in the lower 1st alternate channel.
4	ALT2 UPPer FAIL This bit is set if the limit is exceeded in the upper 2nd alternate channel.
5	ALT2 LOWEr FAIL This bit is set if the limit is exceeded in the lower 2nd alternate channel.
6	ALT3 ... 11 LOWEr/UPPer FAIL This bit is set if the limit is exceeded in one of the lower or upper alternate channels 3 ... 11.
7	CACLR FAIL This bit is set if the CACLR limit is exceeded in one of the gap channels.
8	GAP ACLR FAIL This bit is set if the ACLR limit is exceeded in one of the gap channels.
9 to 14	Unused
15	This bit is always 0.

STATus:QUEStionable:EXTEnded Register

The `STATus:QUEStionable:EXTEnded` register contains further status information not covered by the other status registers of the R&S FPS. A separate `EXTEnded` register exists for each active channel.

You can read out the register with `STATus:QUEStionable:EXTEnded:CONDition?` or `STATus:QUEStionable:EXTEnded[:EVENT]?`

Table 10-7: Meaning of the bits used in the `STATus:QUEStionable:EXTEnded` register

Bit No.	Meaning
0	not used
1	INFO This bit is set if a status message is available for the application. Which type of message occurred is indicated in the <code>STATus:QUEStionable:EXTEnded:INFO Register</code> .
2 to 14	Unused
15	This bit is always 0.

STATus:QUEStionable:EXTEnded:INFO Register

The `STATus:QUEStionable:EXTEnded:INFO` register contains information on the type of messages that occur during operation of the R&S FPS. A separate `INFO` register exists for each active channel.

You can read out the register with `STATus:QUEStionable:EXTEnded:INFO:CONDition?` or `STATus:QUEStionable:EXTEnded:INFO[:EVENT]?`. You can query all messages that occur for a specific channel using the command `SYSTEM:ERRor:EXTEnded?` on page 929.

Table 10-8: Meaning of the bits used in the STATus:QUESTIONable:EXTended:INFO register

Bit No.	Meaning
0	MESSage This bit is set if event or state has occurred that may lead to an error during further operation.
1	INFO This bit is set if an informational status message is available for the application.
2	WARNIng This bit is set if an irregular situation occurs during measurement, e.g. the settings no longer match the displayed results, or the connection to an external device was interrupted temporarily.
3	ERRor This bit is set if an error occurs during a measurement, e.g. due to missing data or wrong settings, so that the measurement cannot be completed correctly.
4	FATal This bit is set if a serious error occurs in the application and regular operation is no longer possible.
5 to 14	Unused
15	This bit is always 0.

STATus:QUESTIONable:FREQUENCY Register

The STATus:QUESTIONable:FREQUENCY register contains information about the condition of the local oscillator and the reference frequency. A separate frequency register exists for each active channel.

You can read out the register with `STATus:QUESTIONable:FREQUENCY:CONDition?` or `STATus:QUESTIONable:FREQUENCY[:EVENT]?`.

Table 10-9: Meaning of the bits used in the STATus:QUESTIONable:FREQUENCY register

Bit No.	Meaning
0	OVEN COLD This bit is set if the reference oscillator has not yet attained its operating temperature. "OCXO" is displayed.
1	LO UNLocked This bit is set if the local oscillator no longer locks. "LOUNL" is displayed.
2 to 7	Not used
8	EXTernalREFerence This bit is set if you have selected an external reference oscillator but did not connect a useable external reference source. In that case the synthesizer can not lock. The frequency in all probability is not accurate.
9 to 14	Not used
15	This bit is always 0.

STATus:QUEStionable:LIMit Register

The STATus:QUEStionable:LIMit register contains information about the results of a limit check when you are working with limit lines.

A separate LIMit register exists for each active channel and for each window.

You can read out the register with `STATus:QUEStionable:LIMit<n>:CONDition?` or `STATus:QUEStionable:LIMit<n>[:EVENT]?`.

Table 10-10: Meaning of the bits used in the STATus:QUEStionable:LIMit register

Bit No.	Meaning
0	LIMit 1 FAIL This bit is set if limit line 1 is violated.
1	LIMit 2 FAIL This bit is set if limit line 2 is violated.
2	LIMit 3 FAIL This bit is set if limit line 3 is violated.
3	LIMit 4 FAIL This bit is set if limit line 4 is violated.
4	LIMit 5 FAIL This bit is set if limit line 5 is violated.
5	LIMit 6 FAIL This bit is set if limit line 6 is violated.
6	LIMit 7 FAIL This bit is set if limit line 7 is violated.
7	LIMit 8 FAIL This bit is set if limit line 8 is violated.
8 to 14	Unused
15	This bit is always 0.

STATus:QUEStionable:LMARgin Register

This register contains information about the observance of limit margins.

A separate LMARgin register exists for each active channel and for each window.

It can be read using the commands

`STATus:QUEStionable:LMARgin:CONDition?` and
`STATus:QUEStionable:LMARgin[:EVENT]?`.

Table 10-11: Meaning of the bits used in the `STATUS:QUESTIONable:LMARgin` register

Bit No.	Meaning
0	LMARgin 1 FAIL This bit is set if limit margin 1 is violated.
1	LMARgin 2 FAIL This bit is set if limit margin 2 is violated.
2	LMARgin 3 FAIL This bit is set if limit margin 3 is violated.
3	LMARgin 4 FAIL This bit is set if limit margin 4 is violated.
4	LMARgin 5 FAIL This bit is set if limit margin 5 is violated.
5	LMARgin 6 FAIL This bit is set if limit margin 6 is violated.
6	LMARgin 7 FAIL This bit is set if limit margin 7 is violated.
7	LMARgin 8 FAIL This bit is set if limit margin 8 is violated.
8 to 14	Not used
15	This bit is always 0.

STATUS:QUESTIONable:POWER Register

The `STATUS:QUESTIONable:POWER` register contains information about possible overload situations that may occur during operation of the R&S FPS. A separate power register exists for each active channel.

You can read out the register with `STATUS:QUESTIONable:POWER:CONDition?` or `STATUS:QUESTIONable:POWER[:EVENT]?`

Table 10-12: Meaning of the bits used in the `STATUS:QUESTIONable:POWER` register

Bit No.	Meaning
0	OVERload This bit is set if an overload occurs at the RF input, causing signal distortion but not yet causing damage to the device. The R&S FPS displays the keyword "RF OVLD".
1	UNDerload This bit is set if an underload occurs at the RF input. The R&S FPS displays the keyword "UNLD".
2	IF_OVERload This bit is set if an overload occurs in the IF path. The R&S FPS displays the keyword "IF OVLD".

Bit No.	Meaning
3	<p>Input Overload</p> <p>This bit is set if the signal level at the RF input connector exceeds the maximum.</p> <p>The RF input is disconnected from the input mixer to protect the device. In order to re-enable measurement, decrease the level at the RF input connector and reconnect the RF input to the mixer input.</p> <p>The R&S FPS displays the keyword "INPUT OVLD".</p>
4 to 14	Unused
15	This bit is always 0.

STATus:QUEStionable:TEMPerature Register

The STATus:QUEStionable:TEMPerature register contains information about possible temperature deviations that may occur during operation of the R&S FPS. A separate temperature register exists for each active channel.

You can read out the register with `STATus:QUEStionable:TEMPerature:CONDition?` or `STATus:QUEStionable:TEMPerature[:EVENT]?`

Table 10-13: Meaning of the bits used in the STATus:QUEStionable:TEMPerature register

Bit No.	Meaning
0	<p>This bit is set if the frontend temperature sensor deviates by a certain degree from the self-alignment temperature.</p> <p>During warmup, this bit is always 0.</p> <p>For details see "Temperature check" on page 506.</p>
1 to 14	Unused
15	This bit is always 0.

STATus:QUEStionable:TIME Register

The STATus:QUEStionable:TIME register contains information about possible time errors that may occur during operation of the R&S FPS. A separate time register exists for each active channel.

You can read out the register with `STATus:QUEStionable:TIME:CONDition?` or `STATus:QUEStionable:TIME[:EVENT]?`

Table 10-14: Meaning of the bits used in the STATus:QUEStionable:TIME register

Bit No.	Meaning
0	not used
1	<p>Sweep time too low</p> <p>This bit is set if the sweep time is too low and thus calibration fails.</p> <p>Note: the STATus:QUEStionable bit for CALibration is not affected by this error.</p>
2 to 14	Unused
15	This bit is always 0.

10.1.5.4 Application of the Status Reporting System

The purpose of the status reporting system is to monitor the status of one or several devices in a measuring system. To do this and react appropriately, the controller must receive and evaluate the information of all devices. The following standard methods are used:

- **Service request** (SRQ) initiated by the instrument
- **Serial poll** of all devices in the bus system, initiated by the controller in order to find out who sent a SRQ and why
- **Parallel poll** of all devices
- Query of a **specific instrument status** by means of commands
- Query of the **error queue**

Service Request

Under certain circumstances, the instrument can send a service request (SRQ) to the controller. A service request is a request from an instrument for information, advice or treatment by the controller. Usually this service request initiates an interrupt at the controller, to which the control program can react appropriately. As evident from [figure 10-1](#), an SRQ is always initiated if one or several of bits 2, 3, 4, 5 or 7 of the status byte are set and enabled in the SRE. Each of these bits combines the information of a further register, the error queue or the output buffer. The `ENABLe` parts of the status registers can be set such that arbitrary bits in an arbitrary status register initiate an SRQ. In order to make use of the possibilities of the service request effectively, all bits should be set to "1" in enable registers SRE and ESE.

The service request is the only possibility for the instrument to become active on its own. Each controller program should cause the instrument to initiate a service request if errors occur. The program should react appropriately to the service request.

Use of the command `*OPC` to generate an SRQ at the end of a sweep

1. `CALL InstrWrite(analyzer, "*ESE 1")` 'Set bit 0 in the ESE (Operation Complete)
2. `CALL InstrWrite(analyzer, "*SRE 32")` 'Set bit 5 in the SRE (ESB)
3. `CALL InstrWrite(analyzer, "*INIT;*OPC")` 'Generate an SRQ after operation complete

After its settings have been completed, the instrument generates an SRQ.

A detailed example for a service request routine can be found in [chapter 11.15.2, "Service Request"](#), on page 979.

Serial Poll

In a serial poll, just as with command `*STB`, the status byte of an instrument is queried. However, the query is realized via interface messages and is thus clearly faster.

The serial poll method is defined in IEEE 488.1 and used to be the only standard possibility for different instruments to poll the status byte. The method also works for instruments which do not adhere to SCPI or IEEE 488.2.

The serial poll is mainly used to obtain a fast overview of the state of several instruments connected to the controller.

Parallel Poll

In a parallel poll, up to eight instruments are simultaneously requested by the controller using a single command to transmit 1 bit of information each on the data lines, i.e., to set the data line allocated to each instrument to a logical "0" or "1".

In addition to the SRE register, which determines the conditions under which an SRQ is generated, there is a Parallel Poll Enable register (PPE) which is ANDed with the STB bit by bit, considering bit 6 as well. This register is ANDed with the STB bit by bit, considering bit 6 as well. The results are ORed, the result is possibly inverted and then sent as a response to the parallel poll of the controller. The result can also be queried without parallel poll using the command `*IST?`.

The instrument first has to be set for the parallel poll using the command `PPC`. This command allocates a data line to the instrument and determines whether the response is to be inverted. The parallel poll itself is executed using `PPE`.

The parallel poll method is mainly used to find out quickly which one of the instruments connected to the controller has sent a service request. To this effect, SRE and PPE must be set to the same value.

Query of an instrument status

Each part of any status register can be read using queries. There are two types of commands:

- The common commands `*ESR?`, `*IDN?`, `*IST?`, `*STB?` query the higher-level registers.
- The commands of the `STATus` system query the SCPI registers (`STATus:QUEStionable...`)

The returned value is always a decimal number that represents the bit pattern of the queried register. This number is evaluated by the controller program.

Queries are usually used after an SRQ in order to obtain more detailed information on the cause of the SRQ.

Decimal representation of a bit pattern

The STB and ESR registers contain 8 bits, the SCPI registers 16 bits. The contents of a status register are specified and transferred as a single decimal number. To make this possible, each bit is assigned a weighted value. The decimal number is calculated as the sum of the weighted values of all bits in the register that are set to 1.

Bits	0	1	2	3	4	5	6	7	...
Weight	1	2	4	8	16	32	64	128	...

Example:

The decimal value 40 = 32 + 8 indicates that bits no. 3 and 5 in the status register (e.g. the `QUESTionable` status summary bit and the `ESB` bit in the `STatus Byte`) are set.

Error Queue

Each error state in the instrument leads to an entry in the error queue. The entries of the error queue are detailed plain text error messages that can be looked up in the Error Log or queried via remote control using `SYSTem:ERRor[:NEXT]?` or `SYSTem:ERRor:ALL?`. Each call of `SYSTem:ERRor[:NEXT]?` provides one entry from the error queue. If no error messages are stored there any more, the instrument responds with 0, "No error".

The error queue should be queried after every SRQ in the controller program as the entries describe the cause of an error more precisely than the status registers. Especially in the test phase of a controller program the error queue should be queried regularly since faulty commands from the controller to the instrument are recorded there as well.

10.1.5.5 Reset Values of the Status Reporting System

The following table contains the different commands and events causing the status reporting system to be reset. None of the commands, except `*RST` and `SYSTem:PRESet`, influence the functional instrument settings. In particular, `DCL` does not change the instrument settings.

Table 10-15: Resetting the status reporting system

Event	Switching on supply voltage Power-On-Status-Clear		DCL, SDC (Device Clear, Selected Device Clear)	*RST or SYS- Tem:PRE- Set	STA- Tus:PRE- Set	*CLS
	0	1				
Clear STB, ESR	-	yes	-	-	-	yes
Clear SRE, ESE	-	yes	-	-	-	-
Clear PPE	-	yes	-	-	-	-
Clear EVENT parts of the registers	-	yes	-	-	-	yes

Event	Switching on supply voltage		DCL, SDC (Device Clear, Selected Device Clear)	*RST or SYS-Tem:PRE-Set	STA-Tus:PRE-Set	*CLS
	Power-On-Status-Clear					
Effect	0	1				
Clear ENABLE parts of all OPERATION and QUESTIONABLE registers; Fill ENABLE parts of all other registers with "1".	-	yes	-	-	yes	-
Fill PTRANSITION parts with "1"; Clear NTRANSITION parts	-	yes	-	-	yes	-
Clear error queue	yes	yes	-	-	-	yes
Clear output buffer	yes	yes	yes	1)	1)	1)
Clear command processing and input buffer	yes	yes	yes	-	-	-
1) The first command in a command line that immediately follows a <PROGRAM MESSAGE TERMINATOR> clears the output buffer.						

10.1.6 General Programming Recommendations

Initial instrument status before changing settings

Manual operation is designed for maximum possible operating convenience. In contrast, the priority of remote control is the "predictability" of the instrument status. Thus, when a command attempts to define incompatible settings, the command is ignored and the instrument status remains unchanged, i.e. other settings are not automatically adapted. Therefore, control programs should always define an initial instrument status (e.g. using the *RST command) and then implement the required settings.

Command sequence

As a general rule, send commands and queries in different program messages. Otherwise, the result of the query may vary depending on which operation is performed first (see also [chapter 10.1.4.1, "Preventing Overlapping Execution"](#), on page 554).

Reacting to malfunctions

The service request is the only possibility for the instrument to become active on its own. Each controller program should instruct the instrument to initiate a service request in case of malfunction. The program should react appropriately to the service request.

Error queues

The error queue should be queried after every service request in the controller program as the entries describe the cause of an error more precisely than the status registers. Especially in the test phase of a controller program the error queue should be queried regularly since faulty commands from the controller to the instrument are recorded there as well.

10.2 GPIB Languages

The R&S FPS analyzer family supports a subset of the GPIB commands used by other devices. Thus it can emulate other devices in order to use existing remote control programs.

The device model to be emulated is selected manually using "SETUP > Network + Remote > GPIB tab > Language". Via the GPIB interface using the [SYSTem: LANGuage](#) on page 939 command.

In order to emulate device models that are not part of the selection list of the GPIB "Language" setting, you can modify the identification string received in response to the ID command ("Identification String" setting). Thus, any device model whose command set is compatible with one of the supported device models can be emulated.

Supported languages

Language	Comment
SCPI	
71100C	Compatible to 8566A/B
71200C	Compatible to 8566A/B
71209A	Compatible to 8566A/B
8560E	
8561E	
8562E	
8563E	
8564E	
8565E	
8566A	Command sets A and B are available. Command sets A and B differ in the rules regarding the command structure.
8566B	
8568A	Command sets A and B are available. Command sets A and B differ in the rules regarding the command structure.
8568A_DC	Uses DC input coupling by default if supported by the instrument

Language	Comment
8568B	Command sets A and B are available. Command sets A and B differ in the rules regarding the command structure.
8568B_DC	Uses DC input coupling by default if supported by the instrument
8591E	Compatible to 8594E
8594E	Command sets A and B are available. Command sets A and B differ in the rules regarding the command structure.
PSA89600	
PSA	

Notes:

- If you select a language other than "SCPI", the GPIB address is set to 18 if it was 20 before.
- The Start/stop frequency, reference level and number of sweep points are adapted to the selected instrument model.
- When you switch between remote control languages, the following settings or changes are made:

SCPI:

The instrument performs a PRESET.

8566A/B, 8568A/B, 8594E; FSEA, FSEB, FSEM; FSEK:

- The instrument performs a PRESET.
- The following instrument settings are changed:

Table 10-16: Instrument settings for emulation of 8566A/B, 8568A/B, 8594E; FSEA, FSEB, FSEM; FSEK instruments

Model	# of Trace Points	Start Freq.	Stop Freq.	Ref Level	Input Coupling
8566A/B	1001	2 GHz	22 GHz	0 dBm	AC
8568A/B	1001	0 Hz	1.5 GHz	0 dBm	AC
8560E	601	0 Hz	2.9 GHz	0 dBm	AC
8561E	601	0 Hz	6.5 GHz	0 dBm	AC
8562E	601	0 Hz	13.2 GHz	0 dBm	AC
8563E	601	0 Hz	26.5 GHz	0 dBm	AC
8564E	601	0 Hz	40 GHz	0 dBm	AC
8565E	601	0 Hz	50 GHz	0 dBm	AC
8594E	401	0 Hz	3 GHz	0 dBm	AC

Note: The stop frequency indicated in the table may be limited to the corresponding frequency of the R&S FPS, if required.

10.3 Network and Remote Control Settings

The network and remote control settings are defined in the "Network + Remote" dialog box which is displayed when you press the SETUP key and then select "Network + Remote".



Some of the following settings and functions are also available directly on the R&S FPS, via the miniature display. See [chapter 3.3, "Miniature Display"](#), on page 39.



Network settings in secure user mode

Be sure to store all network settings before [Secure User Mode](#) is enabled; see [chapter 3.1.6, "Protecting Data Using the Secure User Mode"](#), on page 30.

If the currently stored network settings are not suitable, you must correct them each time you switch on the R&S FPS in secure user mode, as the settings are not stored permanently in this case.

The remote commands required to define these settings are described in [chapter 11.10.5, "Configuring the Network and Remote Control"](#), on page 923.

Step-by-step instructions are provided in [chapter 3.4, "Controlling the R&S FPS Remotely"](#), on page 47.

- [General Network Settings](#)..... 576
- [GPIB Settings](#).....578
- [Compatibility Settings](#).....580
- [LXI Settings](#).....582
- [Remote Errors](#).....584

10.3.1 General Network Settings

The R&S FPS can be operated in a local area network (LAN), for example to control the instrument from a remote PC or use a network printer.

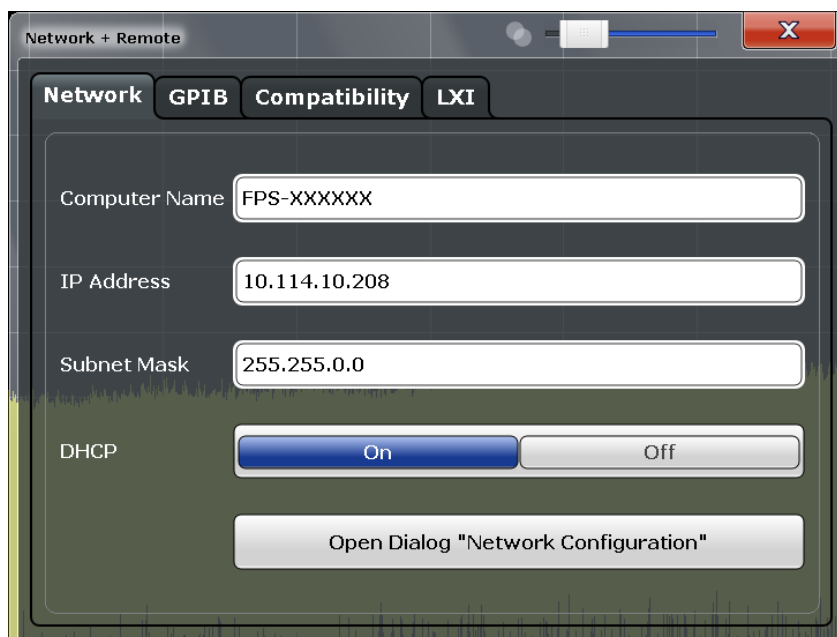
The general network settings are defined in the "Network" tab of the "Network + Remote" dialog box.

NOTICE

Risk of network problems

All parameters can be edited here; however, beware that changing the computer name has major effects in a network.

For details, see [chapter 3.4, "Controlling the R&S FPS Remotely"](#), on page 47.



Computer Name.....577
 IP Address.....577
 Subnet Mask.....578
 DHCP.....578
 Network Configuration.....578

Computer Name

Each instrument is delivered with an assigned computer name, but this name can be changed. The naming conventions of Windows apply. If too many characters and/or numbers are entered, an error message is displayed in the status line.

The default instrument name is a non-case-sensitive string with the following syntax:

<Type><variant>-<serial_number>

For example FPS13-123456

The serial number can be found on the rear panel of the instrument. It is the third part of the device ID printed on the bar code sticker:



IP Address

Defines the IP address. The TCP/IP protocol is preinstalled with the IP address 10.0.0.10. If the DHCP server is available ("DHCP On"), the setting is read-only.

The IP address consists of four number blocks separated by dots. Each block contains 3 numbers in maximum (e.g. 100.100.100.100), but also one or two numbers are allowed in a block (as an example see the preinstalled address).

Subnet Mask

Defines the subnet mask. The TCP/IP protocol is preinstalled with the subnet mask 255.255.255.0. If the DHCP server is available ("DHCP On"), this setting is read-only.

The subnet mask consists of four number blocks separated by dots. Each block contains 3 numbers in maximum (e.g. 100.100.100.100), but also one or two numbers are allowed in a block (as an example see the preinstalled address).

DHCP

Switches between DHCP server available (On) or not available (Off). If a DHCP server is available in the network, the IP address and subnet mask of the instrument are obtained automatically from the DHCP server.

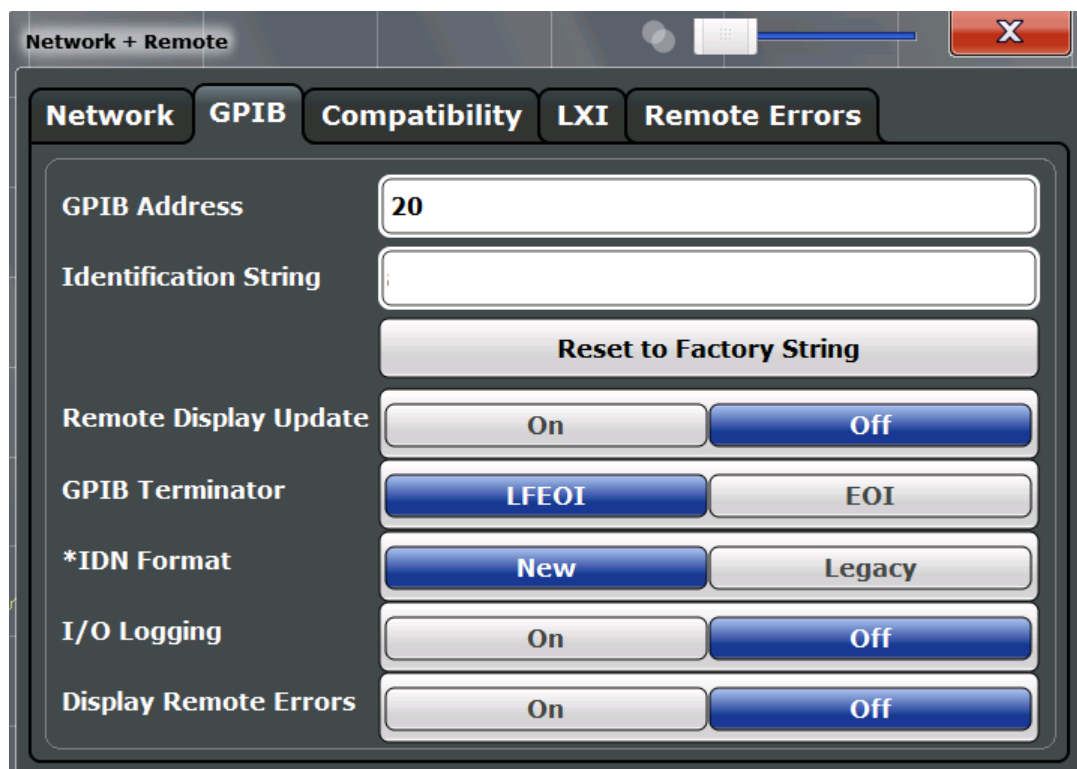
Network Configuration

Opens the standard Windows "Network Configuration" dialog box for further configuration.

10.3.2 GPIB Settings

Alternatively to connecting the R&S FPS to a LAN, the GPIB interface can be used to connect a remote PC. For details see [chapter 3.4.1.2, "GPIB Interface \(IEC 625/IEEE 418 Bus Interface\)"](#), on page 51).

The GPIB settings are defined in the "GPIB" tab of the "Network + Remote" dialog box.



GPIB Address.....	579
Identification String.....	579
Reset to Factory String.....	579
Remote Display Update.....	579
GPIB Terminator.....	579
*IDN Format.....	579
I/O Logging.....	580
Display Remote Errors.....	580

GPIB Address

Defines the GPIB address. Values from 0 to 30 are allowed. The default address is 20.

Remote command:

`SYSTem:COMMunicate:GPIB[:SELF]:ADDRESS` on page 924

Identification String

Defines the identification string for the R&S FPS which is provided as a response to the `*IDN?` query. Maximum 36 characters are allowed.

Remote command:

`SYSTem:IDENTify[:STRing]` on page 925

Reset to Factory String

Restores the default identification string. Each R&S FPS has a unique ID according to the following syntax:

`Rohde&Schwarz,FPS,<Unique number>`

Remote command:

`SYSTem:IDENTify:FACTory` on page 925

Remote Display Update

Defines whether the instrument display is updated or switched off when changing from manual operation to remote control.

Remote command:

`SYSTem:DISPlay:UPDate` on page 924

GPIB Terminator

Changes the GPIB receive terminator.

According to the standard, the terminator in ASCII is `<LF>` and/or `<EOI>`. For binary data transfers (e.g. trace data) from the control computer to the instrument, the binary code used for `<LF>` might be included in the binary data block, and therefore should not be interpreted as a terminator in this particular case. This can be avoided by changing the receive terminator to EOI.

Remote command:

`SYSTem:COMMunicate:GPIB[:SELF]:RTERminator` on page 924

***IDN Format**

Defines the response format to the remote command `*IDN?` (see `*IDN?` on page 590). This function is intended for re-use of existing control programs together with the R&S FPS.

"Leg" Legacy format, compatible to the R&S FSP/FSU/FSQ family

"New" R&S FPS format

Remote command:

[SYSTem:FORMat:IDENT](#) on page 930

I/O Logging

Activates or deactivates the SCPI error log function. All remote control commands received by the R&S FPS are recorded in the following log file:

C:\R_S\instr\ScpiLogging\ScpiLog.txt

Logging the commands may be extremely useful for debug purposes, e.g. in order to find misspelled keywords in control programs.


Remote command:

[SYSTem:CLOGging](#) on page 938

Display Remote Errors

Activates and deactivates the display of errors that occur during remote operation of the R&S FPS. If activated, the R&S FPS displays a message box at the bottom of the screen that contains the type of error and the command that caused the error.



The error message remains in place when you switch to "Local" mode. To close the message box, select the  "Close" icon.

Only the most recent error is displayed in remote mode. However, in local mode, all errors that occurred during remote operation are listed in a separate tab of the "Network + Remote" dialog box (see [chapter 10.3.5, "Remote Errors"](#), on page 584).

Remote command:

[SYSTem:ERRor:DISPlay](#) on page 924

[SYSTem:ERRor:CLEar:REM](#) on page 928

10.3.3 Compatibility Settings

The R&S FPS can emulate the GPIB interface of other signal and spectrum analyzers, e.g. in order to use existing control applications.

The required settings are configured in the "Compatibility" tab of the "Network + Remote" dialog box.



Language..... 581
 IF Gain..... 581
 Sweep Repeat..... 582
 Coupling..... 582
 Revision String..... 582
 Resetting the Factory Revision..... 582

Language

Defines the system language used to control the instrument.

For details on the available GPIB languages, see [chapter 11.13.2, "Reference: GPIB Commands of Emulated HP Models"](#), on page 942.

Note: For PSA89600 emulation, the option is indicated as "B7J" for the *OPT? query ("B7J, 140").

Remote command:

[SYSTem:LANGuage](#) on page 939

IF Gain

Configures the internal IF gain settings in HP emulation mode due to the application needs. This setting is only taken into account for resolution bandwidth < 300 kHz.

NORM	Optimized for high dynamic range, overload limit is close to reference level.
PULS	Optimized for pulsed signals, overload limit up to 10 dB above reference level.

This setting is only available if an HP language is selected (see "Language" on page 581).

Remote command:

`SYSTem:IFGain:MODE` on page 939

Sweep Repeat

Controls a repeated sweep of the E1 and MKPK HI HP model commands (for details on the commands refer to [chapter 11.13.2, "Reference: GPIB Commands of Emulated HP Models"](#), on page 942). If the repeated sweep is OFF, the marker is set without sweeping before.

Note: In single sweep mode, switch off this setting before you set the marker via the E1 and MKPK HI commands in order to avoid sweeping again.

This setting is only available if a HP language is selected (see "Language" on page 581).

Remote command:

`SYSTem:RSW` on page 941

Coupling

Controls the default coupling ratios in the HP emulation mode for:

- span and resolution bandwidth (Span/RBW)
- resolution bandwidth and video bandwidth (RBW/VBW)

For FSx, the standard parameter coupling of the instrument is used. As a result, in most cases a shorter sweep time is used than in case of HP.

This setting is only available if a HP language is selected (see "Language" on page 581).

Remote command:

`SYSTem:HPCoupling` on page 939

Revision String

Defines the response to the `REV?` query for the revision number (HP emulation only, see "GPIB Address" on page 43). Max. 36 characters are allowed.

Remote command:

`SYSTem:REVision[:STRing]` on page 941

Resetting the Factory Revision

Resets the response to the `REV?` query for the revision number to the factory default (HP emulation only, see "Language" on page 581).

Remote command:

`SYSTem:REVision:FACTory` on page 940

10.3.4 LXI Settings

On the R&S FPS the LXI Class C functionality is already installed and enabled; thus, the instrument can be accessed via any web browser (e.g. the Microsoft Internet Explorer) to perform the following tasks:

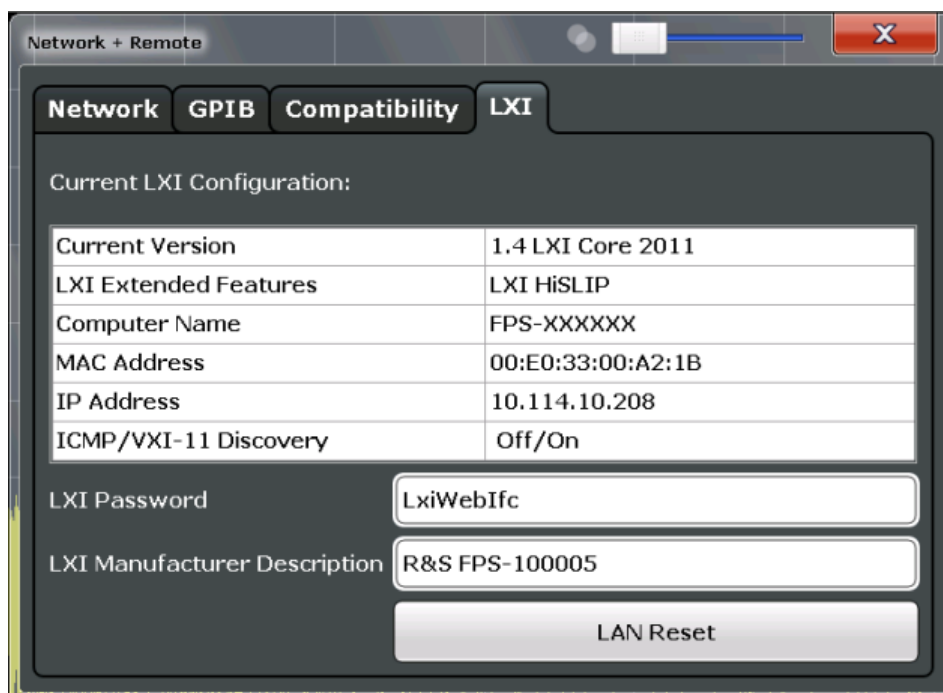
- modifying network configurations
- modifying device configurations
- monitoring connections from the device to other devices

The "LXI" tab of the "Network + Remote" dialog box provides basic LXI functions and information for the R&S FPS.

Alternatively, you can change the LAN settings using the LXI Web browser interface.

For details see [chapter 3.4.2.3, "How to Configure the LAN Using the LXI Browser Interface"](#), on page 55.

Only user accounts with administrator rights are able to use LXI functionality.



Current LXI Configuration	583
LXI Password	584
LXI Manufacturer Description	584
LAN Reset	584

Current LXI Configuration

Displays the current LXI information from the R&S FPS (read-only).

- "Current ver-
sion" Current LXI version
- "LXI Extended
Features" Detected LXI features, such as HiSlip (see "[HiSLIP Protocol](#)" on page 50)
- "Computer
name" Name of the R&S FPS as defined in the operating system (see also "[Computer Name](#)" on page 40)
- "MAC address" Media Access Control address (MAC address), a unique identifier for the network card in the R&S FPS

- "IP address" IP address of the R&S FPS as defined in the operating system (see also "IP Address" on page 41).
- "ICMP" Indicates whether the ping responder is active or not
- "VXI-11 Discovery" If enabled, connected devices are detected automatically using the VXI-11 protocol (see "VXI-11 Protocol" on page 50)

Remote command:

[SYSTem:LXI:INFo?](#) on page 925

LXI Password

Password for LAN configuration. The default password is *LxiWebIfc*.

Remote command:

[SYSTem:LXI:PASSword](#) on page 926

LXI Manufacturer Description

Instrument description of the R&S FPS

Remote command:

[SYSTem:LXI:MDEscription](#) on page 926

LAN Reset

Resets the LAN configuration to its default settings (LCI function).

According to the LXI standard, an LCI must set the following parameters to a default state.

Parameter	Value
TCP/IP Mode	DHCP + Auto IP Address
Dynamic DNS	Enabled
ICMP Ping	Enabled
Password for LAN configuration	LxiWebIfc

The LAN configuration can be reset to its default settings directly on the instrument via the R&S FPS's mini display ("System commands" > "LAN reset"), or in the "Network" tab of the "Network + Remote" dialog box or using the instrument's LXI Browser interface.

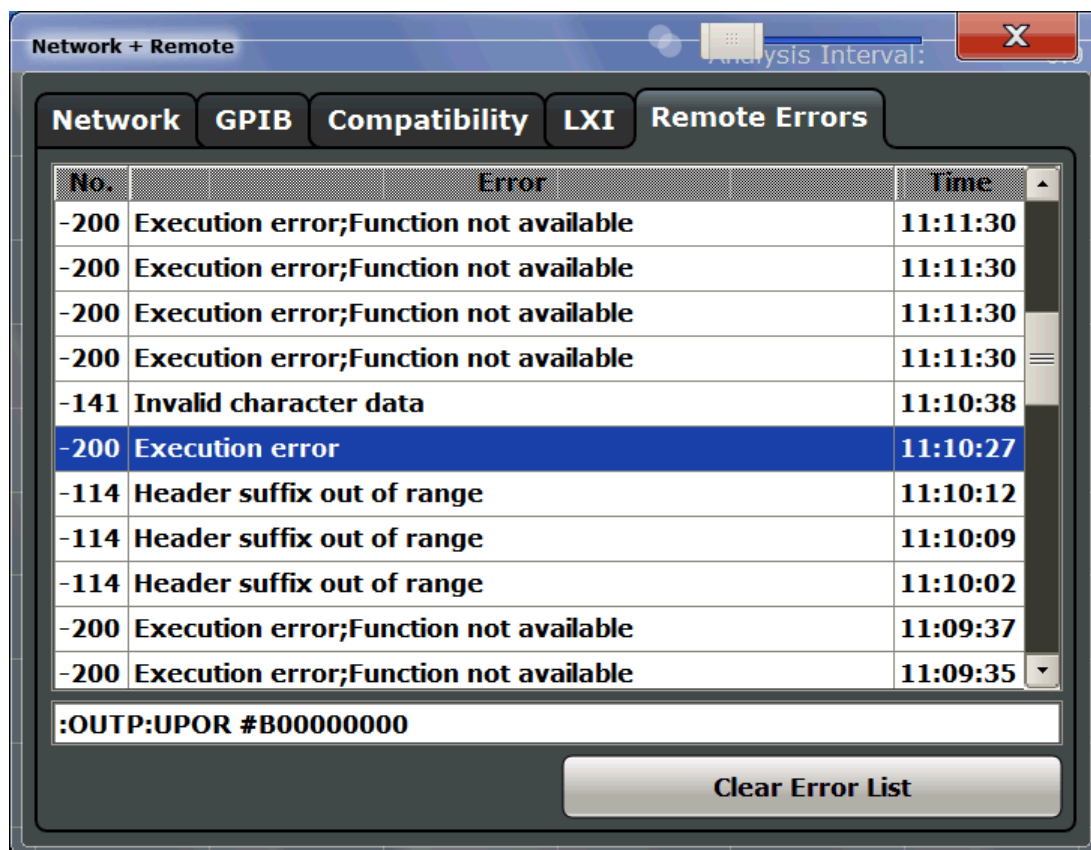
Remote command:

[SYSTem:LXI:LANReset](#) on page 925

10.3.5 Remote Errors

The error messages generated by the R&S FPS during remote operation are displayed in the "Remote Errors" tab of the "Network + Remote" dialog box.

The messages are displayed in the order of their occurrence; the most recent messages are placed at the top of the list.



No.	Error	Time
-200	Execution error;Function not available	11:11:30
-200	Execution error;Function not available	11:11:30
-200	Execution error;Function not available	11:11:30
-200	Execution error;Function not available	11:11:30
-141	Invalid character data	11:10:38
-200	Execution error	11:10:27
-114	Header suffix out of range	11:10:12
-114	Header suffix out of range	11:10:09
-114	Header suffix out of range	11:10:02
-200	Execution error;Function not available	11:09:37
-200	Execution error;Function not available	11:09:35

:OUTP:UPOR #B00000000

Clear Error List



The most recent error message during remote operation can be displayed on the screen, see "[Display Remote Errors](#)" on page 580.

If the number of error messages exceeds the capacity of the error buffer, the oldest error message is removed before the newest one is inserted. To clear the message buffer use the "Clear Error List" button. It is automatically cleared when the R&S FPS is shut down.

The following information is available:

No	Device-specific error code
Error	Brief description of the error
Date/Time	Time the message occurred

Remote command:

`SYSTEM:ERRor:LIST?` on page 929

Clear Error List

Deletes the error message buffer for remote operation.

Note: The remote error list is automatically cleared when the R&S FPS is shut down.

Remote command:

`SYSTem:ERRor:CLEar:REM` on page 928

11 Remote Commands

The commands required to perform measurements in the Spectrum application in a remote environment are described here.

It is assumed that the R&S FPS has already been set up for remote operation in a network as described in [chapter 3.4, "Controlling the R&S FPS Remotely"](#), on page 47.



Compatibility with former R&S signal and spectrum analyzers

As a rule, the R&S FPS supports most commands from previous R&S signal and spectrum analyzers such as the FSQ, FSP, FSU, or FSV. However, the default values, in particular the number of sweep points or particular bandwidths, may vary. Therefore, the R&S FPS can emulate these other devices, including their default values, in order to repeat previous measurements or support existing control applications as in legacy systems.

• Conventions used in SCPI Command Descriptions	587
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11.1 Conventions used in SCPI Command Descriptions

Note the following conventions used in the remote command descriptions:

- **Command usage**
If not specified otherwise, commands can be used both for setting and for querying parameters.
If a command can be used for setting or querying only, or if it initiates an event, the usage is stated explicitly.
- **Parameter usage**
If not specified otherwise, a parameter can be used to set a value and it is the result of a query.
Parameters required only for setting are indicated as **Setting parameters**.
Parameters required only to refine a query are indicated as **Query parameters**.

Parameters that are only returned as the result of a query are indicated as **Return values**.

- **Conformity**
Commands that are taken from the SCPI standard are indicated as **SCPI confirmed**. All commands used by the R&S FPS follow the SCPI syntax rules.
- **Asynchronous commands**
A command which does not automatically finish executing before the next command starts executing (overlapping command) is indicated as an **Asynchronous command**.
- **Reset values (*RST)**
Default parameter values that are used directly after resetting the instrument (*RST command) are indicated as ***RST** values, if available.
- **Default unit**
This is the unit used for numeric values if no other unit is provided with the parameter.
- **Manual operation**
If the result of a remote command can also be achieved in manual operation, a link to the description is inserted.

11.2 Common Suffixes

In the Spectrum application, the following common suffixes are used in remote commands:

Suffix	Value range	Description
<ch>	1..18 (TX channel) 1..11 (ALT channel)	Channel
<k>	1..8 (Limit line) 1 2 (Display line)	Line
<m>	1..16	Marker
<n>	1..16	Window
<t>	1..6	Trace

11.3 Common Commands

Common commands are described in the IEEE 488.2 (IEC 625-2) standard. These commands have the same effect and are employed in the same way on different devices. The headers of these commands consist of "*" followed by three letters. Many common commands are related to the Status Reporting System.

Available common commands:

*CAL?	589
*CLS	589
*ESE	589
*ESR?	590
*IDN?	590
*IST?	590
*OPC	590
*OPT?	590
*PCB	591
*PRE	591
*PSC	591
*RST	591
*SRE	592
*STB?	592
*TRG	592
*TST?	592
*WAI	592

***CAL?**

Calibration query

Initiates a calibration of the instrument and subsequently queries the calibration status. Responses > 0 indicate errors.

Usage: Query only

Manual operation: See ["Self align"](#) on page 41
See ["Starting a Self-alignment"](#) on page 515

***CLS**

Clear status

Sets the status byte (STB), the standard event register (ESR) and the `EVENT` part of the `QUESTIONABLE` and the `OPERATION` registers to zero. The command does not alter the mask and transition parts of the registers. It clears the output buffer.

Usage: Setting only

***ESE <Value>**

Event status enable

Sets the event status enable register to the specified value. The query returns the contents of the event status enable register in decimal form.

Parameters:

<Value> Range: 0 to 255

***ESR?**

Event status read

Returns the contents of the event status register in decimal form and subsequently sets the register to zero.

Return values:

<Contents> Range: 0 to 255

Usage: Query only

***IDN?**

Identification

Returns the instrument identification.

Return values:

<ID> "Rohde&Schwarz,<device type>,<part number>/serial number,<firmware version>"

Example: Rohde&Schwarz,FPS-7,1319.2008K07/100005,1.00

Usage: Query only

Manual operation: See "[*IDN Format](#)" on page 579

***IST?**

Individual status query

Returns the contents of the IST flag in decimal form. The IST flag is the status bit which is sent during a parallel poll.

Return values:

<ISTflag> 0 | 1

Usage: Query only

***OPC**

Operation complete

Sets bit 0 in the event status register when all preceding commands have been executed. This bit can be used to initiate a service request. The query form writes a "1" into the output buffer as soon as all preceding commands have been executed. This is used for command synchronization.

***OPT?**

Option identification query

Queries the options included in the instrument. For a list of all available options and their description refer to the data sheet.

Return values:

<Options> The query returns a list of all installed and activated options, separated by commas, where:
 B<number> describes hardware options
 K<number> describes software options
 For PSA89600 emulation, the option is indicated as "B7J" for the *OPT? query ("B7J, 140" if SYST:PSA:WID is activated).

Usage: Query only

***PCB <Address>**

Pass control back

Indicates the controller address to which remote control is returned after termination of the triggered action.

Setting parameters:

<Address> Range: 0 to 30

Usage: Setting only

***PRE <Value>**

Parallel poll register enable

Sets parallel poll enable register to the indicated value. The query returns the contents of the parallel poll enable register in decimal form.

Parameters:

<Value> Range: 0 to 255

***PSC <Action>**

Power on status clear

Determines whether the contents of the ENABLE registers are preserved or reset when the instrument is switched on. Thus a service request can be triggered when the instrument is switched on, if the status registers ESE and SRE are suitably configured. The query reads out the contents of the "power-on-status-clear" flag.

Parameters:

<Action> 0 | 1

0

The contents of the status registers are preserved.

1

Resets the status registers.

***RST**

Reset

Sets the instrument to a defined default status. The default settings are indicated in the description of commands.

The command is equivalent to `SYSTem:PRESet`.

Usage: Setting only

*SRE <Contents>

Service request enable

Sets the service request enable register to the indicated value. This command determines under which conditions a service request is triggered.

Parameters:

<Contents> Contents of the service request enable register in decimal form.
Bit 6 (MSS mask bit) is always 0.

Range: 0 to 255

*STB?

Status byte query

Reads the contents of the status byte in decimal form.

Usage: Query only

*TRG

Trigger

Triggers all actions waiting for a trigger event. In particular, *TRG generates a manual trigger signal. This common command complements the commands of the `TRIGger` subsystem.

Usage: Event

*TST?

Self test query

Initiates selftests of the instrument and returns an error code in decimal form (see Service Manual supplied with the instrument). "0" indicates no errors occurred.

Usage: Query only

Manual operation: See "[Selftest](#)" on page 41

*WAI

Wait to continue

Prevents servicing of the subsequent commands until all preceding commands have been executed and all signals have settled (see also command synchronization and *OPC).

Usage: Event

11.4 Selecting the Operating Mode and Application

The following commands are required to select the operating mode or the application and to configure a Sequencer in a remote environment. The tasks for manual operation are described in [chapter 4, "Applications and Operating Modes"](#), on page 99.

- [Selecting the Mode and Applications](#)..... 593
- [Performing a Sequence of Measurements](#).....598
- [Programming Example: Performing a Sequence of Measurements](#)..... 601

11.4.1 Selecting the Mode and Applications

DISPlay:ATAB	593
INSTrument:CREate:DUPLicate	593
INSTrument:CREate[:NEW]	594
INSTrument:CREate:REPLace	594
INSTrument:DELeTe	595
INSTrument:LIST?	595
INSTrument:MODE	596
INSTrument:REName	597
INSTrument[:SELect]	597

DISPlay:ATAB <State>

This command switches between the MultiView tab and the most recently displayed measurement channel.

Parameters:

<State>	ON OFF
	ON
	The MultiView tab is displayed.
	OFF
	The most recently displayed measurement channel is displayed.
*RST:	OFF

INSTrument:CREate:DUPLicate

This command duplicates the currently selected measurement channel, i.e creates a new measurement channel of the same type and with the identical measurement settings. The name of the new channel is the same as the copied channel, extended by a consecutive number (e.g. "Spectrum" -> "Spectrum 2").

The channel to be duplicated must be selected first using the `INST:SEL` command.

This command is not available if the MSRA Master channel is selected.

Example: `INST:SEL 'Spectrum'`
`INST:CRE:DUPL`
 Duplicates the channel named 'Spectrum' and creates a new measurement channel named 'Spectrum 2'.

Usage: Event

Manual operation: See "[Duplicate Current Channel](#)" on page 106

INSTrument:CREate[:NEW] <ChannelType>, <ChannelName>

This command adds an additional measurement channel.

The number of measurement channels you can configure at the same time depends on available memory.

See also

- [INSTrument\[:SElect\]](#) on page 597
- [INSTrument:CREate:DUPLicate](#) on page 593

Parameters:

<ChannelType> Channel type of the new channel.
 For a list of available channel types see [INSTrument:LIST?](#) on page 595.

<ChannelName> String containing the name of the channel. The channel name is displayed as the tab label for the measurement channel.
 Note: If the specified name for a new channel already exists, the default name, extended by a sequential number, is used for the new channel (see [INSTrument:LIST?](#) on page 595).

Example: `INST:CRE SAN, 'Spectrum 2'`
 Adds an additional spectrum display named "Spectrum 2".

Manual operation: See "[New Channel](#)" on page 106

INSTrument:CREate:REPLace <ChannelName1>, <ChannelType>, <ChannelName2>

This command replaces a measurement channel with another one.

Setting parameters:

<ChannelName1> String containing the name of the measurement channel you want to replace.

<ChannelType> Channel type of the new channel.
 For a list of available channel types see [INSTrument:LIST?](#) on page 595.

<ChannelName2> String containing the name of the new channel.
 Note: If the specified name for a new channel already exists, the default name, extended by a sequential number, is used for the new channel (see [INSTrument:LIST?](#) on page 595).

Example: `INST:CRE:REPL 'Spectrum2', IQ, 'IQAnalyzer'`
 Replaces the channel named 'Spectrum2' by a new measurement channel of type 'IQ Analyzer' named 'IQAnalyzer'.

Usage: Setting only

Manual operation: See "[Replace Current Channel](#)" on page 106

INSTrument:DELeTe <ChannelName>

This command deletes a measurement channel.

If you delete the last measurement channel, the default "Spectrum" channel is activated.

Parameters:

<ChannelName> String containing the name of the channel you want to delete.
 A measurement channel must exist in order to be able delete it.

Example: `INST:DEL 'Spectrum4'`
 Deletes the channel with the name 'Spectrum4'.

Usage: Event

INSTrument:LIST?

This command queries all active measurement channels. This is useful in order to obtain the names of the existing measurement channels, which are required in order to replace or delete the channels.

Return values:

<ChannelType>, <ChannelName> For each channel, the command returns the channel type and channel name (see tables below).
 Tip: to change the channel name, use the [INSTrument:REName](#) command.

Example: `INST:LIST?`
 Result for 3 measurement channels:
 'ADEM', 'Analog Demod', 'IQ', 'IQ Analyzer', 'IQ', 'IQ Analyzer2'

Usage: Query only

Table 11-1: Available measurement channel types and default channel names in Signal and Spectrum Analyzer mode

Application	<ChannelType> Parameter	Default Channel Name*)
Spectrum	SANALYZER	Spectrum
I/Q Analyzer	IQ	IQ Analyzer
Analog Demodulation (R&S FPS-K7)	ADEM	Analog Demod
GSM (R&S FPS-K10)	GSM	GSM
Noise (R&S FPS-K30)	NOISE	Noise
Phase Noise (R&S FPS-K40)	PNOISE	Phase Noise
VSA (R&S FPS-K70)	DDEM	VSA
3GPP FDD BTS (R&S FPS-K72)	BWCD	3G FDD BTS
3GPP FDD UE (R&S FPS-K73)	MWCD	3G FDD UE
TD-SCDMA BTS (R&S FPS-K76)	BTDS	TD-SCDMA BTS
TD-SCDMA UE (R&S FPS-K77)	MTDS	TD-SCDMA UE
cdma2000 BTS (R&S FPS-K82)	BC2K	CDMA2000 BTS
cdma2000 MS (R&S FPS-K83)	MC2K	CDMA2000 MS
1xEV-DO BTS (R&S FPS-K84)	BDO	1xEV-DO BTS
1xEV-DO MS (R&S FPS-K85)	MDO	1xEV-DO MS
WLAN (R&S FPS-K91)	WLAN	WLAN
LTE (R&S FPS-K10x)	LTE	LTE

Note: the default channel name is also listed in the table. If the specified name for a new channel already exists, the default name, extended by a sequential number, is used for the new channel.

INSTRument:MODE <OpMode>

The operating mode of the R&S FPS determines which applications are available and active. Whenever you change the operating mode, the currently active measurement channels are stored. The default operating mode is Signal and Spectrum Analyzer mode, however, the presetting can be changed.

For details on operating modes and applications see [chapter 4, "Applications and Operating Modes"](#), on page 99.

Parameters:

<OpMode>

SANalyzer

Signal and Spectrum Analyzer mode

MSRAnalyzer

Multi-Standard Radio Analysis (MSRA) mode

*RST: SAN

Example: `INST:MODE MSR`
Switches to MSRA mode.

Usage: SCPI confirmed

INSTrument:REName <ChannelName1>, <ChannelName2>

This command renames a measurement channel.

Parameters:

<ChannelName1> String containing the name of the channel you want to rename.

<ChannelName2> String containing the new channel name.
Note that you can not assign an existing channel name to a new channel; this will cause an error.

Example: `INST:REN 'Spectrum2', 'Spectrum3'`
Renames the channel with the name 'Spectrum2' to 'Spectrum3'.

Usage: Setting only

INSTrument[:SElect] <ChannelType> | <ChannelName>

This command activates a new measurement channel with the defined channel type, or selects an existing measurement channel with the specified name.

Also see

- [INSTrument:CREate\[:NEW\]](#) on page 594
- [chapter 11.4.3, "Programming Example: Performing a Sequence of Measurements"](#), on page 601

Parameters:

<ChannelType> Channel type of the new channel.
For a list of available channel types see [INSTrument:LIST?](#) on page 595.

<ChannelName> String containing the name of the channel.

Example: `INST IQ`
Activates a measurement channel for the I/Q Analyzer application (evaluation mode).
`INST 'MyIQSpectrum'`
Selects the measurement channel named 'MyIQSpectrum' (for example before executing further commands for that channel).

Usage: SCPI confirmed

Manual operation:	See "Spectrum" on page 101
	See "1xEV-DO BTS" on page 101
	See "1xEV-DO MS" on page 102
	See "3G FDD BTS" on page 102
	See "3G FDD UE" on page 102
	See "Analog Demodulation" on page 102
	See "cdma2000 BTS" on page 102
	See "cdma2000 MS" on page 103
	See "GSM" on page 103
	See "I/Q Analyzer" on page 103
	See "LTE" on page 103
	See "Noise Figure" on page 103
	See "Phase Noise" on page 103
	See "TD-SCDMA BTS" on page 104
	See "TD-SCDMA UE" on page 104
	See "Vector Signal Analysis (VSA)" on page 104
	See "WLAN" on page 104
	See "New Channel" on page 106

11.4.2 Performing a Sequence of Measurements

The following commands control the sequencer.

For details on the Sequencer see [chapter 4.5.1, "The Sequencer Concept"](#), on page 107.

INITiate<n>:SEQuencer:ABORt	598
INITiate<n>:SEQuencer:IMMediate	598
INITiate<n>:SEQuencer:MODE	599
SYSTem:SEQuencer	600

INITiate<n>:SEQuencer:ABORt

This command stops the currently active sequence of measurements. The Sequencer itself is not deactivated, so you can start a new sequence immediately using [INITiate<n>:SEQuencer:IMMediate](#) on page 598.

To deactivate the Sequencer use [SYSTem:SEQuencer](#) on page 600.

Suffix:

<n> irrelevant

Usage: Event

Manual operation: See "[Sequencer State](#)" on page 109

INITiate<n>:SEQuencer:IMMediate

This command starts a new sequence of measurements by the Sequencer.

Its effect is similar to the [INITiate<n>\[:IMMediate\]](#) command used for a single measurement.

Before this command can be executed, the Sequencer must be activated (see [SYSTem:SEQuencer](#) on page 600).

Suffix:

<n> irrelevant

Example:

```
SYST:SEQ ON
```

Activates the Sequencer.

```
INIT:SEQ:MODE SING
```

Sets single sequence mode so each active measurement will be performed once.

```
INIT:SEQ:IMM
```

Starts the sequential measurements.

Usage:

Event

Manual operation: See "[Sequencer State](#)" on page 109

INITiate<n>:SEQuencer:MODE <Mode>

This command selects the way the R&S FPS application performs measurements sequentially.

Before this command can be executed, the Sequencer must be activated (see [SYSTem:SEQuencer](#) on page 600).

A detailed programming example is provided in [chapter 11.4.3, "Programming Example: Performing a Sequence of Measurements"](#), on page 601.

A detailed programming example is provided in the "Operating Modes" chapter in the R&S FPS User Manual.

Note: In order to synchronize to the end of a sequential measurement using *OPC, *OPC? or *WAI you must use SINGle Sequence mode.

For details on synchronization see [chapter 10.1.4, "Command Sequence and Synchronization"](#), on page 553

For details on synchronization see the "Remote Basics" chapter in the R&S FPS User Manual.

Suffix:

<n> irrelevant

Parameters:

<Mode>

SINGle

Each measurement is performed once (regardless of the channel's sweep mode), considering each channels' sweep count, until all measurements in all active channels have been performed.

CONTInuous

The measurements in each active channel are performed one after the other, repeatedly (regardless of the channel's sweep mode), in the same order, until the Sequencer is stopped.

CDEFined

First, a single sequence is performed. Then, only those channels in continuous sweep mode (`INIT:CONT ON`) are repeated.

*RST: CONTInuous

Example:

```
SYST:SEQ ON
```

Activates the Sequencer.

```
INIT:SEQ:MODE SING
```

Sets single sequence mode so each active measurement will be performed once.

```
INIT:SEQ:IMM
```

Starts the sequential measurements.

Manual operation: See "[Sequencer Mode](#)" on page 109

SYSTem:SEQuencer <State>

This command turns the Sequencer on and off. The Sequencer must be active before any other Sequencer commands (`INIT:SEQ...`) are executed, otherwise an error will occur.

A detailed programming example is provided in [chapter 11.4.3, "Programming Example: Performing a Sequence of Measurements"](#), on page 601.

A detailed programming example is provided in the "Operating Modes" chapter in the R&S FPS User Manual.

Parameters:

<State>

ON | OFF | 0 | 1

ON | 1

The Sequencer is activated and a sequential measurement is started immediately.

OFF | 0

The Sequencer is deactivated. Any running sequential measurements are stopped. Further Sequencer commands (`INIT:SEQ...`) are not available.

*RST: 0

Example:

```

SYST:SEQ ON
Activates the Sequencer.
INIT:SEQ:MODE SING
Sets single Sequencer mode so each active measurement will
be performed once.
INIT:SEQ:IMM
Starts the sequential measurements.
SYST:SEQ OFF

```

Manual operation: See "[Sequencer State](#)" on page 109

11.4.3 Programming Example: Performing a Sequence of Measurements

This example demonstrates how to perform several measurements in a sequence in a remote environment.

```

//2xSpectrumAnalyzer + 2xIQ, start Sequencer at the end, test OPC?
// -----

//-----Preparing the instrument and first channel -----
*RST
//Activate new IQ channel
INSTrument:CREate:NEW IQ,'IQ 1'
//Set sweep count for new IQ channel
SENS:SWEEP:COUNT 6
//Change trace modes for IQ channel
DISP:TRAC1:MODE BLANK
DISP:TRAC2:MODE MAXH
DISP:TRAC3:MODE MINH
//Switch to single sweep mode
INIT:CONT OFF
//switch back to first (default) analyzer channel
INST:SEL 'Spectrum';*WAI
//Switch into SEM
SENSe:SWEEp:MODE ESpectrum
//Load Sem standard file for W-CDMA
SENSe:ESpectrum:PRESet:STANdard 'WCDMA\3GPP\DL\3GPP_DL.xml'
//Set sweep count in Spectrum channel
SENS:SWEEP:COUNT 5

//-----Creating a second measurement channel -----

//Create second IQ channel
INSTrument:CREate:NEW IQ,'IQ 2'
//Set sweep count
SENS:SWEEP:COUNT 2
//Change trace modes
DISP:TRAC1:MODE MAXH

```

Selecting the Operating Mode and Application

```

DISP:TRAC2:MODE MINH
//Create new analyzer channel
INSTrument:CREate:NEW SANalyzer,'Spectrum 2'
//Activate ACLR measurement in channel 'Spectrum 2'
CALCulate:MARKer:FUNCTion:POWer:SElect ACPower
//Load W-CDMA Standard
CALCulate:MARKer:FUNCTion:POWer:PRESet FW3Gppcdma
//Change trace modes
DISP:TRAC2:MODE MAXH
DISP:TRAC1:MODE MINH

//-----Performing a sweep and retrieving results-----

//Change sweep count
SENS:SWEep:COUNT 7
//Single Sweep mode
INIT:CONT OFF
//Switch back to first IQ channel
INST:SEL 'IQ 1';*WAI
//Perform a measurement
INIT:IMM;*OPC?
//Retrieve results
CALC:MARK:Y?
//Activate Multiview
DISPlay:ATAB ON

//-----Performing a sequence of measurements with the Sequencer-----
//Activate Sequencer
SYSTem:SEQuencer ON
//Start sweep in Sequencer
INITiate:SEQuencer:IMMediate;*OPC?
//Switch into first IQ channel to get results
INST:SEL 'IQ 1';*WAI
CALCulate:MARKer:MAXimum
CALC:MARK:Y?
//Change sweep time in IQ
SENS:SWE:TIME 300us
//Switch to single Sequencer mode
INITiate:SEQuencer:MODE SINGLE
//Sweep all channels once, taking the sweep count in each channel into account
INITiate:SEQuencer:IMMediate;*OPC?
//Set marker to maximum in IQ1 and query result
CALCulate:MARKer:MAXimum
CALC:MARK:Y?
//Switch to second IQ channel and retrieve results
INST:SEL 'IQ 2';*WAI
CALCulate:MARKer:MIN
CALC:MARK:Y?
//Switch to first Spectrum channel
INST:SEL 'Spectrum';*WAI

```

```
//Query one of the SEM results
CALCulate:MARKer:FUNCTion:POWer:RESult? CPOWer
//Switch to second Spectrum channel
INST:SEL 'Spectrum 2';*WAI
//Query channel power result
CALCulate:MARKer:FUNCTion:POWer:RESult? ACPower
```

11.5 Configuring and Performing Measurements

The following commands are required to configure measurements in a remote environment. The tasks for manual operation are described in [chapter 5, "Measurements"](#), on page 111.

• Performing Measurements	603
• Configuring Power Measurements	607
• Measuring the Channel Power and ACLR	611
• Measuring the Carrier-to-Noise Ratio	647
• Measuring the Occupied Bandwidth	647
• Measuring the Spectrum Emission Mask	649
• Measuring Spurious Emissions	684
• Analyzing Statistics (APD, CCDF)	697
• Measuring the Time Domain Power	706
• Measuring the Harmonic Distortion	715
• Measuring the Third Order Intercept Point	718
• Measuring the AM Modulation Depth	720
• List Evaluations	722
• Measuring the Pulse Power	727

11.5.1 Performing Measurements

Useful commands for performing measurements described elsewhere

- [INITiate<n>:ESpectrum](#) on page 651
- [INITiate<n>:SPURious](#) on page 685

Remote commands exclusive for performing measurements:

ABORt	603
INITiate<n>:CONMeas	604
INITiate<n>:CONTinuous	605
INITiate<n>:[IMMediate]	606
[SENSe:]SWEp:COUNT:CURRent?	606

ABORt

This command aborts the measurement in the current measurement channel and resets the trigger system.

To prevent overlapping execution of the subsequent command before the measurement has been aborted successfully, use the `*OPC?` or `*WAI` command after `ABOR` and before the next command.

For details see [chapter 10.1.4.1, "Preventing Overlapping Execution"](#), on page 554.

For details see the "Remote Basics" chapter in the R&S FPS User Manual.

To abort a sequence of measurements by the Sequencer, use the `INITiate<n>:SEQuencer:ABORt` command.

Note on blocked remote control programs:

If a sequential command cannot be completed, for example because a triggered sweep never receives a trigger, the remote control program will never finish and the remote channel to the R&S FPS is blocked for further commands. In this case, you must interrupt processing on the remote channel first in order to abort the measurement.

To do so, send a "Device Clear" command from the control instrument to the R&S FPS on a parallel channel to clear all currently active remote channels. Depending on the used interface and protocol, send the following commands:

- **Visa:** `viClear()`

Now you can send the `ABORt` command on the remote channel performing the measurement.

Example: `ABOR; :INIT:IMM`
Aborts the current measurement and immediately starts a new one.

Example: `ABOR; *WAI`
`INIT:IMM`
Aborts the current measurement and starts a new one once abortion has been completed.

Usage: Event
SCPI confirmed

INITiate<n>:CONMeas

This command restarts a (single) measurement that has been stopped (using `ABORt`) or finished in single sweep mode.

The measurement is restarted at the beginning, not where the previous measurement was stopped.

As opposed to `INITiate<n>[:IMMEDIATE]`, this command does not reset traces in maxhold, minhold or average mode. Therefore it can be used to continue measurements using maxhold or averaging functions.

Suffix:
<n> irrelevant

Example:

```
INIT:CONT OFF
Switches to single sweep mode.
DISP:WIND:TRAC:MODE AVER
Switches on trace averaging.
SWE:COUN 20
Setting the sweep counter to 20 sweep s.
INIT;*WAI
Starts the measurement and waits for the end of the 20 sweep s.
INIT:CONM;*WAI
Continues the measurement (next 20 sweep s) and waits for the
end.
Result: Averaging is performed over 40 sweep s.
```

Usage: Event

Manual operation: See ["Continue Single Sweep"](#) on page 363

INITiate<n>:CONTInuous <State>

This command controls the sweep mode for an individual measurement channel.

Note that in single sweep mode, you can synchronize to the end of the measurement with *OPC, *OPC? or *WAI. In continuous sweep mode, synchronization to the end of the measurement is not possible. Thus, it is not recommended that you use continuous sweep mode in remote control, as results like trace data or markers are only valid after a single sweep end synchronization.

For details on synchronization see [chapter 10.1.4, "Command Sequence and Synchronization"](#), on page 553

If the sweep mode is changed for a measurement channel while the Sequencer is active (see [INITiate<n>:SEQuencer:IMMediate](#) on page 598) the mode is only considered the next time the measurement in that channel is activated by the Sequencer.

Suffix:

<n> irrelevant

Parameters:

<State> ON | OFF | 0 | 1
ON | 1
 Continuous sweep
OFF | 0
 Single sweep
 *RST: 0

Example:

```
INIT:CONT OFF
Switches the sweep mode to single sweep .
INIT:CONT ON
Switches the sweep mode to continuous sweep .
```

Manual operation: See ["Frequency Sweep"](#) on page 112
 See ["Zero Span"](#) on page 112
 See ["Continuous Sweep/RUN CONT"](#) on page 363

INITiate<n>[:IMMEDIATE]

This command starts a (single) new measurement.

With sweep count or average count > 0, this means a restart of the corresponding number of measurements. With trace mode MAXHold, MINHold and AVERage, the previous results are reset on restarting the measurement.

You can synchronize to the end of the measurement with *OPC, *OPC? or *WAI.

For details on synchronization see [chapter 10.1.4, "Command Sequence and Synchronization"](#), on page 553

For details on synchronization see the "Remote Basics" chapter in the R&S FPS User Manual.

Suffix:

<n> irrelevant

Example:

```
INIT:CONT OFF
Switches to single sweep mode.
DISP:WIND:TRAC:MODE AVER
Switches on trace averaging.
SWE:COUN 20
Sets the sweep counter to 20 sweep s.
INIT;*WAI
Starts the measurement and waits for the end of the 20 sweep s.
```

Usage: Event

Manual operation: See ["Frequency Sweep"](#) on page 112
 See ["Zero Span"](#) on page 112
 See ["Single Sweep/ RUN SINGLE"](#) on page 363

[SENSe:]SWEep:COUNT:CURRent?

This query returns the current number of started sweeps or measurements. This command is only available if a sweep count value is defined and the instrument is in single sweep mode.

Example:

```
SWE:COUNt 64
Sets sweep count to 64
INIT:CONT OFF
Switches to single sweep mode
INIT
Starts a sweep (without waiting for the sweep end!)
SWE:COUN:CURR?
Queries the number of started sweeps
```

Usage: Query only

11.5.2 Configuring Power Measurements

The following commands work for several power measurements.

<code>CALCulate<n>:MARKer<m>:FUNction:POWer:MODE</code>	607
<code>CALCulate<n>:MARKer<m>:FUNction:POWer<sb>:RESult?</code>	607
<code>CALCulate<n>:MARKer<m>:FUNction:POWer:SELect</code>	609
<code>CALCulate<n>:MARKer<m>:FUNction:POWer[:STATe]</code>	609
<code>[SENSe:]POWer:ACHannel:PRESet</code>	610
<code>[SENSe:]POWer:ACHannel:PRESet:RLEVel</code>	610
<code>[SENSe:]POWer:TRACe</code>	611

`CALCulate<n>:MARKer<m>:FUNction:POWer:MODE` <Mode>

This command selects the trace display mode for power measurements.

Parameters:

<Mode>

WRITE

The power is calculated from the current trace.

MAXHold

The power is calculated from the current trace and compared with the previous power value using a maximum algorithm.

Manual operation: See "[Power Mode](#)" on page 156

`CALCulate<n>:MARKer<m>:FUNction:POWer<sb>:RESult?` <Measurement>

This command queries the results of power measurements (<n>, <m> are irrelevant).

To get a valid result, you have to perform a complete measurement with synchronization to the end of the measurement before reading out the result. This is only possible for single sweep mode.

See also `INITiate<n>:CONTinuous` on page 605.

Suffix:

<sb>

1 | 2 | 3 (4 | 5)

irrelevant

Query parameters:

<Measurement>

ACPower | MCACpower

ACLR measurements (also known as adjacent channel power or multicarrier adjacent channel measurements).

Returns the power for every active transmission and adjacent channel. The order is:

- power of the transmission channels
- power of adjacent channel (lower,upper)
- power of alternate channels (lower,upper)

MSR ACLR results:

For MSR ACLR measurements, the order of the returned results is slightly different:

- power of the transmission channels
- total power of the transmission channels for each sub block
- power of adjacent channels (lower, upper)
- power of alternate channels (lower, upper)
- power of gap channels (lower1, upper1, lower2, upper2)

The unit of the return values depends on the scaling of the y-axis:

- logarithmic scaling returns the power in the current unit
- linear scaling returns the power in W

CN

Carrier-to-noise measurements.

Returns the C/N ratio in dB.

CNO

Carrier-to-noise measurements.

Returns the C/N ratio referenced to a 1 Hz bandwidth in dBm/Hz.

CPOWer

Channel power measurements.

Returns the channel power. The unit of the return values depends on the scaling of the y-axis:

- logarithmic scaling returns the power in the current unit
- linear scaling returns the power in W

For SEM measurements, the return value is the channel power of the reference range (in the specified sub block).

PPOWer

Peak power measurements.

Returns the peak power. The unit of the return values depends on the scaling of the y-axis:

- logarithmic scaling returns the power in the current unit
- linear scaling returns the power in W

For SEM measurements, the return value is the peak power of the reference range (in the specified sub block).

OBANdwidth | OBWidth

Occupied bandwidth.

Returns the occupied bandwidth in Hz.

Usage:

Query only

Manual operation: See "Ch Power ACLR" on page 113
 See "C/N, C/No" on page 113
 See "OBW" on page 113
 See "Spectrum Emission Mask" on page 114
 See "C/N" on page 189
 See "C/No" on page 189

CALCulate<n>:MARKer<m>:FUNCTION:POWER:SElect <MeasType>

This command selects a power measurement and turns the measurement on.

Parameters:

<MeasType>

ACPower | MCACpower

Adjacent channel leakage ratio (ACLR) aka adjacent channel power or multicarrier adjacent channel.

The R&S FPS performs the measurement on the trace selected with [SENSe:]POWER:TRACe.

CPOWER

Channel power measurement with a single carrier.

The R&S FPS performs the measurement on the trace selected with [SENSe:]POWER:TRACe.

OBANdwidth | OBWidth

Occupied bandwidth measurement.

The R&S FPS performs the measurement on the trace that marker 1 is positioned on.

CN

Carrier-to-noise ratio measurement.

CNO

Carrier-to-noise ratio measurement referenced to 1 Hz bandwidth

Manual operation: See "Ch Power ACLR" on page 113
 See "C/N, C/No" on page 113
 See "OBW" on page 113
 See "C/N" on page 189
 See "C/No" on page 189

CALCulate<n>:MARKer<m>:FUNCTION:POWER[:STATe] <State>

This command turns a power measurement on and off.

The suffixes <n> and <m> are irrelevant.

Parameters:

<State> ON | OFF
ON | 1
 The power measurement selected with `CALCulate<n>`:
`MARKer<m>:FUNCTION:POWER:SElect` is activated.
OFF | 0
 A standard frequency sweep is activated.
 *RST: OFF

Usage: Setting only

Manual operation: See "C/N" on page 189
 See "C/No" on page 189

[SENSe:]POWER:ACHannel:PRESet <Measurement>

This command determines the ideal span, bandwidths and detector for the current power measurement.

To get a valid result, you have to perform a complete measurement with synchronization to the end of the measurement before reading out the result. This is only possible for single sweep mode.

See also `INITiate<n>:CONTinuous` on page 605.

Parameters:

<Measurement> **ACPower | MCACpower**
 ACLR measurement
CPOWER
 channel power measurement
OBANdwidth | OBWidth
 Occupied bandwidth measurement
CN
 Carrier to noise ratio
CNO
 Carrier to noise ration referenced to a 1 Hz bandwidth

Manual operation: See "Optimized Settings (Adjust Settings)" on page 156
 See "Adjust Settings" on page 190
 See "Adjust Settings" on page 194

[SENSe:]POWER:ACHannel:PRESet:RLEVel

This command determines the ideal reference level for the current measurement.

This automatic routine makes sure that the that the signal power level does not overload the R&S FPS or limit the dynamic range by too small a S/N ratio.

To determine the best reference level, the R&S FPS aborts current measurements and performs a series of test sweeps. After it has finished the test, it continues with the actual measurement.

To get a valid result, you have to perform a complete sweep with synchronization to the sweep end. This is only possible in single sweep mode.

Usage: Event

[SENSe:]POWer:TRACe <TraceNumber>

This command selects the trace channel power measurements are performed on.

For the measurement to work, the corresponding trace has to be active.

Parameters:

<TraceNumber> Range: 1 to 6
*RST: 1

Example: POW:TRAC 2
Assigns the measurement to trace 2.

Manual operation: See "[Selected Trace](#)" on page 155

11.5.3 Measuring the Channel Power and ACLR

All remote control commands specific to channel power or ACLR measurements are described here.



See also [chapter 11.5.2, "Configuring Power Measurements"](#), on page 607.

- [Managing Measurement Configurations](#)..... 611
- [Configuring the Channels](#)..... 613
- [Defining Weighting Filters](#)..... 617
- [Selecting the Reference Channel](#)..... 619
- [Checking Limits](#)..... 620
- [General ACLR Measurement Settings](#)..... 626
- [Configuring MSR ACLR Measurements](#)..... 626
- [Performing an ACLR Measurement](#)..... 640
- [Analyzing Measurement Results](#)..... 640
- [Programming Examples for Channel Power Measurements](#)..... 642

11.5.3.1 Managing Measurement Configurations

The following commands control measurement configurations for ACLR measurements.

- CALCulate<n>:MARKer<m>:FUNction:POWer:PRESet..... 612
- CALCulate<n>:MARKer<m>:FUNction:POWer:STANdard:CATalog?..... 612
- CALCulate<n>:MARKer<m>:FUNction:POWer:STANdard:DELeTe..... 612
- CALCulate<n>:MARKer<m>:FUNction:POWer:STANdard:SAVE..... 612

CALCulate<n>:MARKer<m>:FUNction:POWer:PRESet <Standard>

This command loads a measurement configuration.

The measurement configuration for power measurements consists of weighting filter, channel bandwidth and spacing, resolution and video bandwidth, detector and sweep time.

If the "Multi-Standard Radio" standard is selected (see ["Standard"](#) on page 152), different commands are required to configure ACLR measurements (see [chapter 11.5.3.7, "Configuring MSR ACLR Measurements"](#), on page 626).

Parameters:

<Standard> For more information see [chapter 5.3.9, "Reference: Predefined CP/ACLR Standards"](#), on page 185.
If you want to load a customized configuration, the parameter is a string containing the file name.

Manual operation: See ["Predefined Standards"](#) on page 152
See ["User-Defined Standards"](#) on page 152

CALCulate<n>:MARKer<m>:FUNction:POWer:STANdard:CATalog?

This command queries all files containing ACLR standards.

Return values:

<Standards> List of standard files.

Usage: Query only

Manual operation: See ["User-Defined Standards"](#) on page 152

CALCulate<n>:MARKer<m>:FUNction:POWer:STANdard:DELeTe <Standard>

This command deletes a file containing an ACLR standard.

Parameters:

<Standard> String containing the file name of the standard.

Usage: Event

Manual operation: See ["User-Defined Standards"](#) on page 152

CALCulate<n>:MARKer<m>:FUNction:POWer:STANdard:SAVE <Standard>

This command saves the current ACLR measurement configuration as a new ACLR standard.

The measurement configuration for power measurements consists of weighting filter, channel bandwidth and spacing, resolution and video bandwidth, detector and sweep time.

Parameters:

<Standard> String containing the file name. The file format is xml.

Manual operation: See ["User-Defined Standards"](#) on page 152

11.5.3.2 Configuring the Channels

The following commands configure channels for channel power and ACLR measurements.

[SENSe:]POWer:ACHannel:ACPairs.....	613
[SENSe:]POWer:ACHannel:BANDwidth BWIDth:ACHannel.....	613
[SENSe:]POWer:ACHannel:BANDwidth BWIDth:ALternate<ch>.....	613
[SENSe:]POWer:ACHannel:BANDwidth BWIDth[:CHANnel<ch>].....	614
[SENSe:]POWer:ACHannel:NAME:ACHannel.....	614
[SENSe:]POWer:ACHannel:NAME:ALternate<ch>.....	614
[SENSe:]POWer:ACHannel:NAME:CHANnel<ch>.....	615
[SENSe:]POWer:ACHannel:SPACing[:ACHannel].....	615
[SENSe:]POWer:ACHannel:SPACing:ALternate<ch>.....	615
[SENSe:]POWer:ACHannel:SPACing:CHANnel<ch>.....	616
[SENSe:]POWer:ACHannel:TXCHannel:COUnT.....	616

[SENSe:]POWer:ACHannel:ACPairs <ChannelPairs>

This command defines the number of pairs of adjacent and alternate channels.

Parameters:

<ChannelPairs> Range: 0 to 12
 *RST: 1

Manual operation: See ["Number of Channels \(Tx, ADJ\)"](#) on page 154
 See ["Number of Adjacent Channels \(ADJ Count\)"](#) on page 171

[SENSe:]POWer:ACHannel:BANDwidth|BWIDth:ACHannel <Bandwidth>

This command defines the channel bandwidth of the adjacent channels.

The adjacent channels are the first channels to the left and right of the transmission channels. If you set the channel bandwidth for these channels, the R&S FPS sets the bandwidth of the alternate channels to the same value (not for MSR signals).

Steep-edged channel filters are available for fast ACLR measurements.

Parameters:

<Bandwidth> Range: 100 Hz to 1000 MHz
 *RST: 14 kHz

Manual operation: See ["Channel Bandwidths"](#) on page 158
 See ["Adjacent Channel Bandwidths"](#) on page 172

[SENSe:]POWer:ACHannel:BANDwidth|BWIDth:ALternate<ch> <Bandwidth>

This command defines the channel bandwidth of the alternate channels.

If you set the channel bandwidth for the first alternate channel, the R&S FPS sets the bandwidth of the other alternate channels to the same value, but not the other way round (not for MSR signals). The command works hierarchically: to set a bandwidth of the 3rd and 4th channel, you have to set the bandwidth of the 3rd channel first.

Steep-edged channel filters are available for fast ACLR measurements.

Suffix:

<ch> 1 to 11
Alternate channel number

Parameters:

<Bandwidth> Range: 100 Hz to 1000 MHz
*RST: 14 kHz

Manual operation: See ["Channel Bandwidths"](#) on page 158
See ["Adjacent Channel Bandwidths"](#) on page 172

[SENSe:]POWer:ACHannel:BANDwidth|BWIDth[:CHANnel<ch>] <Bandwidth>

This command defines the channel bandwidth of the transmission channels.

Steep-edged channel filters are available for fast ACLR measurements.

Suffix:

<ch> 1 to 18
Tx channel number

Parameters:

<Bandwidth> Range: 100 Hz to 1000 MHz
*RST: 14 kHz

Manual operation: See ["Channel Bandwidths"](#) on page 158
See ["Channel Bandwidth"](#) on page 190
See ["Channel Bandwidth"](#) on page 194

[SENSe:]POWer:ACHannel:NAME:ACHannel <Name>

This command defines a name for the adjacent channel.

For MSR ACLR measurements, this command defines the name for the lower adjacent channel in asymmetric channel definitions. To define the name for the upper adjacent channel use the [\[SENSe:\]POWer:ACHannel:NAME:UACHannel](#) command.

Parameters:

<Name> String containing the name of the channel
*RST: ADJ

Manual operation: See ["Channel Names"](#) on page 160

[SENSe:]POWer:ACHannel:NAME:ALternate<ch> <Name>

This command defines a name for an alternate channel.

For MSR ACLR measurements, this command defines the name for the lower alternate channel in asymmetric channel definitions. To define the name for the upper alternate channels use the `[SENSe:]POWer:ACHannel:NAME:UALTernate<ch>` command.

Suffix:

<ch> 1 to 11
Alternate channel number

Parameters:

<Name> String containing the name of the channel
*RST: ALT<1...11>

Manual operation: See "Channel Names" on page 160

`[SENSe:]POWer:ACHannel:NAME:CHANnel<ch>` <Name>

This command defines a name for a transmission channel.

Suffix:

<ch> 1 to 18
Tx channel number

Parameters:

<Name> String containing the name of the channel
*RST: TX<1...12>

Manual operation: See "Channel Names" on page 160

`[SENSe:]POWer:ACHannel:SPACing[:ACHannel]` <Spacing>

This command defines the distance from transmission channel to adjacent channel.

For MSR signals, this command defines the distance from the CF of the first Tx channel in the first sub block to the lower adjacent channel. To configure the spacing for the upper adjacent channel in asymmetrical configurations, use the `[SENSe:]POWer:ACHannel:SPACing:UACHannel` command.

A change of the adjacent channel spacing causes a change in the spacing of all alternate channels below the adjacent channel (not for MSR signals).

Parameters:

<Spacing> Range: 100 Hz to 2000 MHz
*RST: 14 kHz

Usage: SCPI confirmed

Manual operation: See "Channel Spacings" on page 158
See "Adjacent Channel Spacings" on page 171

`[SENSe:]POWer:ACHannel:SPACing:ALTernate<ch>` <Spacing>

This command defines the distance from transmission channel to alternate channels.

For MSR signals, this command defines the distance from the CF of the first Tx channel in the first sub block to the lower alternate channel. To configure the spacing for the upper alternate channel in asymmetrical configurations, use the `[SENSe:]POWer:ACHannel:SPACing:UALTernate<ch>` command.

If you set the channel spacing for the first alternate channel, the R&S FPS adjusts the spacing of alternate channels of a lower order, but not the other way round (not for MSR signals). The command works hierarchically: to set a distance from the transmission channel to the 2nd and 3rd alternate channel, you have to define a spacing for the 2nd alternate channel first.

Suffix:

<ch> 1 to 11
Alternate channel number

Parameters:

<Spacing> Range: 100 Hz to 2000 MHz
 *RST: 40 kHz (ALT1), 60 kHz (ALT2), 80 kHz (ALT3), ...

Manual operation: See "[Channel Spacings](#)" on page 158
See "[Adjacent Channel Spacings](#)" on page 171

[SENSe:]POWer:ACHannel:SPACing:CHANnel<ch> <Spacing>

This command defines the distance between transmission channels.

If you set the channel spacing for a transmission channel, the R&S FPS sets the spacing of the lower transmission channels to the same value, but not the other way round. The command works hierarchically: to set a distance between the 2nd and 3rd and 3rd and 4th channel, you have to set the spacing between the 2nd and 3rd channel first.

Suffix:

<ch> 1 to 18
Tx channel number

Parameters:

<Spacing> Range: 14 kHz to 2000 MHz
 *RST: 20 kHz

Manual operation: See "[Channel Spacings](#)" on page 158

[SENSe:]POWer:ACHannel:TXChannel:COUNT <Number>

This command defines the number of transmission channels.

The command works for measurements in the frequency domain.

Parameters:

<Number> Range: 1 to 18
 *RST: 1

Manual operation: See "[Number of Channels \(Tx, ADJ\)](#)" on page 154

11.5.3.3 Defining Weighting Filters

The following commands define weighting filters for ACLR measurements.

[SENSe:]POWer:ACHannel:FILTer:ALPHa:ACHannel.....	617
[SENSe:]POWer:ACHannel:FILTer:ALPHa[:ALL].....	617
[SENSe:]POWer:ACHannel:FILTer:ALPHa:ALTErnate<ch>.....	617
[SENSe:]POWer:ACHannel:FILTer:ALPHa:CHANnel<ch>.....	618
[SENSe:]POWer:ACHannel:FILTer[:STATe]:ACHannel.....	618
[SENSe:]POWer:ACHannel:FILTer[:STATe]:ALL.....	618
[SENSe:]POWer:ACHannel:FILTer[:STATe]:ALTErnate<ch>.....	618
[SENSe:]POWer:ACHannel:FILTer[:STATe]:CHANnel<ch>.....	618

[SENSe:]POWer:ACHannel:FILTer:ALPHa:ACHannel <Alpha>

This command defines the roll-off factor for the adjacent channel weighting filter.

Parameters:

<Alpha>	Roll-off factor
	Range: 0 to 1
	*RST: 0.22

Manual operation: See "Weighting Filters" on page 160
See "Weighting Filters" on page 172

[SENSe:]POWer:ACHannel:FILTer:ALPHa[:ALL] <Value>

This command defines the alpha value for the weighting filter for all channels.

Parameters:

<Value>	<numeric value>
	*RST: 0.22

Example: POW:ACH:FILT:ALPH:ALL 0.35

[SENSe:]POWer:ACHannel:FILTer:ALPHa:ALTErnate<ch> <Alpha>

This command defines the roll-off factor for the alternate channel weighting filter.

Suffix:

<ch>	1 to 11
	Alternate channel number

Parameters:

<Alpha>	Roll-off factor
	Range: 0 to 1
	*RST: 0.22

Manual operation: See "Weighting Filters" on page 160
See "Weighting Filters" on page 172

[SENSe:]POWer:ACHannel:FILTER:ALPHA:CHANnel<ch> <Alpha>

This command defines the roll-off factor for the transmission channel weighting filter.

Suffix:

<ch> 1 to 18
Tx channel number

Parameters:

<Alpha> Roll-off factor
Range: 0 to 1
*RST: 0.22

Manual operation: See ["Weighting Filters"](#) on page 160

[SENSe:]POWer:ACHannel:FILTER[:STATe]:ACHannel <State>

This command turns the weighting filter for the adjacent channel on and off.

Parameters:

<State> ON | OFF
*RST: OFF

Manual operation: See ["Weighting Filters"](#) on page 160
See ["Weighting Filters"](#) on page 172

[SENSe:]POWer:ACHannel:FILTER[:STATe]:ALL <State>

This command turns the weighting filters for all channels on and off.

Parameters:

<State> ON | OFF
*RST: OFF

[SENSe:]POWer:ACHannel:FILTER[:STATe]:ALTErnate<ch> <State>

This command turns the weighting filter for an alternate channel on and off.

Suffix:

<ch> 1 to 11
Alternate channel number

Parameters:

<State> ON | OFF
*RST: OFF

Manual operation: See ["Weighting Filters"](#) on page 160
See ["Weighting Filters"](#) on page 172

[SENSe:]POWer:ACHannel:FILTER[:STATe]:CHANnel<ch> <State>

This command turns the weighting filter for a transmission channel on and off.

Suffix:

<ch> 1 to 18
Tx channel number

Parameters:

<State> ON | OFF
*RST: OFF

Manual operation: See "[Weighting Filters](#)" on page 160

11.5.3.4 Selecting the Reference Channel

The following commands define the reference channel for relative ACLR measurements.

[SENSe:]POWer:ACHannel:REFerence:AUTO ONCE.....	619
[SENSe:]POWer:ACHannel:REFerence:TXCHannel:AUTO.....	619
[SENSe:]POWer:ACHannel:REFerence:TXCHannel:MANual.....	620

[SENSe:]POWer:ACHannel:REFerence:AUTO ONCE

This command sets the channel power as the reference for relative ACLR measurements.

Example: POW:ACH:REF:AUTO ONCE

Usage: Event

Manual operation: See "[Setting a Fixed Reference for Channel Power Measurements \(Set CP Reference\)](#)" on page 156

[SENSe:]POWer:ACHannel:REFerence:TXCHannel:AUTO <RefChannel>

This command selects the reference channel for relative measurements.

You need at least one channel for the command to work.

Parameters:

<RefChannel> **MINimum**
Transmission channel with the lowest power

MAXimum
Transmission channel with the highest power

LHIGhest
Lowest transmission channel for lower adjacent channels and highest transmission channel for upper adjacent channels

Example: POW:ACH:REF:TXCH:AUTO MAX
Selects the channel with the peak power as reference channel.

Manual operation: See "[Reference Channel](#)" on page 154

[SENSe:]POWer:ACHannel:REFerence:TXCHannel:MANual <ChannelNumber>

This command defines a reference channel for relative ACLR measurements.

You need at least one channel for the command to work.

Note that this command is not available for MSR ACLR measurements (see [CALCulate<n>:MARKer<m>:FUNction:POWer:PRESet](#) on page 612).

Parameters:

<ChannelNumber> Range: 1 to 18
*RST: 1

Manual operation: See "Reference Channel" on page 154

11.5.3.5 Checking Limits

The following commands configure and query limit checks for channel power and ACLR measurements.



The results of the power limit checks are also indicated in the `STAT:QUES:ACPL` status registry (see "[STATus:QUESTionable:ACPLimit Register](#)" on page 564).

<code>CALCulate<n>:LIMit<k>:ACPower:ACHannel:ABSolute</code>	620
<code>CALCulate<n>:LIMit<k>:ACPower:ACHannel:ABSolute:STATe</code>	621
<code>CALCulate<n>:LIMit<k>:ACPower:ACHannel[:RELative]</code>	621
<code>CALCulate<n>:LIMit<k>:ACPower:ACHannel:RESult?</code>	622
<code>CALCulate<n>:LIMit<k>:ACPower:ACHannel[:RELative]:STATe</code>	622
<code>CALCulate<n>:LIMit<k>:ACPower:ALTernate<ch>:ABSolute</code>	623
<code>CALCulate<n>:LIMit<k>:ACPower:ALTernate<ch>:ABSolute:STATe</code>	623
<code>CALCulate<n>:LIMit<k>:ACPower:ALTernate<ch>[:RELative]</code>	624
<code>CALCulate<n>:LIMit<k>:ACPower:ALTernate<ch>:RESult?</code>	624
<code>CALCulate<n>:LIMit<k>:ACPower:ALTernate<ch>[:RELative]:STATe</code>	625
<code>CALCulate<n>:LIMit<k>:ACPower[:STATe]</code>	625

CALCulate<n>:LIMit<k>:ACPower:ACHannel:ABSolute <LowerLimit>, <UpperLimit>

This command defines the absolute limit of the adjacent channels.

(<n>, <k> are irrelevant.)

If you have defined an absolute limit as well as a relative limit, the R&S FPS uses the lower value for the limit check.

Parameters:

<LowerLimit> The limit of the lower adjacent channel.
Range: -200 dBm to 200 dBm
*RST: -200 dBm

<UpperLimit> The limit of the upper adjacent channel.
 Range: -200 dBm to 200 dBm
 *RST: -200 dBm

Manual operation: See "[Limit Checking](#)" on page 159
 See "[Limit Checking](#)" on page 172

CALCulate<n>:LIMit<k>:ACPoweR:ACHannel:ABSolute:STATe <State>,<State>

This command turns the absolute limit check for the adjacent channels on and off.

(<n>, <k> are irrelevant.)

You have to activate the general ACLR limit check before using this command with
[CALCulate<n>:LIMit<k>:ACPoweR\[:STATe\]](#).

Parameters:

<State> ON | OFF
 Absolute limit check for lower adjacent channel
 *RST: OFF

<State> ON | OFF
 Absolute limit check for upper adjacent channel
 *RST: OFF

Manual operation: See "[Limit Checking](#)" on page 159
 See "[Limit Checking](#)" on page 172

CALCulate<n>:LIMit<k>:ACPoweR:ACHannel[:RELative] <LowerLimit>,
 <UpperLimit>

This command defines the relative limit of the adjacent channels. The reference value for the relative limit is the measured channel power.

(<n>, <k> are irrelevant.)

If you have defined an absolute limit as well as a relative limit, the R&S FPS uses the lower value for the limit check.

Parameters:

<LowerLimit> The limit of the lower adjacent channel.
 Range: 0 dB to 100 dB
 *RST: 0 dB
 Default unit: dB

<UpperLimit> The limit of the upper adjacent channel.
 Range: 0 dB to 100 dB
 *RST: 0 dB
 Default unit: dB

Manual operation: See "[Limit Checking](#)" on page 159
 See "[Limit Checking](#)" on page 172

CALCulate<n>:LIMit<k>:ACPpower:ACHannel:RESult?

This command queries the state of the limit check for the adjacent channels in an ACLR measurement.

(<n>, <k> are irrelevant.)

To get a valid result, you have to perform a complete measurement with synchronization to the end of the measurement before reading out the result. This is only possible for single sweep mode.

See also [INITiate<n>:CONTinuous](#) on page 605.

Return values:

<LowerACH>, text value
<UpperACH> The command returns two results. The first is the result for the lower, the second for the upper adjacent channel.

PASSED

Limit check has passed.

FAIL

Limit check has failed.

Example:

```
INIT:IMM;*WAI;
CALC:LIM:ACP:ACH:RES?
PASSED,PASSED
```

Usage: Query only

Manual operation: See "[Limit Checking](#)" on page 159
See "[Limit Checking](#)" on page 172

CALCulate<n>:LIMit<k>:ACPpower:ACHannel[:RELative]:STATe <State>,<State>

This command turns the relative limit check for the adjacent channels on and off.

(<n>, <k> are irrelevant.)

You have to activate the general ACLR limit check before using this command with [CALCulate<n>:LIMit<k>:ACPpower\[:STATe\]](#).

Parameters:

<State> ON | OFF
Relative limit check for lower adjacent channel
*RST: OFF

<State> ON | OFF
Relative limit check for upper adjacent channel
*RST: OFF

Manual operation: See "[Limit Checking](#)" on page 159
See "[Limit Checking](#)" on page 172

CALCulate<n>:LIMit<k>:ACPpower:ALTErnate<ch>:ABSolute <LowerLimit>, <UpperLimit>

This command defines the absolute limit of the alternate channels.

(<n>, <k> are irrelevant.)

If you have defined an absolute limit as well as a relative limit, the R&S FPS uses the lower value for the limit check.

Suffix:

<ch> 1 to 11
Alternate channel number

Parameters:

<LowerLimit> The limit of the lower adjacent channel.
Range: -200 dBm to 200 dBm
*RST: -200 dBm

<UpperLimit> The limit of the upper adjacent channel.
Range: -200 dBm to 200 dBm
*RST: -200 dBm

Manual operation: See "[Limit Checking](#)" on page 159
See "[Limit Checking](#)" on page 172

CALCulate<n>:LIMit<k>:ACPpower:ALTErnate<ch>:ABSolute:STATe <State>,<State>

This command turns the absolute limit check for the alternate channels on and off.

(<n>, <k> are irrelevant.)

You have to activate the general ACLR limit check before using this command with [CALCulate](#)<n>:LIMit<k>:ACPpower[:STATe].

Suffix:

<ch> 1 to 11
Alternate channel number

Parameters:

<State> ON | OFF
Absolute limit check for lower alternate channel
*RST: OFF

<State> ON | OFF
Absolute limit check for upper alternate channel
*RST: OFF

Manual operation: See "[Limit Checking](#)" on page 159
See "[Limit Checking](#)" on page 172

CALCulate<n>:LIMit<k>:ACPowEr:ALTErnate<ch>[:RELative] <LowerLimit>, <UpperLimit>

This command defines the relative limit of the alternate channels. The reference value for the relative limit is the measured channel power.

(<n>, <k> are irrelevant.)

If you have defined an absolute limit as well as a relative limit, the R&S FPS uses the lower value for the limit check.

Suffix:

<ch> 1 to 11
Alternate channel number

Parameters:

<LowerLimit> The limit of the lower alternate channel.
Range: 0 dB to 100 dB
*RST: 0 dB
Default unit: dB

<UpperLimit> The limit of the upper alternate channel.
Range: 0 dB to 100 dB
*RST: 0 dB
Default unit: dB

Manual operation: See "[Limit Checking](#)" on page 159
See "[Limit Checking](#)" on page 172

CALCulate<n>:LIMit<k>:ACPowEr:ALTErnate<ch>:RESult?

This command queries the state of the limit check for the adjacent or alternate channels in an ACLR measurement.

(<n>, <k> are irrelevant.)

To get a valid result, you have to perform a complete measurement with synchronization to the end of the measurement before reading out the result. This is only possible for single sweep mode.

See also [INITiate<n>:CONTinuous](#) on page 605.

Suffix:

<ch> 1 to 11
Alternate channel number

Return values:

<LowerChan>, text value
<UpperChan> The command returns two results. The first is the result for the lower, the second for the upper adjacent or alternate channel.

PASSED

Limit check has passed.

FAIL

Limit check has failed.

Example: INIT:IMM;*WAI;
 CALC:LIM:ACP:ACH:RES?
 PASSED,PASSED

Usage: Query only

CALCulate<n>:LIMit<k>:ACPpower:ALternate<ch>[:RELative]:STATe
 <State>,<State>

This command turns the relative limit check for the alternate channels on and off.

(<n>, <k> are irrelevant.)

You have to activate the general ACLR limit check before using this command with
[CALCulate<n>:LIMit<k>:ACPpower\[:STATe\]](#).

Suffix:

<ch> 1 to 11
 Alternate channel number

Parameters:

<State> ON | OFF
 Relative limit check for lower alternate channel
 *RST: OFF

<State> ON | OFF
 Relative limit check for upper alternate channel
 *RST: OFF

Manual operation: See "[Limit Checking](#)" on page 159
 See "[Limit Checking](#)" on page 172

CALCulate<n>:LIMit<k>:ACPpower[:STATe] <State>

This command turns the limit check for ACLR measurements on and off.

In addition, limits must be defined and activated individually for each channel (see
[CALCulate<n>:LIMit<k>:ACPpower:ACHannel\[:RELative\]:STATe](#),
[CALCulate<n>:LIMit<k>:ACPpower:ALternate<ch>\[:RELative\]:STATe](#),
[CALCulate<n>:LIMit<k>:ACPpower:GAP<gap>:ABSolute:STATe](#),
[CALCulate<n>:LIMit<k>:ACPpower:GAP<gap>:ACLR\[:RELative:\]STATe](#) and
[CALCulate<n>:LIMit<k>:ACPpower:GAP<gap>\[:CACLR\]\[:RELative:\]STATe](#)).

(<n>, <k> are irrelevant.)

Parameters:

<State> ON | OFF
 *RST: OFF

Manual operation: See "[Limit Checking](#)" on page 159
 See "[Limit Checking](#)" on page 167
 See "[Limit Checking](#)" on page 172
 See "[Limit Checking](#)" on page 175

11.5.3.6 General ACLR Measurement Settings

The following commands control the measurement algorithm.

Useful commands for the ACLR measurement described elsewhere:

- [\[SENSe:\]POWER:NCORrection](#) on page 756
- [\[SENSe:\]POWER:ACHannel:PRESet](#) on page 610
- [\[SENSe:\]POWER:ACHannel:PRESet:RLEVel](#) on page 610
- [\[SENSe:\]POWER:TRACe](#) on page 611
- [CALCulate<n>:MARKer<m>:FUNction:POWER:MODE](#) on page 607

Remote commands exclusive to ACLR measurement

[\[SENSe:\]POWER:HSPeEd](#)..... 626

[SENSe:]POWER:HSPeEd <State>

This command turns high speed ACLR and channel power measurements on and off.

If on, the R&S FPS performs a measurement on each channel in the time domain. It returns to the frequency domain when the measurement is done.

In some telecommunications standards, high speed measurements use weighting filters with characteristic or steep-edged channel filters for band limitation.

Parameters:

<State> ON | OFF
 *RST: OFF

Example: POW:HSP ON

Manual operation: See "[Fast ACLR](#)" on page 155

11.5.3.7 Configuring MSR ACLR Measurements

If the "Multi-Standard Radio" standard is selected (see [CALCulate<n>:MARKer<m>:FUNction:POWER:PRESet](#) on page 612), the channels for the ACLR measurement are configured differently. (For more information see [chapter 5.3.3.4, "Measurement on Multi-Standard Radio \(MSR\) Signals"](#), on page 146.)

In this case, use the following commands.

- [General MSR ACLR Measurement Settings](#).....626
- [MSR Sub Block and Tx Channel Setup](#)..... 627
- [MSR Adjacent Channel Setup](#)..... 629
- [MSR Gap Channel Setup](#).....634
- [MSR Channel Names](#)..... 639

General MSR ACLR Measurement Settings

Useful commands for configuring general MSR ACLR settings described elsewhere:

- [CALCulate<n>:MARKer<m>:FUNction:POWER:PRESet](#) on page 612

- `CALCulate<n>:MARKer<m>:FUNction:POWer<sb>:RESult?` on page 607
- `CALCulate<n>:MARKer<m>:FUNction:POWer:RESult:PHZ` on page 641
- `CALCulate<n>:MARKer<m>:FUNction:POWer:MODE` on page 607
- `CALCulate<n>:LIMit<k>:ACPower[:STATE]` on page 625
- `[SENSe:]POWer:ACHannel:REFerence:TXCHannel:AUTO` on page 619
- `[SENSe:]POWer:NCORrection` on page 756
- `[SENSe:]POWer:TRACe` on page 611
- `[SENSe:]POWer:ACHannel:MODE` on page 642
- `[SENSe:]POWer:ACHannel:PRESet` on page 610
- `[SENSe:]POWer:ACHannel:SSEtup` on page 632

MSR Sub Block and Tx Channel Setup

The functions for manual operation are described in [chapter 5.3.5.2, "MSR Sub Block and Tx Channel Definition"](#), on page 167.

Useful commands for configuring Tx channels described elsewhere:

- `[SENSe:]POWer:ACHannel:SBLOCK<sb>:NAME[:CHANnel<ch>]` on page 640

Remote commands exclusive to configuring sub blocks and Tx channels

<code>[SENSe:]POWer:ACHannel:FILTer:ALPHa:SBLOCK<sb>:CHANnel<ch></code>	627
<code>[SENSe:]POWer:ACHannel:FILTer:STATE:SBLOCK<sb>:CHANnel<ch></code>	628
<code>[SENSe:]POWer:ACHannel:SBCount</code>	628
<code>[SENSe:]POWer:ACHannel:SBLOCK<sb>:BANDwidth[BWIDth[:CHANnel<ch>]]</code>	628
<code>[SENSe:]POWer:ACHannel:SBLOCK<sb>:CENTer[:CHANnel<ch>]</code>	629
<code>[SENSe:]POWer:ACHannel:SBLOCK<sb>:FREQuency:CENTer</code>	629

`[SENSe:]POWer:ACHannel:FILTer:ALPHa:SBLOCK<sb>:CHANnel<ch>` <Alpha>

This command defines the roll-off factor for the specified transmission channel's weighting filter.

Suffix:

<sb>	1 2 3 4 5 sub block number
<ch>	1 to 18 Tx channel number

Parameters:

<Alpha>	Roll-off factor
	Range: 0 to 1
	*RST: 0.22

Manual operation: See "[Weighting Filters](#)" on page 170

[SENSe:]POWer:ACHannel:FILTer:STATe:SBLOCK<sb>:CHANnel<ch> <State>

This command turns the weighting filter for the specified transmission channel on and off.

Suffix:

<sb> 1 | 2 | 3 | 4 | 5
 sub block number

<ch> 1 to 18
 Tx channel number

Parameters:

<State> ON | OFF
 *RST: W-CDMA: ON, other technologies: OFF

Manual operation: See "[Weighting Filters](#)" on page 170

[SENSe:]POWer:ACHannel:SBCount <Number>

This command defines the number of sub blocks, i.e. groups of transmission channels in an MSR signal.

For more information see [chapter 5.3.3.4, "Measurement on Multi-Standard Radio \(MSR\) Signals"](#), on page 146.

Parameters:

<Number> Range: 1 to 5
 *RST: 1

Manual operation: See "[Number of Sub Blocks](#)" on page 164

**[SENSe:]POWer:ACHannel:SBLOCK<sb>:BANDwidth[BWIDth[:CHANnel<ch>]]
 <Bandwidth>**

This command defines the bandwidth of the specified MSR Tx channel.

This command is for MSR signals only (see [CALCulate<n>;MARKer<m>;FUNction:POWer:PRESet](#) on page 612).

Suffix:

<sb> 1 | 2 | 3 | 4 | 5
 sub block number

<ch> 1 to 18
 Tx channel number

Parameters:

<Bandwidth> Bandwidth in Hz

Manual operation: See "[Tx Channel Bandwidth](#)" on page 169

[SENSe:]POWer:ACHannel:SBLock<sb>:CENTer[:CHANnel<ch>] <Frequency>

This command defines the (absolute) center frequency of the specified MSR Tx channel.

Note that the position of the first Tx channel in the first sub block and the last Tx channel in the last sub block also affect the position of the adjacent channels.

This command is for MSR signals only (see [CALCulate<n>:MARKer<m>:FUNction:POWer:PRESet](#) on page 612).

Suffix:

<sb> 1 | 2 | 3 | 4 | 5
 sub block number

<ch> 1 to 18
 Tx channel number

Parameters:

<Frequency> absolute frequency in Hz

Manual operation: See "[Tx Center Frequency](#)" on page 169

[SENSe:]POWer:ACHannel:SBLock<sb>:FREQUENCY:CENTer <Frequency>

This command defines the center of the specified MSR sub block. Note that the position of the sub block also affects the position of the adjacent gap (CACLR) channels.

This command is for MSR signals only (see [CALCulate<n>:MARKer<m>:FUNction:POWer:PRESet](#) on page 612).

Suffix:

<sb> 1 | 2 | 3 | 4 | 5
 sub block number

Parameters:

<Frequency> absolute frequency in Hz

Manual operation: See "[Sub Block Center Frequency](#)" on page 168

MSR Adjacent Channel Setup

The functions for manual operation are described in [chapter 5.3.5.3, "MSR Adjacent Channel Setup"](#), on page 170.

Useful commands for MSR adjacent channel setup described elsewhere:

- [chapter 11.5.3.5, "Checking Limits"](#), on page 620
- "[MSR Channel Names](#)" on page 639

Remote commands exclusive to MSR adjacent channel setup:

[SENSe:]POWer:ACHannel:SBLock<sb>:RFBWidth.....630
[SENSe:]POWer:ACHannel:SBLock<sb>:TECHnology[:CHANnel<ch>].....630
[SENSe:]POWer:ACHannel:SBLock<sb>:TXCHannel:COUNT.....631
[SENSe:]POWer:ACHannel:SPACing:UACHannel.....631

[SENSe:]POWer:ACHannel:SPACing:UALTernate<ch>.....	632
[SENSe:]POWer:ACHannel:SSETup.....	632
[SENSe:]POWer:ACHannel:BANDwidth BWIDth:UACHannel.....	632
[SENSe:]POWer:ACHannel:BANDwidth BWIDth:UALTernate<ch>.....	633
[SENSe:]POWer:ACHannel:FILTer:ALPHa:UACHannel.....	633
[SENSe:]POWer:ACHannel:FILTer:ALPHa:UALTernate<ch>.....	633
[SENSe:]POWer:ACHannel:FILTer[:STATe]:UACHannel.....	634
[SENSe:]POWer:ACHannel:FILTer[:STATe]:UALTernate<ch>.....	634

[SENSe:]POWer:ACHannel:SBLock<sb>:RFBWidth <Bandwidth>

This command defines the bandwidth of the individual MSR sub block. Note that sub block ranges also affect the position of the adjacent gap channels (CACLR).

This command is for MSR signals only (see [CALCulate<n>;MARKer<m>;FUNction:POWer:PRESet](#) on page 612).

Suffix:

<sb> 1 | 2 | 3 | 4 | 5
 sub block number

Parameters:

<Bandwidth> Bandwidth in Hz

Manual operation: See "RF Bandwidth" on page 168

[SENSe:]POWer:ACHannel:SBLock<sb>:TECHnology[:CHANnel<ch>] <Standard>

This command defines the technology used for transmission by the specified MSR Tx channel.

This command is for MSR signals only (see [CALCulate<n>;MARKer<m>;FUNction:POWer:PRESet](#) on page 612).

Suffix:

<sb> 1 | 2 | 3 | 4 | 5
 sub block number

<ch> 1 to 18
 Tx channel number

Parameters:

<Standard> GSM | WCDMA | LTE_1_40 | LTE_3_00 | LTE_5_00 |
 LTE_10_00 | LTE_15_00 | LTE_20_00 | USER
 Technology used for transmission

GSM
 Transmission according to GSM standard

WCDMA
 Transmission according to W-CDMA standard

**LTE_1_40 | LTE_3_00 | LTE_5_00 | LTE_10_00 | LTE_15_00 |
 LTE_20_00**
 Transmission according to LTE standard for different channel
 bandwidths

USER
 User-defined transmission; no automatic preconfiguration possi-
 ble

Manual operation: See "[Technology Used for Transmission](#)" on page 169

[SENSe:]POWer:ACHannel:SBLOCK<sb>:TXChannel:COUNT <Number>

This command defines the number of transmission channels the specific sub block contains.

This command is for MSR signals only (see [CALCulate<n>:MARKer<m>:FUNction:POWer:PRESet](#) on page 612).

Suffix:

<sb> 1 | 2 | 3 | 4 | 5
 sub block number

Parameters:

<Number> Range: 1 to 18
 *RST: 1

Manual operation: See "[Number of Tx Channels \(Tx Count\)](#)" on page 168

[SENSe:]POWer:ACHannel:SPACing:UACHannel <Spacing>

This command defines the distance from the transmission channel to the upper adjacent channel.

For MSR signals, this command defines the distance from the CF of the last Tx channel in the last sub block to the upper adjacent channel in asymmetrical configurations. To configure the spacing for the lower adjacent channel use the [\[SENSe:\]POWer:ACHannel:SPACing\[:ACHannel\]](#) command.

Parameters:

<Spacing> Range: 100 Hz to 2000 MHz
 *RST: 14 kHz

Usage: SCPI confirmed

Manual operation: See ["Adjacent Channel Spacings"](#) on page 171

[SENSe:]POWer:ACHannel:SPACing:UALTernate<ch> <Spacing>

This command defines the distance from transmission channel to the upper alternate channels.

For MSR signals, this command defines the distance from the CF of the last Tx channel in the last sub block to the upper alternate channel in asymmetrical configurations. To configure the spacing for the lower alternate channel, use the [\[SENSe:\]POWer:ACHannel:SPACing:ALTernate<ch>](#) command.

Suffix:

<ch> 1 to 11
Alternate channel number

Parameters:

<Spacing> Range: 100 Hz to 2000 MHz
*RST: 40 kHz (ALT1), 60 kHz (ALT2), 80 kHz (ALT3), ...

Manual operation: See ["Adjacent Channel Spacings"](#) on page 171

[SENSe:]POWer:ACHannel:SSETup <State>

This command defines whether adjacent channels are defined symmetrically or not.

For more information see [chapter 5.3.3.4, "Measurement on Multi-Standard Radio \(MSR\) Signals"](#), on page 146.

Parameters:

<State> ON | OFF | 1 | 0
ON | 1
The upper and lower adjacent and alternate channels are defined symmetrically. This is the default behaviour and corresponds to the behavior in firmware versions before 2.10.
OFF | 0
The upper and lower channels can be configured differently.
*RST: ON

Manual operation: See ["Symmetrical Adjacent Setup"](#) on page 167

[SENSe:]POWer:ACHannel:BANDwidth|BWIDth:UACHannel <Bandwidth>

This command defines the channel bandwidth of the upper adjacent channel in asymmetrical configurations.

The adjacent channel is the first pair of channels next to the transmission channels. To configure the bandwidth for the lower adjacent channel, use the [\[SENSe:\]POWer:ACHannel:BANDwidth|BWIDth:ACHannel](#) command.

Steep-edged channel filters are available for fast ACLR measurements.

Parameters:

<Bandwidth> Range: 100 Hz to 1000 MHz
 *RST: 14 kHz

Manual operation: See ["Adjacent Channel Bandwidths"](#) on page 172

[SENSe:]POWer:ACHannel:BAWIDth|BWIDth:UALTernate<ch> <Bandwidth>

This command defines the channel bandwidth of the upper alternate channels in asymmetrical configurations. To configure the bandwidth for the lower alternate channel, use the [\[SENSe:\]POWer:ACHannel:BAWIDth|BWIDth:ALTernate<ch>](#) command.

Steep-edged channel filters are available for fast ACLR measurements.

Suffix:

<ch> 1 to 11
 Alternate channel number

Parameters:

<Bandwidth> Range: 100 Hz to 1000 MHz
 *RST: 14 kHz

Manual operation: See ["Adjacent Channel Bandwidths"](#) on page 172

[SENSe:]POWer:ACHannel:FILTer:ALPHa:UACHannel <Alpha>

This command defines the roll-off factor for the upper adjacent channel weighting filter for asymmetrical MSR signals. To configure the factor for the upper adjacent channel, use the [\[SENSe:\]POWer:ACHannel:FILTer:ALPHa:ACHannel](#) command.

Parameters:

<Alpha> Roll-off factor
 Range: 0 to 1
 *RST: 0.22

Manual operation: See ["Weighting Filters"](#) on page 172

[SENSe:]POWer:ACHannel:FILTer:ALPHa:UALTernate<ch> <Alpha>

This command defines the roll-off factor for the upper alternate channels' weighting filter for asymmetrical MSR signals. To configure the factor for the upper alternate channels, use the [\[SENSe:\]POWer:ACHannel:FILTer:ALPHa:UALTernate<ch>](#) command.

Suffix:

<ch> 1 to 11
 Alternate channel number

Parameters:

<Alpha> Roll-off factor
 Range: 0 to 1
 *RST: 0.22

Manual operation: See ["Weighting Filters"](#) on page 172

[SENSe:]POWer:ACHannel:FILTer[:STATe]:UACHannel <State>

This command turns the weighting filter for the upper adjacent channel on and off for asymmetrical MSR signals. To configure the factor for the lower adjacent channel, use the `[SENSe:]POWer:ACHannel:FILTer[:STATe]:ACHannel` command.

Parameters:

<State> ON | OFF
 *RST: OFF

Manual operation: See ["Weighting Filters"](#) on page 172

[SENSe:]POWer:ACHannel:FILTer[:STATe]:UALTernate<ch> <State>

This command turns the weighting filter for the upper alternate channels on and off for asymmetrical MSR signals. To configure the factor for the lower alternate channels, use the `[SENSe:]POWer:ACHannel:FILTer[:STATe]:ALTernate<ch>` command.

Suffix:

<ch> 1 to 11
 Alternate channel number

Parameters:

<State> ON | OFF
 *RST: OFF

Manual operation: See ["Weighting Filters"](#) on page 172

MSR Gap Channel Setup

The functions for manual operation are described in [chapter 5.3.5.4, "MSR Gap Channel Setup"](#), on page 173.

<code>CALCulate<n>:LIMit<k>:ACPower:GAP<gap>:ABSolute</code>	635
<code>CALCulate<n>:LIMit<k>:ACPower:GAP<gap>:ABSolute:STATe</code>	635
<code>CALCulate<n>:LIMit<k>:ACPower:GAP<gap>:ACLR[:RELative]</code>	635
<code>CALCulate<n>:LIMit<k>:ACPower:GAP<gap>:ACLR[:RELative:]STATe</code>	636
<code>CALCulate<n>:LIMit<k>:ACPower:GAP<gap>[:CACLR][:RELative]</code>	636
<code>CALCulate<n>:LIMit<k>:ACPower:GAP<gap>[:CACLR][:RELative:]STATe</code>	636
<code>[SENSe:]POWer:ACHannel:AGCHannels</code>	637
<code>[SENSe:]POWer:ACHannel:BANDwidth BWIDth:GAP<gap></code>	637
<code>[SENSe:]POWer:ACHannel:FILTer:ALPHa:GAP<gap></code>	638
<code>[SENSe:]POWer:ACHannel:FILTer:STATe:GAP<gap></code>	638
<code>[SENSe:]POWer:ACHannel:GAP<gap>:MSIZe</code>	638
<code>[SENSe:]POWer:ACHannel:SPACing:GAP<gap></code>	639

CALCulate<n>:LIMit<k>:ACPpower:GAP<gap>:ABSolute <Limit>, <Reserved>

This command defines the absolute limit of the specified gap (CACLR) channel.

(<n>, <k> are irrelevant.)

If you have defined an absolute limit as well as a relative limit, the R&S FPS uses the lower value for the limit check.

Suffix:

<gap> 1 | 2
Gap (CACLR) channel number

Parameters:

<Limit> Defines the absolute limit of the specified gap channel in dBm.
<Reserved> Ignored.

Example: `CALC:LIM:ACP:GAP2:ABS 44.2dBm,0`

Manual operation: See "[Limit Checking](#)" on page 175

CALCulate<n>:LIMit<k>:ACPpower:GAP<gap>:ABSolute:STATe <State>

This command turns the absolute limit check for the specified gap (CACLR) channel on and off.

You have to activate the general ACLR limit check before using this command with `CALCulate<n>:LIMit<k>:ACPpower[:STATe]`.

Suffix:

<gap> 1 | 2
Gap (CACLR) channel number

<n>, <k> irrelevant

Parameters:

<State> ON | OFF
*RST: OFF

Manual operation: See "[Limit Checking](#)" on page 175

CALCulate<n>:LIMit<k>:ACPpower:GAP<gap>:ACLR[:RELative] <Limit>

This command defines the relative limit for the ACLR power in the specified gap channel. The reference value for the relative limit is the measured channel power.

(<n>, <k> are irrelevant.)

If you have defined an absolute limit as well as a relative limit, the R&S FPS uses the lower value for the limit check.

Suffix:

<gap> 1 | 2
Gap channel number

Parameters:

<Limit> Defines the relative limit for the ACLR power in the specified gap channel in dB.

Example:

```
CALC:LIM:ACP:GAP1:ACLR:REL 3dB
```

Manual operation: See "[Limit Checking](#)" on page 175

CALCulate<n>:LIMit<k>:ACPower:GAP<gap>:ACLR[:RELative:]STATe <State>

This command turns the relative limit check for the ACLR power in the specified gap channel on and off.

(<n>, <k> are irrelevant.)

You have to activate the general ACLR limit check before using this command with [CALCulate<n>:LIMit<k>:ACPower\[:STATe\]](#).

Suffix:

<gap> 1 | 2
Gap channel number

Parameters:

<State> ON | OFF
*RST: OFF

Example:

```
CALC:LIM:ACP:GAP1:ACLR:REL:STAT ON
```

Manual operation: See "[Limit Checking](#)" on page 175

CALCulate<n>:LIMit<k>:ACPower:GAP<gap>[:CACLR][:RELative] <Limit>

This command defines the relative limit for the CACLR power in the specified gap channel. The reference value for the relative limit is the measured channel power.

(<n>, <k> are irrelevant.)

If you have defined an absolute limit as well as a relative limit, the R&S FPS uses the lower value for the limit check.

Suffix:

<gap> 1 | 2
Gap channel number

Parameters:

<Limit> Defines the relative limit of the specified gap channel in dB.

Example:

```
CALC:LIM:ACP:GAP1:REL 3dB
```

Manual operation: See "[Limit Checking](#)" on page 175

CALCulate<n>:LIMit<k>:ACPower:GAP<gap>[:CACLR][:RELative:]STATe <State>

This command turns the relative limit check for the CACLR power in the specified gap channel on and off.

(<n>, <k> are irrelevant.)

You have to activate the general ACLR limit check before using this command with `CALCulate<n>:LIMit<k>:ACPower[:STATe]`.

Suffix:

<gap> 1 | 2
Gap channel number

Parameters:

<State> ON | OFF
*RST: OFF

Example: `CALC:LIM:ACP:GAP1:REL:STAT ON`

Manual operation: See "[Limit Checking](#)" on page 175

[SENSe:]POWer:ACHannel:AGCHannels <State>

This command activates or deactivates gap channels in an MSR signal.

For more information see [chapter 5.3.3.4, "Measurement on Multi-Standard Radio \(MSR\) Signals"](#), on page 146.

Parameters:

<State> ON | OFF | 1 | 0
ON | 1
The gap channels are displayed and channel power results are calculated and displayed in the Result Summary.
OFF | 0
The gap channels are not displayed in the diagram and channel power results are not calculated nor displayed in the Result Summary.
*RST: ON

Manual operation: See "[Activate Gaps](#)" on page 174

[SENSe:]POWer:ACHannel:BANDwidth|BWIDth:GAP<gap> <Bandwidth>

This command defines the bandwidth of the specified MSR gap (CACLR) channel.

This command is for MSR signals only (see `CALCulate<n>:MARKer<m>:FUNction:POWer:PRESet` on page 612).

Suffix:

<gap> 1 | 2
Gap (CACLR) channel number

Parameters:

<Bandwidth> numeric value in Hz
*RST: 3.84 MHz

Manual operation: See "[Gap Channel Bandwidths](#)" on page 175

[SENSe:]POWer:ACHannel:FILTER:ALPHA:GAP<gap> <Alpha>

This command defines the roll-off factor for the specified gap (CACLR) channel's weighting filter.

Suffix:

<gap> 1 | 2
Gap (CACLR) channel number

Parameters:

<Alpha> Roll-off factor
Range: 0 to 1
*RST: 0.22

Manual operation: See "[Weighting Filters](#)" on page 175

[SENSe:]POWer:ACHannel:FILTER:STATE:GAP<gap> <State>

This command turns the weighting filter for the specified gap (CACLR) channel on and off.

Suffix:

<gap> 1 | 2
Gap (CACLR) channel number

Parameters:

<State> ON | OFF
*RST: OFF

Manual operation: See "[Weighting Filters](#)" on page 175

[SENSe:]POWer:ACHannel:GAP<gap>:MSIZe <Bandwidth>

If the gap between the sub blocks does not exceed the specified bandwidth, the gap channels are not displayed in the diagram, and the gap channel results are not calculated in the result summary.

Suffix:

<gap> 1 | 2
Gap channel number

Parameters:

<Bandwidth> numeric value in Hz
*RST: gap1: 5 MHz; gap2: 10 MHz

Example: POW:ACH:GAP2:MSIZ 5MHZ

Usage: SCPI confirmed

Manual operation: See "[Minimum gap size to show gap 1/2](#)" on page 174

[SENSe:]POWer:ACHannel:SPACing:GAP<gap> <Spacing>

This command defines the distance from sub block to the specified gap channel.

The channels in the upper gap are identical to those in the lower gap. Thus, in the R&S FPS MSR ACLR measurement, only 2 gap channels are configured.

The spacing for gap channels is defined in relation to the outer edges of the surrounding sub blocks, i.e.

Spacing = [CF of the gap channel] - [left sub block center] + ([RF bandwidth of left sub block] / 2)

(See also [figure 5-24](#) and [figure 5-25](#).)

Suffix:

<gap> 1 | 2
 Gap channel number

Parameters:

<Spacing> numeric value in Hz
 *RST: 2.5 MHz

Usage: SCPI confirmed

Manual operation: See "[Gap Channel Spacings](#)" on page 174

MSR Channel Names

The functions for manual operation are described in [chapter 5.3.5.5, "MSR Channel Names"](#), on page 175.

[SENSe:]POWer:ACHannel:NAME:UACHannel.....	639
[SENSe:]POWer:ACHannel:NAME:UALTernate<ch>.....	639
[SENSe:]POWer:ACHannel:SBlock<sb>:NAME[:CHANnel<ch>].....	640

[SENSe:]POWer:ACHannel:NAME:UACHannel <Name>

This command defines the name for the upper adjacent channel in asymmetrical MSR channel definitions. To define the name for the lower adjacent channel use the [\[SENSe:\]POWer:ACHannel:NAME:ACHannel](#) command.

Parameters:

<Name> String containing the name of the channel
 *RST: ADJ

[SENSe:]POWer:ACHannel:NAME:UALTernate<ch> <Name>

This command defines the name for the specified upper alternate channel in asymmetrical MSR channel definitions. To define the name for the lower adjacent channels use the [\[SENSe:\]POWer:ACHannel:NAME:ALTernate<ch>](#) command.

Suffix:

<ch> 1 to 11
Alternate channel number

Parameters:

<Name> String containing the name of the channel
*RST: ALT<1...11>

[SENSe:]POWer:ACHannel:SBLock<sb>:NAME[:CHANnel<ch>] <Name>

This command defines the name of the specified MSR Tx channel.

This command is for MSR signals only.

Suffix:

<sb> 1 | 2 | 3 | 4 | 5
sub block number

<ch> 1 to 18
Tx channel number

Parameters:

<Name> String containing the name of the channel

Example: POW:ACH:SBL2:NAME:CHAN2 'B:WCDMA'

Manual operation: See "[Tx Channel Definition](#)" on page 168

11.5.3.8 Performing an ACLR Measurement

The following commands are required to perform an ACLR measurement:

CALC:MARK:FUNC:POW:SEL ACP, see [CALCulate<n>:MARKer<m>:FUNctIon:POWer:SElect](#) on page 609

[CALCulate<n>:MARKer<m>:FUNctIon:POWer\[:STATe\]](#) on page 609

[INITiate<n>\[:IMMediate\]](#) on page 606, see [chapter 11.5.1, "Performing Measurements"](#), on page 603

11.5.3.9 Analyzing Measurement Results

The following commands analyze and retrieve measurement results for ACLR measurements.

Useful commands for channel power measurements described elsewhere

- [CALCulate<n>:MARKer<m>:FUNctIon:POWer<sb>:RESult?](#) on page 607
- [TRACe<n>\[:DATA\]](#) on page 813

Remote commands exclusive to channel power measurements

CALCulate<n>:LIMit<k>:ACPower:GAP<gap>:RESult?	641
CALCulate<n>:MARKer<m>:FUNctIon:POWer:RESult:PHZ	641
[SENSe:]POWer:ACHannel:MODE	642

CALCulate<n>:LIMit<k>:ACPower:GAP<gap>:RESult?

This command queries the state of the limit check for *all* gap (CACLR) channels in an MSR ACLR measurement.

(<n>, <k> are irrelevant.)

To get a valid result, you have to perform a complete measurement with synchronization to the end of the measurement before reading out the result. This is only possible for single sweep mode.

See also [INITiate<n>:CONTinuous](#) on page 605.

The results of the power limit checks are also indicated in the `STAT:QUES:ACPL` status registry (see "[STATus:QUESTionable:ACPLimit Register](#)" on page 564).

Suffix:

<gap> 1 | 2
 irrelevant

Return values:

<LowerGap1>, The command returns the results for the four gap channels for
<UpperGap1>, each gap (max. 4).

<LowerGap2>, **PASSED**
<UpperGap2> Limit check has passed.

FAIL
Limit check has failed.

NONE
No results available, e.g. because limit checking was deactivated

Example:

```
INIT:IMM;*WAI;
CALC:LIM:ACP:GAP2:RES?
PASSED,PASSED,
```

Usage: Query only

Manual operation: See "[Limit Checking](#)" on page 175

CALCulate<n>:MARKer<m>:FUNctIon:POWer:RESult:PHZ <State>

This command selects the way the R&S FPS returns results for power measurements.

You can query results with `CALCulate<n>:MARKer<m>:FUNctIon:POWer<sb>:RESult?`.

Parameters:

<State> ON | OFF
ON
 Channel power density in dBm/Hz
OFF
 Channel power in dBm
 *RST: OFF

Example:

CALC:MARK:FUNC:POW:RES:PHZ ON
 Output of results referred to the channel bandwidth.

Manual operation: See ["Channel Power Levels and Density \(Power Unit\)"](#) on page 156

[SENSe:]POWer:ACHannel:MODE <Mode>

This command selects the way the R&S FPS displays the power of adjacent channels.

You need at least one adjacent channel for the command to work.

Parameters:

<Mode> **ABSolute**
 Shows the absolute power of all channels
RELative
 Shows the power of adjacent and alternate channels in relation to the transmission channel
 *RST: RELative

Manual operation: See ["Absolute and Relative Values \(ACLR Mode\)"](#) on page 155

11.5.3.10 Programming Examples for Channel Power Measurements

The following programming examples are meant to demonstrate the most important commands to perform channel power measurements in a remote environment.

- [Example: Configuring and Performing an ACLR Measurement](#).....642
- [Example: Configuring and Performing an MSR ACLR Measurement](#).....644

Example: Configuring and Performing an ACLR Measurement

In this example we will configure and perform an adjacent-channel power measurement. Note that this example is primarily meant to demonstrate the remote control commands, it does not necessarily reflect a useful measurement task. For most common measurement standards, the R&S FPS performs the measurement optimally with the predefined settings, without further configuration.

```
//-----Preparing the measurement-----
*RST
//Resets the instrument
INIT:CONT OFF
//Selects single sweep mode.
```

Configuring and Performing Measurements

```

CALC:MARK:FUNC:POW:SEL ACP
//Activates adjacent-channel power measurement.
CALC:MARK:FUNC:POW:PRES GSM
//Selects the user standard "GSM"

//-----Setting Up Channels-----
POW:ACH:TXCH:COUN 1
//Creates one transmission channel.
POW:ACH:NAME:CHAN1 'TX Channel'
//Names the first transmission channel 'TX Channel'.
POW:ACH:ACP 2
//Creates two adjacent channels - one adjacent channel and one alternate channel.
POW:ACH:NAME:ACH 'ABC'
//Names the adjacent channel 'ABC'
POW:ACH:NAME:ALT1 'XYZ'
//Names the first alternate channel 'XYZ'.
POW:ACH:BWID:CHAN1 30kHz
//Defines a bandwidth of 30 kHz for the transmission channel.
POW:ACH:BWID:ACH 30kHz
//Defines a bandwidth of 30 kHz for the adjacent channel.
POW:ACH:BWID:ALT1 30kHz
//Defines a bandwidth of 30 kHz for the first alternate channel.
POW:ACH:SPAC 33kHz
//Defines a distance of 33 kHz from the center of the transmission channel to the
//center of the adjacent channel.
//Also adjusts the distance to the alternate channels (66 kHz).
POW:ACH:SPAC:ALT1 100kHz
//Defines a distance of 100 kHz from the center of the transmission channel to the
//center of the first alternate channel.

//-----Selecting a Reference Channel--
POW:ACH:MODE REL
//Selects relative display of the channel power.
POW:ACH:REF:TXCH:MAN 1
//Defines transmission channel 1 as the reference channel.

//-----Saving the settings as a user standard-----
CALC:MARK:FUNC:POW:STAN:SAVE 'my_aclr_standard'
//Saves the user standard with the name "my_aclr_standard".
//Weighting filters can only be defined for user-defined standards.

//-----Defining Weighting Filters-----
POW:ACH:FILT:ALPH:CHAN1 0.35
//Defines a roll-off factor of 0.35 for the weighting filter of the first
//transmission channel.
POW:ACH:FILT:CHAN1 ON
//Turns the weighting filter for the first transmission channel on.
POW:ACH:FILT:ALPH:ACH 0.35
//Defines a roll-off factor of 0.35 for the weighting filter of the adjacent
//channel.

```

```

POW:ACH:FILT:ACH ON
//Turns the weighting filter for the adjacent channel on.
POW:ACH:FILT:ALPH:ALT1 0.35
//Defines a roll-off factor of 0.35 for the weighting filter of the first
//alternate channel.
POW:ACH:FILT:ALT1 ON
//Turns the weighting filter for the first alternate channel on.

//-----Working with Limits-----
CALC:LIM:ACP:ACH 30DB,30DB
//Defines a relative limit of 30 dB below the power of the reference channel
//for both adjacent channels.
CALC:LIM:ACP:ALT1 25DB,25DB
//Defines a relative limit of 25 dB below the power of the reference channel
//for the first alternate channels.
CALC:LIM:ACP:ACH:ABS -35DBM,-35DBM
//Defines an absolute limit of -35 dBm for both adjacent channels.
CALC:LIM:ACP ON
//Turns the ACLR limit check on.
CALC:LIM:ACP:ACH:STAT ON
//Turns the relative limit check for adjacent channels on.
CALC:LIM:ACP:ACH:ABS:STAT ON
//Turns the absolute limit check for adjacent channels on.
CALC:LIM:ACP:ALT1:ABS:STAT ON
//Turns the absolute limit check for the first alternate channel on.

//-----Performing the Measurement-----
POW:ACH:PRES ACP;*WAI
//Determines the ideal ACLR measurement configuration.
POW:ACH:PRES:RLEV;*WAI
//Determines the ideal reference level for the measurement.
INIT;*WAI
//Initiates a new measurement and waits until the sweep has finished.

//-----Limit Check-----
CALC:LIM:ACP:ACH:RES?
//Queries the results of the limit check for the adjacent channels.
CALC:LIM:ACP:ALT1:RES?
//Queries the results of the limit check for the first alternate channels.

//-----Retrieving Results-----
CALC:MARK:FUNC:POW:RES? ACP
//Returns the results for the ACLR measurement.

```

Example: Configuring and Performing an MSR ACLR Measurement

This example demonstrates how to configure and perform an ACLR measurement on a multi-standard radio signal in a remote environment.

```

//-----Preparing the instrument -----
//Reset the instrument

```

Configuring and Performing Measurements

```

*RST

// Select ACLR measurement
:CALCulate:MARKer:FUNCTION:POWER:SElect ACPower

// Select MSR Standard :CALCulate:MARKer:FUNCTION:POWER:PRESet MSR

//Configure general measurement settings
:SENSe:FREQuency:CENTer 1.25GHz
:SENSe:FREQuency:SPAN 62.0MHz
:SENSe:POWer:ACHannel:SBCount 3

//----- Configuring Sub block A

:SENSe:POWer:ACHannel:SBLock1:TXChannel:COUNT 3
:SENSe:POWer:ACHannel:SBLock1:FREQuency:CENTer 1.230GHZ
:SENSe:POWer:ACHannel:SBLock1:RFBWidth 12MHZ

:SENSe:POWer:ACHannel:SBLock1:CENTer:CHANnel1 1.226GHZ
:SENSe:POWer:ACHannel:SBLock1:CENTer:CHANnel2 1.230GHZ
:SENSe:POWer:ACHannel:SBLock1:CENTer:CHANnel3 1.234GHZ

:SENSe:POWer:ACHannel:SBLock1:TECHnology:CHANnel1 WCDMA
:SENSe:POWer:ACHannel:SBLock1:TECHnology:CHANnel2 WCDMA
:SENSe:POWer:ACHannel:SBLock1:TECHnology:CHANnel3 GSM

:SENSe:POWer:ACHannel:SBLock1:BANDwidth:CHANnel1 2.5MHZ
:SENSe:POWer:ACHannel:SBLock1:BANDwidth:CHANnel2 2.5MHZ
:SENSe:POWer:ACHannel:SBLock1:BANDwidth:CHANnel3 2.5MHZ

//----- Configuring Sub block B

:SENSe:POWer:ACHannel:SBLock2:TXChannel:COUNT 1
:SENSe:POWer:ACHannel:SBLock2:FREQuency:CENTer 1.255GHZ
:SENSe:POWer:ACHannel:SBLock2:RFBWidth 4MHZ

:SENSe:POWer:ACHannel:SBLock2:CENTer:CHANnel1 1.255GHZ

:SENSe:POWer:ACHannel:SBLock2:TECHnology:CHANnel1 LTE_1_40

:SENSe:POWer:ACHannel:SBLock2:BANDwidth:CHANnel1 3.25MHZ

//----- Configuring Sub block C

:SENSe:POWer:ACHannel:SBLock3:TXChannel:COUNT 2
:SENSe:POWer:ACHannel:SBLock3:FREQuency:CENTer 1.268GHZ
:SENSe:POWer:ACHannel:SBLock3:RFBWidth 8MHZ

:SENSe:POWer:ACHannel:SBLock3:CENTer:CHANnel1 1.266GHZ

```

Configuring and Performing Measurements

```

:SENSe:POWer:ACHannel:SBLock3:CENTer:CHANnel2 1.270GHZ

:SENSe:POWer:ACHannel:SBLock3:BANDwidth:CHANnel1 2.75MHZ
:SENSe:POWer:ACHannel:SBLock3:BANDwidth:CHANnel2 2.75MHZ

//----- Configuring ADJ channels

:SENSe:POWer:ACHannel:BANDwidth:ACHannel 1.60MHZ
:SENSe:POWer:ACHannel:BANDwidth:ALternate1 1.60MHZ

:SENSe:POWer:ACHannel:SPACing:ACHannel 3MHZ
:SENSe:POWer:ACHannel:SPACing:ALternate1 5MHZ

//----- Configuring gap (CACLR) channels

:SENSe:POWer:ACHannel:SPACing:GAP1 2.0MHZ
:SENSe:POWer:ACHannel:SPACing:GAP2 5.0MHZ

:SENSe:POWer:ACHannel:BANDwidth:GAP1 2.0MHZ
:SENSe:POWer:ACHannel:BANDwidth:GAP2 2.0MHZ

//-----Performing the Measurement-----

//Select single sweep mode.
INIT:CONT OFF
//Initiate a new measurement and wait until the sweep has finished.
INIT;*WAI

//-----Retrieving Results-----

//Return the results for the ACLR measurement.
CALC:MARK:FUNC:POW:RES? MCAC
//Results:
//Transmission channels in sub block A
//-13.2346727385,-13.2346723793,-13.2390131759,
//Transmission channels in sub block B
//-17.0863336597,
//Transmission channels in sub block C
//-13.2390127767,-13.2390134744,
//Totals for each sub block
//-8.4649064021,-17.0863336597,-10.2287131689,
//Adjacent channels
//-67.9740721019,-67.9740728014,-0.00434041734,-0.00434041734,
//CACLR channels
//-0.52933512766,-64.9990115835,-64.5012521492,-0.33507330922,
//-64.4924159646,-0.52932552499,-0.52932552495,-64.4934163414

```


11.5.4 Measuring the Carrier-to-Noise Ratio

The following commands are necessary to perform carrier-to-noise measurements.

- `CALC:MARK:FUNC:POW:SEL CN | CN0`, see `CALCulate<n>:MARKer<m>:FUNCTION:POWER:SElect`
- `CALCulate<n>:MARKer<m>:FUNCTION:POWER[:STATe]`
- `CALCulate<n>:MARKer<m>:FUNCTION:POWER<sb>:RESult?`
- `[SENSe:]POWER:ACHannel:BANDwidth|BWIDth[:CHANnel<ch>]`
- `[SENSe:]POWER:ACHannel:PRESet`

Programming example: Measuring the carrier-to-noise ratio

This programming example demonstrates how to perform a Carrier-to-noise measurement in a remote environment.

```
//-----Preparing the measurement-----
*RST
//Reset the instrument
FREQ:CENt 800MHz
//Sets the center frequency to the carrier frequency of 800 MHz.
CALC:MARK:FUNC:POW:SEL CN
//Activates carrier-to-noise ratio measurement.
POW:ACH:PREs CN
//Optimizes the instrument settings according to the channel bandwidth.
POW:ACH:PREs:RLEV
//Determines the ideal reference level for the measurement.

//-----Performing the Measurement-----
INIT:CONT OFF
//Selects single sweep mode.
INIT;*WAI
//Initiates a new measurement and waits until the sweep has finished.

// Now turn off the carrier signal and repeat the measurement:
INIT;*WAI
//Initiates a new measurement and waits until the sweep has finished.

//-----Retrieving Results-----
CALC:MARK:FUNC:POW:RES? CN
//Returns the carrier-to-noise ratio.
```

11.5.5 Measuring the Occupied Bandwidth

All remote control commands specific to occupied bandwidth measurements are described here.

- [Configuring the Measurement](#).....648
- [Programming Example: OBW Measurement](#).....648

11.5.5.1 Configuring the Measurement

The following commands configure measurements of the occupied bandwidth.

Useful commands for occupied bandwidth measurements described elsewhere

Configuring the channel:

- `[SENSe:]POWer:ACHannel:BANDwidth|BWIDth[:CHANnel<ch>]`
- `[SENSe:]POWer:ACHannel:PRESet`
- `[SENSe:]POWer:ACHannel:PRESet:RLEVel`

Defining search limits:

- `CALCulate<n>:MARKer<m>:X:SLIMits[:STATe]` on page 825
- `CALCulate<n>:MARKer<m>:X:SLIMits:LEFT` on page 826
- `CALCulate<n>:MARKer<m>:X:SLIMits:RIGHT` on page 826

Performing the measurement:

- `CALCulate<n>:MARKer<m>:FUNction:POWer:SElect` on page 609
- `CALCulate<n>:MARKer<m>:FUNction:POWer[:STATe]` on page 609

Retrieving results:

- `CALCulate<n>:MARKer<m>:FUNction:POWer<sb>:RESult?` on page 607
- `CALCulate<n>:MARKer<m>:FUNction:POWer:SElect` on page 609
- `CALCulate<n>:MARKer<m>:FUNction:POWer[:STATe]` on page 609

Remote commands exclusive to occupied bandwidth measurements

`[SENSe:]POWer:BANDwidth|BWIDth.....` 648

`[SENSe:]POWer:BANDwidth|BWIDth <Percentage>`

This command selects the percentage of the total power that defines the occupied bandwidth.

Parameters:

<Percentage>	Range:	10 PCT to 99.9 PCT
	*RST:	99 PCT

Example: `POW:BWID 95PCT`

Manual operation: See "% Power Bandwidth" on page 194

11.5.5.2 Programming Example: OBW Measurement

This programming example demonstrates the measurement example described in [chapter 5.5.5, "Measurement Example"](#), on page 196 in a remote environment.

```
//-----Configuring the Measurement-----
*RST
//Resets the instrument
```

```

FREQ:CENT 800MHz
//Sets the center frequency to 800 MHz.
DISP:TRAC:Y:RLEV -10dBm
//Sets the reference level to -10 dBm.
CALC:MARK:FUNC:POW:SEL OBW
//Activates occupied bandwidth measurement.
POW:BWID 99PCT
//Sets the percentage of power to 99%.
POW:ACH:BAND 21kHz
//Sets the channel bandwidth to 21 kHz.
POW:ACH:PRES OBW
//Optimizes the instrument settings according to the channel bandwidth.
POW:ACH:PRES:RLEV
//Determines the ideal reference level for the measurement.
DET APE
//Sets the trace detector to positive peak.

//-----Performing the Measurement-----
INIT:CONT OFF
//Selects single sweep mode.
INIT;*WAI
//Initiates a new measurement and waits until the sweep has finished.

//-----Retrieving Results-----
CALC:MARK:FUNC:POW:RES? OBW
//Returns the occupied bandwidth.

```

11.5.6 Measuring the Spectrum Emission Mask

All remote control commands specific to spectrum emission mask measurements are described here.



See also [chapter 11.5.2, "Configuring Power Measurements"](#), on page 607.

- [Managing Measurement Configurations](#)..... 650
- [Controlling the Measurement](#)..... 651
- [Configuring a Multi-SEM Measurement](#)..... 652
- [Configuring a Sweep List](#)..... 653
- [Configuring the Reference Range](#)..... 667
- [Configuring the Power Classes](#)..... 669
- [Configuring MSR SEM Measurements](#)..... 674
- [Configuring the List Evaluation](#)..... 680
- [Performing an SEM Measurement](#)..... 681
- [Retrieving Results](#)..... 681
- [Example: SEM Measurement](#)..... 681

11.5.6.1 Managing Measurement Configurations

The following commands control measurement configurations for SEM measurements.

CALCulate<n>:LIMit<k>:ESPectrum<sb>:RESTore.....	650
[SENSe:]ESPectrum<sb>:PRESet[:STANdard].....	650
[SENSe:]ESPectrum<sb>:PRESet:RESTore.....	650
[SENSe:]ESPectrum<sb>:PRESet:STORE.....	651

CALCulate<n>:LIMit<k>:ESPectrum<sb>:RESTore

This command restores the predefined limit lines for the selected Spectrum Emission Mask standard (<sb> is irrelevant).

(<n>, <k> are irrelevant.)

All modifications made to the predefined limit lines are lost and the factory-set values are restored.

Example: `CALC:LIM:ESP:REST`
Resets the limit lines for the current Spectrum Emission Mask standard to the default setting.

[SENSe:]ESPectrum<sb>:PRESet[:STANdard] <Standard>

This command loads a measurement configuration.

Standard definitions are stored in an xml file. The default directory for SEM standards is `C:\r_s\instr\sem_std`.

Suffix:
<sb> 1 | 2 | 3
 irrelevant

Parameters:
<Standard> String containing the file name.
If you have stored the file in a subdirectory of the directory mentioned above, you have to include the relative path to the file.

Return values:
<Standard> The query returns the name of the currently loaded standard.

Manual operation: See "[Standard / MSR Settings](#)" on page 217
 See "[Load Standard](#)" on page 224

[SENSe:]ESPectrum<sb>:PRESet:RESTore

This command restores the default configurations of predefined SEM standards.

Note that the command will overwrite customized standards that have the same name as predefined standards.

Suffix:
 <sb> 1 | 2 | 3
 irrelevant

Usage: Event

Manual operation: See "Restore Standard Files" on page 225

[SENSe:]ESpectrum<sb>:PRESet:STORe <Standard>

This command saves the current SEM measurement configuration.

Standard definitions are stored in an xml file. The default directory for SEM standards is C:\r_s\instr\sem_std.

Suffix:
 <sb> 1 | 2 | 3
 irrelevant

Parameters:
 <Standard> String containing the file name.
 You can save the file in a subdirectory of the directory mentioned above. In that case, you have to include the relative path to the file.

Manual operation: See "Save Standard" on page 225

11.5.6.2 Controlling the Measurement

The following commands control the measurement itself.

INITiate<n>:ESpectrum	651
[SENSe:]SWEep:MODE.....	651

INITiate<n>:ESpectrum

This command initiates a Spectrum Emission Mask measurement.

Suffix:
 <n> irrelevant

Usage: Event

[SENSe:]SWEep:MODE <Mode>

This command selects the spurious emission and spectrum emission mask measurements.

You can select other measurements with

- CALCulate<n>:MARKer<m>:FUNction:POWer[:STATe]

Parameters:

<Mode>

AUTO

Turns on basic spectrum measurements.

ESpectrum

Turns on spectrum emission mask measurements.

LIST

Turns on spurious emission measurements.

*RST: AUTO

Usage:

SCPI confirmed

Manual operation:

See "Spectrum Emission Mask" on page 114

See "Spurious Emissions" on page 114

11.5.6.3 Configuring a Multi-SEM Measurement

As of firmware version 1.91, and in the Spectrum application only, spectrum emissions can be measured for multiple sub blocks of channels (see [chapter 5.6.4.5, "SEM with Multiple Sub Blocks \("Multi-SEM"\)](#)", on page 206). Up to three sub blocks (with two gaps) can be defined. For each sub block, the familiar configuration settings concerning ranges, limit lines and MSR can be defined in individual tabs (select the sub block using the <sb> suffix in the corresponding commands). In addition, settings on the sub blocks themselves must be configured.

Useful commands for multi-SEM measurements described elsewhere:

- [\[SENSe:\]ESpectrum<sb>:RANge<range>:MLCalc](#) on page 665

Remote commands exclusive to multi-SEM measurements

[\[SENSe:\]ESpectrum<sb>:SBCenter](#)..... 652

[\[SENSe:\]ESpectrum<sb>:SBCount](#)..... 653

[SENSe:]ESpectrum<sb>:SBCenter <Frequency>

This command defines the center frequency of the selected sub block in a Multi-SEM measurement.

Suffix:

<sb>

1 | 2 | 3

Sub block in a Multi-SEM measurement

Return values:

<Frequency>

Frequency within the currently defined global span (see

[\[SENSe:\]FREQuency:SPAN](#) on page 744 and [\[SENSe:\]FREQuency:CENTer](#) on page 742).

Range: 1 to 3

*RST: 1

Manual operation:

See "Sub Block Center Frequency" on page 217

[SENSe:]ESpectrum<sb>:SBCount <Sub blocks>

This command defines the number of sub blocks in the SEM measurement. (<sb> is irrelevant)

Return values:

<Sub blocks> Number of sub blocks in the SEM measurement.
 Range: 1 to 3
 *RST: 1

Manual operation: See "Sub Block Count" on page 217

11.5.6.4 Configuring a Sweep List

The following commands define a sweep list for SEM measurements.



The sweep list cannot be configured using remote commands during an on-going sweep operation.

See also:

- `CALCulate<n>:LIMit<k>:ESpectrum<sb>:PCLass<class>:LIMit[:STATe]` on page 672

<code>[SENSe:]ESpectrum<sb>:HighSPeed</code>	654
<code>[SENSe:]ESpectrum<sb>:RANGe<range>:BANDwidth[:RESolution]</code>	654
<code>[SENSe:]ESpectrum<sb>:RANGe<range>:BANDwidth:VIDeo</code>	654
<code>[SENSe:]ESpectrum<sb>:RANGe<range>:COUNT?</code>	655
<code>[SENSe:]ESpectrum<sb>:RANGe<range>:DELete</code>	655
<code>[SENSe:]ESpectrum<sb>:RANGe<range>:FILTer:TYPE</code>	655
<code>[SENSe:]ESpectrum<sb>:RANGe<range>[:FREquency]:START</code>	656
<code>[SENSe:]ESpectrum<sb>:RANGe<range>[:FREquency]:STOP</code>	657
<code>[SENSe:]ESpectrum<sb>:RANGe<range>:INPut:ATTenuation</code>	657
<code>[SENSe:]ESpectrum<sb>:RANGe<range>:INPut:ATTenuation:AUTO</code>	658
<code>[SENSe:]ESpectrum<sb>:RANGe<range>:INPut:GAIN:STATe</code>	658
<code>[SENSe:]ESpectrum<sb>:RANGe<range>:INSet</code>	658
<code>[SENSe:]ESpectrum<sb>:RANGe<range>:LIMit<PClass>:ABSolute:START</code>	659
<code>[SENSe:]ESpectrum<sb>:RANGe<range>:LIMit<PClass>:ABSolute:STOP</code>	659
<code>[SENSe:]ESpectrum<sb>:RANGe<range>:LIMit<PClass>:RELative:START</code>	660
<code>[SENSe:]ESpectrum<sb>:RANGe<range>:LIMit<PClass>:RELative:START:ABS</code>	660
<code>[SENSe:]ESpectrum<sb>:RANGe<range>:LIMit<PClass>:RELative:START:FUNCTion</code>	661
<code>[SENSe:]ESpectrum<sb>:RANGe<range>:LIMit<PClass>:RELative:STOP</code>	662
<code>[SENSe:]ESpectrum<sb>:RANGe<range>:LIMit<PClass>:RELative:STOP:ABSolute</code>	663
<code>[SENSe:]ESpectrum<sb>:RANGe<range>:LIMit<PClass>:RELative:STOP:FUNCTion</code>	663
<code>[SENSe:]ESpectrum<sb>:RANGe<range>:LIMit<PClass>:STATe</code>	664
<code>[SENSe:]ESpectrum<sb>:RANGe<range>:POINTs:MIN[:VALue]</code>	665
<code>[SENSe:]ESpectrum<sb>:RANGe<range>:MLCalc</code>	665
<code>[SENSe:]ESpectrum<sb>:RANGe<range>:RLEVel</code>	665

[SENSe:]ESpectrum<sb>:RANGe<range>:SWEp:TIME.....	666
[SENSe:]ESpectrum<sb>:RANGe<range>:SWEp:TIME:AUTO.....	666
[SENSe:]ESpectrum<sb>:RANGe<range>:TRANsducer.....	667

[SENSe:]ESpectrum<sb>:HighSPeed <State>

This command turns high speed mode for SEM measurements on and off.

For more information including restrictions see [chapter 5.6.4.3, "Fast SEM Measurements"](#), on page 205.

Suffix:

<sb> 1 | 2 | 3
 irrelevant

Parameters:

<State> ON | OFF
 *RST: OFF

Example: ESP:HSP ON

Manual operation: See ["Fast SEM"](#) on page 212

[SENSe:]ESpectrum<sb>:RANGe<range>:BANDwidth[:RESolution] <RBW>

This command defines the resolution bandwidth for a SEM range.

In case of high speed measurements, the resolution bandwidth has to be identical for all ranges.

Suffix:

<sb> 1 | 2 | 3
 irrelevant

<range> 1...30
 Selects the measurement range.

Parameters:

<RBW> Resolution bandwidth.
 Refer to the data sheet for available resolution bandwidths.
 *RST: 30.0 kHz
 Default unit: Hz

Manual operation: See ["RBW"](#) on page 212

[SENSe:]ESpectrum<sb>:RANGe<range>:BANDwidth:VIDeo <VBW>

This command defines the video bandwidth for a SEM range.

In case of high speed measurements, the video bandwidth has to be identical for all ranges.

Suffix:

<sb> 1 | 2 | 3
irrelevant

<range> 1...30
Selects the measurement range.

Parameters:

<VBW> Video bandwidth.
Refer to the data sheet for available video bandwidths.
*RST: 10.0 MHz
Default unit: Hz

Manual operation: See "[VBW](#)" on page 212

[SENSe:]ESpectrum<sb>:RANGe<range>:COUNT? <Ranges>

This command queries the number of ranges in the sweep list (<range> is irrelevant).

Suffix:

<sb> 1 | 2 | 3
irrelevant

Return values:

<Ranges> Number of ranges in the sweep list.

Usage: Query only

[SENSe:]ESpectrum<sb>:RANGe<range>:DELEte

This command removes a range from the sweep list.

Note that

- you cannot delete the reference range
- a minimum of three ranges is mandatory.

Suffix:

<sb> 1 | 2 | 3
irrelevant

<range> 1...30
Selects the measurement range.

Usage: Event

Manual operation: See "[Delete Range](#)" on page 216

[SENSe:]ESpectrum<sb>:RANGe<range>:FILTer:TYPE <FilterType>

This command selects the filter type for an SEM range.

In case of high speed measurements, the filter has to be identical for all ranges.

Suffix:

<sb> 1 | 2 | 3
irrelevant

<range> 1...30
Selects the measurement range.

Parameters:

<FilterType> **NORMAL**
Gaussian filters

CFILter
channel filters

RRC
RRC filters

P5
5 Pole filters

*RST: NORM
Refer to the datasheet for available filter bandwidths.

Manual operation: See "[Filter Type](#)" on page 212

[SENSe:]ESpectrum<sb>:RANGe<range>[:FREQUENCY]:START <Frequency>

This command defines the start frequency of a SEM range.

Make sure to set an appropriate span. If you set a span that is

- smaller than the span the SEM sweep list covers, the R&S FPS will not measure the ranges that are outside the span - results may be invalid.
- greater than the span the SEM sweep list covers, the R&S FPS will adjust the start frequency of the first SEM range and the stop frequency of the last SEM range to the span

For more information see [chapter 5.6.4.1, "Ranges and Range Settings"](#), on page 201.

Suffix:

<sb> 1 | 2 | 3
irrelevant

<range> 1...30
Selects the measurement range.

Parameters:

<Frequency> Numeric value. Note that the minimum frequency range of a SEM range is 20 Hz.

*RST: -12.75 MHz (range 1), -2.515 MHz (range 2), 2.515 MHz (range 3)

Default unit: Hz

Manual operation: See "[Range Start / Range Stop](#)" on page 211

[SENSe:]ESpectrum<sb>:RANGe<range>[:FREQUENCY]:STOP <Frequency>

This command defines the stop frequency of a SEM range.

Make sure to set an appropriate span. If you set a span that is

- smaller than the span the SEM sweep list covers, the R&S FPS will not measure the ranges that are outside the span - results may be invalid.
- greater than the span the SEM sweep list covers, the R&S FPS will adjust the start frequency of the first SEM range and the stop frequency of the last SEM range to the span

For more information see [chapter 5.6.4.1, "Ranges and Range Settings"](#), on page 201.

Suffix:

<sb> 1 | 2 | 3
irrelevant

<range> 1...30
Selects the measurement range.

Parameters:

<Frequency> Numeric value.
*RST: -2.52 MHz (range 1), 2.52 MHz (range 2), 250.0 MHz (range 3)
Default unit: Hz

Manual operation: See ["Range Start / Range Stop"](#) on page 211

[SENSe:]ESpectrum<sb>:RANGe<range>:INPut:ATTenuation <Attenuation>

This command defines the input attenuation for a SEM range.

In case of high speed measurements, the input attenuation has to be identical for all ranges.

Suffix:

<sb> 1 | 2 | 3
irrelevant

<range> 1...20
Selects the measurement range.

Parameters:

<Attenuation> Numeric value.
Refer to the data sheet for the attenuation range.
*RST: 10 dB
Default unit: dB

Manual operation: See ["RF Attenuator"](#) on page 213

[SENSe:]ESpectrum<sb>:RANGe<range>:INPut:ATTenuation:AUTO <State>

This command turns automatic selection of the input attenuation for a SEM range on and off.

In case of high speed measurements, the input attenuation has to be identical for all ranges.

Suffix:

<sb> 1 | 2 | 3
irrelevant

<range> 1..30
Selects the measurement range.

Parameters:

<State> ON | OFF | 0 | 1
*RST: 1

Example: ESP:RANG2:INP:ATT:AUTO OFF
Deactivates the RF attenuation auto mode for range 2.

Manual operation: See "[RF Att. Mode](#)" on page 213

[SENSe:]ESpectrum<sb>:RANGe<range>:INPut:GAIN:STATe <State>

This command turns the preamplifier for a SEM range on and off.

In case of high speed measurements, the state of the preamplifier has to be identical for all ranges.

Suffix:

<sb> 1 | 2 | 3
irrelevant

<range> 1..30
Selects the measurement range.

Parameters:

<State> ON | OFF
*RST: OFF

[SENSe:]ESpectrum<sb>:RANGe<range>:INSert <Mode>

This command inserts a new SEM range and updates the range numbers accordingly.

Suffix:

<sb> 1 | 2 | 3
irrelevant

<range> 1..30
Selects the SEM range.

Parameters:

<Mode>	AFTer Inserts a range after the selected range.
	BEFore Inserts a range before the selected range.

Manual operation: See ["Insert before/after Range"](#) on page 215

[SENSe:]ESpectrum<sb>:RANGe<range>:LIMit<PClass>:ABSolute:START
<Level>

This command defines an absolute limit for a SEM range.

Unlike manual operation, you can define an absolute limit anytime and regardless of the limit check mode.

Suffix:

<sb>	1 2 3 irrelevant
<range>	1..30 Selects the measurement range.
<PClass>	1..4 Power class for which the limit is defined.

Parameters:

<Level>	Absolute limit at the start frequency of a SEM range. Range: -400 to 400 *RST: -13 Default unit: dBm
---------	---

Example: `SENSe:ESpectrum:RANGe:LIMit:ABSolute:START -10`
For a detailed example see [chapter 11.5.6.11, "Example: SEM Measurement"](#), on page 681.

Manual operation: See ["Abs Limit Start/Stop <n>"](#) on page 214

[SENSe:]ESpectrum<sb>:RANGe<range>:LIMit<PClass>:ABSolute:STOP
<Level>

This command defines an absolute limit for a SEM range.

Unlike manual operation, you can define an absolute limit anytime and regardless of the limit check mode.

Suffix:

<sb>	1 2 3 irrelevant
<range>	1..30 Selects the measurement range.

<PClass> 1..4
Power class for which the limit is defined.

Parameters:

<Level> Absolute limit at the stop frequency of a SEM range.
Range: -400 to 400
*RST: -13
Default unit: dBm

Example: `SENSe:ESpectrum:RANGe:LIMit:ABSolute:STOP -15`
For a detailed example see [chapter 11.5.6.11, "Example: SEM Measurement"](#), on page 681.

Manual operation: See "[Abs Limit Start/Stop <n>](#)" on page 214

[SENSe:]ESpectrum<sb>:RANGe<range>:LIMit<PClass>:RELative:STARt <Limit>

This command defines a relative limit for a SEM range.

Unlike manual operation, you can define a relative limit regardless of the limit check mode.

Suffix:

<sb> 1 | 2 | 3
irrelevant

<range> 1..30
Selects the SEM range.

<PClass> 1..4
Power class for which the limit is defined.

Parameters:

<Level> Relative limit at the start frequency of a SEM range.
Range: -400 to 400
*RST: -50
Default unit: dBc

Example: `SENS:ESP:RANG:LIM:REL:STAR -10`

Manual operation: See "[Rel Limit Start/Stop <n>](#)" on page 214

[SENSe:]ESpectrum<sb>:RANGe<range>:LIMit<PClass>:RELative:STARt:ABS <Limit>

This command defines an absolute limit for the MAX function of the relative limit for a SEM range.

For more information see "[Relative limit line functions](#)" on page 204.

Suffix:

<sb> 1 | 2 | 3
irrelevant

<range>	1..30 Selects the SEM range.
<PClass>	1..4 Power class for which the limit is defined.
Parameters:	
<Level>	Absolute limit at the start frequency of a SEM range to be used in addition to the relative limit if the MAX function is enabled (see [SENSe:]ESpectrum<sb>:RANGe<range>:LIMit<PClass>:RELative:STARt:FUNctIon on page 661). Range: -400 to 400 *RST: -13 Default unit: dBm
Example:	<code>SENSe:ESpectrum:RANGe:LIMit:RELative:STARt:ABSolute -10</code> For a detailed example see chapter 11.5.6.11, "Example: SEM Measurement" , on page 681.
Manual operation:	See "Rel Limit Start/Stop <n>" on page 214

[SENSe:]ESpectrum<sb>:RANGe<range>:LIMit<PClass>:RELative:STARt:FUNctIon <Function>

This command enables the use of a function when defining the relative limit for a SEM range.

Suffix:	
<sb>	1 2 3 irrelevant
<range>	1..30 Selects the SEM range.
<PClass>	1..4 Power class for which the limit is defined.

Parameters:

<Function>

Defines the function to be used to determine the relative limit line start value

MAX

The maximum of the relative *and* the absolute level is used as the limit start value. Use the `[SENSe:]ESpectrum<sb>:RANge<range>:LIMit<PClass>:RELative:STARt` and `[SENSe:]ESpectrum<sb>:RANge<range>:LIMit<PClass>:RELative:STARt:ABS` commands to define these values.

OFF

No function is used, the relative limit line is defined by a fixed relative start value. Use the `[SENSe:]ESpectrum<sb>:RANge<range>:LIMit<PClass>:RELative:STARt` command to define this value.

*RST: OFF

Example:

```
SENSe:ESpectrum:RANge:LIMit:RELative:STARt:
FUNctIon MAX
```

For a detailed example see [chapter 11.5.6.11, "Example: SEM Measurement"](#), on page 681.

Manual operation: See "[Rel Limit Start/Stop <n>](#)" on page 214

[SENSe:]ESpectrum<sb>:RANge<range>:LIMit<PClass>:RELative:STOP <Limit>

This command defines a relative limit for a SEM range.

Unlike manual operation, you can define a relative limit anytime and regardless of the limit check mode.

Suffix:

<sb>

1 | 2 | 3
irrelevant

<range>

1..30
Selects the SEM range.

<PClass>

1..4
Power class for which the limit is defined.

Parameters:

<Level>

Relative limit at the stop frequency of a SEM range.

Range: -400 to 400

*RST: -50

Default unit: dBc

Example:

```
SENSe:ESpectrum:RANge:LIMit:RELative:STOP -15
```

For a detailed example see [chapter 11.5.6.11, "Example: SEM Measurement"](#), on page 681.

Manual operation: See "[Rel Limit Start/Stop <n>](#)" on page 214

**[SENSe:]ESpectrum<sb>:RANGe<range>:LIMit<PClass>:RELative:STOP:
ABSolute <Limit>**

This command defines an absolute limit for the MAX function of the relative limit for a SEM range.

For more information see ["Relative limit line functions"](#) on page 204.

Suffix:

<sb>	1 2 3 irrelevant
<range>	1..30 Selects the SEM range.
<PClass>	1..4 Power class for which the limit is defined.

Parameters:

<Level>	Absolute limit at the stop frequency of a SEM range to be used in addition to the relative limit if the MAX function is enabled (see [SENSe:]ESpectrum<sb>:RANGe<range>:LIMit<PClass>:RELative:STOP:FUNCTION on page 663). Range: -400 to 400 *RST: -13 Default unit: dBm
---------	--

Example: `SENSe:ESpectrum:RANGe:LIMit:RELative:STOP:
ABSolute -15`

For a detailed example see [chapter 11.5.6.11, "Example: SEM Measurement"](#), on page 681.

Manual operation: See ["Rel Limit Start/Stop <n>"](#) on page 214

**[SENSe:]ESpectrum<sb>:RANGe<range>:LIMit<PClass>:RELative:STOP:
FUNction <Function>**

This command enables the use of a function when defining the relative limit for a SEM range.

Suffix:

<sb>	1 2 3 irrelevant
<range>	1..30 Selects the SEM range.
<PClass>	1..4 Power class for which the limit is defined.

Parameters:

<Function>

Defines the function to be used to determine the relative limit line stop value

MAX

The maximum of the relative *and* the absolute level is used as the limit stop value. Use the `[SENSe:]ESpectrum<sb>:RANGe<range>:LIMit<PClass>:RELative:STOP` and `[SENSe:]ESpectrum<sb>:RANGe<range>:LIMit<PClass>:RELative:STOP:ABSolute` commands to define these values.

OFF

No function is used, the relative limit line is defined by a fixed relative stop value. Use the `[SENSe:]ESpectrum<sb>:RANGe<range>:LIMit<PClass>:RELative:STOP` command to define this value.

*RST: OFF

Example:

```
SENSe:ESpectrum:RANGe:LIMit:RELative:STOP:
FUNction MAX
```

For a detailed example see [chapter 11.5.6.11, "Example: SEM Measurement"](#), on page 681.

Manual operation: See "[Rel Limit Start/Stop <n>](#)" on page 214

`[SENSe:]ESpectrum<sb>:RANGe<range>:LIMit<PClass>:STATe <State>`

This command selects the limit check mode for *all* SEM ranges (<range> is irrelevant).

Suffix:

<sb>

1 | 2 | 3
irrelevant

<PClass>

1..4
Power class for which the limit is defined.

Parameters:

<State>

ABSolute | RELative | AND | OR

ABSolute

Checks only the absolute limits defined.

RELative

Checks only the relative limits. Relative limits are defined as relative to the measured power in the reference range.

AND

Combines the absolute and relative limit. The limit check fails when both limits are violated.

OR

Combines the absolute and relative limit. The limit check fails when one of the limits is violated.

*RST: RELative

Manual operation: See "[Limit Check <n>](#)" on page 214

[SENSe:]ESpectrum<sb>:RANGe<range>:POINTs:MIN[:VALue] <SweepPoint>

Defines the minimum number of sweep points for the range.

Suffix:

<sb> 1 | 2 | 3
 irrelevant

<range> 1..30
 Selects the measurement range.

Parameters:

<SweepPoints> Minimum number of sweep points per range
 Range: 1 to 32001
 *RST: 1

Example: SENSe1:ESpectrum:RANGe3:POINTs:MIN:VALue 400

Manual operation: See "[Minimum Sweep Points](#)" on page 215

[SENSe:]ESpectrum<sb>:RANGe<range>:MLCalc <Function>

Defines the function used to calculate the limit line for the n-th power class for overlapping ranges in Multi-SEM measurements. For details see "[Limit calculation for individual ranges](#)" on page 208.

Suffix:

<sb> 1 | 2 | 3
 irrelevant

<range> 1..30
 Selects the measurement range.

Parameters:

<Function> **NONE**
 (reference ranges only:) the limit of the reference range is used;
 Reference ranges always use the function "NONE".
SUM
 sum of the two limit lines (calculated for linear powers) is used
MAX
 maximum of the two limit lines is used
 *RST: SUM (reference range: NONE)

Manual operation: See "[Multi-Limit Calc <n>](#)" on page 215

[SENSe:]ESpectrum<sb>:RANGe<range>:RLEVel <RefLevel>

This command defines the reference level for a SEM range.

In case of high speed measurements, the reference level has to be identical for all ranges.

Suffix:

<sb> 1 | 2 | 3
irrelevant

<range> 1..30
Selects the measurement range.

Parameters:

<RefLevel> Reference level.
Refer to the data sheet for the reference level range.
*RST: 0 dBm

Manual operation: See "[Ref. Level](#)" on page 213

[SENSE:]ESpectrum<sb>:RANGe<range>:SWEep:TIME <SweepTime>

This command defines the sweep time for a SEM range.

In case of high speed measurements, the sweep time has to be identical for all ranges.

Suffix:

<sb> 1 | 2 | 3
irrelevant

<range> 1..30
Selects the measurement range.

Parameters:

<SweepTime> Sweep time.
The range depends on the ratios of the span to the RBW and the RBW to the VBW. Refer to the data sheet for more information.

Manual operation: See "[Sweep Time](#)" on page 213

[SENSE:]ESpectrum<sb>:RANGe<range>:SWEep:TIME:AUTO <State>

This command turns automatic selection of the sweep time for a SEM range on and off.

In case of high speed measurements, the sweep time has to be identical for all ranges.

Suffix:

<sb> 1 | 2 | 3
irrelevant

<range> 1..30
Selects the measurement range.

Parameters:

<State> ON | OFF | 0 | 1
*RST: 1

Example: `ESP:RANG3:SWE:TIME:AUTO OFF`
Deactivates the sweep time auto mode for range 3.

Manual operation: See ["Sweep Time Mode"](#) on page 213

[SENSe:]ESpectrum<sb>:RANGe<range>:TRANsducer <Transducer>

This command selects a transducer factor for a SEM range.

Note that

- the transducer must cover at least the span of the range
- the x-axis has to be linear
- the unit has to be dB

Suffix:

<sb> 1 | 2 | 3
 irrelevant

<range> 1..30
 Selects the measurement range.

Parameters:

<Transducer> String containing the transducer file name, including the path information.

Manual operation: See ["Transd. Factor"](#) on page 213

11.5.6.5 Configuring the Reference Range

The following commands define the reference range for the SEM sweep list.

[SENSe:]ESpectrum<sb>:BWID	667
[SENSe:]ESpectrum<sb>:FILTer[RRC]:ALPHa	668
[SENSe:]ESpectrum<sb>:FILTer[RRC][:STATe]	668
[SENSe:]ESpectrum<sb>:RRANGe?	668
[SENSe:]ESpectrum<sb>:RTYPE	668

[SENSe:]ESpectrum<sb>:BWID <Bandwidth>

This command defines the channel bandwidth of the reference range.

The bandwidth is available if the power reference is the channel power.

Suffix:

<sb> 1 | 2 | 3
 irrelevant

Parameters:

<Bandwidth> minimum span ≤ value ≤ span of reference range
 *RST: 3.84 MHz

Manual operation: See ["Tx Bandwidth"](#) on page 218

[SENSe:]ESpectrum<sb>:FILTer[:RRC]:ALPHa <Alpha>

This command defines the roll-off factor for the RRC filter.

The RRC filter is available if the power reference is the channel power.

Suffix:

<sb> 1 | 2 | 3
 irrelevant

Parameters:

<Alpha> Range: 0 to 1
 *RST: 0.22

Manual operation: See "[Alpha](#)" on page 219

[SENSe:]ESpectrum<sb>:FILTer[:RRC][:STATe] <State>

This command turns the RRC filter in the reference range on and off.

The RRC filter is available if the power reference is the channel power.

Suffix:

<sb> 1 | 2 | 3
 irrelevant

Parameters:

<State> ON | OFF | 0 | 1
 *RST: 1

Manual operation: See "[RRC Filter State](#)" on page 218

[SENSe:]ESpectrum<sb>:RRANge? <RefRange>

This command queries the reference range.

Suffix:

<sb> 1 | 2 | 3
 irrelevant

Return values:

<RefRange> Number of the current reference range.
 Range: 1 to 30

Usage: Query only

[SENSe:]ESpectrum<sb>:RTYPe <Type>

This command defines the type of the power reference.

Suffix:

<sb> 1 | 2 | 3
 irrelevant

Parameters:

<Type>

PEAK

Measures the highest peak within the reference range.

CPOWer

Measures the channel power within the reference range (integral bandwidth method).

*RST: CPOWer

Manual operation: See "Power Reference Type" on page 218**11.5.6.6 Configuring the Power Classes**

The following commands define the power classes for SEM measurements.

CALCulate<n>:LIMit<k>:ESPectrum<sb>:LIMits.....	669
CALCulate<n>:LIMit<k>:ESPectrum<sb>:MODE.....	670
CALCulate<n>:LIMit<k>:ESPectrum<sb>:VALue.....	671
CALCulate<n>:LIMit<k>:ESPectrum<sb>:PCLass:COUNT.....	671
CALCulate<n>:LIMit<k>:ESPectrum<sb>:PCLass<class>[:EXCLusive].....	672
CALCulate<n>:LIMit<k>:ESPectrum<sb>:PCLass<class>:LIMit[:STATe].....	672
CALCulate<n>:LIMit<k>:ESPectrum<sb>:PCLass<class>:MAXimum.....	673
CALCulate<n>:LIMit<k>:ESPectrum<sb>:PCLass<class>:MINimum.....	673

CALCulate<n>:LIMit<k>:ESPectrum<sb>:LIMits <Max1>,<Max2>,<Max3>

This command sets or queries up to 4 power classes in one step. You can only define values for the number of power classes defined by `CALCulate<n>:LIMit<k>:ESPectrum<sb>:PCLass:COUNT` on page 671.

(<n>, <k> are irrelevant.)

Suffix:

<sb> 1 | 2 | 3
 irrelevant

Setting parameters:

<Max1> Defines the value range for power class 1 as -200 to <Max1>.
 Only available for `CALC:LIM:ESP:PCL:COUNT >=2`
 If only 2 power classes are defined, the value range for power class 2 is defined as <Max1> to 200.
 Range: -199 to + 199

<Max2> Defines the value range for power class 2 as <Max1> to <Max2>.
 Only available for `CALC:LIM:ESP:PCL:COUNT >=3`
 If only 3 power classes are defined, the value range for power class 3 is defined as <Max2> to 200.
 Range: -199 to + 199, <Max2> must be higher than <Max1>

<Max3>	<p>Defines the value range for power class 3 as <Max2> to <Max3>.</p> <p>The value range for power class 4 is defined as <Max3> to 200.</p> <p>Only available for <code>CALC:LIM:ESP:PCL:COUNT = 4</code></p> <p>Range: -199 to + 199, <Max3> must be higher than <Max2></p>
Return values: <RangeLimits>	<p>As a result of the query, the range limits including the beginning of the first power class (-200) and the end of the last power class (+200) are indicated.</p>
Example:	<pre>CALC:LIM:ESP:LIM -50,50,70</pre> <p>Defines the following power classes:</p> <pre><-200, -50> <-50, 50> <50, 70> <70, 200></pre> <p>Query:</p> <pre>CALC:LIM:ESP:LIM?</pre> <p>Response:</p> <pre>-200,-50,50,70,200</pre>

CALCulate<n>:LIMit<k>:ESPectrum<sb>:MODE <Mode>

Which limit line is to be used for an SEM measurement depends on the power class the input signal power belongs to. This command defines whether the power class is determined automatically or manually.

(<n>, <k> are irrelevant.)

Suffix:

<sb> 1 | 2 | 3
 irrelevant

Parameters:

<Mode>

AUTO

The power class (and thus the limit line) is assigned dynamically according to the currently measured channel power.

MANUAL

One of the specified power classes is selected manually for the entire measurement. The selection is made with the

`CALCulate<n>:LIMit<k>:ESPectrum<sb>:`

`PClass<class>[:EXCLUSIVE]` command.

*RST: AUTO

Example:

```
CALC:LIM:ESP:MODE AUTO
```

Activates automatic selection of the limit line.

CALCulate<n>:LIMit<k>:ESPectrum<sb>:VALue <Power>

This command activates the manual limit line selection as and specifies the expected power as a value. Depending on the entered value, the associated predefined limit lines is selected.

(<n>, <k> are irrelevant.)

This command has the same effect as a combination of the [CALC:LIM:ESP:MODE MAN](#) and the [CALCulate<n>:LIMit<k>:ESPectrum<sb>:PCLass<class>\[:EXCLusive\]](#) commands; however, the power class to be used is not defined directly, but via the expected power. As opposed to [CALC:LIM:ESP:MODE AUTO](#), the power class is not re-assigned to the input signal power dynamically, but only once when the command is executed.

Suffix:

<sb> 1 | 2 | 3
 irrelevant

Parameters:

<Power> integer
 Range: -200 to 199
 *RST: 0

Example:

`CALC:LIM:ESP:VAL 33`
Activates manual selection of the limit line and selects the limit line for P = 33.

CALCulate<n>:LIMit<k>:ESPectrum<sb>:PCLass:COUNT <NoPowerClasses>

This command sets the number of power classes to be defined.

(<n>, <k> are irrelevant.)

This command must be executed before any new power class values can be defined using [CALCulate<n>:LIMit<k>:ESPectrum<sb>:PCLass<class>:MAXimum](#) and [CALCulate<n>:LIMit<k>:ESPectrum<sb>:PCLass<class>:MINimum](#).

Suffix:

<sb> 1 | 2 | 3
 irrelevant

Parameters:

<NoPowerClasses> 1 to 4
 *RST: 1

Example:

`CALC:LIM:ESP:PCL:COUN 2`
Two power classes can be defined.

Manual operation: See ["Adding or Removing a Power Class"](#) on page 220

CALCulate<n>:LIMit<k>:ESPectrum<sb>:PCLass<class>[:EXCLUSIVE] <State>

This command selects the power class used by the measurement if `CALCulate<n>:LIMit<k>:ESPectrum<sb>:MODE` is set to manual.

(<n>, <k> are irrelevant.)

Note that:

- You can only use power classes for which limits are defined.

Suffix:

<sb>	1 2 3 irrelevant
<class>	1...4 power class

Parameters:

<State>	ON OFF
*RST:	OFF

Example:

```
CALC:LIM:ESP:PCL1 ON
Activates the first defined power class.
```

Manual operation: See "[Used Power Classes](#)" on page 219

CALCulate<n>:LIMit<k>:ESPectrum<sb>:PCLass<class>:LIMit[:STATe] <State>

This command selects the limit check mode for each power class.

(<n>, <k> are irrelevant.)

Suffix:

<sb>	1 2 3 irrelevant
<class>	1...4 power class

Parameters:

<State>	ABSolute Evaluates only limit lines with absolute power values
	RELative Evaluates only limit lines with relative power values
	AND Evaluates limit lines with relative and absolute power values. A negative result is returned if both limits fail.
	OR Evaluates limit lines with relative and absolute power values. A negative result is returned if at least one limit failed.
*RST:	REL

Example:

```
CALC:LIM:ESP:PCL:LIM ABS
```

Manual operation: See "Used Power Classes" on page 219

CALCulate<n>:LIMit<k>:ESPectrum<sb>:PCLass<class>:MAXimum <Level>

This command defines the upper limit of a particular power class.

(<n>, <k> are irrelevant.)

Note:

- The last power class always has an upper limit of 200 dBm.
- The upper limit of a power class must always be the same as the lower limit of the subsequent power class.
- The power class must already exist (see [CALCulate<n>:LIMit<k>:ESPectrum<sb>:PCLass:COUNT](#) on page 671).

Suffix:

<sb>	1 2 3 irrelevant
<class>	1...4 power class

Parameters:

<Level>	Range: -199.9 dBm to 200 dBm
---------	------------------------------

Example:

```
CALC:LIM:ESP:PCL1:MAX -40 dBm
```

Sets the maximum power value of the first power class to -40 dBm.

Manual operation: See "PMin/PMax" on page 220

CALCulate<n>:LIMit<k>:ESPectrum<sb>:PCLass<class>:MINimum <Level>

This command defines the lower limit of a particular power class.

(<n>, <k> are irrelevant.)

Note:

- The first power class always has a lower limit of -200 dBm.
- The lower limit of a power class must always be the same as the upper limit of the previous power class.
- The power class must already exist (see [CALCulate<n>:LIMit<k>:ESPectrum<sb>:PCLass:COUNT](#) on page 671).

Suffix:

<sb>	1 2 3 irrelevant
<class>	1...4 power class

Parameters:

<Level>	Range: -200 dBm to 199.9 dBm
---------	------------------------------

Example: `CALC:LIM:ESP:PCL2:MIN -40 dBm`
Sets the minimum power value of the second power class to -40 dBm.

Manual operation: See "PMin/PMax" on page 220

11.5.6.7 Configuring MSR SEM Measurements

The following commands configure MSR SEM measurements. For details see [chapter 5.6.4.4, "Multi-Standard Radio \(MSR\) SEM Measurements"](#), on page 206.

For manual operation see [chapter 5.6.5.5, "MSR Settings"](#), on page 220.

<code>[SENSe:]ESpectrum<sb>:MSR:APPLY</code>	674
<code>[SENSe:]ESpectrum<sb>:MSR:BAND</code>	674
<code>[SENSe:]ESpectrum<sb>:MSR:BCATegory</code>	675
<code>[SENSe:]ESpectrum<sb>:MSR:CLAS</code>	676
<code>[SENSe:]ESpectrum<sb>:MSR:GSM:CARR</code>	676
<code>[SENSe:]ESpectrum<sb>:MSR:GSM:CPResent</code>	677
<code>[SENSe:]ESpectrum<sb>:MSR:LTE:CPResent</code>	678
<code>[SENSe:]ESpectrum<sb>:MSR:MPOWER</code>	678
<code>[SENSe:]ESpectrum<sb>:MSR:RFBWidth</code>	679

`[SENSe:]ESpectrum<sb>:MSR:APPLY`

This command configures the SEM sweep list according to the MSR settings defined by previous commands.

Suffix:

<sb> 1 | 2 | 3
 irrelevant

Example:

```
//Select the band category 1
ESP2:MSR:BCAT BC1
//Set the base station class to medium range
ESP2:MSR:CLAS MED
//Set the maximum output power to 10 dBm.
ESP2:MSR:MPOW 10
//Set the frequency range of the base station to > 3 GHz
ESP2:MSR:BAND:HIGH
//Set the base station RF bandwidth to 20 MHz
ESP2:MSR:RFBW 20MHZ
//Calculate limits for MSR SEM
ESP2:MSR:APPL
```

Usage: Event

Manual operation: See "Apply to SEM" on page 223

`[SENSe:]ESpectrum<sb>:MSR:BAND <Range>`

Defines the frequency range of the bands used by the base station.

Suffix:

<sb> 1 | 2 | 3
irrelevant

Parameters:

<Range> **LOW**
≤ 3 GHz
HIGH
> 3 GHz
*RST: LOW

Example:

```
//Select the band category 1
ESP2:MSR:BCAT BC1
//Set the base station class to medium range
ESP2:MSR:CLAS MED
//Set the maximum output power to 10 dBm.
ESP2:MSR:MPOW 10
//Set the frequency range of the base station to > 3 GHz
ESP2:MSR:BAND:HIGH
//Set the base station RF bandwidth to 20 MHz
ESP2:MSR:RFBW 20MHZ
//Calculate limits for MSR SEM
ESP2:MSR:APPL
```

Manual operation: See "[Bands](#)" on page 222

[SENSe:]ESpectrum<sb>:MSR:BCATegory <Category>

This command defines the band category for MSR measurements, i.e. the combination of available carriers to measure.

Suffix:

<sb> 1 | 2 | 3
irrelevant

Parameters:

<Category> 1 | 2 | 3
1
2 carriers: LTE FDD and W-CDMA
2
3 carriers: LTE FDD, W-CDMA and GSM/EDGE
3
2 carriers: LTE TDD and TD-SCDMA
*RST: 1

Example:

```
//Select the band category 1
ESP2:MSR:BCAT BC1
//Set the base station class to medium range
ESP2:MSR:CLAS MED
//Set the maximum output power to 10 dBm.
ESP2:MSR:MPOW 10
//Set the frequency range of the base station to > 3 GHz
ESP2:MSR:BAND:HIGH
//Set the base station RF bandwidth to 20 MHz
ESP2:MSR:RFBW 20MHZ
//Calculate limits for MSR SEM
ESP2:MSR:APPL
```

Manual operation: See ["Band Category"](#) on page 221

[SENSe:]ESpectrum<sb>:MSR:CLAS <Class>

Defines the class of the base station according to its sending range.

Suffix:

<sb> 1 | 2 | 3
 irrelevant

Parameters:

<Class> **WIDE**
 Wide Area
 MEDium
 Medium Range
 LOCal
 Local Area
*RST: WIDE

Example:

```
//Select the band category 1
ESP2:MSR:BCAT BC1
//Set the base station class to medium range
ESP2:MSR:CLAS MED
//Set the maximum output power to 10 dBm.
ESP2:MSR:MPOW 10
//Set the frequency range of the base station to > 3 GHz
ESP2:MSR:BAND:HIGH
//Set the base station RF bandwidth to 20 MHz
ESP2:MSR:RFBW 20MHZ
//Calculate limits for MSR SEM
ESP2:MSR:APPL
```

Manual operation: See ["Base Station Class"](#) on page 221

[SENSe:]ESpectrum<sb>:MSR:GSM:CARR <Power>

Defines the power of the GSM carrier (if available, see [\[SENSe:\]ESpectrum<sb>:MSR:GSM:CARR](#) on page 676).

This command is only available for band category 2 (see [SENSe:]ESpectrum<sb>:MSR:BCATegory on page 675).

Suffix:

<sb> 1 | 2 | 3
 irrelevant

Parameters:

<Power> numeric value
 Range: 0 dBm to 100 dBm
 *RST: 39.0 dBm

Example:

```
//Select the band category 2
ESP2:MSR:BCAT BC2
//Set the base station class to medium range
ESP2:MSR:CLAS MED
//Set the maximum output power to 10 dBm.
ESP2:MSR:MPOW 10
//Set the base station RF bandwidth to 20 MHz
ESP2:MSR:RFBW 20MHZ
//GSM/Edge present
ESP2:MSR:GSM:CPR
//Power of the GSM carrier is 20dBm
ESP2:MSR:GSM:CARR 20
//Calculate limits for MSR SEM
ESP2:MSR:APPL
```

Manual operation: See "Power GSM Carrier" on page 222

[SENSe:]ESpectrum<sb>:MSR:GSM:CPResent <State>

This command defines whether a GSM/Edge carrier is located at the edge of the specified RF bandwidth. In this case, the specification demands specific limits for the SEM ranges.

This command is only available for band category 2 (see [SENSe:]ESpectrum<sb>:MSR:BCATegory on page 675).

Suffix:

<sb> 1 | 2 | 3
 irrelevant

Parameters:

<State> ON | OFF
 *RST: OFF

Example:

```
//Select the band category 2
ESP2:MSR:BCAT BC2
//Set the base station class to medium range
ESP2:MSR:CLAS MED
//Set the maximum output power to 10 dBm.
ESP2:MSR:MPOW 10
//Set the base station RF bandwidth to 20 MHz
ESP2:MSR:RFBW 20MHZ
//GSM/Edge present
ESP2:MSR:GSM:CPR
//Power of the GSM carrier is 20dBm
ESP2:MSR:GSM:CARR 20
```

Manual operation: See "[Carrier Adjacent to RF Bandwidth Edge](#)" on page 222

[SENSe:]ESpectrum<sb>:MSR:LTE:CPreSent <State>

This command defines whether an LTE FDD 1.4 MHz or 3 MHz carrier is located at the edge of the specified RF bandwidth. In this case, the specification demands specific limits for the SEM ranges.

This command is only available for band category 2 (see [\[SENSe:\]ESpectrum<sb>:MSR:BCATegory](#) on page 675).

Suffix:

<sb> 1 | 2 | 3
 irrelevant

Parameters:

<State> ON | OFF
*RST: OFF

Example:

```
//Select the band category 2
ESP2:MSR:BCAT BC2
//Set the base station class to medium range
ESP2:MSR:CLAS MED
//Set the maximum output power to 10 dBm.
ESP2:MSR:MPOW 10
//Set the base station RF bandwidth to 20 MHz
ESP2:MSR:RFBW 20MHZ
//LTE present
ESP2:MSR:LTE:CPR
//Calculate limits for MSR SEM
ESP2:MSR:APPL
```

Manual operation: See "[Carrier Adjacent to RF Bandwidth Edge](#)" on page 222

[SENSe:]ESpectrum<sb>:MSR:MPOWER <Power>

Defines the maximum output power of the base station.

This setting is only available for base stations with a medium range base station class (see [SENSe:]ESpectrum<sb>:MSR:CLAS on page 676).

Suffix:

<sb> 1 | 2 | 3
irrelevant

Parameters:

<Power> Range: 0 dBm to 100 dBm
Increment: 1 dB

Example:

```
//Select the band category 1
ESP2:MSR:BCAT BC1
//Set the base station class to medium range
ESP2:MSR:CLAS MED
//Set the maximum output power to 10 dBm.
ESP2:MSR:MPOW 10
//Set the frequency range of the base station to > 3 GHz
ESP2:MSR:BAND:HIGH
//Set the base station RF bandwidth to 20 MHz
ESP2:MSR:RFBW 20MHZ
```

Manual operation: See "[Base Station Maximum Output Power](#)" on page 222

[SENSe:]ESpectrum<sb>:MSR:RFBWidth <Bandwidth>

This command defines the RF bandwidth of the base station for MSR measurements.

Suffix:

<sb> 1 | 2 | 3
irrelevant

Parameters:

<Bandwidth> Bandwidth in Hz
*RST: 10.0 MHz

Example:

```
//Select the band category 1
ESP2:MSR:BCAT BC1
//Set the base station class to medium range
ESP2:MSR:CLAS MED
//Set the maximum output power to 10 dBm.
ESP2:MSR:MPOW 10
//Set the frequency range of the base station to > 3 GHz
ESP2:MSR:BAND:HIGH
//Set the base station RF bandwidth to 20 MHz
ESP2:MSR:RFBW 20MHZ
//Calculate limits for MSR SEM
ESP2:MSR:APPL
```

Manual operation: See "[Base Station RF Bandwidth](#)" on page 222

11.5.6.8 Configuring the List Evaluation

The following commands configure the list evaluation.

Useful commands for SEM measurements described elsewhere

- `MMEMoRY:STORe<n>:LIST` on page 903

Remote commands exclusive to SEM measurements

<code>CALCulate<n>:ESpectrum:PSEarch:AUTO</code>	680
<code>CALCulate<n>:ESpectrum:PEAKsearch:AUTO</code>	680
<code>CALCulate<n>:ESpectrum:PSEarch[:IMMEDIATE]</code>	680
<code>CALCulate<n>:ESpectrum:PEAKsearch[:IMMEDIATE]</code>	680
<code>CALCulate<n>:ESpectrum:PSEarch:MARGIN</code>	680
<code>CALCulate<n>:ESpectrum:PEAKsearch:MARGIN</code>	680
<code>CALCulate<n>:ESpectrum:PSEarch:PSHOW</code>	681
<code>CALCulate<n>:ESpectrum:PEAKsearch:PSHOW</code>	681

`CALCulate<n>:ESpectrum:PSEarch:AUTO` <State>

`CALCulate<n>:ESpectrum:PEAKsearch:AUTO` <State>

This command turns the list evaluation on and off.

Parameters:

<State> ON | OFF | 0 | 1
 *RST: 1

Example: `CALC:ESP:PSE:AUTO OFF`
 Deactivates the list evaluation.

Manual operation: See "[List Evaluation \(Result Summary\) State](#)" on page 226
 See "[List Evaluation State](#)" on page 248

`CALCulate<n>:ESpectrum:PSEarch[:IMMEDIATE]`

`CALCulate<n>:ESpectrum:PEAKsearch[:IMMEDIATE]`

This command initiates a list evaluation.

Usage: Event

`CALCulate<n>:ESpectrum:PSEarch:MARGIN` <Threshold>

`CALCulate<n>:ESpectrum:PEAKsearch:MARGIN` <Threshold>

This command defines the threshold of the list evaluation.

Parameters:

<Margin> Range: -200 to 200
 *RST: 200
 Default unit: dB

Example: `CALC:ESP:PSE:MARG 100`
 Sets the margin to 100 dB.

Manual operation: See "Margin" on page 226
See "Margin" on page 248

CALCulate<n>:ESPectrum:PSEarch:PSHow <State>
CALCulate<n>:ESPectrum:PEAKsearch:PSHow <State>

This command turns the peak labels in the diagram on and off.

Peak labels are blue squares.

Parameters:

<State> ON | OFF
*RST: OFF

Example: CALC:ESP:PSE:PSH ON
Marks all peaks with blue squares.

Manual operation: See "Show Peaks" on page 226
See "Show Peaks" on page 248

11.5.6.9 Performing an SEM Measurement

The following commands are required to perform an SEM measurement:

SENS:SWE:MODE ESP, see [SENSe:]SWEep:MODE on page 651

INITiate<n>[:IMMEDIATE] on page 606, see chapter 11.5.1, "Performing Measurements", on page 603

11.5.6.10 Retrieving Results

The following commands analyze and retrieve measurement results for SEM measurements.

- CALCulate<n>:LIMit<k>:FAIL? on page 877
- CALCulate<n>:MARKer<m>:FUNction:POWer<sb>:RESult? on page 607
- TRACe<n>[:DATA] on page 813
- TRACe<n>[:DATA]:MEMory? on page 815
- TRACe<n>[:DATA]:X? on page 815

11.5.6.11 Example: SEM Measurement

In this example we will configure and perform an SEM measurement. Note that this example is primarily meant to demonstrate the remote control commands, it does not necessarily reflect a useful measurement task. For most common measurement standards, the R&S FPS performs the measurement optimally with the predefined settings, without further configuration.

```
//----- Preparing the measurement-----  
*RST
```

```

//Resets the instrument
SWE:MODE ESP
//Activates SEM Measurement

INIT:CONT OFF
//Selects single sweep mode.

//SEM has to be in single sweep mode to be configured and no sweep operation  
//may be running!
// If required, a sweep stop can be ensured by INIT:IMM;*WAI

//----- Managing Measurement Configurations-----
ESP:PRES 'WCDMA\3GPP\UL\3GPP_UL.xml'
//Loads the 3GPP configuration stored in the file '3GPP_UL.xml'

//----- Defining the Reference Range-----
ESP:RRAN?
//Queries the current reference range.
ESP:RTYP CPOW
//Selects the channel power as the power reference.
ESP:BWID 4 MHZ
//Defines a channel bandwidth of 4 MHz for the power reference.
ESP:FILT:RRC ON
ESP:FILT:ALPH 0.5
//Uses an RRC filter with a roll-off factor of 0.5 when measuring
//the reference power.

//----- Configuring Power Classes-----
CALC:LIM:ESP:PCL:COUN 3
//Defines 3 power classes.
CALC:LIM:ESP:LIM -100,0
//Defines the value ranges of the three power classes as [dBm]:
//power class 1: -200 to -100
//power class 2: -100 to 0
//power class 3: 0 to 200
CALC:LIM:ESP:PCL1:LIM ABS
//Defines an absolute limit check for class 1.
CALC:LIM:ESP:PCL2:LIM REL
//Defines a relative limit check for class 2.
CALC:LIM:ESP:MODE MAN
//Defines a manual selection of the power class.
CALC:LIM:ESP:PCL2 ON
//Activates the use of the second power class for the entire measurement.

//----- Configuring a Sweep List-----
ESP:RANG2:INS AFT
//Inserts a range after range 2.
ESP:RANG1:INS BEF
//Inserts a range before range 1.

```

Configuring and Performing Measurements

```

ESP:RANG:COUNT?
//Returns the number of measurement ranges in the sweep list (currently 11).
ESP:RANG5:DEL

//Deletes the 11th range.
ESP:RANG1:STOP -10000000

//Defines a stop frequency of -9 MHz for range 1.
ESP:RANG2:STAR -9000000
//Defines a start frequency of -10 MHz for range 2.

ESP:HSP OFF
//Switches off Fast SEM mode so the ranges can be configured individually.

ESP:RANG2:BAND:RES 1000000
//Defines a resolution bandwidth of 1 MHz for range 2.

ESP:RANG2:FILT:TYPE RRC
//Selects an RRC filter for range 2.
ESP:RANG2:BAND:VID 5000000
//Defines a video bandwidth of 5 MHz for range 2.
ESP:RANG2:SWE:TIME 1
//Defines a sweep time of 1 second for range 2.
ESP:RANG2:RLEV 0
//Defines a reference level of 0 dBm for range 2.
ESP:RANG2:INP:ATT 10
//Defines an input attenuation of 10 dB for range 2.

// Create a transducer that can be used.
// It has to cover the corresponding frequency range

SENSE1:CORREction:TRANsdUCer:SElect 'Transducer'
SENSE1:CORREction:TRANsdUCer:UNIT 'DB'
SENSE1:CORREction:TRANsdUCer:COMment 'Test Transducer'
// Frequency Span 0 MHz bis 20 Ghz
SENSE1:CORREction:TRANsdUCer:DATA 0e6,5, 20e9,3

ESP:RANG2:TRAN 'Transducer'
//Includes a transducer called 'transducer' for range 2.

//----- Configuring the limit check-----

ESP:RANG:LIM1:STAT AND
//Checks the absolute and relative limits for all ranges in power class 1 and
//fails if both limits are violated. Since power class 2 is set to be used for
//the entire measurement, values for Limit Check 1 are irrelevant. They are
//defined here to demonstrate the use of the MAX function for relative limits.
ESP:RANG2:LIM1:REL:STAR:FUNC MAX

```

```

//Enables the use of maximum function for relative limit start. If the value
//exceeds the larger of the absolute (-13 dBm) and relative (-10 dBc) start
//values, the check fails.
ESP:RANG2:LIM1:REL:STAR -10
ESP:RANG2:LIM1:REL:STAR:ABS -13
ESP:RANG2:LIM1:REL:STOP:FUNC MAX
ESP:RANG2:LIM1:REL:STOP -10
ESP:RANG2:LIM1:REL:STOP:ABS -13

ESP:RANG:LIM2:STAT OR
//Checks the absolute and relative limits for all ranges in power class 2 and
//fails if either limit is violated. Since power class 2 is set to be used for
//the entire measurement, values for Limit Check 1 are irrelevant.
ESP:RANG2:LIM2:ABS:STAR 10
ESP:RANG2:LIM2:ABS:STOP 10
//Defines an absolute limit of 10 dBm for the entire range 2 for power class 2.
ESP:RANG2:LIM2:REL:STAR -20
ESP:RANG2:LIM2:REL:STOP -20
//Defines a relative limit of -20 dBc for the entire range 2 for power class 2.

//----- Configuring List Evaluation-----
CALC:ESP:PSE:AUTO ON
//Activates list evaluation, i.e. the peak is determined for each range
//after each sweep.
CALC:ESP:PSE:MARG 10dB
//Defines a peak threshold of 10 dB.

//----- Managing Measurement Configurations-----

ESP:PRES:STOR 'WCDMA\3GPP\UL\3GPP_UL_User.xml'
//Saves the current configuration in a new file named '3GPP_UL_User'
//in the same directory so the standard is not overwritten.

//----- Performing the measurement-----
INIT:ESP
//One sweep

//----- Checking the Results-----
CALC:LIM:FAIL?
//Queries the result of the limit check for all ranges.
TRAC:DATA? LIST
//Returns the peak for each range of the SEM measurement as a list.

```

11.5.7 Measuring Spurious Emissions

All remote control commands specific to spurious emissions measurements are described here.

- [Initializing the Measurement](#)..... 685
- [Configuring a Sweep List](#)..... 685
- [Configuring the List Evaluation](#)..... 692
- [Performing a Spurious Measurement](#)..... 694
- [Retrieving and Saving Settings and Results](#)..... 694
- [Programming Example: Spurious Emissions Measurement](#)..... 694

11.5.7.1 Initializing the Measurement

Note that with the R&S FPS, the spurious measurement must be initialized before you can start configuring the sweep list or list evaluation.

[INITiate<n>:SPURious](#)..... 685

INITiate<n>:SPURious

This command initiates a Spurious Emission measurement.

Suffix:

<n> irrelevant

Usage: Event

11.5.7.2 Configuring a Sweep List

The following commands configure the sweep list for spurious emission measurements.



The sweep list cannot be configured using remote commands during an on-going sweep operation.

Useful commands for configuring the sweep described elsewhere:

- [\[SENSe:\] SWEep:MODE](#) on page 651

Remote commands exclusive to spurious measurements:

[SENSe:]LIST:RANGe<range>:BANDwidth[:RESolution]	686
[SENSe:]LIST:RANGe<range>:BANDwidth:VIDeo	686
[SENSe:]LIST:RANGe<range>:BREak	686
[SENSe:]LIST:RANGe<range>:COUNT?	687
[SENSe:]LIST:RANGe<range>:DELeTe	687
[SENSe:]LIST:RANGe<range>:DETector	687
[SENSe:]LIST:RANGe<range>:FILTer:TYPE	688
[SENSe:]LIST:RANGe<range>[:FREQuency]:START	688
[SENSe:]LIST:RANGe<range>[:FREQuency]:STOP	688
[SENSe:]LIST:RANGe<range>:INPut:ATTenuation	689
[SENSe:]LIST:RANGe<range>:INPut:ATTenuation:AUTO	689
[SENSe:]LIST:RANGe<range>:LIMit:START	690
[SENSe:]LIST:RANGe<range>:LIMit:STATe	690

[SENSe:]LIST:RANGe<range>:LIMit:STOP.....	690
[SENSe:]LIST:RANGe<range>:POINts.....	690
[SENSe:]LIST:RANGe<range>:RLEVel.....	691
[SENSe:]LIST:RANGe<range>:SWEep:TIME.....	691
[SENSe:]LIST:RANGe<range>:SWEep:TIME:AUTO.....	691
[SENSe:]LIST:RANGe<range>:TRANsducer.....	692

[SENSe:]LIST:RANGe<range>:BANDwidth[:RESolution] <RBW>

This command defines the resolution bandwidth for a spurious emission measurement range.

Suffix:

<range> 1..30
Selects the measurement range.

Parameters:

<RBW> Resolution bandwidth.
Refer to the data sheet for available resolution bandwidths.
Default unit: Hz

Manual operation: See "RBW" on page 245

[SENSe:]LIST:RANGe<range>:BANDwidth:VIDeo <VBW>

This command defines the video bandwidth for a spurious emission measurement range.

Suffix:

<range> 1..30
Selects the measurement range.

Parameters:

<VBW> Video bandwidth.
Refer to the data sheet for available video bandwidths.
Default unit: Hz

Manual operation: See "VBW" on page 245

[SENSe:]LIST:RANGe<range>:BREak <State>

This command controls the sweep (for all ranges, <range> is irrelevant).

Parameters:

<State> **ON**
The R&S FPS stops after measuring one range.
To continue with the next range, you have to use
[INITiate<n>:CONMeas.](#)

OFF
The R&S FPS sweeps all ranges in one go.
*RST: OFF

Manual operation: See "[Stop After Sweep](#)" on page 246

[SENSe:]LIST:RANGe<range>:COUNT?

This command queries the number of ranges in the sweep list (<range> is irrelevant).

Return values:

<Ranges> Number of ranges in the sweep list.

Usage: Query only

[SENSe:]LIST:RANGe<range>:DELEte

This command removes a range from the sweep list.

Note that

- you cannot delete the reference range
- a minimum of three ranges is mandatory.

Suffix:

<range> 1..30
 Selects the measurement range.

Usage: Event

[SENSe:]LIST:RANGe<range>:DETEctor <Detector>

This command selects the detector for a spurious emission measurement range.

Suffix:

<range> 1..30
 Selects the measurement range.

Parameters:

<Detector> **NEGative**
 minimum peak detector

POSitive
peak detector

SAMPIe
sample detector

RMS
RMS detector

AVERage
average detector

*RST: RMS

Manual operation: See "[Detector](#)" on page 245

[SENSe:]LIST:RANGe<range>:FILTer:TYPE <FilterType>

This command selects the filter type for a spurious emission measurement range.

Suffix:

<range> 1..30
Selects the measurement range.

Parameters:

<FilterType> **NORMAL**
Gaussian filters

CFILter
channel filters

RRC
RRC filters

P5
5 Pole filters

*RST: NORM
The available bandwidths of the filters are specified in the data sheet.

Manual operation: See "[Filter Type](#)" on page 244

[SENSe:]LIST:RANGe<range>[:FREQUency]:STARt <Frequency>

This command defines the start frequency of a spurious emission measurement range.

Make sure to set an appropriate span. If you set a span that is

- smaller than the span the sweep list covers, the R&S FPS will not measure the ranges that are outside the span - results may be invalid.
- greater than the span the sweep list covers, the R&S FPS will adjust the start frequency of the first range and the stop frequency of the last range to the span

For more information see [chapter 5.7, "Spurious Emissions Measurement"](#), on page 239.

Suffix:

<range> 1..30
Selects the measurement range.

Parameters:

<Frequency> Numeric value.

*RST: -12.75 MHz (range 1), -2.515 MHz (range 2), 2.515 MHz (range 3)

Default unit: Hz

Manual operation: See "[Range Start / Range Stop](#)" on page 244

[SENSe:]LIST:RANGe<range>[:FREQUency]:STOP <Frequency>

This command defines the stop frequency of a spurious emission measurement range.

Make sure to set an appropriate span. If you set a span that is

- smaller than the span the sweep list covers, the R&S FPS will not measure the ranges that are outside the span - results may be invalid.
- greater than the span the sweep list covers, the R&S FPS will adjust the start frequency of the first range and the stop frequency of the last range to the span

For more information see [chapter 5.7, "Spurious Emissions Measurement"](#), on page 239 .

Suffix:

<range> 1..30
Selects the measurement range.

Parameters:

<Frequency> Numeric value.
*RST: -2.52 MHz (range 1), 2.52 MHz (range 2), 250.0 MHz (range 3)
Default unit: Hz

Manual operation: See "[Range Start / Range Stop](#)" on page 244

[SENSe:]LIST:RANGe<range>:INPut:ATTenuation <Attenuation>

This command defines the input attenuation for a spurious emission measurement range.

Suffix:

<range> 1..30
Selects the measurement range.

Parameters:

<Attenuation> Numeric value.
Refer to the data sheet for the attenuation range.
*RST: 10 dB
Default unit: dB

Manual operation: See "[RF Attenuator](#)" on page 246

[SENSe:]LIST:RANGe<range>:INPut:ATTenuation:AUTO <State>

This command turns automatic selection of the input attenuation for a spurious emission measurement range on and off.

Suffix:

<range> 1..30
Selects the measurement range.

Parameters:

<State> ON | OFF | 0 | 1
*RST: 1

Manual operation: See "[RF Att. Mode](#)" on page 246

[SENSe:]LIST:RANGe<range>:LIMit:STARt <Level>

This command defines an absolute limit for a spurious emission measurement range.

Suffix:

<range> 1..30
Selects the measurement range.

Parameters:

<Level> Absolute limit at the start frequency of a SEM range.
Range: -400 to 400
*RST: 13
Default unit: dBm

Manual operation: See "[Abs Limit Start/Stop](#)" on page 247

[SENSe:]LIST:RANGe<range>:LIMit:STATe

This command turns the limit check for all spurious emission measurement ranges on and off (<range> is irrelevant).

Parameters:

<State> ON | OFF
*RST: OFF

Manual operation: See "[Limit Check](#)" on page 246

[SENSe:]LIST:RANGe<range>:LIMit:STOP <Level>

This command defines an absolute limit for a spurious emission measurement range.

Suffix:

<range> 1..30
Selects the measurement range.

Parameters:

<Level> Absolute limit at the stop frequency of a SEM range.
Range: -400 to 400
*RST: 13
Default unit: dBm

Manual operation: See "[Abs Limit Start/Stop](#)" on page 247

[SENSe:]LIST:RANGe<range>:POINTs <Points>

This command defines the number of sweep points in a spurious emission measurement range.

Suffix:

<range> 1..30
Selects the measurement range.

Parameters:

<Points> For more information on sweep points see [chapter 6.5.1.8, "How Much Data is Measured: Sweep Points and Sweep Count"](#), on page 356.

*RST: 1001

Manual operation: See "[Sweep Points](#)" on page 246

[SENSe:]LIST:RANGe<range>:RLEVel <RefLevel>

This command defines the reference level for a spurious emission measurement range.

Suffix:

<range> 1..30
Selects the measurement range.

Parameters:

<RefLevel> Reference level.
Refer to the data sheet for the reference level range.

*RST: 0 dBm

Manual operation: See "[Ref. Level](#)" on page 245

[SENSe:]LIST:RANGe<range>:SWEep:TIME <SweepTime>

This command defines the sweep time for a spurious emission measurement range.

Suffix:

<range> 1..30
Selects the measurement range.

Parameters:

<SweepTime> Sweep time.
The range depends on the ratios of the span to the RBW and the RBW to the VBW. Refer to the data sheet for more information.

Manual operation: See "[Sweep Time](#)" on page 245

[SENSe:]LIST:RANGe<range>:SWEep:TIME:AUTO <State>

This command turns automatic selection of the sweep time for a spurious emission measurement range on and off.

Suffix:

<range> 1..30
Selects the measurement range.

Parameters:

<State> ON | OFF | 0 | 1
*RST: 1

Manual operation: See "Sweep Time Mode" on page 245

[SENSe:]LIST:RANGe<range>:TRANsdUCer <Transducer>

This command selects a transducer factor for a spurious emission measurement range.

Note that

- the transducer must cover at least the span of the range
- the x-axis has to be linear
- the unit has to be dB

Suffix:

<range> 1..30
Selects the measurement range.

Parameters:

<Transducer> String containing the transducer file name, including the path information.

Manual operation: See "Transducer" on page 246

11.5.7.3 Configuring the List Evaluation

The following commands configure the list evaluation.

Useful commands for spurious emission measurements described elsewhere

- [MMEMory:STORe<n>:LIST](#) on page 903

Remote commands exclusive to spurious emission measurements

CALCulate<n>:PSEarch:AUTO	692
CALCulate<n>:PEAKsearch:AUTO	692
CALCulate<n>:PSEarch:DETails	693
CALCulate<n>:PEAKsearch:DETails	693
CALCulate<n>:PSEarch:MARGIn	693
CALCulate<n>:PEAKsearch:MARGIn	693
CALCulate<n>:PSEarch:PSHow	693
CALCulate<n>:PEAKsearch:PSHow	693
CALCulate<n>:PSEarch:SUBRanges	694
CALCulate<n>:PEAKsearch:SUBRanges	694

CALCulate<n>:PSEarch:AUTO <State>

CALCulate<n>:PEAKsearch:AUTO <State>

This command turns the list evaluation on and off.

Parameters:

<State> ON | OFF | 0 | 1
*RST: 1

Example: `CALC:PSE:AUTO OFF`
Deactivates the list evaluation.

CALCulate<n>:PSEarch:DEtails <State>

CALCulate<n>:PEAKsearch:DEtails

This command configures how detailed the list in the Result Summary is.

Parameters:

<State> `ON | OFF | 1 | 0`
ON | 1
 Includes all detected peaks (up to a maximum defined by `CALCulate<n>:PEAKsearch:SUBRanges` on page 694).
OFF | 0
 Includes only one peak per range.
 *RST: `OFF`

Example: `CALC:PSE:DET ON`
 `CALC:PSE:SUBR 10`
 Includes up to 10 peaks per range in the list.

Usage: Event

Manual operation: See "[Details](#)" on page 248

CALCulate<n>:PSEarch:MARGin <Threshold>

CALCulate<n>:PEAKsearch:MARGin <Threshold>

This command defines the threshold of the list evaluation.

Parameters:

<Margin> Range: `-200 to 200`
 *RST: `200`
 Default unit: `dB`

Example: `CALC:PSE:MARG 100`
 Sets the threshold to 100 dB.

CALCulate<n>:PSEarch:PSHow <State>

CALCulate<n>:PEAKsearch:PSHow <State>

This command turns the peak labels in the diagram on and off.

Peak labels are blue squares.

Parameters:

<State> `ON | OFF`
 *RST: `OFF`

Example: `CALC:PSE:PSH ON`
 Marks all peaks with blue squares.

CALCulate<n>:PSEarch:SUBRanges <NumberPeaks>

CALCulate<n>:PEAKsearch:SUBRanges <NumberPeaks>

This command defines the number of peaks included in the peak list.

After this number of peaks has been found, the R&S FPS stops the peak search and continues the search in the next measurement range.

Parameters:

<NumberPeaks> Range: 1 to 50
 *RST: 25

Example: CALC:PSE:SUBR 10
 Sets 10 peaks per range to be stored in the list.

Manual operation: See "Peaks per Range" on page 249

11.5.7.4 Performing a Spurious Measurement

The following commands are required to perform a Spurious measurement:

SENS:SWE:MODE LIST, see [SENSe:]SWEep:MODE on page 651

INITiate<n>[:IMMediate] on page 606, see chapter 11.5.1, "Performing Measurements", on page 603

11.5.7.5 Retrieving and Saving Settings and Results

The following commands analyze and retrieve measurement results for Spurious measurements.

Useful commands for spurious emission measurements described elsewhere

- CALCulate<n>:LIMit<k>:FAIL? on page 877
- TRACe<n>[:DATA] on page 813
- TRACe<n>[:DATA]:MEMory? on page 815
- TRACe<n>[:DATA]:X? on page 815

11.5.7.6 Programming Example: Spurious Emissions Measurement

In the following example, the Spurious Emissions measurement is configured by defining ranges and parameters to create the following sweep list.

Spurious Emissions			
	Range 1	Range 2	Range 3
Range Start	10 MHz	100 MHz	100.0000...
Range Stop	100 MHz	100.0000...	1 GHz
Filter Type	RRC	Normal(3...	Normal(3...
Res BW	24.3 kHz	10 kHz	100 kHz
Video BW	5 MHz	30 kHz	300 kHz
Sweep Time Mode	Manual	Auto	Auto
Sweep Time	1 s	4.01 ms	32.1 ms
Detector	Sample	RMS	RMS
Ref. Level	-20 dBm	0 dBm	0 dBm
RF Att. Mode	Manual	Auto	Auto
RF Attenuator	10 dB	10 dB	10 dB
Preamp	On	Off	Off
Sweep Points	601	4001	32001
Stop After Sweep	Off	Off	Off
Transducer	None	None	None
Limit Check	Absolute	Absolute	Absolute
Abs Limit Start	10 dBm	-13 dBm	-13 dBm
Abs Limit Stop	10 dBm	-13 dBm	-13 dBm

Note that this example is primarily meant to demonstrate the remote control commands, it does not necessarily reflect a useful measurement task.

```
//-----Preparing the measurement-----
*RST
//Resets the instrument

SWE:MODE LIST
//Activates spurious emissions measurement

INIT:CONT OFF
//Selects single sweep mode.

//Spurious measurement has to be in single sweep mode to be configured
//and no sweep operation may be running!

// If required, a sweep stop can be ensured by INIT:IMM;*WAI

//-----Configuring a Sweep List-----

LIST:RANG:COUNT?
//Returns the number of measurement ranges in the sweep list.
LIST:RANG4:DEL
```

```

//Deletes the fourth range.
LIST:RANG1:STAR 10000000
//Defines a start frequency of 10 MHz for range 1.
LIST:RANG1:STOP 100000000
//Defines a stop frequency of 100 MHz for range 1.
LIST:RANG1:BAND 500000
//Defines a resolution bandwidth of 500 kHz in range 1.
LIST:RANG1:BAND:VID 5000000
//Defines a video bandwidth of 5 MHz for range 1.
LIST:RANG1:INP:ATT:AUTO OFF
//Turns automatic selection of the input attenuation in range 1 off.

LIST:RANG1:INP:ATT 10
//Defines a input attenuation of 10 dBm for range 1.

LIST:RANG1:FILT:TYPE CFILter
//Selects an Channel filter for range 1.
LIST:RANG1:DET SAMP
//Selects a sample detector for range 1.
LIST:RANG1:POIN 601
//Defines 601 sweep points for range 1.
LIST:RANG1:RLEV -20
//Defines a reference level of -20 dBm for range 1.
LIST:RANG1:SWE:TIME 5
//Defines a manual sweep time of 5 second for range 1.

// Create a transducer that can be used.
// It has to cover the corresponding frequency range
//
SENSE1:CORRection:TRANsducer:SElect 'Test'
SENSE1:CORRection:TRANsducer:UNIT 'DB'
SENSE1:CORRection:TRANsducer:COMment 'Test Transducer'
// Frequency Span 0 MHz to 20 Ghz
SENSE1:CORRection:TRANsducer:DATA 0e6,5, 20e9,3

SENS:LIST:RANG1:TRAN 'Test'
//Includes a transducer called 'Test' for range 1.

LIST:RANG1:LIM:STAR 10
LIST:RANG1:LIM:STOP 10
//Defines an absolute limit of 10 dBm at the start and stop frequencies of range 1.
LIST:RANG:LIM:STAT ON
//Turns the limit check for all ranges on.

//-----Configuring the List Evaluation-----
CALC:PSE:MARG 100
//Sets the threshold to 100 dB.
CALC:PSE:PSH ON
//Marks all peaks in the diagram with blue squares.

```

```

CALC:PSE:SUBR 10
//Sets 10 peaks per range to be stored in the list.

//-----Performing the Measurement-----

INIT:SPUR; *WAI
//Performs a spurious emission measurement and waits until the sweep has finished.

//-----Retrieving Results-----
CALC:LIM1:FAIL?
//Queries the result of the check for limit line 1.
TRAC? SPUR
//Queries the peak list of the spurious emission measurement.

```

11.5.8 Analyzing Statistics (APD, CCDF)

All remote control commands specific to statistical measurements are described here.

- [Activating Statistical Measurements](#)..... 697
- [Configuring Statistical Measurements](#).....698
- [Using Gate Ranges for Statistical Measurements](#)..... 699
- [Scaling the Diagram](#).....701
- [Performing a Statistical Measurement](#)..... 703
- [Retrieving Results](#)..... 703
- [Programming Example: Measuring Statistics](#)..... 705

11.5.8.1 Activating Statistical Measurements

The following commands activate statistical measurements.

```

CALCulate<n>:STATistics:APD[:STATe]..... 697
CALCulate<n>:STATistics:CCDF[:STATe]..... 697

```

CALCulate<n>:STATistics:APD[:STATe] <State>

This command turns the APD measurement on and off.

Parameters:

```

<State>          ON | OFF
                 *RST:    OFF

```

Example:

```

CALC:STAT:APD ON
Switches on the APD measurement.

```

Manual operation: See "[APD](#)" on page 114

CALCulate<n>:STATistics:CCDF[:STATe] <State>

This command turns the CCDF on and off.

The suffix <n> is irrelevant.

Parameters:

<State> ON | OFF
 *RST: OFF

Example:

CALC:STAT:CCDF ON
 Switches on the CCDF measurement.

Manual operation: See "CCDF" on page 114

11.5.8.2 Configuring Statistical Measurements

The following commands configure the measurement.

Useful commands for configuring statistical measurements described elsewhere:

- [SENSe:]BANDwidth[:RESolution] on page 747

Remote commands exclusive to statistical measurements:

CALCulate<n>:MARKer<m>:Y:PERCent..... 698
 CALCulate<n>:STATistics:NSAMples..... 698

CALCulate<n>:MARKer<m>:Y:PERCent <Probability>

This command sets a marker to a particular probability value. You can query the corresponding level with `CALCulate<n>:MARKer<m>:X`.

Using the command turns delta markers into normal markers.

This command is available for CCDF measurements.

Parameters:

<Probability> Range: 0 % to 100 %

Example:

CALC1:MARK:Y:PERC 95PCT
 Positions marker 1 to a probability of 95 %.

Manual operation: See "Percent Marker (CCDF only)" on page 258

CALCulate<n>:STATistics:NSAMples <Samples>

This command defines the number of samples included in the analysis of statistical measurement functions.

Parameters:

<Samples> Range: Min: 100, Max: depends on the RBW filter
 *RST: 100000

Example:

CALC:STAT:NSAM 500
 Sets the number of measurement points to be acquired to 500.

Manual operation: See "Number of Samples" on page 259

11.5.8.3 Using Gate Ranges for Statistical Measurements

The following commands control gated statistical measurements.

[SENSe:]SWEep:EGATe:TRACe<k>:COMMeNt.....	699
[SENSe:]SWEep:EGATe:TRACe:PERiod.....	699
[SENSe:]SWEep:EGATe:TRACe<k>:STARt<range>.....	699
[SENSe:]SWEep:EGATe:TRACe<k>[:STATe<range>].....	700
[SENSe:]SWEep:EGATe:TRACe<k>:STOP<range>.....	700

[SENSe:]SWEep:EGATe:TRACe<k>:COMMeNt <Comment>

This command defines a comment for the gate of a particular trace.

Parameters:

<Comment> String containing the comment.

Example:

```
SWE:EGAT:TRAC1:COMM 'MyComment'
```

Defines a comment for the gate in trace 1.

Manual operation: See "[Comment](#)" on page 260

[SENSe:]SWEep:EGATe:TRACe:PERiod <Length>

This command defines the length of the gate for all traces.

The gate length applies to all traces.

Parameters:

<Length> Range: 100 ns to 1000 s
 *RST: 2 ms

Example:

```
SWE:EGAT:TRAC1:PER 5ms
```

Defines the period for gated triggering to 5 ms.

Manual operation: See "[Period](#)" on page 260

[SENSe:]SWEep:EGATe:TRACe<k>:STARt<range> <Time>

This command defines the start time for a gate range.

Suffix:

<range> 1...3
 gate range

Parameters:

<Time> The value range depends on the gate period you have set for the selected trace with `[SENSe:]SWEep:EGATe:TRACe:PERiod`. The following rules apply:

- the start time may not be higher than the length of the gate
- the start time may not be lower than the stop time of the gate range of a lower order

The reset values depend on the gate range.

- for gate range 1, the start time is 0 ms
- for gate range 3, the start time is 2 ms
- for gate range 5, the start time is 4 ms

Example:

```
SWE:EGAT:TRAC1:STAR1 3ms
```

Sets the Starting point for range 1 on trace 1 at 3 ms.

Manual operation: See "[Range <x> Start/Stop](#)" on page 260

[SENSe:]SWEep:EGATe:TRACe<k>[:STATe<range>] <State>

This command includes or excludes a gate range for a particular trace.

Suffix:

<range> 1...3
gate range

Parameters:

<State> ON | OFF
*RST: OFF

Example:

```
SWE:EGAT:TRAC1:STAT1 ON
```

Activates gate range 1 for trace 1.

Manual operation: See "[Gated Trigger](#)" on page 259
See "[Range <x> Use](#)" on page 260

[SENSe:]SWEep:EGATe:TRACe<k>:STOP<range> <Time>

This command defines the stop time for a gate range.

Suffix:

<range> 1...3
gate range

Parameters:

<Time>

The value range depends on the gate period you have set for the selected trace with `[SENSe:]SWEp:EGATe:TRACe:PERiod`. The following rules apply:

- the stop time may not be higher than the length of the gate
- the stop time may not be lower than the start time

The reset values depend on the gate range.

- for gate range 1, the stop time is 1 ms
- for gate range 3, the stop time is 3 ms
- for gate range 5, the stop time is 5 ms

Example:

```
SWE:EGAT:TRAC1:STOP1 5ms
```

Sets the stopping point for range 1 on trace 1 at 5 ms.

Manual operation: See "[Range <x> Start/Stop](#)" on page 260

11.5.8.4 Scaling the Diagram

The following commands set up the diagram for statistical measurements.

<code>CALCulate<n>:STATistics:PRESet</code>	701
<code>CALCulate<n>:STATistics:SCALE:AUTO ONCE</code>	702
<code>CALCulate<n>:STATistics:SCALE:X:RANGe</code>	702
<code>CALCulate<n>:STATistics:SCALE:X:RLEVel</code>	702
<code>CALCulate<n>:STATistics:SCALE:Y:LOWer</code>	703
<code>CALCulate<n>:STATistics:SCALE:Y:UNIT</code>	703
<code>CALCulate<n>:STATistics:SCALE:Y:UPPer</code>	703

CALCulate<n>:STATistics:PRESet

This command resets the scale of the diagram (x- and y-axis).

- Reference level (x-axis)
0.0 dBm
- Display range (x-axis) for APD measurements
100 dB
- Display range (x-axis) for CCDF measurements
20 dB
- Upper limit of the y-axis
1.0
- Lower limit of the y-axis
1E-6

Example:

```
CALC:STAT:PRES
```

Resets the scaling for statistical functions

Usage:

Event

Manual operation: See "[Default Settings](#)" on page 262

CALCulate<n>:STATistics:SCALE:AUTO ONCE

This command initiates an automatic scaling of the diagram (x- and y-axis).

To obtain maximum resolution, the level range is set as a function of the measured spacing between peak power and the minimum power for the APD measurement and of the spacing between peak power and mean power for the CCDF measurement. In addition, the probability scale for the number of test points is adapted.

To get valid results, you have to perform a complete sweep with synchronization to the end of the auto range process. This is only possible in single sweep mode.

Parameters:

ONCE

Example:

```
CALC:STAT:SCAL:AUTO ONCE;*WAI
```

Adapts the level setting for statistical measurements.

Usage:

Event

Manual operation: See ["Adjust Settings"](#) on page 259

CALCulate<n>:STATistics:SCALE:X:RANGe <Range>

This command defines the display range of the x-axis for statistical measurements.

The effects are identical to `DISPlay[:WINDow<n>]:TRACe<t>:Y[:SCALE]`.

Parameters:

<Range> Range: 1 dB to 200 dB
 *RST: 100 dB

Example:

```
CALC:STAT:SCAL:X:RANG 20dB
```

Manual operation: See ["Range"](#) on page 262

CALCulate<n>:STATistics:SCALE:X:RLEVel <RefLevel>

This command sets the reference level for statistical measurements. The effects are identical to `DISPlay[:WINDow<n>]:TRACe<t>:Y[:SCALE]:RLEVel`.

Note that in case of statistical measurements the reference level applies to the x-axis.

Parameters:

<RefLevel> The unit is variable.
 If a reference level offset is included, the range is adjusted by that offset.
 Range: -130 dBm to 30 dBm
 *RST: 0 dBm

Example:

```
CALC:STAT:SCAL:X:RLEV -60dBm
```

Manual operation: See ["Ref Level"](#) on page 262

CALCulate<n>:STATistics:SCALE:Y:LOWer <Magnitude>

This command defines the lower vertical limit of the diagram.

Parameters:

<Magnitude> The number is a statistical value and therefore dimensionless.
 Range: 1E-9 to 0.1
 *RST: 1E-6

Example: `CALC:STAT:SCAL:Y:LOW 0.001`

Manual operation: See "Y-Max / Y-Min" on page 262

CALCulate<n>:STATistics:SCALE:Y:UNIT <Unit>

This command selects the unit of the y-axis.

Parameters:

<Unit> PCT | ABS
 *RST: ABS

Example: `CALC:STAT:SCAL:Y:UNIT PCT`
 Sets the percentage scale.

Manual operation: See "Y-Unit" on page 262

CALCulate<n>:STATistics:SCALE:Y:UPPer <Magnitude>

This command defines the upper vertical limit of the diagram.

Parameters:

<Magnitude> The number is a statistical value and therefore dimensionless.
 Range: 1E-5 to 1.0
 *RST: 1.0

Example: `CALC:STAT:SCAL:Y:UPP 0.01`

Manual operation: See "Y-Max / Y-Min" on page 262

11.5.8.5 Performing a Statistical Measurement

The following commands are required to perform a statistical measurement:

`INITiate<n>[:IMMediate]` on page 606, see [chapter 11.5.1, "Performing Measurements"](#), on page 603

11.5.8.6 Retrieving Results

The following commands are required to retrieve the measurement results.

Useful commands for retrieving results described elsewhere:

- `CALCulate<n>:MARKer<m>:X` on page 823

Remote commands exclusive to statistical results

<code>CALCulate<n>:STATistics:CCDF:X<t>?</code>	704
<code>CALCulate<n>:STATistics:RESult<t>?</code>	704

CALCulate<n>:STATistics:CCDF:X<t>? <Probability>

This command queries the results of the CCDF.

Query parameters:

<Probability>	P0_01 Level value for 0.01 % probability
	P0_1 Level value for 0.1 % probability
	P1 P1: Level value for 1 % probability
	P10 Level value for 10 % probability

Example: `CALC:STAT:CCDF:X1? P10`
Returns the level values that are over 10 % above the mean value.

Usage: Query only

Manual operation: See "CCDF" on page 114

CALCulate<n>:STATistics:RESult<t>? <ResultType>

This command queries the results of a CCDF or ADP measurement for a specific trace.

(<n> is irrelevant.)

Parameters:

<ResultType>	MEAN Average (=RMS) power in dBm measured during the measurement time.
	PEAK Peak power in dBm measured during the measurement time.
	CFACTOR Determined crest factor (= ratio of peak power to average power) in dB.
	ALL Results of all three measurements mentioned before, separated by commas: <mean power>,<peak power>,<crest factor>

Example: `CALC:STAT:RES2? ALL`
Reads out the three measurement results of trace 2. Example of answer string: 5.56,19.25,13.69 i.e. mean power: 5.56 dBm, peak power 19.25 dBm, crest factor 13.69 dB

Usage: Query only

Manual operation: See "APD" on page 114
See "CCDF" on page 114

11.5.8.7 Programming Example: Measuring Statistics

This example demonstrates how to determine statistical values for a measurement in a remote environment using the gated statistics example described in [chapter 5.8.4, "APD and CCDF Basics - Gated Triggering"](#), on page 256.

Gate Ranges	
	Trace 1
Comment	GSM - useful part
Period	4.615 ms
Range 1 Use	On
Range 1 Start	15 μ s
Range 1 Stop	557.8 μ s
Range 2 Use	Off
Range 2 Start	2 ms
Range 2 Stop	3 ms
Range 3 Use	Off
Range 3 Start	4 ms

```
//-----Configuring the measurement -----
*RST
//Reset the instrument
TRIG:SOUR EXT
//Defines the use of an external trigger.
TRIG:HOLD 25us
//Defines a trigger offset of 25  $\mu$ s.
CALC:STAT:APD ON
//Activates APD measurement.
CALC:STAT:NSAM 1000
//Sets the number of samples to be included in the statistical evaluation to 1000.

//-----Defining Gate ranges -----

SWE:EGAT:TRAC1:COMM 'GSM - useful part'
//Defines a comment for the gate
SWE:EGAT:TRAC1:PER 4.61536ms
//Sets the gate period to 4.61536ms.
SWE:EGAT:TRAC1:STAR1 15us
//Sets the start of range 1 to 15  $\mu$ s.
SWE:EGAT:TRAC1:STOP1 557.8us
```

```

//Sets the end of range 1 to 15 µs (start time) + 542.77 µs (useful part) = 557.8 µs.
SWE:EGAT:TRAC1:STAT1 ON
//Activates the use of range 1.

//-----Performing the Measurement-----
INIT:CONT OFF
//Selects single sweep mode.
INIT;*WAI
//Initiates a new measurement and waits until the sweep has finished.

//-----Retrieving Results-----
CALC:STAT:RES1? MEAN
//Returns the mean average power for the useful part of the GSM signal.

//----- Determining the CCDF values-----

CALC:STAT:CCDF ON
//Activates CCDF measurement.
CALC:MARK2:Y:PERC 95PCT
//Sets marker 2 to the 95% probability value.
INIT;*WAI
//Initiates a new measurement and waits until the sweep has finished.
CALC:STAT:CCDF:X? P1
//Returns the level value for 10% probability for the CCDF.
CALC:MARK2:X?
//Returns the level for a probability of 95%.

//----- Scaling the diagram -----
CALC:STAT:SCAL:X:RLEV -70dBm
//Sets the reference level to -70 dBm (x-axis!)
CALC:STAT:SCAL:X:RANG 20dB
//Defines a power level range of 20 dB for the x-axis
CALC:STAT:SCAL:Y:LOW 0.0001
//Sets the minimum of the y-axis to 0.01% probability
CALC:STAT:SCAL:Y:UPP 1.0
//Sets the maximum of the y-axis to 100% probability
CALC:STAT:SCAL:Y:UNIT PCT
//Displays percentage values on y-axis scale

```

11.5.9 Measuring the Time Domain Power

All remote control commands specific to time domain power measurements are described here.

- [Configuring the Measurement](#).....707
- [Performing a Time Domain Power Measurement](#)..... 709
- [Retrieving Measurement Results](#)..... 709
- [Programming Example: Time Domain Power](#)..... 713

11.5.9.1 Configuring the Measurement

The following remote commands measure the time domain power.

Useful commands for time domain power measurements described elsewhere

- `CALCulate<n>:MARKer<m>:X:SLIMits:LEFT`
- `CALCulate<n>:MARKer<m>:X:SLIMits:RIGHT`
- `CALCulate<n>:MARKer<m>:X:SLIMits[:STATe]`

Remote commands exclusive to time domain power measurements

<code>CALCulate<n>:MARKer<m>:FUNction:SUMMary:AOff</code>	707
<code>CALCulate<n>:MARKer<m>:FUNction:SUMMary:AVERage</code>	707
<code>CALCulate<n>:MARKer<m>:FUNction:SUMMary:PHOLd</code>	708
<code>CALCulate<n>:MARKer<m>:FUNction:SUMMary[:STATe]</code>	708
<code>CALCulate<n>:MARKer<m>:FUNction:SUMMary:MEAN[:STATe]</code>	708
<code>CALCulate<n>:MARKer<m>:FUNction:SUMMary:PPEak[:STATe]</code>	709
<code>CALCulate<n>:MARKer<m>:FUNction:SUMMary:RMS[:STATe]</code>	709
<code>CALCulate<n>:MARKer<m>:FUNction:SUMMary:SDEViation[:STATe]</code>	709

`CALCulate<n>:MARKer<m>:FUNction:SUMMary:AOff`

This command turns all time domain power evaluation modes off.

Usage: Event

`CALCulate<n>:MARKer<m>:FUNction:SUMMary:AVERage <State>`

This command switches on or off averaging for the active power measurement in zero span in the window specified by the suffix <n>. If activated, a time domain value is calculated from the trace after each sweep; in the end, all values are averaged to calculate the final result.

The number of results required for the calculation of average is defined with `[SENSe:]AVERage<n>:COUNT`.

Averaging is reset by switching it off and on again.

Synchronization to the end of averaging is only possible in single sweep mode.

Parameters:

<State> ON | OFF
 *RST: OFF

Example:

```
INIT:CONT OFF
Switches to single sweep mode.
CALC:MARK:FUNC:SUMM:AVER ON
Switches on the calculation of average.
AVER:COUN 200
Sets the measurement counter to 200.
INIT;*WAI
Starts a sweep and waits for the end.
```

CALCulate<n>:MARKer<m>:FUNctioN:SUMMery:PHOLd <State>

This command switches on or off the peak-hold function for the active power measurement in zero span in the window specified by the suffix <n>. If activated, the peak for each sweep is compared to the previously stored peak; the maximum of the two is stored as the current peak.

The peak-hold function is reset by switching it off and on again.

Parameters:

```
<State>          ON | OFF
*RST:           OFF
```

CALCulate<n>:MARKer<m>:FUNctioN:SUMMery[:STATe] <State>

This command turns time domain power measurements on and off. This measurement is only available in zero span.

When you turn the measurement on, the R&S FPS activates a marker and positions it on the peak power level in the marker search range.

Parameters:

```
<State>          ON | OFF
*RST:           OFF
```

Manual operation: See ["Time Domain Power"](#) on page 115

CALCulate<n>:MARKer<m>:FUNctioN:SUMMery:MEAN[:STATe] <State>

This command turns the evaluation to determine the mean time domain power on and off.

The R&S FPS performs the measurement on the trace marker 1 is positioned on.

Parameters:

```
<State>          ON | OFF
*RST:           OFF
```

Manual operation: See ["Results"](#) on page 269

CALCulate<n>:MARKer<m>:FUNction:SUMMARY:PPEak[:STATe] <State>

This command turns the evaluation to determine the positive peak time domain power on and off.

The R&S FPS performs the measurement on the trace marker 1 is positioned on.

Parameters:

<State> ON | OFF
*RST: OFF

Manual operation: See ["Results"](#) on page 269

CALCulate<n>:MARKer<m>:FUNction:SUMMARY:RMS[:STATe] <State>

This command turns the evaluation to determine the RMS time domain power on and off.

The R&S FPS performs the measurement on the trace marker 1 is positioned on.

Parameters:

<State> ON | OFF
*RST: OFF

Manual operation: See ["Results"](#) on page 269

CALCulate<n>:MARKer<m>:FUNction:SUMMARY:SDEVIation[:STATe] <State>

This command turns the evaluation to determine the standard deviation of the time domain power on and off.

The R&S FPS performs the measurement on the trace marker 1 is positioned on.

Parameters:

<State> ON | OFF
*RST: OFF

11.5.9.2 Performing a Time Domain Power Measurement

The following commands are required to perform a Time Domain Power measurement:

[INITiate<n>\[:IMMediate\]](#) on page 606, see [chapter 11.5.1, "Performing Measurements"](#), on page 603

11.5.9.3 Retrieving Measurement Results

The following commands query the results for time domain measurements.

Measuring the Mean Power

<code>CALCulate<n>:MARKer<m>:FUNction:SUMMary:MEAN:AVERage:RESult?</code>	710
<code>CALCulate<n>:MARKer<m>:FUNction:SUMMary:MEAN:PHOLd:RESult?</code>	710
<code>CALCulate<n>:MARKer<m>:FUNction:SUMMary:MEAN:RESult?</code>	710

`CALCulate<n>:MARKer<m>:FUNction:SUMMary:MEAN:AVERage:RESult?`

This command queries the average mean time domain power. The query is only possible if averaging has been activated previously using `CALCulate<n>:MARKer<m>:FUNction:SUMMary:AVERage` on page 707.

To get a valid result, you have to perform a complete measurement with synchronization to the end of the measurement before reading out the result. This is only possible for single sweep mode.

See also `INITiate<n>:CONTinuous` on page 605.

Return values:

<MeanPower> Mean power of the signal during the measurement time.

Usage: Query only

`CALCulate<n>:MARKer<m>:FUNction:SUMMary:MEAN:PHOLd:RESult?`

This command queries the maximum mean time domain power. The query is only possible if the peak hold function has been activated previously using `CALCulate<n>:MARKer<m>:FUNction:SUMMary:PHOLd`.

To get a valid result, you have to perform a complete measurement with synchronization to the end of the measurement before reading out the result. This is only possible for single sweep mode.

See also `INITiate<n>:CONTinuous` on page 605.

Return values:

<MeanPower> Mean power of the signal during the measurement time.

Usage: Query only

`CALCulate<n>:MARKer<m>:FUNction:SUMMary:MEAN:RESult?`

This command queries the mean time domain power.

To get a valid result, you have to perform a complete measurement with synchronization to the end of the measurement before reading out the result. This is only possible for single sweep mode.

See also `INITiate<n>:CONTinuous` on page 605.

Return values:

<MeanPower> Mean power of the signal during the measurement time.

Usage: Query only

Manual operation: See "Results" on page 269

Measuring the Peak Power

CALCulate<n>:MARKer<m>:FUNction:SUMMary:PPEak:AVERage:RESult?

This command queries the average positive peak time domain power. The query is only possible if averaging has been activated previously using [CALCulate<n>:MARKer<m>:FUNction:SUMMary:AVERage](#) on page 707.

To get a valid result, you have to perform a complete measurement with synchronization to the end of the measurement before reading out the result. This is only possible for single sweep mode.

See also [INITiate<n>:CONTInuous](#) on page 605.

Parameters:

<PeakPower> Peak power of the signal during the measurement time.

Usage: Query only

CALCulate<n>:MARKer<m>:FUNction:SUMMary:PPEak:PHOLd:RESult?

This command queries the maximum positive peak time domain power. The query is only possible if the peak hold function has been activated previously using [CALCulate<n>:MARKer<m>:FUNction:SUMMary:PHOLd](#).

To get a valid result, you have to perform a complete measurement with synchronization to the end of the measurement before reading out the result. This is only possible for single sweep mode.

See also [INITiate<n>:CONTInuous](#) on page 605.

Parameters:

<PeakPower> Peak power of the signal during the measurement time.

Usage: Query only

CALCulate<n>:MARKer<m>:FUNction:SUMMary:PPEak:RESult?

This command queries the positive peak time domain power.

To get a valid result, you have to perform a complete measurement with synchronization to the end of the measurement before reading out the result. This is only possible for single sweep mode.

See also [INITiate<n>:CONTInuous](#) on page 605.

Parameters:

<PeakPower> Peak power of the signal during the measurement time.

Usage: Query only

Manual operation: See "[Results](#)" on page 269

Measuring the RMS Power

CALCulate<n>:MARKer<m>:FUNction:SUMMary:RMS:AVERage:RESult?

This command queries the average RMS of the time domain power. The query is only possible if averaging has been activated previously using [CALCulate<n>:MARKer<m>:FUNction:SUMMary:AVERage](#) on page 707.

To get a valid result, you have to perform a complete measurement with synchronization to the end of the measurement before reading out the result. This is only possible for single sweep mode.

See also [INITiate<n>:CONTInuous](#) on page 605.

Return values:

<RMSPower> RMS power of the signal during the measurement time.

Usage: Query only

CALCulate<n>:MARKer<m>:FUNction:SUMMary:RMS:PHOLd:RESult?

This command queries the maximum RMS of the time domain power. The query is only possible if the peak hold function has been activated previously using [CALCulate<n>:MARKer<m>:FUNction:SUMMary:PHOLd](#).

To get a valid result, you have to perform a complete measurement with synchronization to the end of the measurement before reading out the result. This is only possible for single sweep mode.

See also [INITiate<n>:CONTInuous](#) on page 605.

Return values:

<RMSPower> RMS power of the signal during the measurement time.

Usage: Query only

CALCulate<n>:MARKer<m>:FUNction:SUMMary:RMS:RESult?

This command queries the RMS of the time domain power.

To get a valid result, you have to perform a complete measurement with synchronization to the end of the measurement before reading out the result. This is only possible for single sweep mode.

See also [INITiate<n>:CONTInuous](#) on page 605.

Return values:

<RMSPower> RMS power of the signal during the measurement time.

Usage: Query only

Manual operation: See "[Results](#)" on page 269

Measuring the Standard Deviation

CALCulate<n>:MARKer<m>:FUNction:SUMMary:SDEVIation:AVERage:RESult?

This command queries the average standard deviation of the time domain power. The query is only possible if averaging has been activated previously using [CALCulate<n>:MARKer<m>:FUNction:SUMMary:AVERage](#) on page 707.

To get a valid result, you have to perform a complete measurement with synchronization to the end of the measurement before reading out the result. This is only possible for single sweep mode.

See also [INITiate<n>:CONTInuous](#) on page 605.

Return values:

<StandardDeviation> Standard deviation of the signal during the measurement time.

Usage: Query only

CALCulate<n>:MARKer<m>:FUNction:SUMMary:SDEVIation:PHOLd:RESult?

This command queries the maximum standard deviation of the time domain power. The query is only possible if the peak hold function has been activated previously using [CALCulate<n>:MARKer<m>:FUNction:SUMMary:PHOLd](#).

To get a valid result, you have to perform a complete measurement with synchronization to the end of the measurement before reading out the result. This is only possible for single sweep mode.

See also [INITiate<n>:CONTInuous](#) on page 605.

Return values:

<StandardDeviation> Standard deviation of the signal during the measurement time.

Usage: Query only

CALCulate<n>:MARKer<m>:FUNction:SUMMary:SDEVIation:RESult?

This command queries the standard deviation of the time domain power.

To get a valid result, you have to perform a complete measurement with synchronization to the end of the measurement before reading out the result. This is only possible for single sweep mode.

See also [INITiate<n>:CONTInuous](#) on page 605.

Return values:

<StandardDeviation> Standard deviation of the signal during the measurement time.

Usage: Query only

11.5.9.4 Programming Example: Time Domain Power

This programming example demonstrates the measurement example described in [chapter 5.9.6, "Measurement Example"](#), on page 270 in a remote environment.

```
//-----Configuring the Measurement-----
*RST
//Resets the instrument

INIT:CONT OFF
//Turns on single sweep mode.

FREQ:CENT 1.8GHz
//Sets the center frequency to 1.8 GHz.

BAND:RES 100kHz
//Sets the bandwidth to 100 kHz.

SWE:TIME 10ms
//Sets the sweep time to 640  $\mu$ s.

FREQ:SPAN 0
//Sets the instrument to zero span.

CALC:MARK:FUNC:SUMM:STAT ON
//Turns on time domain power measurements.

CALC:MARK:FUNC:SUMM:MEAN ON
CALC:MARK:FUNC:SUMM:PPE ON
CALC:MARK:FUNC:SUMM:RMS ON
//Turns the evaluation of the mean, peak and RMS time domain power.

CALC:MARK:X:SLIM ON
//Activates limit lines for evaluation.

CALC:MARK:X:SLIM:LEFT 1ms
//Sets the left limit line to 326  $\mu$ s.

CALC:MARK:X:SLIM:RIGH 6ms
//Sets the right limit line to 538  $\mu$ s.

//-----Performing the Measurement-----

INIT;*WAI
//Initiates the measurement and waits until the measurement is finished.

//-----Retrieving the Results-----
CALC:MARK:FUNC:SUMM:MEAN:RES?
CALC:MARK:FUNC:SUMM:PPE:RES?
CALC:MARK:FUNC:SUMM:RMS:RES?
//Queries the mean, peak and RMS time domain power.
```

11.5.10 Measuring the Harmonic Distortion

All remote control commands specific to harmonic distortion measurements are described here.

- [Activating the Measurement](#).....715
- [Configuring the Measurement](#).....715
- [Performing the Measurement](#).....716
- [Retrieving Results](#).....717
- [Example: Measuring the Harmonic Distortion](#).....717

11.5.10.1 Activating the Measurement

The following command activates harmonic distortion measurement.

`CALCulate<n>:MARKer<m>:FUNction:HARMonics[:STATe]`..... 715

CALCulate<n>:MARKer<m>:FUNction:HARMonics[:STATe] <State>

This command turns the harmonic distortion measurement on and off.

Note the following:

- If you perform the measurement in the frequency domain, the search range for the frequency of the first harmonic, whose power is determined, is defined by the last span.
- If you perform the measurement in the time domain, the current center frequency is used as the frequency of the first harmonic. Thus, the frequency search is bypassed. The first harmonic frequency is set by a specific center frequency in zero span before the harmonic measurement is started.

Parameters:

<State> ON | OFF
 *RST: OFF

Example:

`CALC:MARK:FUNC:HARM ON`
 Activates the harmonic distortion measurement.

Manual operation: See "[Harmonic Distortion](#)" on page 115

11.5.10.2 Configuring the Measurement

The following commands control the harmonic distortion measurement.

Useful commands for harmonic distortion measurements described elsewhere

- `CALCulate<n>:MARKer<m>:FUNction:CENTer` on page 741
- `[SENSe:]SWEep:TIME:AUTO` on page 753

Remote commands exclusive to harmonic distortion measurements

CALCulate<n>:MARKer<m>:FUNction:HARMonics:BANDwidth:AUTO.....	716
CALCulate<n>:MARKer<m>:FUNction:HARMonics:NHARmonics.....	716
CALCulate<n>:MARKer<m>:FUNction:HARMonics:PRESet.....	716

CALCulate<n>:MARKer<m>:FUNction:HARMonics:BANDwidth:AUTO <State>

This command selects the resolution bandwidth of the harmonic in respect to the bandwidth of the first harmonic.

Parameters:

<State> ON | OFF | 0 | 1
 OFF | 0
 identical
 ON | 1
 a multiple
 *RST: 1

Manual operation: See "[Harmonic RBW Auto](#)" on page 276

CALCulate<n>:MARKer<m>:FUNction:HARMonics:NHARmonics <NoHarmonics>

This command selects the number of harmonics that the R&S FPS looks for.

Parameters:

<NoHarmonics> Range: 1 to 26
 *RST: 10

Manual operation: See "[No. of Harmonics](#)" on page 276

CALCulate<n>:MARKer<m>:FUNction:HARMonics:PRESet

This command initiates a measurement to determine the ideal configuration for the harmonic distortion measurement.

The method depends on the span.

- Frequency domain (span > 0)
 Frequency and level of the first harmonic are determined and used for the measurement list.
- Time domain (span = 0)
 The level of the first harmonic is determined. The frequency remains unchanged.

Usage: Event

Manual operation: See "[Adjust Settings](#)" on page 277

11.5.10.3 Performing the Measurement

The following commands are required to perform a harmonic distortion measurement:

`INITiate<n>[:IMMediate]` on page 606, see [chapter 11.5.1, "Performing Measurements"](#), on page 603

11.5.10.4 Retrieving Results

The following commands retrieve the results of the harmonic distortion measurement.

<code>CALCulate<n>:MARKer<m>:FUNCTion:HARMonics:DISToRTion?</code>	717
<code>CALCulate<n>:MARKer<m>:FUNCTion:HARMonics:LIST?</code>	717

`CALCulate<n>:MARKer<m>:FUNCTion:HARMonics:DISToRTion? TOtal`

This command queries the total harmonic distortion of the signal.

To get a valid result, you have to perform a complete measurement with synchronization to the end of the measurement before reading out the result. This is only possible for single sweep mode.

See also `INITiate<n>:CONTInuous` on page 605.

Return values:

`<Result>` `<Distortion_%>,<Distortion_dB>`
 Pair of values, one showing the THD in %, one in dB.

Usage: Query only

Manual operation: See "[Harmonic Distortion](#)" on page 115

`CALCulate<n>:MARKer<m>:FUNCTion:HARMonics:LIST?`

This command queries the position of the harmonics.

To get a valid result, you have to perform a complete measurement with synchronization to the end of the measurement before reading out the result. This is only possible for single sweep mode.

See also `INITiate<n>:CONTInuous` on page 605.

Return values:

`<Harmonics>` Returns one value for every harmonic.
 The first value is the absolute power of the first harmonic. The unit is variable.
 The other values are power levels relative to the first harmonic. The unit for these is dB.

Usage: Query only

Manual operation: See "[Harmonic Distortion](#)" on page 115

11.5.10.5 Example: Measuring the Harmonic Distortion

```
//-----Configuring the Measurement-----
*RST
//Resets the instrument.
```

```

INIT:CONT OFF
//Turns on single sweep mode.

CALC:MARK:FUNC:HARM ON
//Turns on the harmonic distortion measurement.
CALC:MARK:FUNC:HARM:NHAR 3
//Defines three harmonics to be found.

CALC:MARK:FUNC:HARM:BAND:AUTO OFF
//Turns off automatic bandwidth selection.
CALC:MARK:FUNC:HARM:PRES
//Determines the ideal configuration.

//-----Performing the Measurement-----

INIT;*WAI
//Initiates the measurement and finishes the sweep.

//-----Retrieving the Results-----
CALC:MARK:FUNC:HARM:LIST?
//Queries the position of the harmonics.
CALC:MARK:FUNC:HARM:DIST? TOT
//Queries the total harmonic distortion.

```

11.5.11 Measuring the Third Order Intercept Point

- [Determining the TOI](#)..... 718
- [Programming Example: Measuring the TOI](#)..... 720

11.5.11.1 Determining the TOI

All remote control commands specific to TOI measurements are described here.

Useful commands for TOI measurements described elsewhere

- [CALCulate<n>:DELTamarker<m>:X](#) on page 822
- [CALCulate<n>:DELTamarker<m>:X:RELative?](#) on page 833
- [CALCulate<n>:DELTamarker<m>:Y?](#) on page 833
- [CALCulate<n>:MARKer<m>:X](#) on page 823
- [CALCulate<n>:MARKer<m>:Y?](#) on page 834

Remote commands exclusive to TOI measurements

CALCulate<n>:MARKer<m>:FUNction:TOI[:STATe]	719
CALCulate<n>:MARKer<m>:FUNction:TOI:SEARChsignal ONCE	719
CALCulate<n>:MARKer<m>:FUNction:TOI:RESult?	719

CALCulate<n>:MARKer<m>:FUNction:TOI[:STATe] <State>

This command initiates a measurement to determine the third intercept point.

A two-tone signal with equal carrier levels is expected at the RF input of the instrument. Marker 1 and marker 2 (both normal markers) are set to the maximum of the two signals. Delta marker 3 and delta marker 4 are positioned to the intermodulation products. The delta markers can be modified separately afterwards with the `CALCulate<n>:DELTAmarker<m>:X` command.

The third-order intercept is calculated from the level spacing between the normal markers and the delta markers.

Parameters:

<State> ON | OFF
*RST: OFF

Example:

`CALC:MARK:FUNC:TOI ON`
Switches on the measurement of the third-order intercept.

Manual operation: See "TOI" on page 115

CALCulate<n>:MARKer<m>:FUNction:TOI:SEARchsignal ONCE

This command initiates a search for signals in the current trace to determine the third intercept point.

(<n>,<m> are irrelevant.)

Parameters:

ONCE

Example:

`CALC:MARK:FUNC:TOI:SEAR ONCE`
Executes the search for 2 signals and their intermodulation product at the currently available trace.

Usage: Event

Manual operation: See "Search Signals" on page 284

CALCulate<n>:MARKer<m>:FUNction:TOI:RESult?

This command queries the results for the third order intercept point measurement.

To get a valid result, you have to perform a complete measurement with synchronization to the end of the measurement before reading out the result. This is only possible for single sweep mode.

See also `INITiate<n>:CONTinuous` on page 605.

Parameters:

<TOI> Third order intercept point.

Example: INIT:CONT OFF
 Switches to single sweep mode.
 CALC:MARK:FUNC:TOI ON
 Switches the intercept measurement.
 INIT;*WAI
 Starts a sweep and waits for the end.
 CALC:MARK:FUNC:TOI:RES?
 Outputs the measured value.

Usage: Query only

Manual operation: See "TOI" on page 115

11.5.11.2 Programming Example: Measuring the TOI

This example demonstrates how to determine the TOI in a remote environment.

```
//-----Configuring the measurement -----
*RST
//Reset the instrument
CALC:MARK:FUNC:TOI ON
//Activate TOI measurement.

//-----Performing the Measurement-----
INIT:CONT OFF
//Selects single sweep mode.

CALC:MARK:FUNC:TOI:SEAR ONCE
//Initiates a search for signals in the current trace.

//-----Retrieving Results-----
CALC:MARK:FUNC:TOI:RES?
//Returns the TOI.
```

11.5.12 Measuring the AM Modulation Depth

All remote control commands specific to AM modulation depth measurements are described here.

- [Configuring and Performing the Measurement](#)..... 720
- [Example: Measuring the AM Modulation Depth](#).....722

11.5.12.1 Configuring and Performing the Measurement

The following commands control the measurement.

Useful commands for AM modulation depth described elsewhere

- [CALCulate<n>:DELTamarker<m>:X](#) on page 822
- [CALCulate<n>:DELTamarker<m>:X:RELative?](#) on page 833

- `CALCulate<n>:MARKer<m>:X` on page 823

Remote commands exclusive to AM modulation depth measurements

<code>CALCulate<n>:MARKer<m>:FUNCTION:MDEPth[:STATe]</code>	721
<code>CALCulate<n>:MARKer<m>:FUNCTION:MDEPth:SEARChsignal ONCE</code>	721
<code>CALCulate<n>:MARKer<m>:FUNCTION:MDEPth:RESult?</code>	721

`CALCulate<n>:MARKer<m>:FUNCTION:MDEPth[:STATe]` <State>

This command turns the AM Modulation Depth measurement on and off.

To work correctly, the measurement requires an AM modulated signal.

Parameters:

<State> ON | OFF
 *RST: OFF

Manual operation: See "[AM Mod Depth](#)" on page 115

`CALCulate<n>:MARKer<m>:FUNCTION:MDEPth:SEARChsignal ONCE`

This command initiates a search for the signals required for the AM depth measurement.

Note that the command does not perform a new measurement, but looks for the signals on the current trace.

Parameters:

ONCE

Example:

```
CALC:MARK:FUNC:MDEP:SEAR ONCE
```

Executes the search of an AM modulated signal at the currently available trace.

Usage: Event

Manual operation: See "[Search Signals](#)" on page 289

`CALCulate<n>:MARKer<m>:FUNCTION:MDEPth:RESult?`

This command queries the results of the AM modulation depth measurement..

To get a valid result, you have to perform a complete measurement with synchronization to the end of the measurement before reading out the result. This is only possible for single sweep mode.

See also `INITiate<n>:CONTinuous` on page 605.

Return values:

<ModulationDepth> Modulation depth in %.

Usage: Query only

Manual operation: See "[AM Mod Depth](#)" on page 115

11.5.12.2 Example: Measuring the AM Modulation Depth

This example demonstrates how to determine the AM modulation depth in a remote environment. Note that without a real input signal this measurement will not return useful results.

```
//-----Configuring the measurement -----
*RST
//Reset the instrument
FREQ:CENT 100MHz
//Set center frequency
FREQ:SPAN 10KHz
// Set span
CALC:MARK:FUNC:MDEP ON
//Activate AM modulation depth measurement.

//-----Performing the Measurement-----
INIT:CONT OFF
//Selects single sweep mode.
INIT:IMM
// Perform a single measurement
CALC:MARK:FUNC:MDEP:SEAR ONCE
//Initiates a search for signals in the current trace.

//-----Retrieving Results-----
CALC:MARK:FUNC:MDEP:RES?
//Queries the measurement results.

//If the results are not accurate, change the position of the
//the temporary markers manually.

//----Changing the position of the temp markers----
CALC:MARK:X 100MHZ
//Positions the reference marker on 100 MHz.
CALC:DELT2:X 5KHZ
//Positions delta marker 2 and 3 at a distance of 5 kHz to the reference marker.
CALC:DELT3:X 1KHZ
//Corrects the position of delta marker 3 by 1 kHz.

CALC:MARK:FUNC:MDEP:RES?
//Queries the measurement results for the repositioned markers.
```

11.5.13 List Evaluations

A list evaluation is a multiple power measurement that measures the power at up to 200 frequencies. The measurement itself is a time domain measurement. Note that if you set a span greater than 0, the R&S FPS aborts the list evaluation.

**Noise cancellation in list evaluations**

Noise cancellation is also available in zero span and thus also for list evaluations. See "[Noise cancellation](#)" on page 155 for details.

List evaluations allow for a different instrument setup for each frequency you want to measure. You can define most of the settings with the commands described here. Settings not covered by the commands listed below can be controlled with the common commands (see [chapter 11.7, "Setting Basic Measurement Parameters"](#), on page 741. Note that these commands have to be sent prior to the commands that control the list evaluation.

In case of a triggered measurement, a separate trigger event is required for each frequency to initiate that measurement. Note that you have to make changes to the trigger level in the time domain in order for it to take effect for the List Evaluation commands.



The list evaluation is incompatible to other measurement functions (e.g. marker functionality or statistics). If you use a command that controls those functions, the R&S FPS aborts the list evaluation.

The R&S FPS also aborts the list evaluation if you end the remote session.

The commands can be used in two different ways.

- Instrument setup, measurement and querying of the results in a single command line. This method causes the least delay between the measurement and the result output. However, it requires the control computer to wait for the response from the instrument.
- Instrument setup and querying of the result list at the end of the measurement: With this method, the control computer may be used for other activities while the measurement is being performed. However, more time is needed for synchronization via service request.

11.5.13.1 Performing List Evaluations

All remote control commands specific to list evaluations (which are available via remote control only) are described here.

Useful commands for list evaluation described elsewhere:

- [\[SENSe:\]POWer:NCORrection](#) on page 756

Remote commands exclusive to list evaluation

[SENSe:]LIST:POWer:RESult?	724
[SENSe:]LIST:POWer[;SEQUence]	724
[SENSe:]LIST:POWer:SET	725
[SENSe:]LIST:POWer:STATe	726

[SENSe:]LIST:POWer:RESult?

This command queries the results of the list evaluation.

This command may be used to obtain measurement results in an asynchronous way, using the service request mechanism for synchronization to the end of the measurement.

If there are no results, the command returns an error.

Return values:

<PowerLevel> Power level for each frequency included in the measurement. The command returns up to 3 power levels for each frequency, depending on the number of evaluation modes you have turned on with [\[SENSe:\]LIST:POWer:SET](#). The result is a list of floating point values separated by commas. The unit depends on [CALCulate<n>:UNIT:POWer](#).

Usage: Query only

[SENSe:]LIST:POWer[:SEQuence] <Frequency>, <RefLevel>, <RFAttenuation>, <EIAttenuation>, <FilterType>, <RBW>, <VBW>, <MeasTime>, <TriggerLevel>

This command configures and initiates the List Evaluation measurement.

The list can contain up to 200 entries (frequencies). You can define a different instrument setup for each frequency that is in the list.

If you synchronize the measurement with *OPC, the R&S FPS produces a service request when all frequencies have been measured and the number of individual measurements has been performed.

Note that using the command as a query initiates the measurement and returns the results if all frequencies have been measured. For more information on querying the results see [\[SENSe:\]LIST:POWer:RESult?](#).

Parameters:

<Frequency> Defines the frequency. Each frequency corresponds to one list entry.
Range: 0 to Fmax
Default unit: Hz

<RefLevel> Defines the reference level for a list entry.
Range: -130 to 30
Increment: 0.01
Default unit: dBm

<RFAttenuation> Defines the RF attenuation for a list entry.
Range: 0 to 70
Increment: 1
Default unit: dB

<EIAttenuation>	Defines the electronic attenuation for a list entry. Range: 0 to 30 Increment: 1 Default unit: dB
<FilterType>	Selects the filter type for a list entry. For more information see [SENSe:]BANDwidth[:RESolution]:TYPE .
<RBW>	Defines the resolution bandwidth for a list entry.
<VBW>	Defines the video bandwidth for a list entry.
<MeasTime>	Defines the measurement time for a list entry. Range: 1 µs to 16000 s
<TriggerLevel>	The trigger level must be 0.
Return values:	
<PowerLevel>	Power level for each frequency included in the measurement. The command returns up to 3 power levels for each frequency, depending on the number of evaluation modes you have turned on with [SENSe:]LIST:POWer:SET . The result is a list of floating point values separated by commas. The unit depends on CALCulate<n>:UNIT:POWer .

[SENSe:]LIST:POWer:SET <PeakPower>, <RMSPower>, <AVGPower>, <TriggerSource>, <TriggerSlope>, <TriggerOffset>, <GateLength>

This command defines global List Evaluation parameters.

These parameters are valid for every frequency you want to measure.

The state of the first three parameters (<PeakPower>, <RMSPower> and <AVGPower>) define the number of results for each frequency in the list.

Note that you have to set the trigger level *after* sending this command.

Parameters:

<PeakPower>	ON OFF 0 1 Turns peak power evaluation on and off. *RST: 1
<RMSPower>	ON OFF 0 1 Turns RMS power evaluation on and off. *RST: 0
<AVGPower>	ON OFF 0 1 Turns average power evaluation on and off. *RST: 0
<TriggerSource>	EXTernal EXT2 IMMEDIATE IFPower RFPower VIDEO Selects a trigger source. For more information see Configuring Triggered and Gated Measurements .

<TriggerSlope>	NEGative POSitive Selects the trigger slop.
<TriggerOffset>	Defines the trigger delay. Range: negative measurement time to 30 s *RST: 0 Default unit: s
<GateLength>	Defines the gate length for gated measurements. Setting 0 seconds turns gated measurements off. To perform gated measurements, the trigger source must be different from IMMEDIATE. Range: 31.25 ns to 30 s *RST: 0 s

[SENSe:]LIST:POWer:STATe <State>

This command turns the List Evaluation off.

Parameters:

<State>	OFF
*RST:	OFF

11.5.13.2 Example: Performing List Evaluation

The following example shows a list evaluation with the following configuration.

No	Freq [MHz]	Ref Level [dBm]	RF Attenuation [dB]	EI Attenuation [dB]	Filter	RBW	VBW	Meas Time	Trigger Level
1	935.2	0	10	---	Normal	1 MHz	3 MHz	440 µs	0
2	935.4	0	10	10	Channel	30 kHz	100 kHz	440 µs	0
3	935.6	0	10	20	Channel	30 kHz	100 kHz	440 µs	0

```

-----Measurement with synchronization via service request-----
*ESE 1
*SRE 32
// Configures the status reporting system to produce a service request.
LIST:POW:SET ON,ON,OFF,EXT,POS,10us,434us
//Turns on the list evaluation, configures the global list evaluation settings and
//evaluates the peak and RMS power.
LIST:POW
935.2MHZ,0,10,OFF,NORM,1MHZ,3MHZ,440us,0,
935.4MHZ,0,10,10,CFIL,30KHZ,100KHZ,440us,0,
935.6MHZ,0,10,20,CFIL,30KHZ,100KHZ,440us,0;
*OPC

```



```
//Defines a list with 3 entries and initiates the measurement with synchronization to the end
//Analyzer produces a service request
//On service request:
SENS:LIST:POW:RES?
//Returns the results of the measurements, two for each frequency (peak and RMS power).

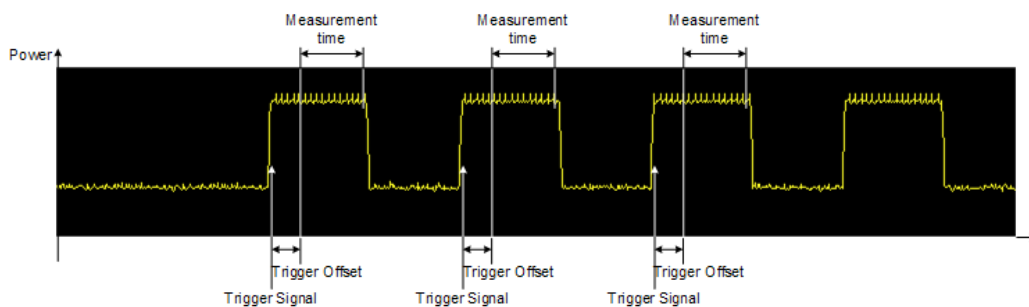
-----Initiliazing the measurement and querying results simultaneously-----
LIST:POW?
935.2MHZ,0,10,OFF,NORM,1MHZ,3MHZ,440us,0,
935.4MHZ,0,10,10,CFIL,30KHZ,100KHZ,440us,0,
935.6MHZ,0,10,20,CFIL,30KHZ,100KHZ,440us,0
//Defines a list with 3 entries, initiates the measurement and queries the results.
//Result example:
-28.3,-30.6,-38.1
```

11.5.14 Measuring the Pulse Power

All remote control commands specific to measuring the mean or peak pulse power (e.g. bursts in various telecommunications standards) are described here. This measurement is available via remote control only.

The Pulse Power measurement is a gated measurement that determines the power over a particular number of pulses. The measurement is controlled by an external trigger or the video signal. A separate trigger event is required for each burst included in the measurement. In case of an external trigger source, the trigger level corresponds to the TTL level. In case of a video signal, you can define any threshold.

The figure below shows the relations between the available trigger settings.



The measurement is always on trace 1, either with the peak detector to determine the peak power or the RMS detector to determine the RMS power. Overall, you can configure the measurement independent of the instrument setup with the commands listed below only, which results in faster measurements.



The Pulse Power measurement is incompatible to other measurement functions (e.g. marker functionality or statistics). If you use a command that controls those functions, the R&S FPS aborts the Pulse Power measurement.

The R&S FPS also aborts the Pulse Power measurement if you end the remote session.

The commands can be used in two different ways.

- Instrument setup, measurement and querying of the results in a single command line. With this method, there is the least delay between the measurement and the result output. However, it requires the control computer to wait for the response from the instrument.
- Instrument setup and querying of the result list at the end of the measurement: With this method, the control computer may be used for other activities while the measurement is being performed. However, more time is needed for synchronization via service request.

11.5.14.1 Performing Pulse Power Measurements

The following commands control pulse power measurements.

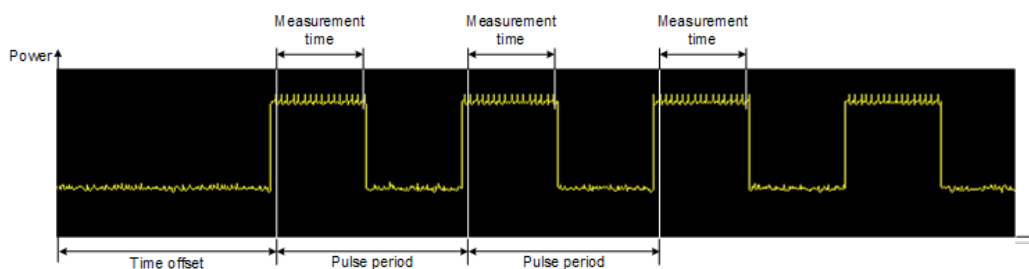
CALCulate<n>:MARKer<m>:FUNCTION:MSUMmary	728
[SENSe:]MPOWER:FTYPE	729
[SENSe:]MPOWER:RESult[:LIST]?	729
[SENSe:]MPOWER[:SEQUence]	729
[SENSe:]MPOWER:RESult:MIN?	731

CALCulate<n>:MARKer<m>:FUNCTION:MSUMmary

<TimeOffset>, <MeasTime>, <PulsePeriod>, <#OfPulses>

This command configures power measurements on pulses in the time domain.

To evaluate the pulse power, the R&S FPS uses the data captured during a previous measurement. The data recorded during the set measurement time is combined to a measured value for each pulse according to the detector specified and the indicated number of results is output as a list.



To get a valid result, you have to perform a complete measurement with synchronization to the end of the measurement before reading out the result. This is only possible for single sweep mode.

See also [INITiate<n>:CONTinuous](#) on page 605.

Parameters:

<TimeOffset> Defines a time offset to start the measurement at the first pulse of a trace.
 *RST: 0
 Default unit: s

<MeasTime>	Defines the measurement time. Default unit: s
<PulsePeriod>	Defines the pulse period
<#OfPulses>	Defines the number of pulses to measure.
Example:	<code>CALC:MARK:FUNC:MSUM 50US,450US,576.9US,8</code> Evaluates data that contains 8 pulses during a measurement time of 450 μ s and a pulse period of 576.9 μ s. The evaluation starts with an offset of 50 μ s.

[SENSe:]MPOWer:FTYPe <FilterType>

This command selects the filter type for pulse power measurements.

Parameters:

<FilterType>	CFILter NORMal P5 RRC
--------------	--

[SENSe:]MPOWer:RESult[:LIST]?

This command queries the results of the pulse power measurement.

This command may be used to obtain measurement results in an asynchronous way, using the service request mechanism for synchronization to the end of the measurement.

If there are no results, the command returns an error.

Return values:

<PulsePower>	List of pulse powers. The number of values depends on the number of pulses you have been measuring. The unit is dBm.
--------------	--

Usage: Query only

[SENSe:]MPOWer[:SEQuence] <Frequency>, <RBW>, <MeasTime>, <TriggerSource>, <TriggerLevel>, <TriggerOffset>, <Detector>, <#OfPulses>

This command configures and initiates the pulse power measurement.

The R&S FPS caches all measurement parameters that you can set with this command. If you use the command repeatedly, the R&S FPS only changes those settings that you have actually changed before initiating the measurement. Thus, measurement times are kept as low as possible.

If you synchronize the measurement with *OPC, the R&S FPS produces a service request when all frequencies have been measured and the number of individual measurements has been performed.

Note that using the command as a query initiates the measurement and returns the results if all frequencies have been measured. For more information on querying the results see [\[SENSe:\]LIST:POWer:RESult?](#).

Parameters:

<Frequency>	Defines the pulse frequency. Range: 0 to Fmax Default unit: Hz
<RBW>	Defines the resolution bandwidth.
<MeasTime>	Defines the measurement time. Range: 1 μ s to 30 s
<TriggerSource>	EXTernal EXT2 VIDEo Selects a trigger source. For more information see Configuring Triggered and Gated Measurements .
<TriggerLevel>	Defines a trigger level. The trigger level is available for the video trigger. In that case, the level is a percentage of the diagram height. In case of an external trigger, the R&S FPS uses a fix TTL level. Range: 0 to 100 Default unit: PCT
<TriggerOffset>	Defines the trigger delay. Range: 0 s to 30 s *RST: 0 s Default unit: s
<Detector>	Selects the detector and therefore the way the measurement is evaluated. MEAN Calculates the RMS pulse power. PEAK Calculates the peak pulse power.
<#OfPulses>	Defines the number of pulses included in the measurement. Range: 1 to 32001

Return values:

<PowerLevel>	Pulse power level. The result is a list of floating point values separated by commas. The unit is dBm.
--------------	--

[SENSe:]MPOWer:RESult:MIN?

This command queries the lowest pulse power that has been measured during a pulse power measurement.

If there are no results, the command returns an error.

Return values:

<PulsePower> Lowest power level of the pulse power measurement.
The unit is dBm.

Usage: Query only

11.5.14.2 Example: Performing a Pulse Power Measurement

The following example shows a pulse power measurement.

```
-----Measurement with synchronization via service request-----
*ESE 1
*SRE 32
// Configures the status reporting system to produce a service request.
MPOW:FTYP NORM
//Selects a Gaussian filter for the measurement.
MPOW 935.2MHZ,1MHZ,434us,VID,50,5us,MEAN,20;
*OPC
//Configures and initiates a measurement on 20 pulses with synchronization to the end.
//Analyzer produces a service request
//On service request:
MPOW:RES?
//Returns the results of the measurements (20 power levels).
MPOW:RES:MIN?
//Returns the lowest of the 20 power level that have been measured.

-----Initiliazing the measurement and querying results simultaneously-----
MPOW? 935.2MHZ,1MHZ,434us,VID,50,5us,MEAN,20
//Configures, initiates and queries the results of the measurement.
//Result example:
-105.225059509,-105.656074524,-105.423065186,-104.374649048,-103.059822083,-101.29511261,
-99.96534729,-99.7452468872,-99.6610794067,-100.327224731,-100.96686554,-101.450386047,
-102.150642395,-103.240142822,-105.95476532,-110.583129883,-115.7760849,-126.279388428,
-124.620399475,-116.97366333
```

11.6 Configuring the Result Display

The commands required to configure the screen display in a remote environment are described here.

The tasks for manual operation are described in [chapter 7.1, "Result Display Configuration"](#), on page 385.

- [General Window Commands](#)..... 732
- [Working with Windows in the Display](#)..... 733
- [Examples: Configuring the Result Display](#)..... 738

11.6.1 General Window Commands

The following commands are required to configure general window layout, independent of the application.

Note that the suffix <n> always refers to the window *in the currently selected measurement channel* (see [INSTrument\[:SElect\]](#) on page 597).

DISPlay:FORMat	732
DISPlay[:WINDow<n>]:SIZE	732

DISPlay:FORMat <Format>

This command determines which tab is displayed.

Parameters:

<Format>	SPLit Displays the MultiView tab with an overview of all active channels (See chapter 4.1, "R&S MultiView" , on page 100).
	SINGLE Displays the measurement channel that was previously focused.
	*RST: SING

Example: DISP:FORM SPL

DISPlay[:WINDow<n>]:SIZE <Size>

This command maximizes the size of the selected result display window *temporarily*. To change the size of several windows on the screen permanently, use the [LAYout:SPLitter](#) command (see [LAYout:SPLitter](#) on page 735).

Parameters:

<Size>	LARGE Maximizes the selected window to full screen. Other windows are still active in the background.
	SMALI Reduces the size of the selected window to its original size. If more than one measurement window was displayed originally, these are visible again.
	*RST: SMALI

Example: DISP:WIND2:LARG

11.6.2 Working with Windows in the Display

The following commands are required to change the evaluation type and rearrange the screen layout for a measurement channel as you do using the SmartGrid in manual operation. Since the available evaluation types depend on the selected application, some parameters for the following commands also depend on the selected measurement channel.

Note that the suffix <n> always refers to the window *in the currently selected measurement channel* (see [INSTrument\[:SElect\]](#) on page 597).

LAYout:ADD[:WINDow]?	733
LAYout:CATalog[:WINDow]?	734
LAYout:IDENtify[:WINDow]?	734
LAYout:REMove[:WINDow]	735
LAYout:REPLace[:WINDow]	735
LAYout:SPLitter	735
LAYout:WINDow<n>:ADD?	737
LAYout:WINDow<n>:IDENtify?	737
LAYout:WINDow<n>:REMove	738
LAYout:WINDow<n>:REPLace	738

LAYout:ADD[:WINDow]? <WindowName>,<Direction>,<WindowType>

This command adds a window to the display in the active measurement channel.

This command is always used as a query so that you immediately obtain the name of the new window as a result.

To replace an existing window, use the [LAYout:REPLace\[:WINDow\]](#) command.

Parameters:

<WindowName>	String containing the name of the existing window the new window is inserted next to. By default, the name of a window is the same as its index. To determine the name and index of all active windows, use the LAYout:CATalog[:WINDow]? query.
<Direction>	LEFT RIGHT ABOVE BELOW Direction the new window is added relative to the existing window.
<WindowType>	text value Type of result display (evaluation method) you want to add. See the table below for available parameter values.

Return values:

<NewWindowName>	When adding a new window, the command returns its name (by default the same as its number) as a result.
-----------------	---

- Example:** `LAY:ADD? '1',LEFT,MTAB`
Result:
`'2'`
 Adds a new window named '2' with a marker table to the left of window 1.
- Usage:** Query only
- Manual operation:** See "Diagram" on page 386
 See "Marker Table" on page 386
 See "Marker Peak List" on page 386
 See "Result Summary" on page 387
 See "Spectrogram" on page 387

Table 11-2: <WindowType> parameter values for the Spectrum application

Parameter value	Window type
DIAGram	Diagram
MTABle	Marker table
PEAKlist	Marker peak list
RSUMmary	Result summary
SGRam	Spectrogram

LAYout:CATalog[:WINDow]?

This command queries the name and index of all active windows in the active measurement channel from top left to bottom right. The result is a comma-separated list of values for each window, with the syntax:

<WindowName_1>,<WindowIndex_1>..<WindowName_n>,<WindowIndex_n>

Return values:

- <WindowName> **string**
 Name of the window.
 In the default state, the name of the window is its index.
- <WindowIndex> **numeric value**
 Index of the window.

- Example:** `LAY:CAT?`
Result:
`'2',2,'1',1`
 Two windows are displayed, named '2' (at the top or left), and '1' (at the bottom or right).

- Usage:** Query only

LAYout:IDENTify[:WINDow]? <WindowName>

This command queries the **index** of a particular display window in the active measurement channel.

Note: to query the **name** of a particular window, use the `LAYout:WINDow<n>:IDENTify?` query.

Query parameters:

<WindowName> String containing the name of a window.

Return values:

<WindowIndex> Index number of the window.

Usage: Query only

LAYout:REMOve[:WINDow] <WindowName>

This command removes a window from the display in the active measurement channel.

Parameters:

<WindowName> String containing the name of the window.
In the default state, the name of the window is its index.

Usage: Event

LAYout:REPLace[:WINDow] <WindowName>,<WindowType>

This command replaces the window type (for example from "Diagram" to "Result Summary") of an already existing window in the active measurement channel while keeping its position, index and window name.

To add a new window, use the `LAYout:ADD[:WINDow]?` command.

Parameters:

<WindowName> String containing the name of the existing window.
By default, the name of a window is the same as its index. To determine the name and index of all active windows in the active measurement channel, use the `LAYout:CATalog[:WINDow]?` query.

<WindowType> Type of result display you want to use in the existing window.
See `LAYout:ADD[:WINDow]?` on page 733 for a list of available window types.

Example: `LAY:REPL:WIND '1',MTAB`
Replaces the result display in window 1 with a marker table.

LAYout:SPLitter <Index1>,<Index2>,<Position>

This command changes the position of a splitter and thus controls the size of the windows on each side of the splitter.

Compared to the `DISPlay[:WINDow<n>]:SIZE` on page 732 command, the `LAYout:SPLitter` changes the size of all windows to either side of the splitter permanently, it does not just maximize a single window temporarily.

Note that windows must have a certain minimum size. If the position you define conflicts with the minimum size of any of the affected windows, the command will not work, but does not return an error.

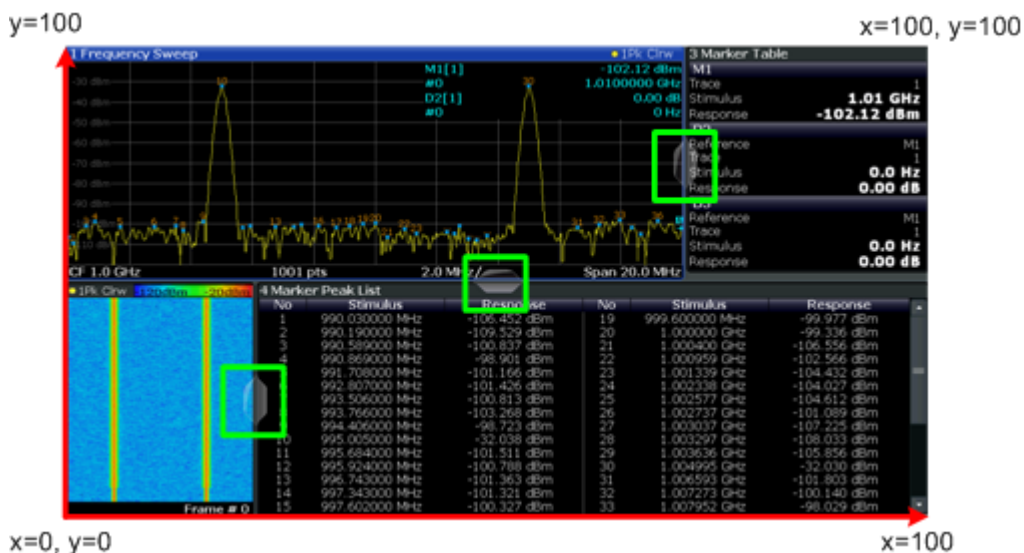


Fig. 11-1: SmartGrid coordinates for remote control of the splitters

Parameters:

- <Index1> The index of one window the splitter controls.
- <Index2> The index of a window on the other side of the splitter.
- <Position> New vertical or horizontal position of the splitter as a fraction of the screen area (without channel and status bar and softkey menu).
The point of origin ($x = 0$, $y = 0$) is in the lower left corner of the screen. The end point ($x = 100$, $y = 100$) is in the upper right corner of the screen. (See figure 11-1.)
The direction in which the splitter is moved depends on the screen layout. If the windows are positioned horizontally, the splitter also moves horizontally. If the windows are positioned vertically, the splitter also moves vertically.
- Range: 0 to 100

Example:

LAY:SPL 1,3,50

Moves the splitter between window 1 ('Frequency Sweep') and 3 ('Marker Table') to the center (50%) of the screen, i.e. in the figure above, to the left.

Example: `LAY:SPL 1,4,70`
 Moves the splitter between window 1 ('Frequency Sweep') and 3 ('Marker Peak List') towards the top (70%) of the screen. The following commands have the exact same effect, as any combination of windows above and below the splitter moves the splitter vertically.

`LAY:SPL 3,2,70`
`LAY:SPL 4,1,70`
`LAY:SPL 2,1,70`

LAYout:WINDow<n>:ADD? <Direction>,<WindowType>

This command adds a measurement window to the display. Note that with this command, the suffix <n> determines the existing window next to which the new window is added, as opposed to `LAYout:ADD[:WINDow]?`, for which the existing window is defined by a parameter.

To replace an existing window, use the `LAYout:WINDow<n>:REPLace` command.

This command is always used as a query so that you immediately obtain the name of the new window as a result.

Parameters:

<Direction> LEFT | RIGHT | ABOVE | BELOW
 <WindowType> Type of measurement window you want to add.
 See `LAYout:ADD[:WINDow]?` on page 733 for a list of available window types.

Return values:

<NewWindowName> When adding a new window, the command returns its name (by default the same as its number) as a result.

Example: `LAY:WIND1:ADD? LEFT,MTAB`
 Result:
 '2'
 Adds a new window named '2' with a marker table to the left of window 1.

Usage: Query only

LAYout:WINDow<n>:IDENTify?

This command queries the **name** of a particular display window (indicated by the <n> suffix) in the active measurement channel.

Note: to query the **index** of a particular window, use the `LAYout:IDENTify[:WINDow]?` command.

Return values:

<WindowName> String containing the name of a window.
 In the default state, the name of the window is its index.

Usage: Query only

LAYout:WINDow<n>:REMOve

This command removes the window specified by the suffix <n> from the display in the active measurement channel.

The result of this command is identical to the `LAYout:REMOve[:WINDow]` command.

Usage: Event

LAYout:WINDow<n>:REPLace <WindowType>

This command changes the window type of an existing window (specified by the suffix <n>) in the active measurement channel.

The result of this command is identical to the `LAYout:REPLace[:WINDow]` command.

To add a new window, use the `LAYout:WINDow<n>:ADD?` command.

Parameters:

<WindowType> Type of measurement window you want to replace another one with.
See `LAYout:ADD[:WINDow]?` on page 733 for a list of available window types.

11.6.3 Examples: Configuring the Result Display

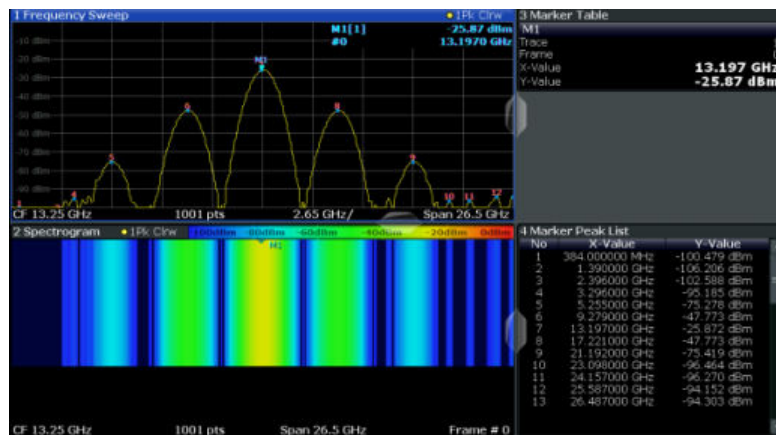
The following example demonstrates how to configure result displays in a remote environment.

11.6.3.1 Example 1: Adding and Arranging Windows

Starting from the default initial display in the Spectrum application (Frequency Sweep), we will configure the following result displays:

1 Frequency Sweep	3 Marker Table
2 Spectrogram	4 Marker Peak List

Configuring the Result Display



```
//-----Resetting the instrument -----
*RST
//----- Adding new windows -----
//Add a Spectrogram window beneath the Frequency Sweep window
LAY:ADD? '1',BEL,SGR
//Result: window number: '2'
//Add a Marker Table window to the right of the Frequency Sweep window
LAY:ADD? '1',RIGH,MTAB
//Result: window number: '3'
//Add a Marker Peak List window to the right of the Spectrogram window
LAY:WIND2:ADD? RIGH,PEAK
//Result: window number: '4'

//----- Changing the size of individual windows -----
//Move the splitter between the Frequency Sweep window and the Marker Table
//window to enlarge the spectrum display to 60% of the entire width.
LAY:SPL 1,3,60
//Move the splitter between the Spectrogram window and the Marker Peak List
//window to enlarge the Spectrogram display to 60% of the entire width.
LAY:SPL 2,4,60

//----- Querying all displayed windows -----
//Query the name and number of all displayed windows
//(from top left to bottom right)
LAY:CAT?
//Result : '1',1,'2',2,'3',3,'4',4

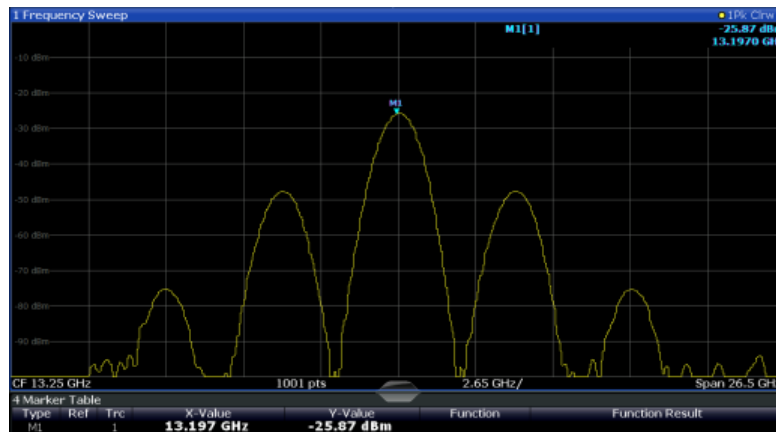
//----- Maximizing a Window -----
//Maximize the window "2 Spectrogram"
DISP:WIND2:SIZE LARG

//-----Restore multiple window display -----
DISP:WIND2:SIZE SMAL
```

11.6.3.2 Example 2: Replacing and Removing Windows

Starting from the display configured in [Example 1: Adding and Arranging Windows](#), we will remove and replace result displays to obtain the following configuration:

1 Frequency Sweep
4 Marker Table



```
//----- Preparing the configuration from example 1 -----
*RST
LAY:ADD? '1',BEL,SGR
LAY:ADD? '1',RIGH,MTAB
LAY:WIND2:ADD? RIGH,PEAK
LAY:CAT?
//Result : '1',1,'2',2,'3',3,'4',4
//Remove Spectrogram
LAY:WIND2:REM //Remove Marker Table window
LAY:REM '3'
//Replace Marker Peak List window by Marker Table
LAY:REPL '4',MTAB

//----- Querying all displayed windows -----
//Query the name and number of all displayed windows (from top left to bottom right)
LAY:CAT?
//Result : '1',1,'4',4

//----- Changing the size of individual windows -----
//Move the splitter between the Frequency Sweep window and the Marker Table window
//to enlarge the spectrum display to 80% of the entire height.
LAY:SPL 1,4,80
```

11.7 Setting Basic Measurement Parameters

All commands that set measurement-independent parameters are described here.

- [Defining the Frequency and Span](#).....741
- [Configuring Bandwidth and Sweep Settings](#).....747
- [Configuring the Vertical Axis \(Amplitude, Scaling\)](#).....754
- [Configuring Triggered and Gated Measurements](#).....760
- [Adjusting Settings Automatically](#).....769
- [Configuring the Data Input and Output](#).....773

11.7.1 Defining the Frequency and Span

The commands required to configure the frequency and span settings in a remote environment are described here. The tasks for manual operation are described in [chapter 6.3, "Frequency and Span Configuration"](#), on page 333.

- [Defining the Frequency Range](#).....741
- [Configuring Signal Tracking](#).....745

11.7.1.1 Defining the Frequency Range

CALCulate<n>:MARKer<m>:FUNCTION:CENTer	741
CALCulate<n>:MARKer<m>:FUNCTION:CSTep	742
DISPlay[:WINDow<n>]:TRACe:X:SPACing	742
[SENSe:]FREQUency:CENTer	742
[SENSe:]FREQUency:CENTer:STEP	742
[SENSe:]FREQUency:CENTer:STEP:AUTO	743
[SENSe:]FREQUency:CENTer:STEP:LINK	743
[SENSe:]FREQUency:CENTer:STEP:LINK:FACTor	744
[SENSe:]FREQUency:OFFSet	744
[SENSe:]FREQUency:SPAN	744
[SENSe:]FREQUency:SPAN:FULL	745
[SENSe:]FREQUency:START	745
[SENSe:]FREQUency:STOP	745

CALCulate<n>:MARKer<m>:FUNCTION:CENTer

This command matches the center frequency to the frequency of a marker.

If you use the command in combination with a delta marker, that delta marker is turned into a normal marker.

Example: `CALC:MARK2:FUNC:CENT`
Sets the center frequency to the frequency of marker 2.

Usage: Event

Manual operation: See ["Harmonic Distortion"](#) on page 115
See ["Center Frequency = Marker Frequency"](#) on page 449

CALCulate<n>:MARKer<m>:FUNction:CSTep

This command matches the center frequency step size to the current marker frequency.

The command turns delta markers into normal markers.

Usage: Event

DISPlay[:WINDow<n>]:TRACe:X:SPACing <ScalingType>

This command selects the scaling of the x-axis.

Parameters:

<ScalingType> **LOGarithmic**
Logarithmic scaling.

LINear
Linear scaling.

*RST: LINear

Example: DISP:TRAC:X:SPAC LOG

Manual operation: See "[Frequency Axis Scaling](#)" on page 338

[SENSe:]FREQuency:CENTer <Frequency>

This command defines the center frequency.

Parameters:

<Frequency> The allowed range and f_{\max} is specified in the data sheet.

UP
Increases the center frequency by the step defined using the
[\[SENSe:\]FREQuency:CENTer:STEP](#) command.

DOWN
Decreases the center frequency by the step defined using the
[\[SENSe:\]FREQuency:CENTer:STEP](#) command.

*RST: $f_{\max}/2$
Default unit: Hz

Example: `FREQ:CENT 100 MHz`
 `FREQ:CENT:STEP 10 MHz`
 `FREQ:CENT UP`
 Sets the center frequency to 110 MHz.

Usage: SCPI confirmed

Manual operation: See "[Center frequency](#)" on page 337
See "[Frequency](#)" on page 374

[SENSe:]FREQuency:CENTer:STEP <StepSize>

This command defines the center frequency step size.

You can increase or decrease the center frequency quickly in fixed steps using the `SENS:FREQ UP` AND `SENS:FREQ DOWN` commands, see [\[SENSe:\]FREQuency:CENTer](#) on page 742.

Parameters:

<StepSize> f_{\max} is specified in the data sheet.
 Range: 1 to fMAX
 *RST: 0.1 x span
 Default unit: Hz

Example:

```
FREQ:CENT 100 MHz
FREQ:CENT:STEP 10 MHz
FREQ:CENT UP
Sets the center frequency to 110 MHz.
```

Manual operation: See ["Center Frequency Stepsize"](#) on page 339

[SENSe:]FREQuency:CENTer:STEP:AUTO <State>

This command couples or decouples the center frequency step size to the span.

In time domain (zero span) measurements, the center frequency is coupled to the RBW.

Parameters:

<State> ON | OFF | 0 | 1
 *RST: 1

Example:

```
FREQ:CENT:STEP:AUTO ON
Activates the coupling of the step size to the span.
```

[SENSe:]FREQuency:CENTer:STEP:LINK <CouplingType>

This command couples and decouples the center frequency step size to the span or the resolution bandwidth.

Parameters:

<CouplingType> **SPAN**
 Couples the step size to the span. Available for measurements in the frequency domain.
RBW
 Couples the step size to the resolution bandwidth. Available for measurements in the time domain.
OFF
 Decouples the step size.
 *RST: SPAN

Example:

```
FREQ:CENT:STEP:LINK SPAN
```

Manual operation: See ["Center Frequency Stepsize"](#) on page 339

[SENSe:]FREQUENCY:CENTer:STEP:LINK:FACTOR <Factor>

This command defines a step size factor if the center frequency step size is coupled to the span or the resolution bandwidth.

Parameters:

<Factor> 1 to 100 PCT
 *RST: 10

Example: `FREQ:CENT:STEP:LINK:FACT 20PCT`

Manual operation: See "[Center Frequency Stepsize](#)" on page 339

[SENSe:]FREQUENCY:OFFSet <Offset>

This command defines a frequency offset.

If this value is not 0 Hz, the application assumes that the input signal was frequency shifted outside the application. All results of type "frequency" will be corrected for this shift numerically by the application.

See also "[Frequency Offset](#)" on page 339.

Note: In MSRA mode, the setting command is only available for the MSRA Master. For MSRA applications, only the query command is available.

Parameters:

<Offset> Range: -100 GHz to 100 GHz
 *RST: 0 Hz

Example: `FREQ:OFFS 1GHZ`

Usage: SCPI confirmed

Manual operation: See "[Frequency Offset](#)" on page 339

**[SENSe:]FREQUENCY:SPAN **

This command defines the frequency span.

If you set a span of 0 Hz in the Spectrum application, the R&S FPS starts a measurement in the time domain.

Parameters:

 The minimum span for measurements in the frequency domain is 10 Hz. For SEM and spurious emission measurements, the minimum span is 20 Hz.

Range: 0 Hz to fmax
 *RST: Full span

Usage: SCPI confirmed

Manual operation: See ["Zero Span"](#) on page 112
 See ["Span"](#) on page 337
 See ["Zero Span"](#) on page 338
 See ["Last Span"](#) on page 339

[SENSe:]FREQuency:SPAN:FULL

This command restores the full span.

Usage: Event
 SCPI confirmed

Manual operation: See ["Full Span"](#) on page 338

[SENSe:]FREQuency:STARt <Frequency>

This command defines a start frequency for measurements in the frequency domain.

Parameters:
 <Frequency> 0 to (fmax - min span)
 *RST: 0

Example: `FREQ:STAR 20MHz`

Usage: SCPI confirmed

Manual operation: See ["Frequency Sweep"](#) on page 112
 See ["Start / Stop"](#) on page 338

[SENSe:]FREQuency:STOP <Frequency>

This command defines a stop frequency for measurements in the frequency domain.

Parameters:
 <Frequency> min span to fmax
 *RST: fmax

Example: `FREQ:STOP 2000 MHz`

Usage: SCPI confirmed

Manual operation: See ["Frequency Sweep"](#) on page 112
 See ["Start / Stop"](#) on page 338

11.7.1.2 Configuring Signal Tracking

When signal tracking is activated, the maximum signal is determined after each frequency sweep and the center frequency is set to the frequency of this signal. Thus with drifting signals the center frequency follows the signal.

For more details see [chapter 6.3.1, "Impact of the Frequency and Span Settings"](#), on page 333..

CALCulate<n>:MARKer<m>:FUNctioN:STRack[:STATe].....	746
CALCulate<n>:MARKer<m>:FUNctioN:STRack:BANDwidth.....	746
CALCulate<n>:MARKer<m>:FUNctioN:STRack:THReshold.....	746
CALCulate<n>:MARKer<m>:FUNctioN:STRack:TRACe.....	746

CALCulate<n>:MARKer<m>:FUNctioN:STRack[:STATe] <State>

This command turns signal tracking on and off.

(<n>, <m> are irrelevant.)

Parameters:

<State> ON | OFF
 *RST: OFF

Manual operation: See "[Signal Tracking State](#)" on page 340

CALCulate<n>:MARKer<m>:FUNctioN:STRack:BANDwidth <Bandwidth>

This command defines the bandwidth around the center frequency that is included in the signal tracking process.

(<n>, <m> are irrelevant.)

Note that you have to turn on signal tracking before you can use the command.

Parameters:

<Bandwidth> Range: 10 Hz to Max span
 *RST: (= span/10 on activating the function)
 Default unit: Hz

Manual operation: See "[Tracking Bandwidth](#)" on page 340

CALCulate<n>:MARKer<m>:FUNctioN:STRack:THReshold <Level>

This command defines the threshold level for the signal tracking process.

(<n>, <m> are irrelevant.)

Note that you have to turn on signal tracking before you can use the command.

Parameters:

<Level> The unit depends on [CALCulate<n>:UNIT:POWER](#).
 Range: -130 dBm to 30 dBm
 *RST: -120 dBm

Manual operation: See "[Tracking Threshold](#)" on page 340

CALCulate<n>:MARKer<m>:FUNctioN:STRack:TRACe <TraceNumber>

This command selects the trace on which the largest signal is searched for.

(<n>, <m> are irrelevant.)

Parameters:

<TraceNumber> 1 to 6
 Range: 1 to 6
 *RST: 1

Manual operation: See "Signal Track Trace" on page 340

11.7.2 Configuring Bandwidth and Sweep Settings

The commands required to configure the bandwidth, sweep and filter settings in a remote environment are described here. The tasks for manual operation are described in [chapter 6.5, "Bandwidth, Filter and Sweep Configuration"](#), on page 351.

- [Configuring the Bandwidth and Filter](#).....747
- [Configuring the Sweep](#).....750

11.7.2.1 Configuring the Bandwidth and Filter

[SENSe:]BWIDth[:RESolution]	747
[SENSe:]BANDwidth[:RESolution]	747
[SENSe:]BWIDth[:RESolution]:AUTO	748
[SENSe:]BANDwidth[:RESolution]:AUTO	748
[SENSe:]BWIDth[:RESolution]:RATio	748
[SENSe:]BANDwidth[:RESolution]:RATio	748
[SENSe:]BWIDth[:RESolution]:TYPE	748
[SENSe:]BANDwidth[:RESolution]:TYPE	748
[SENSe:]BWIDth:VIDeo	749
[SENSe:]BANDwidth:VIDeo	749
[SENSe:]BWIDth:VIDeo:AUTO	749
[SENSe:]BANDwidth:VIDeo:AUTO	749
[SENSe:]BWIDth:VIDeo:RATio	750
[SENSe:]BANDwidth:VIDeo:RATio	750
[SENSe:]BWIDth:VIDeo:TYPE	750
[SENSe:]BANDwidth:VIDeo:TYPE	750

[SENSe:]BWIDth[:RESolution] <Bandwidth>

[SENSe:]BANDwidth[:RESolution] <Bandwidth>

This command defines the resolution bandwidth and decouples the resolution bandwidth from the span.

For statistics measurements, this command defines the **demodulation** bandwidth.

Parameters:

<Bandwidth> refer to data sheet
 *RST: RBW: AUTO is set to ON; DBW: 3MHz

Example:

BAND 1 MHz
 Sets the resolution bandwidth to 1 MHz

Usage:

SCPI confirmed

Manual operation: See "Analysis Bandwidth" on page 258
 See "RBW" on page 359
 See "RBW" on page 374

[SENSe:]BWIDth[:RESolution]:AUTO <State>
[SENSe:]BANDwidth[:RESolution]:AUTO <State>

This command couples and decouples the resolution bandwidth to the span.

Parameters:

<State> ON | OFF | 0 | 1
 *RST: 1

Example: BAND:AUTO OFF
 Switches off the coupling of the resolution bandwidth to the span.

Usage: SCPI confirmed

Manual operation: See "RBW" on page 359
 See "Default Coupling" on page 361

[SENSe:]BWIDth[:RESolution]:RATio <Ratio>
[SENSe:]BANDwidth[:RESolution]:RATio <Ratio>

This command defines the ratio between the resolution bandwidth (Hz) and the span (Hz).

Note that the ratio defined with this remote command (RBW/span) is reciprocal to that of the coupling ratio (span/RBW).

Parameters:

<Ratio> Range: 0.0001 to 1
 *RST: 0.01

Example: BAND:RAT 0.1

Usage: SCPI confirmed

Manual operation: See "Span/RBW" on page 360

[SENSe:]BWIDth[:RESolution]:TYPE <FilterType>
[SENSe:]BANDwidth[:RESolution]:TYPE <FilterType>

This command selects the resolution filter type.

When you change the filter type, the command selects the next larger filter bandwidth if the same bandwidth is unavailable for that filter.

Parameters:

<FilterType>

CFILter

Channel filters

NORMal

Gaussian filters

P5

5-pole filters

The 5-pole filter is not available for FFT sweeps.

RRC

RRC filters

*RST: NORMal

Example:

BAND:TYPE NORM

Manual operation: See "[Filter Type](#)" on page 361**[SENSe:]BWIDth:VIDeo** <Bandwidth>**[SENSe:]BANDwidth:VIDeo** <Bandwidth>

This command defines the video bandwidth.

The command decouples the video bandwidth from the resolution bandwidths.

Parameters:

<Bandwidth>

refer to data sheet

*RST: AUTO is set to ON

Example:

BAND:VID 10 kHz

Usage:

SCPI confirmed

Manual operation: See "[VBW](#)" on page 359**[SENSe:]BWIDth:VIDeo:AUTO** <State>**[SENSe:]BANDwidth:VIDeo:AUTO** <State>

This command couples and decouples the video bandwidth to the resolution bandwidth.

Parameters:

<State>

ON | OFF | 0 | 1

*RST: 1

Example:

BAND:VID:AUTO OFF

Usage:

SCPI confirmed

Manual operation: See "[VBW](#)" on page 359
See "[RBW/VBW](#)" on page 360
See "[Default Coupling](#)" on page 361

```
[SENSe:]BWIDth:VIDeo:RATio <Ratio>
```

```
[SENSe:]BANDwidth:VIDeo:RATio <Ratio>
```

This command defines the coupling ratio of the video bandwidth to the resolution bandwidth (RBW/VBW).

Parameters:

```
<Ratio>          Range:    0,001 to 1000
                  *RST:    1
```

Example:

```
BAND:VID:RAT 3
```

Sets the coupling of video bandwidth to video bandwidth = 3*resolution bandwidth

Usage: SCPI confirmed

Manual operation: See "RBW/VBW " on page 360

```
[SENSe:]BWIDth:VIDeo:TYPE <Mode>
```

```
[SENSe:]BANDwidth:VIDeo:TYPE <Mode>
```

This command selects the position of the video filter in the signal path.

Changing the video filter position is possible only if the resolution bandwidth is ≤ 100 kHz.

Parameters:

```
<Mode>
```

LINEar

The video filter is applied in front of the logarithmic amplifier. In linear mode, measurements with a logarithmic level scale result in flatter falling edges compared to logarithmic mode. The reason is the conversion of linear power values into logarithmic level values: if you halve the linear power, the logarithmic level decreases by 3 dB.

LOGarithmic

The video filter is applied after the logarithmic amplifier

```
*RST:    LOGarithmic
```

Example:

```
BAND:VID:TYPE LIN
```

Video filter ahead of the logarithmic amplifier

11.7.2.2 Configuring the Sweep

Useful commands for configuring sweeps described elsewhere:

- [SENSe:]AVERage<n>:COUNT on page 802
- [SENSe:]AVERage<n>[:STATe<t>] on page 802
- [SENSe:]AVERage<n>:TYPE on page 802

Remote commands exclusive to configuring sweeps:

[SENSe:]SWEep:COUNT.....	751
[SENSe:]SWEep:OPTimize.....	751
[SENSe:]SWEep:POINTS.....	752
[SENSe:]SWEep:TIME.....	753
[SENSe:]SWEep:TIME:AUTO.....	753
[SENSe:]SWEep:TYPE.....	753
[SENSe:]SWEep:TYPE:USED.....	754
[SENSe:]BWIDth[:RESolution]:FFT.....	754
[SENSe:]BANDwidth[:RESolution]:FFT.....	754

[SENSe:]SWEep:COUNT <SweepCount>

This command defines the number of sweep s that the application uses to average traces.

In case of continuous sweep mode, the application calculates the moving average over the average count.

In case of single sweep mode, the application stops the measurement and calculates the average after the average count has been reached.

Parameters:

<SweepCount> When you set a sweep count of 0 or 1, the R&S FPS performs one single sweep in single sweep mode.
In continuous sweep mode, if the sweep count is set to 0, a moving average over 10 sweep s is performed.

Range: 0 to 200000
*RST: 0

Example:

```
SWE:COUN 64
Sets the number of sweep s to 64.
INIT:CONT OFF
Switches to single sweep mode.
INIT;*WAI
Starts a sweep and waits for its end.
```

Usage: SCPI confirmed

Manual operation: See "[Sweep / Average Count](#)" on page 361

[SENSe:]SWEep:OPTimize <Mode>

In FFT mode, several FFT analysis steps are required to cover the entire measurement span. The span which is covered by one FFT analysis step is called *partial span*. The partial span cannot be defined directly, but it can be optimized according to measurement requirements.

Table 11-3: Optimization parameters in FFT mode

Optimization mode	Description
Dynamic	Optimizes the dynamic range by using the narrowest possible partial span (depending on the RBW). The autorange function for the internal IF gain calculation is activated to obtain the best control range for the A/D converter.
Speed	Optimizes the sweep rate by using the widest possible partial span (depending on the RBW). The autorange function for the internal IF gain calculation is deactivated. (Note: set the reference level accordingly to optimize the control range for the A/D converter). It is recommended that you set the sweep time to "Auto" to optimize the sweep rate (see [SENSe:]SWEep:TIME:AUTO on page 753).
Auto	Uses a medium-sized partial span to obtain a compromise between a large dynamic range and a fast sweep rate. The autorange function for the internal IF gain calculation is activated to obtain the best control range for the A/D converter.

Zero span mode

For zero span measurements, the optimization mode defines the selection of the A/D converter prefilter.

Table 11-4: Optimization parameters in zero span mode

Optimization mode	Description
Dynamic	The narrowest filter possible (depending on the RBW) is used.
Speed	The widest filter possible (depending on the RBW) is used.
Auto	A medium-sized prefilter is used.

Parameters:

<Mode> *RST: AUTO

Example:

SWE:OPT DYN

Selects optimization for dynamic range.

Manual operation: See "[Optimization](#)" on page 362

[SENSe:]SWEep:POINTs <SweepPoints>

This command defines the number of sweep points to analyze after a sweep .

Note that the number of sweep points is limited to 10001 when measuring spurious emissions.

Parameters:

<SweepPoints> Range: 101 to 32001
*RST: 1001

Example:

SWE:POIN 251

Usage:

SCPI confirmed

Manual operation: See ["Sweep Points"](#) on page 361

[SENSe:]SWEep:TIME <Time>

This command defines the sweep (or: data capture) time.

Parameters:

<Time> refer to data sheet
 *RST: depends on current settings (determined automatically)

Example: SWE:TIME 10s

Usage: SCPI confirmed

Manual operation: See ["Sweep Time"](#) on page 157
 See ["Sweep Time"](#) on page 359
 See ["Sweep Time"](#) on page 374

[SENSe:]SWEep:TIME:AUTO <State>

This command couples and decouples the sweep time to the span and the resolution and video bandwidths.

Parameters:

<State> ON | OFF | 0 | 1
 *RST: 1

Example: SWE:TIME:AUTO ON
 Activates automatic sweep time.

Usage: SCPI confirmed

Manual operation: See ["Harmonic Sweep Time"](#) on page 276
 See ["Sweep Time"](#) on page 359
 See ["Default Coupling"](#) on page 361

[SENSe:]SWEep:TYPE <Type>

This command selects the sweep type.

Parameters:

<Type> **AUTO**
 Automatic selection of the sweep type between sweep mode and FFT.
FFT
 FFT mode
 *RST: AUTO

Example: SWE:TYPE FFT

Manual operation: See ["Sweep Type"](#) on page 362

[SENSe:]SWEep:TYPE:USED

This command queries the sweep type if you have turned on automatic selection of the sweep type.

Return values:

<Type>	SWE Normal sweep
	FFT FFT mode

[SENSe:]BWIDth[:RESolution]:FFT <FilterMode>**[SENSe:]BANDwidth[:RESolution]:FFT <FilterMode>**

Defines the filter mode to be used for FFT filters by defining the partial span size. The partial span is the span which is covered by one FFT analysis.

This command is only available when using the sweep type "FFT".

Note: this command is maintained for compatibility reasons only. For new remote control programs, use the `[SENSe:]SWEep:OPTimize` command.

Parameters:

<FilterMode>	WIDE AUTO NARRow
	AUTO Automatically applies the sweep optimization mode that is best for the current measurement.
	NARRow Optimizes the sweep mode for a large dynamic range.
	WIDE Optimizes the sweep mode for high performance.
	*RST: AUTO

Example: BAND:TYPE FFT
Select FFT filter.

Example: BAND:FFT NARR
Select narrow partial span for FFT filter.

11.7.3 Configuring the Vertical Axis (Amplitude, Scaling)

The following commands are required to configure the amplitude and vertical axis settings in a remote environment.

- [Amplitude Settings](#)..... 755
- [Configuring the Attenuation](#)..... 756
- [Configuring a Preamplifier](#)..... 758
- [Scaling the Y-Axis](#)..... 759

11.7.3.1 Amplitude Settings

The tasks for manual configuration are described in [chapter 6.4.2, "Amplitude Settings"](#), on page 345.

Useful commands for amplitude configuration described elsewhere:

- [\[SENSe:\]ADJust:LEVel](#) on page 772

Remote commands exclusive to amplitude configuration:

CALCulate<n>:MARKer<m>:FUNction:REFerence	755
CALCulate<n>:UNIT:POWer	755
DISPlay[:WINDow<n>]:TRACe<t>:Y[:SCALe]:RLEVel	755
DISPlay[:WINDow<n>]:TRACe<t>:Y[:SCALe]:RLEVel:OFFSet	756
[SENSe:]POWer:NCORrection	756

CALCulate<n>:MARKer<m>:FUNction:REFerence

This command matches the reference level to the power level of a marker.

If you use the command in combination with a delta marker, that delta marker is turned into a normal marker.

Example: `CALC:MARK2:FUNC:REF`
Sets the reference level to the level of marker 2.

Usage: Event

Manual operation: See "[Reference Level = Marker Level](#)" on page 450

CALCulate<n>:UNIT:POWer <Unit>

This command selects the unit of the y-axis.

The unit applies to all measurement windows.

Parameters:

<Unit> DBM | V | A | W | DBPW | WATT | DBUV | DBMV | VOLT |
DBUA | AMPere
*RST: dBm

Example: `CALC:UNIT:POW DBM`
Sets the power unit to dBm.

Manual operation: See "[Unit](#)" on page 346

DISPlay[:WINDow<n>]:TRACe<t>:Y[:SCALe]:RLEVel <ReferenceLevel>

This command defines the reference level (for all traces, <t> is irrelevant).

With a reference level offset ≠ 0, the value range of the reference level is modified by the offset.

Parameters:

<ReferenceLevel> The unit is variable.
 Range: see datasheet
 *RST: 0 dBm

Example: DISP:TRAC:Y:RLEV -60dBm

Usage: SCPI confirmed

Manual operation: See ["Reference Level"](#) on page 345

DISPlay[:WINDow<n>]:TRACe<t>:Y[:SCALE]:RLEVel:OFFSet <Offset>

This command defines a reference level offset (for all traces, <t> is irrelevant).

Parameters:

<Offset> Range: -200 dB to 200 dB
 *RST: 0dB

Example: DISP:TRAC:Y:RLEV:OFFS -10dB

Manual operation: See ["Shifting the Display \(Offset\)"](#) on page 262

See ["Shifting the Display \(Offset\)"](#) on page 346

[SENSe:]POWer:NCORrection <State>

This command turns noise cancellation on and off.

If noise cancellation is on, the R&S FPS performs a reference measurement to determine its inherent noise and subtracts the result from the channel power measurement result (first active trace only).

For more information see ["Noise cancellation"](#) on page 155.

Parameters:

<State> ON | OFF
 *RST: OFF

Example: POW:NCOR ON

Manual operation: See ["Noise cancellation"](#) on page 155

11.7.3.2 Configuring the Attenuation

INPut:ATTenuation.....	756
INPut:ATTenuation:AUTO.....	757
INPut:EATT.....	757
INPut:EATT:AUTO.....	758
INPut:EATT:STATe.....	758

INPut:ATTenuation <Attenuation>

This command defines the total attenuation for RF input.

If an electronic attenuator is available and active, the command defines a mechanical attenuation (see `INPut:EATT:STATE` on page 758).

If you set the attenuation manually, it is no longer coupled to the reference level, but the reference level is coupled to the attenuation. Thus, if the current reference level is not compatible with an attenuation that has been set manually, the command also adjusts the reference level.

Parameters:

<Attenuation> Range: see data sheet
 Increment: 5 dB
 *RST: 10 dB (AUTO is set to ON)

Example:

`INP:ATT 30dB`
 Defines a 30 dB attenuation and decouples the attenuation from the reference level.

Usage: SCPI confirmed

Manual operation: See "[Attenuation Mode / Value](#)" on page 347

INPut:ATTenuation:AUTO <State>

This command couples or decouples the attenuation to the reference level. Thus, when the reference level is changed, the R&S FPS determines the signal level for optimal internal data processing and sets the required attenuation accordingly.

Parameters:

<State> ON | OFF | 0 | 1
 *RST: 1

Example:

`INP:ATT:AUTO ON`
 Couples the attenuation to the reference level.

Usage: SCPI confirmed

Manual operation: See "[Attenuation Mode / Value](#)" on page 347

INPut:EATT <Attenuation>

This command defines an electronic attenuation manually. Automatic mode must be switched off (`INP:EATT:AUTO OFF`, see `INPut:EATT:AUTO` on page 758).

If the current reference level is not compatible with an attenuation that has been set manually, the command also adjusts the reference level.

Parameters:

<Attenuation> attenuation in dB
 Range: see data sheet
 Increment: 1 dB
 *RST: 0 dB (OFF)

Example:

`INP:EATT:AUTO OFF`
`INP:EATT 10 dB`

Manual operation: See ["Using Electronic Attenuation"](#) on page 347

INPut:EATT:AUTO <State>

This command turns automatic selection of the electronic attenuation on and off.

If on, electronic attenuation reduces the mechanical attenuation whenever possible.

Parameters:

<State> ON | OFF | 0 | 1
 *RST: 1

Example: INP:EATT:AUTO OFF

Manual operation: See ["Using Electronic Attenuation"](#) on page 347

INPut:EATT:STATe <State>

This command turns the electronic attenuator on and off.

Parameters:

<State> ON | OFF
 *RST: OFF

Example: INP:EATT:STAT ON
 Switches the electronic attenuator into the signal path.

Manual operation: See ["Using Electronic Attenuation"](#) on page 347

11.7.3.3 **Configuring a Preamp**

[INPut:GAIN:STATe](#)..... 758

INPut:GAIN:STATe <State>

This command turns the preamplifier on and off.

If activated, the input signal is amplified by 20 dB.

If option R&S FPS-B22 is installed, the preamplifier is only active below 7 GHz.

If option R&S FPS-B24 is installed, the preamplifier is active for all frequencies.

Parameters:

<State> ON | OFF
 *RST: OFF

Example: INP:GAIN:STAT ON
 Switches on 20 dB preamplification.

Usage: SCPI confirmed

Manual operation: See ["Preamp \(option B22/B24\)"](#) on page 348

11.7.3.4 Scaling the Y-Axis

DISPlay[:WINDow<n>]:TRACe<t>:Y[:SCALe].....	759
DISPlay[:WINDow<n>]:TRACe<t>:Y[:SCALe]:AUTO ONCE.....	759
DISPlay[:WINDow<n>]:TRACe<t>:Y[:SCALe]:MODE.....	759
DISPlay[:WINDow<n>]:TRACe<t>:Y[:SCALe]:RPOSition.....	760
DISPlay[:WINDow<n>]:TRACe<t>:Y:SPACing.....	760

DISPlay[:WINDow<n>]:TRACe<t>:Y[:SCALe] <Range>

This command defines the display range of the y-axis (for all traces, <t> is irrelevant).

Note that the command works only for a logarithmic scaling. You can select the scaling with `DISPlay[:WINDow<n>]:TRACe<t>:Y:SPACing`.

Parameters:

<Range> Range: 1 dB to 200 dB
 *RST: 100 dB

Example: DISP:TRAC:Y 110dB

Usage: SCPI confirmed

Manual operation: See "[Range](#)" on page 349

DISPlay[:WINDow<n>]:TRACe<t>:Y[:SCALe]:AUTO ONCE

Automatic scaling of the y-axis is performed once, then switched off again (for all traces, <t> is irrelevant).

Usage: SCPI confirmed

Manual operation: See "[Auto Scale Once](#)" on page 350

DISPlay[:WINDow<n>]:TRACe<t>:Y[:SCALe]:MODE <Mode>

This command selects the type of scaling of the y-axis (for all traces, <t> is irrelevant).

When the display update during remote control is off, this command has no immediate effect.

Parameters:

<Mode> **ABSolute**
 absolute scaling of the y-axis
 RELative
 relative scaling of the y-axis
 *RST: ABSolute

Example: DISP:TRAC:Y:MODE REL

Manual operation: See "[Scaling](#)" on page 350

DISPlay[:WINDow<n>]:TRACe<t>:Y[:SCALe]:RPOSition <Position>

This command defines the vertical position of the reference level on the display grid (for all traces, <t> is irrelevant).

The R&S FPS adjusts the scaling of the y-axis accordingly.

For measurements with the optional external generator control, the command defines the position of the reference value.

Parameters:

<Position> 0 PCT corresponds to the lower display border, 100% corresponds to the upper display border.
 *RST: 100 PCT = frequency display; 50 PCT = time display

Example: DISP:TRAC:Y:RPOS 50PCT

Usage: SCPI confirmed

Manual operation: See ["Reference Position"](#) on page 322
 See ["Ref Level Position"](#) on page 350

DISPlay[:WINDow<n>]:TRACe<t>:Y:SPACing <ScalingType>

This command selects the scaling of the y-axis (for all traces, <t> is irrelevant).

Parameters:

<ScalingType> **LOGarithmic**
 Logarithmic scaling.
 LINear
 Linear scaling in %.
 LDB
 Linear scaling in the specified unit.
 PERCent
 Linear scaling in %.
 *RST: LOGarithmic

Example: DISP:TRAC:Y:SPAC LIN
 Selects linear scaling in %.

Usage: SCPI confirmed

Manual operation: See ["Scaling"](#) on page 350

11.7.4 Configuring Triggered and Gated Measurements

The commands required to configure a triggered or gated measurement in a remote environment are described here. The tasks for manual operation are described in [chapter 6.6, "Trigger and Gate Configuration"](#), on page 366.



*OPC should be used after requesting data. This will hold off any subsequent changes to the selected trigger source, until after the sweep is completed and the data is returned.

- [Configuring the Triggering Conditions](#).....761
- [Configuring Gated Measurements](#).....765
- [Configuring the Trigger Output](#).....768

11.7.4.1 Configuring the Triggering Conditions

TRIGger[:SEquence]:DTIME.....	761
TRIGger[:SEquence]:HOLDoff[:TIME].....	761
TRIGger[:SEquence]:IFPower:HOLDoff.....	762
TRIGger[:SEquence]:IFPower:HYSteresis.....	762
TRIGger[:SEquence]:LEVel[:EXternal<port>].....	762
TRIGger[:SEquence]:LEVel:IFPower.....	763
TRIGger[:SEquence]:LEVel:IQPower.....	763
TRIGger[:SEquence]:LEVel:RFPower.....	763
TRIGger[:SEquence]:LEVel:VIDeo.....	764
TRIGger[:SEquence]:SLOpe.....	764
TRIGger[:SEquence]:SOURce.....	764

TRIGger[:SEquence]:DTIME <DropoutTime>

Defines the time the input signal must stay below the trigger level before a trigger is detected again.

Parameters:

<DropoutTime> Dropout time of the trigger.
 Range: 0 s to 10.0 s
 *RST: 0 s

Manual operation: See "[Drop-Out Time](#)" on page 376

TRIGger[:SEquence]:HOLDoff[:TIME] <Offset>

Defines the time offset between the trigger event and the start of the sweep .

A negative offset is possible for time domain measurements.

For the trigger sources "External" or "IF Power", a common input signal is used for both trigger and gate. Therefore, changes to the gate delay will affect the trigger offset as well.

Parameters:

<Offset> For measurements in the frequency domain, the range is 0 s to 30 s.
 For measurements in the time domain, the range is the negative sweep time to 30 s.
 *RST: 0 s

Example: TRIG:HOLD 500us

Manual operation: See "[Trigger Offset](#)" on page 377

TRIGger[:SEquence]:IFPower:HOLDoff <Period>

This command defines the holding time before the next trigger event.

Note that this command can be used for **any trigger source**, not just IF Power (despite the legacy keyword).

Note: If you perform gated measurements in combination with the IF Power trigger, the R&S FPS ignores the holding time for frequency sweep, FFT sweep, zero span and I/Q data measurements.

Parameters:

<Period> Range: 0 s to 10 s
 *RST: 0 s

Example: TRIG:SOUR EXT
 Sets an external trigger source.
 TRIG:IFP:HOLD 200 ns
 Sets the holding time to 200 ns.

Manual operation: See "[Trigger Holdoff](#)" on page 377

TRIGger[:SEquence]:IFPower:HYSteresis <Hysteresis>

This command defines the trigger hysteresis, which is only available for "IF Power" trigger sources.

Parameters:

<Hysteresis> Range: 3 dB to 50 dB
 *RST: 3 dB

Example: TRIG:SOUR IFP
 Sets the IF power trigger source.
 TRIG:IFP:HYST 10DB
 Sets the hysteresis limit value.

Manual operation: See "[Hysteresis](#)" on page 377

TRIGger[:SEquence]:LEVel[:EXternal<port>] <TriggerLevel>

This command defines the level the external signal must exceed to cause a trigger event.

Note that the variable INPUT/OUTPUT connectors (ports 2+3) must be set for use as input using the [OUTPut:TRIGger<port>:DIRection](#) command.

Suffix:

<port> Selects the trigger port.
 1 = trigger port 1 (TRIG IN connector on rear panel)
 2 = trigger port 2 (TRIG AUX connector on rear panel)

Parameters:

<TriggerLevel> Range: 0.5 V to 3.5 V
 *RST: 1.4 V

Example: TRIG:LEV 2V

Manual operation: See ["Trigger Level"](#) on page 376

TRIGger[:SEQuence]:LEVel:IFPower <TriggerLevel>

This command defines the power level at the third intermediate frequency that must be exceeded to cause a trigger event. Note that any RF attenuation or preamplification is considered when the trigger level is analyzed. If defined, a reference level offset is also considered.

Parameters:

<TriggerLevel> For details on available trigger levels and trigger bandwidths see the data sheet.
 *RST: -10 dBm

Example: TRIG:LEV:IFP -30DBM

Manual operation: See ["Trigger Level"](#) on page 376

TRIGger[:SEQuence]:LEVel:IQPower <TriggerLevel>

This command defines the magnitude the I/Q data must exceed to cause a trigger event. Note that any RF attenuation or preamplification is considered when the trigger level is analyzed.

Parameters:

<TriggerLevel> Range: -130 dBm to 30 dBm
 *RST: -20 dBm

Example: TRIG:LEV:IQP -30DBM

Manual operation: See ["Trigger Level"](#) on page 376

TRIGger[:SEQuence]:LEVel:RFPower <TriggerLevel>

This command defines the power level the RF input must exceed to cause a trigger event. Note that any RF attenuation or preamplification is considered when the trigger level is analyzed. If defined, a reference level offset is also considered.

The input signal must be between 500 MHz and 8 GHz.

Parameters:

<TriggerLevel> For details on available trigger levels and trigger bandwidths see the data sheet.
 *RST: -20 dBm

Example: TRIG:LEV:RFP -30dBm

Manual operation: See ["Trigger Level"](#) on page 376

TRIGger[:SEQUence]:LEVel:VIDeo <Level>

This command defines the level the video signal must exceed to cause a trigger event. Note that any RF attenuation or preamplification is considered when the trigger level is analyzed.

Parameters:

<Level> Range: 0 PCT to 100 PCT
 *RST: 50 PCT

Example: TRIG:LEV:VID 50PCT

Manual operation: See "[Trigger Level](#)" on page 376

TRIGger[:SEQUence]:SLOPe <Type>

For all trigger sources except time you can define whether triggering occurs when the signal rises to the trigger level or falls down to it.

Parameters:

<Type> POSitive | NEGative
 POSitive
 Triggers when the signal rises to the trigger level (rising edge).
 NEGative
 Triggers when the signal drops to the trigger level (falling edge).
 *RST: POSitive

Example: TRIG:SLOP NEG

Manual operation: See "[Slope](#)" on page 377

TRIGger[:SEQUence]:SOURce <Source>

This command selects the trigger source.

For details on trigger sources see "[Trigger Source](#)" on page 374.

Note on external triggers:

If a measurement is configured to wait for an external trigger signal in a remote control program, remote control is blocked until the trigger is received and the program can continue. Make sure this situation is avoided in your remote control programs.

For troubleshooting tips see "[Uncompleted sequential commands - blocked remote channels](#)" on page 990.

Parameters:

<Source>	IMMediate Free Run
	EXTernal Trigger signal from the TRIGGER IN connector.
	EXT2 Trigger signal from the TRIGGER AUX connector.
	RFPower First intermediate frequency
	IFPower Second intermediate frequency
	VIDeo Video mode is available in the time domain and only in the Spectrum application.
	*RST: IMMediate

Example:

TRIG:SOUR EXT
Selects the external trigger input as source of the trigger signal

Manual operation:

See ["Using the power sensor as an external trigger"](#) on page 302
See ["Trigger Source"](#) on page 374
See ["Free Run"](#) on page 374
See ["External Trigger 1/2"](#) on page 375
See ["Video"](#) on page 375
See ["IF Power"](#) on page 375
See ["RF Power"](#) on page 376

11.7.4.2 Configuring Gated Measurements

[SENSe:]SWEep:EGATe.....	765
[SENSe:]SWEep:EGATe:HOLDoff.....	766
[SENSe:]SWEep:EGATe:LENGth.....	766
[SENSe:]SWEep:EGATe:POLarity.....	766
[SENSe:]SWEep:EGATe:SOURce.....	767
[SENSe:]SWEep:EGATe:TYPE.....	767

[SENSe:]SWEep:EGATe <State>

This command turns gated measurements on and off.

In case of measurements with an external gate, the measured values are recorded as long as the gate is opened. During a sweep the gate can be opened and closed several times. The synchronization mechanisms with *OPC, *OPC? and *WAI remain completely unaffected.

The measurement ends when a particular number of measurement points has been recorded (see [\[SENSe:\]SWEep:POINts](#) on page 752).

Performing gated measurements turns the squelch off.

Parameters:

<State> ON | OFF
 *RST: OFF

Example:

```
SWE:EGAT ON
Switches on the external gate mode.
SWE:EGAT:TYPE EDGE
Switches on the edge-triggered mode.
SWE:EGAT:HOLD 100US
Sets the gate delay to 100 µs.
SWE:EGAT:LEN 500US
Sets the gate opening time to 500 µs.
INIT;*WAI
Starts a sweep and waits for its end.
```

[SENSe:]SWEep:EGATe:HOLDoff <DelayTime>

This command defines the length of the trigger delay.

The trigger delay has no effect on

- measurements using the "Level" gate mode
- frequency sweep, FFT sweep, zero span and I/Q mode measurements using an IF Power trigger.

Parameters:

<DelayTime> Range: 0 s to 30 s
 *RST: 0 s

Example: SWE:EGAT:HOLD 100us

Manual operation: See "[Gate Delay](#)" on page 379

[SENSe:]SWEep:EGATe:LENGth <GateLength>

This command defines the gate length.

Parameters:

<GateLength> Range: 125 ns to 30 s
 *RST: 400µs

Example: SWE:EGAT:LENG 10ms

Manual operation: See "[Gate Length](#)" on page 379

[SENSe:]SWEep:EGATe:POLarity <Polarity>

This command selects the polarity of an external gate signal.

The setting applies both to the edge of an edge-triggered signal and the level of a level-triggered signal.

Parameters:

<Polarity> POSitive | NEGative
 *RST: POSitive

Example: SWE:EGAT:POL POS

Manual operation: See ["Slope"](#) on page 377

[SENSe:]SWEep:EGATe:SOURce <Source>

This command selects the signal source for gated measurements.

If an IF power signal is used, the gate is opened as soon as a signal at > -20 dBm is detected within the IF path bandwidth (10 MHz).

For more information see ["Trigger Source"](#) on page 374.

Parameters:

<Source> EXTernal | EXT2 | IFPower | VIDEo | RFPower
 *RST: IFPower

Example: SWE:EGAT:SOUR IFP
 Switches the gate source to IF power.

Manual operation: See ["Trigger Source"](#) on page 374
 See ["External Trigger 1/2"](#) on page 375
 See ["Video"](#) on page 375
 See ["IF Power"](#) on page 375
 See ["RF Power"](#) on page 376

[SENSe:]SWEep:EGATe:TYPE <Type>

This command selects the way gated measurements are triggered.

Parameters:

<Type> **LEVEL**
 The trigger event for the gate to open is a particular power level. After the gate signal has been detected, the gate remains open until the signal disappears.

Note: If you perform gated measurements in combination with the IF Power trigger, the R&S FPS ignores the holding time for frequency sweep, FFT sweep, zero span and I/Q mode measurements.

EDGE
 The trigger event for the gate to open is the detection of the signal edge. After the gate signal has been detected, the gate remains open until the gate delay is over.

*RST: EDGE

Example: SWE:EGAT:TYPE EDGE

Manual operation: See ["Gate Mode"](#) on page 379

11.7.4.3 Configuring the Trigger Output

The following commands are required to send the trigger signal to one of the variable TRIGGER INPUT/OUTPUT connectors.

OUTPut:TRIGger<port>:DIRection.....	768
OUTPut:TRIGger<port>:LEVel.....	768
OUTPut:TRIGger<port>:OTYPe.....	769
OUTPut:TRIGger<port>:PULSe:IMMEDIATE.....	769
OUTPut:TRIGger<port>:PULSe:LENGth.....	769

OUTPut:TRIGger<port>:DIRection <Direction>

This command selects the trigger direction for trigger ports that serve as an input as well as an output.

Suffix:

<port> Selects the used trigger port.
2 = TRG AUX

Parameters:

<Direction> **INPut**
Port works as an input.

OUTPut
Port works as an output.

*RST: INPut

Manual operation: See "Trigger 2" on page 332

OUTPut:TRIGger<port>:LEVel <Level>

This command defines the level of the signal generated at the trigger output.

This command works only if you have selected a user defined output with `OUTPut:TRIGger<port>:OTYPe`.

Suffix:

<port> Selects the trigger port to which the output is sent.
2 = TRG AUX

Parameters:

<Level> **HIGH**
TTL signal.

LOW
0 V

*RST: LOW

Manual operation: See "Trigger 2" on page 332
 See "Level" on page 332

OUTPut:TRIGger<port>:OTYPe <OutputType>

This command selects the type of signal generated at the trigger output.

Suffix:

<port> Selects the trigger port to which the output is sent.
2 = TRG AUX

Parameters:

<OutputType>

DEVICE

Sends a trigger signal when the R&S FPS has triggered internally.

TARMed

Sends a trigger signal when the trigger is armed and ready for an external trigger event.

UDEFined

Sends a user defined trigger signal. For more information see [OUTPut:TRIGger<port>:LEVel](#).

*RST: DEVICE

Manual operation: See "[Output Type](#)" on page 332

OUTPut:TRIGger<port>:PULSe:IMMediate

This command generates a pulse at the trigger output.

Suffix:

<port> Selects the trigger port to which the output is sent.
2 = TRG AUX

Usage:

Event

Manual operation: See "[Send Trigger](#)" on page 333

OUTPut:TRIGger<port>:PULSe:LENGth <Length>

This command defines the length of the pulse generated at the trigger output.

Suffix:

<port> Selects the trigger port to which the output is sent.
2 = TRG AUX

Parameters:

<Length> Pulse length in seconds.

Manual operation: See "[Pulse Length](#)" on page 333

11.7.5 Adjusting Settings Automatically

The commands required to adjust settings automatically in a remote environment are described here.

The tasks for manual operation are described in [chapter 6.7, "Adjusting Settings Automatically"](#), on page 382.



MSRA operating mode

In MSRA operating mode, settings related to data acquisition (measurement time, hysteresis) can only be adjusted automatically in the MSRA Master, not in the MSRA applications.

[SENSe:]ADJust:ALL.....	770
[SENSe:]ADJust:CONFigure:DURation.....	770
[SENSe:]ADJust:CONFigure:DURation:MODE.....	771
[SENSe:]ADJust:CONFigure:HYSteresis:LOWer.....	771
[SENSe:]ADJust:CONFigure:HYSteresis:UPPer.....	771
[SENSe:]ADJust:CONFigure:TRIG.....	772
[SENSe:]ADJust:FREquency.....	772
[SENSe:]ADJust:LEVel.....	772

[SENSe:]ADJust:ALL

This command initiates a measurement to determine and set the ideal settings for the current task automatically (only once for the current measurement).

This includes:

- Center frequency
- Reference level

Example: ADJ:ALL

Usage: Event

Manual operation: See "[Adjusting all Determinable Settings Automatically \(Auto All\)](#)" on page 383

[SENSe:]ADJust:CONFigure:DURation <Duration>

In order to determine the ideal reference level, the R&S FPS performs a measurement on the current input data. This command defines the length of the measurement if `[SENSe:]ADJust:CONFigure:DURation:MODE` is set to `MANual`.

Parameters:

<Duration> Numeric value in seconds
 Range: 0.001 to 16000.0
 *RST: 0.001
 Default unit: s

Example: ADJ:CONF:DUR:MODE MAN
 Selects manual definition of the measurement length.
 ADJ:CONF:LEV:DUR 5ms
 Length of the measurement is 5 ms.

Manual operation: See ["Changing the Automatic Measurement Time \(Meastime Manual\)"](#) on page 384

[SENSe:]ADJust:CONFigure:DURation:MODE <Mode>

In order to determine the ideal reference level, the R&S FPS performs a measurement on the current input data. This command selects the way the R&S FPS determines the length of the measurement .

Parameters:

<Mode>

AUTO

The R&S FPS determines the measurement length automatically according to the current input data.

MANual

The R&S FPS uses the measurement length defined by [\[SENSe:\]ADJust:CONFigure:DURation](#) on page 770.

*RST: AUTO

Manual operation: See ["Resetting the Automatic Measurement Time \(Meastime Auto\)"](#) on page 384
See ["Changing the Automatic Measurement Time \(Meastime Manual\)"](#) on page 384

[SENSe:]ADJust:CONFigure:HYSTeresis:LOWer <Threshold>

When the reference level is adjusted automatically using the [\[SENSe:\]ADJust:LEVe1](#) on page 772 command, the internal attenuators and the preamplifier are also adjusted. In order to avoid frequent adaptation due to small changes in the input signal, you can define a hysteresis. This setting defines a lower threshold the signal must fall below (compared to the last measurement) before the reference level is adapted automatically.

Parameters:

<Threshold>

Range: 0 dB to 200 dB

*RST: +1 dB

Default unit: dB

Example:

SENS:ADJ:CONF:HYST:LOW 2

For an input signal level of currently 20 dBm, the reference level will only be adjusted when the signal level falls below 18 dBm.

Manual operation: See ["Lower Level Hysteresis"](#) on page 384

[SENSe:]ADJust:CONFigure:HYSTeresis:UPPer <Threshold>

Parameters:

<Threshold>

Range: 0 dB to 200 dB

*RST: +1 dB

Default unit: dB

Example:

SENS:ADJ:CONF:HYST:UPP 2

Example: For an input signal level of currently 20 dBm, the reference level will only be adjusted when the signal level rises above 22 dBm.

Manual operation: See ["Upper Level Hysteresis"](#) on page 384

[SENSe:]ADJust:CONFigure:TRIG <State>

Defines the behaviour of the measurement when adjusting a setting automatically (using `SENS:ADJ:LEV ON`, for example).

See ["Adjusting settings automatically during triggered measurements"](#) on page 383.

Parameters:

<State>

ON | 1

The measurement for automatic adjustment waits for the trigger.

OFF | 0

The measurement for automatic adjustment is performed immediately, without waiting for a trigger.

*RST: 1

[SENSe:]ADJust:FREQuency

This command sets the center frequency to the frequency with the highest signal level in the current frequency range.

At the same time, the optimal reference level is also set (see [\[SENSe:\]ADJust:LEVel](#) on page 772).

Example: `ADJ:FREQ`

Usage: Event

Manual operation: See ["Adjusting the Center Frequency Automatically \(Auto Freq\)"](#) on page 383

[SENSe:]ADJust:LEVel

This command initiates a single (internal) measurement that evaluates and sets the ideal reference level for the current input data and measurement settings. This ensures that the settings of the RF attenuation and the reference level are optimally adjusted to the signal level without overloading the R&S FPS or limiting the dynamic range by an S/N ratio that is too small.

Example: `ADJ:LEV`

Usage: Event

Manual operation: See ["Setting the Reference Level Automatically \(Auto Level\)"](#) on page 346

11.7.6 Configuring the Data Input and Output

- [RF Input](#)..... 773
- [External Generator Control](#)..... 774
- [Working with Power Sensors](#)..... 785
- [Configuring the Outputs](#)..... 795

11.7.6.1 RF Input

INPut:COUPling	773
INPut:DPATH	773
INPut:FILTer:YIG[:STATe]	773
INPut:IMPedance	774
INPut:SELEct	774

INPut:COUPling <CouplingType>

This command selects the coupling type of the RF input.

Parameters:

<CouplingType> **AC**
 AC coupling

DC
 DC coupling

*RST: AC

Example: INP:COUP DC

Usage: SCPI confirmed

Manual operation: See "[Input Coupling](#)" on page 295

INPut:DPATH <State>

Enables or disables the use of the direct path for frequencies close to 0 Hz.

Parameters:

<State> **AUTO | 1**
 (Default) the direct path is used automatically for frequencies
 close to 0 Hz.

OFF | 0
 The analog mixer path is always used.

*RST: 1

Example: INP:DPAT OFF

Usage: SCPI confirmed

INPut:FILTer:YIG[:STATe] <State>

This command turns the YIG-preselector on and off.

Note the special conditions and restrictions for the YIG filter described in "[YIG-Preselector](#)" on page 296.

Parameters:

<State> ON | OFF | 0 | 1
 *RST: 1 (0 for I/Q Analyzer, GSM, VSA and MC Group Delay measurements)

Example:

INP:FILT:YIG OFF
 Deactivates the YIG-preselector.

Manual operation: See "[YIG-Preselector](#)" on page 296

INPut:IMPedance <Impedance>

This command selects the nominal input impedance of the RF input.

75 Ω should be selected if the 50 Ω input impedance is transformed to a higher impedance using a matching pad of the RAZ type (= 25 Ω in series to the input impedance of the instrument). The power loss correction value in this case is 1.76 dB = 10 log (75 Ω /50 Ω).

Parameters:

<Impedance> 50 | 75
 *RST: 50 Ω

Example:

INP:IMP 75

Usage:

SCPI confirmed

Manual operation: See "[Impedance](#)" on page 295
 See "[Unit](#)" on page 346

INPut:SElect <Source>

This command selects the signal source for measurements, i.e. it defines which connector is used to input data to the R&S FPS. If no additional input options are installed, only RF input is supported.

Parameters:

<Source> **RF**
 Radio Frequency ("RF INPUT" connector)
 *RST: RF

Manual operation: See "[Radio Frequency State](#)" on page 295

11.7.6.2 External Generator Control

External generator control commands are available if the R&S FPS External Generator Control option (R&S FPS-B10) is installed. For each measurement channel one external generator can be configured. To switch between different configurations define multiple measurement channels.

For more information on external generator control see [chapter 6.2.4.2, "Basics on External Generator Control"](#), on page 306.

- [Measurement Configuration](#).....775
- [Interface Configuration](#).....778
- [Source Calibration](#).....780
- [Programming Example for External Generator Control](#)..... 783

Measurement Configuration

The following commands are required to activate external generator control and to configure a calibration measurement with an external tracking generator.

SOURce:EXTernal:FREQUency	775
SOURce:EXTernal:FREQUency:COUPling[:STATe]	775
SOURce:EXTernal:FREQUency[:FACTor]:DENominator	776
SOURce:EXTernal:FREQUency[:FACTor]:NUMerator	776
SOURce:EXTernal:FREQUency:OFFSet	777
SOURce:EXTernal:POWer[:LEVel]	777
SOURce:EXTernal[:STATe]	777
SOURce:POWer[:LEVel][:IMMediate]:OFFSet	777

SOURce:EXTernal:FREQUency <Frequency>

This command defines a fixed source frequency for the external generator.

Parameters:

<Frequency> Source frequency of the external generator.
 *RST: 1100050000

Example: SOUR:EXT:FREQ 10MHz

Manual operation: See "[\(Manual\) Source Frequency](#)" on page 319

SOURce:EXTernal:FREQUency:COUPling[:STATe] <State>

This command couples the frequency of the external generator output to the R&S FPS.

Parameters:

<State> ON | OFF | 0 | 1
ON | 1
 Default setting: a series of frequencies is defined (one for each sweep point), based on the current frequency at the RF input of the R&S FPS; the RF frequency range covers the currently defined span of the R&S FPS (unless limited by the range of the signal generator)
OFF | 0
 The generator uses a single fixed frequency, defined by [SOURce:EXTernal:FREQUency](#).

*RST: 1

Example: SOUR:EXT:FREQ:COUP ON

Manual operation: See "[Source Frequency Coupling](#)" on page 319

SOURce:EXTernal:FREQUENCY[:FACTOR]:DENominator <Value>

This command defines the denominator of the factor with which the analyzer frequency is multiplied in order to obtain the transmit frequency of the selected generator.

Select the multiplication factor such that the frequency range of the generator is not exceeded if the following formula is applied to the start and stop frequency of the analyzer:

$$\text{Source Freq} = \text{RF} \cdot \frac{\text{Numerator}}{\text{Denominator}} + \text{Offset}$$

Parameters:

<Value> <numeric value>
 *RST: 1

Example:

```
SOUR:EXT:FREQ:NUM 4
SOUR:EXT:FREQ:DEN 3
```

Sets a multiplication factor of 4/3, i.e. the transmit frequency of the generator is 4/3 times the analyzer frequency.

Manual operation: See "[\(Automatic\) Source Frequency \(Numerator/Denominator/Offset\)](#)" on page 319

SOURce:EXTernal:FREQUENCY[:FACTOR]:NUMerator <Value>

This command defines the numerator of the factor with which the analyzer frequency is multiplied in order to obtain the transmit frequency of the selected generator.

Select the multiplication factor such that the frequency range of the generator is not exceeded if the following formula is applied to the start and stop frequency of the analyzer:

$$\text{Source Freq} = \text{RF} \cdot \frac{\text{Numerator}}{\text{Denominator}} + \text{Offset}$$

Parameters:

<Value> <numeric value>
 *RST: 1

Example:

```
SOUR:EXT:FREQ:NUM 4"
"SOUR:EXT:FREQ:DEN 3"
```

Sets a multiplication factor of 4/3, i.e. the transmit frequency of the generator is 4/3 times the analyzer frequency.

Manual operation: See "[\(Automatic\) Source Frequency \(Numerator/Denominator/Offset\)](#)" on page 319

SOURce:EXTernal:FREQuency:OFFSet <Offset>

This command defines the frequency offset of the generator with reference to the analyzer frequency.

Select the offset such that the frequency range of the generator is not exceeded if the following formula is applied to the start and stop frequency of the analyzer:

$$\text{Source Freq} = \text{RF} \cdot \frac{\text{Numerator}}{\text{Denominator}} + \text{Offset}$$

Parameters:

<Offset> <numeric value>, specified in Hz, kHz, MHz or GHz, rounded to the nearest Hz

*RST: 0 Hz

Example:

SOUR:EXT:FREQ:OFFS 10HZ

Sets an offset of the generator output frequency compared to the analyzer frequency of 10 Hz.

Manual operation: See "[\(Automatic\) Source Frequency \(Numerator/Denominator/Offset\)](#)" on page 319

SOURce:EXTernal:POWer[:LEVel] <Level>

This command sets the output power of the selected generator.

Parameters:

<Level> <numeric value>

*RST: -20 dBm

Example:

SOUR:EXT:POW -30dBm

Sets the generator level to -30 dBm

Manual operation: See "[Source Power](#)" on page 318

SOURce:EXTernal[:STATe] <State>

This command activates or deactivates the connected external generator.

Parameters:

<State> ON | OFF

*RST: OFF

Manual operation: See "[Source State](#)" on page 318

SOURce:POWer[:LEVel][:IMMediate]:OFFSet <Offset>

This command defines a level offset for the external generator level. Thus, for example, attenuators or amplifiers at the output of the external generator can be taken into account for the setting.

Parameters:

<Offset> Range: -200 dB to +200 dB
 *RST: 0dB

Example:

SOUR:POW:OFFS -10dB
 Sets the level offset of the external generator to – 20 dBm.

Usage:

SCPI confirmed

Manual operation: See "[Source Offset](#)" on page 318

Interface Configuration

The following commands are required to configure the interface for the connection to the external generator.

SOURce:EXTernal:ROSCillator[:SOURce]	778
SYSTem:COMMunicate:PEXPress:RDEvice:GENerator:ADDRess	778
SYSTem:COMMunicate:PEXPress:RDEvice:GENerator:ADDRess:CATalog?	779
SYSTem:COMMunicate:PEXPress:RESCan	779
SYSTem:COMMunicate:RDEvice:GENerator:INTerface	779
SYSTem:COMMunicate:RDEvice:GENerator:TYPE	779
SYSTem:COMMunicate:TCPip:RDEvice:GENerator:ADDRess	780

SOURce:EXTernal:ROSCillator[:SOURce] <Source>

This command controls selection of the reference oscillator for the external generator.

If the external reference oscillator is selected, the reference signal must be connected to the rear panel of the instrument.

Parameters:

<Source> **INTernal**
 the internal reference is used

EXTernal
 the external reference is used; if none is available, an error flag is displayed in the status bar

*RST: INT

Example:

SOUR:EXT:ROSC EXT
 Switches to external reference oscillator

Manual operation: See "[Reference](#)" on page 317

SYSTem:COMMunicate:PEXPress:RDEvice:GENerator:ADDRess <SerialNo>

This command sets the PCIe serial number of the R&S FPS.

Parameters:

<SerialNo> string
 PCIe serial number

*RST: not changed during preset;

Example: `SYST:COMM:PEXP:RDEV:GEN:ADDR '100015'`
Usage: SCPI confirmed
Manual operation: See "[Serial Number](#)" on page 317

SYSTem:COMMunicate:PEXPpress:RDEvice:GENerator:ADDRess:CATalog?

This command queries the available PCIe serial numbers of the R&S FPS.

Return values:

<SerialNos> string
 available PCIe serial numbers

Example: `SYST:COMM:PEXP:RDEV:GEN:ADDR:CAT?`
Result:
 '100015,101977'

Usage: Query only
 SCPI confirmed

Manual operation: See "[Serial Number](#)" on page 317

SYSTem:COMMunicate:PEXPpress:RESCan

Repeats a scan for external generators connected to the R&S FPS. This is useful if new generators were connected recently and are not yet displayed in the list of serial numbers.

Example: `SYST:COMM:PEXP:RESC`

Usage: Event
 SCPI confirmed

Manual operation: See "[Rescan](#)" on page 317

SYSTem:COMMunicate:RDEvice:GENerator:INTerface <Type>

Defines the interface used for the connection to the external generator.

This command is only available if external generator control is active (see [SOURCE:EXTernal\[:STATe\]](#) on page 777).

Parameters:

<Type> PEXP | TCPip
 *RST: PEXP

Example: `SYST:COMM:RDEV:GEN:INT TCP`

Manual operation: See "[Interface](#)" on page 316

SYSTem:COMMunicate:RDEvice:GENerator:TYPE <Type>

This command selects the type of external generator.

For a list of the available generator types see "[Overview of Supported Generators](#)" on page 308.

Parameters:

<Name> <Generator name as string value>
*RST: SMU02

Example:

SYST:COMM:RDEV:GEN:TYPE 'SMW06'
Selects SMW06 as an external generator

Manual operation: See "[Generator Type](#)" on page 316

SYSTem:COMMunicate:TCPip:RDEvice:GENerator:ADDRess <Address>

Configures the TCP/IP address for the external generator.

Parameters:

<Address> TCP/IP address between 0.0.0.0 and 0.255.255.255
*RST: 0.0.0.0

Example:

SYST:COMM:TCP:RDEV:GEN:ADDR 130.094.122.195

Manual operation: See "[TCP/IP Address](#)" on page 316

Source Calibration

The following commands are required to activate the calibration functions of the external tracking generator. However, they are only available if external generator control is active (see [SOURCE:EXTERNAL\[:STATE\]](#) on page 777).

Useful commands for source calibration described elsewhere:

- [chapter 11.10.3, "Working with Transducers"](#), on page 914
- [DISPLAY\[:WINDOW<n>\]:TRACE<t>:Y\[:SCALE\]:RPOSITION](#) on page 760

Remote commands exclusive to source calibration:

DISPLAY[:WINDOW<n>]:TRACE<t>:Y[:SCALE]:RVALUE	780
[SENSe:]CORRection:COLLect[:ACQUIRE]	781
[SENSe:]CORRection:METhod	781
[SENSe:]CORRection:RECall	782
[SENSe:]CORRection[:STATE]	782
[SENSe:]CORRection:TRANsducer:GENerator	783

DISPlay[:WINDow<n>]:TRACe<t>:Y[:SCALE]:RVALue <Value>

The command defines the power value assigned to the reference position in the grid (for all traces, <t> is irrelevant).

For external generator calibration measurements (requires the optional External Generator Control), this command defines the power offset value assigned to the reference position.

Parameters:

<Value> *RST: 0 dBm, coupled to reference level

Example:

DISP:TRAC:Y:RVAL -20dBm

Sets the power value assigned to the reference position to -20 dBm

Manual operation: See ["Reference Value"](#) on page 322

[SENSe:]CORRection:COLLect[:ACQuire] <MeasType>

This command initiates a reference measurement (calibration). The reference measurement is the basis for the measurement normalization. The result depends on whether a reflection measurement or transmission measurement is performed (see [\[SENSe:\]CORRection:METhod](#) on page 781).

To obtain a correct reference measurement, a complete sweep with synchronization to the end of the sweep must have been carried out. This is only possible in the single sweep mode.

This command is only available if external generator control is active (see [SOURCE:EXTeRnal\[:STATe\]](#) on page 777).

Parameters:

<MeasType>

THRough

"TRANsmission" mode: calibration with direct connection between external generator and device input

"REFLection" mode: calibration with short circuit at the input

OPEN

only allowed in "REFLection" mode: calibration with open input

Example:

INIT:CONT OFF

Selects single sweep operation

CORR:METH TRAN

Selects a transmission measurement.

CORR:COLL THR;*WAI

Starts the measurement of reference data using direct connection between generator and device input and waits for the sweep end.

Usage:

Setting only

SCPI confirmed

Manual operation: See ["Calibrate Reflection Short"](#) on page 321

See ["Calibrate Reflection Open"](#) on page 321

[SENSe:]CORRection:METhod

This command selects the type of measurement to be performed with the external generator.

This command is only available if external generator control is active (see [SOURCE:EXTeRnal\[:STATe\]](#) on page 777).

Parameters:**REFlection**

Selects reflection measurements.

TRANsmission

Selects transmission measurements.

*RST: TRANsmission

Example:

CORR:METH TRAN

Sets the type of measurement to "transmission".

Manual operation:

See "[Calibrate Transmission](#)" on page 321

See "[Calibrate Reflection Short](#)" on page 321

See "[Calibrate Reflection Open](#)" on page 321

[SENSe:]CORRection:RECall

This command restores the measurement configuration used for calibration.

This command is only available if external generator control is active (see [SOURCE:EXTernal\[:STATe\]](#) on page 777).

Example:

CORR:REC

Usage:

Event

Manual operation:

See "[Recall](#)" on page 321

[SENSe:]CORRection[:STATe] <State>

This command turns correction of measurement results (normalization) on and off.

The command is available after you have created a reference trace for the selected measurement type with [\[SENSe:\]CORRection:COLLect\[:ACQuire\]](#) on page 781.

This command is only available if external generator control is active (see [SOURCE:EXTernal\[:STATe\]](#) on page 777).

Parameters:

<State>

ON | OFF

*RST: OFF

Example:

CORR ON

Activates normalization.

Usage:

SCPI confirmed

Manual operation:

See "[Source Calibration Normalize](#)" on page 321

[SENSe:]CORRection:TRANsducer:GENerator <Name>

This command uses the normalized measurement data to generate a transducer factor with up to 1001 points. The trace data is converted to a transducer with unit dB and stored in a file with the specified name and the suffix `.trd` under `c:\r_s\instr\trd`. The frequency points are allocated in equidistant steps between start and stop frequency.

The generated transducer factor can be further adapted using the commands described in [chapter 11.10.3, "Working with Transducers"](#), on page 914).

Parameters:

<Name> '<name>'

Example:

```
CORR:TRAN:GEN 'SMW200A1'
Creates the transducer file
C:\r_s\instr\trd\SMW200A.trd.
```

Usage:

SCPI confirmed

Manual operation: See ["Save As Trd Factor"](#) on page 322

Programming Example for External Generator Control

The following example demonstrates how to work with an external generator in a remote environment.

It assumes a signal generator of the type SMA01A is connected to the R&S FPS via TCP/IP, as described in ["External Generator Connections"](#) on page 306.

```
//-----Preparing the instrument -----

//Reset the instrument
*RST

//Set the frequency span.
SENS:FREQ:STAR 10HZ
SENS:FREQ:STOP 1MHZ

//-----Configuring the interface -----

//Set the generator type to SMW06 with a frequency range of 100 kHz to 3GHz
SYST:COMM:RDEV:GEN:TYPE 'SMA01A'

//Set the interface used to the TCP/IP address 130.094.122.195
SYST:COMM:RDEV:GEN:INT TCP
SYST:COMM:TCP:RDEV:GEN:ADDR 130.094.122.195

//Activate the use of the external reference frequency at 10 MHz on the generator
SOUR:EXT:ROSC EXT

//-----Configuring the calibration measurement -----
```

Setting Basic Measurement Parameters

```

//Activate external generator control.
SOUR:EXT:STAT ON
//Set the generator output level to -10 dBm.
SOUR:EXT:POW -10DBM
//Set the frequency coupling to automatic
SOUR:EXT:FREQ:COUP:STAT ON

//-----Configuring the generator frequency range -----

//Define a series of frequencies (one for each sweep point) based on the current
//frequency at the RF input of the analyzer; the generator frequency is half the
//frequency of the analyzer, with an offset of 100 kHz;
// analyzer start:          10 Hz
// analyzer stop:           1 MHz
// analyzer span:           999.99 KHz
// generator frequency start: 100.005 KHz
// generator frequency stop:  600 KHz
// generator span:          499.995 KHz

SOUR:EXT:FREQ:FACT:NUM 1
SOUR:EXT:FREQ:FACT:DEN 2
SOUR:EXT:FREQ:OFFS 100KHZ

//-----Performing the calibration measurement -----

//Perform a transmission measurement with direct connection between the generator
//and the analyzer and wait till the end
SENS:CORR:METH TRAN
SENS:CORR:COLL:ACQ THR; *WAI

//-----Retrieving the calibration trace results -----

//Retrieve the measured frequencies (10 Hz - 600 kHz)
TRAC:DATA:X? TRACE1

//Retrieve the measured power levels; = 0 between 10 Hz and 100 kHz (below
//generator minimum frequency); nominal -5dBm as of 100 kHz;
TRAC:DATA? TRACE1

//-----Normalizing the calibration trace results -----

//Retrieve the normalized power levels (= power offsets from calibration results)
//Should be 0 for all sweep points directly after calibration
SENS:CORR:STAT ON
TRAC:DATA? TRACE1

//-----Changing the display of the calibration results -----
//Shift the reference line so the -5 dB level is displayed in the center
DISP:TRAC:Y:SCAL:RVAL -5DB

```

DISP:TRAC:Y:SCAL:RPOS 50PCT

11.7.6.3 Working with Power Sensors

The following commands describe how to work with power sensors.

- [Configuring Power Sensors](#)..... 785
- [Configuring Power Sensor Measurements](#)..... 786
- [Triggering with Power Sensors](#)..... 793

Configuring Power Sensors

SYSTem:COMMunicate:RDEvice:PMETer<p>:CONFigure:AUTO[:STATe]	785
SYSTem:COMMunicate:RDEvice:PMETer:COUNT?	785
SYSTem:COMMunicate:RDEvice:PMETer<p>:DEFine	785

SYSTem:COMMunicate:RDEvice:PMETer<p>:CONFigure:AUTO[:STATe] <State>

This command turns automatic assignment of a power sensor to the power sensor index on and off.

Suffix:

<p> 1...4
Power sensor index

Parameters:

<State> ON | OFF | 0 | 1
*RST: 1

Example: SYST:COMM:RDEV:PMET:CONF:AUTO OFF

Manual operation: See "[Select](#)" on page 300

SYSTem:COMMunicate:RDEvice:PMETer:COUNT?

This command queries the number of power sensors currently connected to the R&S FPS.

Parameters:

<NumberSensors> Number of connected power sensors.

Example: SYST:COMM:RDEV:PMET:COUN?

Usage: Query only

Manual operation: See "[Select](#)" on page 300

SYSTem:COMMunicate:RDEvice:PMETer<p>:DEFine <Placeholder>, <Type>, <Interface>, <SerialNo>

This command assigns the power sensor with the specified serial number to the selected power sensor index (configuration).

The query returns the power sensor type and serial number of the sensor assigned to the specified index.

Suffix:

<p> 1...4
Power sensor index

Setting parameters:

<Placeholder> Currently not evaluated
<SerialNo> Serial number of a connected power sensor

Query parameters:

<Type> The power sensor type, e.g. "NRP-Z81".
<Interface> Currently not evaluated

Return values:

<Placeholder> Currently not used
<Type> Detected power sensor type, e.g. "NRP-Z81".
<Interface> Interface the power sensor is connected to; always "USB"
<SerialNo> Serial number of the power sensor assigned to the specified index

Example:

```
SYST:COMM:RDEV:PMET2:DEF ' ', 'NRP-Z81', ' ', '123456'
```

Assigns the power sensor with the serial number '123456' to the configuration "Power Sensor 2".

```
SYST:COMM:RDEV:PMET2:DEF?
```

Queries the sensor assigned to "Power Sensor 2".

Result:

```
' ', 'NRP-Z81', 'USB', '123456'
```

The NRP-Z81 power sensor with the serial number '123456' is assigned to the "Power Sensor 2".

Manual operation: See ["Select"](#) on page 300

Configuring Power Sensor Measurements

CALibration:PMETer<p>:ZERO:AUTO ONCE.....	787
CALCulate<n>:PMETer<p>:RELative[MAGNitude].....	787
CALCulate<n>:PMETer<p>:RELative[MAGNitude]:AUTO ONCE.....	787
CALCulate<n>:PMETer<p>:RELative:STATe.....	788
FETCh:PMETer<p>?.....	788
READ:PMETer<p>?.....	788
[SENSe:]PMETer<p>:DCYClE[STATe].....	789
[SENSe:]PMETer<p>:DCYClE:VALue.....	789
[SENSe:]PMETer<p>:FREQuency.....	789
[SENSe:]PMETer<p>:FREQuency:LINK.....	790
[SENSe:]PMETer<p>:MTIme.....	790
[SENSe:]PMETer<p>:MTIme:AVERAge:COUNT.....	790
[SENSe:]PMETer<p>:MTIme:AVERAge[STATe].....	791

[SENSe:PMETer<p>:ROFFset[:STATe].....	791
[SENSe:PMETer<p>[:STATe].....	792
[SENSe:PMETer<p>:UPDate[:STATe].....	792
UNIT<n>:PMETer<p>:POWer.....	792
UNIT<n>:PMETer<p>:POWer:RATio.....	793

CALibration:PMETer<p>:ZERO:AUTO ONCE

This commands starts to zero the power sensor.

Note that you have to disconnect the signals from the power sensor input before you start to zero the power sensor. Otherwise, results are invalid.

Suffix:

<p> 1...4
Power sensor index

Parameters:

ONCE

Example:

CAL:PMET2:ZERO:AUTO ONCE;*WAI

Starts zeroing the power sensor 2 and delays the execution of further commands until zeroing is concluded.

Usage: Event

Manual operation: See "[Zeroing Power Sensor](#)" on page 300

CALCulate<n>:PMETer<p>:RELative[:MAGNitude] <RefValue>

This command defines the reference value for relative measurements.

Suffix:

<p> 1...4
Power sensor index

Parameters:

<RefValue> Range: -200 dBm to 200 dBm
*RST: 0

Example:

CALC:PMET2:REL -30

Sets the reference value for relative measurements to -30 dBm for power sensor 2.

Manual operation: See "[Reference Value](#)" on page 301

CALCulate<n>:PMETer<p>:RELative[:MAGNitude]:AUTO ONCE

This command sets the current measurement result as the reference level for relative measurements.

Suffix:

<p> 1...4
Power sensor index

Parameters:

ONCE

Example:

CALC:PMET2:REL:AUTO ONCE

Takes the current measurement value as reference value for relative measurements for power sensor 2.

Usage:

Event

Manual operation:

See "[Setting the Reference Level from the Measurement \(Meas->Ref\)](#)" on page 301

CALCulate<n>:PMETer<p>:RELative:STATe <State>

This command turns relative power sensor measurements on and off.

Suffix:

<p>

1...4

Power sensor index

Parameters:

<State>

ON | OFF

*RST: OFF

Example:

CALC:PMET2:REL:STAT ON

Activates the relative display of the measured value for power sensor 2.

FETCh:PMETer<p>?

This command queries the results of power sensor measurements.

Suffix:

<p>

1...4

Power sensor index

Return values:

<Level>

Power level that has been measured by a power sensor. The unit is either dBm (absolute measurements) or dB (relative measurements).

Usage:

Query only

READ:PMETer<p>?

This command initiates a power sensor measurement and queries the results.

Suffix:

<p>

1...4

Power sensor index

Usage:

Query only

[SENSe:]PMETer<p>:DCYClE[:STATe] <State>

This command turns the duty cycle correction on and off.

Suffix:

<p> 1...4
Power sensor index

Parameters:

<State> ON | OFF
*RST: OFF

Example: PMET2:DCYC:STAT ON

Manual operation: See "Duty Cycle" on page 302

[SENSe:]PMETer<p>:DCYClE:VALue <Percentage>

This command defines the duty cycle for the correction of pulse signals.

The power sensor uses the duty cycle in combination with the mean power to calculate the power of the pulse.

Suffix:

<p> 1...4
Power sensor

Parameters:

<Percentage> Range: 0.001 to 99.999
*RST: 99.999
Default unit: %

Example: PMET2:DCYC:STAT ON
Activates the duty cycle correction.
PMET2:DCYC:VAL 0.5
Sets the correction value to 0.5%.

Manual operation: See "Duty Cycle" on page 302

[SENSe:]PMETer<p>:FREQUency <Frequency>

This command defines the frequency of the power sensor.

Suffix:

<p> 1...4
Power sensor index

Parameters:

<Frequency> The available value range is specified in the data sheet of the power sensor in use.
*RST: 50 MHz

Example: PMET2:FREQ 1GHZ
Sets the frequency of the power sensor to 1 GHz.

Manual operation: See ["Frequency Manual"](#) on page 300

[SENSe:]PMETer<p>:FREQuency:LINK <Coupling>

This command selects the frequency coupling for power sensor measurements.

Suffix:

<p> 1...4
Power sensor index

Parameters:

<Coupling> **CENTer**
Couples the frequency to the center frequency of the analyzer

MARKer1
Couples the frequency to the position of marker 1

OFF
Switches the frequency coupling off

*RST: CENTer

Example: PMET2:FREQ:LINK CENT
Couples the frequency to the center frequency of the analyzer

Manual operation: See ["Frequency Coupling"](#) on page 301

[SENSe:]PMETer<p>:MTIME <Duration>

This command selects the duration of power sensor measurements.

Suffix:

<p> 1...4
Power sensor index

Parameters:

<Duration> SHORt | NORMAl | LONG

*RST: NORMAl

Example: PMET2:MTIM SHOR
Sets a short measurement duration for measurements of stationary high power signals for the selected power sensor.

Manual operation: See ["Meas Time/Average"](#) on page 301

[SENSe:]PMETer<p>:MTIME:AVERAge:COUNT <NumberReadings>

This command sets the number of power readings included in the averaging process of power sensor measurements.

Extended averaging yields more stable results for power sensor measurements, especially for measurements on signals with a low power, because it minimizes the effects of noise.

Suffix:

<p> 1...4
Power sensor index

Parameters:

<NumberReadings> An average count of 0 or 1 performs one power reading.
Range: 0 to 256
Increment: binary steps (1, 2, 4, 8, ...)

Example:

```
PMET2:MTIM:AVER ON
Activates manual averaging.
PMET2:MTIM:AVER:COUN 8
Sets the number of readings to 8.
```

Manual operation: See "[Average Count \(Number of Readings\)](#)" on page 302

[SENSe:]PMETer<p>:MTIMe:AVERage[:STATe] <State>

This command turns averaging for power sensor measurements on and off.

Suffix:

<p> 1...4
Power sensor index

Parameters:

<State> ON | OFF
*RST: OFF

Example:

```
PMET2:MTIM:AVER ON
Activates manual averaging.
```

Manual operation: See "[Meas Time/Average](#)" on page 301

[SENSe:]PMETer<p>:ROFFset[:STATe] <State>

This command includes or excludes the reference level offset of the analyzer for power sensor measurements.

Suffix:

<p> 1...4
Power sensor index

Parameters:

<State> **ON | 1**
Includes the reference level offset in the results.
OFF | 0
Ignores the reference level offset.
*RST: 1

Example:

```
PMET2:ROFF OFF
Takes no offset into account for the measured power.
```

Manual operation: See "[Use Ref Lev Offset](#)" on page 302

[SENSe:]PMETer<p>[:STATe] <State>

This command turns a power sensor on and off.

Suffix:

<p> 1...4
Power sensor index

Parameters:

<State> ON | OFF
*RST: OFF

Example:

PMET1 ON
Switches the power sensor measurements on.

Manual operation: See "[State](#)" on page 299
See "[Select](#)" on page 300

[SENSe:]PMETer<p>:UPDate[:STATe] <State>

This command turns continuous update of power sensor measurements on and off.

If on, the results are update even if a single sweep is complete.

Suffix:

<p> 1...4
Power sensor index

Parameters:

<State> ON | OFF
*RST: OFF

Example:

PMET1:UPD ON
The data from power sensor 1 is updated continuously.

Manual operation: See "[Continuous Value Update](#)" on page 300

UNIT<n>:PMETer<p>:POWer <Unit>

This command selects the unit for absolute power sensor measurements (<n> is irrelevant).

Suffix:

<p> 1...4
Power sensor index

Parameters:

<Unit> DBM | WATT | W
*RST: DBM

Example:

UNIT:PMET:POW DBM

Manual operation: See "[Unit/Scale](#)" on page 301

UNIT<n>:PMETer<p>:POWER:RATio <Unit>

This command selects the unit for relative power sensor measurements (<n> is irrelevant).

Suffix:

<p> 1...4
Power sensor index

Parameters:

<Unit> DB | PCT
*RST: DB

Example: UNIT:PMET:POW:RAT DB

Manual operation: See "Unit/Scale" on page 301

Triggering with Power Sensors

[SENSe:]PMETer<p>:TRIGger:DTIME.....	793
[SENSe:]PMETer<p>:TRIGger:HOLDoff.....	793
[SENSe:]PMETer<p>:TRIGger:HYSTeresis.....	794
[SENSe:]PMETer<p>:TRIGger:LEVel.....	794
[SENSe:]PMETer<p>:TRIGger:SLOPe.....	795
[SENSe:]PMETer<p>:TRIGger[:STATe].....	795

[SENSe:]PMETer<p>:TRIGger:DTIME <Time>

This command defines the time period that the input signal has to stay below the IF power trigger level before the measurement starts.

Suffix:

<p> 1...4
Power sensor index

Parameters:

<Time> Range: 0 s to 1 s
Increment: 100 ns
*RST: 100 µs

Example: PMET2:TRIG:DTIME 0.001

[SENSe:]PMETer<p>:TRIGger:HOLDoff <Holdoff>

This command defines the trigger holdoff for external power triggers.

Suffix:

<p> 1...4
Power sensor index

Parameters:

<Holdoff> Time period that has to pass between the trigger event and the start of the measurement, in case another trigger event occurs.

Range: 0 s to 1 s
 Increment: 100 ns
 *RST: 0 s

Example:

PMET2:TRIG:HOLD 0.1
 Sets the holdoff time of the trigger to 100 ms

Manual operation: See ["Trigger Holdoff"](#) on page 303

[SENSe:]PMETer<p>:TRIGger:HYSTeresis <Hysteresis>

This command defines the trigger hysteresis for external power triggers.

The hysteresis in dB is the value the input signal must stay below the IF power trigger level in order to allow a trigger to start the measurement.

Suffix:

<p> 1...4
 Power sensor index

Parameters:

<Hysteresis> Range: 3 dB to 50 dB
 Increment: 1 dB
 *RST: 0 dB

Example:

PMET2:TRIG:HYST 10
 Sets the hysteresis of the trigger to 10 dB.

Manual operation: See ["Hysteresis"](#) on page 303

[SENSe:]PMETer<p>:TRIGger:LEVel <Level>

This command defines the trigger level for external power triggers.

This command requires the use of an R&S NRP-Z81 power sensor.

Suffix:

<p> 1...4
 Power sensor index

Parameters:

<Level> -20 to +20 dBm
 Range: -20 dBm to 20 dBm
 *RST: -10 dBm

Example:

PMET2:TRIG:LEV -10 dBm
 Sets the level of the trigger

Manual operation: See ["External Trigger Level"](#) on page 302

[SENSe:]PMETer<p>:TRIGger:SLOPe <Edge>

This command selects the trigger condition for external power triggers.

Suffix:

<p> 1...4
Power sensor index

Parameters:

<Edge> **POSitive**
The measurement starts in case the trigger signal shows a positive edge.

NEGative
The measurement starts in case the trigger signal shows a negative edge.

*RST: POSitive

Example: PMET2:TRIG:SLOP NEG

Manual operation: See "[Slope](#)" on page 303

[SENSe:]PMETer<p>:TRIGger[:STATe] <State>

This command turns the external power trigger on and off.

This command requires the use of an R&S NRP-Z81 power sensor.

Suffix:

<p> 1...4
Power sensor index

Parameters:

<State> ON | OFF
*RST: OFF

Example: PMET2:TRIG ON
Switches the external power trigger on

Manual operation: See "[Using the power sensor as an external trigger](#)" on page 302

11.7.6.4 Configuring the Outputs

Configuring trigger input/output is described in [chapter 11.7.4.3, "Configuring the Trigger Output"](#), on page 768.

DIAGnostic:SERvice:NSource	796
OUTPut:IF[:SOURce]	796

DIAGnostic:SERVice:NSource <State>

This command turns the 28 V supply of the BNC connector labeled NOISE SOURCE CONTROL on the R&S FPS on and off.

For details see [chapter 6.2.1.1, "Input from Noise Sources"](#), on page 293.

Parameters:

<State> ON | OFF
*RST: OFF

Example: DIAG:SERV:NSO ON

Manual operation: See ["Noise Source"](#) on page 332

OUTPut:IF[:SOURce] <Source>

Defines the type of signal available at the IF/VIDEO or IF OUT 2 GHZ connector of the R&S FPS.

Parameters:

<Source> **IF**
The measured IF value is available at the IF/VIDEO output connector.

VIDeo

The displayed video signal (i.e. the filtered and detected IF signal, 200mV) is available at the IF/VIDEO output connector. This setting is required to provide demodulated audio frequencies at the output.

*RST: IF

Example: OUTP:IF VID
Selects the video signal for the IF/VIDEO output connector.

Manual operation: See ["IF/Video Output"](#) on page 331

11.8 Analyzing Measurements (Basics)

The commands for general analysis tasks are described here.

- [Zooming into the Display](#).....797
- [Configuring the Trace Display and Retrieving Trace Data](#).....799
- [Working with Markers](#).....819
- [Configuring Display and Limit Lines](#).....864

11.8.1 Zooming into the Display

11.8.1.1 Using the Single Zoom

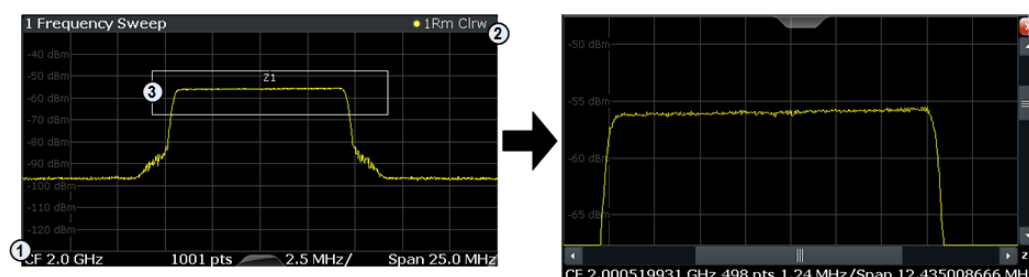
DISPlay[:WINDow<n>]:ZOOM:AREA..... 797

DISPlay[:WINDow<n>]:ZOOM:STATe..... 797

DISPlay[:WINDow<n>]:ZOOM:AREA <x1>,<y1>,<x2>,<y2>

This command defines the zoom area.

To define a zoom area, you first have to turn the zoom on.



1 = origin of coordinate system (x1 = 0, y1 = 0)

2 = end point of system (x2 = 100, y2 = 100)

3 = zoom area (e.g. x1 = 60, y1 = 30, x2 = 80, y2 = 75)

Parameters:

<x1>,<y1>,

<x2>,<y2>

Diagram coordinates in % of the complete diagram that define the zoom area.

The lower left corner is the origin of coordinate system. The upper right corner is the end point of the system.

Range: 0 to 100

Default unit: PCT

Manual operation: See ["Single Zoom"](#) on page 393

DISPlay[:WINDow<n>]:ZOOM:STATe <State>

This command turns the zoom on and off.

Parameters:

<State>

ON | OFF

*RST: OFF

Example:

DISP:ZOOM ON

Activates the zoom mode.

Manual operation: See ["Single Zoom"](#) on page 393

See ["Restore Original Display"](#) on page 394

See ["Deactivating Zoom \(Selection mode\)"](#) on page 394

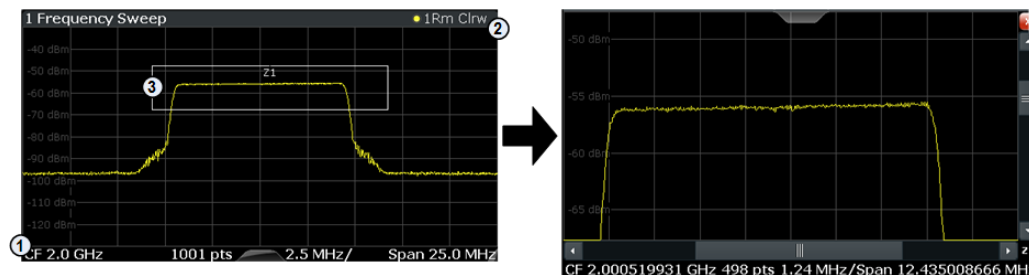
11.8.1.2 Using the Multiple Zoom

DISPlay[:WINDow<n>]:ZOOM:MUlTiple<zoom>:AREA.....	798
DISPlay[:WINDow<n>]:ZOOM:MUlTiple<zoom>:STATe.....	798

DISPlay[:WINDow<n>]:ZOOM:MUlTiple<zoom>:AREA <x1>,<y1>,<x2>,<y2>

This command defines the zoom area for a multiple zoom.

To define a zoom area, you first have to turn the zoom on.



- 1 = origin of coordinate system (x1 = 0, y1 = 0)
- 2 = end point of system (x2 = 100, y2 = 100)
- 3 = zoom area (e.g. x1 = 60, y1 = 30, x2 = 80, y2 = 75)

Suffix:

<zoom> 1...4
Selects the zoom window.

Parameters:

<x1>,<y1>,
<x2>,<y2> Diagram coordinates in % of the complete diagram that define the zoom area.
The lower left corner is the origin of coordinate system. The upper right corner is the end point of the system.
Range: 0 to 100
Default unit: PCT

Manual operation: See "[Multiple Zoom](#)" on page 394

DISPlay[:WINDow<n>]:ZOOM:MUlTiple<zoom>:STATe <State>

This command turns the mutiple zoom on and off.

Suffix:

<zoom> 1...4
Selects the zoom window.
If you turn off one of the zoom windows, all subsequent zoom windows move up one position.

Parameters:

<State> ON | OFF
*RST: OFF

- Manual operation:** See "Multiple Zoom" on page 394
 See "Restore Original Display" on page 394
 See "🖱️ Deactivating Zoom (Selection mode)" on page 394

11.8.2 Configuring the Trace Display and Retrieving Trace Data

The commands required to work with traces are described here.



Commands required to export traces (and other result data) are described in [chapter 11.9.5, "Storing Measurement Results"](#), on page 902.

- [Configuring Standard Traces](#)..... 799
- [Configuring Spectrograms](#)..... 804
- [Using Trace Mathematics](#)..... 810
- [Retrieving Trace Results](#)..... 812
- [Formats for Returned Values: ASCII Format and Binary Format](#)..... 816
- [Programming Example: Configuring a Spectrogram](#)..... 816

11.8.2.1 Configuring Standard Traces

Useful commands for trace configuration described elsewhere

- `DISPlay[:WINDow<n>]:TRACe<t>:Y:SPACing` on page 760
- `DISPlay[:WINDow<n>]:TRACe<t>:Y[:SCALE]` on page 759

Remote commands exclusive to trace configuration

<code>DISPlay[:WINDow<n>]:TRACe<t>:MODE</code>	799
<code>DISPlay[:WINDow<n>]:TRACe<t>:MODE:HCONtinuous</code>	800
<code>DISPlay[:WINDow<n>]:TRACe<t>[:STATE]</code>	801
<code>DISPlay[:WINDow<n>]:TRACe<t>:SMOothing:APERture</code>	801
<code>DISPlay[:WINDow<n>]:TRACe<t>:SMOothing[:STATE]</code>	801
<code>[SENSe:]AVERAge<n>:COUNT</code>	802
<code>[SENSe:]AVERAge<n>[:STATE<t>]</code>	802
<code>[SENSe:]AVERAge<n>:TYPE</code>	802
<code>[SENSe:]WINDow<n>:DETEctor<t>[:FUNCTION]</code>	803
<code>[SENSe:]WINDow<n>:DETEctor<t>[:FUNCTION]:AUTO</code>	803
<code>TRACe<n>:COPY</code>	804

`DISPlay[:WINDow<n>]:TRACe<t>:MODE <Mode>`

This command selects the trace mode.

In case of max hold, min hold or average trace mode, you can set the number of single measurements with `[SENSe:]SWEep:COUNT`. Note that synchronization to the end of the measurement is possible only in single sweep mode.

Parameters:

<Mode>

WRITE

Overwrite mode: the trace is overwritten by each sweep. This is the default setting.

AVERage

The average is formed over several sweeps. The "Sweep/Average Count" determines the number of averaging procedures.

MAXHold

The maximum value is determined over several sweeps and displayed. The R&S FPS saves the sweep result in the trace memory only if the new value is greater than the previous one.

MINHold

The minimum value is determined from several measurements and displayed. The R&S FPS saves the sweep result in the trace memory only if the new value is lower than the previous one.

VIEW

The current contents of the trace memory are frozen and displayed.

BLANK

Hides the selected trace.

*RST: Trace 1: WRITE, Trace 2-6: BLANK

Example:

```
INIT:CONT OFF
```

Switching to single sweep mode.

```
SWE:COUN 16
```

Sets the number of measurements to 16.

```
DISP:TRAC3:MODE WRIT
```

Selects clear/write mode for trace 3.

```
INIT;*WAI
```

Starts the measurement and waits for the end of the measurement.

Manual operation: See "[Trace Mode](#)" on page 410

DISPlay[:WINDow<n>]:TRACe<t>:MODE:HCONTinuous <State>

This command turns an automatic reset of a trace on and off after a parameter has changed.

The reset works for trace modes min hold, max hold and average.

Note that the command has no effect if critical parameters like the span have been changed to avoid invalid measurement results

Parameters:

<State> **ON**
 The automatic reset is off.

OFF
 The automatic reset is on.

*RST: OFF

Example:

DISP:WIND:TRAC3:MODE:HCON ON
 Switches off the reset function.

Manual operation: See "[Hold](#)" on page 411

DISPlay[:WINDow<n>]:TRACe<t>[:STATe] <State>

This command turns a trace on and off.

The measurement continues in the background.

Parameters:

<State> ON | OFF | 0 | 1
 *RST: 1 for TRACe1, 0 for TRACe 2 to 6

Example:

DISP:TRAC3 ON

Usage:

SCPI confirmed

Manual operation: See "[Trace 1/Trace 2/Trace 3/Trace 4 \(Softkeys\)](#)" on page 413

DISPlay[:WINDow<n>]:TRACe<t>:SMOothing:APERture <Percentage>

This command defines the degree (aperture) of the trace smoothing, if [DISPlay\[:WINDow<n>\]:TRACe<t>:SMOothing\[:STATe\]](#) TRUE.

Parameters:

<Percentage> Range: 1 to 50
 *RST: 2
 Default unit: PCT

Example:

DISP3:TRAC2:SMO:APER 5
 Defines an aperture of 5% for trace 2 in window 3

Manual operation: See "[Smoothing](#)" on page 412

DISPlay[:WINDow<n>]:TRACe<t>:SMOothing[:STATe] <State>

This command turns trace smoothing for a particular trace on and off.

If enabled, the trace is smoothed by the value specified using [DISPlay\[:WINDow<n>\]:TRACe<t>:SMOothing:APERture](#) on page 801.

For more information see [chapter 7.3.1.6, "Trace Smoothing"](#), on page 402.

Parameters:

<State> ON | OFF
 *RST: OFF

Example:

DISP3:TRAC2:SMO ON
 Turns on trace smoothing for trace 2 in window 3

Usage:

SCPI confirmed

Manual operation: See "[Smoothing](#)" on page 412

[SENSe:]AVERAge<n>:COUNT <AverageCount>

This command defines the number of sweeps that the application uses to average traces (for all windows, <n> is irrelevant).

In case of continuous sweeps, the application calculates the moving average over the average count.

In case of single sweep measurements, the application stops the measurement and calculates the average after the average count has been reached.

Parameters:

<AverageCount> If you set a average count of 0 or 1, the application performs one single sweep in single sweep mode.
 In continuous sweep mode, if the average count is set to 0, a moving average over 10 sweeps is performed.
 Range: 0 to 200000
 *RST: 0

Usage:

SCPI confirmed

Manual operation: See "[Sweep / Average Count](#)" on page 361
 See "[Average Count](#)" on page 412

[SENSe:]AVERAge<n>[:STATe<t>] <State>

This command turns averaging for a particular trace in a particular window on and off.

Parameters:

<State> ON | OFF

Usage:

SCPI confirmed

[SENSe:]AVERAge<n>:TYPE <Mode>

This command selects the trace averaging mode.

Parameters:

<Mode>

VIDeo

The logarithmic power values are averaged.

LINear

The power values are averaged before they are converted to logarithmic values.

POWer

The power level values are converted into unit Watt prior to averaging. After the averaging, the data is converted back into its original unit.

*RST: VIDeo

Example:

AVER:TYPE LIN

Switches to linear average calculation.

Usage:

SCPI confirmed

Manual operation: See "[Average Mode](#)" on page 412**[SENSe:][WINDow<n>:]DETEctor<t>[:FUNctioN] <Detector>**

Defines the trace detector to be used for trace analysis.

For details see [chapter 7.3.1.1, "Mapping Samples to sweep Points with the Trace Detector"](#), on page 397.**Parameters:**

<Detector>

APEak

Autopeak

NEGative

Negative peak

POSitive

Positive peak

SAMPlE

First value detected per trace point

RMS

RMS value

AVERage

Average

*RST: APEak (I/Q Analyzer: RMS)

Example:

DET POS

Sets the detector to "positive peak".

Manual operation: See "[Detector](#)" on page 411**[SENSe:][WINDow<n>:]DETEctor<t>[:FUNctioN]:AUTO <State>**

This command couples and decouples the detector to the trace mode.

Parameters:

<State> ON | OFF | 0 | 1
 *RST: 1

Example:

DET:AUTO OFF

The selection of the detector is not coupled to the trace mode.

Manual operation: See "[Detector](#)" on page 411

TRACe<n>:COPY <TraceNumber>, <TraceNumber>

This command copies data from one trace to another.

Parameters:

<TraceNumber>, **TRACE1 | TRACE2 | TRACE3 | TRACE4 | TRACE5 | TRACE6**
 <TraceNumber> The first parameter is the destination trace, the second parameter is the source.
 (Note the 'e' in the parameter is required!)

Example:

TRAC:COPY TRACE1,TRACE2

Copies the data from trace 2 to trace 1.

Usage:

SCPI confirmed

Manual operation: See "[Copy Trace](#)" on page 413

11.8.2.2 Configuring Spectrograms

In addition to the standard "level versus frequency" or "level versus time" spectrum traces, the R&S FPS also provides a spectrogram display of the measured data. A spectrogram shows how the spectral density of a signal varies over time. The x-axis shows the frequency, the y-axis shows the time. The commands required to configure spectrograms in a remote environment are described here. For details and manual operation see [chapter 7.3.2.4, "Spectrogram Settings"](#), on page 417.



When configuring spectrograms, the window suffix is irrelevant. The settings are always applied to the spectrogram window, or to all spectrogram windows, if several are active for the same measurement channel.

For commands to set markers in spectrograms, see [chapter 11.8.3.6, "Marker Search \(Spectrograms\)"](#), on page 835.

Configuring a Spectrogram Measurement..... 804

Configuring the Color Map..... 808

Configuring a Spectrogram Measurement

CALCulate<n>:SGRam:CLEAr[:IMMEDIATE].....805

CALCulate<n>:SPEctrogram:CLEAr[:IMMEDIATE]..... 805

CALCulate<n>:SGRam:CONT.....805

CALCulate<n>:SPEctrogram:CONT..... 805

CALCulate<n>:SGRam:FRAMe:COUNT.....	806
CALCulate<n>:SPECtrogram:FRAMe:COUNT.....	806
CALCulate<n>:SGRam:FRAMe:SElect.....	806
CALCulate<n>:SPECtrogram:FRAMe:SElect.....	806
CALCulate<n>:SGRam:HDEPth.....	806
CALCulate<n>:SPECtrogram:HDEPth.....	806
CALCulate<n>:SGRam:TSTamp:DATA?.....	807
CALCulate<n>:SPECtrogram:TSTamp:DATA?.....	807
CALCulate<n>:SGRam:TSTamp[:STATe].....	808
CALCulate<n>:SPECtrogram:TSTamp[:STATe].....	808
CALCulate<n>:SGRam[:STATe].....	808
CALCulate<n>:SPECtrogram[:STATe].....	808

CALCulate<n>:SGRam:CLEAr[:IMMediate]**CALCulate<n>:SPECtrogram:CLEAr[:IMMediate]**

This command resets the spectrogram and clears the history buffer.

(<n> is irrelevant.)

Example: `CALC:SGR:CLE`
Resets the result display and clears the memory.

Usage: Event

Manual operation: See "[Clear Spectrogram](#)" on page 364

CALCulate<n>:SGRam:CONT <State>**CALCulate<n>:SPECtrogram:CONT <State>**

This command determines whether the results of the last measurement are deleted before starting a new measurement in single sweep mode.

(<n> is irrelevant.)

Parameters:
<State> ON | OFF
*RST: OFF

Example: `INIT:CONT OFF`
Selects single sweep mode.
`INIT;*WAI`
Starts the sweep and waits for the end of the sweep.
`CALC:SGR:CONT ON`
Repeats the single sweep measurement without deleting the results of the last measurement.

Manual operation: See "[Single Sweep/ RUN SINGLE](#)" on page 363
See "[Continue Frame](#)" on page 364

CALCulate<n>:SGRam:FRAMe:COUNt <Frames>

CALCulate<n>:SPECTrogram:FRAMe:COUNt <Frames>

This command defines the number of frames to be recorded in a single sweep.

(<n> is irrelevant.)

Parameters:

<Frames> The maximum number of frames depends on the history depth.
 Range: 1 to history depth
 Increment: 1
 *RST: 1

Example:

```
INIT:CONT OFF
Selects single sweep mode.
CALC:SGR:FRAM:COUN 200
Sets the number of frames to 200.
```

Manual operation: See "[Frame Count](#)" on page 364

CALCulate<n>:SGRam:FRAMe:SElect <Frame> | <Time>

CALCulate<n>:SPECTrogram:FRAMe:SElect <Frame> | <Time>

This command selects a specific frame for further analysis.

(<n> is irrelevant.)

The command is available if no measurement is running or after a single sweep has ended.

Parameters:

<Frame> Selects a frame directly by the frame number. Valid if the time stamp is off.
 The range depends on the history depth.

<Time> Selects a frame via its time stamp. Valid if the time stamp is on.
 The number is the distance to frame 0 in seconds. The range depends on the history depth.

Example:

```
INIT:CONT OFF
Stop the continuous sweep.
CALC:SGR:FRAM:SEL -25
Selects frame number -25.
```

Manual operation: See "[Selecting a frame to display](#)" on page 364

CALCulate<n>:SGRam:HDEPth <History>

CALCulate<n>:SPECTrogram:HDEPth <History>

This command defines the number of frames to be stored in the R&S FPS memory.

(<n> is irrelevant.)

Parameters:

<History> The maximum number of frames depends on the number of sweep points.
 Range: 781 to 20000
 Increment: 1
 *RST: 3000

Example:

CALC:SGR:SPEC 1500
 Sets the history depth to 1500.

Manual operation: See ["History Depth"](#) on page 419

CALCulate<n>:SGRam:TSTamp:DATA? <Frames>

CALCulate<n>:SPECTrogram:TSTamp:DATA? <Frames>

This command queries the starting time of the frames.

(<n> is irrelevant.)

The return values consist of four values for each frame. If the Spectrogram is empty, the command returns '0,0,0,0'. The times are given as delta values, which simplifies evaluating relative results; however, you can also calculate the absolute date and time as displayed on the screen.

The frame results themselves are returned with TRAC:DATA? SGR

See [TRACe<n> \[:DATA\]](#) on page 813.

Query parameters:

<Frames>

CURRENT

Returns the starting time of the current frame.

ALL

Returns the starting time for all frames. The results are sorted in descending order, beginning with the current frame.

Return values:

<Seconds>

Number of seconds that have passed since 01.01.1970 till the frame start

<Nanoseconds>

Number of nanoseconds that have passed *in addition to the* <Seconds> since 01.01.1970 till the frame start.

<Reserved>

The third and fourth value are reserved for future uses.

Example:

CALC:SGR:TST ON

Activates the time stamp.

CALC:SGR:TST:DATA? ALL

Returns the starting times of all frames sorted in a descending order.

Usage:

Query only

Manual operation: See ["Timestamp"](#) on page 419

CALCulate<n>:SGRam:TSTamp[:STATe] <State>

CALCulate<n>:SPECTrogram:TSTamp[:STATe] <State>

This command activates and deactivates the time stamp.

(<n> is irrelevant.)

If the time stamp is active, some commands do not address frames as numbers, but as (relative) time values:

- [CALCulate<n>:DELTaMarker<m>:SPECTrogram:FRAMe](#) on page 840
- [CALCulate<n>:MARKer<m>:SPECTrogram:FRAMe](#) on page 836
- [CALCulate<n>:SPECTrogram:FRAMe:SElect](#) on page 806

Parameters:

<State> ON | OFF
 *RST: OFF

Example:

CALC:SGR:TST ON
 Activates the time stamp.

Manual operation: See "[Timestamp](#)" on page 419

CALCulate<n>:SGRam[:STATe] <State>

CALCulate<n>:SPECTrogram[:STATe] <State>

This command turns the spectrogram on and off.

(<n> is irrelevant.)

Parameters:

<State> ON | OFF
 *RST: OFF

Example:

CALC:SGR ON
 Activates the Spectrogram result display.

Manual operation: See "[State](#)" on page 418

Configuring the Color Map

DISPlay[:WINDow<n>]:SGRam:COLor:DEFault	809
DISPlay[:WINDow<n>]:SPECTrogram:COLor:DEFault	809
DISPlay[:WINDow<n>]:SGRam:COLor:LOWer	809
DISPlay[:WINDow<n>]:SPECTrogram:COLor:LOWer	809
DISPlay[:WINDow<n>]:SGRam:COLor:SHAPE	809
DISPlay[:WINDow<n>]:SPECTrogram:COLor:SHAPE	809
DISPlay[:WINDow<n>]:SGRam:COLor:UPPer	809
DISPlay[:WINDow<n>]:SPECTrogram:COLor:UPPer	809
DISPlay[:WINDow<n>]:SGRam:COLor[:STYLe]	810
DISPlay[:WINDow<n>]:SPECTrogram:COLor[:STYLe]	810

DISPlay[:WINDow<n>]:SGRam:COLor:DEFault
DISPlay[:WINDow<n>]:SPECtrogram:COLor:DEFault

This command restores the original color map.

Usage: Event

Manual operation: See ["Set to Default"](#) on page 421

DISPlay[:WINDow<n>]:SGRam:COLor:LOWer <Percentage>
DISPlay[:WINDow<n>]:SPECtrogram:COLor:LOWer <Percentage>

This command defines the starting point of the color map.

Parameters:

<Percentage> Statistical frequency percentage.
 Range: 0 to 66
 *RST: 0
 Default unit: %

Example: DISP:WIND:SGR:COL:LOW 10
 Sets the start of the color map to 10%.

Manual operation: See ["Start / Stop"](#) on page 421

DISPlay[:WINDow<n>]:SGRam:COLor:SHAPE <Shape>
DISPlay[:WINDow<n>]:SPECtrogram:COLor:SHAPE <Shape>

This command defines the shape and focus of the color curve for the spectrogram result display.

Parameters:

<Shape> Shape of the color curve.
 Range: -1 to 1
 *RST: 0

Manual operation: See ["Shape"](#) on page 421

DISPlay[:WINDow<n>]:SGRam:COLor:UPPer <Percentage>
DISPlay[:WINDow<n>]:SPECtrogram:COLor:UPPer <Percentage>

This command defines the end point of the color map.

Parameters:

<Percentage> Statistical frequency percentage.
 Range: 0 to 66
 *RST: 0
 Default unit: %

Example: DISP:WIND:SGR:COL:UPP 95
 Sets the start of the color map to 95%.

Manual operation: See ["Start / Stop"](#) on page 421

DISPlay[:WINDow<n>]:SGRam:COLor[:STYLE] <ColorScheme>

DISPlay[:WINDow<n>]:SPEctrogram:COLor[:STYLE] <ColorScheme>

This command selects the color scheme.

Parameters:

<ColorScheme>

HOT

Uses a color range from blue to red. Blue colors indicate low levels, red colors indicate high ones.

COLD

Uses a color range from red to blue. Red colors indicate low levels, blue colors indicate high ones.

RADar

Uses a color range from black over green to light turquoise with shades of green in between.

GRAYscale

Shows the results in shades of gray.

*RST: HOT

Example:

DISP:WIND:SPEC:COL GRAY

Changes the color scheme of the spectrogram to black and white.

Manual operation: See "[Hot/Cold/Radar/Grayscale](#)" on page 421

11.8.2.3 Using Trace Mathematics

The following commands control trace mathematics.

CALCulate<n>:MATH[:EXpression][:DEFine].....	810
CALCulate<n>:MATH:MODE.....	811
CALCulate<n>:MATH:POSition.....	811
CALCulate<n>:MATH:STATe.....	811

CALCulate<n>:MATH[:EXpression][:DEFine] <Expression>

This command selects the mathematical expression for trace mathematics.

Before you can use the command, you have to turn trace mathematics on.

Parameters:

<Expression>

(TRACE1-TRACE2)

Subtracts trace 2 from trace 1.

(TRACE1-TRACE3)

Subtracts trace 3 from trace 1.

(TRACE1-TRACE4)

Subtracts trace 4 from trace 1.

(TRACE1-TRACE5)

Subtracts trace 5 from trace 1.

(TRACE1-TRACE6)

Subtracts trace 6 from trace 1.

- Example:** `CALC:MATH:STAT ON`
Turns trace mathematics on.
`CALC:MATH:EXPR:DEF (TRACE1-TRACE3)`
Subtracts trace 3 from trace 1.
- Usage:** SCPI confirmed
- Manual operation:** See "[Trace Math Function](#)" on page 414

CALCulate<n>:MATH:MODE <Mode>

This command selects the way the R&S FPS calculates trace mathematics.

Parameters:

<Mode> For more information on the way each mode works see [Trace Math Mode](#).

LINEar

Linear calculation.

LOGarithmic

Logarithmic calculation.

POWER

Linear power calculation.

*RST: LOGarithmic

- Example:** `CALC:MATH:MODE LIN`
Selects linear calculation.

Manual operation: See "[Trace Math Mode](#)" on page 415

CALCulate<n>:MATH:POSition <Position>

This command defines the position of the trace resulting from the mathematical operation.

Parameters:

<Position> Vertical position of the trace in % of the height of the diagram area.

100 PCT corresponds to the upper diagram border.

Range: -100 to 200

*RST: 50

Default unit: PCT

- Example:** `CALC:MATH:POS 100`
Moves the trace to the top of the diagram area.

Manual operation: See "[Trace Math Position](#)" on page 415

CALCulate<n>:MATH:STATe <State>

This command turns the trace mathematics on and off.

Parameters:

<State> ON | OFF
 *RST: OFF

Example:

CALC:MATH:STAT ON
 Turns on trace mathematics.

Usage:

SCPI confirmed

Manual operation:

See ["Trace Math Function"](#) on page 414
 See ["Trace Math Off"](#) on page 415

11.8.2.4 Retrieving Trace Results

This chapter describes how to retrieve data from standard traces.

For spectrograms see also [chapter 11.8.3.6, "Marker Search \(Spectrograms\)"](#), on page 835.

For details on the format of the retrieved trace data see also [chapter 11.8.2.5, "Formats for Returned Values: ASCII Format and Binary Format"](#), on page 816.



Commands required to export traces (and other result data) are described in [chapter 11.9.5, "Storing Measurement Results"](#), on page 902.

FORMat[:DATA]	812
TRACe<n>[:DATA]	813
TRACe<n>[:DATA]:MEMory?	815
TRACe<n>[:DATA]:X?	815

FORMat[:DATA] <Format>

This command selects the data format that is used for transmission of trace data from the R&S FPS to the controlling computer.

Note that the command has no effect for data that you send to the R&S FPS. The R&S FPS automatically recognizes the data it receives, regardless of the format.

For details on data formats see [chapter 11.8.2.5, "Formats for Returned Values: ASCII Format and Binary Format"](#), on page 816.

Parameters:

<Format>

ASCII

ASCII format, separated by commas.

This format is almost always suitable, regardless of the actual data format. However, the data is not as compact as other formats may be.

REAL,32

32-bit IEEE 754 floating-point numbers in the "definite length block format".

In the Spectrum application, the format setting `REAL` is used for the binary transmission of trace data.

For I/Q data, 8 bytes per sample are returned for this format setting.

*RST: ASCII

Example:

```
FORM REAL, 32
```

Usage:

SCPI confirmed

TRACe<n>[:DATA] <Trace>, <Data> | <ResultType>

This command queries current trace data and measurement results.

If you use it as a setting command, it transfers trace data from an external source to the R&S FPS.

The data format depends on `FORMat [:DATA]`.

Parameters:

<Trace>

Selects the trace to write the data to.

TRACE1 | ... | TRACE6

<Data>

Contains the data to transfer.

Query parameters:

<ResultType>	Selects the type of result to be returned.
	TRACE1 ... TRACE6
	Returns the trace data for the corresponding trace. For details see table 11-5 .
	LIST
	Returns the results of the peak list evaluation for Spurious Emission and Spectrum Emission Mask measurements. For SEM measurements, one peak per range is returned. For spurious emission measurements, the number of peaks returned for each measurement range is defined by the "Peaks per Range" parameter (see CALCulate<n>:PEAKsearch:SUBRanges on page 694), regardless of the "Details" setting. For details see table 11-6 .
	SPURious
	Returns the peak list of Spurious Emission measurements.
	SPECTrogram SGRam
	Returns the results of the spectrogram result display. For details see table 11-7 .

Return values:

<TraceData> For more information see tables below.

Example: `TRAC TRACE1, +A$`
Transfers trace data ('+A\$') to trace 1.

Example: `TRAC? TRACE3`
Queries the data of trace 3.

Usage: SCPI confirmed

Manual operation: See "[Spectrum Emission Mask](#)" on page 114
See "[Spurious Emissions](#)" on page 114
See "[List Evaluation \(Result Summary\) State](#)" on page 226
See "[List Evaluation State](#)" on page 248

Table 11-5: Return values for TRACE1 to TRACE6 parameter

The trace data consists of a list of power levels that have been measured. The number of power levels in the list depends on the currently selected number of sweep points. The unit depends on the measurement and on the unit you have currently set.

If you are measuring with the auto peak detector, the command returns positive peak values only. (To retrieve negative peak values, define a second trace with a negative peak detector.)

For SEM or Spurious Emission measurement results, the x-values should be queried as well, as they are not equi-distant (see [TRACe<n>\[:DATA\]:X?](#) on page 815).

Table 11-6: Return values for LIST parameter

<p>For each peak, the command returns 11 values in the following order: <No>,<StartFreq>,<StopFreq>,<RBW>,<PeakFreq>,<PowerAbs>,<PowerRel>,<PowerDelta>,<LimitCheck>,<Unused1>,<Unused2></p> <ul style="list-style-type: none"> • <No>: range number • <StartFreq>,<StopFreq>: start and stop frequency of the range • <RBW>: resolution bandwidth • <PeakFreq>: frequency of the peak in a range • <PowerAbs>: absolute power of the peak in dBm • <PowerRel>: power of the peak in relation to the channel power in dBc • <PowerDelta>: distance from the peak to the limit line in dB, positive values indicate a failed limit check • <LimitCheck>: state of the limit check (0 = PASS, 1 = FAIL) • <Unused1>,<Unused2>: reserved (0.0)

Table 11-7: Return values for SPECTrogram parameter

<p>For every frame in the spectrogram, the command returns the power levels that have been measured, one for each sweep point. The number of frames depends on the size of the history depth. The power level depends on the unit you have currently set.</p>

TRACe<n>[:DATA]:MEMory? <Trace>,<OffsSwPoint>,<NoOfSwPoints>

This command queries the previously captured trace data for the specified trace from the memory. As an offset and number of sweep points to be retrieved can be specified, the trace data can be retrieved in smaller portions, making the command faster than the TRAC:DATA? command. This is useful if only specific parts of the trace data are of interest.

If no parameters are specified with the command, the entire trace data is retrieved; in this case, the command is identical to TRAC:DATA? TRACE1

For details on the returned values see the TRAC:DATA? <TRACE...> command.

Query parameters:

<Trace>	TRACE1 TRACE2 TRACE3 TRACE4 TRACE5 TRACE6
<OffsSwPoint>	The offset in sweep points related to the start of the measurement at which data retrieval is to start.
<NoOfSwPoints>	Number of sweep points to be retrieved from the trace.

Example: TRAC:DATA:MEM? TRACE1,25,100
 Retrieves 100 sweep points from trace 1, starting at sweep point 25.

Usage: Query only

TRACe<n>[:DATA]:X? <TraceNumber>

This command queries the horizontal trace data for each sweep point in the specified window, for example the frequency in frequency domain or the time in time domain measurements.

This is especially useful for traces with non-equidistant x-values, e.g. for SEM or Spurious Emissions measurements.

Query parameters:`<TraceNumber>` Trace number.**TRACE1 | ... | TRACE6****Example:**`TRAC3:X? TRACE1`

Returns the x-values for trace 1 in window 3.

Usage:

Query only

Manual operation: See "[Spectrum Emission Mask](#)" on page 114**11.8.2.5 Formats for Returned Values: ASCII Format and Binary Format**

When trace data is retrieved using the `TRAC:DATA` or `TRAC:IQ:DATA` command, the data is returned in the format defined using the `FORMat[:DATA]`. The possible formats are described here.

- **ASCII Format (FORMat ASCII):**
The data is stored as a list of comma separated values (CSV) of the measured values in floating point format.
- **Binary Format (FORMat REAL,32):**
The data is stored as binary data (Definite Length Block Data according to IEEE 488.2), each measurement value being formatted in 32 Bit IEEE 754 Floating-Point-Format.
The schema of the result string is as follows:
`#41024<value1><value2>...<value n>` with

#4	number of digits (= 4 in the example) of the following number of data bytes
1024	number of following data bytes (= 1024 in the example)
<Value>	4-byte floating point value



Reading out data in binary format is quicker than in ASCII format. Thus, binary format is recommended for large amounts of data.

11.8.2.6 Programming Example: Configuring a Spectrogram

This example demonstrates how to configure a spectrogram for a basic frequency sweep in a remote environment. The spectrogram is displayed in addition to the spectrum display, in a new window. In addition, the usage of special spectrogram markers is demonstrated (see [chapter 11.8.3.6, "Marker Search \(Spectrograms\)"](#), on page 835).



Basic trace settings are demonstrated in the [chapter 11.15.1, "Programming Example: Performing a Basic Frequency Sweep"](#), on page 976.

```
//-----Preparing the Measurement -----
*RST
```

```

//Resets the instrument
LAY:ADD? '1',BEL,SGR
//Displays a new window below window 1 and activates spectrogram display.
//The new window name is returned as a result: '2'.
//The spectrogram is updated with each new sweep.
INIT:CONT OFF
//Selects single sweep mode.

//-----Configuring the Spectrogram-----
CALC:SGR:CLE
//Clears the displayed spectrogram to start a new one.
CALC:SGR:CONT ON
//Configures a continuous spectrogram for a series of measurements.
//The display is not cleared when a new measurement is started.
CALC:SGR:FRAM:COUN 100
//Sets the number of frames to be recorded per sweep to 100.
CALC:SGR:HDEP 1000
//Sets the number of frames to be stored to 1000 (=10 sweeps)
CALC:SGR:TST ON
//Activates a time stamp for each frame.

//-----Configuring the Color Map-----
DISP:WIND:SGR:COL GRAY
//Defines a gray-scaled coloring: low values light gray, high values dark gray.
DISP:WIND:SGR:COL:LOW 30
DISP:WIND:SGR:COL:UPP 70
DISP:WIND:SGR:COL:SHAP 0.8
//Defines a color map for a range that comprises 40% of the measurement range,
//excluding 30% at each end. The colors are not scaled linearly; the light gray
//colors are stretched to distinguish low values better.

//-----Performing the Measurement-----
SWE:COUN 10
//Defines 10 sweeps to be performed per measurement.
INIT;*WAI
//Initiates a new measurement and waits until the sweeps have finished.
//The spectrogram is updated with each new sweep.

//-----Positioning Markers-----
CALC:MARK:SGR:SAR MEM
//Includes all frames in the memory in the search area

CALC:MARK1:SGR:FRAM -1s
//Sets marker 1 to the frame 1 second after measurement begin. (Note the
//negative value!
CALC:MARK1:MIN
//Sets marker 1 to the minimum level in this frame.
CALC:MARK1:SGR:Y:MIN
//Sets marker 1 to the minimum level for the same frequency the marker is

```

```

//currently positioned at in all frames.

CALC:MARK2:SGR:XY:MAX
//Sets marker 2 to the maximum level in the entire spectrogram.

CALC:DELT1:SGR:FRAM 3s
//Sets the deltamarker 1 to the frame captured 3 seconds after marker 1. By default
//it is set to the peak of that frame and displays the level difference to marker 1.
//Note the positive value!
CALC:DELT1:MIN
//Sets deltamarker 1 to the minimum level in this frame.

CALC:DELT3:SGR:XY:MAX
//Sets deltamarker 3 to the maximum level in the entire spectrogram. By default
//its value is the difference to marker 1. We will change it to refer to marker 2.
CALC:DELT3:MREF 2
//Deltamarker 3 now refers to marker 2, both are positioned on the maximum of the
//spectrogram. Thus, D3=0. We will move deltamarker 3 to the next peak level
//for the same frequency.
CALC:DELT3:SGR:Y:MAX:NEXT

//-----Retrieving Results-----
CALC:MARK1:X?
CALC:MARK1:Y?
CALC:MARK1:SGR:FRAM?
//Queries the frequency (x), level (y) and frame values of marker 1.

CALC:MARK2:X?
CALC:MARK2:Y?
CALC:MARK2:SGR:FRAM?
//Queries the frequency (x), level (y) and frame values of marker 2.

CALC:DELT1:X?
CALC:DELT1:Y?
CALC:DELT1:SGR:FRAM?
//Queries the frequency (x), level (y) and frame values of deltamarker 1.

CALC:DELT3:X?
CALC:DELT3:Y?
CALC:DELT3:SGR:FRAM?
//Queries the frequency (x), level (y) and frame values of deltamarker 3.

CALC:SGR:TST:DATA? ALL
//Queries the time stamps of all stored frames.
CALC:SGR:FRAM:SEL -1
//Selects the frame that was captured 1 second after measurement start (Note the
//negative value!). This frame is displayed in the Spectrum window.
TRAC:DATA? SGR
//Retrieves the trace data for the spectrogram. For each frame, the power level
//and frequency at each sweep point are returned.

```

```
TRAC:DATA? TRACE1
//Retrieves the trace data for the selected frame only.
```

11.8.3 Working with Markers

The commands required to work with markers and marker functions in a remote environment are described here. The tasks for manual operation are described in [chapter 7.4, "Marker Usage"](#), on page 426.



In the Spectrum application, markers are identical in all windows. Thus, the suffix <n> for the window is generally irrelevant.

• Setting Up Individual Markers	819
• General Marker Settings	824
• Configuring and Performing a Marker Search	824
• Positioning the Marker	828
• Retrieving Marker Results	832
• Marker Search (Spectrograms)	835
• Fixed Reference Marker Settings	843
• Marker Peak Lists	845
• Noise Measurement Marker	848
• Phase Noise Measurement Marker	848
• Band Power Marker	850
• n dB Down Marker	852
• Signal Count Marker	856
• Programming Examples for Using Markers and Marker Functions	857

11.8.3.1 Setting Up Individual Markers

The following commands define the position of markers in the diagram.

CALCulate<n>:DELTamarker<m>:AOFF	819
CALCulate<n>:DELTamarker<m>:LINK	820
CALCulate<n>:DELTamarker<m>:LINK:TO:MARKer<m>	820
CALCulate<n>:DELTamarker<m>:MODE	820
CALCulate<n>:DELTamarker<m>:MREF	821
CALCulate<n>:DELTamarker<m>[:STATE]	821
CALCulate<n>:DELTamarker<m>:TRACe	821
CALCulate<n>:DELTamarker<m>:X	822
CALCulate<n>:MARKer<m>:AOFF	822
CALCulate<n>:MARKer<m>:LINK:TO:MARKer<m>	822
CALCulate<n>:MARKer<m>[:STATE]	823
CALCulate<n>:MARKer<m>:TRACe	823
CALCulate<n>:MARKer<m>:X	823

CALCulate<n>:DELTamarker<m>:AOFF

This command turns *all* delta markers off.

(<m> is irrelevant)

Example: `CALC:DELT:AOff`
Turns all delta markers off.

Usage: Event

CALCulate<n>:DELTamarker<m>:LINK <State>

This command links delta marker <m> to marker 1.

If you change the horizontal position (x-value) of marker 1, delta marker <m> changes its horizontal position to the same value.

Tip: to link any marker to a different marker than marker 1, use the `CALCulate<n>:DELTamarker<m>:LINK:TO:MARKer<m>` or `CALCulate<n>:MARKer<m>:LINK:TO:MARKer<m>` commands.

Parameters:
<State> ON | OFF
*RST: OFF

Example: `CALC:DELT2:LINK ON`

Manual operation: See "[Linking to Another Marker](#)" on page 439

CALCulate<n>:DELTamarker<m>:LINK:TO:MARKer<m> <State>

This command links delta marker <m1> to any active normal marker <m2>.

If you change the horizontal position of marker <m2>, delta marker <m1> changes its horizontal position to the same value.

Parameters:
<State> ON | OFF
*RST: OFF

Example: `CALC:DELT4:LINK:TO:MARK2 ON`
Links the delta marker 4 to the marker 2.

Manual operation: See "[Linking to Another Marker](#)" on page 439

CALCulate<n>:DELTamarker<m>:MODE <Mode>

This command defines whether the position of a delta marker is provided as an absolute value or relative to a reference marker (for *all* delta markers, <m> is irrelevant).

Note that when the position of a delta marker is *queried*, the result is always an absolute value (see `CALCulate<n>:DELTamarker<m>:X` on page 822)!

Parameters:

<Mode>

ABSolute

Delta marker position in absolute terms.

RELative

Delta marker position in relation to a reference marker.

***RST:** RELative**Example:**`CALC:DELT:MODE ABS`

Absolute delta marker position.

CALCulate<n>:DELTaMarker<m>:MREF <Reference>

This command selects a reference marker for a delta marker other than marker 1.

The reference may be another marker or the fixed reference.

Parameters:

<Reference>

FIXed

Selects the fixed reference as the reference.

Example:`CALC:DELT3:MREF 2`

Specifies that the values of delta marker 3 are relative to marker 2.

Manual operation: See ["Reference Marker"](#) on page 438**CALCulate<n>:DELTaMarker<m>[:STATe] <State>**

This command turns delta markers on and off.

If necessary, the command activates the delta marker first.

No suffix at DELTmarker turns on delta marker 1.

Parameters:

<State>

ON | OFF

***RST:** OFF**Example:**`CALC:DELT2 ON`

Turns on delta marker 2.

Manual operation: See ["Marker State"](#) on page 438See ["Marker Type"](#) on page 438**CALCulate<n>:DELTaMarker<m>:TRACe <Trace>**

This command selects the trace a delta marker is positioned on.

Note that the corresponding trace must have a trace mode other than "Blank".

If necessary, the command activates the marker first.

Parameters:

<Trace>

Trace number the marker is assigned to.

Example: `CALC:DELT2:TRAC 2`
 Positions delta marker 2 on trace 2.

CALCulate<n>:DELTaMarker<m>:X <Position>

This command moves a delta marker to a particular coordinate on the x-axis.

If necessary, the command activates the delta marker and positions a reference marker to the peak power.

Parameters:

<Position> Numeric value that defines the marker position on the x-axis. The position is relative to the reference marker. To select an absolute position you have to change the delta marker mode with `CALCulate<n>:DELTaMarker<m>:MODE` on page 820. A query returns the absolute position of the delta marker.

Range: The value range and unit depend on the measurement and scale of the x-axis.

Example: `CALC:DELT:X?`
 Outputs the absolute x-value of delta marker 1.

Manual operation: See "[Marker 1/2/3/4](#)" on page 284
 See "[Marker 1/2/3](#)" on page 289
 See "[Marker Position \(X-value\)](#)" on page 438

CALCulate<n>:MARKer<m>:AOFF

This command turns all markers off.

Example: `CALC:MARK:AOFF`
 Switches off all markers.

Usage: Event

Manual operation: See "[All Markers Off](#)" on page 440

CALCulate<n>:MARKer<m>:LINK:TO:MARKer<m> <State>

This command links normal marker <m1> to any active normal marker <m2>.

If you change the horizontal position of marker <m2>, marker <m1> changes its horizontal position to the same value.

Parameters:

<State> ON | OFF
 *RST: OFF

Example: `CALC:MARK4:LINK:TO:MARK2 ON`
 Links marker 4 to marker 2.

Manual operation: See "[Linking to Another Marker](#)" on page 439

CALCulate<n>:MARKer<m>[:STATe] <State>

This command turns markers on and off. If the corresponding marker number is currently active as a deltamarker, it is turned into a normal marker.

Parameters:

<State> ON | OFF
*RST: OFF

Example:

CALC:MARK3 ON
Switches on marker 3.

Manual operation: See ["Marker State"](#) on page 438
See ["Marker Type"](#) on page 438

CALCulate<n>:MARKer<m>:TRACe <Trace>

This command selects the trace the marker is positioned on.

Note that the corresponding trace must have a trace mode other than "Blank".

If necessary, the command activates the marker first.

Parameters:

<Trace> 1 to 6
Trace number the marker is assigned to.

Example:

CALC:MARK3:TRAC 2
Assigns marker 3 to trace 2.

Manual operation: See ["Assigning the Marker to a Trace"](#) on page 439

CALCulate<n>:MARKer<m>:X <Position>

This command moves a marker to a particular coordinate on the x-axis.

If necessary, the command activates the marker.

If the marker has been used as a delta marker, the command turns it into a normal marker.

Parameters:

<Position> Numeric value that defines the marker position on the x-axis.
The unit is either Hz (frequency domain) or s (time domain) or dB (statistics).
Range: The range depends on the current x-axis range.

Example:

CALC:MARK2:X 1.7MHz
Positions marker 2 to frequency 1.7 MHz.

Manual operation: See ["Marker 1/2/3/4"](#) on page 284
See ["Marker 1/2/3"](#) on page 289
See ["Marker Table"](#) on page 386
See ["Marker Peak List"](#) on page 386
See ["Marker Position \(X-value\)"](#) on page 438

11.8.3.2 General Marker Settings

The following commands control general marker functionality.

Remote commands exclusive to general marker functionality

DISPlay:MTABle.....	824
CALCulate<n>:MARKer<m>:X:SSIZe.....	824

DISPlay:MTABle <DisplayMode>

This command turns the marker table on and off.

Parameters:

<DisplayMode>	ON	Turns the marker table on.
	OFF	Turns the marker table off.
	AUTO	Turns the marker table on if 3 or more markers are active.
	*RST: AUTO	

Example: DISP:MTAB ON
Activates the marker table.

Manual operation: See "[Marker Table Display](#)" on page 441

CALCulate<n>:MARKer<m>:X:SSIZe <StepSize>

This command selects the marker step size mode for *all* markers in *all* windows (<m>, <n> are irrelevant).

The step size defines the distance the marker moves when you move it with the rotary knob.

It therefore takes effect in manual operation only.

Parameters:

<StepSize>	STANdard	the marker moves from one pixel to the next
	POINTs	the marker moves from one sweep point to the next
	*RST: POINTs	

Example: CALC:MARK:X:SSIZ STAN
Sets the marker step size to one pixel.

Manual operation: See "[Marker Stepsize](#)" on page 441

11.8.3.3 Configuring and Performing a Marker Search

The following commands control the marker search.

CALCulate<n>:MARKer<m>:LOEXclude.....	825
CALCulate<n>:MARKer<m>:PEXCursion.....	825
CALCulate<n>:MARKer<m>:X:SLIMits[:STATe].....	825
CALCulate<n>:MARKer<m>:X:SLIMits:LEFT.....	826
CALCulate<n>:MARKer<m>:X:SLIMits:RIGHT.....	826
CALCulate<n>:MARKer<m>:X:SLIMits:ZOOM[:STATe].....	827
CALCulate<n>:THReshold.....	827
CALCulate<n>:THReshold:STATe.....	827

CALCulate<n>:MARKer<m>:LOEXclude <State>

This command turns the suppression of the local oscillator during automatic marker positioning on and off (for *all* markers in *all* windows; <m>, <n> are irrelevant).

Parameters:

<State> ON | OFF | 0 | 1
 *RST: 1

Example: CALC:MARK:LOEX ON

Manual operation: See "Exclude LO" on page 443

CALCulate<n>:MARKer<m>:PEXCursion <Excursion>

This command defines the peak excursion (for *all* markers in *all* windows; <m>, <n> are irrelevant).

The peak excursion sets the requirements for a peak to be detected during a peak search.

The unit depends on the measurement.

Application/Result display	Unit
Spectrum	dB

Parameters:

<Excursion> The excursion is the distance to a trace maximum that must be attained before a new maximum is recognized, or the distance to a trace minimum that must be attained before a new minimum is recognized
 *RST: 6 dB in the Spectrum application and RF displays

Example: CALC:MARK:PEXC 10dB
 Defines peak excursion as 10 dB.

Manual operation: See "Peak Excursion" on page 444

CALCulate<n>:MARKer<m>:X:SLIMits[:STATe] <State>

This command turns marker search limits on and off for *all* markers in *all* windows (<m>, <n> are irrelevant).

If you perform a measurement in the time domain, this command limits the range of the trace to be analyzed.

Parameters:

<State> ON | OFF
*RST: OFF

Example:

CALC:MARK:X:SLIM ON
Switches on search limitation.

Manual operation: See ["Search Limits \(Left / Right\)"](#) on page 194
See ["Deactivating All Search Limits"](#) on page 195
See ["Limit State"](#) on page 269

CALCulate<n>:MARKer<m>:X:SLIMits:LEFT <SearchLimit>

This command defines the left limit of the marker search range for *all* markers in *all* windows (<m>, <n> are irrelevant).

If you perform a measurement in the time domain, this command limits the range of the trace to be analyzed.

Parameters:

<SearchLimit> The value range depends on the frequency range or sweep time.
The unit is Hz for frequency domain measurements and s for time domain measurements.
*RST: left diagram border

Example:

CALC:MARK:X:SLIM ON
Switches the search limit function on.
CALC:MARK:X:SLIM:LEFT 10MHz
Sets the left limit of the search range to 10 MHz.

Manual operation: See ["Search Limits \(Left / Right\)"](#) on page 194
See ["Left Limit / Right Limit"](#) on page 270

CALCulate<n>:MARKer<m>:X:SLIMits:RIGHT <SearchLimit>

This command defines the right limit of the marker search range for *all* markers in *all* windows (<m>, <n> are irrelevant).

If you perform a measurement in the time domain, this command limits the range of the trace to be analyzed.

Parameters:

<Limit> The value range depends on the frequency range or sweep time.
The unit is Hz for frequency domain measurements and s for time domain measurements.
*RST: right diagram border

Example: `CALC:MARK:X:SLIM ON`
 Switches the search limit function on.
`CALC:MARK:X:SLIM:RIGH 20MHz`
 Sets the right limit of the search range to 20 MHz.

Manual operation: See "[Search Limits \(Left / Right\)](#)" on page 194
 See "[Left Limit / Right Limit](#)" on page 270

CALCulate<n>:MARKer<m>:X:SLIMits:ZOOM[:STATe] <State>

This command adjusts the marker search range to the zoom area for *all* markers in *all* windows (<m>, <n> are irrelevant).

Parameters:

<State> ON | OFF
 *RST: OFF

Example: `CALC:MARK:X:SLIM:ZOOM ON`
 Switches the search limit function on.
`CALC:MARK:X:SLIM:RIGH 20MHz`
 Sets the right limit of the search range to 20 MHz.

Manual operation: See "[Using Zoom Limits](#)" on page 444

CALCulate<n>:THReshold <Level>

This command defines a threshold level for the marker peak search (for *all* markers in *all* windows; <n> is irrelevant).

Parameters:

<Level> Numeric value. The value range and unit are variable.
 *RST: -120 dBm

Example: `CALC:THR -82DBM`
 Sets the threshold value to -82 dBm.

Manual operation: See "[Search Threshold](#)" on page 444

CALCulate<n>:THReshold:STATe <State>

This command turns a threshold for the marker peak search on and off (for *all* markers in *all* windows; <n> is irrelevant).

Parameters:

<State> ON | OFF
 *RST: OFF

Example: `CALC:THR:STAT ON`
 Switches on the threshold line.

Manual operation: See "[Deactivating All Search Limits](#)" on page 195

11.8.3.4 Positioning the Marker

This chapter contains remote commands necessary to position the marker on a trace.

- [Positioning Normal Markers](#) 828
- [Positioning Delta Markers](#)..... 830

Positioning Normal Markers

The following commands position markers on the trace.

CALCulate<n>:MARKer<m>:MAXimum:AUTO	828
CALCulate<n>:MARKer<m>:MAXimum:LEFT	828
CALCulate<n>:MARKer<m>:MAXimum:NEXT	828
CALCulate<n>:MARKer<m>:MAXimum[:PEAK]	829
CALCulate<n>:MARKer<m>:MAXimum:RIGHT	829
CALCulate<n>:MARKer<m>:MINimum:AUTO	829
CALCulate<n>:MARKer<m>:MINimum:LEFT	829
CALCulate<n>:MARKer<m>:MINimum:NEXT	830
CALCulate<n>:MARKer<m>:MINimum[:PEAK]	830
CALCulate<n>:MARKer<m>:MINimum:RIGHT	830

CALCulate<n>:MARKer<m>:MAXimum:AUTO <State>

This command turns an automatic marker peak search for a trace maximum on and off. The R&S FPS performs the peak search after each sweep.

Parameters:

<State> ON | OFF
 *RST: OFF

Example:

CALC:MARK:MAX:AUTO ON
 Activates the automatic peak search function for marker 1 at the end of each particular sweep.

Manual operation: See "[Auto Max / Min Peak Search](#)" on page 444

CALCulate<n>:MARKer<m>:MAXimum:LEFT

This command moves a marker to the next lower peak.

The search includes only measurement values to the left of the current marker position.

In the spectrogram, the command moves a marker horizontally to the maximum level in the currently selected frame. The vertical marker position remains the same.

Usage: Event

CALCulate<n>:MARKer<m>:MAXimum:NEXT

This command moves a marker to the next lower peak.

In the spectrogram, the command moves a marker horizontally to the maximum level in the currently selected frame. The vertical marker position remains the same.

Usage: Event

Manual operation: See "[Search Next Peak](#)" on page 449

CALCulate<n>:MARKer<m>:MAXimum[:PEAK]

This command moves a marker to the highest level.

In the spectrogram, the command moves a marker horizontally to the maximum level in the currently selected frame. The vertical marker position remains the same.

If the marker is not yet active, the command first activates the marker.

Usage: Event

Manual operation: See "[Marker Search Type](#)" on page 446
See "[Peak Search](#)" on page 449

CALCulate<n>:MARKer<m>:MAXimum:RIGHT

This command moves a marker to the next lower peak.

The search includes only measurement values to the right of the current marker position.

In the spectrogram, the command moves a marker horizontally to the maximum level in the currently selected frame. The vertical marker position remains the same.

Usage: Event

CALCulate<n>:MARKer<m>:MINimum:AUTO <State>

This command turns an automatic marker peak search for a trace minimum on and off. The R&S FPS performs the peak search after each sweep.

Parameters:

<State> ON | OFF
*RST: OFF

Example: `CALC:MARK:MIN:AUTO ON`
Activates the automatic minimum value search function for marker 1 at the end of each particular sweep.

Manual operation: See "[Auto Max / Min Peak Search](#)" on page 444

CALCulate<n>:MARKer<m>:MINimum:LEFT

This command moves a marker to the next minimum value.

The search includes only measurement values to the right of the current marker position.

In the spectrogram, the command moves a marker horizontally to the minimum level in the currently selected frame. The vertical marker position remains the same.

Usage: Event

CALCulate<n>:MARKer<m>:MINimum:NEXT

This command moves a marker to the next minimum value.

In the spectrogram, the command moves a marker horizontally to the minimum level in the currently selected frame. The vertical marker position remains the same.

Usage: Event

Manual operation: See ["Search Next Minimum"](#) on page 449

CALCulate<n>:MARKer<m>:MINimum[:PEAK]

This command moves a marker to the minimum level.

In the spectrogram, the command moves a marker horizontally to the minimum level in the currently selected frame. The vertical marker position remains the same.

If the marker is not yet active, the command first activates the marker.

Usage: Event

Manual operation: See ["Marker Search Type"](#) on page 446
See ["Search Minimum"](#) on page 449

CALCulate<n>:MARKer<m>:MINimum:RIGHT

This command moves a marker to the next minimum value.

The search includes only measurement values to the right of the current marker position.

In the spectrogram, the command moves a marker horizontally to the minimum level in the currently selected frame. The vertical marker position remains the same.

Usage: Event

Positioning Delta Markers

The following commands position delta markers on the trace.

CALCulate<n>:DELTamarker<m>:MAXimum:LEFT	831
CALCulate<n>:DELTamarker<m>:MAXimum:NEXT	831
CALCulate<n>:DELTamarker<m>:MAXimum[:PEAK]	831
CALCulate<n>:DELTamarker<m>:MAXimum:RIGHT	831
CALCulate<n>:DELTamarker<m>:MINimum:LEFT	831
CALCulate<n>:DELTamarker<m>:MINimum:NEXT	832
CALCulate<n>:DELTamarker<m>:MINimum[:PEAK]	832
CALCulate<n>:DELTamarker<m>:MINimum:RIGHT	832

CALCulate<n>:DELTaMarker<m>:MAXimum:LEFT

This command moves a delta marker to the next higher value.

The search includes only measurement values to the left of the current marker position.

In the spectrogram, the command moves a marker horizontally to the maximum level in the currently selected frame. The vertical marker position remains the same.

Usage: Event

CALCulate<n>:DELTaMarker<m>:MAXimum:NEXT

This command moves a marker to the next higher value.

In the spectrogram, the command moves a marker horizontally to the maximum level in the currently selected frame. The vertical marker position remains the same.

Usage: Event

Manual operation: See ["Search Next Peak"](#) on page 449

CALCulate<n>:DELTaMarker<m>:MAXimum[:PEAK]

This command moves a delta marker to the highest level.

In the spectrogram, the command moves a marker horizontally to the maximum level in the currently selected frame. The vertical marker position remains the same.

If the marker is not yet active, the command first activates the marker.

Usage: Event

Manual operation: See ["Marker Search Type"](#) on page 446

See ["Peak Search"](#) on page 449

CALCulate<n>:DELTaMarker<m>:MAXimum:RIGHT

This command moves a delta marker to the next higher value.

The search includes only measurement values to the right of the current marker position.

In the spectrogram, the command moves a marker horizontally to the maximum level in the currently selected frame. The vertical marker position remains the same.

Usage: Event

CALCulate<n>:DELTaMarker<m>:MINimum:LEFT

This command moves a delta marker to the next higher minimum value.

The search includes only measurement values to the right of the current marker position.

In the spectrogram, the command moves a marker horizontally to the minimum level in the currently selected frame. The vertical marker position remains the same.

Usage: Event

CALCulate<n>:DELTaMarker<m>:MINimum:NEXT

This command moves a marker to the next higher minimum value.

In the spectrogram, the command moves a marker horizontally to the minimum level in the currently selected frame. The vertical marker position remains the same.

Usage: Event

Manual operation: See "[Search Next Minimum](#)" on page 449

CALCulate<n>:DELTaMarker<m>:MINimum[:PEAK]

This command moves a delta marker to the minimum level.

In the spectrogram, the command moves a marker horizontally to the minimum level in the currently selected frame. The vertical marker position remains the same.

If the marker is not yet active, the command first activates the marker.

Usage: Event

Manual operation: See "[Marker Search Type](#)" on page 446
See "[Search Minimum](#)" on page 449

CALCulate<n>:DELTaMarker<m>:MINimum:RIGHT

This command moves a delta marker to the next higher minimum value.

The search includes only measurement values to the right of the current marker position.

In the spectrogram, the command moves a marker horizontally to the minimum level in the currently selected frame. The vertical marker position remains the same.

Usage: Event

11.8.3.5 Retrieving Marker Results

The following commands are used to retrieve the results of markers.



You can use the marker values to position the center frequency or reference level directly using the following commands:

- [CALCulate<n>:MARKer<m>:FUNction:CENTer](#) on page 741
- [CALCulate<n>:MARKer<m>:FUNction:REFerence](#) on page 755

Useful commands for retrieving results described elsewhere:

- `CALCulate<n>:DELTaMarker<m>:X` on page 822
- `CALCulate<n>:MARKer<m>:X` on page 823
- `CALCulate<n>:MARKer<m>:FUNCTION:FPEaks:COUNT?` on page 845
- `CALCulate<n>:MARKer<m>:FUNCTION:FPEaks:X?` on page 847
- `CALCulate<n>:MARKer<m>:FUNCTION:FPEaks:Y?` on page 847
- `CALCulate<n>:MARKer<m>:FUNCTION:NOISE:RESult?` on page 848
- `CALCulate<n>:DELTaMarker<m>:FUNCTION:PNOise:RESult?` on page 849
- `CALCulate<n>:DELTaMarker<m>:FUNCTION:BPOwer:RESult?` on page 852
- `CALCulate<n>:MARKer<m>:FUNCTION:BPOwer:RESult?` on page 851
- `CALCulate<n>:MARKer<m>:FUNCTION:NDBDown:RESult?` on page 854
- `CALCulate<n>:MARKer<m>:FUNCTION:NDBDown:FREQuency?` on page 853
- `CALCulate<n>:MARKer<m>:FUNCTION:NDBDown:QFACTOR?` on page 854
- `CALCulate<n>:MARKer<m>:COUNT:FREQuency?` on page 856

Remote commands exclusive to retrieving marker results

<code>CALCulate<n>:DELTaMarker<m>:X:RELative?</code>	833
<code>CALCulate<n>:DELTaMarker<m>:Y?</code>	833
<code>CALCulate<n>:MARKer<m>:Y?</code>	834

`CALCulate<n>:DELTaMarker<m>:X:RELative?`

This command queries the relative position of a delta marker on the x-axis.

If necessary, the command activates the delta marker first.

Return values:

<Position> Position of the delta marker in relation to the reference marker.

Example:

`CALC:DELT3:X:REL?`

Outputs the frequency of delta marker 3 relative to marker 1 or relative to the reference position.

Usage:

Query only

Manual operation:

See "[Marker 1/2/3/4](#)" on page 284

See "[Marker 1/2/3](#)" on page 289

`CALCulate<n>:DELTaMarker<m>:Y?`

This command queries the relative position of a delta marker on the y-axis.

If necessary, the command activates the delta marker first.

To get a valid result, you have to perform a complete measurement with synchronization to the end of the measurement before reading out the result. This is only possible for single sweep mode.

See also `INITiate<n>:CONTInuous` on page 605.

The unit depends on the application of the command.

Table 11-8: Base unit

Parameter, measuring function or result display	Output unit
DBM DBPW DBUV DBMV DBUA	dB (lin/log)
WATT VOLT AMPere	dB (lin), % (log)
statistics function (APD or CCDF) on	dimensionless output

Return values:

<Position> Position of the delta marker in relation to the reference marker or the fixed reference.

Example:

```
INIT:CONT OFF
Switches to single sweep mode.
INIT;*WAI
Starts a sweep and waits for its end.
CALC:DELT2 ON
Switches on delta marker 2.
CALC:DELT2:Y?
Outputs measurement value of delta marker 2.
```

Usage: Query only

CALCulate<n>:MARKer<m>:Y?

This command queries the position of a marker on the y-axis.

If necessary, the command activates the marker first.

To get a valid result, you have to perform a complete measurement with synchronization to the end of the measurement before reading out the result. This is only possible for single sweep mode.

See also `INITiate<n>:CONTInuous` on page 605.

Return values:

<Result> Result at the marker position.
The unit is variable and depends on the one you have currently set.

Example: INIT:CONT OFF
Switches to single measurement mode.
CALC:MARK2 ON
Switches marker 2.
INIT;*WAI
Starts a measurement and waits for the end.
CALC:MARK2:Y?
Outputs the measured value of marker 2.

Usage: Query only

Manual operation: See "Marker Table" on page 386
See "Marker Peak List" on page 386

11.8.3.6 Marker Search (Spectrograms)

The following commands automatically define the marker and delta marker position in the spectrogram.



The usage of these markers is demonstrated in [chapter 11.8.2.6, "Programming Example: Configuring a Spectrogram"](#), on page 816.

Using Markers

The following commands control spectrogram markers.

Useful commands for spectrogram markers described elsewhere

The following commands define the horizontal position of the markers.

- [CALCulate<n>:MARKer<m>:MAXimum:LEFT](#) on page 828
- [CALCulate<n>:MARKer<m>:MAXimum:NEXT](#) on page 828
- [CALCulate<n>:MARKer<m>:MAXimum\[:PEAK\]](#) on page 829
- [CALCulate<n>:MARKer<m>:MAXimum:RIGHT](#) on page 829
- [CALCulate<n>:MARKer<m>:MINimum:LEFT](#) on page 829
- [CALCulate<n>:MARKer<m>:MINimum:NEXT](#) on page 830
- [CALCulate<n>:MARKer<m>:MINimum\[:PEAK\]](#) on page 830
- [CALCulate<n>:MARKer<m>:MINimum:RIGHT](#) on page 830

Remote commands exclusive to spectrogram markers

CALCulate<n>:MARKer<m>:SGRam:FRAME	836
CALCulate<n>:MARKer<m>:SPEctrogram:FRAME	836
CALCulate<n>:MARKer<m>:SGRam:SARea	836
CALCulate<n>:MARKer<m>:SPEctrogram:SARea	836
CALCulate<n>:MARKer<m>:SGRam:XY:MAXimum[:PEAK]	837
CALCulate<n>:MARKer<m>:SPEctrogram:XY:MAXimum[:PEAK]	837
CALCulate<n>:MARKer<m>:SGRam:XY:MINimum[:PEAK]	837
CALCulate<n>:MARKer<m>:SPEctrogram:XY:MINimum[:PEAK]	837

CALCulate<n>:MARKer<m>:SGRam:Y:MAXimum:ABOVE.....	837
CALCulate<n>:MARKer<m>:SPECTrogram:Y:MAXimum:ABOVE.....	837
CALCulate<n>:MARKer<m>:SGRam:Y:MAXimum:BELOW.....	837
CALCulate<n>:MARKer<m>:SPECTrogram:Y:MAXimum:BELOW.....	837
CALCulate<n>:MARKer<m>:SGRam:Y:MAXimum:NEXT.....	837
CALCulate<n>:MARKer<m>:SPECTrogram:Y:MAXimum:NEXT.....	837
CALCulate<n>:MARKer<m>:SGRam:Y:MAXimum[:PEAK].....	838
CALCulate<n>:MARKer<m>:SPECTrogram:Y:MAXimum[:PEAK].....	838
CALCulate<n>:MARKer<m>:SGRam:Y:MINimum:ABOVE.....	838
CALCulate<n>:MARKer<m>:SPECTrogram:Y:MINimum:ABOVE.....	838
CALCulate<n>:MARKer<m>:SGRam:Y:MINimum:BELOW.....	838
CALCulate<n>:MARKer<m>:SPECTrogram:Y:MINimum:BELOW.....	838
CALCulate<n>:MARKer<m>:SGRam:Y:MINimum:NEXT.....	838
CALCulate<n>:MARKer<m>:SPECTrogram:Y:MINimum:NEXT.....	838
CALCulate<n>:MARKer<m>:SGRam:Y:MINimum[:PEAK].....	839
CALCulate<n>:MARKer<m>:SPECTrogram:Y:MINimum[:PEAK].....	839

CALCulate<n>:MARKer<m>:SGRam:FRAME <Frame> | <Time>

CALCulate<n>:MARKer<m>:SPECTrogram:FRAME <Frame> | <Time>

This command positions a marker on a particular frame.

Parameters:

<Frame>	Selects a frame directly by the frame number. Valid if the time stamp is off. The range depends on the history depth.
<Time>	Selects a frame via its time stamp. Valid if the time stamp is on. The number is the (negative) distance to frame 0 in seconds. The range depends on the history depth.

Example:

CALC:MARK:SGR:FRAM -20

Sets the marker on the 20th frame before the present.

CALC:MARK2:SGR:FRAM -2s

Sets second marker on the frame 2 seconds ago.

Manual operation: See "[Frame \(Spectrogram only\)](#)" on page 438

CALCulate<n>:MARKer<m>:SGRam:SAREa <SearchArea>

CALCulate<n>:MARKer<m>:SPECTrogram:SAREa <SearchArea>

This command defines the marker search area for all spectrogram markers in the measurement channel (<n>, <m> are irrelevant).

Parameters:

<SearchArea>	VISible Performs a search within the visible frames. Note that the command does not work if the spectrogram is not visible for any reason (e.g. if the display update is off).
	MEMory Performs a search within all frames in the memory.
*RST:	VISible

Manual operation: See ["Marker Search Area"](#) on page 447

**CALCulate<n>:MARKer<m>:SGRam:XY:MAXimum[:PEAK]
CALCulate<n>:MARKer<m>:SPECTrogram:XY:MAXimum[:PEAK]**

This command moves a marker to the highest level of the spectrogram.

Usage: Event

Manual operation: See ["Marker Search Type"](#) on page 446

**CALCulate<n>:MARKer<m>:SGRam:XY:MINimum[:PEAK]
CALCulate<n>:MARKer<m>:SPECTrogram:XY:MINimum[:PEAK]**

This command moves a marker to the minimum level of the spectrogram.

Usage: Event

Manual operation: See ["Marker Search Type"](#) on page 446

**CALCulate<n>:MARKer<m>:SGRam:Y:MAXimum:ABOVE
CALCulate<n>:MARKer<m>:SPECTrogram:Y:MAXimum:ABOVE**

This command moves a marker vertically to the next lower peak level for the current frequency.

The search includes only frames above the current marker position. It does not change the horizontal position of the marker.

Usage: Event

Manual operation: See ["Search Mode for Next Peak in Y Direction"](#) on page 446

**CALCulate<n>:MARKer<m>:SGRam:Y:MAXimum:BELOW
CALCulate<n>:MARKer<m>:SPECTrogram:Y:MAXimum:BELOW**

This command moves a marker vertically to the next lower peak level for the current frequency.

The search includes only frames below the current marker position. It does not change the horizontal position of the marker.

Usage: Event

Manual operation: See ["Search Mode for Next Peak in Y Direction"](#) on page 446

**CALCulate<n>:MARKer<m>:SGRam:Y:MAXimum:NEXT
CALCulate<n>:MARKer<m>:SPECTrogram:Y:MAXimum:NEXT**

This command moves a marker vertically to the next lower peak level for the current frequency.

The search includes all frames. It does not change the horizontal position of the marker.

Usage: Event

Manual operation: See ["Search Mode for Next Peak in Y Direction"](#) on page 446

CALCulate<n>:MARKer<m>:SGRam:Y:MAXimum[:PEAK]

CALCulate<n>:MARKer<m>:SPECTrogram:Y:MAXimum[:PEAK]

This command moves a marker vertically to the highest level for the current frequency.

The search includes all frames. It does not change the horizontal position of the marker.

If the marker hasn't been active yet, the command looks for the peak level in the whole spectrogram.

Usage: Event

Manual operation: See ["Marker Search Type"](#) on page 446

CALCulate<n>:MARKer<m>:SGRam:Y:MINimum:ABOVE

CALCulate<n>:MARKer<m>:SPECTrogram:Y:MINimum:ABOVE

This command moves a marker vertically to the next higher minimum level for the current frequency.

The search includes only frames above the current marker position. It does not change the horizontal position of the marker.

Usage: Event

Manual operation: See ["Search Mode for Next Peak in Y Direction"](#) on page 446

CALCulate<n>:MARKer<m>:SGRam:Y:MINimum:BELOW

CALCulate<n>:MARKer<m>:SPECTrogram:Y:MINimum:BELOW

This command moves a marker vertically to the next higher minimum level for the current frequency.

The search includes only frames below the current marker position. It does not change the horizontal position of the marker.

Usage: Event

Manual operation: See ["Search Mode for Next Peak in Y Direction"](#) on page 446

CALCulate<n>:MARKer<m>:SGRam:Y:MINimum:NEXT

CALCulate<n>:MARKer<m>:SPECTrogram:Y:MINimum:NEXT

This command moves a marker vertically to the next higher minimum level for the current frequency.

The search includes all frames. It does not change the horizontal position of the marker.

Usage: Event

Manual operation: See ["Search Mode for Next Peak in Y Direction"](#) on page 446

CALCulate<n>:MARKer<m>:SGRam:Y:MINimum[:PEAK]

CALCulate<n>:MARKer<m>:SPECTrogram:Y:MINimum[:PEAK]

This command moves a marker vertically to the minimum level for the current frequency.

The search includes all frames. It does not change the horizontal position of the marker.

If the marker hasn't been active yet, the command first looks for the peak level for all frequencies and moves the marker vertically to the minimum level.

Usage: Event

Manual operation: See ["Marker Search Type"](#) on page 446

Using Delta Markers

The following commands control spectrogram delta markers.

Useful commands for spectrogram markers described elsewhere

The following commands define the horizontal position of the delta markers.

- [CALCulate<n>:DELTaMarker<m>:MAXimum:LEFT](#) on page 831
- [CALCulate<n>:DELTaMarker<m>:MAXimum:NEXT](#) on page 831
- [CALCulate<n>:DELTaMarker<m>:MAXimum\[:PEAK\]](#) on page 831
- [CALCulate<n>:DELTaMarker<m>:MAXimum:RIGHT](#) on page 831
- [CALCulate<n>:DELTaMarker<m>:MINimum:LEFT](#) on page 831
- [CALCulate<n>:DELTaMarker<m>:MINimum:NEXT](#) on page 832
- [CALCulate<n>:DELTaMarker<m>:MINimum\[:PEAK\]](#) on page 832
- [CALCulate<n>:DELTaMarker<m>:MINimum:RIGHT](#) on page 832

Remote commands exclusive to spectrogram markers

CALCulate<n>:DELTaMarker<m>:SGRam:FRAMe	840
CALCulate<n>:DELTaMarker<m>:SPECTrogram:FRAMe	840
CALCulate<n>:DELTaMarker<m>:SGRam:SARea	840
CALCulate<n>:DELTaMarker<m>:SPECTrogram:SARea	840
CALCulate<n>:DELTaMarker<m>:SGRam:XY:MAXimum[:PEAK]	841
CALCulate<n>:DELTaMarker<m>:SPECTrogram:XY:MAXimum[:PEAK]	841
CALCulate<n>:DELTaMarker<m>:SGRam:XY:MINimum[:PEAK]	841
CALCulate<n>:DELTaMarker<m>:SPECTrogram:XY:MINimum[:PEAK]	841
CALCulate<n>:DELTaMarker<m>:SGRam:Y:MAXimum:ABOVe	841
CALCulate<n>:DELTaMarker<m>:SPECTrogram:Y:MAXimum:ABOVe	841
CALCulate<n>:DELTaMarker<m>:SGRam:Y:MAXimum:BELow	841
CALCulate<n>:DELTaMarker<m>:SPECTrogram:Y:MAXimum:BELow	841
CALCulate<n>:DELTaMarker<m>:SGRam:Y:MAXimum:NEXT	841
CALCulate<n>:DELTaMarker<m>:SPECTrogram:Y:MAXimum:NEXT	841

CALCulate<n>:DELTamarker<m>:SGRam:Y:MAXimum[:PEAK].....	842
CALCulate<n>:DELTamarker<m>:SPECTrogram:Y:MAXimum[:PEAK].....	842
CALCulate<n>:DELTamarker<m>:SGRam:Y:MINimum:ABOVE.....	842
CALCulate<n>:DELTamarker<m>:SPECTrogram:Y:MINimum:ABOVE.....	842
CALCulate<n>:DELTamarker<m>:SGRam:Y:MINimum:BELOW.....	842
CALCulate<n>:DELTamarker<m>:SPECTrogram:Y:MINimum:BELOW.....	842
CALCulate<n>:DELTamarker<m>:SGRam:Y:MINimum:NEXT.....	842
CALCulate<n>:DELTamarker<m>:SPECTrogram:Y:MINimum:NEXT.....	842
CALCulate<n>:DELTamarker<m>:SGRam:Y:MINimum[:PEAK].....	843
CALCulate<n>:DELTamarker<m>:SPECTrogram:Y:MINimum[:PEAK].....	843

CALCulate<n>:DELTamarker<m>:SGRam:FRAME <Frame> | <Time>

CALCulate<n>:DELTamarker<m>:SPECTrogram:FRAME <Frame> | <Time>

This command positions a delta marker on a particular frame. The frame is relative to the position of marker 1.

The command is available for the spectrogram.

Parameters:

<Frame>	Selects a frame directly by the frame number. Valid if the time stamp is off. The range depends on the history depth.
<Time>	Selects a frame via its time stamp. Valid if the time stamp is on. The number is the distance to frame 0 in seconds. The range depends on the history depth.

Example:

`CALC:DELT4:SGR:FRAM -20`

Sets fourth deltamarker 20 frames below marker 1.

`CALC:DELT4:SGR:FRAM 2 s`

Sets fourth deltamarker 2 seconds above the position of marker 1.

Manual operation: See "[Frame \(Spectrogram only\)](#)" on page 438

CALCulate<n>:DELTamarker<m>:SGRam:SARea <SearchArea>

CALCulate<n>:DELTamarker<m>:SPECTrogram:SARea <SearchArea>

This command defines the marker search area for *all* spectrogram markers in the measurement channel (<n> and <m> are irrelevant).

Parameters:

<SearchArea>	VISible Performs a search within the visible frames. Note that the command does not work if the spectrogram is not visible for any reason (e.g. if the display update is off).
	MEMory Performs a search within all frames in the memory.
	*RST: VISible

Manual operation: See "[Marker Search Area](#)" on page 447

CALCulate<n>:DELTamarker<m>:SGRam:XY:MAXimum[:PEAK]
CALCulate<n>:DELTamarker<m>:SPECtrogram:XY:MAXimum[:PEAK]

This command moves a marker to the highest level of the spectrogram over all frequencies.

Usage: Event

Manual operation: See "[Marker Search Type](#)" on page 446

CALCulate<n>:DELTamarker<m>:SGRam:XY:MINimum[:PEAK]
CALCulate<n>:DELTamarker<m>:SPECtrogram:XY:MINimum[:PEAK]

This command moves a delta marker to the minimum level of the spectrogram over all frequencies.

Usage: Event

Manual operation: See "[Marker Search Type](#)" on page 446

CALCulate<n>:DELTamarker<m>:SGRam:Y:MAXimum:ABOVE
CALCulate<n>:DELTamarker<m>:SPECtrogram:Y:MAXimum:ABOVE

This command moves a marker vertically to the next higher level for the current frequency.

The search includes only frames above the current marker position. It does not change the horizontal position of the marker.

Usage: Event

Manual operation: See "[Search Mode for Next Peak in Y Direction](#)" on page 446

CALCulate<n>:DELTamarker<m>:SGRam:Y:MAXimum:BELOW
CALCulate<n>:DELTamarker<m>:SPECtrogram:Y:MAXimum:BELOW

This command moves a marker vertically to the next higher level for the current frequency.

The search includes only frames below the current marker position. It does not change the horizontal position of the marker.

Usage: Event

Manual operation: See "[Search Mode for Next Peak in Y Direction](#)" on page 446

CALCulate<n>:DELTamarker<m>:SGRam:Y:MAXimum:NEXT
CALCulate<n>:DELTamarker<m>:SPECtrogram:Y:MAXimum:NEXT

This command moves a delta marker vertically to the next higher level for the current frequency.

The search includes all frames. It does not change the horizontal position of the marker.

Usage: Event

Manual operation: See ["Search Mode for Next Peak in Y Direction"](#) on page 446

CALCulate<n>:DELTamarker<m>:SGRam:Y:MAXimum[:PEAK]

CALCulate<n>:DELTamarker<m>:SPECTrogram:Y:MAXimum[:PEAK]

This command moves a delta marker vertically to the highest level for the current frequency.

The search includes all frames. It does not change the horizontal position of the marker.

If the marker hasn't been active yet, the command looks for the peak level in the whole spectrogram.

Usage: Event

Manual operation: See ["Marker Search Type"](#) on page 446

CALCulate<n>:DELTamarker<m>:SGRam:Y:MINimum:ABOVE

CALCulate<n>:DELTamarker<m>:SPECTrogram:Y:MINimum:ABOVE

This command moves a delta marker vertically to the next minimum level for the current frequency.

The search includes only frames above the current marker position. It does not change the horizontal position of the marker.

Usage: Event

Manual operation: See ["Search Mode for Next Peak in Y Direction"](#) on page 446

CALCulate<n>:DELTamarker<m>:SGRam:Y:MINimum:BELOW

CALCulate<n>:DELTamarker<m>:SPECTrogram:Y:MINimum:BELOW

This command moves a delta marker vertically to the next minimum level for the current frequency.

The search includes only frames below the current marker position. It does not change the horizontal position of the marker.

Usage: Event

Manual operation: See ["Search Mode for Next Peak in Y Direction"](#) on page 446

CALCulate<n>:DELTamarker<m>:SGRam:Y:MINimum:NEXT

CALCulate<n>:DELTamarker<m>:SPECTrogram:Y:MINimum:NEXT

This command moves a delta marker vertically to the next minimum level for the current frequency.

The search includes all frames. It does not change the horizontal position of the marker.

Usage: Event

Manual operation: See ["Search Mode for Next Peak in Y Direction"](#) on page 446

CALCulate<n>:DELTamarker<m>:SGRam:Y:MINimum[:PEAK]

CALCulate<n>:DELTamarker<m>:SPECTrogram:Y:MINimum[:PEAK]

This command moves a delta marker vertically to the minimum level for the current frequency.

The search includes all frames. It does not change the horizontal position of the marker.

If the marker hasn't been active yet, the command first looks for the peak level in the whole spectrogram and moves the marker vertically to the minimum level.

Usage: Event

Manual operation: See ["Marker Search Type"](#) on page 446

11.8.3.7 Fixed Reference Marker Settings

The following commands configure a fixed reference marker.

CALCulate<n>:DELTamarker<m>:FUNCTION:FIXed:RPOint:MAXimum[:PEAK].....	843
CALCulate<n>:DELTamarker<m>:FUNCTION:FIXed:RPOint:X.....	843
CALCulate<n>:DELTamarker<m>:FUNCTION:FIXed:RPOint:Y.....	844
CALCulate<n>:DELTamarker<m>:FUNCTION:FIXed:RPOint:Y:OFFSet.....	844
CALCulate<n>:DELTamarker<m>:FUNCTION:FIXed[:STATe].....	844

CALCulate<n>:DELTamarker<m>:FUNCTION:FIXed:RPOint:MAXimum[:PEAK]

This command moves the fixed reference marker to the peak power.

Example: `CALC:DELT:FUNC:FIX:RPO:MAX`
Sets the reference point level for delta markers to the peak of the selected trace.

Usage: Event

Manual operation: See ["Defining a Fixed Reference"](#) on page 441
See ["Defining a Reference Point"](#) on page 454

CALCulate<n>:DELTamarker<m>:FUNCTION:FIXed:RPOint:X <RefPoint>

This command defines the horizontal position of the fixed delta marker reference point. The coordinates of the reference may be anywhere in the diagram.

Parameters:

<RefPoint> Numeric value that defines the horizontal position of the reference.
 For frequency domain measurements, it is a frequency in Hz.
 For time domain measurements, it is a point in time in s.
 *RST: Fixed Reference: OFF

Example:

CALC:DELT:FUNC:FIX:RPO:X 128 MHz
 Sets the frequency reference to 128 MHz.

Manual operation:

See ["Defining a Fixed Reference"](#) on page 441
 See ["Defining a Reference Point"](#) on page 454

CALCulate<n>:DELTaMarker<m>:FUNCTION:FIXed:RPOint:Y <RefPointLevel>

This command defines the vertical position of the fixed delta marker reference point. The coordinates of the reference may be anywhere in the diagram.

Parameters:

<RefPoint> Numeric value that defines the vertical position of the reference. The unit and value range is variable.
 *RST: Fixed Reference: OFF

Example:

CALC:DELT:FUNC:FIX:RPO:Y -10dBm
 Sets the reference point level for delta markers to -10 dBm.

Manual operation:

See ["Defining a Fixed Reference"](#) on page 441
 See ["Defining a Reference Point"](#) on page 454

CALCulate<n>:DELTaMarker<m>:FUNCTION:FIXed:RPOint:Y:OFFSet <Offset>

This command defines a level offset for the fixed delta marker reference point.

Parameters:

<Offset> Numeric value
 *RST: 0
 Default unit: dB

CALCulate<n>:DELTaMarker<m>:FUNCTION:FIXed[:STATe] <State>

This command activates or deactivates a marker that defines a fixed reference point for relative marker analysis.

If necessary, the command activates a marker and positions it on the peak power.

Subsequently, you can change the coordinates of the fixed reference independent of the marker. The fixed reference is independent of the trace and is applied to all active delta markers.

Parameters:

<State> ON | OFF
 *RST: OFF

- Example:** `CALC:DELT:FUNC:FIX ON`
 Switches on the measurement with fixed reference value for all delta markers.
`CALC:DELT:FUNC:FIX:RPO:X 128 MHZ`
 Sets the frequency reference to 128 MHz.
`CALC:DELT:FUNC:FIX:RPO:Y 30 DBM`
 Sets the reference level to +30 dBm.
- Manual operation:** See ["Defining a Fixed Reference"](#) on page 441

11.8.3.8 Marker Peak Lists

Useful commands for peak lists described elsewhere

- `CALCulate<n>:MARKer<m>:PEXCursion` on page 825
- `MMEMoRY:STORe<n>:PEAK` on page 903
- [chapter 11.8.3.3, "Configuring and Performing a Marker Search"](#), on page 824

Remote commands exclusive to peak lists

<code>CALCulate<n>:MARKer<m>:FUNCTION:FPEaks:ANNOtation:LABel[:STATe]</code>	845
<code>CALCulate<n>:MARKer<m>:FUNCTION:FPEaks:COUNT?</code>	845
<code>CALCulate<n>:MARKer<m>:FUNCTION:FPEaks[:IMMEDIATE]</code>	846
<code>CALCulate<n>:MARKer<m>:FUNCTION:FPEaks:LIST:SIZE</code>	846
<code>CALCulate<n>:MARKer<m>:FUNCTION:FPEaks:SORT</code>	846
<code>CALCulate<n>:MARKer<m>:FUNCTION:FPEaks:STATe</code>	847
<code>CALCulate<n>:MARKer<m>:FUNCTION:FPEaks:X?</code>	847
<code>CALCulate<n>:MARKer<m>:FUNCTION:FPEaks:Y?</code>	847

`CALCulate<n>:MARKer<m>:FUNCTION:FPEaks:ANNOtation:LABel[:STATe]` `<State>`

This command turns labels for peaks found during a peak search on and off.

The labels correspond to the marker number in the marker peak list.

Parameters:

`<State>` `ON | OFF | 0 | 1`
`*RST:` `1`

- Example:** `CALC:MARK:FUNC:FPE:ANN:LAB:STAT OFF`
 Removes the peak labels from the diagram

Manual operation: See ["Displaying Marker Numbers"](#) on page 460

`CALCulate<n>:MARKer<m>:FUNCTION:FPEaks:COUNT?`

This command queries the number of peaks that have been found during a peak search.

The actual number of peaks that have been found may differ from the number of peaks you have set to be found because of the peak excursion.

(<n>, <m> are irrelevant.)

Return values:

<NumberOfPeaks>

Example:

`CALC:MARK:FUNC:FPE:COUN?`
Queries the number of peaks.

Usage:

Query only

CALCulate<n>:MARKer<m>:FUNction:FPEaks[:IMMediate] <Peaks>

This command initiates a peak search.

Parameters:

<Peaks> This parameter defines the number of peaks to find during the search.
Note that the actual number of peaks found during the search also depends on the peak excursion you have set with [CALCulate<n>:MARKer<m>:PEXCursion](#).
Range: 1 to 200

Example:

`CALC:MARK:PEXC 5`
Defines a peak excursion of 5 dB, i.e. peaks must be at least 5 dB apart to be detected as a peak.
`CALC:MARK:FUNC:FPE 10`
Initiates a search for 10 peaks on the current trace.

CALCulate<n>:MARKer<m>:FUNction:FPEaks:LIST:SIZE <MaxNoPeaks>

This command defines the maximum number of peaks that the R&S FPS looks for during a peak search.

Parameters:

<MaxNoPeaks> Maximum number of peaks to be determined.
Range: 1 to 200
*RST: 50

Example:

`CALC:MARK:FUNC:FPE:LIST:SIZE 10`
The marker peak list will contain a maximum of 10 peaks.

Manual operation:

See "[Maximum Number of Peaks](#)" on page 459

CALCulate<n>:MARKer<m>:FUNction:FPEaks:SORT <SortMode>

This command selects the order in which the results of a peak search are returned.

Parameters:

<SortMode> **X**
Sorts the peaks according to increasing position on the x-axis.

Y
Sorts the peaks according to decreasing position on the y-axis.

*RST: X

Example:

CALC:MARK:FUNC:FPE:SORT Y
Sets the sort mode to decreasing y values

Manual operation: See "[Sort Mode](#)" on page 459

CALCulate<n>:MARKer<m>:FUNction:FPEaks:STATe <State>

This command turns a peak search on and off.

Parameters:

<State> ON | OFF

*RST: OFF

Example:

CALC:MARK:FUNC:FPE:STAT ON
Activates marker peak search

Manual operation: See "[Peak List State](#)" on page 459

CALCulate<n>:MARKer<m>:FUNction:FPEaks:X?

This command queries the position of the peaks on the x-axis.

The order depends on the sort order that has been set with [CALCulate<n>:MARKer<m>:FUNction:FPEaks:SORT](#).

(<n>, <m> are irrelevant.)

Return values:

<PeakPosition> Position of the peaks on the x-axis. The unit depends on the measurement.

Usage: Query only

CALCulate<n>:MARKer<m>:FUNction:FPEaks:Y?

This command queries the position of the peaks on the y-axis.

The order depends on the sort order that has been set with [CALCulate<n>:MARKer<m>:FUNction:FPEaks:SORT](#).

(<n>, <m> are irrelevant.)

Return values:

<PeakPosition> Position of the peaks on the y-axis. The unit depends on the measurement.

Usage: Query only

11.8.3.9 Noise Measurement Marker

The following commands control the noise measurement marker function.

<code>CALCulate<n>:MARKer<m>:FUNCTION:NOISe:RESult?</code>	848
<code>CALCulate<n>:MARKer<m>:FUNCTION:NOISe[:STATe]</code>	848

CALCulate<n>:MARKer<m>:FUNCTION:NOISe:RESult?

This command queries the result of the noise measurement.

To get a valid result, you have to perform a complete measurement with synchronization to the end of the measurement before reading out the result. This is only possible for single sweep mode.

See also `INITiate<n>:CONTinuous` on page 605.

Return values:

<NoiseLevel> Current noise level. The unit is the one currently active.

Example:

```
INIT:CONT OFF
Switches to single sweep mode.
CALC:MARK2 ON
Switches on marker 2.
CALC:MARK:FUNC:NOIS ON
Switches on noise measurement.
INIT;*WAI
Starts a sweep and waits for the end.
CALC:MARK2:NOIS:RES?
Outputs the noise result of marker 2.
```

Usage: Query only

Manual operation: See "Noise Measurement State" on page 453

CALCulate<n>:MARKer<m>:FUNCTION:NOISe[:STATe] <State>

This command turns the noise measurement at the marker position on and off.

Parameters:

<State> ON | OFF
 *RST: OFF

Example:

```
CALC:MARK:FUNC:NOIS ON
Switches on the noise measurement.
```

Manual operation: See "Noise Measurement State" on page 453
 See "Switching All Noise Measurements Off" on page 453

11.8.3.10 Phase Noise Measurement Marker

The following commands control the phase noise measurement marker function.

Useful commands for phase noise markers described elsewhere

- `CALCulate<n>:DELTamarker<m>:FUNCTION:FIXed:RPOint:MAXimum[:PEAK]`
- `CALCulate<n>:DELTamarker<m>:FUNCTION:FIXed:RPOint:X`
- `CALCulate<n>:DELTamarker<m>:FUNCTION:FIXed:RPOint:Y`

Remote commands exclusive to phase noise markers

<code>CALCulate<n>:DELTamarker<m>:FUNCTION:PNOise:AUTO</code>	849
<code>CALCulate<n>:DELTamarker<m>:FUNCTION:PNOise:RESult?</code>	849
<code>CALCulate<n>:DELTamarker<m>:FUNCTION:PNOise[:STATe]</code>	849

CALCulate<n>:DELTamarker<m>:FUNCTION:PNOise:AUTO <State>

This command turns an automatic peak search for the fixed reference marker at the end of a sweep on and off.

Parameters:

<State> ON | OFF
 *RST: OFF

Example:

`CALC:DELT:FUNC:PNO:AUTO ON`

Activates an automatic peak search for the reference marker in a phase-noise measurement.

Manual operation: See "[Defining a Reference Point](#)" on page 454

CALCulate<n>:DELTamarker<m>:FUNCTION:PNOise:RESult?

This command queries the result of a phase noise measurement.

If necessary, the command activates the measurement first.

This command is only available in the Spectrum application.

Return values:

<PhaseNoise> numeric value
 The difference in level between the reference point and the noise power density at the position of the specified delta marker.

Example:

`CALC:DELT2:FUNC:PNO:RES?`

Outputs the result of phase-noise measurement of the delta-marker 2.

Usage:

Query only

Manual operation: See "[Phase Noise Measurement State](#)" on page 454

CALCulate<n>:DELTamarker<m>:FUNCTION:PNOise[:STATe] <State>

This command turns the phase noise measurement at the delta marker position on and off.

The reference marker for phase noise measurements is either a normal marker or a fixed reference. If necessary, the command turns on the reference marker.

The correction values for the bandwidth and the log amplifier are taken into account in the measurement.

Parameters:

<State> ON | OFF
*RST: OFF

Example:

```
CALC:DELT:FUNC:PNO ON
Switches on the phase-noise measurement with all delta markers.
CALC:DELT:FUNC:FIX:RPO:X 128 MHZ
Sets the frequency reference to 128 MHz.
CALC:DELT:FUNC:FIX:RPO:Y 30 DBM
Sets the reference level to +30 dBm
```

Manual operation: See ["Phase Noise Measurement State"](#) on page 454
See ["Switching All Phase Noise Measurements Off"](#) on page 455

11.8.3.11 Band Power Marker

The following commands control the marker for band power measurements.

Using Markers

CALCulate<n>:MARKer<m>:FUNctio:n:BPOWer:MODE	850
CALCulate<n>:MARKer<m>:FUNctio:n:BPOWer:RESult?	851
CALCulate<n>:MARKer<m>:FUNctio:n:BPOWer:SPAN	851
CALCulate<n>:MARKer<m>:FUNctio:n:BPOWer[:STATe]	851

CALCulate<n>:MARKer<m>:FUNctio:n:BPOWer:MODE <Mode>

This command selects the way the results for a band power marker are displayed.

Parameters:

<Mode> **POWER**
Result is displayed as a power in dBm.
DENSity
Result is displayed as a density in dBm/Hz.
*RST: POWER

Example:

```
CALC:MARK4:FUNC:BPOW:MODE DENS
Configures marker 4 to show the measurement results in dBm/Hz.
```

Manual operation: See ["Power Mode"](#) on page 458

CALCulate<n>:MARKer<m>:FUNction:BPOWer:RESult?

This command queries the results of the band power measurement.

Return values:

<Power> Signal power over the marker bandwidth.

Example:

Activate the band power marker:

```
CALC:MARK:FUNC:BPOW:STAT ON
```

Select the density mode for the result:

```
CALC:MARK:FUNC:BPOW:MODE DENS
```

Query the result:

```
CALC:MARK:FUNC:BPOW:RES?
```

Response:

```
20dBm/Hz
```

Usage: Query only

**CALCulate<n>:MARKer<m>:FUNction:BPOWer:SPAN **

This command defines the bandwidth around the marker position.

Parameters:

 Frequency. The maximum span depends on the marker position and R&S FPS model.

*RST: 5% of current span

Default unit: Hz

Example:

```
CALC:MARK:FUNC:BPOW:SPAN 2MHZ
```

Measures the band power over 2 MHz around the marker.

Manual operation: See ["Span"](#) on page 458

CALCulate<n>:MARKer<m>:FUNction:BPOWer[:STATe] <State>

This command turns markers for band power measurements on and off.

Parameters:

<State> ON | OFF

*RST: OFF

Example:

```
CALC:MARK4:FUNC:BPOW:STAT ON
```

Activates or turns marker 4 into a band power marker.

Manual operation: See ["Band Power Measurement State"](#) on page 457
See ["Switching All Band Power Measurements Off"](#) on page 458

Using Delta Markers

CALCulate<n>:DELTaMarker<m>:FUNction:BPOWer:MODE	852
CALCulate<n>:DELTaMarker<m>:FUNction:BPOWer:RESult?	852
CALCulate<n>:DELTaMarker<m>:FUNction:BPOWer:SPAN	852
CALCulate<n>:DELTaMarker<m>:FUNction:BPOWer[:STATe]	852

CALCulate<n>:DELTaMarker<m>:FUNctioN:BPOWer:MODE <Mode>

This command selects the way the results for a band power delta marker are displayed.

Parameters:

<Mode>	POWER Result is displayed as a power in dBm.
	DENSITY Result is displayed as a density in dBm/Hz.
*RST:	POWER

CALCulate<n>:DELTaMarker<m>:FUNctioN:BPOWer:RESult?

This command queries the results of the band power measurement.

Return values:

<Power> Signal power over the delta marker bandwidth.

Usage: Query only

**CALCulate<n>:DELTaMarker<m>:FUNctioN:BPOWer:SPAN **

This command defines the bandwidth around the delta marker position.

Parameters:

	Frequency. The maximum span depends on the marker position and R&S FPS model.
*RST:	5% of current span
	Default unit: Hz

CALCulate<n>:DELTaMarker<m>:FUNctioN:BPOWer[:STATe] <State>

This command turns delta markers for band power measurements on and off.

If necessary, the command also turns on a reference marker.

Parameters:

<State>	ON OFF
*RST:	OFF

11.8.3.12 n dB Down Marker

The following commands control the n dB down markers.

CALCulate<n>:MARKer<m>:FUNctioN:NDBDown.....	853
CALCulate<n>:MARKer<m>:FUNctioN:NDBDown:FREQuency?.....	853
CALCulate<n>:MARKer<m>:FUNctioN:NDBDown:QFACTOR?.....	854

CALCulate<n>:MARKer<m>:FUNction:NDBDown:RESult?.....	854
CALCulate<n>:MARKer<m>:FUNction:NDBDown:STATe.....	855
CALCulate<n>:MARKer<m>:FUNction:NDBDown:TIME?.....	855

CALCulate<n>:MARKer<m>:FUNction:NDBDown <Distance>

This command defines the distance of the n dB down markers to the reference marker.

(<n>, <m> are irrelevant.)

Parameters:

<Distance> Distance of the temporary markers to the reference marker in dB.
 For a positive offset, the markers T1 and T2 are placed *below* the active reference point.
 For a negative offset (for example for notch filter measurements), the markers T1 and T2 are placed *above* the active reference point.

*RST: 6dB

Example:

CALC:MARK:FUNC:NDBD 3dB

Sets the distance to the reference marker to 3 dB.

CALCulate<n>:MARKer<m>:FUNction:NDBDown:FREQuency?

This command queries the position of the n dB down markers on the x-axis when measuring in the frequency domain.

(<n>, <m> are irrelevant.)

To get a valid result, you have to perform a complete measurement with synchronization to the end of the measurement before reading out the result. This is only possible for single sweep mode.

See also [INITiate<n>:CONTinuous](#) on page 605.

Return values:

<Frequency> **<frequency 1>**
 absolute frequency of the n dB marker to the left of the reference marker in Hz
 <frequency 2>
 absolute frequency of the n dB marker to the right of the reference marker in Hz.

Example:

```
INIT:CONT OFF
Switches to single sweep mode.
CALC:MARK:FUNC:NDBD ON
Switches on the n dB down function.
INIT;*WAI
Starts a sweep and waits for the end.
CALC:MARK:FUNC:NDBD:FREQ?
```

This command would return, for example, 100000000, 200000000, meaning that the first marker position is at 100 MHz, the second marker position is at 200 MHz

Usage: Query only

Manual operation: See "[n dB down Delta Value](#)" on page 456

CALCulate<n>:MARKer<m>:FUNCTion:NDBDown:QFACTOR?

This command queries the Q factor of n dB down measurements.

(<n>, <m> are irrelevant.)

Return values:

<QFactor>

Usage: Query only

CALCulate<n>:MARKer<m>:FUNCTion:NDBDown:RESult?

This command queries the distance of the n dB down markers from each other.

(<n>, <m> are irrelevant.)

To get a valid result, you have to perform a complete measurement with synchronization to the end of the measurement before reading out the result. This is only possible for single sweep mode.

See also [INITiate<n>:CONTinuous](#) on page 605.

Return values:

<Distance>

The result depends on the span.

In case of frequency domain measurements, the command returns the bandwidth between the two n dB down markers in Hz.

In case of time domain measurements, the command returns the pulse width between the two n dB down markers in seconds.

Example:

```
INIT:CONT OFF
Switches to single sweep mode.
CALC:MARK:FUNC:NDBD ON
Switches on the n dB down function.
INIT;*WAI
Starts a sweep and waits for the end.
CALC:MARK:FUNC:NDBD:RES?
```

Outputs the measured value.

Usage: Query only
Manual operation: See "[n dB down Marker State](#)" on page 455

CALCulate<n>:MARKer<m>:FUNction:NDBDown:STATe <State>

This command turns the n dB Down marker function on and off.

(<n>, <m> are irrelevant.)

Parameters:

<State> ON | OFF
 *RST: OFF

Example: CALC:MARK:FUNC:NDBD:STAT ON
 Turns the n dB Down marker on.

Manual operation: See "[n dB down Marker State](#)" on page 455

CALCulate<n>:MARKer<m>:FUNction:NDBDown:TIME?

This command queries the position of the n dB down markers on the x-axis when measuring in the time domain.

(<n>, <m> are irrelevant.)

To get a valid result, you have to perform a complete measurement with synchronization to the end of the measurement before reading out the result. This is only possible for single sweep mode.

See also [INITiate<n>:CONTinuous](#) on page 605.

Return values:

<TimeX1> absolute position in time of the n dB marker to the left of the reference marker in seconds
 <TimeX2> absolute position in time of the n dB marker to the right of the reference marker in seconds

Example: INIT:CONT OFF
 Switches to single sweep mode
 CALC:MARK:FUNC:NDBD ON
 Switches on the n dB down function.
 INIT;*WAI
 Starts a sweep and waits for the end.
 CALC:MARK:FUNC:NDBD:TIME?
 Outputs the time values of the temporary markers.

Usage: Query only
Manual operation: See "[n dB down Delta Value](#)" on page 456

11.8.3.13 Signal Count Marker

The following commands control the frequency counter.

<code>CALCulate<n>:MARKer<m>:COUNT</code>	856
<code>CALCulate<n>:MARKer<m>:COUNT:FREQUency?</code>	856
<code>CALCulate<n>:MARKer<m>:COUNT:RESolution</code>	857

CALCulate<n>:MARKer<m>:COUNT <State>

This command turns the frequency counter at the marker position on and off.

The frequency counter works for one marker only. If you perform a frequency count with another marker, the R&S FPS deactivates the frequency count of the first marker.

To get a valid result, you have to perform a complete measurement with synchronization to the end of the measurement before reading out the result. This is only possible for single sweep mode.

See also `INITiate<n>:CONTinuous` on page 605.

Parameters:

<State> ON | OFF
 *RST: OFF

Example:

```
INIT:CONT OFF
Switches to single sweep mode.
CALC:MARK ON
Switches on marker 1.
CALC:MARK:COUN ON
Switches on the frequency counter for marker 1.
INIT;*WAI
Starts a sweep and waits for the end.
CALC:MARK:COUN:FREQ?
Outputs the measured value.
```

Manual operation: See "[Signal Count Marker State](#)" on page 451

CALCulate<n>:MARKer<m>:COUNT:FREQUency?

This command queries the frequency at the marker position.

To get a valid result, you have to perform a complete measurement with synchronization to the end of the measurement before reading out the result. This is only possible for single sweep mode.

See also `INITiate<n>:CONTinuous` on page 605.

Before you can use the command, you have to turn on the frequency counter.

Return values:

<Frequency> Frequency at the marker position.

Example: INIT:CONT OFF
Switches to single sweep mode.
CALC:MARK ON
Switches on marker 2.
CALC:MARK:COUN ON
Activates the frequency counter for marker 1.
INIT;*WAI
Starts a sweep and waits for the end.
CALC:MARK:COUN:FREQ?
Outputs the measured value of marker 1.

Usage: Query only

Manual operation: See ["Signal Count Marker State"](#) on page 451

CALCulate<n>:MARKer<m>:COUNt:RESolution <Resolution>

This command defines the resolution of the frequency counter.

Parameters:

<Resolution> 0.001 | 0.01 | 0.1 | 1 | 10 | 100 | 1000 | 10000 Hz
*RST: 0.1 Hz

Example: CALC:MARK:COUN:RES 1kHz
Sets the resolution of the frequency counter to 1 kHz.

Manual operation: See ["Resolution"](#) on page 451

11.8.3.14 Programming Examples for Using Markers and Marker Functions

Various programming examples on how to use markers and the special marker functions are provided here.



The use of spectrogram markers is demonstrated in [chapter 11.8.2.6, "Programming Example: Configuring a Spectrogram"](#), on page 816.

- [Example: Basic Markers](#)..... 858
- [Example: Marker Search in Spectrograms](#)..... 859
- [Basic Frequency Sweep Measurement for Marker Function Examples](#)..... 860
- [Example: Using a Fixed Reference Marker](#)..... 860
- [Example: Obtaining a Marker Peak List](#)..... 861
- [Example: Measuring Noise Density](#)..... 861
- [Example: Measuring Phase Noise](#)..... 862
- [Example: Measuring the Power in a Channel Using Band Power Markers](#)..... 863
- [Example: Measuring Characteristic Bandwidths \(Using the n dB Down Marker\)](#)
..... 863
- [Example: Performing a Highly Accurate Frequency Measurement Using the Signal Count Marker](#)..... 864

Example: Basic Markers

This example demonstrates how to configure and define markers for a basic spectrum measurement in a remote environment. It assumes that the basic frequency sweep described in [chapter 11.15.1, "Programming Example: Performing a Basic Frequency Sweep"](#), on page 976 has been performed and thus does not begin by presetting the instrument.

```
//-----Configuring marker behavior -----
DISP:MTAB ON
//Marker information is always displayed in a separate table.
CALC:MARK:X:SSIZ STAN
//The marker moves from one pixel to the next instead of sweep points in manual op.
CALC:MARK:PEXC 6dB
//Defines a peak excursion of 6 dB.
CALC:MARK:X:SLIM ON
CALC:MARK:X:SLIM:LEFT 50MHz
CALC:MARK:X:SLIM:RIGH 150MHz
//Restricts the search area for peaks to the frequencies between 50 and 150 MHz.
CALC:THR -100dBm
CALC:THR:STAT ON
//Configures a threshold level for peak searches at -100 dBm.

//-----Defining and positioning markers -----
CALC:MARK1 ON
//Activates marker 1 and sets it to the peak of trace 1.
CALC:MARK2:TRAC 2
//Activates marker 2 and sets it to the peak of trace 2.
CALC:MARK3:X 150MHz
//Activates marker 3 and sets it to the freq. 150 MHz on trace 1.
CALC:MARK4:TRAC 4
//Activates marker 4 and sets it to the peak of trace 4.

CALC:MARK1:MAX:AUTO ON
//Moves M1 to the current peak of trace 1 after each sweep.
CALC:MARK2:MAX:NEXT
//Moves M2 to the next lower peak of trace 2.

CALC:DELT5 ON
CALC:DELT5:LINK ON
//Activates delta marker 5 and links it to marker 1. If M1 moves, so does D5.
CALC:DELT5:MREF 4
//Changes the reference for D5 to marker 4. D5 now shows the difference between
//the peak of trace 1 after each sweep and the value at the same position in
//trace 4, which is a copy of trace 1, averaged over 10 sweeps.
CALC:DELT5:MODE REL
//Shows the difference as relative values.

CALC:DELT6 ON
CALC:DELT6:MAX:NEXT
```

```

//Activates delta marker 6 and sets it to the next lower maximum of trace 1.
//Thus it shows the difference between the two highest peaks in trace 1.

//-----Retrieving marker values -----
CALC:MARK1:Y?
CALC:MARK2:Y?
CALC:MARK3:Y?
CALC:MARK4:Y?
CALC:DELT5:Y?
CALC:DELT6:Y?
//Retrieves the marker levels of each active normal and delta marker.
CALC:DELT5:X:REL?
CALC:DELT6:X:REL?
//Retrieves the frequency difference between the delta marker and marker 1.

//-----Deactivating all markers -----
//CALC:MARK:AOFF
//CALC:DELT:AOFF

```

Example: Marker Search in Spectrograms

This example demonstrates how to search for peak values in spectrograms in a remote environment. It assumes a spectrogram is already available (see [chapter 11.8.2.6, "Programming Example: Configuring a Spectrogram"](#), on page 816) and thus does not begin by presetting the instrument.

```

//----- Analyzing the results using markers -----
//Set marker1 on the peak power in the most recent spectrum and query
//its position
CALC2:SPEC:FRAM:SEL 0
CALC2:MARK1 ON
CALC2:MARK1:X?
CALC2:MARK1:Y?

//Set marker2 on the peak power in frame at -324ms and query its position
CALC2:MARK2 ON
CALC2:MARK2:SGR:FRAM -324ms
CALC2:MARK2:X?
CALC2:MARK2:Y?

//Set marker3 on peak power level in the entire spectrogram in memory and
//query its position
CALC2:MARK3 ON
CALC2:MARK:SPEC:SAR MEM
CALC2:MARK3:SPEC:XY:MAX
CALC2:MARK3:X?
CALC2:MARK3:Y?

//Move marker 3 to the next lower peak level for the same frequency
CALC2:MARK3:SPEC:Y:MAX:NEXT
CALC2:MARK3:X?

```

```

CALC2:MARK3:Y?

//Set marker 4 to the highest level in the (visible) spectrogram.
CALC2:MARK:SPEC:SAR VIS
CALC2:MARK4:SPEC:XY:MAX
//Move marker 4 to the next higher level in the frames above its current position.
CALC2:MARK4:SPEC:Y:MAX:ABOV

```

Basic Frequency Sweep Measurement for Marker Function Examples

Since markers can only be placed on an existing trace, the following example provides a simple frequency sweep measurement to be used as a basis for the subsequent marker function scripts.

```

//----- Configuring the basic frequency sweep -----
*RST
//Resets the instrument
INIT:CONT OFF
//Selects single sweep mode.
FREQ:CENT 100MHz
//Defines the center frequency
FREQ:SPAN 200MHz
//Sets the span to 100 MHz on either side of the center frequency.
DISP:TRAC1:Y:RLEV 0dBm
//Sets the reference level to 0 dBm.

//----- Performing the measurement -----
INIT;*WAI
//Performs a measurement and waits for it to end

```

Example: Using a Fixed Reference Marker

This example demonstrates how to configure and use reference markers in a basic spectrum measurement in a remote environment. It assumes that the basic frequency sweep described in "[Basic Frequency Sweep Measurement for Marker Function Examples](#)" on page 860 has been performed and thus does not begin by presetting the instrument.

```

//-----Configuring the reference marker -----
//Activate a fixed reference marker. It is set to the current maximum of trace 1.
CALC:DELT:FUNC:FIX ON
//Set the reference frequency to 128 MHz.
CALC:DELT:FUNC:FIX:RPO:X 128 MHZ
//Set the reference level to +30 dBm.
CALC:DELT:FUNC:FIX:RPO:Y 30 DBM

//Use the fixed reference marker as a reference for deltamarker 2
CALC:DELT2:MREF FIX

//Reset the reference marker to the current maximum of trace 1
CALC:DELT:FUNC:FIX:RPO:MAX
//Query the new position of the reference marker

```

```
CALC:DELT:FUNC:FIX:RPO:X?
CALC:DELT:FUNC:FIX:RPO:Y?
```

Example: Obtaining a Marker Peak List

This example demonstrates how to obtain a marker peak list in a basic spectrum measurement in a remote environment. It assumes that the basic frequency sweep described in ["Basic Frequency Sweep Measurement for Marker Function Examples"](#) on page 860 has been performed and thus does not begin by presetting the instrument.

In this example, the peak search is restricted to the frequency range of 50 MHz to 150 MHz. The top 5 power levels with a peak excursion of 10dB and a minimum of -100 dBm are to be determined and displayed with their marker numbers. The results are sorted by frequency values. The resulting peak list is then exported to a file.

```
//----- Configuring the peak search -----
CALC:MARK:X:SLIM ON
CALC:MARK:X:SLIM:LEFT 50MHz
CALC:MARK:X:SLIM:RIGH 150MHz
CALC:MARK:PEXC 10DB
CALC:THR -100DBM
CALC:THR:STAT ON

CALC:MARK:FUNC:FPE:STAT ON
CALC:MARK:FUNC:FPE:LIST:SIZE 5
CALC:MARK:FUNC:FPE:SORT X
CALC:MARK:FUNC:FPE:ANN:LAB ON

//----- Retrieving results -----
CALC:MARK:FUNC:FPE:COUN?
CALC:MARK:FUNC:FPE:X?
CALC:MARK:FUNC:FPE:Y?

//----- Exporting the peak list -----
MMEM:STOR:PEAK 'PeakList'
```

Example: Measuring Noise Density

This example demonstrates how to measure noise density using noise markers in a basic spectrum measurement in a remote environment. It assumes that the basic frequency sweep described in ["Basic Frequency Sweep Measurement for Marker Function Examples"](#) on page 860 has been performed and thus does not begin by presetting the instrument.

```
CALC:MARK1:FUNC:NOIS ON
//Switches on noise measurement at marker 1.

INIT;*WAI
//Performs a measurement and waits for it to end
```

```
CALC:MARK1:FUNC:NOIS:RES?
//Queries the measured noise level (per Hz bandwidth)
```

Example: Measuring Phase Noise

This example demonstrates how to measure phase noise using markers in a basic spectrum measurement in a remote environment. It assumes that the basic frequency sweep described in "[Basic Frequency Sweep Measurement for Marker Function Examples](#)" on page 860 has been performed and thus does not begin by presetting the instrument.

```
//----- Configuring the phase noise marker -----
DET SAMP
//Switches to Sample detector

CALC:MARK1 ON
//Activates marker1 and sets it to the maximum power level

CALC:DELT:FUNC:PNO ON
//Activates phase noise marker function

CALC:DELT1 ON
CALC:DELT1:X 100kHz

CALC:DELT2 ON
CALC:DELT2:X 500kHz

CALC:DELT3 ON
CALC:DELT3:X 1MHz

CALC:DELT4 ON
CALC:DELT4:X 1.5MHz

//Activates the phase noise measurement function for offsets 100kHz/500kHz/1MHz/1.5MHz.

BAND:VID?
//Queries the used VBW (= 0.1*RBW)

//----- Querying the phase noise results -----

CALC:DELT1:FUNC:PNO:RES?
CALC:DELT2:FUNC:PNO:RES?
CALC:DELT3:FUNC:PNO:RES?
CALC:DELT4:FUNC:PNO:RES?
//Queries the difference in level between the peak and the noise power density
//measured at the deltamarkers, referred to the carrier power level (dBc)
```


Example: Measuring the Power in a Channel Using Band Power Markers

This example demonstrates how to measure the power in a specific channel or band using markers in a basic spectrum measurement in a remote environment. It assumes that the basic frequency sweep described in ["Basic Frequency Sweep Measurement for Marker Function Examples"](#) on page 860 has been performed and thus does not begin by presetting the instrument.

```
//----- Configuring the band power marker -----
CALC:MARK1 ON
//Activates marker1 and sets it to the maximum power level
CALC:MARK1:FUNC:BPOW:STAT ON
//Activates the band power measurement for the band around marker 1
CALC:MARK1:FUNC:BPOW:SPAN 30MHz
//Sets the bandwidth to be measured to 30 MHz
CALC:MARK1:FUNC:BPOW:MODE DENS
//Sets the result to be a density (power per Hz bandwidth)

CALC:DELT2 ON
//Activates deltamarker2
CALC:DELT2:FUNC:BPOW:STAT ON
//Activates the band power measurement for the band around deltamarker 2
CALC:DELT2:FUNC:BPOW:SPAN 30MHz
//Sets the bandwidth to be measured to 30 MHz
CALC:DELT2:FUNC:BPOW:MODE DENS
//Sets the result to be a density (power per Hz bandwidth)

CALC:DELT3 ON
//Activates deltamarker3
CALC:DELT3:FUNC:BPOW:STAT ON
//Activates the band power measurement for the band around deltamarker 3
CALC:DELT3:FUNC:BPOW:SPAN 30MHz
//Sets the bandwidth to be measured to 30 MHz
CALC:DELT3:FUNC:BPOW:MODE DENS
//Sets the result to be a density (power per Hz bandwidth)

//-----Retrieving Results-----
CALC:MARK1:FUNC:BPOW:RES?
//Returns the power sum for the specified bandwidth around marker 1.
CALC:DELT2:FUNC:BPOW:RES?
//Returns the power sum for the specified bandwidth around deltamarker 2.
CALC:DELT3:FUNC:BPOW:RES?
//Returns the power sum for the specified bandwidth around deltamarker 3.
```

Example: Measuring Characteristic Bandwidths (Using the n dB Down Marker)

This example demonstrates how to measure a characteristic bandwidth using markers in a basic spectrum measurement in a remote environment. It assumes that the basic frequency sweep described in [chapter 11.15.1, "Programming Example: Performing a Basic Frequency Sweep"](#), on page 976 has been performed and thus does not begin by presetting the instrument.

```
//----- Configuring the n dB down marker -----
CALC:MARK1 ON
//Activates marker1 and sets it to the maximum power level
CALC:MARK1:FUNC:NDBD 3DB
//Sets the level offset to 3 dB
CALC:MARK1:FUNC:NDBD:STAT ON
//Activates the n dB down measurement

//-----Retrieving Results-----
CALC:MARK:FUNC:NDBD:RES?
//Returns the bandwidth at the specified power offset.
CALC:MARK:FUNC:NDBD:FREQ?
//Returns the frequencies of the temporary markers at the power offsets
CALC:MARK:FUNC:NDBD:QFAC?
//Returns the quality factor of the resulting bandwidth
```

Example: Performing a Highly Accurate Frequency Measurement Using the Signal Count Marker

This example demonstrates how to determine highly accurate frequency values using signal count markers in a basic spectrum measurement in a remote environment. It assumes that the basic frequency sweep described in [chapter 11.15.1, "Programming Example: Performing a Basic Frequency Sweep"](#), on page 976 has been performed and thus does not begin by presetting the instrument.

```
//----- Configuring the signal count marker -----
CALC:MARK1 ON
//Activates marker1
CALC:MARK1:COUN ON
//Switches on the frequency counter for marker 1.
CALC:MARK1:COUN:RES 1kHz
//Sets the resolution of the frequency counter to 1kHz

//----- Performing the measurement -----
INIT;*WAI
//Performs a measurement and waits for it to end

//-----Retrieving Results-----
CALC:MARK1:COUN:FREQ?
//Returns the signal counter value as the precise marker frequency.
```

11.8.4 Configuring Display and Limit Lines

The commands required to configure display and limit lines in a remote environment are described here. The tasks for manual operation are described in [chapter 7.5.4, "How to Work with Display and Limit Lines"](#), on page 474.

- [Configuring Display Lines](#)..... 865
- [Defining Limit Checks](#)..... 866

11.8.4.1 Configuring Display Lines

The following commands configure vertical and horizontal display lines.

CALCulate<n>:DLINe<k>.....	865
CALCulate<n>:DLINe<k>:STATe.....	865
CALCulate<n>:FLINe<k>.....	865
CALCulate<n>:FLINe<k>:STATe.....	866
CALCulate<n>:TLINe<k>.....	866
CALCulate<n>:TLINe<k>:STATe.....	866

CALCulate<n>:DLINe<k> <Position>

This command defines the (vertical) position of a display line.

Parameters:

<Position> The value range is variable.
 You can use any unit you want, the R&S FPS then converts the unit to the currently selected unit. If you omit a unit, the R&S FPS uses the currently selected unit.
 *RST: (state is OFF)

Example: CALC:DLIN -20dBm
 Positions the display line at -20 dBm.

Manual operation: See "[Horizontal Line 1/2](#)" on page 468

CALCulate<n>:DLINe<k>:STATe <State>

This command turns a display line on and off

Parameters:

<State> ON | OFF
 *RST: OFF

Example: CALC:DLIN2:STAT ON
 Turns on display line 2.

CALCulate<n>:FLINe<k> <Frequency>

This command defines the position of a frequency line.

Parameters:

<Frequency> Note that you can not set a frequency line to a position that is outside the current span.
 Range: 0 Hz to Fmax
 *RST: (STATe to OFF)

Example: CALC:FLIN2 120MHz
 Sets frequency line 2 to a frequency of 120 MHz.

Manual operation: See "[Vertical Line 1/2](#)" on page 468

CALCulate<n>:FLINe<k>:STATe <State>

This command turns a frequency line on and off

Parameters:

<State> ON | OFF
*RST: OFF

Example: CALC:FLIN2:STAT ON
Turns frequency line 2 on.

CALCulate<n>:TLINe<k> <Time>

This command defines the position of a time line.

Parameters:

<Time> Note that you can not set a time line to a position that is higher than the current sweep time.
Range: 0 s to 1600 s
*RST: (STATe to OFF)

Example: CALC:TLIN 10ms
Sets the first time line to 10 ms.

Manual operation: See "[Vertical Line 1/2](#)" on page 468

CALCulate<n>:TLINe<k>:STATe <State>

This command turns a time line on and off

Parameters:

<State> ON | OFF
*RST: OFF

Example: CALC:TLIN:STAT ON
Turns the first time line on.

11.8.4.2 Defining Limit Checks

Note that in remote control, upper and lower limit lines are configured using separate commands. Thus, you must decide in advance which you want to configure. The x-values for both upper and lower limit lines are defined as a common control line. This control line is the reference for the y-values for both upper and lower limit lines.

- [Configuring Limit Lines](#).....867
- [Managing Limit Lines](#).....874
- [Checking the Results of a Limit Check](#).....876
- [Programming Example: Using Limit Lines](#).....877

Configuring Limit Lines

CALCulate<n>:LIMit<k>:COMMeNt.....	867
CALCulate<n>:LIMit<k>:CONTRol[:DATA].....	867
CALCulate<n>:LIMit<k>:CONTRol:DOMain.....	868
CALCulate<n>:LIMit<k>:CONTRol:MODE.....	868
CALCulate<n>:LIMit<k>:CONTRol:OFFSet.....	868
CALCulate<n>:LIMit<k>:CONTRol:SHIFt.....	869
CALCulate<n>:LIMit<k>:CONTRol:SPACing.....	869
CALCulate<n>:LIMit<k>:LOWer[:DATA].....	869
CALCulate<n>:LIMit<k>:LOWer:MARGin.....	870
CALCulate<n>:LIMit<k>:LOWer:MODE.....	870
CALCulate<n>:LIMit<k>:LOWer:OFFSet.....	870
CALCulate<n>:LIMit<k>:LOWer:SHIFt.....	870
CALCulate<n>:LIMit<k>:LOWer:SPACing.....	871
CALCulate<n>:LIMit<k>:LOWer:STATe.....	871
CALCulate<n>:LIMit<k>:LOWer:THReshold.....	871
CALCulate<n>:LIMit<k>:NAME.....	872
CALCulate<n>:LIMit<k>:UNIT.....	872
CALCulate<n>:LIMit<k>:UPPer[:DATA].....	872
CALCulate<n>:LIMit<k>:UPPer:MARGin.....	872
CALCulate<n>:LIMit<k>:UPPer:MODE.....	873
CALCulate<n>:LIMit<k>:UPPer:OFFSet.....	873
CALCulate<n>:LIMit<k>:UPPer:SHIFt.....	873
CALCulate<n>:LIMit<k>:UPPer:SPACing.....	874
CALCulate<n>:LIMit<k>:UPPer:STATe.....	874
CALCulate<n>:LIMit<k>:UPPer:THReshold.....	874

CALCulate<n>:LIMit<k>:COMMeNt <Comment>

This command defines a comment for a limit line.

(<n> is irrelevant.)

Parameters:

<Comment> String containing the description of the limit line. The comment may have up to 40 characters.

Manual operation: See "[Comment](#)" on page 472

CALCulate<n>:LIMit<k>:CONTRol[:DATA] <LimitLinePoints>

This command defines the horizontal definition points of a limit line.

(<n> is irrelevant.)

Parameters:

<LimitLinePoints> Variable number of x-axis values.
 Note that the number of horizontal values has to be the same as the number of vertical values set with `CALCulate<n>:LIMit<k>:LOWer[:DATA]` or `CALCulate<n>:LIMit<k>:UPPer[:DATA]`. If not, the R&S FPS either adds missing values or ignores surplus values.
 The unit is Hz or s.
 *RST: -

Usage: SCPI confirmed

Manual operation: See "Data points" on page 473

CALCulate<n>:LIMit<k>:CONTrol:DOMain <SpanSetting>

This command selects the domain of the limit line.
 (<n> is irrelevant.)

Parameters:

<SpanSetting> FREQUENCY | TIME
 *RST: FREQUENCY

Manual operation: See "X-Axis" on page 473

CALCulate<n>:LIMit<k>:CONTrol:MODE <Mode>

This command selects the horizontal limit line scaling.
 (<n> is irrelevant.)

Parameters:

<Mode> **ABSolute**
 Limit line is defined by absolute physical values (Hz or s).
RELative
 Limit line is defined by relative values related to the center frequency (frequency domain) or the left diagram border (time domain).
 *RST: ABSolute

CALCulate<n>:LIMit<k>:CONTrol:OFFSet <Offset>

This command defines an offset for a complete limit line.

Compared to shifting the limit line, an offset does not actually change the limit line definition points.

(<n> is irrelevant.)

Parameters:

<Offset> Numeric value.
 The unit depends on the scale of the x-axis.
 *RST: 0

Manual operation: See "[X-Offset](#)" on page 470

CALCulate<n>:LIMit<k>:CONTrol:SHIFt <Distance>

This command moves a complete limit line horizontally.

Compared to defining an offset, this command actually changes the limit line definition points by the value you define.

(<n> is irrelevant.)

Parameters:

<Distance> Numeric value.
 The unit depends on the scale of the x-axis.

Manual operation: See "[Shift x](#)" on page 474

CALCulate<n>:LIMit<k>:CONTrol:SPACing <InterpolMode>

This command selects linear or logarithmic interpolation for the calculation of limit lines from one horizontal point to the next.

Parameters:

<InterpolMode> LINear | LOGarithmic
 *RST: LIN

Example: `CALC:LIM:CONT:SPAC LIN`

CALCulate<n>:LIMit<k>:LOWer[:DATA] <LimitLinePoints>

This command defines the vertical definition points of a lower limit line.

(<n> is irrelevant.)

Parameters:

<LimitLinePoints> Variable number of level values.
 Note that the number of vertical values has to be the same as the number of horizontal values set with `CALCulate<n>:LIMit<k>:CONTrol[:DATA]`. If not, the R&S FPS either adds missing values or ignores surplus values.
 The unit depends on `CALCulate<n>:LIMit<k>:UNIT` on page 872.
 *RST: Limit line state is OFF

Usage: SCPI confirmed

Manual operation: See "[Data points](#)" on page 473

CALCulate<n>:LIMit<k>:LOWer:MARGin <Margin>

This command defines an area around a lower limit line where limit check violations are still tolerated.

(<n> is irrelevant.)

Parameters:

<Margin> **numeric value**
 *RST: 0
 Default unit: dB

Manual operation: See "[Margin](#)" on page 473

CALCulate<n>:LIMit<k>:LOWer:MODE <Mode>

This command selects the vertical limit line scaling.

Parameters:

<Mode> **ABSolute**
 Limit line is defined by absolute physical values.
 The unit is variable.

RELative
 Limit line is defined by relative values related to the reference
 level (dB).
 *RST: ABSolute

Manual operation: See "[X-Axis](#)" on page 473

CALCulate<n>:LIMit<k>:LOWer:OFFSet <Offset>

This command defines an offset for a complete lower limit line.

Compared to shifting the limit line, an offset does not actually change the limit line definition points.

Parameters:

<Offset> Numeric value.
 *RST: 0
 Default unit: dB

Manual operation: See "[Y-Offset](#)" on page 471

CALCulate<n>:LIMit<k>:LOWer:SHIFt <Distance>

This command moves a complete lower limit line vertically.

Compared to defining an offset, this command actually changes the limit line definition points by the value you define.

Parameters:

<Distance> Defines the distance that the limit line moves.
The unit depends on [CALCulate<n>:LIMit<k>:UNIT](#) on page 872.

Manual operation: See ["Shift y"](#) on page 474

CALCulate<n>:LIMit<k>:LOWer:SPACing <InterpolType>

This command selects linear or logarithmic interpolation for the calculation of a lower limit line from one horizontal point to the next.

Parameters:

<InterpolType> LINear | LOGarithmic
*RST: LIN

Manual operation: See ["X-Axis"](#) on page 473
See ["Y-Axis"](#) on page 473

CALCulate<n>:LIMit<k>:LOWer:STATe <State>

This command turns a lower limit line on and off.

Before you can use the command, you have to select a limit line with [CALCulate<n>:LIMit<k>:NAME](#) on page 872.

(<n> is irrelevant.)

Parameters:

<State> ON | OFF
*RST: OFF

Usage: SCPI confirmed

Manual operation: See ["Visibility"](#) on page 470

CALCulate<n>:LIMit<k>:LOWer:THReshold <Threshold>

This command defines a threshold for relative limit lines.

The R&S FPS uses the threshold for the limit check, if the limit line violates the threshold.

(<n> is irrelevant.)

Parameters:

<Threshold> Numeric value.
The unit depends on [CALCulate<n>:LIMit<k>:UNIT](#) on page 872.
*RST: -200 dBm

Manual operation: See ["Threshold"](#) on page 472

CALCulate<n>:LIMit<k>:NAME <Name>

This command selects a limit line that already exists or defines a name for a new limit line.

Parameters:

<Name> String containing the limit line name.
*RST: REM1 to REM8 for lines 1 to 8

Manual operation: See "[Name](#)" on page 472

CALCulate<n>:LIMit<k>:UNIT <Unit>

This command defines the unit of a limit line.

(<n> is irrelevant.)

Parameters:

<Unit> DBM | DBPW | WATT | DBUV | DBMV | VOLT | DBUA |
AMPere | DB | DBUV_M | DBUA_M | (unitless)
If you select dB as the limit line unit, the command automatically
turns the limit line into a relative limit line.
*RST: DBM

Manual operation: See "[Y-Axis](#)" on page 473

CALCulate<n>:LIMit<k>:UPPer[:DATA] <LimitLinePoints>

This command defines the vertical definition points of an upper limit line.

(<n> is irrelevant.)

Parameters:

<LimitLinePoints> Variable number of level values.
Note that the number of vertical values has to be the same as
the number of horizontal values set with [CALCulate<n>:
LIMit<k>:CONTrol\[:DATA\]](#). If not, the R&S FPS either adds
missing values or ignores surplus values.
The unit depends on [CALCulate<n>:LIMit<k>:UNIT](#)
on page 872.
*RST: Limit line state is OFF

Usage: SCPI confirmed

Manual operation: See "[Data points](#)" on page 473

CALCulate<n>:LIMit<k>:UPPer:MARGin <Margin>

This command defines an area around an upper limit line where limit check violations are still tolerated.

(<n> is irrelevant.)

Parameters:

<Margin> **numeric value**
 *RST: 0
 Default unit: dB

Manual operation: See "[Margin](#)" on page 473

CALCulate<n>:LIMit<k>:UPPer:MODE <Mode>

This command selects the vertical limit line scaling.

Parameters:

<Mode> **ABSolute**
 Limit line is defined by absolute physical values.
 The unit is variable.

RELative
 Limit line is defined by relative values related to the reference
 level (dB).

 *RST: ABSolute

Manual operation: See "[X-Axis](#)" on page 473

CALCulate<n>:LIMit<k>:UPPer:OFFSet <Offset>

This command defines an offset for a complete upper limit line.

Compared to shifting the limit line, an offset does not actually change the limit line definition points.

(<n> is irrelevant.)

Parameters:

<Offset> Numeric value.
 *RST: 0
 Default unit: dB

Manual operation: See "[Y-Offset](#)" on page 471

CALCulate<n>:LIMit<k>:UPPer:SHIFt <Distance>

This command moves a complete upper limit line vertically.

Compared to defining an offset, this command actually changes the limit line definition points by the value you define.

(<n> is irrelevant.)

Parameters:

<Distance> Defines the distance that the limit line moves.
 The unit depends on [CALCulate<n>:LIMit<k>:UNIT](#)
 on page 872.

Usage: Event

Manual operation: See "Shift y" on page 474

CALCulate<n>:LIMit<k>:UPPer:SPACing <InterpolType>

This command selects linear or logarithmic interpolation for the calculation of an upper limit line from one horizontal point to the next.

Parameters:

<InterpolType> LINear | LOGarithmic
 *RST: LIN

Manual operation: See "X-Axis" on page 473
 See "Y-Axis" on page 473

CALCulate<n>:LIMit<k>:UPPer:STATe <State>

This command turns an upper limit line on and off.

Before you can use the command, you have to select a limit line with [CALCulate<n>:LIMit<k>:NAME](#) on page 872.

(<n> is irrelevant.)

Parameters:

<State> ON | OFF
 *RST: OFF

Usage: SCPI confirmed

Manual operation: See "Visibility" on page 470

CALCulate<n>:LIMit<k>:UPPer:THReshold <Limit>

This command defines an absolute limit for limit lines with a relative scale.

The R&S FPS uses the threshold for the limit check, if the limit line violates the threshold.

(<n> is irrelevant.)

Parameters:

<Limit> Numeric value.
 The unit depends on [CALCulate<n>:LIMit<k>:UNIT](#) on page 872.
 *RST: -200
 Default unit: dBm

Manual operation: See "Threshold" on page 472

Managing Limit Lines

Useful commands for managing limit lines described in the R&S FPS User Manual:

- `MMEM:SEL[:ITEM]:LIN:ALL`

- MMEM:STOR:TYPE
- MMEM:LOAD:TYPE

Remote commands exclusive to managing limit lines:

CALCulate<n>:LIMit<k>:ACTive?	875
CALCulate<n>:LIMit<k>:COPY	875
CALCulate<n>:LIMit<k>:DELeTe	875
CALCulate<n>:LIMit<k>:STATe	876
CALCulate<n>:LIMit<k>:TRACe<t>:CHECK	876

CALCulate<n>:LIMit<k>:ACTive?

This command queries the names of *all* active limit lines (<n>, <k> are irrelevant).

Return values:

<LimitLines> String containing the names of all active limit lines in alphabetical order.

Example: CALC:LIM:ACT?
Queries the names of all active limit lines.

Usage: Query only

Manual operation: See "[Visibility](#)" on page 470

CALCulate<n>:LIMit<k>:COPY <Line>

This command copies a limit line.

Parameters:

<Line> **1 to 8**
number of the new limit line
<name>
String containing the name of the limit line.

Example: CALC:LIM1:COPY 2
Copies limit line 1 to line 2.
CALC:LIM1:COPY 'FM2'
Copies limit line 1 to a new line named FM2.

Manual operation: See "[Copy Line](#)" on page 471

CALCulate<n>:LIMit<k>:DELeTe

This command deletes a limit line.

Usage: Event

Manual operation: See "[Delete Line](#)" on page 471

CALCulate<n>:LIMit<k>:STATe <State>

This command turns the limit check for a specific limit line on and off.

To query the limit check result, use `CALCulate<n>:LIMit<k>:FAIL?`.

Note that a new command exists to activate the limit check and define the trace to be checked in one step (see `CALCulate<n>:LIMit<k>:TRACe<t>:CHECK` on page 876).

(<n> is irrelevant.)

Parameters:

<State> ON | OFF
*RST: OFF

Example:

`CALC:LIM:STAT ON`
Switches on the limit check for limit line 1.

Usage:

SCPI confirmed

Manual operation: See "[Disable All Lines](#)" on page 471

CALCulate<n>:LIMit<k>:TRACe<t>:CHECK <State>

This command turns the limit check for a specific trace on and off.

To query the limit check result, use `CALCulate<n>:LIMit<k>:FAIL?`.

Note that this command replaces the two commands from previous signal and spectrum analyzers (which are still supported, however):

- `CALCulate<n>:LIMit<k>:TRACe` on page 975
- `CALCulate<n>:LIMit<k>:STATe` on page 876

Parameters:

<State> ON | OFF
*RST: OFF

Example:

`CALC:LIM3:TRAC2:CHEC ON`
Switches on the limit check for limit line 3 on trace 2.

Manual operation: See "[Traces to be Checked](#)" on page 470

Checking the Results of a Limit Check

<code>CALCulate<n>:LIMit<k>:CLEAr[:IMMEDIATE]</code>	876
<code>CALCulate<n>:LIMit<k>:FAIL?</code>	877

CALCulate<n>:LIMit<k>:CLEAr[:IMMEDIATE]

This command deletes the result of the current limit check.

The command works on *all* limit lines in *all* measurement windows at the same time (<n>, <k> are irrelevant).

Example: `CALC:LIM:CLE`
Deletes the result of the limit check.

Usage: SCPI confirmed

CALCulate<n>:LIMit<k>:FAIL?

This command queries the result of a limit check.

Note that for SEM measurements, the limit line suffix <k> is irrelevant, as only one specific SEM limit line is checked for the currently relevant power class.

To get a valid result, you have to perform a complete measurement with synchronization to the end of the measurement before reading out the result. This is only possible for single sweep mode.

See also [INITiate<n>:CONTinuous](#) on page 605.

Return values:

<Result> **0**
 PASS
 1
 FAIL

Example: `INIT;*WAI`
Starts a new sweep and waits for its end.
`CALC:LIM3:FAIL?`
Queries the result of the check for limit line 3.

Usage: Query only
 SCPI confirmed

Manual operation: See "[Spectrum Emission Mask](#)" on page 114
 See "[Limit Check <n>](#)" on page 214
 See "[Limit Check](#)" on page 246

Programming Example: Using Limit Lines

The following examples demonstrate how to work with limit lines in a remote environment.

- [Example: Configuring Limit Lines](#).....877
- [Example: Performing a Limit Check](#).....879

Example: Configuring Limit Lines

This example demonstrates how to configure 2 limit lines - an upper and a lower limit - for a measurement in a remote environment.

```
//----- Configuing the limit lines -----
CALC:LIM1:NAME 'FM1'
//Names limit line 1 'FM1'.

CALC:LIM1:CONT:MODE ABS
//Selects absolute scaling for the horizontal axis.
```

```

CALC:LIM1:CONT 1 MHz,50MHz,100 MHz,150MHz,200MHz
//Defines 5 horizontal definition points for limit line 1.
CALC:LIM1:UPP:MODE ABS
//Selects an absolute vertical scale for limit line 1.
CALC:LIM1:UNIT DBM
//Selects the unit dBm for limit line 1.
CALC:LIM1:UPP -10,-5,0,-5,-10
//Defines 5 definition points for limit line 1.

CALC:LIM1:UPP:MARG 5dB
//Defines an area of 5 dB around limit line 1 where limit check violations
//are still tolerated.

CALC:LIM1:UPP:SHIF -10DB
//Shifts the limit line 1 by -10 dB.
CALC:LIM1:UPP:OFFS -3dB
//Defines an additional -3 dB offset for limit line 1.

CALC:LIM3:NAME 'FM3'
//Names limit line 3 'FM3'.

CALC:LIM3:LOW:MODE REL
//Selects a relative vertical scale for limit line 3.
CALC:LIM3:UNIT DB

CALC:LIM3:CONT 1 MHz,50MHz,100 MHz,150MHz,200MHz
//Defines 5 horizontal definition points for limit line 3.
CALC:LIM3:LOW -90,-60,-40,-60,-90
//Defines 5 definition points relative to the reference level for limit line 3.

CALC:LIM3:LOW:SHIF 2
//Shifts the limit line 3 by 2dB.
CALC:LIM3:LOW:OFFS 3
//Defines an additional 3 dB offset for limit line 3.

CALC:LIM3:LOW:THR -200DBM
//Defines a power threshold of -200dBm that must be exceeded for limit to be checked

CALC:LIM3:LOW:MARG 5dB
//Defines an area of 5dB around limit line 3 where limit check violations
//are still tolerated.

//----- Storing the limit lines -----
MMEM:SEL:CHAN:LIN:ALL ON
MMEM:STOR:TYPE CHAN
MMEM:STOR:STAT 1,'LimitLines_FM1_FM3'

```


Example: Performing a Limit Check

This example demonstrates how to perform a limit check during a basic frequency sweep measurement in a remote environment. The limit lines configured in ["Example: Configuring Limit Lines"](#) on page 877 are assumed to exist and be active.

```
//-----Preparing the instrument -----
*RST
//Resets the instrument
INIT:CONT OFF
//Selects single sweep mode.

//-----Configuring the measurement -----
FREQ:CENT 100MHz
//Defines the center frequency
FREQ:SPAN 200MHz
//Sets the span to 100 MHz on either side of the center frequency.
SENS:SWE:COUN 10
//Defines 10 sweeps to be performed in each measurement.
DISP:TRAC1:Y:RLEV 0dBm
//Sets the reference level to 0 dBm.
TRIG:SOUR IFP
TRIG:LEV:IFP -10dBm
//Defines triggering when the second intermediate frequency rises to a level
//of -10 dBm.

//-----Configuring the Trace-----
DISP:TRAC2 ON
DISP:TRAC2:MODE AVER
DISP:TRAC3 ON
DISP:TRAC3:MODE MAXH
//Configures 3 traces: 1 (default): clear/write; 2: average; 3: max hold

//----- Configuring the limit check -----
MMEM:LOAD:TYPE REPL
MMEM:LOAD:STAT 1,'LimitLines_FM1_FM3'
//Loads the limit lines stored in 'LimitLines_FM1_FM3'
CALC:LIM1:NAME 'FM1'
CALC:LIM1:UPP:STAT ON
//Activates upper limit FM1 as line 1.
CALC:LIM3:NAME 'FM3'
CALC:LIM3:LOW:STAT ON
//Activates lower limit line FM3 as line 3.
CALC:LIM:ACT?
//Queries the names of all active limit lines
//Result: 'FM1,FM3'
CALC:LIM1:TRAC3:CHEC ON
//Activates the upper limit to be checked against trace3 (maxhold trace)
CALC:LIM3:TRAC2:CHEC ON
//Activates the upper limit to be checked against trace2 (average trace)
CALC:LIM:CLE
```

```
//Clears the previous limit check results

//----- Performing the measurement-----
INIT;*WAI
//Initiates a new measurement and waits until the last sweep has finished.

//----- Retrieving limit check results-----

CALC:LIM1:FAIL?
//Queries the result of the upper limit line check
CALC:LIM3:FAIL?
//Queries the result of the lower limit line check
```

11.9 Managing Settings and Results

The commands required to store and load instrument settings and import and export measurement results in a remote environment are described here.

The tasks for manual operation are described in [chapter 8, "Data Management"](#), on page 478.

Addressing drives

The various drives can be addressed via the "mass storage instrument specifier" <msis> using the conventional Windows syntax. The internal hard disk is addressed by "C:".

For details on storage locations refer to [chapter 8.3.2.2, "Storage Location and File Name"](#), on page 486.

The file names (<FileName> parameter) are given as string parameters enclosed in quotation marks. They also comply with Windows conventions. Windows file names do not distinguish between uppercase and lowercase notation.

Wildcards

The two characters "*" and "?" can be used as "wildcards", i.e., they are variables for a selection of several files. The question mark "?" replaces exactly one character, the asterisk replaces any of the remaining characters in the file name. "*.*" thus means all files in a directory.

Path names

Storage locations can be specified either as absolute (including the entire path) or relative paths (including only subfolders of the current folder). Use the `MMEM:CDIR?` query to determine the current folder.



Secure user mode

In secure user mode, settings that are to be stored on the instrument are stored to volatile memory, which is restricted to 256 MHz. Thus, a "Memory full" error may occur although the hard disk indicates that storage space is still available.

- [General Data Storage and Loading Commands](#)..... 881
- [Selecting the Items to Store](#)..... 887
- [Storing and Loading Instrument Settings](#)..... 890
- [Storing or Printing Screenshots](#)..... 895
- [Storing Measurement Results](#)..... 902
- [Examples: Managing Data](#)..... 906

11.9.1 General Data Storage and Loading Commands

See also:

- [FORMat \[: DATA \]](#) on page 812

FORMat:DEXPort:DSEPARATOR	881
MMEMory:CATalog?	882
MMEMory:CATalog:LONG?	882
MMEMory:CDIRectory	883
MMEMory:COMMeNt	883
MMEMory:COpy	884
MMEMory:DATA	884
MMEMory:DELeTe	884
MMEMory:MDIRectory	885
MMEMory:MOVe	885
MMEMory:MSIS	885
MMEMory:NAME	885
MMEMory:NETWork:DISConnect	886
MMEMory:NETWork:MAP	886
MMEMory:NETWork:UNUSeddrives?	886
MMEMory:NETWork:USEDdrives?	887
MMEMory:RDIRectory	887

FORMat:DEXPort:DSEPARATOR <Separator>

This command selects the decimal separator for data exported in ASCII format.

Parameters:

<Separator>

COMMa

Uses a comma as decimal separator, e.g. 4,05.

POINt

Uses a point as decimal separator, e.g. 4.05.

*RST: *RST has no effect on the decimal separator.
Default is POINt.

Example:

```
FORM:DEXP:DSEP POIN
```

Sets the decimal point as separator.

Manual operation: See ["Saving the Result Summary \(Evaluation List\) to a File"](#) on page 226
 See ["Saving the Evaluation List"](#) on page 249
 See ["Decimal Separator"](#) on page 417
 See ["Exporting the Peak List"](#) on page 460

MMEMory:CATalog? <Path>

This command returns the contents of a particular directory.

Query parameters:

<Path> String containing the path and directory
 If you leave out the path, the command returns the contents of the directory selected with `MMEMory:CDIRectory`.
 The path may be relative or absolute. Using wildcards (*) is possible to query a certain type of files only.
 If you use a specific file as a parameter, the command returns the name of the file if the file is found in the specified directory, or an error if the file is not found ("-256, "File name not found").

Return values:

<FileNames> List of file and directory names, separated by commas
 If no files are found, an error is displayed: "-256, "File name not found"

Example: `MMEM:CAT? 'C:\R_S\Instr\user\SPOOL?.PNG'`
 Returns all files in C:\R_S\Instr\user whose names start with SPOOL, have 6 letters and the extension ".PNG", e.g.:
 SPOOL1.PNG, SPOOL2.PNG, SPOOL3.PNG

Example: `MMEM:CAT? 'C:\R_S\Instr\user\SPOOL6.PNG'`
 Query whether the file 'SPOOL6.PNG' also exists in the directory;
Result:
 -256, "File name not found";MMEMory:CATalog? 'C:\R_S\Instr\user\SPOOL6.PNG'

Usage: Query only
 SCPI confirmed

Manual operation: See ["Selecting the Storage Location - Drive/ Path/ Files"](#) on page 224

MMEMory:CATalog:LONG? <Path>

This command returns the contents of a particular directory with additional information about the files.

Query parameters:

<Path> String containing the path and directory.
 If you leave out the path, the command returns the contents of the directory selected with `MMEMory:CDIRectory`.
 The path may be relative or absolute. Using wildcards ('*') is possible to query a certain type of files only.

Return values:

<UsedDiskSpace> Byte size of all files in the directory.
 <FreeDiskSpace> Remaining disk space in bytes.
 <FileInfo> <NameFileN>,<SuffixFileN>,<SizeFileN>
 Describes the individual file.
<NameFileN>
 Name of the file.
<SuffixFileN>
 Type of the file. Possible suffixes are: ASCii, BINary, DIRectory, STAT
<SizeFileN>
 Size of the file in bytes.

Usage: Query only

MMEMory:CDIRectory <Directory>

This command changes the current directory.

Parameters:

<Directory> String containing the path to another directory.
 The path may be relative or absolute.

Usage: SCPI confirmed

MMEMory:COMMeNT <Comment>

This command defines a comment for the stored settings.

Parameters:

<Comment> String containing the comment.

Example:

```
MMEMory:COMMeNT "ACP measurement with Standard
Tetra from 23.05."
MMEMory::MMEMory:STORel:STATe 1, "ACP_T"
As a result, in the selection list for recall settings, the comment
"ACP measurement with Standard Tetra from
23.05." is added to the ACP entry.
```

Manual operation: See "[Comment](#)" on page 488

MMEMory:COPY <SourceFile>,<DestinationFile>

This command copies one or more files to another directory.

Parameters:

<SourceFile> String containing the path and file name of the source file.

<DestinationFile> String containing the path and name of the target file.
The path may be relative or absolute.

Usage: SCPI confirmed

MMEMory:DATA <FileName>, [<Block>]

This command writes block data into a file. The delimiter must be set to EOI to obtain error-free data transfer.

When you query the contents of a file, you can save them in a file on the remote control computer.

The command is useful for reading stored settings files or trace data from the instrument or for transferring them to the instrument

Parameters:

<FileName> String containing the path and name of the target file.

<Block> Data block with the following structure.

#
Hash sign.

<number>
Length of the length information.

<number>
Length information of the binary data (number of bytes).

<data>
Binary data with the indicated <number> of bytes.

Example:

```
MMEM:NAME '\Public\User\Testfile.txt'
```

Creates a new file called 'testfile.txt'.

```
MMEM:DATA 'Testfile.txt',#220
```

Contents of the file

The parameter means:

#2: hash sign and length of the length information (20 bytes = 2 digits)

20: indicates the number of subsequent binary data bytes.

Contents of the file: store 20 binary bytes (characters) to the file.

Usage: SCPI confirmed

MMEMory:DELeTe <FileName>

This command deletes a file.

Parameters:

<FileName> String containing the path and file name of the file to delete.
The path may be relative or absolute.

Usage:

Event
SCPI confirmed

MMEMory:MDIRectory <Directory>

This command creates a new directory.

Parameters:

<Directory> String containing the path and new directory name
The path may be relative or absolute.

Usage:

Event

MMEMory:MOVE <SourceFile>,<NewFileName>

This command moves a file to another directory.

The command also renames the file if you define a new name in the target directory.

If you do not include a path for <NewFileName>, the command just renames the file.

Parameters:

<SourceFile> String containing the path and file name of the source file.
<NewFileName> String containing the path and name of the target file.

Example:

```
MMEM:MOVE 'C:\TEST01.CFG', 'SETUP.CFG'
```

Renames TEST01.CFG in SETUP.CFG in directory C:\.

Usage:

Event
SCPI confirmed

MMEMory:MSIS <Device>

This command selects the default storage device used by all MMEMory commands.

Parameters:

<Device> 'A:' | 'C:' | ... | 'Z:'
String containing the device drive name
*RST: 'C:'

Usage:

SCPI confirmed

MMEMory:NAME <FileName>

This command creates a new and empty file.

It also sets the file name for screenshots taken with `HCOpy[:IMMediate<device>]`.

Note that you have to route the printer output to a file.

Parameters:

<FileName> String containing the path and name of the target file.

Example:

MMEM:NAME 'C:\R_S\instr\user\PRINT1.BMP'
Selects the file name.

Usage:

Event
SCPI confirmed

MMEMory:NETWork:DISConnect <Drive>

This command disconnects a network drive.

Parameters:

<Drive> String containing the drive name.

Usage:

Event

MMEMory:NETWork:MAP <Drive>, <HostName> [, <UserName>, <Password>][, <Reconnect>]

This command maps a drive to a server or server directory of the network.

Note that you have to allow sharing for a server or folder in Microsoft networks first.

Parameters:

<Drive> String containing the drive name or path of the directory you want to map.

<HostName> String containing the host name of the computer or the IP address and the share name of the drive.
'<host name or IP address\share name>'

<UserName> String containing a user name in the network.
The user name is optional.

<Password> String containing the password corresponding to the <User-Name>.
The password is optional.

<Reconnect> ON | OFF
ON
Reconnects at logon with the same user name.
OFF
Does not reconnect at logon.

Usage:

Event

MMEMory:NETWork:UNUseddrives?

This command returns a list of unused network drives.

Return values:

<DriveName> List of network drives in alphabetically descending order, e.g. 'W:,V:,U:,...'

Usage: Query only

MMEMory:NETWork:USEDdrives? <State>

This command returns a list of all network drives in use.

Parameters:

<State> You do not have to use the parameter. If you do not include the parameter, the command returns a list of all drives in use. This is the same behavior as if you were using the parameter OFF.

ON

Returns a list of all drives in use including the folder information.

OFF

Returns a list of all drives in use.

Usage: Query only

MMEMory:RDIRECTory <Directory>

This command deletes the indicated directory.

Parameters:

<Directory> String containing the path of the directory to delete. Note that the directory you want to remove may contain no contents.

Usage: Event

11.9.2 Selecting the Items to Store

The following commands select the items to be included in the configuration file.

Depending on the used command, either the items from the entire instrument (MMEMory:SELEct[:ITEM] . . .), or only those from the currently selected channel (MMEM:SELEct:CHANnel[:ITEM] . . .) are stored.

MMEMory:SELEct:CHANnel[:ITEM]:ALL.....	888
MMEMory:SELEct[:ITEM]:ALL.....	888
MMEMory:SELEct:CHANnel[:ITEM]:DEFault.....	888
MMEMory:SELEct[:ITEM]:DEFault.....	888
MMEMory:SELEct:CHANnel[:ITEM]:HWSettings.....	888
MMEMory:SELEct[:ITEM]:HWSettings.....	888
MMEMory:SELEct:CHANnel[:ITEM]:LINes:ALL.....	889
MMEMory:SELEct[:ITEM]:LINes:ALL.....	889
MMEMory:SELEct:CHANnel[:ITEM]:NONE.....	889
MMEMory:SELEct[:ITEM]:NONE.....	889

<code>MMEMemory:SElect:CHANnel[:ITEM]:SGRam</code>	889
<code>MMEMemory:SElect[:ITEM]:SGRam</code>	889
<code>MMEMemory:SElect:CHANnel[:ITEM]:TRACe[:ACTive]</code>	890
<code>MMEMemory:SElect[:ITEM]:TRACe[:ACTive]</code>	890
<code>MMEMemory:SElect:CHANnel[:ITEM]:TRANsducer:ALL</code>	890
<code>MMEMemory:SElect[:ITEM]:TRANsducer:ALL</code>	890

MMEMemory:SElect:CHANnel[:ITEM]:ALL

MMEMemory:SElect[:ITEM]:ALL

This command includes all items when storing or loading a configuration file.

The items are:

- Hardware configuration: `MMEMemory:SElect[:ITEM]:HWSettings`
- Limit lines: `MMEMemory:SElect[:ITEM]:LINES:ALL`
- Spectrogram data: `MMEMemory:SElect[:ITEM]:SGRam`
- Trace data: `MMEMemory:SElect[:ITEM]:TRACe[:ACTive]`
- Transducers: `MMEMemory:SElect[:ITEM]:TRANsducer:ALL`

Example: `MME:SEL:ALL`

Usage: Event

Manual operation: See "Items" on page 488

MMEMemory:SElect:CHANnel[:ITEM]:DEFault

MMEMemory:SElect[:ITEM]:DEFault

This command selects the current settings as the only item to store to and load from a configuration file.

Usage: Event

Manual operation: See "Items" on page 488

MMEMemory:SElect:CHANnel[:ITEM]:HWSettings <State>

MMEMemory:SElect[:ITEM]:HWSettings <State>

This command includes or excludes measurement (hardware) settings when storing or loading a configuration file.

Measurement settings include:

- general channel configuration
- measurement hardware configuration including markers
- limit lines

Note that a configuration may include no more than 8 limit lines. This number includes active limit lines as well as inactive limit lines that were used last. Therefore the combination of inactivate limit lines depends on the sequence of use with `MMEMemory:LOAD:STATE`.
- color settings

- configuration for the hardcopy output

Parameters:

<State> ON | OFF | 0 | 1
 *RST: 1

Example: MMEM:SEL:HWS ON

Manual operation: See "Items" on page 488

MMEMory:SElect:CHANnel[:ITEM]:LINES:ALL <State>

MMEMory:SElect[:ITEM]:LINES:ALL <State>

This command includes or excludes all limit lines (active and inactive) when storing or loading a configuration file.

Parameters:

<State> ON | OFF
 *RST: OFF

Example: MMEM:SEL:LIN:ALL ON

Manual operation: See "Items" on page 488

MMEMory:SElect:CHANnel[:ITEM]:NONE

MMEMory:SElect[:ITEM]:NONE

This command does not include any of the following items when storing or loading a configuration file.

- Hardware configuration: [MMEMory:SElect\[:ITEM\]:HWSettings](#)
- Limit lines: [MMEMory:SElect\[:ITEM\]:LINES:ALL](#)
- Spectrogram data: [MMEMory:SElect\[:ITEM\]:SGRam](#)
- Trace data: [MMEMory:SElect\[:ITEM\]:TRACe\[:ACTive\]](#)
- Transducers: [MMEMory:SElect\[:ITEM\]:TRANsducer:ALL](#)

Example: MMEM:SEL:NONE

Usage: Event

Manual operation: See "Items" on page 488

MMEMory:SElect:CHANnel[:ITEM]:SGRam <State>

MMEMory:SElect[:ITEM]:SGRam <State>

This command includes or excludes spectrogram data when storing or loading a configuration file.

Parameters:

<State> ON | OFF
 *RST: OFF

Example: `MMEM:SEL:SGR ON`
Adds the spectrogram data to the list of data subsets.

MMEMory:SElect:CHANnel[:ITEM]:TRACe[:ACTiVe] <State>
MMEMory:SElect[:ITEM]:TRACe[:ACTiVe] <State>

This command includes or excludes trace data when storing or loading a configuration file.

Parameters:
<State> ON | OFF
*RST: OFF, i.e. no traces is stored

Example: `MMEM:SEL:TRAC ON`

Manual operation: See ["Items"](#) on page 488

MMEMory:SElect:CHANnel[:ITEM]:TRANsducer:ALL <State>
MMEMory:SElect[:ITEM]:TRANsducer:ALL <State>

This command includes or excludes transducer factors when storing or loading a configuration file.

Parameters:
<State> ON | OFF
*RST: OFF

Example: `MMEM:SEL:TRAN:ALL ON`

Manual operation: See ["Items"](#) on page 488
See ["Save"](#) on page 514

11.9.3 Storing and Loading Instrument Settings

See also:

- `INSTRument[:SElect]` on page 597 to select the channel.

<code>MMEMory:CLEar:ALL</code>	890
<code>MMEMory:CLEar:STATe</code>	891
<code>MMEMory:LOAD:AUTO</code>	891
<code>MMEMory:LOAD:STATe</code>	891
<code>MMEMory:LOAD:TYPE</code>	892
<code>MMEMory:STORe<n>:STATe</code>	893
<code>MMEMory:STORe<n>:STATe:NEXT</code>	894
<code>MMEMory:STORe<n>:TYPE</code>	894
<code>SYSTem:PRESet</code>	895
<code>SYSTem:PRESet:CHANnel[:EXECute]</code>	895

MMEMory:CLEar:ALL

This command deletes all instrument configuration files in the current directory.

You can select the directory with `MMEemory:CDIRectory`.

Example: `MMEM:CLE:ALL`

Usage: Event

MMEemory:CLEar:STATe 1,<FileName>

This command deletes a instrument configuration file.

Parameters:

1

<FileName> String containing the path and name of the file to delete.
The string may or may not contain the file's extension.

Example: `MMEM:CLE:STAT 1, 'TEST'`

Usage: Event

MMEemory:LOAD:AUTO 1, 'Factory' | <FileName>

This command restores an instrument configuration and defines that configuration as the default state.

The default state is restored after a preset (`*RST`) or after you turn on the R&S FPS.

Parameters:

1

'Factory' | **'Factory'**
<FileName> Restores the factory settings as the default state.

'<file_name>
String containing the path and name of the configuration file.
Note that only *instrument* settings files can be selected for the startup recall function; channel settings files cause an error.

Example: `MMEM:LOAD:AUTO 1, 'C:\R_S\Instr\user\TEST'`

Usage: Event

Manual operation: See "[Startup Recall](#)" on page 490

MMEemory:LOAD:STATe 1, <FileName>

This command restores and activates the instrument configuration stored in a *.dfl file.

Note that files with other formats cannot be loaded with this command.

The contents that are reloaded from the file are defined by the last selection made either in the "Save/Recall" dialogs (manual operation) or through the `MMEemory:SElect[:ITEM]` commands (remote operation; the settings are identical in both cases).

By default, the selection is limited to the user settings ("User Settings" selection in the dialogs, `HWSettings` in SCPI). The selection is not reset by PRESET or *RST.

As a consequence, the results of a SCPI script using the `MMEMemory:LOAD:STATe` command without a previous `MMEMemory:SElect[:ITEM]` command may vary, depending on previous actions in the GUI or in previous scripts, even if the script starts with the *RST command.

It is therefore recommended that you use the appropriate `MMEMemory:SElect[:ITEM]` command before using `MMEMemory:LOAD:STATe`.

Parameters:

1

<FileName> String containing the path and name of the file to load.
The string may or may not include the file's extension.

Example:

```
MMEM:SEL:ALL
//Save all items (User Settings, All Traces, All Limit Lines) from
the R&S FPS.
MME:LOAD:STAT 1, 'C:\R_S\Instr\user\TEST01'
//Reloads all items
In the "Recall" dialog, select only "User Settings" and "All Limit
Lines".
MME:LOAD:STAT 1, 'C:\R_S\Instr\user\TEST01'
//Reloads user settings and all limit lines.
*RST
//Reset instrument.
MME:LOAD:STAT 1, 'C:\R_S\Instr\user\TEST01'
//Selected items are retained. Reloads user settings and all limit
lines.
Restart the instrument.
(Switch the ON/OFF key off and on).
MME:LOAD:STAT 1, 'C:\R_S\Instr\user\TEST01'
// Selected items are set to default. Reloads only the user set-
tings.
```

Usage: SCPI confirmed

Manual operation: See ["Recall"](#) on page 485
See ["Recall in New Channel / Recall in Current Channel"](#)
on page 489

MMEMemory:LOAD:TYPE <Mode>

This command defines whether the channel-specific settings that will be loaded with the subsequent `MMEMemory:LOAD:STAT` command will replace the current channel or activate a new channel.

Parameters:

<Mode> NEW | REPLace

NEW

The loaded settings will be activated in a new channel.

REPLace

The loaded settings will replace the currently active channel.

*RST: NEW

Example:

INST:SEL 'SPECTRUM2'

Selects measurement channel 'SPECTRUM2'.

MMEM:STOR:TYP CHAN

Specifies that channel-specific data is to be stored.

MMEM:STOR:STAT 1, 'C:\R_S\Instr\user\Spectrum'

Stores the settings from channel 'SPECTRUM2' to the file

'C:\R_S\Instr\user\Spectrum'.

MMEM:LOAD:TYPE NEW

Specifies that channel-specific settings are to be activated in a new channel.

MMEM:LOAD:STAT 1, 'C:\R_S\Instr\user\Spectrum'

Loads the channel-specific settings from the file

'C:\R_S\Instr\user\Spectrum' to the new channel

'SPECTRUM2* '.

MMEMory:STORe<n>:STATe 1,<FileName>

This command saves the current instrument configuration in a *.dfl file.

The suffix <n> is irrelevant.

Secure User Mode

In secure user mode, settings that are to be stored on the instrument are stored to volatile memory, which is restricted to 256 MB. Thus, a "Memory full" error may occur although the hard disk indicates that storage space is still available.

To store data permanently, select an external storage location such as a USB memory device.

For details see [chapter 3.1.6, "Protecting Data Using the Secure User Mode"](#), on page 30.

For details see "Protecting Data Using the Secure User Mode" in the "Data Management" section of the R&S FPS User Manual.

Parameters:

1

<FileName> String containing the path and name of the target file.
The file extension is .dfl.**Example:**

MMEM:STOR:STAT 1, 'Save'

Saves the current instrument settings in the file Save.dfl.

Usage: Event
SCPI confirmed

Manual operation: See ["Save File"](#) on page 488
See ["Save"](#) on page 514

MMEMory:STORe<n>:STATe:NEXT

This command saves the current instrument configuration in a *.df1 file.

The suffix <n> is irrelevant.

The file name depends on the one you have set with `MMEMory:STORe<n>:STATe`. This command adds a consecutive number to the file name.

Secure User Mode

In secure user mode, settings that are to be stored on the instrument are stored to volatile memory, which is restricted to 256 MB. Thus, a "Memory full" error may occur although the hard disk indicates that storage space is still available.

To store data permanently, select an external storage location such as a USB memory device.

For details see [chapter 3.1.6, "Protecting Data Using the Secure User Mode"](#), on page 30.

For details see "Protecting Data Using the Secure User Mode" in the "Data Management" section of the R&S FPS User Manual.

Example:

```
MMEM:STOR:STAT 1, 'Save'
```

Saves the current instrument settings in the file `Save.df1`.

```
MMEM:STOR:STAT:NEXT
```

Saves the current instrument settings in the file `Save_001.df1`

```
MMEM:STOR:STAT:NEXT
```

Saves the current instrument settings in the file `Save_002.df1`

Usage: Event

Manual operation: See ["Save File"](#) on page 488

MMEMory:STORe<n>:TYPE <Mode>

This command defines whether the data from the entire instrument or only from the current channel is stored with the subsequent `MMEM:STOR...` command.

The suffix <n> is irrelevant.

Parameters:

<Mode> INSTrument | CHANnel
INSTrument
 Stores data from the entire instrument.
CHANnel
 Stores data from an individual channel.
 *RST: INST

Example:

```
INST:SEL 'SPECTRUM2'
Selects measurement channel 'SPECTRUM2'.
MMEM:STOR:TYPE CHAN
Specifies that channel-specific data is to be stored.
```

SYSTem:PRESet

This command presets the R&S FPS.

Example: SYST:PRES

Usage: Event
 SCPI confirmed

SYSTem:PRESet:CHANnel[:EXECute]

This command restores the default instrument settings in the current channel.

Use `INST:SEL` to select the channel.

For details see [chapter 8.1.1, "Factory Default Configuration"](#), on page 479.

Example: INST 'Spectrum2'
 Selects the channel for "Spectrum2".
 SYST:PRES:CHAN:EXEC
 Restores the factory default settings to the "Spectrum2" channel.

Usage: Event

Manual operation: See "[Preset Channel](#)" on page 292

11.9.4 Storing or Printing Screenshots

Useful commands to configure screenshots described elsewhere

- [MMEMory:NAME](#) on page 885

Remote commands exclusive to configure screenshots

DISPlay:LOGO	896
HCOPy:ABORt	896
HCOPy:CMAP<item>:DEFault<colors>	896
HCOPy:CMAP<item>:HSL	897

HCOPY:CMAP<item>:PDEFined.....	897
HCOPY:DESTination<device>.....	898
HCOPY:DEvice:COLor.....	898
HCOPY:DEvice:LANGuage<device>.....	899
HCOPY[:IMMediate<device>].....	899
HCOPY[:IMMediate<device>]:NEXT.....	899
HCOPY:ITEM:ALL.....	900
HCOPY:ITEM:WINDow:TEXT.....	900
HCOPY:PAGE:ORlentation<device>.....	900
HCOPY:TDSTamp:STATe<device>.....	900
SYSTem:COMMunicate:PRINter:ENUMerate:FIRSt?.....	901
SYSTem:COMMunicate:PRINter:ENUMerate[:NEXT]?.....	901
SYSTem:COMMunicate:PRINter:SElect<device>.....	901

DISPlay:LOGO <State>

Activates/deactivates the printout of the Rohde & Schwarz company logo in the upper left corner.

Parameters:

<State> ON | OFF
 *RST: ON

Example: DISP:LOGO OFF

Manual operation: See "[Print Logo](#)" on page 502

HCOPY:ABORt

This command aborts a running hardcopy output.

Example: HCOPY:ABOR

Usage: Event
 SCPI confirmed

HCOPY:CMAP<item>:DEFault<colors>

This command defines the color scheme for print jobs.

Suffix:

<item> Selects the item for which the color scheme is to be defined.
 For more information see [chapter 11.10.4.3, "CMAP Suffix Assignment"](#), on page 922.

<colors> 1...4
 1
 Current colors with a white background and a black grid.
 2
 Optimized colors.
 3
 Customized colors.
 4
 Current screen colors (setting for hardcopies).

Example: HCOPY:CMAP:DEF2
 Selects the optimized color set for the color settings of a printout or a hardcopy.

Usage: Event

Manual operation: See "[Print colors](#)" on page 534

HCOPY:CMAP<item>:HSL <Color>

This command selects the color for various screen elements in print jobs.

Suffix:
 <item> Selects the item for which the color scheme is to be defined. For more information see [chapter 11.10.4.3, "CMAP Suffix Assignment"](#), on page 922.

Parameters:

<Color> **hue**
 tint
sat
 saturation
lum
 brightness
 The value range is 0 to 1 for all parameters.

Example: HCOPY:CMAP2:HSL 0.3,0.8,1.0
 Changes the grid color

Manual operation: See "[Defining User-specific Colors](#)" on page 535

HCOPY:CMAP<item>:PDEFined <Color>

This command selects a predefined color for various screen elements in print jobs.

Suffix:
 <item> Selects the item for which the color scheme is to be defined. For more information see [chapter 11.10.4.3, "CMAP Suffix Assignment"](#), on page 922.

Parameters:

<Color> BLACK | BLUE | BROWN | GREEN | CYAN | RED | MAGENTA |
 YELLOW | WHITE | DGRAY | LGRAY | LBLUE | LGREEN |
 LCYAN | LRED | LMAGENTA

Example:

HCOP:CMAP2:PDEF GRE

Manual operation: See "Predefined Colors" on page 535

HCOPY:DESTINATION<device> <Destination>

This command selects the destination of a print job.

Suffix:

<device> 1 | 2
 Printing device.

Parameters:

<Destination>

'MMEM'

Sends the hardcopy to a file.

You can select the file name with `MMEMory:NAME`.

You can select the file format with `HCOPY:DEVICE:LANGUage<device>`.

'SYST:COMM:PRIN'

Sends the hardcopy to a printer.

You can select the printer with `SYSTEM:COMMunicate:PRINter:SElect<device>`.

'SYST:COMM:CLIP'

Sends the hardcopy to the clipboard.

The format should be WEMF.

*RST: 'SYST:COMM:CLIP'

Usage:

SCPI confirmed

Manual operation: See "Device" on page 503

HCOPY:DEVICE:COLOR <State>

This command turns color printing on and off.

Parameters:

<State> **ON**
 Color printing
OFF
 Black and white printing
 *RST: OFF

Example:

HCOP:DEV:COL ON

Usage:

SCPI confirmed

HCOPY:DEVICE:LANGUage<device> <Format>

This command selects the file format for a print job.

Suffix:

<device> 1 | 2
Printing device.

Parameters:

<Format>

GDI

Graphics Device Interface.

Default format for the output to a printer configured under Windows. Must be selected for the output to the printer interface.

Can be used for the output to a file. The printer driver configured under Windows is used in this case and a printer-specific file format is thus generated.

BMP, JPG, PNG

Data format for output to files only.

Usage: SCPI confirmed

Manual operation: See "[Output Medium](#)" on page 502

HCOPY[:IMMEDIATE<device>]

This command initiates a print job.

If you are printing to a file, the file name depends on [MMEMory:NAME](#).

Suffix:

<device> 1 | 2
Printing device.

Usage: Event
SCPI confirmed

Manual operation: See "[Printing or Storing a Screenshot \(Print Screen\)](#)" on page 501

HCOPY[:IMMEDIATE<device>]:NEXT

This command initiates a print job.

If you are printing to a file, the file name depends on [MMEMory:NAME](#). This command adds a consecutive number to the file name.

Suffix:

<device> 1 | 2
Printing device.

Usage: Event

Manual operation: See "[Printing or Storing a Screenshot \(Print Screen\)](#)" on page 501

HCOPY:ITEM:ALL

This command includes all screen elements in the printout.

The screen elements include comments, title, time and date.

Usage: SCPI confirmed

Manual operation: See ["Printing or Storing a Screenshot \(Print Screen\)"](#) on page 501

HCOPY:ITEM:WINDOW:TEXT <Comment>

This command defines a comment to be added to the printout.

Parameters:

<Comment> String containing the comment.

Usage: SCPI confirmed

Manual operation: See ["Comment"](#) on page 503

HCOPY:PAGE:ORIENTATION<device> <Orientation>

The command selects the format of the print job.

The command is only available if the output device is a printer.

Suffix:

<device> 1 | 2
Printing device.

Parameters:

<Orientation> LANDscape | PORTRait
*RST: PORTRait

Usage: SCPI confirmed

Manual operation: See ["Orientation"](#) on page 503

HCOPY:TDSTAMP:STATE<device> <State>

This command includes or excludes the time and date in the printout.

Suffix:

<device> 1 | 2
Printing device.

Parameters:

<State> ON | OFF
*RST: OFF

Manual operation: See ["Print Date and Time"](#) on page 502

SYSTem:COMMunicate:PRINter:ENUMerate:FIRSt?

This command queries the name of the first available printer.

To query the name of other installed printers, use `SYSTem:COMMunicate:PRINter:ENUMerate[:NEXT]?`.

Return values:

<PrinterName> String containing the name of the first printer as defined in Windows.
If the command cannot find a printer, it returns an empty string ('').

Usage: Query only

Manual operation: See "Printer Name" on page 503

SYSTem:COMMunicate:PRINter:ENUMerate[:NEXT]?

This command queries the name of available printers.

You have to use `SYSTem:COMMunicate:PRINter:ENUMerate:FIRSt?` for this command to work properly.

Return values:

<PrinterName> String containing the name of one printer as defined in Windows. To get a complete list of printers you have to send this query several times until no more printers could be found. In that case, the return value is an empty string (' '). Further queries after the empty string result in an error.

Usage: Query only

Manual operation: See "Printer Name" on page 503

SYSTem:COMMunicate:PRINter:SELEct<device> <PrinterName>

This command selects the printer that processes jobs sent by the R&S FPS.

Use `HCOpy:DESTination<device>` to select another output destination.

Suffix:

<device> 1 | 2
Printing device.

Parameters:

<PrinterName> String containing the printer name.
Use

- `SYSTem:COMMunicate:PRINter:ENUMerate:FIRSt?` and
- `SYSTem:COMMunicate:PRINter:ENUMerate[:NEXT]?`

to query all available printers.

*RST: NONE

Manual operation: See "Printer Name" on page 503

11.9.5 Storing Measurement Results

The following commands can be used to store the results of a measurement.

Useful commands for storing results described elsewhere:

- [FORMat \[: DATA \]](#) on page 812

Remote commands exclusive to storing results:

FORMat:DEXPort:HEADer	902
FORMat:DEXPort:TRACes	902
MMEMory:STORe<n>:LIST	903
MMEMory:STORe<n>:PEAK	903
MMEMory:STORe<n>:SGRam	904
MMEMory:STORe<n>:SPECtrogram	904
MMEMory:STORe<n>:SPURious	905
MMEMory:STORe<n>:TRACe	905

FORMat:DEXPort:HEADer <State>

If enabled, additional instrument and measurement settings are included in the header of the export file for result data. If disabled, only the pure result data from the selected traces and tables is exported.

See [chapter 8.4.4, "Reference: ASCII File Export Format"](#), on page 497 for details.

Parameters:

<State> ON | OFF | 0 | 1
 *RST: 1

Usage: SCPI confirmed

Manual operation: See ["Include Instrument Measurement Settings"](#) on page 416

FORMat:DEXPort:TRACes <Selection>

This command selects the data to be included in a data export file (see [MMEMory:STORe<n>:TRACe](#) on page 905).

For details on exporting data see [chapter 7.3.2.3, "Trace / Data Export Configuration"](#), on page 415.

Parameters:

<Selection>

SINGLE

Only a single trace is selected for export, namely the one specified by the `MMEMoRY:STORe<n>:TRACe` command.

ALL

Selects all active traces and result tables (e.g. Result Summary, marker peak list etc.) in the current application for export to an ASCII file.

The <trace> parameter for the `MMEMoRY:STORe<n>:TRACe` command is ignored.

*RST: SINGLE

Usage:

SCPI confirmed

Manual operation: See "[Export all Traces and all Table Results](#)" on page 416

MMEMoRY:STORe<n>:LIST <FileName>

This command exports the SEM and spurious emission list evaluation to a file.

The file format is *.dat.

Secure User Mode

In secure user mode, settings that are to be stored on the instrument are stored to volatile memory, which is restricted to 256 MB. Thus, a "Memory full" error may occur although the hard disk indicates that storage space is still available.

To store data permanently, select an external storage location such as a USB memory device.

For details see [chapter 3.1.6, "Protecting Data Using the Secure User Mode"](#), on page 30.

For details see "Protecting Data Using the Secure User Mode" in the "Data Management" section of the R&S FPS User Manual.

Parameters:

<FileName>

String containing the path and name of the target file.

Example:

```
MMEMoRY:STOR:LIST 'test'
```

Stores the current list evaluation results in the `test.dat` file.

Manual operation: See "[Saving the Result Summary \(Evaluation List\) to a File](#)" on page 226
See "[Saving the Evaluation List](#)" on page 249

MMEMoRY:STORe<n>:PEAK <FileName>

This command exports the marker peak list to a file.

Secure User Mode

In secure user mode, settings that are to be stored on the instrument are stored to volatile memory, which is restricted to 256 MB. Thus, a "Memory full" error may occur although the hard disk indicates that storage space is still available.

To store data permanently, select an external storage location such as a USB memory device.

For details see [chapter 3.1.6, "Protecting Data Using the Secure User Mode"](#), on page 30.

For details see "Protecting Data Using the Secure User Mode" in the "Data Management" section of the R&S FPS User Manual.

Parameters:

<FileName> String containing the path, name and extension of the target file.

Example:

```
MMEM:STOR:PEAK 'test.dat'
```

Saves the current marker peak list in the file `test.dat`.

Usage:

Event

Manual operation: See ["Exporting the Peak List"](#) on page 460

MMEMory:STORe<n>:SGRam <FileName>

MMEMory:STORe<n>:SPECTrogram <FileName>

This command exports spectrogram data to an ASCII file.

The file contains the data for every frame in the history buffer. The data corresponding to a particular frame begins with information about the frame number and the time that frame was recorded.

Note that, depending on the size of the history buffer, the process of exporting the data can take a while.

Secure User Mode

In secure user mode, settings that are to be stored on the instrument are stored to volatile memory, which is restricted to 256 MB. Thus, a "Memory full" error may occur although the hard disk indicates that storage space is still available.

To store data permanently, select an external storage location such as a USB memory device.

For details see [chapter 3.1.6, "Protecting Data Using the Secure User Mode"](#), on page 30.

For details see "Protecting Data Using the Secure User Mode" in the "Data Management" section of the R&S FPS User Manual.

Parameters:

<FileName> String containing the path and name of the target file.

Example:

```
MMEM:STOR:SGR 'Spectrogram'
```

Copies the spectrogram data to a file.

Manual operation: See ["Export Trace to ASCII File"](#) on page 417

MMEMory:STORe<n>:SPURious <FileName>

This command exports the marker peak list available for spurious emission measurements to a file.

The suffix <n> is irrelevant.

Secure User Mode

In secure user mode, settings that are to be stored on the instrument are stored to volatile memory, which is restricted to 256 MB. Thus, a "Memory full" error may occur although the hard disk indicates that storage space is still available.

To store data permanently, select an external storage location such as a USB memory device.

For details see [chapter 3.1.6, "Protecting Data Using the Secure User Mode"](#), on page 30.

For details see "Protecting Data Using the Secure User Mode" in the "Data Management" section of the R&S FPS User Manual.

Parameters:

<FileName> String containing the path and name of the target file.

Example:

```
MMEM:STOR:SPUR 'test'
```

Saves the current marker peak list in the file test.dat.

Usage:

Event

MMEMory:STORe<n>:TRACe <Trace>, <FileName>

This command exports trace data from the specified window to an ASCII file.

For details on the file format see [chapter 8.4.4, "Reference: ASCII File Export Format"](#), on page 497.

Secure User Mode

In secure user mode, settings that are to be stored on the instrument are stored to volatile memory, which is restricted to 256 MB. Thus, a "Memory full" error may occur although the hard disk indicates that storage space is still available.

To store data permanently, select an external storage location such as a USB memory device.

For details see [chapter 3.1.6, "Protecting Data Using the Secure User Mode"](#), on page 30.

For details see "Protecting Data Using the Secure User Mode" in the "Data Management" section of the R&S FPS User Manual.

Parameters:

<Trace> Number of the trace to be stored
(This parameter is ignored if the option "Export all Traces and all Table Results" is activated in the Export configuration settings, see [FORMat:DEXPort:TRACes](#) on page 902).

<FileName> String containing the path and name of the target file.

Example: MMEM:STOR1:TRAC 3, 'C:\TEST.ASC'
Stores trace 3 from window 1 in the file TEST.ASC.

Usage: SCPI confirmed

Manual operation: See "Export Trace to ASCII File" on page 417

11.9.6 Examples: Managing Data

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• Loading Data.....	907
• Storing Instrument Settings.....	907
• Loading Instrument Settings.....	907
• Printing to a File.....	908
• Printing on a Printer.....	908

11.9.6.1 Storing Data

```

MMEM:MSIS 'C:'
//Selects drive C: as the default storage device.
-----Connecting a network drive-----
MMEM:NETW:USED?
//Returns a list of all drives in use in the network.
MMEM:NETW:UNUS?
//Returns a list of free drive names in the network.
MMEM:NETW:MAP 'T:', 'Server\ACLRTest'
//Maps drive T: to the directory 'Server\ACLRTest'
-----Saving data on the instrument-----
MMEM:MDIR 'C:\R_S\INST\USER\ACLRTest'
//Creates a directory called 'ACLRTest' on drive C:
MMEM:NAME 'C:\R_S\INST\USER\Test001.txt'
//Creates a file called 'Test001.txt'
MMEM:COMM 'ACLR test results'
//Creates a comment for the file.
MMEM:DATA 'Test001.txt', #212FileContents
//Writes 12 characters to the file 'Test001.txt'
-----Copying the data to another location---
MMEM:COPY 'C:\R_S\INST\USER\Results\Test001.txt', 'T:'
//Copies the specified file to network drive T:.
MMEM:DEL 'C:\R_S\INST\USER\Results\Test001.txt'
//Deletes the specified file from the instrument hard disk.
//or
MMEM:MOVE 'C:\R_S\INST\USER\Results\Test001.xml', 'D:\TestResults.txt'//
//Moves the file 'Test001.txt' to drive T:, renames it to 'Testresults.txt'
//and removes it from the instrument hard disk.
MMEM:RDIR 'C:\R_S\INST\USER\Results'
//Deletes the directory called 'Results' from drive C:, unless it still contains any content.
-----Disconnecting the network drive---

```

```
MMEM:NETW:DISC 'T:'
//Disconnect drive T:.
```

11.9.6.2 Loading Data

```
MMEM:CDir?
//Returns the path of the current directory.
//e.g.
C:\R_S\Instr\user\
MMEM:CDir 'C:\R_S\INST\USER\Results'
//Changes the current directory.
MMEM:CAT? 'C:\R_S\INST\USER\Results\*.xml'
//or
MMEM:CAT? '*.xml'
//Returns a list of all xml files in the directory 'C:\R_S\INST\USER\Results'.
MMEM:CAT:LONG? '*.xml'
//Returns additional information about the xml files in the directory 'C:\R_S\INST\USER\Results'.
```

11.9.6.3 Storing Instrument Settings

In this example we will store the instrument settings for the "Spectrum" channel.

```
INST:SEL 'SPECTRUM'
//Selects measurement channel 'SPECTRUM'.
MEMM:STOR:TYPE CHAN
//Specifies that channel-specific data is to be stored.
MMEM:STOR:STAT 1, 'C:\R_S\Instr\user\Spectrum'
//Stores the channel settings from the 'Spectrum' channel
// to the file 'Spectrum.dfl'.
```

11.9.6.4 Loading Instrument Settings

In this example we will load the hardware settings from the configuration file Spectrum.dfl to a new "Spectrum2" channel.

```
MEMM:LOAD:TYPE NEW
//Specifies that settings will be loaded to a new channel besides the existing
//'Spectrum' channel.
MMEM:SEL:CHAN:HWS ON
//Selects only hardware settings to be loaded.
MMEM:LOAD:STAT 1, 'C:\R_S\Instr\user\Spectrum'
//Loads the channel-specific settings from the file 'C:\R_S\Instr\user\Spectrum.dfl'
//to a new channel. The new channel is named 'Spectrum2' to avoid a naming conflict
//with the existing 'Spectrum' channel.
INST:REN 'Spectrum2','Spectrum3'
//Renames the loaded channel to 'Spectrum3'.
```

11.9.6.5 Printing to a File

```

HCOP:DEST 'MMEM'
//Prints the data to a file.
HCOP:DEV:LANG BMP
//Selects bmp as the file format.
MMEM:NAME 'C:\R_S\INST\USER\Screenshot.bmp'
//Selects the file name for the printout.
HCOP:ITEM:ALL
//Prints all screen elements
HCOP:ITEM:WIND:TEXT 'ACLRResults'
//Adds a comment to the printout.
HCOP
//Stores the printout in a file called 'Screenshot.bmp'.
HCOP:NEXT
//Stores the printout in a file called 'Screenshot_001.bmp'.

```

11.9.6.6 Printing on a Printer

```

HCOP:DEST2 'SYST:COMM:PRIN'
//Prints the data on a printer.
SYST:COMM:PRIN:ENUM:FIRS?
SYST:COMM:PRIN:ENUM?
//Returns the available printers, e.g.
'LASER on LPT1'
''
//Means that one printer is available.
SYST:COMM:PRIN:SEL2 'LASER on LPT1'
//Selects the printer for the print job on device 2.
HCOP:PAGE:ORI2 LAND
//Selects the landscape format for the printout.
HCOP:TDST:STAT2 ON
//Includes date and time on the printout.
HCOP:ITEM:ALL
//Prints all screen elements
HCOP
//Initiates the printout.

```

11.10 Configuring the R&S FPS

The remote commands required to set up the R&S FPS are described here.

- [Configuring the Reference Frequency](#)..... 909
- [Calibration and Temperature Checks](#)..... 910
- [Working with Transducers](#).....914
- [Customizing the Screen Layout](#)..... 917

- [Configuring the Network and Remote Control](#)..... 923
- [Checking the System Configuration](#)..... 926
- [Using Service Functions](#)..... 932

11.10.1 Configuring the Reference Frequency

[SENSe:]ROSCillator:O640	909
SOURce:EXTernal:ROSCillator:EXTernal:FREQuency	909
[SENSe:]ROSCillator:SOURce	909
[SENSe:]ROSCillator:SOURce:EAUTO?	910

[SENSe:]ROSCillator:O640 <State>

If enabled, a 640 MHz reference signal is provided to the REF OUTPUT 640 MHz connector.

Parameters:

<State> ON | OFF
 *RST: OFF

Example: ROSC:O640 ON

SOURce:EXTernal:ROSCillator:EXTernal:FREQuency <Frequency>

This command defines the frequency of the external reference oscillator.

If the external reference oscillator is selected, the reference signal must be connected to the rear panel of the instrument.

Parameters:

<Frequency> Range: 1 MHz to 20 MHz

Example:

```
ROSC:EXT:FREQ 13MHZ
Sets the frequency to 13 MHz.
SOUR:EXT:ROSC:EXT:FREQ 13MHZ
```

Manual operation: See "[Reference Frequency Input](#)" on page 508

[SENSe:]ROSCillator:SOURce <Source>

This command selects the reference oscillator.

If you want to select the external reference, it must be connected to the R&S FPS.

Parameters:

<Source>

INTernal

the internal reference is used (10 MHz)

EXTernal

the external reference from REF INPUT 1..20 MHz connector is used with a variable frequency; if none is available, an error flag is displayed in the status bar

E10

the external reference from REF INPUT 1..20 MHz connector is used with a fixed 10 MHz frequency; if none is available, an error flag is displayed in the status bar

EAUTO

the external reference is used as long as it is available, then the instrument switches to the internal reference

Example:

ROSC:SOUR EXT

Usage:

SCPI confirmed

Manual operation:See ["Reference Frequency Input"](#) on page 508
See ["Behavior in case of missing external reference"](#) on page 509**[SENSe:]ROSCillator:SOURce:EAUTO?**

This command queries the current reference type in case you have activated an automatic switch to the internal reference if the external reference is missing.

Parameters:

<Reference>

INT

internal reference

EXT

external reference

Example:

SENS:ROSC:SOUR:EAUT?

Queries the currently available reference type.

Usage:

Query only

Manual operation:See ["Behavior in case of missing external reference"](#) on page 509

11.10.2 Calibration and Temperature Checks

The following commands control calibration and temperature checks on the R&S FPS.

CALibration[:ALL]?	911
CALibration:RESult?	911
DIAGnostic:SERVice:INPut:PULSed:CFRequency	912
DIAGnostic<n>:SERVice:INPut:PULSed:MCFRequency	912
DIAGnostic:SERVice:INPut:PULSed:WBFRequency	912

DIAGnostic:SERvice:INPut:RF:SPEctrum.....	913
DIAGnostic:SERvice:INPut[:SElect].....	913
DIAGnostic:SERvice:STEst:RESult?.....	913
SOURce:TEMPerature:FRONtend?.....	914

CALibration[:ALL]?

This command initiates a calibration (self-alignment) routine and queries if calibration was successful.

During the acquisition of correction data the instrument does not accept any remote control commands.

In order to recognize when the acquisition of correction data is completed, the MAV bit in the status byte can be used. If the associated bit is set in the Service Request Enable (SRE) register, the instrument generates a service request after the acquisition of correction data has been completed.

Return values:

<CalibrationState> **0**
The command returns a '0' if calibration was successful.

Example:

```
*CLS
Resets the status management.
*SRE 16
Enables MAV bit in the Service Request Enable register.
*CAL?
Starts the correction data recording, and then a service request
is generated.
```

Usage: Query only
SCPI confirmed

Manual operation: See "[Self align](#)" on page 41
See "[Starting a Self-alignment](#)" on page 515

CALibration:RESult?

This command returns the results collected during calibration.

Return values:

<CalibrationData> String containing the calibration data.

Example:

```
CAL:RES?
would return, e.g.
Total Calibration Status:
PASSED, Date (dd/mm/yyyy): 12/07/2004,
Time: 16:24:54, Runtime: 00.06
```

Usage: Query only

Manual operation: See "[Alignment Results](#)" on page 515

DIAGnostic:SERVice:INPut:PULSed:CFrequency <Frequency>

This command defines the frequency of the calibration signal.

Before you can use the command, you have to feed in a calibration signal with

[DIAGnostic:SERVice:INPut\[:SElect\]](#).

Parameters:

<Frequency>

Possible frequencies of the calibration signal are fix. If you define a frequency that is not available, the R&S FPS uses the next available frequency. Example: a frequency of 20 MHz is rounded up to the next available frequency (21.33 MHz).

*RST: 64 MHz

Default unit: Hz

Manual operation: See ["Calibration Frequency RF"](#) on page 525

DIAGnostic<n>:SERVice:INPut:PULSed:MCFrequency <Frequency>

This command sets the calibration frequency for frequencies greater than 7 GHz. This command only takes effect if a microwave calibration signal is selected for input ([DIAGnostic:SERVice:INPut\[:SElect\]](#) on page 913).

Suffix:

<n> irrelevant

Parameters:

<Frequency>

<numeric value>

*RST: 7 GHz

Example:

DIAG:SERV:INP:PULS:MCFR 7,1 GHz

Usage:

SCPI confirmed

Manual operation: See ["Calibration Frequency MW"](#) on page 525

DIAGnostic:SERVice:INPut:PULSed:WBFrequency <Frequency>

Defines the frequency of the internal broadband calibration signal to be used for IF filter calibration.

This command is only available if the bandwidth extension option R&S FPS-B160 is installed.

Before you can use the command, you have to feed in a calibration signal with

[DIAGnostic:SERVice:INPut\[:SElect\]](#) on page 913.

Parameters:

<Frequency>

2 MHz | 4 MHz | 8 MHz | 16 MHz

If you define a frequency that is not available, the R&S FPS uses the next available frequency.

*RST: 16 MHz

Example: `DIAG:SERV:INP:PULS:WBFR 8 MHz`
Defines a calibration signal frequency of 8 MHz.

Example: `DIAG:SERV:INP:SEL WBC`
`DIAG:SERV:INP:PULS:WBFR 4MHz`

Manual operation: See "[Calibration Frequency Wideband](#)" on page 525

DIAGnostic:SERVice:INPut:RF:SPECTrum <Bandwidth>

This command selects the bandwidth of the calibration signal.

Parameters:

<Bandwidth> **NARRowband**
Narrowband signal for power calibration of the frontend.

BROadband
Broadband signal for calibration of the IF filter.

Manual operation: See "[Spectrum](#)" on page 525

DIAGnostic:SERVice:INPut[:SELEct] <Signal>

This command activates or deactivates the use of an internal calibration signal as input for the R&S FPS.

Parameters:

<Signal> **CALibration**
Uses the calibration signal as RF input.

MCALibration
Uses the calibration signal for the microwave range as RF input.

RF
Uses the signal from the RF input.

WBCal
Uses the wideband calibration signal (requires bandwidth extension option R&S FPS-B160)

*RST: RF

Example: `DIAG:SERV:INP CAL`
Uses the calibration signal as RF input.

Manual operation: See "[None](#)" on page 524
See "[Calibration Frequency RF](#)" on page 525
See "[Calibration Frequency MW](#)" on page 525
See "[Calibration Frequency Wideband](#)" on page 525

DIAGnostic:SERVice:STESt:RESult?

This command queries the self test results.

Return values:

<Results> String of data containing the results.
The rows of the self test result table are separated by commas.

Example:

```
DIAG:SERV:STES:RES?
would return, e.g.
"Total Selftest Status:
PASSED", "Date (dd/mm/yyyy): 09/07/2004 TIME:
16:24:54", "Runtime: 00:06", "...
```

Usage: Query only

Manual operation: See "[Selftest](#)" on page 41

SOURce:TEMPerature:FRONtend?

This command queries the current frontend temperature of the R&S FPS.

During self-alignment, the instrument's (frontend) temperature is also measured (as soon as the instrument has warmed up completely). This temperature is used as a reference for a continuous temperature check during operation. If the current temperature deviates from the stored self-alignment temperature by a certain degree, a warning is displayed in the status bar indicating the resulting deviation in the measured power levels. A status bit in the `STATUS:QUESTIONable:TEMPerature` register indicates a possible deviation.

Return values:

<Temperature> Temperature in degrees Celsius.

Example:

```
SOUR:TEMP:FRON?
Queries the temperature of the frontend sensor.
```

Usage: Query only

11.10.3 Working with Transducers

The following commands configure and control transducer factors.

Useful commands for transducer management described elsewhere

- `MMEMemory:SElect[:ITEM]:TRANsdncer:ALL` on page 890

Remote commands exclusive to transducer management

<code>[SENSe:]CORRection:TRANsdncer:ADJust:RLEVel[:STATe]</code>	915
<code>[SENSe:]CORRection:TRANsdncer:COMMeNt</code>	915
<code>[SENSe:]CORRection:TRANsdncer:DATA</code>	915
<code>[SENSe:]CORRection:TRANsdncer:DELeTe</code>	916
<code>[SENSe:]CORRection:TRANsdncer:SCALing</code>	916
<code>[SENSe:]CORRection:TRANsdncer:SELeCt</code>	916
<code>[SENSe:]CORRection:TRANsdncer[:STATe]</code>	916
<code>[SENSe:]CORRection:TRANsdncer:UNIT</code>	916

[SENSe:]CORRection:TRANsducer:ADJust:RLeVel[:STATe] <State>

This command turns an automatic adjustment of the reference level to the transducer on and off.

Before you can use the command, you have to select and turn on a transducer.

Parameters:

<State> ON | OFF
*RST: OFF

Manual operation: See ["Adjusting the Reference Level"](#) on page 511

[SENSe:]CORRection:TRANsducer:COMMeNt <Comment>

This command defines the comment for the selected transducer factor.

Before you can use the command, you have to select and turn on a transducer.

Parameters:

<Comment> *RST: (empty comment)

Manual operation: See ["Comment"](#) on page 513

**[SENSe:]CORRection:TRANsducer:DATA
<Frequency>,<Level>[,<Frequency>,<Level>]**

This command configures transducer factors for specific trace points. A set of transducer factors defines an interpolated transducer line and can be stored on the instrument.

For details see [chapter 9.2, "Basics on Transducer Factors"](#), on page 506.

Parameters:

<Frequency> The unit for <Frequency> is Hz, which may or may not be omitted. Frequencies have to be sorted in ascending order.
<Level> The unit for <Level> depends on [\[SENSe:\]CORRection:TRANsducer:UNIT](#).

Example:

```
SENSe1:CORRection:TRANsducer:UNIT 'DB'  
// Frequency Span 0 Hz to 4 Ghz  
SENSe1:CORRection:TRANsducer:DATA 0,8,2e6,5,4GHz,3
```

Creates the transducer points:

Manual operation: See ["Data points"](#) on page 513

Frequency	Level
0 Hz	8 dB
2 GHz	5 dB
4 GHz	3 dB

[SENSe:]CORRection:TRANsducer:DELeTe

This command deletes the currently selected transducer factor.

Before you can use the command, you have to select a transducer.

Example: CORR:TRAN:DEL

Usage: Event

Manual operation: See "[Delete Line](#)" on page 512

[SENSe:]CORRection:TRANsducer:SCALing <ScalingType>

This command selects the frequency scaling of the transducer factor.

Parameters:

<ScalingType> LINear | LOGarithmic

*RST: LINear

Manual operation: See "[X-Axis Scaling](#)" on page 513

[SENSe:]CORRection:TRANsducer:SELEct <Name>

This command selects a transducer factor.

Parameters:

<Name> String containing the name of the transducer factor.
If the name does not exist yet, the R&S FPS creates a transducer factor by that name.

Example: CORR:TRAN:SEL 'FACTOR1'

Manual operation: See "[Activating/Deactivating](#)" on page 511
See "[Create New Line](#)" on page 512
See "[Name](#)" on page 513

[SENSe:]CORRection:TRANsducer[:STATe] <State>

This command turns the selected transducer factor on or off.

Before you can use the command, you have to select a transducer.

Parameters:

<State> ON | OFF

*RST: OFF

Manual operation: See "[Activating/Deactivating](#)" on page 511

[SENSe:]CORRection:TRANsducer:UNIT <Unit>

This command selects the unit of the transducer factor.

Before you can use the command, you have to select and turn on a transducer.

Parameters:

<Unit> string as defined in table below
 *RST: DB

Example:

CORR:TRAN:UNIT 'DBUV'

Manual operation: See "Unit" on page 513

String	Unit
'DB'	dB
'DBM'	dBm
'DBMV'	dBmV
'DBUV'	dB μ V
'DBUV/M'	dB μ V/m
'DBUA'	dB μ A
'DBUA/M'	dB μ A/m
'DBPW'	dBpW
'DBPT'	dBpT

11.10.4 Customizing the Screen Layout

The remote commands required to set up the display of the R&S FPS are described here.

- [General Display Settings and Items](#)..... 917
- [Colors and Themes](#)..... 920
- [CMAP Suffix Assignment](#)..... 922

11.10.4.1 General Display Settings and Items

The following commands add, remove or customize general display and screen elements.

Useful commands for general display settings described elsewhere

- [DISPlay:MTABLE](#) on page 824

Remote commands exclusive to general display settings

DISPlay:ANNotation:CBAR	918
DISPlay:ANNotation:FREQuency	918
DISPlay:SBAR[:STATE]	918
DISPlay:SKEYs[:STATE]	918
DISPlay:TBAR[:STATE]	919

DISPlay[:WINDow]:TIME.....	919
DISPlay[:WINDow]:TIME:FORMat.....	919
SYSTem:DISPlay:FPANel[:STATe].....	919

DISPlay:ANNOtation:CBAR <State>

This command hides or displays the channel bar information.

Parameters:

<State> ON | OFF | 0 | 1
 *RST: 1

Example: DISP:ANN:CBAR OFF

Usage: SCPI confirmed

Manual operation: See "[Channel Bar](#)" on page 530

DISPlay:ANNOtation:FREQuency <State>

This command turns the label of the x-axis on and off.

Parameters:

<State> ON | OFF | 0 | 1
 *RST: 1

Example: DISP:ANN:FREQ OFF

Usage: SCPI confirmed

Manual operation: See "[Diagram Footer \(Annotation\)](#)" on page 530

DISPlay:SBAR[:STATe] <State>

This command turns the status bar on and off.

Parameters:

<State> ON | OFF | 0 | 1
 *RST: 1

Example: DISP:SBAR:OFF

Manual operation: See "[Status Bar](#)" on page 530

DISPlay:SKEYs[:STATe] <State>

This command turns the softkey bar on and off.

Parameters:

<State> ON | OFF | 0 | 1
 *RST: 1

Example: DISP:SKEY:OFF

Manual operation: See ["Softkey Bar"](#) on page 530

DISPlay:TBAR[:STATe] <State>

This command turns the toolbar on or off.

Parameters:

<State> ON | OFF
 *RST: OFF

Example: DISP:TOOL ON

Manual operation: See ["Toolbar"](#) on page 530

DISPlay[:WINDow]:TIME <State>

This command adds or removes the date and time from the display.

Parameters:

<State> ON | OFF
 *RST: OFF

Example: DISP:TIME ON

Manual operation: See ["Date and Time"](#) on page 530

DISPlay[:WINDow]:TIME:FORMat <Format>

This command selects the time and date format.

Parameters:

<Format> **DE**
 dd.mm.yyyy hh:mm:ss
 24 hour format.
 US
 mm/dd/yyyy hh:mm:ss
 12 hour format.
 *RST: DE

Example: DISP:TIME ON
 Switches the screen display of date and time on.
 DISP:TIME:FORM US
 Switches the date and time format to US.

Manual operation: See ["Date and Time Format"](#) on page 529

SYSTem:DISPlay:FPANel[:STATe] <State>

This command includes or excludes the front panel keys when working with the remote desktop.

Parameters:

<State> ON | OFF | 0 | 1
 *RST: 1

Manual operation: See ["Front Panel"](#) on page 531
 See ["Mini Front Panel"](#) on page 531

11.10.4.2 Colors and Themes**Useful commands to customize display colors described elsewhere**

The HCOPY commands define the print colors and thus only take effect on the display colors, if the display shows the printing colors.

- [HCOPY:CMAP<item>:DEFault<color>](#) on page 896
- [HCOPY:CMAP<item>:HSL](#) on page 897
- [HCOPY:CMAP<item>:PDEFined](#) on page 897

Remote commands exclusive to customize the display colors and themes

DISPlay:CMAP<item>:DEFault<color>	920
DISPlay:CMAP<item>:HSL	921
DISPlay:CMAP<item>:PDEFined	921
DISPlay:THEMe:CATalog?	921
DISPlay:THEMe:SElect	921

DISPlay:CMAP<item>:DEFault<color>

This command resets the color scheme for the display.

Suffix:

<item> Selects the item for which the color scheme is to be defined.
 For more information see [chapter 11.10.4.3, "CMAP Suffix Assignment"](#), on page 922.

<color> 1...4
 1
 Current colors with a white background and a black grid.
 2
 Optimized colors.
 3
 Customized colors.
 4
 Current screen colors (setting for hardcopies).

Example: DISP:CMAP:DEF2
 Selects default setting 2 for setting the colors.

Usage: Event
 SCPI confirmed

Manual operation: See ["Screen colors"](#) on page 533

DISPlay:CMAP<item>:HSL <Color>

This command selects the color for various screen elements in the display.

Suffix:

<item> Selects the item for which the color scheme is to be defined. For more information see [chapter 11.10.4.3, "CMAP Suffix Assignment"](#), on page 922.

Parameters:

<Color> **hue**
 tint
sat
 saturation
lum
 brightness

The value range is 0 to 1 for all parameters.

Example:

```
DISP:CMAP2:HSL 0.3,0.8,1.0
Changes the grid color.
```

DISPlay:CMAP<item>:PDEFined <Color>

This command selects a predefined color for various screen elements.

Suffix:

<item> Selects the item for which the color scheme is to be defined. For more information see [chapter 11.10.4.3, "CMAP Suffix Assignment"](#), on page 922.

Parameters:

<Color> BLACK | BLUE | BROWN | GREEN | CYAN | RED | MAGenta |
 YELLOW | WHITE | DGRAY | LGRAY | LBLUE | LGREEN |
 LCYan | LRED | LMAGenta

Example:

```
DISP:CMAP2:PDEF GRE
```

Manual operation: See ["Restoring the User Settings to Default Colors"](#) on page 536

DISPlay:THEMe:CATalog?

This command queries all available display themes.

Parameters:

<Themes> String containing all available display themes.

Example:

```
DISP:THEMe:CAT?
```

Usage:

Query only

DISPlay:THEMe:SElect <Theme>

This command selects the display theme.

Parameters:

<Theme> String containing the name of the theme.
 *RST: SPL

Example:

DISP:THEM:SEL "OceanBlue"

Manual operation: See "Theme" on page 533

11.10.4.3 CMAP Suffix Assignment

Several commands to change the color settings of individual items of the display or printout are available. Which item is to be configured is defined using a <CMAP> suffix. The following assignment applies:

Suffix	Description
CMAP1	Background
CMAP2	Grid
CMAP3 *)	Common Text
CMAP4 *)	Check Status OK
CMAP5 *)	Check Status Error
CMAP6 *)	Text Special 1
CMAP7 *)	Text Special 2
CMAP8	Trace 1
CMAP9	Trace 2
CMAP10	Trace 3
CMAP11	Marker Info Text
CMAP12	Limit Lines
CMAP13	Limit and Margin Check – "Pass"
CMAP14	Limit and Margin Check – "Fail"
CMAP15 *)	Softkey Text
CMAP16 *)	Softkey Background
CMAP17 *)	Selected Field Text
CMAP18 *)	Selected Field Background
CMAP19 *)	Softkey 3D Bright Part
CMAP20 *)	Softkey 3D Dark Part
CMAP21 *)	Softkey State "On"
CMAP22 *)	Softkey State "Dialog open"
CMAP23 *)	Softkey Text Disabled
CMAP24	Logo

Suffix	Description
CMAP25	Trace 4
CMAP26	Grid – Minorlines
CMAP27	Marker
CMAP28	Display Lines
CMAP29 *)	Sweepcount – Text
CMAP30	Limit and Margin Check – Text
CMAP31	Limit and Margin Check – \"Margin\"
CMAP32 *)	Table Overall – Title Text
CMAP33 *)	Table Overall – Title Background
CMAP34 *)	Table Overall – Text
CMAP35 *)	Table Overall – Background
CMAP36 *)	Table Value – Title Text
CMAP37 *)	Table Value – Title Background
CMAP38 *)	Table Value – Text
CMAP39 *)	Table Value – Background
CMAP40	Trace 5
CMAP41	Trace 6

*) these settings can only be defined via the theme (`DISPlay:THEMe:SElect`) and are thus ignored in the SCPI command

11.10.5 Configuring the Network and Remote Control

The following commands are required to configure a network or remote control for the R&S FPS.

Remote commands exclusive to configuring a network and remote control

<code>SYSTem:COMMunicate:GPIB[:SELF]:ADDRess</code>	924
<code>SYSTem:COMMunicate:GPIB[:SELF]:RTERminator</code>	924
<code>SYSTem:DISPlay:UPDate</code>	924
<code>SYSTem:ERRor:DISPlay</code>	924
<code>SYSTem:IDENtify:FACTory</code>	925
<code>SYSTem:IDENtify[:STRing]</code>	925
<code>SYSTem:LXI:INFo?</code>	925
<code>SYSTem:LXI:LANReset</code>	925
<code>SYSTem:LXI:MDEscription</code>	926
<code>SYSTem:LXI:PASSword</code>	926

SYSTem:COMMunicate:GPIB[:SELF]:ADDRess <Address>

This command sets the GPIB address of the R&S FPS.

Parameters:

<Address>	Range:	0 to 30
	*RST:	(no influence on this parameter, factory default 20)

Example: `SYST:COMM:GPIB:ADDR 18`**Usage:** SCPI confirmed**Manual operation:** See "[GPIB Address](#)" on page 43

SYSTem:COMMunicate:GPIB[:SELF]:RTERminator <Terminator>

This command selects the GPIB receive terminator.

According to the standard the terminator in ASCII is <LF> and/or <EOI>. For binary data transfers (e.g. trace data) from the control computer to the instrument, the binary code (0AH) used for <LF> might be included in the binary data block, and therefore should not be interpreted as a terminator in this particular case. This can be avoided by changing the receive terminator to EOI.

Output of binary data from the instrument to the control computer does not require such a terminator change.

Parameters:

<Terminator>	LFEOI EOI
	*RST: (no influence on this parameter, factory default LFEOI)

Example: `SYST:COMM:GPIB:RTER EOI`**Manual operation:** See "[GPIB Terminator](#)" on page 579

SYSTem:DISPlay:UPDate <State>

This command turns the display during remote operation on and off.

If on, the R&S FPS updates the diagrams, traces and display fields only.

The best performance is obtained if the display is off during remote control operation.

Parameters:

<State>	ON OFF
	*RST: OFF

Example: `SYST:DISP:UPD ON`**Manual operation:** See "[Remote Display Update](#)" on page 579

SYSTem:ERRor:DISPlay <State>

This command the error display during remote operation on and off.

If activated, the R&S FPS displays a message box at the bottom of the screen that contains the most recent type of error and the command that caused the error.

Parameters:

<State> ON | OFF | 1 | 0
*RST: 0

Example: SYST:ERR:DISP ON

Manual operation: See "[Display Remote Errors](#)" on page 580

SYSTem:IDEntify:FACTory

This command resets the query to *IDN? to its default value.

Usage: Event

Manual operation: See "[Reset to Factory String](#)" on page 579

SYSTem:IDEntify[:STRing] <String>

This command defines the response to *IDN?.

Parameters:

<String> String containing the description of the instrument.

Manual operation: See "[Identification String](#)" on page 579

SYSTem:LXI:INFo?

This command queries the LXI settings.

Return values:

<LXIInfo> <current version> | <LXI class> | <Computername> |
<MAC adress> | <IP adress> | <Auto MDIX>

String containing the current LXI parameters.

- <version>
- <LXIclass>
- <ComputerName>
- <MACAddress>
- <IPAddress>
- <AutoMDIX>

Usage: Query only

Manual operation: See "[Current LXI Configuration](#)" on page 583

SYSTem:LXI:LANReset

This command resets the LAN configuration as required by the LXI standard. The command also resets the LXI password and instrument description.

Usage: Event

Manual operation: See "[LAN Reset](#)" on page 42

SYSTem:LXI:MDEscription <Description>

This command defines the LXI instrument description.

Parameters:

<Description> String containing the instrument description.

Manual operation: See "[LXI Manufacturer Description](#)" on page 584

SYSTem:LXI:PASSword <Password>

This command defines the LXI password.

Parameters:

<Password> String containing the password.

Return values:

<Password> The query returns the current password.

Manual operation: See "[LXI Password](#)" on page 584

11.10.6 Checking the System Configuration

The following commands are required to check the system configuration on the R&S FPS.

Useful commands for obtaining system information described elsewhere:

- [DIAGnostic:SERVice:SINfo?](#) on page 933

Remote commands exclusive to obtaining system information:

DIAGnostic:INFO:CCOunter?	926
DIAGnostic:SERVice:BIOSinfo?	927
DIAGnostic:SERVice:HWInfo?	927
DIAGnostic:SERVice:VERSinfo?	928
SYSTem:ERRor:CLEar:ALL	928
SYSTem:ERRor:CLEar:REM	928
SYSTem:ERRor:EXTended?	929
SYSTem:ERRor:LIST?	929
SYSTem:ERRor[:NEXT]?	930
SYSTem:FORMat:IDENT	930
SYSTem:PRESet:COMPatible	930
SYSTem:SECurity[:STATe]	931

DIAGnostic:INFO:CCOunter? <Relay>

This command queries how many switching cycles the individual relays have performed since they were installed.

Query parameters:

<Relay>	ACDC Mechanical Attenuation Coupling
	ATT5 Mechanical Attenuation 05 DB
	ATT10 Mechanical Attenuation 10 DB
	ATT20 Mechanical Attenuation 20 DB
	ATT40 Mechanical Attenuation 40 DB
	CAL Mechanical Calibration Source
	EATT Electrical Attenuation Bypass
	PREamp Preamplifier Bypass

Return values:

<Cycles> Number of switching cycles.

Example: `DIAG:INFO:CCO? CAL`

Usage: Query only

DIAGnostic:SERVice:BIOSinfo?

This command queries the BIOS version of the CPU board.

Return values:

<BiosInformation> String containing the BIOS version.

Example: `DIAG:SERV:BIOS?`
Returns the BIOS version.

Usage: Query only

DIAGnostic:SERVice:HWInfo?

This command queries hardware information.

Return values:

<Hardware> String containing the following information for every hardware component.
 <component>: name of the hardware component
 <serial#>: serial number of the component
 <order#>: order number of the component
 <model>: model of the component
 <code>: code of the component
 <revision>: revision of the component

Example: `DIAG:SERV:HWIN?`
 Queries the hardware information.
`"FRONTEND|100001/003|1300.3009|03|01|00|00",`
`"MOTHERBOARD|123456/002|1300.3080|02|00|00|00",`
 ...

Usage: Query only

DIAGnostic:SERVice:VERSinfo?

This command queries information about the hardware and software components.

Return values:

<Information> String containing the version of hardware and software components including the types of licenses for installed options.

Example: `DIAG:SERV:VERS?`
 Queries the version information.
 Response:
 Instrument Firmware |1.80
 BIOS |FPS Analyzer BIOS V1.03-1-32-4-3 IPC10
 Image Version |1.2.0
 PCI-FPGA |9.01
 SA-FPGA |2.43
 MB-FPGA |2.0.8.0
 SYNTH-FPGA |3.9.0.0
 REF-FPGA |3.4.0.0
 Data Sheet Version |01.00
 Time Control Management |active
 Analog Demod K7| |permanent

Usage: Query only
 SCPI confirmed

SYSTem:ERRor:CLEar:ALL

This command deletes all contents of the "System Messages" table.

Example: `SYST:ERR:CLE:ALL`

Usage: Event

SYSTem:ERRor:CLEar:REM

This command deletes all contents of the "Remote Errors" table.

Note: The remote error list is automatically cleared when the R&S FPS is shut down.

Example: `SYST:ERR:CLE:REM`

Usage: Event

Manual operation: See ["Display Remote Errors"](#) on page 580
See ["Clear Error List"](#) on page 585

SYSTem:ERRor:EXTended? <MessageType>[, <ChannelName>]

This command queries all system messages, or all messages of a defined type, displayed in the status bar for a specific measurement channel (application).

Note: This command queries the strings displayed for manual operation. For remote programs, do not define processing steps depending on these results. Instead, query the results of the `STATUS:QUESTIONABLE:EXTENDED:INFO` status register, which indicates whether messages of a certain type have occurred (see ["STATUS:QUESTIONABLE:EXTENDED:INFO Register"](#) on page 565).

Query parameters:

<MessageType> ALL | INFO | WARNING | ERROR | FATAL | MESSAGE
 <ChannelName> String containing the name of the channel.
 The parameter is optional. If you omit it, the command works for the currently active channel.

Return values:

<Messages> String containing all messages of the selected type for the specified measurement channel. Each message is separated by a comma and inserted in parentheses. If no messages are available, empty parentheses are returned.

Example:

`SYST:ERR:EXT? ALL`
 Returns all messages for the currently active application, e.g. *"Message 1", "Message 2"*.

Example:

`SYST:ERR:EXT? FAT, 'Spectrum2'`
 Queries fatal errors in the 'Spectrum2' application. If none have occurred, the result is: " ".

Usage: Query only

SYSTem:ERRor:LIST? [<MessType>]

This command queries the error messages that occur during R&S FPS operation.

Query parameters:

<MessType> **SMSG**
 (default) Queries the system messages which occurred during manual operation.
REMOte
 Queries the error messages that occurred during remote operation.
 Note: The remote error list is automatically cleared when the R&S FPS is shut down.

Return values:

<SystemMessages> String containing all messages in the "System Messages" table.

<RemoteErrors>	<Error_no> <Description> <Command> <Date> <Time> Comma-separated list of errors from the "Remote Errors" table, where: <Error_no>: device-specific error code <Description>: brief description of the error <Command>: remote command causing the error <Date> <Time>: date and time the error occurred
Example:	SYST:ERR:LIST?
Usage:	Query only

SYSTem:ERRor[:NEXT]?

This command queries the most recent error queue entry and deletes it.

Positive error numbers indicate device-specific errors, negative error numbers are error messages defined by SCPI. If the error queue is empty, the error number 0, "No error", is returned.

For details on error queues see [chapter 10.1.5, "Status Reporting System"](#), on page 556.

Usage: Query only

SYSTem:FORMat:IDENt <IDNFormat>

This command selects the response format to the *IDN? query.

Parameters:

<IDNFormat>	LEGacy Format is compatible to R&S FSP/FSU/FSQ/FSG family.
	NEW FSL R&S FPS format Format is also compatible to the R&S FSL and R&S FSV family
	*RST: not reset!

Example: SYST:FORM:IDEN LEG
Adapts the return value of *IDN? to the R&S FSP/FSU/FSQ family.

Manual operation: See ["*IDN Format"](#) on page 579

SYSTem:PRESet:COMPAtible <OpMode>

This command defines the operating mode that is activated when you switch on the R&S FPS or press the PRESET key.

For details on operating modes see [chapter 4, "Applications and Operating Modes"](#), on page 99.

Parameters:

<OpMode>

SANalyzer

(Default:) Defines Signal and Spectrum Analyzer operating mode as the presetting.

MSRA

Defines Multi-Standard Radio Analysis (MSRA) as the preset default operating mode.

*RST: SAN

Usage:

Event

Manual operation: See "[Preset Mode](#)" on page 520

SYSTem:SECurity[:STATe] <State>

Activates or queries secure user mode.

Note: Before you activate secure user mode, store any instrument settings that are required beyond the current session, such as predefined instrument settings, transducer files, or self-alignment data.

Note: Initially after installation of the R&S FPS-K33 option, secure user mode must be enabled manually once before remote control is possible. This is necessary to prompt for a change of passwords.

For details on the secure user mode see [chapter 3.1.6, "Protecting Data Using the Secure User Mode"](#), on page 30.

Parameters:

<State>

ON | OFF | 0 | 1

ON | 1

The R&S FPS automatically reboots and starts in secure user mode. In secure user mode, no data is written to the instrument's internal solid-state drive. Data that the R&S FPS normally stores on the solid-state drive is redirected to SDRAM.

OFF | 0

The R&S FPS is set to normal instrument mode. Data is stored to the internal solid-state drive.

Note: this parameter is for query only. Secure user mode cannot be deactivated via remote operation.

*RST: 0

Manual operation: See "[Enable SecureUser / Disable SecureUser](#)" on page 43
See "[Secure User Mode](#)" on page 520

11.10.7 Using Service Functions

DIAGnostic:SERVice:SFUNction.....	932
DIAGnostic:SERVice:SFUNction:LASTresult?.....	932
DIAGnostic:SERVice:SFUNction:RESults:DELeTe.....	932
DIAGnostic:SERVice:SFUNction:RESults:SAVE.....	932
DIAGnostic:SERVice:SINFo?.....	933

DIAGnostic:SERVice:SFUNction <ServiceFunction>

This command starts a service function.

The service functions are available after you have entered the level 1 or level 2 system password.

Parameters:

<ServiceFunction> String containing the ID of the service function.
 The ID of the service function is made up out of five numbers, separated by a point.

- function group number
- board number
- function number
- parameter 1 (see the Service Manual)
- parameter 2 (see the Service Manual)

Usage: Event

Manual operation: See "[Service Function](#)" on page 526
 See "[Send](#)" on page 527

DIAGnostic:SERVice:SFUNction:LASTresult?

This command queries the results of the most recent service function you have used.

Usage: Query only

DIAGnostic:SERVice:SFUNction:RESults:DELeTe

This command deletes the results of the most recent service function you have used.

Usage: Event

Manual operation: See "[Clear Results](#)" on page 527

DIAGnostic:SERVice:SFUNction:RESults:SAVE <FileName>

This command saves the results of the most recent service function you have used.

Parameters:

<FileName> String containing the file name.

Manual operation: See "[Save Results](#)" on page 527

DIAGnostic:SERVice:SINFo? <FileName>

This command creates a *.zip file with important support information. The *.zip file contains the system configuration information ("device footprint"), the current eeprom data and a screenshot of the screen display (if available).

This data is stored to the C:\R_S\Instr\user\ directory on the instrument.

As a result of this command, the created file name (including the drive and path) is returned.

You can use the resulting file name information as a parameter for the `MMEM:COPY` command to store the file on the controller PC.

(See `MMEMory:COPY` on page 884)

If you contact the Rohde&Schwarz support to get help for a certain problem, send this file to the support in order to identify and solve the problem faster.

Return values:

<FileName> C:\R_S\Instr\user\<<R&S Device ID>_<CurrentDate>_<Current-Time>

String containing the drive, path and file name of the created support file, where the file name consists of the following elements:

<R&S Device ID>: The unique R&S device ID indicated in the "Versions + Options" information

(See [chapter 9.3.4.2, "Information on Versions and Options"](#), on page 516)

<CurrentDate>: The date on which the file is created (<YYYYMMDD>)

<CurrentTime>: The time at which the file is created (<HHMMSS>)

Example:

DIAG:SERV:SINF?

Result:

"c:\R&S\instr\user\FPS-26_1312.8000K26-100005-xx_20130116_165858.zip"

```
MMEM:COPY "c:\R&S\instr\user\FPS-26_
1312.8000K26-100005-xx_20130116_165858.zip",
"S:\Debug\FPS-26_1312.8000K26-100005-xx_
20130116_165858.zip"
```

Usage: Query only

Manual operation: See ["Creating R&S Support Information"](#) on page 522

11.11 Using the Status Register

For more information on the contents of the status registers see:

- ["STATus:OPERation Register"](#) on page 562
- ["STATus:QUEStionable:ACPLimit Register"](#) on page 564

- "STATus:QUEStionable:EXTended Register" on page 565
- "STATus:QUEStionable:FREQuency Register" on page 566
- "STATus:QUEStionable:LIMit Register" on page 567
- "STATus:QUEStionable:LMARgin Register" on page 567
- "STATus:QUEStionable:POWer Register" on page 568
- "STATus:QUEStionable:TEMPerature Register" on page 569
- "STATus:QUEStionable:TIME Register" on page 569
- General Status Register Commands..... 934
- Reading Out the CONDition Part..... 934
- Reading Out the EVENT Part..... 935
- Controlling the ENABLE Part..... 936
- Controlling the Negative Transition Part..... 936
- Controlling the Positive Transition Part..... 937

11.11.1 General Status Register Commands

STATus:PRESet.....	934
STATus:QUEue[:NEXT]?	934

STATus:PRESet

This command resets the edge detectors and ENABLE parts of all registers to a defined value. All PTRansition parts are set to FFFFh, i.e. all transitions from 0 to 1 are detected. All NTRansition parts are set to 0, i.e. a transition from 1 to 0 in a CONDition bit is not detected. The ENABLE part of the STATus:OPERation and STATus:QUEStionable registers are set to 0, i.e. all events in these registers are not passed on.

Usage: Event

STATus:QUEue[:NEXT]?

This command queries the most recent error queue entry and deletes it.

Positive error numbers indicate device-specific errors, negative error numbers are error messages defined by SCPI. If the error queue is empty, the error number 0, "No error", is returned.

This command is identical to the SYSTem:ERRor[:NEXT]? command.

Usage: Query only

11.11.2 Reading Out the CONDition Part

For more information on the condition part see [chapter 10.1.5.2, "Structure of a SCPI Status Register"](#), on page 558.

```

STATus:OPERation:CONDition?
STATus:QUESTionable:CONDition?
STATus:QUESTionable:ACPLimit:CONDition? <ChannelName>
STATus:QUESTionable:EXTended:CONDition? <ChannelName>
STATus:QUESTionable:EXTended:INFO:CONDition? <ChannelName>
STATus:QUESTionable:FREQuency:CONDition? <ChannelName>
STATus:QUESTionable:LIMit<n>:CONDition? <ChannelName>
STATus:QUESTionable:LMARgin<n>:CONDition? <ChannelName>
STATus:QUESTionable:POWer:CONDition? <ChannelName>
STATus:QUESTionable:TEMPerature:CONDition? <ChannelName>
STATus:QUESTionable:TIME:CONDition? <ChannelName>

```

These commands read out the CONDition section of the status register.

The commands do not delete the contents of the CONDition section.

Query parameters:

<ChannelName> String containing the name of the channel.
 The parameter is optional. If you omit it, the command works for the currently active channel.

Usage: Query only

11.11.3 Reading Out the EVENT Part

For more information on the event part see [chapter 10.1.5.2, "Structure of a SCPI Status Register"](#), on page 558.

```

STATus:OPERation[:EVENT]?
STATus:QUESTionable[:EVENT]?
STATus:QUESTionable:ACPLimit[:EVENT]? <ChannelName>
STATus:QUESTionable:EXTended[:EVENT]? <ChannelName>
STATus:QUESTionable:EXTended:INFO[:EVENT]? <ChannelName>
STATus:QUESTionable:FREQuency[:EVENT]? <ChannelName>
STATus:QUESTionable:LIMit<n>[:EVENT]? <ChannelName>
STATus:QUESTionable:LMARgin<n>[:EVENT]? <ChannelName>
STATus:QUESTionable:POWer[:EVENT]? <ChannelName>
STATus:QUESTionable:TEMPerature[:EVENT]? <ChannelName>
STATus:QUESTionable:TIME[:EVENT]? <ChannelName>

```

These commands read out the EVENT section of the status register.

At the same time, the commands delete the contents of the EVENT section.

Query parameters:

<ChannelName> String containing the name of the channel.
 The parameter is optional. If you omit it, the command works for the currently active channel.

Usage: Query only

11.11.4 Controlling the ENABLE Part

For more information on the enable part see [chapter 10.1.5.2, "Structure of a SCPI Status Register"](#), on page 558.

```

STATus:OPERation:ENABLE <SumBit>
STATus:QUESTionable:ENABLE <SumBit>
STATus:QUESTionable:ACPLimit:ENABLE <SumBit>,<ChannelName>
STATus:QUESTionable:EXTended:ENABLE <SumBit>,<ChannelName>
STATus:QUESTionable:EXTended:INFO:ENABLE <SumBit>,<ChannelName>
STATus:QUESTionable:FREQuency:ENABLE <SumBit>,<ChannelName>
STATus:QUESTionable:LIMit<n>:ENABLE <SumBit>,<ChannelName>
STATus:QUESTionable:LMARgin<n>:ENABLE <SumBit>,<ChannelName>
STATus:QUESTionable:POWer:ENABLE <SumBit>,<ChannelName>
STATus:QUESTionable:TEMPerature:ENABLE <SumBit>,<ChannelName>
STATus:QUESTionable:TIME:ENABLE <SumBit>,<ChannelName>

```

These commands control the ENABLE part of a register.

The ENABLE part allows true conditions in the EVENT part of the status register to be reported in the summary bit. If a bit is 1 in the enable register and its associated event bit transitions to true, a positive transition will occur in the summary bit reported to the next higher level.

Parameters:

<SumBit>	Range: 0 to 65535
<ChannelName>	String containing the name of the channel. The parameter is optional. If you omit it, the command works for the currently active channel.

11.11.5 Controlling the Negative Transition Part

For more information on the positive transition part see [chapter 10.1.5.2, "Structure of a SCPI Status Register"](#), on page 558.

```

STATus:OPERation:NTRansition <SumBit>
STATus:QUESTionable:NTRansition <SumBit>
STATus:QUESTionable:ACPLimit:NTRansition <SumBit>,<ChannelName>
STATus:QUESTionable:EXTended:NTRansition <SumBit>,<ChannelName>
STATus:QUESTionable:EXTended:INFO:NTRansition <SumBit>,<ChannelName>
STATus:QUESTionable:FREQuency:NTRansition <SumBit>,<ChannelName>
STATus:QUESTionable:LIMit<n>:NTRansition <SumBit>,<ChannelName>
STATus:QUESTionable:LMARgin<n>:NTRansition <SumBit>,<ChannelName>
STATus:QUESTionable:POWer:NTRansition <SumBit>,<ChannelName>
STATus:QUESTionable:TEMPerature:NTRansition <SumBit>,<ChannelName>
STATus:QUESTionable:TIME:NTRansition <SumBit>,<ChannelName>

```

These commands control the Negative TRansition part of a register.

Setting a bit causes a 1 to 0 transition in the corresponding bit of the associated register. The transition also writes a 1 into the associated bit of the corresponding EVENT register.

Parameters:

<SumBit> Range: 0 to 65535

<ChannelName> String containing the name of the channel.
The parameter is optional. If you omit it, the command works for the currently active channel.

11.11.6 Controlling the Positive Transition Part

For more information on the negative transition part see [chapter 10.1.5.2, "Structure of a SCPI Status Register"](#), on page 558.

STATus:OPERation:PTRansition <SumBit>
STATus:QUESTionable:PTRansition <SumBit>
STATus:QUESTionable:ACPLimit:PTRansition <SumBit>,<ChannelName>
STATus:QUESTionable:EXTended:PTRansition <SumBit>,<ChannelName>
STATus:QUESTionable:EXTended:INFO:PTRansition <SumBit>,<ChannelName>
STATus:QUESTionable:FREQUency:PTRansition <SumBit>,<ChannelName>
STATus:QUESTionable:LIMit<n>:PTRansition <SumBit>,<ChannelName>
STATus:QUESTionable:LMARgin<n>:PTRansition <SumBit>,<ChannelName>
STATus:QUESTionable:POWer:PTRansition <SumBit>,<ChannelName>
STATus:QUESTionable:TEMPerature:PTRansition <SumBit>,<ChannelName>
STATus:QUESTionable:TIME:PTRansition <SumBit>,<ChannelName>

These commands control the Positive TRansition part of a register.

Setting a bit causes a 0 to 1 transition in the corresponding bit of the associated register. The transition also writes a 1 into the associated bit of the corresponding EVENT register.

Parameters:

<SumBit> Range: 0 to 65535

<ChannelName> String containing the name of the channel.
The parameter is optional. If you omit it, the command works for the currently active channel.

11.12 Commands for Remote Instrument Operation

The following commands are required to shutdown or reboot the R&S FPS from a remote PC.

SYSTem:CLOGging	938
SYSTem:REBoot	938
SYSTem:SHUTdown	938

SYSTem:CLOGging <State>

This command turns logging of remote commands on and off.

Parameters:

<State> **ON**
 Writes all remote commands that have been sent to a file.
 The destination is C :
 \R_S\instr\ScpiLogging\ScpiLog.txt.

OFF
 *RST: OFF

Manual operation: See "[I/O Logging](#)" on page 580

SYSTem:REBoot

This command reboots the instrument, including the operating system.

Usage: Event

Manual operation: See "[Reboot](#)" on page 42

SYSTem:SHUTdown

This command shuts down the instrument.

Usage: Event

11.13 Emulating Other Instruments' Commands

The R&S FPS analyzer family supports a subset of the GPIB commands of several HP and PSA instruments.

For details see [chapter 10.2, "GPIB Languages"](#), on page 574.

- [Setting up Instrument Emulation](#)..... 938
- [Reference: GPIB Commands of Emulated HP Models](#)..... 942
- [Reference: Command Set of Emulated PSA Models](#)..... 969
- [Reference: Command Set of Emulated PXA Models](#)..... 973

11.13.1 Setting up Instrument Emulation

The following commands are required to set up the use of commands to emulate other instruments.

SYSTem:HPCoupling	939
SYSTem:IFGain:MODE	939
SYSTem:LANGuage	939
SYSTem:PSA:WIDeband	940

SYSTem:REVision:FACTory	940
SYSTem:REVision[:STRing]	941
SYSTem:RSW	941

SYSTem:HPCoupling <CouplingType>

Controls the default coupling ratios in the HP emulation mode for:

- span and resolution bandwidth (Span/RBW) and
- resolution bandwidth and video bandwidth (RBW/VBW)

This command is only available if a HP language is selected using [SYSTem:LANGuage](#) on page 939.

Parameters:

<CouplingType> HP | FSP
 *RST: FSP

Example: SYSTem:HPC HP

Manual operation: See "[Coupling](#)" on page 582

SYSTem:IFGain:MODE <Mode>

Configures the internal IF gain settings in HP emulation mode due to the application needs. This setting is only taken into account for resolution bandwidth < 300 kHz and is only available if a HP language is selected using [SYSTem:LANGuage](#).

Parameters:

<Mode> NORM | PULS

NORM
 Optimized for high dynamic range, overload limit is close to reference level.

PULS
 Optimized for pulsed signals, overload limit up to 10 dB above reference level.

*RST: NORM

Example: SYST:IFG:MODE PULS

Manual operation: See "[IF Gain](#)" on page 581

SYSTem:LANGuage <Language>

This command defines the system language.

For details see [chapter 10.2, "GPIB Languages"](#), on page 574.

Parameters:

<Language> "SCPI" | "8560E" | "8561E" | "8562E" | "8563E" | "8564E" |
 "8565E" | "8566A" | "8566B" | "8568A" | "8568A_DC" | "8568B" |
 "8568B_DC" | "8591E" | "8594E" | "71100C" | "71200C" |
 "71209A" | "PSA89600" | "PSA" | "PXA" | "FSP" | "FSU" |
 "FSQ" | "FSV" | "FSEA" | "FSEB" | "FSEM" | "FSEK"
 *RST: SCPI

Example:

```
SYST:LANG '8560E'
```

Sets the system language to 8560E to simulate the HP model.

Usage:

SCPI confirmed

Manual operation: See "[Language](#)" on page 581

Note: If you use "**PSA89600**", you must switch to an HP language first before returning to SCPI (in remote operation only). For the identical language "PSA", this intermediate step is not necessary.

SYSTem:PSA:WIDeband <State>

This command defines which option is returned when the *OPT? query is executed, depending on the state of the wideband option.

It is only available for PSA89600 emulation.

Parameters:

<State> ON | OFF | HIGH

OFF
 The option is indicated as "B7J"

ON
 The 40 MHz wideband is used.
 The option is indicated as "B7J, 140".

HIGH
 The 80 MHz wideband is used.
 The option is indicated as "B7J, 122".

*RST: OFF

SYSTem:REVision:FACTory

Resets the response to the REV? query to the default value, e.g. after a user string was defined using the [SYSTem:REVision\[:STRing\]](#) command. (REV? query available for HP emulation only, see [SYSTem:LANGUage](#) on page 939.)

Example: Define the system language:
`SYST:LANG '8563E'`
 Set the response back to factory setting:
`SYS:REV:FACT`
 Query the revision:
`REV?`
 Response:
 920528

Manual operation: See "[Resetting the Factory Revision](#)" on page 582

SYSTem:REVision[:STRing] <Name>

Sets the response to the `REV?` query to the defined string (HP emulation only, see [SYSTem:LANGuage](#) on page 939).

Parameters:

<Name>

Example: Define the system language:
`SYST:LANG '8563E'`
 Query the revision:
`REV?`
 Response:
 920528
 Set the response to 'NewRevision':
`SYST:REV:STR 'NewRevision'`
 Query the response:
`SYST:REV:STR?`
 Response:
 NewRevision

Manual operation: See "[Revision String](#)" on page 582

SYSTem:RSW <State>

Controls a repeated sweep of the E1 and MKPK HI HP model commands (for details on the commands refer to [chapter 11.13.2, "Reference: GPIB Commands of Emulated HP Models"](#), on page 942). If the repeated sweep is OFF, the marker is set without sweeping before.

This command is only available if a HP language is selected using [SYSTem:LANGuage](#) on page 939

Parameters:

<State> ON | OFF
 *RST: OFF

Example: SYSTem:RSW ON

Manual operation: See "[Sweep Repeat](#)" on page 582

11.13.2 Reference: GPIB Commands of Emulated HP Models

The R&S FPS analyzer family supports a subset of the GPIB commands of HP models 8560E, 8561E, 8562E, 8563E, 8564E, 8565E, 8566A, 8566B, 8568A, 8568B and 8594E.

Despite the differences in system architecture and device features, the supported commands have been implemented in a way to ensure a sufficiently high degree of correspondence with the original.

This includes the support of syntax rules for not only newer device families (B and E models) but for the previous A family as well.

In many cases the selection of commands supported by the R&S FPS is sufficient to run an existing GPIB program without adaptation.

After the introduction, this section includes the following topics:

- [Command Set of Models 8560E, 8561E, 8562E, 8563E, 8564E, 8565E, 8566A/B, 8568A/B, 8591E, 8594E, 71100C, 71200C, and 71209A](#)..... 942
- [Special Features of the Syntax Parsing Algorithms for 8566A and 8568A Models](#) 965
- [Special Behavior of Commands](#)..... 966
- [Model-Dependent Default Settings](#)..... 967
- [Data Output Formats](#)..... 968
- [Trace Data Output Formats](#)..... 968
- [Trace Data Input Formats](#)..... 969
- [GPIB Status Reporting](#)..... 969

11.13.2.1 Command Set of Models 8560E, 8561E, 8562E, 8563E, 8564E, 8565E, 8566A/B, 8568A/B, 8591E, 8594E, 71100C, 71200C, and 71209A

As with the original units, the R&S FPS includes the command set of the A models in the command set of the B models.



The HP model 8591E is compatible to HP model 8594E, the HP models 71100C, 71200C, and 71209A are compatible to HP models 8566A/B.

Command	Supported subset	Function	Corresp. HP-Models	Status
A1	A1	Clear/Write A	HP 8566A/ HP 8568A	available
A2	A2	Max Hold A	HP 8566A/ HP 8568A	available
A3	A3	View A	HP 8566A/ HP 8568A	available
A4	A4	Blank A	HP 8566A/ HP 8568A	available

Emulating Other Instruments' Commands

Command	Supported subset	Function	Corresp. HP-Models	Status
ABORT ¹⁾	ABORT	Stop previous function	HP 856xE/ HP 8566B/HP 8568B/HP 8594E	available
ADD		Add	HP 8566B/ HP 8568B/ HP 8594E	available
ADJALL	ADJALL	Adjust all	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
ADJCRT ²⁾	ADJCRT	Adjust CRT	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
ADJIF ²⁾	ADJIF	Auto adjust IF	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
AMB	AMB ON OFF AMB 1 0 AMB?	Trace A – B -> Trace A	HP 856xE/ HP 8594E	available
AMBPL	AMBPL ON OFF AMBPL 1 0 AMBPL?		HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
ANNOT	ANNOT ON OFF ANNOT 1 0 ANNOT?	Annotation	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
APB	APB	Trace A + B -> Trace A	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
AT	AT <numeric_value> DB DM AT DN AT UP AT AUTO AT?	Attenuation	HP 8566A/ HP 8568A/ HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available

Command	Supported subset	Function	Corresp. HP-Models	Status
AUNITS	AUNITS DBM DBMV DBUV AUNITS?	Amplitude Units	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
AUTOCP	AUTOCP	Coupling default	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
AXB	AXB	Exchange trace A and B	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
B1	B1	Clear/Write B	HP 8566A/ HP 8568A	available
B2	B2	Max Hold B	HP 8566A/ HP 8568A	available
B3	B3	View B	HP 8566A/ HP 8568A	available
B4	B4	Blank B	HP 8566A/ HP 8568A	available
BL	BL	Trace B – Display Line -> Trace B	HP 8566A/ HP 8568A	available
BML	BML	Trace B – Display Line -> Trace B	HP 856xE/ HP8594E	available
BTC	BTC	Transfer Trace B -> C	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
BXC	BXC	Exchange Trace B and C	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
BLANK	BLANK TRA TRB TRC	Blank Trace	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
C1	C1	A-B off	HP 8566A/ HP 8568A	available

Command	Supported subset	Function	Corresp. HP-Models	Status
C2	C2	A-B -> A	HP 8566A/ HP 8568A	available
CA	CA	Couple Attenuation	HP 8566A/ HP 8568A	available
CAL ¹⁾	CAL ALL CAL ON CAL OFF	Start analyzer self alignment	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
CF	CF <numeric_value> HZ KHZ MHZ GHZ CF UP CF DN CF?	Center Frequency	HP 8566A/ HP 8568A/ HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
CHANPWR	CHANPWR TRA TRB, <numeric_value>,<?>	Channel Power Measurement	HP 856xE/ HP 8594E	available
CHPWRBW	CHPWRBW <numeric_value> HZ KHZ MHZ GHZ	Channel Power Bandwidth	HP 856xE/ HP 8594E	available
CLRW	CLRW TRA TRB TRC	Clear/Write Trace	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
CLS ¹⁾	CLS	Clear all status bits	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
CONTS	CONTS		HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
COUPLE	COUPLE AC DC	Input coupling	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
CR	CR	Couple RBW	HP 8566A/ HP 8568A	available
CS	CS	Couple Step Size	HP 8566A/ HP 8568A	available

Command	Supported subset	Function	Corresp. HP-Models	Status
CT	CT	Couple SWT	HP 8566A/ HP 8568A	available
CTA		Convert to absolute units	HP 8566B/ HP 8568B/ HP 8594E	available
CV	CV	Couple VBW	HP 8566A/ HP 8568A	available
D1 ²⁾	D1	Display Size normal	HP 8566A/ HP 8568A	available
DA ²⁾	DA	Display address		available
DEMODO ¹⁾	DEMODO ON OFF AM FM	AF Demodulator	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
DEMODOAGC ²⁾	DEMODOAGC ON OFF 1 0 DEMODOAGC?	Demodulation AGC	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
DEMOT	DEMOT <numeric_value> S MS US SC DEMOT UP DN DEMOT?	Demodulation time	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
DET	DET POS SMP NEG DET?	Detector	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
DISPOSE ²⁾	ONEOS TRMATH ONSWP ALL <numeric_value>			available
DIV		Divide	HP 8566B/ HP 8568B/ HP 8594E	available
DL	DL <numeric_value> DB DM DL DN DL UP DL ON DL OFF DL?	Display Line	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available

Emulating Other Instruments' Commands

Command	Supported subset	Function	Corresp. HP-Models	Status
DLE	DLE ON OFF	Display Line enable	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
DONE	DONE DONE?	Done query	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
DW ²⁾	DW	Write to display and increment address		available
E1	E1	Peak Search	HP 8566A/ HP 8568A	available
E2	E2	Marker to Center Freq.	HP 8566A/ HP 8568A	available
E3	E3	Deltamarker Step Size	HP 8566A/ HP 8568A	available
E4	E4	Marker to Ref. Level	available	available
EDITDONE		limit line edit done	HP 856xE	available
EDITLIML		edit limit line	HP 856xE	available
ERR	ERR 250 cal level error ERR 300 LO unlock ERR 472 cal error digital filter ERR 473 cal error analog filter ERR 552 cal error log amp ERR 902 unscale tracking generator ERR 906 oven cold ERR 117 numeric unit error ERR 112 Unrecognized Command	Now some FSx errors are mapped to HP errors.	HP8568A HP856xE	not yet available
ERR?	ERR?	Error queue query	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	not yet available
EX	EX	Exchange trace A and B	HP 8566A/ HP 8568A	available

Emulating Other Instruments' Commands

Command	Supported subset	Function	Corresp. HP-Models	Status
FA	FA <numeric_value> HZ KHZ MHZ GHZ FA UP FA DN FA?	Start Frequency	HP 8566A/ HP 8568A/ HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
FB	FB <numeric_value> HZ KHZ MHZ GHZ FB UP FB DN FB?	Stop Frequency	HP 8566A/ HP 8568A/ HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
FDSP		Frequency display off	8560E 8561E 8562E 8563E 8564E 8565E	available
FOFFSET ¹⁾	FOFFSET <numeric_value> HZ KHZ MHZ GHZ FOFFSET?	Frequency Offset	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
FREF	FREF INT EXT	Reference Frequency	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
FS	FS	Full Span	HP 8566A/ HP 8568A	available
FUNCDEF		Define Function Function must be in one line between delimiters @	HP 8594E/ HP 856xE/ HP 8566B	available
GATE ¹⁾	GATE ON OFF GATE 1 0		HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
GATECTL ¹⁾	GATECTL EDGE LEVEL GATECTL?		HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available

Command	Supported subset	Function	Corresp. HP-Models	Status
GD ¹⁾	GD <numeric_value> US MS SC GD DN GD UP GD?		HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
GL ¹⁾	GL <numeric_value> US MS SC GL DN GL UP GL?		HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
GP ¹⁾	GP POS NEG GP?		HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
GRAT ²⁾	GRAT ON OFF	Graticule	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
I1	I1		HP 8566A/ HP 8568A	available
I2	I2		HP 8566A/ HP 8568A	available
ID	ID ID?	Identify	HP 8566A/ HP 8568A/ HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
INZ ¹⁾	INZ 75 INZ 50 INZ?	Input Impedance	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
IP	IP	Instrument preset	HP 8566A/ HP 8568A	available
KEYDEF	KEYDEF	Key definition	HP 8566B/ HP 856xE/ HP 859xE	available
KEYEXEC	KEYEXEC	Key execute	HP 8566B	available

Emulating Other Instruments' Commands

Command	Supported subset	Function	Corresp. HP-Models	Status
KS=	KS= <numeric_value> HZ KHZ MHZ GHZ KS= DN KS= UP KS=?	Marker Frequency Counter Resolution	HP 8566A/ HP 8568A	available
KS/	KS/	Manual Peaking	HP 8566A/ HP 8568A	available
KS(KS(Lock register	HP 8566A/ HP 8568A	available
KS)	KS)	Unlock register	HP 8566A/ HP 8568A	available
KS91	KS91	Read Amplitude Error	HP 8566A/ HP 8568A	available
KSA	KSA	Amplitude Units in dBm	HP 8566A/ HP 8568A	available
KSB	KSB	Amplitude Units in dBmV	HP 8566A/ HP 8568A	available
KSC	KSC	Amplitude Units in dBuV	HP 8566A/ HP 8568A	available
KSD	KSD	Amplitude Units in V	HP 8566A/ HP 8568A	available
KSE	KSE <numeric_value> <char data>@	Title mode	HP 8566A/ HP 8568A	available
KSG	KSG KSG ON KSG <numeric_value>	Video Averaging on	HP 8566A/ HP 8568A	available
KSH	KSH	Video Averaging Off	HP 8566A/ HP 8568A	available
KSK		Marker to Next Peak	HP 8566A/ HP 8568A	available
KSL		Marker Noise off	HP 8566A/ HP 8568A	available
KSM		Marker Noise on	HP 8566A/ HP 8568A	available
KSO	KSO	Deltamarker to span	HP 8566A/ HP 8568A	available
KSP	KSP <numeric_value>	HPIB address	HP 8566A/ HP 8568A	available

Emulating Other Instruments' Commands

Command	Supported subset	Function	Corresp. HP-Models	Status
KSQ ²⁾	KSQ	Band lock off	HP 8566A/ HP 8568A	available
KST	KST	Fast Preset	HP 8566A/ HP 8568A	available
KSV	KSV <numeric_value> HZ KHZ MHZ GHZ KSV?	Frequency Offset	HP 8566A/ HP 8568A	available
KSW	KSW	Error Correction Routine	HP 8566A/ HP 8568A	available
KSX	KSX	Correction Values On	HP 8566A/ HP 8568A	available
KSY	KSY	Correction Values Off	HP 8566A/ HP 8568A	available
KSZ	KSZ <numeric_value> DB KSZ?	Reference Value Offset	HP 8566A/ HP 8568A	available
KSa	KSa	Normal Detection	HP 8566A/ HP 8568A	available
KSb	KSb	Pos Peak Detection	HP 8566A/ HP 8568A	available
KSd	KSd	Neg Peak Detection	HP 8566A/ HP 8568A	available
KSe	KSe	Sample Detection	HP 8566A/ HP 8568A	available
KSg		CRT beam off		available
KSh		CRT beam on		available
KSj	KSj	View Trace C	HP 8566A/ HP 8568A	available
KSk	KSk	Blank Trace C	HP 8566A/ HP 8568A	available
KSl	KSl	Transfer B to C	HP 8566A/ HP 8568A	available
KSm	KSm	Graticule off	HP 8566A/ HP 8568A	available
KSn ²⁾	KSn	Grid on	HP 8566A/ HP 8568A	available
KSo	KSn	Character display off	HP 8566A/ HP 8568A	available

Command	Supported subset	Function	Corresp. HP-Models	Status
KSp	KSp	Character display on	HP 8566A/ HP 8568A	available
KSr	KSr	Create service request	HP 8566A/ HP 8568A	available
KSt ²⁾	KSt	Band lock on	HP 8566A/ HP 8568A	available
KSv ²⁾	KSv	Signal ident on	HP 8566A/ HP 8568A	available
L0	L0	Display line off	HP 8566A/ HP 8568A	available
LB	LB <numeric_value> <char data>@	Label	HP 8566A/ HP 8568A	available
LF	LF	Low frequency band pre- set	HP 8566A/ HP 8568A	available
LIMD		limit line delta	HP 856xE	available
LIMF		limit line frequency	HP 856xE	available
LIMIFAIL		limit fail query	HP 856xE	available
LIMIPURGE		purge limit line	HP 856xE	available
LIMIRCL		recall limit line	HP 856xE	available
LIMIREL		relative limit line	HP 856xE	available
LIMISAV		save limit line	HP 856xE	available
LIMITEST		limit line test	HP 856xE	available
LIML		lower limit line value	HP 856xE	available
LIMM		middle limit line value	HP 856xE	available
LIMTFL		flat limit line segment	HP 856xE	available
LIMTSL		slope limit line segment	HP 856xE	available
LIMU		upper limit line value	HP 856xE	available
LG	LG <numeric_value> DB DM LG?	Amplitude Scale Log	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
LL ²⁾	LL	Plot command	HP 8566A/ HP 8568A	available

Command	Supported subset	Function	Corresp. HP-Models	Status
LN	LN	Amplitude Scale Lin	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
M1	M1	Marker Off	HP 8566A/ HP 8568A	available
M2	M2 M2 <numeric_value> HZ KHZ MHZ GHZ M2 DN M2 UP M2?	Marker Normal	HP 8566A/ HP 8568A	available
M3	M3 M3 <numeric_value> HZ KHZ MHZ GHZ M3 DN M3 UP M3?	Delta Marker	HP 8566A/ HP 8568A	available
M4	M4 <numeric_value> HZ KHZ MHZ GHZ	Marker Zoom	HP 8566A/ HP 8568A	available
MA	MA	Marker Amplitude	HP 8566A/ HP 8568A	available
MC0	MC0	Marker Count off	HP 8566A/ HP 8568A	available
MC1	MC1	Marker Count on	HP 8566A/ HP 8568A	available
MDS	MDS	Measurement data size	HP 8566B	available
MEAS		Measurement status	HP 856xE	available
MF	MF MF?	Marker Frequency	HP 8566A/ HP 8568A/ HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
MINH ¹⁾	MINH TRC	Minimum Hold	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available

Command	Supported subset	Function	Corresp. HP-Models	Status
MKA	MKA <numeric_value> MKA?	Marker Amplitude	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
MKACT	MKACT 1 MKACT?	Select the active marker	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	not available
MKBW ¹⁾	MKBW <numeric_value> MKBW ON MKBW OFF	N dB Down	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
MKD	MKD MKD <numeric_value> HZ KHZ MHZ GHZ MKD DN MKD UP MKD ON MKD OFF MKD?	Delta Marker	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
MKDR	MKDR <numeric_value> HZ KHZ MHZ GHZ S SC MS MSEC USMKDR?	Delta Marker reverse	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
MKDR?		Delta Marker reverse query		available
MKF	MKF <numeric_value> HZ KHZ MHZ GHZ MKF?	Set Marker Frequency	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
MKFC	MKFC ON OFF	Frequency Counter on/off	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available

Command	Supported subset	Function	Corresp. HP-Models	Status
MKFCR ¹⁾	MKFCR <numeric_value> HZ KHZ MHZ GHZ MKFCR DN MKFCR UP MKFCR?	Frequency Counter Resolution	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
MKMIN	MKMIN	Marker -> Min	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
MKN	MKN MKN <numeric_value> HZ KHZ MHZ GHZ MKN DN MKN UP MKN ON MKN OFF MKN?	Normal Marker	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
MKNOISE	MKNOISE ON OFF MKNOISE 1 0 MKNOISE?	Noise Measurement	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
MKOFF	MKOFF MKOFF ALL	Marker off	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
MKP	MKP <numeric_value> MKP?	Marker position	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
MKPK	MKPK MKPK HI MKPK NH MKPK NR MKPK NL	Marker Search	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
MKPT	MKPT MKPT HI MKPT NH MKPT NR MKPT NL	Marker Peak Threshold	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available

Emulating Other Instruments' Commands

Command	Supported subset	Function	Corresp. HP-Models	Status
MKPX	MKPX <numeric_value> DB MKPX DN MKPX UP MKPX?	Peak Excursion	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
MKRL	MKRL	Ref Level = Marker Level	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
MKSP	MKSP	Deltamarker to span	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
MKSS	MKSS	CF Stepsize = Marker Freq	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
MKT	MKT <numeric_value> S MS US SC MKT?	MKF = fstart + MKT/ SWT*Span	HP 856xE/ HP 8594E	available
MKTRACE	MKTRACE TRA TRB TRC	Marker to Trace	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
MKTRACK	MKTRACK ON OFF MKTRACK 1 0 MKTRACK?	Signal Track	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
MKTYPE	MKTYPE AMP MK TYPE?	Marker type	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
ML		Mixer level	HP 856xE	available
MOV	MOV TRA TRB TRC, TRA TRB TRC	Move Trace Contents	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
MPY		Multiply	HP 8566B/ HP 8568B/ HP 8594E	available

Command	Supported subset	Function	Corresp. HP-Models	Status
MT0	MT0	Marker Track Off	HP 8566A/ HP 8568A	available
MT1	MT1	Marker Track On	HP 8566A/ HP 8568A	available
MXMH	MXMH TRA TRB	Maximum Hold	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
NORMALIZE	NORMALIZE	Normalize trace	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	not available available
NRL ¹⁾	NRL <numeric_value> DB DM NRL?	Normalized Reference Level	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
NRPOS	NRPOS <numeric_value> NRL?	Normalize position	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
O1	O1	Format ASCII, Values 0 to 4095	HP 8566A/ HP 8568A	available
O2	O2	Format Binary, Values 0 to 4095	HP 8566A/ HP 8568A	available
O3	O3	Format ASCII	HP 8566A/ HP 8568A	available
OA	OA	Output All	HP 8566A/ HP 8568A	available
OL	OL <80 characters> OL?	Output Learn String	HP 8566A/ HP 8568A	available
OT	OT	Output Trace Annotations	HP 8566A/ HP 8568A	available
PA	PA <numeric_value>, <numeric_value	Plot command	HP 8566A/ HP 8568A	available
PD	PD <numeric_value>, <numeric_value	Plot command	HP 8566A/ HP 8568A	available
PH_MKF		Spot frequency in Hz	HP 856xE	available
PH_FMIN		Min offset frequency to be measured	HP 856xE	available

Command	Supported subset	Function	Corresp. HP-Models	Status
PH_FMAX		Max offset frequency to be measured	HP 856xE	available
PH_MKA		Queries amplitude at the spot frequency	HP 856xE	available
PH_DRIFT		0: for stable signals, 1: for drifty	HP 856xE	available
PH_RLVL		Reference level for the log plot	HP 856xE	available
PH_SMTHV		Trace smoothing	HP 856xE	available
PH_VBR		Filtering	HP 856xE	available
PH_RMSPT		Amount of data points to skip when doing the integration	HP 856xE	available
PH_RMSFL		Lower integration frequency in Hz	HP 856xE	available
PH_RMSFU		Upper integration frequency in Hz	HP 856xE	available
PH_EXIT		Quits phase noise	HP 856xE	available
PH_F_UDT		Updates internal frequency variables	HP 856xE	available
PH_LMT_L		Apply limits to PH_FMIN and PH_FMAX	HP 856xE	available
PH_MEAS		Generates log frequency plot	HP 856xE	available
PH_MKF_D		Updates the spot frequency	HP 856xE	available
PH_RMS		Requests the rms phase noise	HP 856xE	available
PH_RMSFT		Updates internal frequency variables	HP 856xE	available
PH_RMSX		Calculates the rms phase noise	HP 856xE	available
PH_SPOTF		Executes the spot frequency measurement	HP 856xE	available
PLOTORG ²⁾	PLOTORG DSP GRT	Plot command	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
PLOTSRC ²⁾	PLOTSRC ANNT GRT TRB TRA ALLDSP GRT	Plot command	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available

Command	Supported subset	Function	Corresp. HP-Models	Status
PP	PP	Preselector Peaking	HP 8566A/ HP 8568A	available
PRINT ¹⁾	PRINT PRINT 1 0	Hardcopy	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
PSDAC ²⁾	PSDAC <numeric_value> PSDAC UP DN	Preselector DAC value	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
PSTATE ²⁾	PSTATE ON OFF 1 0	Protect State	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
PU	PU	Pen Up	HP 8566A/ HP 8568A	available
PWRBW	PWRBW	Power Bandwidth	HP 8566B/ HP 859x/ HP 856xE	available
R1	R1	Set Status Bit Enable	HP 8566A/ HP 8568A	available
R2	R2	Set Status Bit Enable	HP 8566A/ HP 8568A	available
R3	R3	Set Status Bit Enable	HP 8566A/ HP 8568A	available
R4	R4	Set Status Bit Enable	HP 8566A/ HP 8568A	available
RB	RB <numeric_value> HZ KHZ MHZ GHZ RB DN RB UP RB AUTO RB?	Resolution Bandwidth	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
RBR	RBR <numeric_value> RBR DN RBR UP RBR?	Resolution Bandwidth Ratio	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
RC1...6	RC1...6	Recall Last State	HP 8566A/ HP 8568A	available

Command	Supported subset	Function	Corresp. HP-Models	Status
RCLS	RCLS <numeric_value>	Recall State Register	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
RCLT	RCLT TRA TRB, <number>	Recall Trace	HP856xE/ HP8594E	available
RESET	RESET	Instrument preset	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
REV	REV REV?	Firmware revision	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
RL	RL <numeric_value> DB DM RL DN RL UP RL?	Reference Level	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
RLCAL	RLCAL <numeric_value> RL?	Reference Level Calibration	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
RCLOSCAL	RCLOSCAL	Recall Open/Short Average	HP 856xE/ HP 8594E	not available
RCLTHRU	RCLTHRU	Recall Thru	HP 856xE/ HP 8594E	not available
RLPOS ¹⁾	RLPOS <numeric_value> RLPOS DN RLPOS UP RLPOS?	Reference Level Position	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
ROFFSET	ROFFSET <numeric_value> DB DM ROFFSET?	Reference Level Offset	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
RQS	RQS	Service Request Bit mask	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available

Command	Supported subset	Function	Corresp. HP-Models	Status
S1	S1	Continuous Sweep	HP 8566A/ HP 8568A	available
S2	S2	Single Sweep	HP 8566A/ HP 8568A	available
SADD		add a limit line segment	HP 856xE	available
SAVES	SAVES <numeric_value>	Save State Register	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
SAVET	SAVET TRA TRB,<num- ber>	Save Trace	HP856xE/ HP8594E	available
SDEL		delete limit line segment	HP 856xE	available
SDON		limit line segment done	HP 856xE	available
SEDI		edit limit line segment	HP 856xE	available
SMOOTH	SMOOTH TRA TRB TRC, <number of points>	Smooth Trace	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
SNGLS	SNGLS	Single Sweep	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
SQUELCH ²⁾	SQUELCH <numeric_value> DM DB SQUELCH UP DN SQUELCH ON OFF	Squelch	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
SP	SP <numeric_value> HZ KHZ MHZ GHZ SP DN SP UP SP?	Span	HP 8566A/ HP 8568A/ HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
SRCNORM ¹⁾	SRCNORM ON OFF SRCNORM 1 0	Source Normalization	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	not available

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Command	Supported subset	Function	Corresp. HP-Models	Status
SRCPOFS ¹⁾	SRCPOFS <numeric_value> DB DM SRCPOFS DN SRCPOFS UP SRCPOFS?	Source Power Offset	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	not available
SRCPWR ¹⁾	SRCPWR <numeric_value> DB DM SRCPWR DN SRCPWR UP SRCPWR ON SRCPWR OFF SRCPWR?	Source Power	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	not available
SS	SS <numeric_value> HZ KHZ MHZ GHZ SS DN SS UP SS AUTO SS?	CF Step Size	HP 8566A/ HP 8568A/ HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
ST	ST <numeric_value> US MS SC ST DN ST UP ST AUTO ST?	Sweep Time	HP 8566A/ HP 8568A/ HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
STB	STB	Status byte query	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
STOREOPEN	STOREOPEN	Store Open	HP 856xE/ HP 8594E	not available
STORESHORT	STORESHORT	Store Short	HP 856xE/ HP 8594E	not available
STORETHRU	STORETHRU	Store Thru	HP 856xE/ HP 8594E	not available
SUB		Subtract	HP 8566B/ HP 8568B/ HP 8594E	available

Command	Supported subset	Function	Corresp. HP-Models	Status
SUM		sum of trace amplitudes	HP 8566B/ HP 8568B/ HP 8594E	available
SV1...6	SV1...6	Save State	HP 8566A/ HP 8568A	available
SWPCPL ²⁾	SWPCPL SA SR SWPCPL?	Sweep Couple	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
SWPOUT ²⁾	SWPOUT FAV FAVA RAMP SWPOUT?	Sweep Output	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
T0	T0	Threshold off	HP 8566A/ HP 8568A	available
T1	T1	Free Run Trigger	HP 8566A/ HP 8568A	available
T2 ²⁾	T2	Line Trigger	HP 8566A/ HP 8568A	available
T3	T3	External Trigger	HP 8566A/ HP 8568A	available
T4	T4	Video Trigger	HP 8566A/ HP 8568A	available
TA	TA	Transfer A	HP 8566A/ HP 8568A	available
TACL	TACL?	Returns instantaneous measurement results. See TRACE<trace #>:IMMEDIATE:LEVEL? for full description.		not available
TBCL	TBCL?			
TCCL	TCCL?			
TACR	TACR?	Returns instantaneous measurement results. See TRACE<trace #>:IMMEDIATE:LEVEL? for full description.		not available
TBCR	TBCR?			
TCCR	TCCR?			

Command	Supported subset	Function	Corresp. HP-Models	Status
TB	TB	Transfer B	HP 8566A/ HP 8568A	available
TDF	TDF P TDF M TDF B TDF A TDF I	Trace Data Format	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
TH	TH <numeric_value> DB DM TH DN TH UP TH ON TH OFF TH AUTO TH?	Threshold	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
THE	THE ON OFF	Threshold Line enable	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
TIMEDSP ¹⁾	TIMEDSP ON OFF TIMEDSP 1 0 TIMEDSP?	Time Display	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
TM	TM FREE VID EXT LINE ²⁾ TM?	Trigger Mode	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
TM LINE ²⁾	TM LINE	Trigger Line	HP 8566B	available
TRA	TRA B TRA A TRA I	Transfer A	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
TRB	TRB B TRB A TRB I	Transfer B	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
TRSTAT	TRSTAT?	Trace State Query	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available

Command	Supported subset	Function	Corresp. HP-Models	Status
TS	TS	Take Sweep	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
UR ²⁾	UR	Plot Command	HP 8566A/ HP 8568A	available
VARDEF	VARDEF	Variable definition, arrays are not supported	HP 8566B/ HP 8568B/ HP 8594E	available
VAVG	VAVG VAVG TRA TRB TRC	Video Averaging	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
VB	VB <numeric_value> HZ KHZ MHZ GHZ VB DN VB UP VB AUTO VB?	Video Bandwidth	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
VBR ¹⁾	VBR <numeric_value> VBR DN VBR UP VBR?	Video Bandwidth Ratio	HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
VIEW	VIEW TRA TRB TRC		HP 856xE/ HP 8566B/ HP 8568B/ HP 8594E	available
VTL	VTL <numeric_value> DB DM VTL DN VTL UP VTL?	Video Trigger Level	HP 856xE/ HP 8594E	not available
1) HP 8594E only				
2) Command is accepted without error message, but is ignored				

11.13.2.2 Special Features of the Syntax Parsing Algorithms for 8566A and 8568A Models

The command syntax is very different for models A and B. Different names are assigned to identical instrument functions, and the command structure likewise differs considerably between models A and models B.

The command structure for models A is as follows:

```
<command> ::= <command
code> [<SPC>] [<data> | <step>] [<SPC>] [<delimiter>] [<command
code>] ... <delimiter>
```

```
<data> ::= <Value> [<SPC>] [<units
code>] [<SPC>] [<delimiter>] [<SPC>] [<data>] ...
```

```
<step> ::= UP | DN
```

where

<command code> = see Table "Supported Commands"

<Value> = integer or floating-point numerical value

<units code> = DM | -DM | DB | HZ | KZ | MZ | GZ | MV | UV | SC | MS | US

<delimiter> = <CR> | <LF> | <,> | <;> | <ETX>

<SPC> = 32₁₀

<ETX> = 3₁₀

Command sections given in [] are optional.

The R&S FPS GPIB hardware differs from that used in the HP analyzers. Therefore, the following constraint exists:

<LF> | <EOI> are still used as delimiters since the GPIB hardware is able to identify them. The other delimiters are identified and evaluated during syntax analysis.

11.13.2.3 Special Behavior of Commands

Command	Known Differences
ABORT	Does not automatically set the command complete bit (bit 4) in the status byte. An additional DONE is required for that purpose.
ANNOT	Only frequency axis annotation is affected.
AT	AT DN/UP: Step size
CAL	The CAL commands do not automatically set the command complete bit (bit 4) in the status byte. An additional DONE command is required for that purpose.
CF	Default value, range, step size
CR	Default ratio Span/RBW
CT	Formula for coupled sweep time
CV	Default ratio RBW/VBW
DET	DET? returns SAMP instead of SMP on the R&S FPS. DET not automatically set the command complete bit (bit 4) in the status byte. An additional DONE is required for that purpose.
ERR?	Deletes the error bit in the status register but always returns a '0' in response.

Command	Known Differences
FA	Default value, range, step size
FB	Default value, range, step size
ID	
M2	Default value, range, step size
M3	Default value, range, step size
MKACT	Only marker 1 is supported as the active marker.
MKBW	Default value
MKPT	Step size
MKPX	Step size
OL?	Storage of instrument settings: 80 characters are returned as information on the instrument settings. The contents of the 80 characters returned does not correspond to the original data contents of the 8566A/8568A family.
OL	Readout of instrument settings: The 80 characters read by means of OL? are accepted as information on the corresponding instrument settings. The contents of the 80 characters read does not correspond to the original data contents of the 8566A/8568A family.
RB	Default value, range, step size
RL	Default value, step size
RLPOS	Adapts the position of the reference level even if the tracking generator normalization is not active.
RQS	Supported bits: 1 (Units key pressed) 2 (End of Sweep) 3 (Device error) 4 (Command complete) 5 (Illegal command)

11.13.2.4 Model-Dependent Default Settings

If the GPIB language is switched over to an 85xx model, the GPIB address is automatically switched over to 18 provided that the default address of the R&S FPS (20) is still set. If a different value is set, this value is maintained. Upon return to SCPI, this address remains unchanged.

The following table shows the default settings obtained after a change of the GPIB language and for the commands IP, KST and RESET:

Model	# of Trace Points	Start Freq.	Stop Freq.	Ref Level	Input Coupling
8566A/B	1001	2 GHz	22 GHz	0 dBm	AC
8568A/B	1001	0 Hz	1.5 GHz	0 dBm	AC
8560E	601	0 Hz	2.9 GHz	0 dBm	AC
8561E	601	0 Hz	6.5 GHz	0 dBm	AC
8562E	601	0 Hz	13.2 GHz	0 dBm	AC
8563E	601	0 Hz	26.5 GHz	0 dBm	AC
8564E	601	0 Hz	40 GHz	0 dBm	AC
8565E	601	0 Hz	50 GHz	0 dBm	AC
8594E	401	0 Hz	3 GHz	0 dBm	AC



Stop frequency

The stop frequency given in the table may be limited to the corresponding frequency range of the R&S FPS.

Command LF sets the stop frequency for 8566A/B to a maximum value of 2 GHz.

Test points (trace points)

The number of trace points is switched over only upon transition to the REMOTE state.

11.13.2.5 Data Output Formats

In the case of the SCPI and IEEE488.2 standards, the output formats for numerical data are flexible to a large extent. The output format for the HP units, by contrast, is accurately defined with respect to the number of digits. The memory areas for reading instrument data have therefore been adapted accordingly in the remote-control programs for instruments of this series.

Therefore, in response to a query, the R&S FPS returns data of the same structure as that used by the original instruments; this applies in particular to the number of characters returned.

Two formats are currently supported when trace data is output: Display Units (command O1) and physical values (command O2, O3 or TDF P). As to the "Display Units" format, the level data of the R&S FPS is converted to match the value range and the resolution of the 8566/8568 series. Upon transition to the **REMOTE** state, the R&S FPS is reconfigured such that the number of test points (trace points) corresponds to that of the 85xx families (1001 for 8566A/B and 8568A/B, 601 for 8560E to 8565E, 401 for 8594E).

11.13.2.6 Trace Data Output Formats

All formats are supported for trace data output: display units (command O1), display units in two byte binary data (command O2 or TDF B and MDS W), display units in one

byte binary data (command O4 or TDF B and MDS B) and physical values (commands O3 or TDF P). With format "display units" the level data is converted into value range and resolution of the 8566/8568 models. On transition to REMOTE state the number of trace points are reconfigured in order to be conform to the selected instrument model (1001 for 8566A/B and 8568 A/B, 601 for 8560E to 8565E, 401 for 8594E).

11.13.2.7 Trace Data Input Formats

Trace data input is only supported for binary date (TDF B, TDF A, TDF I, MDS W, MDS B).

11.13.2.8 GPIB Status Reporting

The assignment of status bits by commands R1, R2, R3, R4, RQS is supported.

The STB command and the serial poll respond with an 8-bit value with the following assignment:

Bit enabled by RQS	Description
0	not used (value 0)
1	Units key pressed
2	End of Sweep
3	Device Error
4	Command Complete
5	Illegal Command
6	Service Request
7	not used (value 0)

Bits 0 and 7 are not used and always have the value 0.

Please note that the R&S FPS reports any key pressed on the front panel rather than only the unit keys if bit 1 was enabled.

Another difference is the behavior of bit 6 when using the STB? query. On the HP analyzers this bit monitors the state of the SRQ line on the bus. On the R&S FPS this is not possible. Therefore this bit is set, as soon as one of the bits 1 to 5 is set. It won't be reset by performing a serial poll.

11.13.3 Reference: Command Set of Emulated PSA Models

The R&S FPS analyzer family supports a subset of the GPIB commands of PSA89600 and ESA instruments.

Despite the differences in system architecture and device features, the supported commands have been implemented in a way to ensure a sufficiently high degree of correspondence with the original.

In many cases the selection of commands supported by the R&S FPS is sufficient to run an existing GPIB program without adaptation.

Supported 89600 commands
*CAL?
*CLS
*ESE
*ESR?
*IDN?
*IST?
*OPC
*OPT?
*PCB
*PRE
*PSC
*RST
*SRE
*STB?
*TRG
*TST?
*WAI
:CALibration:AUTO OFF ON ALERT
:CALibration:TCORrections AUTO ON OFF
:CONFigure:WAVeform
:DIAGnostic:EABY ON OFF
:DIAGnostic:LATCh:VALue <numeric>
:DIAGnostic:LATCh:SElect <string>
:DISPlay:ANNotation:TITLe:DATA <string>
:DISPlay:ENABle OFF ON
:DISPlay:WINDow:TRACe:Y:[SCALe]:PDIVision <numeric>
:DISPlay:WINDow:TRACe:Y:[SCALe]:RLEVel <numeric>
:DISPlay:WINDow:TRACe:Y:[SCALe]:RLEVel:OFFSet <numeric>
:FORMat:BORDer NORMAl SWAPped
:FORMat[:DATA] ASCii REAL UINT MATLAB,<numeric>
:INITiate:CONTinuous OFF ON

Supported 89600 commands
:INITiate[:IMMEDIATE]
:INSTrument:CATalog?
:INSTrument:NSElect <numeric>
:MMEMory:CATalog? <dir_name>
:MMEMory:COpy <'file_name1'>,<'file_name2'>
:MMEMory:DATA <'file_name'>,<definite_length_block>
:MMEMory:DELeTe <'file_name'>
:MMEMory:LOAD:STATe 1,<'file_name'>
:MMEMory:LOAD:TRACe 1,<'file_name'>
:MMEMory:MDIRectory <'dir_name'>
:MMEMory:MOVE <'file_name1'>,<'file_name2'>
:MMEMory:STORE:STATe 1,<'file_name'>
:MMEMory:STORE:TRACe <numeric>,<'file_name'>
:READ:WAVform?
[:SENSe]:FREQUency:CENTer <numeric>
[:SENSe]:FREQUency:STARt <numeric>
[:SENSe]:FREQUency:STOP <numeric>
[:SENSe]:FREQUency:SPAN <numeric>
[:SENSe]:POWer:ATTenuation <numeric>
[:SENSe]:ROSCillator:EXTernal:FREQUency <numeric>
[:SENSe]:ROSCillator:OUTPut OFF ON
[:SENSe]:ROSCillator:SOURce INTernal EXTernal EAUTO
[:SENSe]:SPECTrum:TRIGger:SOURce EXTernal<1 2> IF IMMEDIATE
[:SENSe]:WAVeform:ADC:RANGe P6
[:SENSe]:WAVeform:APER?
[:SENSe]:WAVeform:AVERage:TACount <numeric>
[:SENSe]:WAVeform:BWIDth:ACTive?
[:SENSe]:WAVeform:BWIDth:TYPE FLAT GAUSSian
[:SENSe]:WAVeform:IFGain <numeric>
[:SENSe]:WAVeform:IFPath NARRow WIDE
[:SENSe]:WAVeform:NCPTTrace ON OFF
[:SENSe]:WAVeform:PDIT ON OFF
[:SENSe]:WAVeform:SRATe <numeric>

Supported 89600 commands
[:SENSe]:WAVeform:SWEep:TIME <numeric>
[:SENSe]:WAVeform:TRIGger:EOFFset?
[:SENSe]:WAVeform:TRIGger:INTerpolation ON OFF
[:SENSe]:WAVeform:TRIGger:SOURce EXTernal<1 2> IF IMMediate
:STATus:QUEStionable:CONDition?
:STATus:QUEStionable:ENABle <number>
:STATus:QUEStionable:NTRansition <number>
:STATus:QUEStionable:PTRansition <number>
:STATus:QUEStionable[:EVENT]?
:STATus:QUEStionable:CALibration:CONDition?
:STATus:QUEStionable:CALibration:ENABle <number>
:STATus:QUEStionable:CALibration:NTRansition <number>
:STATus:QUEStionable:CALibration:PTRansition <number>
:STATus:QUEStionable:CALibration[:EVENT]?
:STATus:QUEStionable:FREQuency:CONDition?
:STATus:QUEStionable:FREQuency:ENABle <number>
:STATus:QUEStionable:FREQuency:NTRansition <number>
:STATus:QUEStionable:FREQuency:PTRansition <number>
:STATus:QUEStionable:FREQuency[:EVENT]?
:STATus:QUEStionable:INTegrity:CONDition?
:STATus:QUEStionable:INTegrity:ENABle <number>
:STATus:QUEStionable:INTegrity:NTRansition <number>
:STATus:QUEStionable:INTegrity:PTRansition <number>
:STATus:QUEStionable:INTegrity[:EVENT]?
:STATus:OPERation:CONDition?
:STATus:OPERation:ENABle <integer>
:STATus:OPERation:NTRansition <integer>
:STATus:OPERation:PTRansition <integer>
:STATus:OPERation[:EVENT]?
:SYSTem:COMMunicate:GPIB[:SELF]:ADDRess <integer>
:SYSTem:DATE <year>,<month>,<day>
:SYSTem:ERRor[:NEXT]?
:SYSTem:KLOCK?

Supported 89600 commands
:SYSTem:MESSAge <string>
:SYSTem:PRESet
:SYSTem:TIME <hour>,<minute>,<second>
:SYSTem:VERSion?
:TRACe:COPIY <src_trace>,<dest_trace>
:TRACe[:DATA] TRACE1 TRACE2 TRACE3 TRACE4 TRACE5 TRACE6, <definite_length_block> <comma_separated_ASCII_data>
:TRACe:MODE WRITe MAXHold MINHold VIEW BLANK
:TRIGger[:SEQuence]:DELay <numeric>
:TRIGger[:SEQuence]:DELay:STATe OFF ON 0 1
:TRIGger[:SEQuence]:EXTeRmal:DELay <numeric>
:TRIGger[:SEQuence]:EXTeRmal:LEVel <numeric>
:TRIGger[:SEQuence]:EXTeRmal:SLOPe POSitive NEGative
:TRIGger[:SEQuence]:HOLDoff <numeric>
:TRIGger[:SEQuence]:IF:DELay <numeric>
:TRIGger[:SEQuence]:IF:LEVel <numeric>
:TRIGger[:SEQuence]:IF:SLOPe POSitive NEGative
:TRIGger[:SEQuence]:SLOPe POSitive NEGative
:TRIGger[:SEQuence]:SOURce IMMEDIATE VIDeo EXTeRmal<1 2>
:TRIGger[:SEQuence]:VIDeo:LEVel <numeric>
:TRIGger[:SEQuence]:VIDeo:LEVel:FREQuency <freq>

11.13.4 Reference: Command Set of Emulated PXA Models

The R&S FPS analyzer family supports a subset of the GPIB commands of PXA instruments.

Despite the differences in system architecture and device features, the supported commands have been implemented in a way to ensure a sufficiently high degree of correspondence with the original.

In many cases the selection of commands supported by the R&S FPS is sufficient to run an existing GPIB program without adaptation.

Table 11-9: Supported PXA commands

MMEMory:DELete <file_name>[, <directory_name>]
MMEMory:LOAD:STATe 1, <filename>
MMEMory:MDIRectory <directory_name>

MMEMory:MOVE <string>, <string>[, <string>, <string>]
MMEMory:RDIREctory <directory_name>
MMEMory:STORe:STATe 1, <filename>
[[:SENSe]:FREQuency:CARRier[?] <freq>
[[:SENSe]:FREQuency:CARRier:SEARch
[[:SENSe]:FREQuency:CARRier:TRACk:ACCuracy[?] LOW MED HIGH
[[:SENSe]:FREQuency:CARRier:TRACk:SPAN[?] <freq>
[[:SENSe]:FREQuency:CARRier:TRACk:SPAN:AUTO[?] ON OFF 1 0
[[:SENSe]:FREQuency:CARRier:TRACk[:STATe][?] OFF ON 0 1
[[:SENSe]:LPLot:AMRejection[?] ON OFF 1 0
[[:SENSe]:LPLot:AVERAge:COUNT[?] <integer>
[[:SENSe]:LPLot:AVERAge[:STATe][?] OFF ON 0 1
[[:SENSe]:LPLot:AVERAge:TCONtrol[?] EXPonential REPeat
[[:SENSe]:LPLot:CANCellation:DELTA[?] <rel_ampl>
[[:SENSe]:LPLot:CANCellation[:STATe][?] OFF ON 0 1
[[:SENSe]:LPLot:CANCellation:TRACe[?] <integer>
[[:SENSe]:LPLot:DETector[:FUNction]?
[[:SENSe]:LPLot:FILTerIng NONE LITTLe MEDIUm MAXimum
[[:SENSe]:LPLot:FILTerIng:LITTLe
[[:SENSe]:LPLot:FILTerIng:MAXimum
[[:SENSe]:LPLot:FILTerIng:MEDIUm
[[:SENSe]:LPLot:FILTerIng:NONE
[[:SENSe]:LPLot:FREQuency:OFFSet:STARt[?] <freq>
[[:SENSe]:LPLot:FREQuency:OFFSet:STOP[?] <freq>
[[:SENSe]:LPLot:METHod[?] DANL PN
[[:SENSe]:LPLot:ODRive[?] ON OFF 1 0
[[:SENSe]:LPLot:ODRive:ATTenuation:ZERO[?] ON OFF 1 0
[[:SENSe]:LPLot:SMOoth[?] <real>
TRACe[1] 2 3:LPLot:TYPE[?] RAW SMOothed VIEW BLANK

11.14 Commands for Compatibility

The following commands are provided for compatibility to other signal analyzers only. For new remote control programs use the specified alternative commands.

CALCulate<n>:LIMit<k>:TRACe.....	975
DISPlay[:WINDow<n>]:STATe.....	975
DISPlay[:WINDow<n>]:TYPE.....	975
TRIGger[:SEQuence]:RFPower:HOLDoff.....	976

CALCulate<n>:LIMit<k>:TRACe <TraceNumber>

This command links a limit line to one or more traces.

Note that this command is maintained for compatibility reasons only. Limit lines no longer need to be assigned to a trace explicitly. The trace to be checked can be defined directly (as a suffix) in the new command to activate the limit check (see [CALCulate<n>:LIMit<k>:TRACe<t>:CHECK](#) on page 876).

Parameters:

<TraceNumber> 1 to 6
 *RST: 1

Example:

CALC:LIM2:TRAC 3
 Assigns limit line 2 to trace 3.

DISPlay[:WINDow<n>]:STATe <State>

This command changes the display state of the selected measurement window.

Note that this command is maintained for compatibility reasons only. Use the `LAYout` commands for new remote control programs

(See [chapter 11.6.2, "Working with Windows in the Display"](#), on page 733).

Parameters:

<State> ON | OFF
 OFF
 The window is closed.
 *RST: OFF

Usage:

SCPI confirmed

DISPlay[:WINDow<n>]:TYPE <WindowType>

This command selects the results displayed in a measurement window.

Note that this command is maintained for compatibility reasons only. Use the `LAYout` commands for new remote control programs (see [chapter 11.6.2, "Working with Windows in the Display"](#), on page 733).

Parameters:

<WindowType>

DIAGram

Selects a diagram.

MTABLE

Selects a marker table

PEAKlist

Selects a peak list

RSUMmary

Selects a result summary.

SGRam

Selects a spectrogram.

TRIGger[:SEquence]:RFPower:HOLDoff <Time>

This command defines the holding time before the next trigger event. Note that this command is available for any trigger source, not just RF Power.

Note that this command is maintained for compatibility reasons only. Use the [TRIGger\[:SEquence\]:IFPower:HOLDoff](#) on page 762 command for new remote control programs.

Parameters:

<Time>

Default unit: S

11.15 Programming Examples

Some advanced programming examples for complex measurement tasks are provided here.

- [Programming Example: Performing a Basic Frequency Sweep](#)..... 976
- [Service Request](#).....979

11.15.1 Programming Example: Performing a Basic Frequency Sweep

This example demonstrates how to configure and perform a basic frequency sweep measurement in a remote environment.

```
//-----Preparing the measurement -----
*RST
//Resets the instrument
INIT:CONT OFF
//Selects single sweep mode.

//-----Configuring the Frequency and Span-----
FREQ:CENT 100MHz
//Defines the center frequency
FREQ:SPAN 200MHz
```

```

//Sets the span to 100 MHz on either side of the center frequency.

//Activate signal tracking to keep the center frequency on the signal peak:
CALC:MARK:FUNC:STR ON
CALC:MARK:FUNC:STR:BAND 20MHz
CALC:MARK:FUNC:STR:THR -90dBm
CALC:MARK:FUNC:STR:TRAC 1
//After each sweep the maximum on trace 1 is searched within a range of 20 MHz
//around the center frequency. It must have a minimum power of -90dBm.

//-----Configuring the Bandwidth-----
BAND:AUTO OFF
BAND 1MHz
BAND:TYPE RRC
//Defines the RBW as 1 MHz using an RRC filter

BAND:VID:AUTO OFF
BAND:VID 500kHz
//Decouples the VBW from the RBW and decreases it to smooth the trace.

//-----Configuring the Sweep-----
SENS:SWE:COUN 10
//Defines 10 sweeps to be performed in each measurement.
SENS:SWE:POIN 500
//During each sweep, 500 trace points will be measured.
SENS:SWE:TIME:AUTO OFF
SENS:SWE:TIME 50ms
//Decouples the sweep time from the RBW,VBW and span and increases it to
//make the measurement more precise.

//-----Configuring Attenuation-----
//Only if electronic attenuator is available:
//INP:EATT:STAT ON
//Switches on the electronic attenuator.
//INP:EATT 30dB
//Sets the electronic attenuation to 30 dB.
INP:ATT 10dB
//Sets the mechanical attenuation to 10 dB and couples the reference level
//to the attenuation instead of vice versa.

//-----Configuring the Amplitude and Scaling-----
DISP:TRAC1:Y:RLEV -10dBm
//Sets the reference level to -10 dBm.
DISP:TRAC1:Y:RLEV:OFFS 10dB
//Shifts the trace display in the diagram up by 10dB.
CALC:UNIT:POW V
//Sets the unit of the y-axis to Volt. The reference level is now 70.711 mV.
DISP:TRAC1:Y:SPAC LOG
//Uses logarithmic scaling with absolute values (V).
DISP:TRAC1:Y 110dB

```

```
//Increases the displayed range of the y-axis to 110 dB.
DISP:TRAC1:Y:RPOS 80PCT
//Shifts the display of the reference level down, it is no longer the top line
//in the diagram. The reference level is displayed as a red line.

//-----Triggering-----
TRIG:SOUR IFP
TRIG:LEV:IFP -10dBm
TRIG:SLOP POS
TRIG:DTIM 50ms
TRIG:IFP:HYST 5dB
TRIG:HOLD 10ms
//Defines triggering when the second intermediate frequency rises to a level
//of -10 dBm, with a dropout time of 50 ms, a hysteresis of 5 dB and a delay
//of 10 ms.

SWE:EGAT ON
SWE:EGAT:TYPE EDGE
SWE:EGAT:LENG 5ms
//Defines gating. Values are measured for 5 ms after triggering.

OUTP:TRIG2:DIR OUTP
OUTP:TRIG2:OTYP UDEF
OUTP:TRIG2:LEV HIGH
OUTP:TRIG2:PULS:LENG 100us
OUTP:TRIG2:PULS:IMM
//Configures a high trigger signal with a pulse length of 100 us to be output at
//the front TRIGGER INPUT/OUTPUT connector once.

//-----Configuring the Trace-----
DISP:TRAC2 ON
DISP:TRAC2:MODE AVER
DISP:TRAC3 ON
DISP:TRAC3:MODE MAXH
//Configures 3 traces: 1 (default): clear/write; 2: average; 3: max hold

SENS:DET1 POS
SENS:DET2 RMS
SENS:DET3 POS
//Configures traces 1 and 3 to use the positive peak detector; trace 2 uses
//the RMS detector.

TRAC:COPY TRACE4,TRACE1
//Copies trace 1 to a new trace 4 which will then be averaged.

SENS:AVER:STAT4 ON
SENS:AVER:COUN 10
SENS:AVER:TYPE LIN
//Configures trace 4 to be averaged linearly over 10 sweeps.
```

```

CALC:MATH:STAT ON
CALC:MATH:MODE LIN
CALC:MATH (TRACE1-TRACE2)
CALC:MATH:POS 100
//Calculates the linear difference between the measured and average values.
//The resulting trace is displayed at the top of the diagram.

//-----Performing the Measurement-----
INIT;*WAI
//Initiates a new measurement and waits until the last sweep has finished.

//-----Retrieving Results-----
TRAC:DATA? TRACE1
TRAC:DATA? TRACE2
TRAC:DATA? TRACE3
TRAC:DATA? TRACE4
//Returns one power and one frequency value per sweep point for each trace.

```

11.15.2 Service Request

The service request routine requires an extended initialization of the instrument in which the relevant bits of the transition and enable registers are set. In addition the service request event must be enabled in the VISA session.

11.15.2.1 Initiate Service Request

```

REM ---- Example of initialization of the SRQ in the case
' of errors -----
PUBLIC SUB SetupSRQ()
CALL InstrWrite (analyzer, "*CLS") 'Reset status reporting system
CALL InstrWrite (analyzer, "*SRE 168") 'Enable service request for
'STAT:OPER, STAT:QUES and ESR
'register
CALL InstrWrite (analyzer, "*ESE 60") 'Set event enable bit for
'command, execution, device-
'dependent and query error
CALL InstrWrite (analyzer, "STAT:OPER:ENAB 32767")
'Set OPERATION enable bit for
'all events
CALL InstrWrite (analyzer, "STAT:OPER:PTR 32767")
'Set appropriate OPERATION
'Ptransition bits
CALL InstrWrite (analyzer, "STAT:QUES:ENAB 32767")
'Set questionable enable bits
'for all events
CALL InstrWrite (analyzer, "STAT:QUES:PTR 32767")
'Set appropriate questionable

```

```

'Ptransition bits
CALL viEnableEvent(analyzer, VI_EVENT_SERVICE_REQ, VI_QUEUE, 0)
'Enable the event for service
'request
Status = viWaitOnEvent(analyzer, VI_EVENT_SERVICE_REQ, SRQWaitTimeout, VI_NULL,
    VI_NULL)
IF (status = VI_SUCCESS) THEN CALL Srq
'If SRQ is recognized =>
'subroutine for evaluation
END SUB
REM *****

```

11.15.2.2 Waiting for the Arrival of a Service Request

There are basically two methods of waiting for the arrival of a service request:

Blocking (user inputs not possible):

This method is appropriate if the waiting time until the event to be signaled by an SRQ is short (shorter than the selected timeout), if no response to user inputs is required during the waiting time, and if – as the main criterion – the event is absolutely certain to occur.

Reason:

From the time the `viWaitOnEvent()` function is called until the occurrence of the expected event, it does not allow the program to respond to mouse clicks or key entries during the waiting time. Moreover, it returns an error if the SRQ event does not occur within the predefined timeout period.

The method is, therefore, in many cases not suitable for waiting for measurement results, especially when using triggered measurements.

The following function calls are required:

```

Status = viWaitOnEvent(analyzer, VI_EVENT_SERVICE_REQ, SRQWaitTimeout, VI_NULL,
    VI_NULL)
'Wait for service request user
'inputs are not possible during
'the waiting time!
IF (status = VI_SUCCESS) THEN CALL Srq
'If SRQ is recognized =>
'subroutine for evaluation

'----- Sweep in first Spectrum Tab and query marker -----
Dim Status = mbSession.WaitOnEvent( _
MessageBasedSessionEventType.ServiceRequest, SRQWaitTimeout)
'Wait for service request user inputs are not possible
'during the waiting time!
If (Status.EventType() = MessageBasedSessionEventType.ServiceRequest) Then
'If SRQ is recognized => subroutine for evaluation

```

```

    Srq()
End If

```

Non-blocking (user inputs possible):

This method is recommended if the waiting time until the event to be signaled by an SRQ is long (longer than the selected timeout), and user inputs should be possible during the waiting time, or if the event is not certain to occur. This method is, therefore, the preferable choice for waiting for the end of measurements, i.e. the output of results, especially in the case of triggered measurements.

The method necessitates a waiting loop that checks the status of the SRQ line at regular intervals and returns control to the operating system during the time the expected event has not yet occurred. In this way, the system can respond to user inputs (mouse clicks, key entries) during the waiting time.

It is advisable to employ the Hold() auxiliary function, which returns control to the operating system for a selectable waiting time (see section [Waiting Without Blocking the Keyboard and Mouse](#)), so enabling user inputs during the waiting time.

```

result% = 0
For i = 1 To 10 'Abort after max. 10 loop
'iterations
Status = viWaitOnEvent(analyzer, VI_EVENT_SERVICE_REQ, VI_TMO_IMMEDIATE, VI_NULL,
    VI_NULL)
'Check event queue
If (status = VI_SUCCESS) Then
result% = 1
CALL Srq 'If SRQ is recognized =>
'subroutine for evaluation
Else
CALL Hold(20) 'Call hold function with
'20 ms 'waiting time. User inputs
'are possible.
Endif
Next i
If result% = 0 Then
Debug.Print "Timeout Error; Program aborted" 'Output error message
STOP 'Stop software
Endif

```

11.15.2.3 Waiting Without Blocking the Keyboard and Mouse

A frequent problem with remote control programs using Visual Basic is to insert waiting times without blocking the keyboard and the mouse.

If the program is to respond to user inputs also during a waiting time, control over the program events during this time must be returned to the operating system. In Visual Basic, this is done by calling the DoEvents function. This function causes keyboard-or mouse-triggered events to be executed by the associated elements. For example, it allows the operation of buttons and input fields while the user waits for an instrument setting to be completed.

The following programming example describes the `Hold()` function, which returns control to the operating system for the period of the waiting time selectable in milliseconds.

```
Rem *****
Rem The waiting function below expects the transfer of the desired
Rem waiting time in milliseconds. The keyboard and the mouse remain
Rem operative during the waiting period, thus allowing desired elements
Rem to be controlled
Rem *****
Public Sub Hold(delayTime As Single)
Start = Timer 'Save timer count on calling the
'function
Do While Timer < Start + delayTime/1000 'Check timer count
DoEvents 'Return control to operating
'system to enable control of
'desired elements as long as
'timer has not elapsed
Loop
End Sub
Rem *****
```

The waiting procedure is activated simply by calling `Hold(<Waiting time in milliseconds>)`.

11.15.2.4 Service Request Routine

A service request is processed in the service request routine.



The variables `userN%` and `userM%` must be pre-assigned usefully!

```
REM ----- Service request routine -----
Public SUB Srq()
ON ERROR GOTO noDevice 'No user existing
CALL viReadSTB(analyzer, STB%) 'Serial poll, read status byte
IF STB% > 0 THEN 'This instrument has bits set in
'the STB
SRQFOUND% = 1
IF (STB% AND 16) > 0 THEN CALL Outputqueue
IF (STB% AND 4) > 0 THEN CALL ErrorQueueHandler
IF (STB% AND 8) > 0 THEN CALL Questionablestatus
IF (STB% AND 128) > 0 THEN CALL Operationstatus
IF (STB% AND 32) > 0 THEN CALL Esrread
END IF
noDevice:
END SUB 'End of SRQ routine
REM *****
```



```

REM ----- Subroutine for evaluation Service Request Routine -----

Public Sub Srq()
    Try
        Dim mySTB As Short = mbSession.ReadStatusByte()
                                'Serial poll, read status byte
        Console.WriteLine("Reading Service Request Routine:" + mySTB.ToString())
        If mySTB > 0 Then 'This instrument has bits set in the STB
            If (mySTB And 16) > 0 Then Call Outputqueue()
            If (mySTB And 4) > 0 Then Call ErrorQueueHandler()
            If (mySTB And 8) > 0 Then Call Questionablestatus()
            If (mySTB And 128) > 0 Then Call Operationstatus()
            If (mySTB And 32) > 0 Then Call Esrread()
        End If
    Catch exp As Exception
        Console.WriteLine(exp.Message)
    End Try
End Sub 'End of SRQ routine

```

Reading out the status event registers, the output buffer and the error/event queue is effected in subroutines.

11.15.2.5 Reading Out the Output Buffer

```

REM ----- Subroutine for the individual STB bits -----
Public SUB Outputqueue() 'Reading the output buffer
result$ = SPACE$(100) 'Make space for response
CALL InstrRead(analyzer, result$)
Debug.Print "Contents of Output Queue:"; result$
END SUB
REM *****

REM ----- Subroutine for the output queue -----
Public Sub Outputqueue() 'Reading the output buffer
    Try
        Dim result As String = mbSession.ReadString()
        Console.WriteLine("Contents of Output Queue:" + result)
    Catch exp As Exception
        Console.WriteLine(exp.Message)
    End Try
End Sub

```

11.15.2.6 Reading Error Messages

```

REM ----- Subroutine for reading the error queue -----
Public SUB ErrorQueueHandler()
ERROR$ = SPACE$(100) 'Make space for error variable
CALL InstrWrite (analyzer, "SYSTEM:ERROR?")
CALL InstrRead(analyzer, ERROR$)
Debug.Print "Error Description:"; ERROR$

```

```

END SUB
REM *****
REM ----- Subroutine for reading the error queue -----
Sub ErrorQueueHandler()
    Dim result As String
    Dim hasErr As Boolean = True
    Do
        mbSession.Write("SYST:ERR?")
        result = mbSession.ReadString()
        Dim parts As String() = result.Split(",")
        If parts(0) = 0 Then
            hasErr = False
            Console.WriteLine(result)
        Else
            Console.WriteLine(result)
        End If
    Loop While hasErr
End Sub

```

11.15.2.7 Evaluation of SCPI Status Registers

```

REM ----- Subroutine for evaluating Questionable Status Register -----
Public SUB Questionablestatus()
    Ques$ = SPACE$(20)
    'Preallocate blanks to text
    'variable
    CALL InstrWrite (analyzer, "STATus:QUESTionable:EVENT?")
    CALL InstrRead(analyzer, Ques$)
    Debug.Print "Questionable Status: "; Ques$
END SUB
REM *****
REM ----- Subroutine for evaluating Operation Status Register -----
Public SUB Operationstatus()
    Oper$ = SPACE$(20) 'Preallocate blanks to text
    'variable
    CALL InstrWrite (analyzer, "STATus:OPERation:EVENT?")
    CALL InstrRead(analyzer, Oper$)
    Debug.Print "Operation Status: "; Oper$
END SUB
REM *****
REM ----- Subroutine for evaluating Questionable Status Register -----
Public Sub Questionablestatus()
    Dim myQSR As String = Nothing
    Try
        myQSR = mbSession.Query("STATus:QUESTionable:EVENT?") 'Read QSR
        Console.WriteLine("Questionable Status:" + myQSR)
    Catch exp As Exception
        Console.WriteLine(exp.Message)
    End Try
End Sub

```

```

        End Try
    End Sub

    REM ----- Subroutine for evaluating Operation Status Register -----
    Public Sub Operationstatus()
        Dim myOSR As String = Nothing
        Try
            myOSR = mbSession.Query("STaTus:OPERation:EVENT?") 'Read OSR
            Console.WriteLine("Operation Status:" + myOSR)
        Catch exp As Exception
            Console.WriteLine(exp.Message)
        End Try
    End Sub

```

11.15.2.8 Evaluation of Event Status Register

```

    REM ----- Subroutine for evaluating the Event Status Register -----
    Public SUB Esrread()
    Esr$ = SPACE$(20) 'Preallocate blanks to text
    'variable
    CALL InstrWrite (analyzer, "*ESR?") 'Read ESR
    CALL InstrRead(analyzer, Esr$)
    IF (VAL(Esr$) AND 1) > 0 THEN Debug.Print "Operation complete"
    IF (VAL(Esr$) AND 2) > 0 THEN Debug.Print "Request Control"
    IF (VAL(Esr$) AND 4) > 0
    THEN Debug.Print "Query Error"
    IF (VAL(Esr$) AND 8) > 0
    THEN Debug.Print "Device dependent error"
    IF (VAL(Esr$) AND 16) > 0
    THEN Debug.Print "Execution Error; Program aborted"'Output error message
    STOP 'Stop software
    END IF
    IF (VAL(Esr$) AND 32) > 0
    THEN Debug.Print "Command Error; Program aborted"'Output error message
    STOP 'Stop software
    END IF
    IF (VAL(Esr$) AND 64) > 0 THEN Debug.Print "User request"
    IF (VAL(Esr$) AND 128) > 0 THEN Debug.Print "Power on"END SUB
    REM *****

    REM ----- Subroutine for evaluating the Event Status Register -----
    Public Sub Esrread()
        Try
            Dim myESR As Short = mbSession.Query("*ESR?") 'Read ESR
            If (myESR And 1) > 0 Then Console.WriteLine("Operation complete")
            If (myESR And 2) > 0 Then Console.WriteLine("Request Control")
            If (myESR And 4) > 0 Then Console.WriteLine("Query Error")
            If (myESR And 8) > 0 Then Console.WriteLine("Device dependent error")
            If (myESR And 16) > 0 Then
                Console.WriteLine("Execution Error; Program aborted") 'Output error message
            End If
        End Try
    End Sub

```

```
        Stop 'Stop software
    End If
    If (myESR And 32) > 0 Then
        Console.WriteLine("Command Error; Program aborted") 'Output error message
        Stop 'Stop software
    End If
    If (myESR And 64) > 0 Then Console.WriteLine("User request")
    If (myESR And 128) > 0 Then Console.WriteLine("Power on")
    Catch exp As Exception
        Console.WriteLine(exp.Message)
    End Try
End Sub
```

12 Maintenance

The R&S FPS does not require regular maintenance. Maintenance is essentially restricted to cleaning the R&S FPS. It is however advisable to check the nominal data from time to time.

NOTICE**Instrument damage caused by cleaning agents**

Cleaning agents contain substances that may damage the instrument. For example, cleaning agents that contain a solvent may damage the front panel labeling, plastic parts, or the display.

Never use cleaning agents such as solvents (thinners, acetone, etc), acids, bases, or other substances.

The outside of the instrument can be cleaned sufficiently using a soft, lint-free dust cloth.

The storage temperature range for the R&S FPS is specified in the data sheet. The instrument must be protected against dust if it is to be stored for a long period.

When transporting or shipping the instrument, it is advisable to use the original packing material (especially the two protective covers for the front and rear panel).

13 Optimizing and Troubleshooting

If the results do not meet your expectations, the following sections may contain helpful hints and information.



Error message display

Note that any error messages caused by the Windows 7 operating system are only visible on an external monitor or via RemoteDesktop from a control PC. Thus, if operation of the R&S FPS seems to fail for no obvious reason, try connecting a monitor or a control PC to check for any messages awaiting confirmation or action.

(See [chapter 3.1.3, "Connecting USB Devices"](#), on page 27 or [chapter 3.4.6, "How to Set Up Remote Desktop"](#), on page 62)

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- [Error Messages in Remote Control Mode](#)..... 989
- [Troubleshooting Remote Operation](#)..... 990
- [Minimizing the Measurement Duration](#)..... 991
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13.1 Error Information

If errors or irregularities are detected, a keyword and an error message, if available, are displayed in the status bar.



Depending on the type of message, the status message is indicated in varying colors.

Table 13-1: Status bar information - color coding

Color	Type	Description
red	Error	An error occurred at the start or during a measurement, e.g. due to missing data or wrong settings, so that the measurement cannot be started or completed correctly.
orange	Warning	An irregular situation occurred during measurement, e.g. the settings no longer match the displayed results, or the connection to an external device was interrupted temporarily.
gray	Information	Information on the status of individual processing steps.
no color	No errors	No message displayed - normal operation.
green	Measurement successful	Some applications visualize that the measurement was successful by showing a message.



If any error information is available for a measurement channel, an exclamation mark is displayed next to the channel name (❗). This is particularly useful when the MultiView tab is displayed, as the status bar in the MultiView tab always displays the information for the currently selected measurement only.

Furthermore, a status bit is set in the `STATUS:QUESTIONable:EXTended:INFO` register for the application concerned (see "[STATUS:QUESTIONable:EXTended:INFO Register](#)" on page 565). Messages of a specific type can be queried using the `SYST:ERR:EXT?` command, see [SYSTEM:ERRor:EXTended?](#) on page 929.

The following keywords are used:

IF OVLD	Overload of the IF signal path in the A/D converter or in the digital IF. <ul style="list-style-type: none"> Increase the reference level.
INPUT OVLD	The signal level at the RF input connector exceeds the maximum. The RF input is disconnected from the input mixer to protect the device. In order to re-enable measurement, decrease the level at the RF input connector and reconnect the RF input to the mixer input.
LOUNL	Error in the instrument's frequency processing hardware was detected.
NO REF	Instrument was set to an external reference but no signal was detected on the reference input.
OVEN	The optional OCXO reference frequency has not yet reached its operating temperature. The message usually disappears a few minutes after power has been switched on.
RF OVLD	Overload of the input mixer or of the analog IF path. <ul style="list-style-type: none"> Increase the RF attenuation (for RF input). Reduce the input level (for digital input)
UNCAL	One of the following conditions applies: <ul style="list-style-type: none"> Correction data has been switched off. No correction values are available, for example after a firmware update. Record the correction data by performing a self alignment (For details refer to chapter 3.1.4, "Performing a Self Alignment and a Self Test", on page 29).
WRONG_FW	The firmware version is out-of-date and does not support the currently installed hardware. Until the firmware version is updated, this error message is displayed and self-alignment fails. (For details refer to chapter 9.3.4.4, "Firmware Updates" , on page 519).

13.2 Error Messages in Remote Control Mode

In remote control mode error messages are entered in the error/event queue of the status reporting system and can be queried with the command `SYSTEM:ERRor?`. The answer format of R&S FPS to the command is as follows:

```
<error code>, "<error text with queue query>; <remote control command concerned>"
```

The indication of the remote control command with prefixed semicolon is optional.

Example:

The command `TEST:COMMAND` generates the following answer to the query `SYSTEM:ERROR?`

```
-113,"Undefined header;TEST:COMMAND"
```

There are two types of error messages:

- Error messages defined by SCPI are marked by negative error codes. These messages are defined and described in the SCPI standard and not listed here.
- Device-specific error messages use positive error codes. These messages are described below.

Table 13-2: Device-specific error messages

Error code	Error text in the case of queue poll Error explanation
1052	Frontend LO is Unlocked This message is displayed when the phase regulation of the local oscillator fails in the RF front-end.
1060	Trigger-Block Gate Delay Error- gate length < Gate Delay This message is displayed when the gate signal length is not sufficient for the pull-in delay with a predefined gate delay.
1064	Tracking LO is Unlocked This message is displayed when the phase regulation of the local oscillator fails on the external generator module.
2028	Hardcopy not possible during measurement sequence This message is displayed when a printout is started during scan sequences that cannot be interrupted. Such sequences are for example: <ul style="list-style-type: none"> • Recording the system error correction data (alignment) • Instrument self test In such cases synchronization to the end of the scan sequence should be performed prior to starting the printout.
2033	Printer Not Available This message is displayed when the selected printer is not included in the list of available output devices. A possible cause is that the required printer driver is missing or incorrectly installed.
2034	CPU Temperature is too high This message is displayed when the temperature of the processor exceeds 70 °C.

13.3 Troubleshooting Remote Operation

If problems arise during measurement in remote operation, try the following methods to solve them.

Uncompleted sequential commands - blocked remote channels

If a sequential command cannot be completed, for example because a triggered sweep never receives a trigger, the remote control program will never finish and the remote

channel to the R&S FPS is blocked for further commands. In this case, you must interrupt processing on the remote channel in order to abort the measurement.

To regain control over a blocked remote channel

1. Send a "Device Clear" command from the control instrument to the R&S FPS to clear all currently active remote channels. Depending on the used interface and protocol, send the following commands:

- **Visa:** `viClear()`

The remote channel currently processing the uncompleted command is then ready to receive further commands again.

2. On the remote channel performing the measurement, send the SCPI command `ABORT` to abort the current measurement and reset the trigger system.

Ignored commands

When a remote command attempts to define incompatible settings, the command is ignored and the instrument status remains unchanged, i.e. other settings are not automatically adapted. Therefore, control programs should always define an initial instrument status (e.g. using the `*RST` command) and then implement the required settings.

Detecting false commands

If a remote program does not provide the expected results and you are using a GPIB connection, you can log the commands and any errors that may occur. To activate the SCPI error log function, in the "Network + Remote" dialog box, in the "GPIB" tab, select "I/O Logging".

All remote control commands received by the R&S FPS are recorded in the following log file:

```
C:\R_S\instr\ScpiLogging\ScpiLog.txt
```

Logging the commands may be extremely useful for debug purposes, e.g. in order to find misspelled keywords in control programs. However, remember to turn off the logging function after debugging to avoid unnecessary access to the hard drive and use of storage space.

13.4 Minimizing the Measurement Duration

If you want to minimize the measurement duration, try the following methods to optimize the measurement:

- Reduce the **span** of the measurement to the relevant parts of the signal only.
- Increase the **RBW** to minimize the measurement time; however, consider the requirements of the standard if you need to measure according to standard!
- Take advantage of the **speed optimization mode** in the "Sweep" settings if you do not require the larger dynamic range (see "[Optimization](#)" on page 362).

- Reduce the **sweep time** and thus the amount of data to be captured and calculated; however, consider the requirements regarding the standard deviation.
- To determine average (or peak) values, use an **RMS detector (or peak detector) with a higher sweep time** instead of trace averaging to obtain better average power results in less time. Furthermore, enforce the use of the **sweep type "FFT"** (as opposed to "Auto"; in Sweep mode, the averaging effect of the RMS detector may be less efficient).
- When performing multiple measurements, use **multiple measurement channels** to switch between measurements rather than changing the settings within one channel repeatedly.
Take advantage of the **Sequencer** function to switch between multiple measurements automatically or continuously (see also [chapter 4.5, "Running a Sequence of Measurements"](#), on page 107).

13.5 Improving Averaging Results

Instead of **trace averaging**, use an RMS detector with a higher sweep time to obtain better average power results in less time. Furthermore, enforce the use of the **sweep type "FFT"** (as opposed to "Auto"; in Sweep mode, the averaging effect of the RMS detector may be less efficient).

In FFT mode, FFTs are calculated per bin and combined using the RMS detector. For trace averaging, on the other hand, the local oscillator must be switched repeatedly for each trace, which takes additional time.

Generally, a higher **sweep time** leads to more data to be averaged and thus stabilizes the results. In FFT mode, a higher sweep time means more FFTs are calculated and combined per bin.

Thus, in the same capture time, the FFT mode with an RMS detector can provide better results than an averaged trace.

13.6 Miscellaneous Troubleshooting Hints

Power levels for low frequency signals not correct	992
Invalid trace display	992

Power levels for low frequency signals not correct

By default, the R&S FPS uses AC coupling for RF input. For very low frequencies, the input signal may be distorted with this setting. In this case, use DC coupling instead. To change the setting, select INPUT/OUTPUT > "Input Source Config > Radio Frequency > Input Coupling > DC".

Invalid trace display

If output to the IF 2 GHZ OUT connector is activated, the measured values are no longer sent to the display; thus, the trace data currently displayed on the R&S FPS becomes invalid. A message in the status bar indicates this situation.

13.7 Obtaining Technical Support

If problems occur, the instrument generates error messages which in most cases will be sufficient for you to detect the cause of an error and find a remedy.

Error messages are described in [chapter 13, "Optimizing and Troubleshooting"](#), on page 988.

In addition, our customer support centers are there to assist you in solving any problems that you may encounter with your R&S FPS. We will find solutions more quickly and efficiently if you provide us with the information listed below.

- **System Configuration:** The "System Configuration" dialog box (in the "Setup" menu of the soft front panel) provides information on:
 - **Hardware Info:** hardware assemblies
 - **Versions and Options:** the status of all software and hardware options installed on your instrument
 - **System Messages:** messages on any errors that may have occurred

An .xml file with information on the system configuration ("device footprint") can be created automatically (using the `DIAGnostic:SERvice:SIInfo` command or as described in ["To collect the support information"](#) on page 993).

- **Error Log:** The `RSError.log` file (in the log directory of the main installation directory) contains a chronological record of errors.
- **Support file:** a *.zip file with important support information can be created automatically. The *.zip file contains the system configuration information ("device footprint"), the current eeprom data and a screenshot of the screen display.

See also [chapter 9.3.5, "Service Functions"](#), on page 522.

To collect the support information

1. Select the SETUP key in the soft front panel on the Remote Desktop.
2. Select "Service > R&S Support" and then "Create R&S Support Information".

The file is stored as `C:\R_S\instr\user\service.zip`.

Attach the support file to an e-mail in which you describe the problem and send it to the customer support address for your region as listed in the Internet (http://www.rohde-schwarz.com/en/service-support/customer_support_107711.html).



Packing and transporting the instrument

If the instrument needs to be transported or shipped, e.g. due to damage during delivery, observe the notes described in [chapter 3.1.1.1, "Unpacking and Checking the Instrument"](#), on page 19.

List of remote commands (base unit)

[SENSe:] [WINDow<n>:] DETector<t>[:FUNction]	803
[SENSe:] [WINDow<n>:] DETector<t>[:FUNction]:AUTO	803
[SENSe:] ADJust:ALL	770
[SENSe:] ADJust:CONFigure:DURation	770
[SENSe:] ADJust:CONFigure:DURation:MODE	771
[SENSe:] ADJust:CONFigure:HYSteresis:LOWer	771
[SENSe:] ADJust:CONFigure:HYSteresis:UPPer	771
[SENSe:] ADJust:CONFigure:TRIG	772
[SENSe:] ADJust:FREQuency	772
[SENSe:] ADJust:LEVel	772
[SENSe:] AVERAge<n>:COUNT	802
[SENSe:] AVERAge<n>:TYPE	802
[SENSe:] AVERAge<n>[:STATe<t>]	802
[SENSe:] BANDwidth:VIDeo	749
[SENSe:] BANDwidth:VIDeo:AUTO	749
[SENSe:] BANDwidth:VIDeo:RATio	750
[SENSe:] BANDwidth:VIDeo:TYPE	750
[SENSe:] BANDwidth[:RESolution]	747
[SENSe:] BANDwidth[:RESolution]:AUTO	748
[SENSe:] BANDwidth[:RESolution]:FFT	754
[SENSe:] BANDwidth[:RESolution]:RATio	748
[SENSe:] BANDwidth[:RESolution]:TYPE	748
[SENSe:] BWIDth:VIDeo	749
[SENSe:] BWIDth:VIDeo:AUTO	749
[SENSe:] BWIDth:VIDeo:RATio	750
[SENSe:] BWIDth:VIDeo:TYPE	750
[SENSe:] BWIDth[:RESolution]	747
[SENSe:] BWIDth[:RESolution]:AUTO	748
[SENSe:] BWIDth[:RESolution]:FFT	754
[SENSe:] BWIDth[:RESolution]:RATio	748
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